

Oben angegebenen Systemen gegebenes ungelenk
 gegen Tasse werden wir lösen $\int T_1 dt$

$$T_1 = v_2 (120 v_2^{(1)} \omega^2 \omega^{(1)} - 5 v_2^{(1)} \omega^{(3)} - 16 v_2 \omega^5 - 10 v_2^{(2)} \omega^{(2)} + \\ + 60 v_2 \omega (\omega^{(1)})^2 - 10 v_2^{(3)} \omega^{(1)} + 40 v_2^{(2)} \omega^3 - 5 v_2^{(4)} \omega - v_2 \omega^{(4)} + 40 v_2 \omega^2 \omega^{(2)}) \\ \text{Nagelbuch } \omega = \frac{dt}{v_2}, \text{ wegen}$$

$$T_1 = \frac{4}{v_2^3} \left\{ 6 \dot{v}_2^4 - \frac{14(\dot{v}_2)^2 \ddot{v}_2 v_2 + 20(\dot{v}_2)^2 \dot{v}_2^2}{6} + \frac{7 \dot{v}_2 v_2^2 v_2^{(3)}}{c} + 4(\ddot{v}_2)^2 v_2^2 - \right. \\ \left. - \frac{4 v_2^3 v_2^{(4)}}{a} - 16 \dot{v}_2^4 \right\}$$

$$a: \int v_2^{(4)} dt = v_2^{(3)} \Big| = 0.$$

$$b: \int \frac{\dot{v}_2^2 \ddot{v}_2}{v_2^2} dt = \frac{\dot{v}_2^3}{v_2^2} \Big|_{v_{min}}^{\infty} - \int \dot{v}_2 \left(\frac{2 \dot{v}_2 \ddot{v}_2}{v_2^2} - \frac{2 \dot{v}_2^3}{v_2^3} \right) dt \\ \parallel \frac{2}{3} \int \frac{\dot{v}_2^4}{v_2^3} dt.$$

$$c: \int \frac{\dot{v}_2 v_2^{(4)}}{v_2} = \frac{\dot{v}_2 \ddot{v}_2}{\frac{v_2}{6}} \Big| - \int v_2^{(2)} \left(\frac{v_2^{(4)}}{v_2} - \frac{\dot{v}_2^2}{v_2^2} \right) = \int \frac{\dot{v}_2^2 \ddot{v}_2}{v_2^2} - \frac{(v_2^{(2)})^2}{v_2}$$

$$\int T_1 dt = \int \frac{4}{v_2^3} \left(\frac{4}{3} \dot{v}_2^4 + 20 \dot{v}_2^2 \dot{v}_2^2 + 3 v_2^2 (\ddot{v}_2)^2 - 16 \dot{v}_2^4 \right) dt = \quad dt = \frac{dv_2}{\dot{v}_2}$$

$$= - \int_{v_{min}}^{\infty} \frac{4}{v_2^3} \left(\frac{4}{3} \dot{v}_2^4 + 20 \dot{v}_2^2 \dot{v}_2^2 + 3 v_2^2 (\ddot{v}_2)^2 - 16 \dot{v}_2^4 \right) \frac{dv_2}{\dot{v}_2} =$$

$$= \frac{2}{3} 4 \int_{v_{min}}^{\infty} \frac{25 v_2^2 \dot{v}_2^4 + 28 \dot{v}_2^4 v_2 + 82 v_2^{3/2} \dot{v}_2^2 - 56 \dot{v}_2^4 + 56 \dot{v}_2^2 \sqrt{v_2} + 72 v_2}{v_2^3 \sqrt{4^2 v_2 + 25 v_2 - 4^2}} dv_2.$$