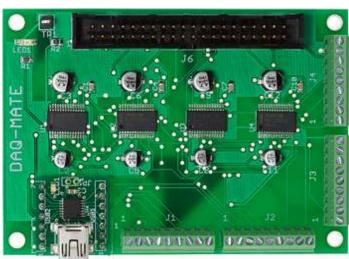
EMBEDDED TEST SOLUTIONS

DAQ-MATE

32-CH DATA ACQUISITION MODULE





USER'S MANAUAL



NOTICE

The information contained in this document is subject to change without notice. To the extent allowed by local law, Overton Instruments (OI), shall not be liable for errors contained herein or for incidental or consequential damages in connection with the furnishing, performance, or use of this material. No part of this document may be photocopied, reproduced, or translated to another language without the prior written consent of OI.

WARNING

The instrument you have purchased and are about to use may be NOT an ISOLATED product. This means that it may be susceptible to common mode voltages that could cause damage to the instrument. SUCH DAMAGE IS NOT COVERED BY THE PRODUCT'S WARRANTY. Please read the following carefully before deploying the product. Contact OI for all questions.

WARRENTY

OI warrants that this instrument will be free from defects in materials and workmanship under normal use and service for a period of 90 days from the date of shipment. OI obligations under this warranty shall not arise until the defective material is shipped freight prepaid to OI. The only responsibility of OI under this warranty is to repair or replace, at it's discretion and on a free of charge basis, the defective material. This warranty does not extend to products that have been repaired or altered by persons other than OI employees, or products that have been subjected to misuse, neglect, improper installation, or accident. OVERTON INSTRUMENTS SHALL HAVE NO LIABILITY FOR INCIDENTAL OR CONSEQUENTIAL DEMAGES OF ANY KIND ARISING OUT OF THE SALE, INSTALLATION, OR USE OF ITS PRODUCTS.

SERVICE POLICY

- 1. All products returned to OI for service, regardless of warranty status, must be on a freight-prepaid basis.
- OI will repair or replace any defective product within 10 days of its receipt.
- 3. For in-warranty repairs, OI will return repaired items to buyer freight prepaid. Out of warranty repairs will be returned with freight prepaid and added to the service invoice.

Table Of Contents

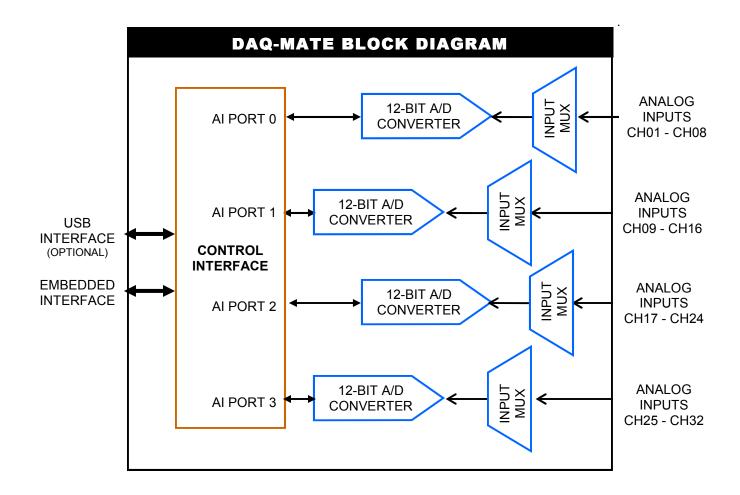
1.0 INTRODUCTION	4
1.1 Overview	4
1.2 Highlights	5
1.3 Specifications	6
2.0 DESCRIPTION	7
2.1 Hardware Details	7
2.2 Board Layout	8
2.3 Connections	9
3.0 OPERATION	11
3.1 Embedded Control	11
3.1.1 Embedded Configuration	12
3.1.2 Embedded Programming	13
3.1.3 Embedded Program Example	14
3.2 PC Control	15
3.2.1 PC Programming	16
3.2.1.1 HyperTerminal	16
3.2.1.2 Virtual Instrument Panel	17
3.2.1.3 PC Programming Example	18
APPENDIX A. SERIAL COMMAND SET	19
APPENDIX B. SCHEMATIC	20
APPENDIX C. MECHANICAL DIMENSIONS	21

1. Introduction

1.1 Overview

The DAQ-MATE offers an impressive 32-channels of analog data acquisition, including 12-bit resolution (and a sample rate of 100ksps). In addition each channel can be independently programmed for either single-ended or differential operation, and 4 different input ranges (0-5V, 0-10V, ± 5 and ± 10 V).

