Directory: ./		Exec	Total	Coverage
Date: 2022-03-26 23:05:02	Lines:	158	280	56.4 %
Legend: low: < 75.0 % medium: >= 75.0 % high: >= 90.0 %	Branches:	258	734	35.1 %

File	Lines			Branches		
include/bitset utils.hpp		100.0 %	21 / 21	100.0 %	6 / 6	
include/byte utils.hpp		100.0 %	9/9	- %	0/0	
include/static map.hpp		100.0 %	5 / 5	100.0 %	4 / 4	
src/i2c utils.cpp		0.0 %	0 / 41	0.0 %	0 / 12	
src/restricted base.cpp		0.0 %	0 / 1	- %	0/0	
src/spi_utils.cpp		0.0 %	0 / 28	0.0 %	0 / 18	
src/timer manager.cpp		0.0 %	0 / 32	0.0 %	0 / 20	
src/usart utils.cpp		0.0 %	0 / 20	0.0 %	0 / 12	
tests/catch bitset utils.cpp		100.0 %	86 / 86	37.5 %	156 / 416	
tests/catch byte utils.cpp		100.0 %	8/8	37.5 %	12 / 32	
tests/catch static map.cpp		100.0 %	29 / 29	37.4 %	80 / 214	

Directory: ./		Exec	Total	Coverage
Date: 2022-03-26 23:05:02	Lines:	158	280	56.4 %
Legend: low: < 75.0 % medium: >= 75.0 % high: >= 90.0 %	Branches:	258	734	35.1 %

File	Lines			Branches		
include/bitset utils.hpp		100.0 %	21 / 21	100.0 %	6 / 6	
include/byte utils.hpp		100.0 %	9/9	- %	0/0	
include/static map.hpp		100.0 %	5 / 5	100.0 %	4 / 4	
src/i2c utils.cpp		0.0 %	0 / 41	0.0 %	0 / 12	
src/restricted base.cpp		0.0 %	0 / 1	- %	0/0	
src/spi_utils.cpp		0.0 %	0 / 28	0.0 %	0 / 18	
<pre>src/timer manager.cpp</pre>		0.0 %	0 / 32	0.0 %	0 / 20	
src/usart utils.cpp		0.0 %	0 / 20	0.0 %	0 / 12	
tests/catch bitset utils.cpp		100.0 %	86 / 86	37.5 %	156 / 416	
tests/catch byte utils.cpp		100.0 %	8/8	37.5 %	12 / 32	
tests/catch static map.cpp		100.0 %	29 / 29	37.4 %	80 / 214	

 Directory: ./
 Exec
 Total
 Coverage

 File: include/bitset_utils.hpp
 Lines:
 21
 21
 100.0 %

 Date: 2022-03-26 23:05:02
 Branches:
 6
 6
 100.0 %

```
Line Branch Exec Source
                  // MIT License
                  // Copyright (c) 2022 Chris Suttor
                  // Permission is hereby granted, free of charge, to any person obtaining a copy // of this software and associated documentation files (the "Software"), to deal
                  // in the Software without restriction, including without limitation the rights
                  //\ {\tt to}\ {\tt use,\ copy,\ modify,\ merge,\ publish,\ distribute,\ sublicense,\ {\tt and/or\ sell}\\
                  // copies of the Software, and to permit persons to whom the Software is
                  // furnished to do so, subject to the following conditions:
  11
  12
                  \ensuremath{//} The above copyright notice and this permission notice shall be included in all
  13
                  // copies or substantial portions of the Software.
  15
                  // THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR
  16
                  // IMPLIED. INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY
                  // FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE
                  // AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER
                  // LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM, // OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE
  19
  20
                  // SOFTWARE.
  22
                  #ifndef __BITSET_UTILS_HPP_
#define __BITSET_UTILS_HPP_
  23
  24
                    used for x86-based testing
  27
                  #ifdef X86 UNIT TESTING ONLY
  28
                      #include <iostream>
                  #endif
  29
  30
  31
                  // used for arm target debug mode only.
                  #ifdef USE_RTT
  33
                    #include <SEGGER_RTT.h>
  34
                  #endif
  35
                  #include <stdint.h>
                  #include <bitset>
  38
                  #include <arrav>
  39
                  namespace noarch::bit_manip
  41
  42
  43
                  // @brief Adds source std::bitset to target std::bitset with msb_offset
                  // @tparam TARGET_SIZE The size of the source bitset container // @tparam SOURCE_SIZE The size of the target bitset container
  45
  46
                  // @param target The target bitset container to copy into
                  // @param source The source bitset container to copy from
  49
                  // @param msb\_offset insertion index starting from the right-most position
  50
                  template<std::size_t TARGET_SIZE, std::size_t SOURCE_SIZE>
  52
  53
                       // protect against oversized msb offset or SOURCE params
  54
  57
  58
                       // iterate over the source bitset pattern
  59
                           (uint16_t idx = 0; idx < source.size(); idx++
  60
  61
                           // start from the common register msb and work backwards towards lsb,
  62
                              ...minus the offset
  63
  65
  66
                           else
  69
                      return true;
  74
                  // @brief Converts bits to same sized byte array LSB first. 0101 becomes 1010.
                  // Oversized bitsets are truncated, undersized bitsets are zero-padded
                     @tparam TARGET_SIZE The size of the target_array std::array
  78
                  // @tparam SOURCE_SIZE The size of the source_bitset std::bitset
  79
                     @param target_array The std::array object copied to. Caution, all pre-existing contents is destroyed.
                  // @param source_bitset The std::bitset object copied from.
                  template<std::size_t TARGET_SIZE, std::size_t SOURCE_SIZE>
  82
                 bool bitset_to_bytearray(std::array<uint8_t, TARGET_SIZE> &target_array, const std::bitset<SOURCE_SIZE> &source_bitset)
  83
  85
                      const uint8_t word_size_bits = 8;
  86
  87
                          clear the array before starting
  89
                      target_array.fill(0);
  90
                       // iterate each byte in the array and fill it
                      for (uint16_t byte_array_idx = 0; byte_array_idx < target_array.size(); byte_array_idx++)
```

```
93
                         // This is the current position within the bitset, relative to the current byte
 94
 95
96
97
                         // used to bitshift the individual bits into the current byte
                         int8_t bit_offset_within_byte = word_size_bits -
99
                         // iterate the bitset position [n -> n + 8)
100
                        for (uint16_t pattern_idx = bit_offset_within_pattern; pattern_idx < bit_offset_within_pattern + word_size_bits; pattern_idx++)
101
102
103
                             // double check we haven't overshot the input bitset length
104
            40
                             if (pattern_idx < source_bitset.size())</pre>
105
                             {
106
                                 target_array[byte_array_idx] |= (source_bitset.test(pattern_idx) << bit_offset_within_byte);</pre>
107
108
                                 bit_offset_within_byte--;
109
110
                             else
111
                             {
                                 target_array[byte_array_idx] |= 0;
bit_offset_within_byte--;
112
114
115
116
118
119
                // @brief Print out the provided bitset as bytes
120
121
                \ensuremath{//} @param pattern The bitset to print
122
                template<std::size_t BITSET_SIZE>
123
                void print bits(std::bitset<BITSET SIZE> &pattern [[maybe unused]])
124
125
                    #ifdef USE RTT
126
127
                        for (uint16_t idx = 0; idx < pattern.size(); idx++)
129
                             if (idx % 8 == 0)
                             SEGGER_RTT_printf(0, " ");
if (idx % 64 == 0)
130
131
                                 SEGGER_RTT_printf(0, "\n");
                             SEGGER_RTT_printf(0, "%u ", +pattern.test(idx));
133
134
135
                        SEGGER_RTT_printf(0, "\n");
136
                    #endif
                    #ifdef X86_UNIT_TESTING_ONLY
137
                        for (uint16_t idx = 0; idx < pattern.size(); idx++)
138
139
140
                             if (idx % 8 == 0)
141
142
                                 std::cout << " ";
143
144
                             if (idx % 64 == 0)
145
146
                                 std::cout << std::endl;
147
148
                             std::cout << std::noboolalpha << pattern.test(idx);</pre>
149
150
                        std::cout << std::endl;
151
152
153
154
                } // namespace noarch::bit manip
156
157
                #endif // BITSET UTILS HPP
```

