FOREVER MAZE GAME GROUP 20 CHARLES RAGONA, JENNIFER BUSS, MAXWELL DANKU, SAYONTAN ROY

911: WHAT'S YOUR EMERGENCY?

CALLER: HELP, I'M STUCK IN A MAZE AND I CAN'T GET OUT!

GAME DESCRIPTION

• In the Endless Maze game, a maze is displayed on a LED display and a joystick is used to traverse through the maze. Once the end of the maze is reached, a new maze is generated and the game continues.

MICROCHIP PIC24 MICROCONTROLLER

ANALOG 2-AXIS THUMB JOYSTICK WITH SELECT BUTTON + BREAKOUT BOARD

ADAFRUIT NEOPIXEL NEOMATRIX 8X8 - 64 RGB LED PIXEL MATRIX

LCD MODULE

ADAFRUIT 5 V USB BREAKOUT

APPLICATION DEVELOPMENT

- During the first week, two teams were formed to initially develop libraries needed for the game such as a joystick library, a LED library and a maze library of pre-constructed mazes.
- During the second week, the members of the group collaborated to complete the libraries, combine the libraries into the Forever Maze game, and prepare the presentation.

JOYSTICK STRATEGY

- Determine direction of joystick: up/down, left/right
- •Communicate with Maze array to determine:
- •if requested movement is allowed, e.g. no traveling through maze walls, off LED
- •light up square to indicate position of player



JOYSTICK IMPLEMENTATION

- •joystickSetup()
- getJoystickDirection()

LED STRATEGY

- Turn on appropriate LEDs to outline the maze
- Turn on/off LEDs to indicate position of player as player moves through the maze



LED IMPLEMENTATION

- writeColor()
- updateMaze()
 - How it clears

```
;1 code total: 62.5 ns * 20 cycles = 1.25 us
;T1H: 62.5 ns * 12 cycles = 75.0 us
;20 cycles - 12 high 8 low
write 1:
    ; call 2
    bset LATB, #7
                             ; high 1
    repeat #9
                    ; high 1
                    ;high 10
    nop
    bclr LATB, #7
                             :low 1
                    ;low 1
    nop
                    :low 1
    nop
                    ;low 3 + 2 for call
    return
;0 code total: 62.5 ns * 20 cycles = 1.25 us
;TOH: 62.5 ns * 6 cycles = .375 us
write 0:
    ; call 2
    bset LATB, #7
                             ; high 1
    repeat #3
    nop
                             ;low 1
    bclr LATB, #7
    repeat #6
                    ;low 1
                     :10w 7
    nop
                    ;low 3 + 2 for call
    return
```

```
#include "bitBangHead.h"
     //bit shifts right 1 bit, takes remainder of that which is our binary bit starting
     //from the most significant position, checks this bit and writes in the order of
     //rbg colors from R --> G --> B
     void writeColor(int r, int g, int b)
         if(r >= 0 && r <= 255 && g >= 0 && g <= 255 && b >= 0 && b <= 255)
             int shift = 7;
10
             int count = 8;
             while(count > 0)
                 if( (r >> shift) % 2 == 1)
14
                     write_1();
                 else
                     write_0();
                 count --;
                 shift--;
28
             shift = 7;
             count = 8;
             while(count > 0)
                 if( (g >> shift) % 2 == 1)
                     write_1();
                 else
                     write_0();
                 count --;
                 shift--;
             shift = 7;
             count = 8;
             while(count > 0)
                 if( (b >> shift) % 2 == 1)
                     write_1();
                 else
                     write_0();
                 count--;
                 shift--;
             //oneMilliSec();
46
47 }
```

```
heckPlayer(int direction)
left = 3, up = 2, right = 1, down = 4, center = 5
ayerPrevRow = playerRow; //pass position to previous
ayerPrevCol = playerCol;
itch(direction)
  case 1://right
     if(playerCol == 7)//out of bounds
         break;
     else if(maze[playerRow][playerCol + 1] == 1) //wall
         break;
     else
         playerCol++; //move right
     break;
                                                                        void updateMaze(int direction)
  case 2://up
  if(playerRow == 0)//out of bounds move
     break;
  else if(maze[playerRow - 1][playerCol] == 1)//wall
     break;
                                                                             checkPlayer(direction);
 else
     playerRow--; //move up
 return;
                                                                             maze[playerPrevRow][playerPrevCol] = 0;
  case 3://left
     if(playerCol == 0)//out of bounds move
                                                                             maze[playerRow][playerCol] = 8;
         break:
     else if(maze[playerRow][playerCol - 1] == 1)//wall
         break;
     else
         playerCol--; //move left
     break;
  case 4://down
     if(playerRow == 7)
     else if(maze[playerRow + 1][playerCol] == 1)
         break;
     else
         playerRow++; //move down
     break;
  default: //5 - center
     break;
```

MAZE STRATEGY

 Choosing between mazes constructed by an algorithm and pre-constructed mazes

MAZE IMPLEMENTATION

- •mazeSetup()
- writeMaze()

```
heckPlayer(int direction)
left = 3, up = 2, right = 1, down = 4, center = 5
ayerPrevRow = playerRow; //pass position to previous
ayerPrevCol = playerCol;
itch(direction)
  case 1://right
      if(playerCol == 7)//out of bounds
          break;
      else if(maze[playerRow][playerCol + 1] == 1) //wall
          break;
      else
          playerCol++; //move right
      break;
  case 2://up
  if(playerRow == 0)//out of bounds move
      break;
  else if(maze[playerRow - 1][playerCol] == 1)//wall
      break;
  else
      playerRow--; //move up
  return;
  case 3://left
      if(playerCol == 0)//out of bounds move
          break;
      else if(maze[playerRow][playerCol - 1] == 1)//wall
          break;
      else
          playerCol--; //move left
      break;
  case 4://down
      if(playerRow == 7)
          break;
      else if(maze[playerRow + 1][playerCol] == 1)
          break;
      else
          playerRow++; //move down
      break;
  default: //5 - center
      break;
```

PROJECT DEMONSTRATION

Conclusion

References

- joystick tutorial (https://www.sparkfun.com/tutorials/272)
- Section 17. 10-Bit A/D Converter Manual from Microchip
- WS2812 Intelligent control LED integrated light source datasheet