The DAQ-MATE is made available is two versions, a standard model or with a USB option. The standard model is designed for embedded applications and provides a simple SPI-bus interface for control by a external microcontroller. With the USB option, many test solutions can be quickly built by connecting the DAQ-MATE to a PC laptop or desktop, and then running our GUI software. No external power source is required, since power is supplied through the USB interface. Any either case, easy access to the hardware is made available through a convenient collection of screw terminal connectors.



1.2 Highlights

BENEFITS	APPLICATIONS	FEATURES
 A flexible, low-cost alternative to expensive PC-based DAQ cards Quickly measure a wide array of analog signals. Each analog channel can be independently programmed for 4 different range modes Great for embedded solutions - place inside mechanical test fixtures, instrument boxes or rack-mount enclosures 	 Burn-In Engineering Depot Repair Production Test QA/QC Quality Control OEM Test Instruments 	 32 12-bit A/D channels 100Ksps sample rate Programmable Single/ Differential 4 Programmable Input Ranges (0-5V, 0-10V, ±5V and ±10V) USB interface or embedded control Low Cost Compact size, a 2.5" x 3.5" PCB, with four #4 mounting holes in each corner (spacers and hardware included)

1.3 Specifications

Analog Inputs	
Number of inputs	32, 12-bit, single/differential
Input Ranges	0-5V, 0-10V, ±5V, ±10V programmable
Max Sample Rate	100ksps
Nonlinearity	±1LSB, no missing codes
Input Control	
Embedded	SPI-bus & control logic
USB Interface	Optional USB module
General	
Power Supply	+5VDC±10%@30mA
Operating Temp	0-50°C
Dimensions	2.5" x 3.5"

2. Description

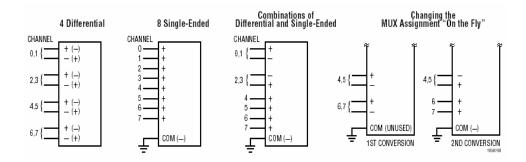
2.1 Hardware Details

Access to DAQ-MATE hardware is made possible through a convenient set of screw terminal connections (J1 - J4), and J6 (which consolidates all signals into a single 40-pin header).

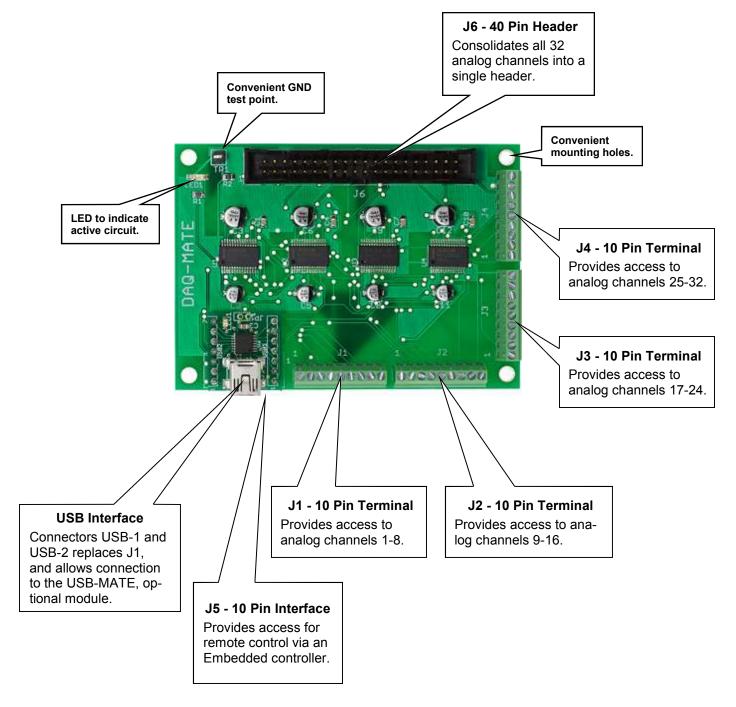
The analog inputs (or channels) can be programmed for any combination of single-ended or differential operation. The diagram below shows examples of various configurations. You will also note the polarity of connections related to differential operation can be transposed as well. Each channel can be programmed for anyone of 4 different range modes (i.e., 0-5V, \pm 5, 0-10V and \pm 10V). Keep in mind, the circuit provides \pm 25V protection on each channel.