 Directory: ./
 Exec
 Total
 Coverage

 File: include/byte_utils.hpp
 Lines: 9
 9
 100.0 %

 Date: 2022-03-26 23:05:02
 Branches: 0
 0
 - %

```
LineBranchExec Source
                // MIT License
  2
  3
                // Copyright (c) 2022 Chris Sutton
  4
                // Permission is hereby granted, free of charge, to any person obtaining a copy
                // of this software and associated documentation files (the "Software"), to deal
  6
                // in the Software without restriction, including without limitation the rights
  8
                // to use, copy, modify, merge, publish, distribute, sublicense, and/or sell
  9
                // copies of the Software, and to permit persons to whom the Software is
 10
                // furnished to do so, subject to the following conditions:
 11
 12
                // The above copyright notice and this permission notice shall be included in all
 13
                // copies or substantial portions of the Software.
 14
                // THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR
 15
 16
                // IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY,
 17
                // FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE
                // AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER
 18
                // LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM,
 19
 20
                // OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE
                // SOFTWARE.
 21
 22
 23
                #ifndef __BYTE_UTILS_HPP__
 24
                #define __BYTE_UTILS_HPP__
 25
 2.6
                #include <stdint.h>
 27
                #ifdef X86_UNIT_TESTING_ONLY
 28
                    #include <iostream>
 29
                    #include <iomanip>
 30
                #endif
 31
 32
                namespace noarch::byte_manip
 33
 34
                template<std::size_t BYTE_ARRAY_SIZE>
 35
 36
                bool print_bytes(std::array<uint8_t, BYTE_ARRAY_SIZE> &bytes [[maybe_unused]])
 37
                {
 38
                     if (bytes.empty())
 39
 40
                         return false;
 41
 42
                     for (uint16_t idx = 0; idx < bytes.size(); idx++)
            65
 43
 44
 45
            64
                             if (idx % 16 == 0)
 46
 47
                                 #if defined(USE_RTT)
                                     SEGGER_RTT_printf(0, "\n");
 48
 49
                                 #elif defined(X86_UNIT_TESTING_ONLY)
 50
                                    std::cout << std::endl;
 51
                                 #endif
 52
 53
                             #if defined(USE RTT)
 54
                                 SEGGER_RTT_printf(0, "0x%02x ", +bytes[idx]);
                             #elif defined(X86 UNIT TESTING ONLY)
 55
                                 std::cout << " 0x" << std::setfill('0') << std::setw(2) << std::hex << +bytes[idx];
 56
            64
 57
                             #endif
 58
 59
                    #if defined(USE_RTT)
 60
                         SEGGER RTT printf(0, "\n");
 61
                     #elif defined(X86_UNIT_TESTING_ONLY)
 62
                        std::cout << std::endl;
                    #endif
 63
 64
                    return true;
 65
                }
 66
 67
                    // namespace noarch::byte_manip
 68
```