External control of the DAQ-MATE can be provided by a embedded controller (such as the Micro-MATE), or with a PC. Embedded control is supported by J1 (Oi-BUS interface), which is a 10-pin header that includes a 3-wire SPI-bus, chip select logic, power and ground. In PC applications, connector J5 is replaced with the USB-MATE. The USB-MATE contains a USB connector (for the PC), and a dual set of 7-pin headers that mount to the DAQ-MATE. The USB-MATE is designed to interpret a set of ASCII commands sent from the PC, and then perform various DAQ-MATE functions. For more information for the DAQ-MATE command set, go to Appendix A. To support embedded applications, a complete driver for the DAQ-MATE is provided in TES-MATE (or Test Executive Suite).

After power is applied to the DAQ-MATE, the analog inputs are configured for single-ended (0-5V range).



2.2 Board Layout



2.3 Connections

J1				
Pin	Name	Dir.	Description	
1	Port0-0	ı	Input CH 1	
2	Port0-1	ı	Input CH 2	
3	Port0-2	I	Input CH 3	
4	Port0-3	I	Input CH 4	
5	Port0-4	I	Input CH 5	
6	Port0-5	ı	Input CH 6	
7	Port0-6	ı	Input CH 7	
8	Port0-7	ı	Input CH 8	
9	AGND		Analog Ground	

	J2				
Pin	Name	Dir.	Description		
1	Port1-0	ı	Input CH 9		
2	Port1-1	- 1	Input CH 10		
3	Port1-2	ı	Input CH 11		
4	Port1-3	ı	Input CH 12		
5	Port1-4	ı	Input CH 13		
6	Port1-5	ı	Input CH 14		
7	Port1-6	ı	Input CH 15		
8	Port1-7	I	Input CH 16		
9	AGND		Analog Ground		

J3				
Pin	Name	Dir.	Description	
1	Port2-0	I	Input CH 17	
2	Port2-1	ı	Input CH 18	
3	Port2-2	ı	Input CH 19	
4	Port2-3	I	Input CH 20	
5	Port2-4	ı	Input CH 21	
6	Port2-5	ı	Input CH 22	
7	Port2-6	I	Input CH 23	
8	Port2-7	ı	Input CH 24	
9	AGND		Analog Ground	

J4				
Pin	Name	Dir.	Description	
1	Port3-0	ı	Input CH 25	
2	Port3-1	ı	Input CH 26	
3	Port3-2	I	Input CH 27	
4	Port3-3	ı	Input CH 28	
5	Port3-4	ı	Input CH 29	
6	Port3-5	I	Input CH 30	
7	Port3-6	ı	Input CH 31	
8	Port3-7	I	Input CH 32	
9	AGND		Analog Ground	

2.2 Connections cont.

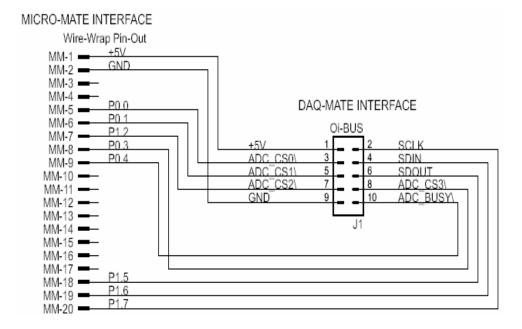
		J5	
Pin	Name	Dir.	Description
1	VCC		A regulated +5Vdc output for external use. Current limited to roughly 100mA.
2	SCLK	I	Part of a 3-wire SPI-Bus, SCLK synchronizes the serial data transfer for the DIN and DOUT signals.
3	ADC_CS0	ı	A TTL active-low "input' signal that provides a chip-select for the ADC, Port 0.
4	DIN	ı	Part of a 3-wire SPI-Bus, DIN is serial command and control data for the, ADC ports.
5	ADC_CS1	ı	A TTL active-low "input' signal that provides a chip-select for the ADC, Port 1.
6	DOUT	0	Part of a 3-wire SPI-Bus, DOUT is serial output data from the ADC and DIO circuits.
7	ADC_CS2	ı	A TTL active-low "input' signal that provides a chip-select for the ADC, Port 2.
8	ADC_CS3	I	A TTL active-low "input' signal that provides a chip-select for the ADC, Port 3.
9	DGND		Digital Ground
10	BUSY\	0	A TTL active-low "output' signal that indicates the ADC is busy.

3. Operation

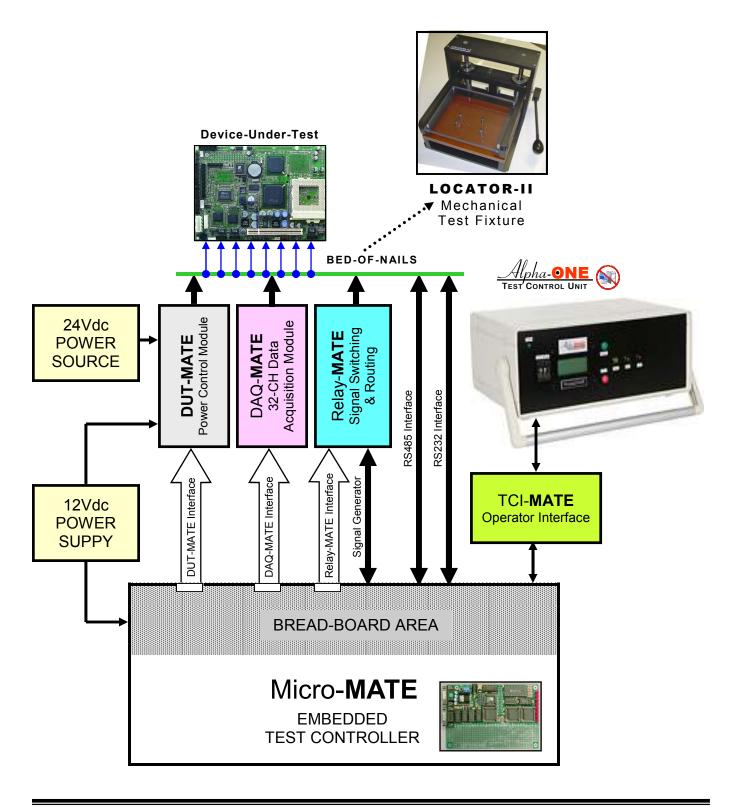
3.1 Embedded Control

In section 3.1.1 (on the next page), the DAQ-MATE is shown integrated with other ETS Series components that collectively form a complete Embedded Test Solution. The diagram shows the DAQ-MATE being driven by the Micro-MATE. The Micro-MATE is a low-cost "Embedded Test Controller", which stores a special program that is designed to exercise the device-under-test and generate Go/No-Go test results. The Micro-MATE also provides a sizable breadboard area to support the development of custom circuits. Adjacent to the breadboard area is a series of wire-wrap pins that comprise a goodly amount of general purpose Digital I/O. The schematic below shows the wire-wrap connections which create the interface between the Micro-MATE and the DAQ-MATE (J1, 10-pin header connector).

Actually the DAQ-MATE can be easily driven by most microcontrollers (including an ARM, AVR, PIC or even a STAMP). When developing an interface for the DAQ-MATE, it is recommended the designer start-by reviewing the interface requirements as outlined in the J1 Table (which is provided in the I/O Description section). The next step is to review the DAQ-MATE schematic, which is provided in Appendix A. What could be the most challenging aspect of the design effort is controlling the SPI-bus devices. The DAQ-MATE contains 4 SPI-bus devices which are exactly the same analog-to-converter chip. The ADC is a 12-bit 8-channel data acquisition IC from Linear Technology (part number LTC1857). Details for specific device performance and SPI-bus operation can be found in the data sheet. Go to the manufacturers website to download said documents.



3.1.1 Embedded Configuration



3.1.2 Embedded Programming

To build-on the PCB board test example (shown in section 3.1.1), we have constructed a demo program using BASCOM. BASCOM is a BASIC language compiler that includes a powerful Windows IDE (Integrated Development Environment), and a full suite of "QuickBASIC" like commands and statements. The demo program (which is outlined in section 3.2.3), illustrates the ease of controlling the DAQ-MATE via the Micro-MATE microcontroller.