Directory: ./		Exec	Total	Coverage
File: include/static_map.hpp	Lines:	5	5	100.0 %
Date: 2022-03-26 23:05:02	Branches:	4	4	100.0 %

```
LineBranch Exec Source
                 // MIT License
                 // Copyright (c) 2022 Chris Sutton
  3
                 // Permission is hereby granted, free of charge, to any person obtaining a copy
                 // of this software and associated documentation files (the "Software"), to deal
                 // in the Software without restriction, including without limitation the rights
                 // to use, copy, modify, merge, publish, distribute, sublicense, and/or sell
  9
                 // copies of the Software, and to permit persons to whom the Software is
                 // furnished to do so, subject to the following conditions:
 11
 12
                 // The above copyright notice and this permission notice shall be included in all
                 // copies or substantial portions of the Software.
 14
 15
                 // THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR
 16
                 // IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY,
                 // FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE
 17
 18
                 // AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER
 19
                 // LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM,
                 // OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE
 20
                 // SOFTWARE.
 21
 22
 23
                 #ifndef ___STATIC_MAP_HPP___
                 #define ___STATIC_MAP_HPP_
 2.5
 26
 27
                 // #include <algorithm>
 2.8
                 #include <arrav>
 29
 30
                 // @brief For working example see https://godbolt.org/z/deza1Ecnn
 31
 32
                 namespace noarch::containers
 33
 34
 35
                 // @brief Associative container with contains key-value pairs that is allocated at compile-time
 36
                 // @tparam Key The Key
 37
                 // @tparam Value The Value
 38
                 // @tparam Size The size of the map/number of Key/Value pairs. Must be constant.
 39
                 template <typename Key, typename Value, std::size_t Size>
                 struct StaticMap {
 41
                     // @brief The dictionary
 42
                     std::array<std::pair<Key, Value>, Size> data;
 43
 44
 45
                     // @brief access specified element
                     // @param key The key element to match
 46
                     // @return Value* Pointer to the value element, or nullptr if not found
 47
 48
                     Value* find_key(const Key &key) {
 49
 50
             10
                          for (std::pair<Key, Value> &pair : data)
 51
 52
                              if (pair.first == key)
 53
 54
                                 return &pair.second;
  55
 56
 57
                          // or return nullptr as the search completed without match
 58
                          return nullptr;
 59
 60
                 };
 61
 62
                 } // namespace oarch::containers
 63
                 #endif // __STATIC_MAP_HPP__
```

 Directory: ./
 Exec
 Total
 Coverage

 File: src/i2c_utils.cpp
 Lines:
 0
 41
 0.0 %

 Date: 2022-03-26 23:05:02
 Branches:
 0
 12
 0.0 %

```
Line Branch Exec
                Source
                // MIT License
                // Copyright (c) 2022 Chris Sutton
                // Permission is hereby granted, free of charge, to any person obtaining a copy
                // of this software and associated documentation files (the "Software"), to deal
                // in the Software without restriction, including without limitation the rights
                // to use, copy, modify, merge, publish, distribute, sublicense, and/or sell
  9
                \ensuremath{//} copies of the Software, and to permit persons to whom the Software is
 10
                // furnished to do so, subject to the following conditions:
 11
 12
                // The above copyright notice and this permission notice shall be included in all
 13
                // copies or substantial portions of the Software.
 14
 15
                // THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR
 16
                // IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY,
                // FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE
 18
                // AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER
 19
                // LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM,
                // OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE
                // SOFTWARE.
                #include <i2c_utils.hpp>
                #include <timer manager.hpp>
 26
                namespace stm32::i2c
 28
                 // we can't unit test this without mocking
 29
                Status send_addr(I2C_TypeDef* i2c_handle [[maybe_unused]], uint8_t addr [[maybe_unused]], MsgType type [[maybe_unused]])
 30
 31
                  // Set the master to operate in 7-bit addressing mode. Clear ADD10 bit[11]
 32
                 i2c handle->CR2 = i2c handle->CR2 & ~(I2C CR2 ADD10);
 33
 34
 35
                 // Set the address for the slave device. Set SADD bits[7:1].
 36
                 // The bits SADD[9], SADD[8] and SADD[0] are don't care.
                 i2c_handle->CR2 = i2c_handle->CR2 & ~(I2C_CR2_SADD);
 37
                 i2c_handle->CR2 = i2c_handle->CR2 | (addr << 0);
 38
 39
                 if (type == MsgType::PROBE) // generate START with AUTO-END enabled
 40
 41
                  // Master requests a write transfer
 42
 43
                  i2c_handle->CR2 = i2c_handle->CR2 & ~(I2C_CR2_RD_WRN);
 44
 45
                  // Enable AUTOEND Mode. A STOP condition is automatically sent when NBYTES data are transferred.
 46
                  i2c_handle->CR2 = i2c_handle->CR2 | I2C_CR2_AUTOEND;
 47
 48
 49
                 else if (type == MsgType::WRITE) // generate START with AUTO-END disabled
 50
 51
                   // Master requests a write transfer
 52
                  i2c_handle->CR2 = i2c_handle->CR2 & ~(I2C_CR2_RD_WRN);
 53
 54
                   // Disable RELOAD Mode. The transfer is completed after the NBYTES data transfer (STOP or RESTART follows).
                  i2c_handle->CR2 = i2c_handle->CR2 & ~(I2C_CR2_RELOAD);
 55
 56
                   // Disable AUTOEND Mode. TC flag is set when NBYTES data are transferred, stretching SCL low.
 57
                  i2c_handle->CR2 = i2c_handle->CR2 & ~(I2C_CR2_AUTOEND);
 59
 60
                 else if (type == MsgType::READ) // generate REPEATED START
 63
                   // Master requests a read transfer
 64
                  i2c_handle->CR2 = i2c_handle->CR2 | (I2C_CR2_RD_WRN);
 66
                  // Disable RELOAD Mode. The transfer is completed after the NBYTES data transfer (STOP or RESTART follows).
                  i2c_handle->CR2 = i2c_handle->CR2 & ~(I2C_CR2_RELOAD);
 68
                  // Disable AUTOEND Mode. TC flag is set when NBYTES data are transferred, stretching SCL low.
 69
                  i2c_handle->CR2 = i2c_handle->CR2 & ~(I2C_CR2_AUTOEND);
 70
 71
 72
                  // Generate the restart/start condition
 73
 74
                 generate_start_condition(i2c_handle);
 75
 76
                  // give slave a chance to respond
 77
                 stm32::TimerManager::delay_microsecond(1000);
 78
 79
                  // check if addr was not recognised by slave device
 80
                 if ( (i2c_handle->ISR & I2C_ISR_NACKF) == I2C_ISR_NACKF )
 81
 82
                  return Status::NACK;
```

```
83
                 // otherwise slave device is happy
 84
 85
                return Status::ACK;
 86
 87
 88
 89
 90
 91
               Status receive_byte(I2C_TypeDef* i2c_handle [[maybe_unused]], uint8_t &rx_byte [[maybe_unused]])
 92
 93
                rx_byte = i2c_handle->RXDR & I2C_RXDR_RXDATA;
 94
 95
                return Status::ACK;
 96
 97
 98
 99
100
               Status send_byte(I2C_TypeDef* i2c_handle [[maybe_unused]], uint8_t tx_byte [[maybe_unused]])
101
102
                i2c_handle->TXDR = tx_byte;
103
104
                 // wait for TX FIFO to be transmitted before continuing
                while (((i2c_handle->ISR & I2C_ISR_TXE) == I2C_ISR_TXE) == false)
105
106
                 // do nothing
107
                 stm32::TimerManager::delay_microsecond(10);
108
109
                // check if slave device responded with NACK
110
                if (((i2c_handle->ISR & I2C_ISR_NACKF) == I2C_ISR_NACKF) == true)
111
112
                {
113
                 return Status::NACK;
114
                return Status::ACK;
115
116
117
               void generate_stop_condition(I2C_TypeDef* i2c_handle)
118
119
                i2c_handle->CR2 = i2c_handle->CR2 | (I2C_CR2_STOP);
120
121
122
123
               void generate_start_condition(I2C_TypeDef* i2c_handle)
124
125
                i2c_handle->CR2 = i2c_handle->CR2 | (I2C_CR2_START);
126
127
128
               void set_numbytes(I2C_TypeDef* i2c_handle, uint32_t nbytes)
129
130
                i2c_handle->CR2 = i2c_handle->CR2 & ~(I2C_CR2_NBYTES);
131
                i2c_handle->CR2 = i2c_handle->CR2 | (nbytes << I2C_CR2_NBYTES_Pos);</pre>
132
133
134
               void send_ack(I2C_TypeDef* i2c_handle)
135
136
                i2c_handle->CR2 = i2c_handle->CR2 & ~(I2C_CR2_NACK);
137
138
               void send_nack(I2C_TypeDef* i2c_handle)
139
140
                i2c_handle->CR2 = i2c_handle->CR2 | (I2C_CR2_NACK);
141
142
143
144
               } // namespace stm32::i2c
```