The program starts by initialing the Micro-MATE for proper operation. You will note that the BASCOM software provides excellent bit-manipulation capabilities, as evident by the use of the ALIAS statement. The Micro-MATE (P0 & P1 port bits) are assigned unique label names (i.e., SCLK, DOUT), which are used to support various DAQ-MATE functions. In the "Main" program section, the Micro-MATE receives "high level" serial commands from a host PC, parses them and then executes accordingly. When (for example), the "DQ_CC17S01" command is entered, the program selects analog channel number 17 ('S' for single-ended, '0' for +/- polarity, and '1' for 5V range. Finally, when command "DQ_RV?" is entered, the program call's subroutine "Daq_rd_adc(chk_adc_val , Daq_ch , Daq_adc_range)". This causes the DAQ-MATE to take an analog measurement and return the results in a 4 character hexadecimal "ASCII" string.

Independent of the microcontroller hardware or programming language you choose, the program sequence described above will likely resemble the way you implement your DAQ-MATE application. For this reason, we suggest that you go to our website and download the "DAQ-MATE.zip" file. In the Documents folder will contain more extensive examples of routines to control the DAQ-MATE.

3.1.3 Embedded Program Example

```
Program: DAQ-MATE Demo
 ---[ Initialization ]-
$large
 $romstart = &H2000
 $default Xram
Dim Daq_adc_word As Word Dim Daq_adc_val As Single
Dim A_num, A_byte, A_cnt As Byte
Dim A_num, A_byte, A_cnt As Byte
Dim Daq_ch, Daq_adc_range, Daq_num, Daq_cnt, Daq_dev, Daq_cntl-byte As Byte
Dim S As String * 10, A_resp AS String * 10, A_str AS String * 10
Dim S{_str AS String * 1, Sf_str AS String * 10
Dim A_word as Word
Dim A_val as Single
Dim Tay As Const 1
Dim True As Const 1
Dim False As Const 0
Sclk Alias P1 7
                                                   SPI-bus serial clock
 Dout Alias P1.6
                                                   SPI-bus serial data output
Din Alias P1.5
                                                   SPI-bus serial data input
Daq _adc_0cs Alias P0.0
                                                   ADC port0 chip select, active low
 Daq _adc_1cs Alias P0.1
                                                   ADC port1 chip select, active low
Daq_adc_2cs Alias P0.2
Daq_adc_3cs Alias P0.3
                                                   ADC port2 chip select, active low ADC port3 chip select, active low
Daq_busy Alias P0.4
                                                   ADC busy, active low input
Declare Sub Print_ic
                                                   print invalid command
Declare Sub Print orr
                                                   print out-of-range
 Declare Sub Print ur
                                                   print under range
Declare Sub Print_ok
                                                    print command is OK
Declare Sub Daq_rd_adc(daq_adc_val As Single , Daq_ch As Byte , Daq_adc_range As
' In the Main the Operator or Host, is prompted to enter a command. The command is
parsed and then executed if valid. Only two command examples are shown.
 Set Sclk, Dout, Daq_adc_0cs, Daq_adc_1cs, Daq_adc_2cs, Daq_adc_3cs Do
   Print
  Err_trap = False
Input "-> " , S Noecho
S = Ucase(s)
  A_num = Len(s)
If A num > 0 Then
    Select Case A_resp
         Case "CC":
                                       'Configure ADC channel
            A_resp = Mid(s , 6 , 1)
           If A_resp = "?" Then
    Print "<" ; Daq_conf_code ; ">"
              A_resp = Mid(s , 6 , 2)
A_ch = Val(a_resp)
              If A_ch > 32 Then Err_trap = True
A char = Mid(s, 8, 1)
              If A_char <> "D" And A_char <> "S" Then
                Err_trap = True
                If A_char = "D" Then Daq_mux_mode = 0
If A_char = "S" Then Daq_mux_mode = 1