 Directory: ./
 Exec
 Total
 Coverage

 File: src/restricted_base.cpp
 Lines: 0 1 0.0 %

 Date: 2022-03-26 23:05:02
 Branches: 0 0 - %

```
Line Branch Exec Source
                   // MIT License
   2
                   // Copyright (c) 2022 Chris Sutton
   3
   4
   5
                   // Permission is hereby granted, free of charge, to any person obtaining a copy
                   // of this software and associated documentation files (the "Software"), to deal
   6
                   // in the Software without restriction, including without limitation the rights
   8
                   // to use, copy, modify, merge, publish, distribute, sublicense, and/or sell
   9
                   // copies of the Software, and to permit persons to whom the Software is
  10
                   // furnished to do so, subject to the following conditions:
  11
  12
                   // The above copyright notice and this permission notice shall be included in all
  13
                   // copies or substantial portions of the Software.
  14
  15
                   // THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR
  16
                   // IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY,
                   // FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE
  17
  18
                   // AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER
  19
                   // LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM,
  20
                   // OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE
  21
                   // SOFTWARE.
  22
  23
                   #include <restricted_base.hpp>
  24
  25
                   void invalid_allocation_error_handler()
  26
  27
                       #ifdef X86_UNIT_TESTING_ONLY
  2.8
  29
                       #else
  30
                           while(true)
  31
                            {
  32
  33
  34
                       #endif
  35
                   }
  36
  37
  38
  39
                   // void* RestrictedBase::operator new(size_t size [[maybe_unused]]) noexcept
  40
  41
                   // {
                   //
  42
                          while(true)
  43
                   //
                          {
                   //
                               // forbidden
  44
  45
                   //
  46
                   //
                          // just to prevent compiler errors
  47
                   //
                          void *p;
                          return p;
  48
                   //
  49
                   // }
  50
  51
  52
                   // void RestrictedBase::operator delete(void* ptr) noexcept
  53
                   // {
  54
                   //
                           while(true)
                   //
  55
                          {
  56
                   //
                               // forbidden
  57
                   //
  58
                   // }
  59
```