              A_char = Mid(s , 9 , 1)

If A char <> "0" And A char <> "1" Then
                Err_trap = True
              Else
                If A char = "0" Then Dag mux pol = 0
              If A_char = "1" Then Daq_mux_pol = 1
End If
              If A_ch > 4 And A_ch < 9 Then
              If Daq_mux_mode = 0 Then Err_trap = True
Elseif A ch > 12 And A ch < 17 Then
              If Daq_mux_mode = 0 Then Err_trap = True
Elseif A_ch > 20 And A_ch < 25 Then
                If Daq_mux_mode = 0 Then Err_trap = True
              Elseif A_ch > 28 And A_ch < 33 Then
If Daq_mux_mode = 0 Then Err_trap = True
               A char = Mid(s , 10 , 1)
              A_num = Val(a_char)
              If A_num < 1 Or A_num > 4 Then Err_trap = True
              If Err trap = False Then
                 If A_num = 1 Then Daq_range = Daq_adc_5v
                If A_num = 2 Then Daq_range = Daq_adc_5v5v
```

```
If A_num = 3 Then Daq_range = Daq_adc_10v

If A_num = 4 Then Daq_range = Daq_adc_10v10v

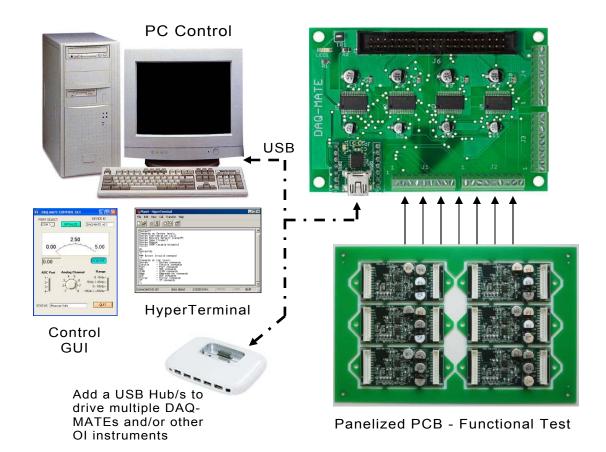
If Daq_mux_mode = 1 Then
                Daq_ch = Daq_ch_buf(a_ch)
                                                       ' set single-ended ch
                Daq_ch = Daq_ch_buf_d(a_ch) 'set differential-ended ch
Daq_ch.6 = Daq_mux_pol 'set polarity (+/-)
               End If
               Daq_conf_code = Mid(s, 6, 5) 'set configuration code
               Call Print_ok
             Fise
               Call Print oor
             End If
          Fnd If
        Case "RV":
                                    ' read voltage
          A_resp = Mid(s , 6 , 1)
If A resp = "?" Then
            Call Daq_rd_adc(daq_word , Daq_ch , Daq_range)
If Daq_word > 4095 Then
               Call Print oor
             Else
               A_str = Str(daq_word)
Print "<" ; A_str ; ">"
             End If
           Else
             Call Print_ic
                                   ' invalid command
          End If
        Case Else
         Call Print_ic
                                   'invalid command
        End Select
    Else
      Call Print_ic
                                  ' invalid command
    End If
 End If
Loop
'---[ Sub-Routines]-
   Daq_val = &H0000
    Daq_num_2 = Daq_ch
                                           ' Select analog channel
    If Daq_ch < 9 Then
      Daq_dev = 0
    Elseif Daq_ch => 9 And Daq_ch <= 16 Then
      Daq_num = Daq_ch - 8
      Daq_dev = 1
    Elseif Daq_ch => 17 And Daq_ch <= 24 Then
      Daq_num = Daq_ch - 16
      Daq_dev = 2
    Elseif Daq_ch => 25 And Daq_ch <= 32 Then
Dag_num = Daq_ch - 24
   Daq_dev = 3
End If
    Daq_ch = Daq_ch_buf(daq_num)
    Daq_cntl_byte = Daq_range Or Daq_ch While Daq_busy = 0
                                                               ' check busy flag
    Wend
    Reset Sclk
    For Daq_cnt = 1 To Daq_m_cnts
Dag_word = 0
                                                       ' take X measurements
      If Daq_dev = 0 Then Reset Daq_adc_cs0
                                                                  ' assert low using alias port pin
      If Daq_dev = 1 Then Reset Daq_adc_cs1
If Daq_dev = 2 Then Reset Daq_adc_cs2
      If Daq_dev = 3 Then Reset Daq_adc_cs3
For Daq_cnt = 15 Downto 0
If Daq_cnt >= 8 Then
                                                              ' transceive serial data
          Daq_num = Daq_cnt - 8
          Dout = Daq_cntl_byte.daq_num
        End If
        Set Sclk
        Delay
        Daq_word = Din
        Delay
        Reset Sclk
      Next Daq_cnt
Set Daq_adc_cs0
                                               ' assert high using alias port pin
      Set Daq_adc_cs1
Set Dag adc cs2
      Set Daq_adc_cs3
   Next Daq_cnt
Daq_val = Daq_val / Daq_m_cnts
                                                         ' compute average
Daq_ch = Daq_num_2
End Sub
```