 Directory: ./
 Exec
 Total
 Coverage

 File: src/spi_utils.cpp
 Lines: 0 28 0.0 %

 Date: 2022-03-26 23:05:02
 Branches: 0 18 0.0 %

```
LineBranch Exec Source
                  // MIT License
  1
  2
                  // Copyright (c) 2022 Chris Sutton
  3
  4
  5
                  // Permission is hereby granted, free of charge, to any person obtaining a copy
                  // of this software and associated documentation files (the "Software"), to deal
  6
  7
                  // in the Software without restriction, including without limitation the rights
  8
                  // to use, copy, modify, merge, publish, distribute, sublicense, and/or sell
                  // copies of the Software, and to permit persons to whom the Software is
  9
                  // furnished to do so, subject to the following conditions:
  10
 11
 12
                  // The above copyright notice and this permission notice shall be included in all
                  // copies or substantial portions of the Software.
 14
 15
                  // THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR
 16
                  // IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY,
 17
                  // FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE
 18
                  // AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER
 19
                  // LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM,
 20
                  // OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE
                  // SOFTWARE.
 21
 22
 23
                  #include <spi_utils.hpp>
 2.5
                  #include <timer_manager.hpp>
                  namespace stm32::spi
 26
 27
 2.8
                  void enable_spi(SPI_TypeDef *spi_handle, bool enable)
 29
 30
                  {
                      if (enable)
 31
 32
                      {
                          spi_handle->CR1 = spi_handle->CR1 | SPI_CR1_SPE;
 33
 34
                      }
 35
                      else
 36
                      {
 37
                          spi_handle->CR1 = spi_handle->CR1 & ~SPI_CR1_SPE;
 38
 39
 40
 41
                  void send_byte(SPI_TypeDef *spi_handle, uint8_t byte)
 42
                      volatile uint8_t *spidr = ((volatile uint8_t *)&spi_handle->DR);
  43
 44
                      *spidr = byte;
 45
                      // check the data has left the SPI FIFO
                      while (!stm32::spi::wait_for_txe_flag(spi_handle, 10));
 46
 47
                      while (!stm32::spi::wait_for_bsy_flag(spi_handle, 10));
 48
 49
 50
                  bool wait_for_txe_flag(SPI_TypeDef *spi_handle, uint32_t delay_us)
 51
 52
                      if (spi_handle == nullptr)
 53
 54
 55
                          return false;
 56
 57
                      // The TXE flag is set when transmission TXFIFO has enough space to store data to send.
                      if ((spi_handle->SR & SPI_SR_TXE) != (SPI_SR_TXE))
 58
 59
                           // give TX FIFO a chance to clear before checking again
 60
                          stm32::TimerManager::delay_microsecond(delay_us);
 61
 62
                          if ((spi_handle->SR & SPI_SR_TXE) != (SPI_SR_TXE))
 63
                          {
                              return false;
 64
 65
 66
```

```
68
                     return true;
69
70
                bool wait_for_bsy_flag(SPI_TypeDef *spi_handle, uint32_t delay_us)
71
72
                     if (spi_handle == nullptr)
73
74
                     {
75
                         return false;
76
                    }
                     // When BSY is set, it indicates that a data transfer is in progress on the SPI
77
78
                     if ((spi_handle->SR & SPI_SR_BSY) == (SPI_SR_BSY))
79
80
                         // give SPI bus a chance to finish sending data before checking again
                         stm32::TimerManager::delay_microsecond(delay_us);
81
                         if ((spi_handle->SR & SPI_SR_BSY) == (SPI_SR_BSY))
82
83
                             return false;
84
85
                         }
86
87
                     return true;
88
89
                void set_prescaler(SPI_TypeDef *spi_handle, uint32_t new_value)
90
91
                     \label{eq:spi_handle} $$ spi_handle->CR1 & \sim(SPI_CR1_BR_2 \mid SPI_CR1_BR_1 \mid SPI_CR1_BR_0); $$
92
93
                     spi_handle->CR1 = spi_handle->CR1 | (new_value);
94
95
96
97
                } // namespace stm32::spi
```

 Directory: ./
 Exec
 Total
 Coverage

 File: src/timer_manager.cpp
 Lines: 0 32 0.0 %

 Date: 2022-03-26 23:05:02
 Branches: 0 20 0.0 %

```
Line Branch Exec Source
                   // MIT License
   2
  3
                   // Copyright (c) 2022 Chris Sutton
   4
   5
                   // Permission is hereby granted, free of charge, to any person obtaining a copy
                   // of this software and associated documentation files (the "Software"), to deal
   6
   7
                   // in the Software without restriction, including without limitation the rights
   8
                   // to use, copy, modify, merge, publish, distribute, sublicense, and/or sell
  9
                   // copies of the Software, and to permit persons to whom the Software is
  10
                   // furnished to do so, subject to the following conditions:
  11
  12
                   // The above copyright notice and this permission notice shall be included in all
  13
                   // copies or substantial portions of the Software.
  14
  15
                   // THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR
  16
                   // IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY,
  17
                   // FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE
  18
                   // AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER
  19
                   // LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM,
  20
                   // OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE
  21
                   // SOFTWARE.
  22
  23
                   #include <timer_manager.hpp>
  24
  25
                   namespace stm32
  26
  27
  2.8
                   void delay_millisecond(uint32_t Delay)
  29
  30
  31
                       _IO uint32_t tmp = SysTick->CTRL; /* Clear the COUNTFLAG first */
                      uint32_t tmpDelay; /* MISRAC2012-Rule-17.8 */
  32
                     /* Add this code to indicate that local variable is not used */
  33
  34
                     ((void)tmp);
  35
                     tmpDelay = Delay;
  36
                     /* Add a period to guaranty minimum wait */
  37
                     if (tmpDelay < LL_MAX_DELAY)
  38
  39
                       tmpDelay ++;
  40
  41
  42
                     while (tmpDelay != 0U)
  43
                       if ((SysTick->CTRL & SysTick_CTRL_COUNTFLAG_Msk) != 0U)
  44
  45
  46
                         tmpDelay --;
  47
                       }
  48
                     }
  49
  50
                   void TimerManager::initialise(TIM_TypeDef *timer)
  51
  52
  53
                       // if (m_timer == nullptr) { m_timer = std::unique_ptr<TIM_TypeDef>(timer); }
  54
                       if (m_timer == nullptr) { m_timer = timer; }
  55
                       else { error_handler(); }
  56
                       reset();
  57
  58
  59
                   void TimerManager::reset()
  60
                       // wait in limbo if not initialised
  61
  62
                       if (m_timer == nullptr) { error_handler(); }
  63
  64
  65
                       // ensure the timer is disabled before setup
                       if ( (m_timer->CR1 & TIM_CR1_CEN) == TIM_CR1_CEN )
  66
```

```
68
                          m_timer->CR1 = m_timer->CR1 & ~(TIM_CR1_CEN);
69
                      }
                      // setup the timer to 1 us resolution (depending on the system clock frequency)
70
71
                      m_timer->PSC = SystemCoreClock / 1000000UL;
72
73
                      // allow largest possible timeout
74
                      m_timer->ARR = 0xFFFF-1;
75
76
                      // reset CNT
77
                      m_timer->CNT = 0;
78
79
                      // start the timer and wait for the timeout
                      m_timer->CR1 = m_timer->CR1 | (TIM_CR1_CEN);
80
81
82
83
84
85
                  void TimerManager::delay_microsecond(uint32_t delay_us)
86
                      // wait in limbo if not initialised
87
                      if (m_timer == nullptr) { error_handler(); }
88
89
90
                      // @TODO change the prescaler to allow longer delays, clamp for now
91
                      if (delay_us > 0xfffE) { delay_us = 0xfffE; }
92
93
                      // setup the timer for timeout function
94
                      reset();
95
                      while (m_timer->CNT < delay_us);</pre>
96
                  }
97
98
                  uint32_t TimerManager::get_count()
99
100
                      // make sure timer is running
101
                      if ( (m_timer->CR1 & TIM_CR1_CEN) == TIM_CR1_CEN )
102
                      {
103
                          m_timer->CR1 = m_timer->CR1 | (TIM_CR1_CEN);
104
                      }
105
                      return m_timer->CNT;
106
107
                  }
108
                  void TimerManager::error_handler()
109
110
111
                      while(1)
112
                      {
113
                          // stay here to allow stack trace to be shown in debugger...
114
115
                  }
116
                  } // namespace stm32:
117
```

 Directory: ./
 Exec
 Total
 Coverage

 File: src/usart_utils.cpp
 Lines: 0 20 0.0 %

 Date: 2022-03-26 23:05:02
 Branches: 0 12 0.0 %

```
Line Branch Exec Source
                  // MIT License
   2
  3
                   // Copyright (c) 2022 Chris Sutton
  4
  5
                   // Permission is hereby granted, free of charge, to any person obtaining a copy
                   // of this software and associated documentation files (the "Software"), to deal
  6
                   // in the Software without restriction, including without limitation the rights
  8
                   // to use, copy, modify, merge, publish, distribute, sublicense, and/or sell
  9
                   // copies of the Software, and to permit persons to whom the Software is
  10
                   // furnished to do so, subject to the following conditions:
 11
 12
                  // The above copyright notice and this permission notice shall be included in all
                   // copies or substantial portions of the Software.
  13
 14
 15
                   // THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR
 16
                   // IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY,
 17
                   // FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE
 18
                   // AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER
 19
                   // LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM,
 20
                   // OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE
                   // SOFTWARE.
  21
 22
 23
                   #include <usart_utils.hpp>
  24
 2.5
                   #include <timer_manager.hpp>
 26
                  namespace stm32::usart
  27
 2.8
                  void enable_usart(USART_TypeDef *usart_handle)
 29
 30
                   {
 31
                       usart_handle->CR1 = usart_handle->CR1 | USART_CR1_UE;
  32
 33
 34
                  void transmit_byte(USART_TypeDef *usart_handle, uint8_t byte)
  35
 36
                       usart_handle->TDR = byte;
 37
 38
 39
                  bool wait_for_tc_flag(USART_TypeDef *usart_handle, uint32_t delay_us)
 40
 41
 42
                       if (usart_handle == nullptr)
  43
 44
                           return false;
 45
                       // Check the previous tranmission has completed
  46
                       if ((usart_handle->ISR & USART_ISR_TC) != (USART_ISR_TC))
 47
 48
                       {
 49
                           // if not then wait before checking again
                           stm32::TimerManager::delay_microsecond(delay_us);
 50
  51
                           if ((usart_handle->ISR & USART_ISR_TC) != (USART_ISR_TC))
 52
                           {
 53
                               return false;
  54
 55
 56
  57
 5.8
                       return true;
 59
  60
                  bool wait_for_bsy_flag(USART_TypeDef *usart_handle, uint32_t delay_us)
 61
 62
                       if (usart_handle == nullptr)
 63
 64
                       {
  65
                           return false;
  66
                       // When BSY is set, it indicates that a data transfer is in progress on the USART
```

```
68
                     if ((usart_handle->ISR & USART_ISR_BUSY) == (USART_ISR_BUSY))
69
                     {
70
                          \ensuremath{//} give USART bus a chance to finish sending data before checking again
71
                          stm32::TimerManager::delay_microsecond(delay_us);
                          if ((usart_handle->ISR & USART_ISR_BUSY) == (USART_ISR_BUSY))
72
73
74
                              return false;
75
76
                     return true;
77
78
79
80
                 } // namespace stm32::spi
```