3.2 PC Control

For those who are more comfortable building traditional PC-based "Automated Test Equipment" (ATE), the DAQ-MATE offers many features that are well suited for that environment as well.

Controlling the DAQ-MATE from a PC, requires that it be equipped with an optional USB-MATE module. The USB-MATE module contains a USB bridge-chip and a PIC microcontroller. On the PC side, the USB bridge-chip receives a special set of serial commands. On the DAQ-MATE side, the PIC controller processes the serial commands and then drives the DAQ-MATE accordingly. In order to be recognized by the PC, the USB-MATE module requires a set of Windows' drivers be installed. To do so, go to "www.DAQ-MATE.info", click "Download", select the "OI VCP Interface" file and follow the prompts. The letters VCP stands for "Virtual COM Port", and is a method by-which the USB interface can appear to the PC as a standard serial COM port. With the drivers installed and the USB-MATE connected to the PC, go to the Device Manager (click on Ports) and verify "OI Serial Interface (COM#)" is included.

The diagram below provides a basic illustration of a PC-driven configuration. As shown, the DAQ-MATE is used to perform a quick "Acceptance" test by collecting analog measurements from a full panel of PCBs.

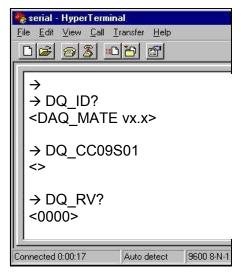


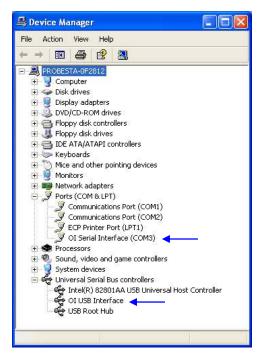
3.2.1 PC Programming

The starting point for developing code to control the DAQ-MATE, begins with acquainting yourself with its Serial Command Set. The serial commands are a set (or group) of ASCII characters that originate from the PC and are designed to instruct the DAQ-MATE to perform specific functions. The complete serial command set is detailed in Appendix B. There are two ways to exercise the serial commands, (1) using HyperTerminal or (2), run our Virtual Instrument Panel software (GUI Control).

3.2.1.1 HyperTerminal

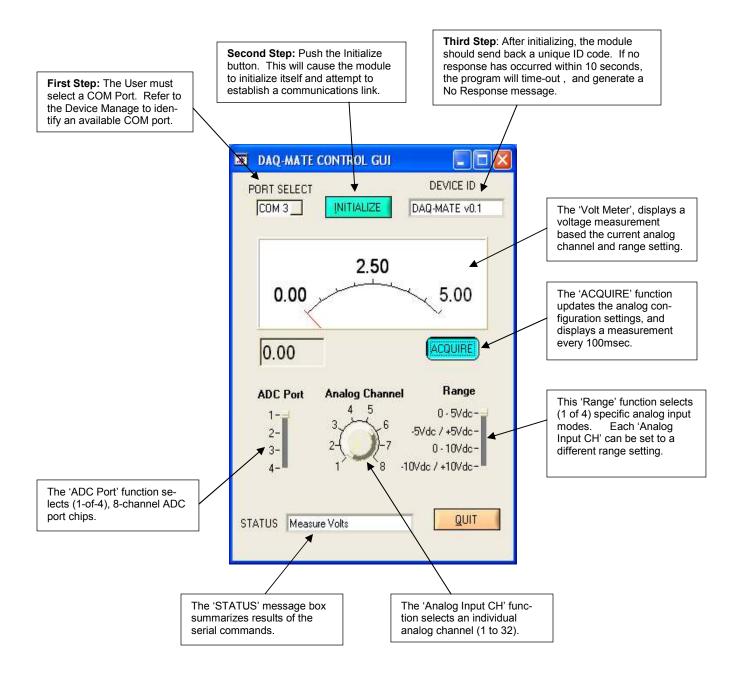
HyperTerminal is a serial communications program that comes with the Windows OS and is located in the Accessories folder. Use the USB cable to connect the PC to the DAQ-MATE. Run HyperTerminal and configure the settings for 19200 bps, 8 data bits, no parity, 1 stop bit and no flow control. Select the COM port based on the available COM port as indicated in the Device Manager (example shown below). Press the 'Enter' key and the '→' prompt should appear on the screen (as demonstrated in the example on the right). Refer to the table in Appendix B, to begin to experiment with the serial commands.