 Directory: ./
 Exec
 Total
 Coverage

 File: tests/catch_bitset_utils.cpp
 Lines:
 86
 86
 100.0 %

 Date: 2022-03-26 23:05:02
 Branches:
 156
 416
 37.5 %

```
LineBranchExec Source
                #include <catch2/catch_all.hpp>
                #include <bitset_utils.hpp>
                #include <byte_utils.hpp>
                /// @brief insert bit pattern starting from zero msb_offset argument
             1 TEST_CASE("insert_bitset_at_offset - zero msb_offset", "[bitset_utils]"
                {
  8
                     const size t target size {8};
                    const size_t source_size{4};
 10
                     std::bitset<target_size> target("00000000");
 11
 12
        ✓ X
                    std::bitset<source_size> source("1111");
 13
 14
                     std::bitset<target_size> expected_output("00001111
        1)
 15
      /X/)
      /X/)
                    REQUIRE(noarch::bit_manip::insert_bitset_at_offset(target, source, 0));
      /XXX
       XX
      /X/)
      1X1)
                    REQUIRE(target == expected_output);
      VXXX
        XX
 18
 19
                     // reset back to 00000000 and check
      /X/)
                    REQUIRE(noarch::bit_manip::insert_bitset_at_offset(target, source.flip(), 0));
      /XXX
       XX
      VXVX
      VXV
                    REQUIRE(target == 0);
      /XXX
        XX
 22
 23
 24
 25
                 /// @brief Insert at -1 offset (wraps around to 65535, which is handled by input checks)
 26
                TEST_CASE("insert_bitset_at_offset - msb_offset wraparound", "[bitset_utils]")
 28
                     const size_t target_size{8};
 29
                    const size_t source_size{4};
 30
                    std::bitset<target size> target("00000000");
 31
 32
                    std::bitset<source_size> source("1111");
 33
 34
                    std::bitset<target_size> expected_output("00001111");
 35
                    std::bitset<target_size> original_target(target);
 36
 37
                     // operation fails, target is not undated
      /X/)
      1X1)
 38
                    REQUIRE_FALSE(noarch::bit_manip::insert_bitset_at_offset(target, source, -1));
      /X/)
      XXXX
      /X/)
      /X/)
 39
                    REQUIRE_FALSE(target == expected_output);
      /X/)
      XXXX
      /X/)
      /X/X
 40
                    REQUIRE(target == original_target);
      /XXX
 41
 42
                /// @brief Insert at offset larger than target bitset
 43
 44
                TEST_CASE("insert_bitset_at_offset - oversized msb_offset", "[bitset_utils]
 45
                {
                     const size_t target_size{8};
 46
 47
                    const size_t source_size{4};
 48
                     std::bitset<target size> target("00000000");
 49
 50
                    std::bitset<source_size> source("1111");
 51
                     std::bitset<target_size> expected_output("00001111");
 52
 53
                    std::bitset<target size> original target(target);
 54
                     // operation fails, target is not undated
 55
      1X1)
                    REQUIRE_FALSE(noarch::bit_manip::insert_bitset_at_offset(target, source, target_size + 1));
      1X1)
```

```
/X/X
                    REQUIRE_FALSE(target == expected_output);
     /X/)
     XXXX
     VXV
     /X/X
                    REQUIRE(target == original_target);
 58
     VXXX
       XX
 59
             1 }
 60
                /// @brief Insert at offset within tolerances for SOURCE to fit within TARGET
 61
 62
             1 TEST_CASE("insert_bitset_at_offset - offset_index_at_limit_for_source_size", "[bitset_utils]")
 63
 64
                    const size_t target_size{8};
 65
                    const size_t source_size{4};
 66
                    const size_t offset_index_at_limit_for_source_size = target_size - source_size;
 67
                    std::bitset<target_size> target("00000000");
 68
 69
       / X
                    std::bitset<source_size> source("1111");
 70
 71
                    std::bitset<target_size> expected_output("11110000");
 72
     /X/)
     1X1)
 73
                    {\tt REQUIRE (noarch::bit\_manip::insert\_bitset\_at\_offset(target, source, offset\_index\_at\_limit\_for\_source\_size));}
     /XXX
     /X/)
     VXV
 74
                    REQUIRE(target == expected_output);
     /XX)
       XX
 75
 76
                    // reset back to 00000000 and check
     1X1)
     /X/X
 77
                    \label{eq:require} \texttt{REQUIRE} (no arch:: bit\_manip:: insert\_bitset\_at\_off set (target, source\_flip(), off set\_index\_at\_limit\_for\_source\_size)); \\
     /XXX
       XX
     1X1)
     1X1)
                    REQUIRE(target == 0);
 78
     /XX)
       XX
 79
 80
 81
                /// @brief Insert at offset that surpasses tolerances for SOURCE to fit within TARGET
 82
             1 TEST_CASE("insert_bitset_at_offset · offset_index_too_large_for_source_size", "[bitset_utils]")
 83
 84
               {
                    const size_t target_size{8};
 85
 86
             1
                    const size_t source_size{4};
 87
                    const size_t offset_index_too_large_for_source_size = target_size-(source_size - 1);
 88
 89
                    std::bitset<target_size> target("00000000");
 90
                    std::bitset<source_size> source("1111");
             1
       / X
 91
                    std::bitset<target_size> expected_output("00001111");
 92
       1)
 93
                    std::bitset<target_size> original_target(target);
 94
 95
                    // operation fails, target is not undated
     /X/X
     /X/X
 96
                    REQUIRE FALSE (noarch::bit manip::insert bitset at offset (target, source, offset index too large for source size));
     /X/X
     XXXX
     /X/)
     /X/)
 97
             1
                   REOUIRE FALSE(target == expected output);
     /X/X
     XXXX
     /X/X
     /X/)
 98
                    REOUIRE(target == original target):
     99
100
                /// @brief SOURCE is too large to fit within TARGET
101
102
             1 TEST_CASE("insert_bitset_at_offset - ", "[bitset_utils]")
103
                {
104
                    const size t target size {8};
105
                    const size_t source_size{9};
106
                    std::bitset<target_size> target("00000000");
107
108
                    std::bitset<source_size> source("1111");
109
110
                    std::bitset<target_size> expected_output("00001111");
       1)
111
                    std::bitset<target size> original target(target);
112
113
                    // operation fails, target is not undated
     /X/)
     1X1)
                    REQUIRE_FALSE(noarch::bit_manip::insert_bitset_at_offset(target, source, 0));
     1X1)
```

```
/X/)
                   REQUIRE_FALSE(target == expected_output);
     /X/)
     XXXX
     VXV
     /X/X
                   REQUIRE(target == original_target);
     /XXX
117
               }
118
119
120
                /// @brief check order is reversed as expected
121
               TEST_CASE("bitset_to_bytearray - check MSB/LSB integrity", "[bitset_utils]")
122
                   std::bitset<16> input_16bits(0xAAAA);
123
124
                   std::array<uint8_t, 2> expected_2byte{0x55, 0x55};
                                                                             // 01010101 01010101
125
                   std::array<uint8_t, 2> output_2byte;
     1X1)
     1X1)
126
                   REQUIRE(noarch::bit_manip::bitset_to_bytearray(output_2byte, input_16bits));
       XX
127
                   // noarch::byte_manip::print_bytes(output_2byte);
                    // noarch::byte manip::print bytes(expected 2byte);
128
     1X1)
129
                   REQUIRE(output_2byte == expected_2byte);
     VXXX
       XX
130
131
                /// @brief Check input bits are truncated if output byte array is too small
132
133
              TEST_CASE("bitset_to_bytearray - param size mismatch: bits > bytes TRUNCATION", "[bitset_utils]")
134
                   std::bitset<8> input_16bits(0xAAAA);
135
                                                                            // 10101010 10101010
136
                   std::array<uint8_t, 1> expected_2byte{0x55};
                                                                       // 01010101 01010101
137
                    std::array<uint8_t, 1> output_2byte;
                   REQUIRE(noarch::bit_manip::bitset_to_bytearray(output_2byte, input_16bits));
138
                   // noarch::byte_manip::print_bytes(output_2byte);
140
                    // noarch::byte_manip::print_bytes(expected_2byte);
     /X/)
141
                   REQUIRE(output_2byte == expected_2byte);
142
143
144
                /// @brief Check input bits are xero-padded if output byte array is too large
145
              TEST_CASE("bitset_to_bytearray - param size mismatch: bytes > bits ZERO PADDING", "[bitset_utils]"
146
               {
                   std::bitset<8> input_16bits(0xAA);
                                                                             // 10101010 10101010
147
                                                                             // 01010101 00000000
148
                   std::array<uint8_t, 2> expected_2byte{0x55, 0x00};
149
                   std::array<uint8_t, 2> output_2byte;
150
                   REQUIRE(noarch::bit_manip::bitset_to_bytearray(output_2byte, input_16bits));
     /XXX
       XX
                   // noarch::byte_manip::print_bytes(output_2byte);
152
                    // noarch::byte_manip::print_bytes(expected_2byte);
153
                   REQUIRE(output_2byte == expected_2byte);
     / X X X
```

Directory: ./		Exec	Total	Coverage
File: tests/catch_byte_utils.cpp	Lines:	8	8	100.0 %
Date: 2022-03-26 23:05:02	Branches:	12	32	37.5 %

```
Line Branch Exec Source
                   #include <catch2/catch_all.hpp>
  3
                   #include <byte_utils.hpp>
  4
                   #include <algorithm>
                TEST_CASE("Empty byte array", "[byte_utils]")
  8
                       std::array<uint8_t, 0> bytes;
      /X/X
      /X/X
  9
                       REQUIRE_FALSE(noarch::byte_manip::print_bytes(bytes));
      /X/X
      XXXX
  10
  11
                   TEST_CASE("Initialised byte array", "[byte_utils]")
  12
  13
  14
                       const size_t array_size{64};
  15
                       std::array<uint8_t, array_size> input_bytes;
  16
                       std::fill(input_bytes.begin(), input_bytes.end(), 10);
        ✓ X
      /X/X
       ✓ X ✓ X
  17
                       REQUIRE(noarch::byte_manip::print_bytes(input_bytes));
       ✓ X X X
  18
```

 Directory: ./
 Exec
 Total
 Coverage

 File: tests/catch_static_map.cpp
 Lines:
 29
 29
 100.0 %

 Date: 2022-03-26 23:05:02
 Branches:
 80
 214
 37.4 %

```
Line Branch Exec
                Source
                #include <catch2/catch all.hpp>
                #include <static map.hpp>
                #include <static_string.hpp>
                using namespace noarch::containers;
   6
                 /// @brief lookup a valid "Key"; must check for nullptr
  8
  9
                TEST_CASE("Static_map - valid lookup", "[static_map]'
  10
  11
  12
                     // an example enum for map "Keys"
                     enum class ExampleKeyType
  15
                         ONE,
                         TWO,
  16
                         THREE,
  18
                         FOUR
  20
                     // an example type for map "Values"
  21
                     struct ExampleValueType
  23
                         // constructor/initialiser
  24
                         {\tt ExampleValueType(int\ int\_value,\ std::string\ string\_value)\ :\ m\_int\_value(int\_value)\ ,\ m\_string\_value(string\_value)}
  25
  26
  27
                             // no action
  28
  29
                         // some integer data member
  30
                         int m_int_value;
  31
                         // some string data member
  32
                         std::string m_string_value;
  33
                    }:
  34
  35
                     // declare our data pair for the map at compile time
                     const int value_for_key_one{100};
  36
  37
             1
                     const int value_for_key_two{200};
  38
                    const int value_for_key_three{300};
  39
                     static std::array<std::pair<ExampleKeyType, ExampleValueType>, 3 > data_set
  40
  41
                           ExampleKeyType::ONE, ExampleValueType(value_for_key_one, "100") },
  42
      /X/X
                           ExampleKeyType::TWO, ExampleValueType(value_for_key_two, "200") },
                         { ExampleKeyType::THREE, ExampleValueType(value_for_key_three, "300") }
  43
      /X/X
      /X/X
  44
        XX
  45
  46
  47
                     // initialise the StaticMap container with our static allocated data set
  48
                     StaticMap<ExampleKeyType, ExampleValueType, data_set.size()> the_map =
  49
                        StaticMap<ExampleKeyType, ExampleValueType, data_set.size()>{{data_set}};
  50
  51
                     // lookup valid key ONE
                     ExampleValueType* res_one = the_map.find_key(ExampleKeyType::ONE);
  52
  53
                     REQUIRE(res_one != nullptr);
      ✓ X X X
       XX
      /X/X
      /X/X
                     REQUIRE(res_one->m_int_value == value_for_key_one);
      ✓ X X X
       XX
      /X/X
      /X/X
  55
                     REQUIRE_FALSE(res_one->m_int_value == value_for_key_two);
      /X/X
      XXXX
      /X/X
      /X/X
  56
                     REQUIRE_FALSE(res_one->m_int_value == value_for_key_three);
      /X/X
  58
                     // lookup valid key TWO
                     ExampleValueType* res_two = the_map.find_key(ExampleKeyType::TWO);
      /X/X
  60
                     REOUIRE(res two != nullptr);
                     REQUIRE(res_two->m_int_value == value_for_key_two);
```

```
/X/X
    /X/X
/X/X
                    REQUIRE_FALSE(res_two->m_int_value == value_for_key_one);
    XXXX
    /X/X
/X/X
/X/X
63
                    REQUIRE_FALSE(res_two->m_int_value == value_for_key_three);
    XXXX
64
65
                    // lookup valid key THREE
                    ExampleValueType* res_three = the_map.find_key(ExampleKeyType::THREE);
66
    /X/X
    /X/X
67
                    REQUIRE(res_three != nullptr);
    ✓ X X X
    /X/X
                    REQUIRE(res_three->m_int_value == value_for_key_three);
68
    ✓ X X X
     XX
    /X/X
    ✓×✓×
✓×✓×
69
                    REQUIRE_FALSE(res_three->m_int_value == value_for_key_one);
    XXXX
    /X/X
    / X / X
/ X / X
70
                    REQUIRE_FALSE(res_three->m_int_value == value_for_key_two);
    XXXX
71
                    // lookup invalid key FOUR
ExampleValueType* res_four = the_map.find_key(ExampleKeyType::FOUR);
72
73
    ✓X✓X
    /X/X
/XXX
74
                    REQUIRE(res_four == nullptr);
      хх
75
76
77
78
```