3.2.1.2 Virtual Instrument Panel

The Virtual Instrument Panel (or Control GUI), removes the hassle of "manually "typing ASCII commands and provides the User a more efficient method to interact and control the DAQ-MATE. Download the panel from our website at www.check-mate.com, click on downloads and select "DAQ-Matexxx.exe".



3.2.1.3 PC Programming Example

```
// DAQ-MATE programming example in 'C'
// The following program tests an array of 16 multi-color LED's. Each LED // can produce Red, Green and Blue light. The objective of test is to
// measure each LED for color & intensity, and save the results to a file.
// Sixteen sensors are used to convert the LED light to an analog voltage.
// Each LED sensor provides two outputs (a 0-5Vdc for color and a 0-10Vdc
// for intensity). The outputs of the LED sensors are connected to the DAQ-
// MATE's 32 analog channels. The DIO-MATE (a 48-bit digital I/O module)
// is used to turn-On/Off the individual LEDs. The test sequence involves
// selecting an analog channel, turning-On the LED, measuring color &
// intensity, and then save the results and repeat the cycle.
#define
                 MSWIN
                                                    // serial comm libraries from
                 MSWINDLL
                                                   // www.wcscnet.com
#define
#include <comm.h>
#include <stdlib.h>
 #include <stddio.h>
int stat, port=0, dq_port=0, io_port-0, a_byte = 0, True;
int a_cnt = 0, a_ch = 0, idx = 0, first_shift, dio_bit[10] = 0, False;
char a_str[10], a_str_1[10], a_str_2[10];
char dio_byte[10], dir_byte[10];
char send_data[64], read_data[64];
char dg get id[] = "DQ ID?"
                                                                     // get module ID
char dq_get_idj = 'DQ_iD';

char dq_master_clr[] = "DQ_MC";

char set_adc_ch[] = "DQ_CC";

char get_adc_volts[] = "DQ_RV?";
                                                                     // set master clear
                                                                     // set ADC channel
                                                                     // read voltage
                                                                     // set DIO port direction
char set dio dir[] = "IO PD"
char set_dio_bort[] = "IO_PD";
char set_dio_byte[] = "IO_PB";
char io_get_id[] = "IO_ID?";
                                                                     // set DIO port number
                                                                    // set DIO byte, write
// get module ID
char io_master_clr[] = "IO_MC";
                                                                    // set master clear
main()
    dq_port=OpenComPort(1,256,64); // Open COM 1 - DAQ-MATE
    dq_port=OpenComPort(1,256,64);
for (a_cnt = 0; a_cnt <= 1; a_cnt++) {
    if (a_cnt == 0) port = dq_port;
    if (a_cnt == 0) port = dq_port;</pre>
                                                   // Open COM 2 - DIO-MATE
        if ((stat = SetPortCharacteristics(port,BAUD19200,PAR_EVEN,
            LENGTH_8,STOPBIT_1,PROT_NONNON)) != RS232ERR_NONE) {
            printf("Error #%d setting characteristics\n",stat);
        CdrvSetTimerResolution(port,1); // 1 msec ticks
        SetTimeout(port,2000);
FlushReceiveBuffer(port);
                                                   // 2000 ticks = 2 sec time-out period
// clear receiver buffer
        FlushTransmitBuffer(port);
                                                   // Get device prompt
        sprintf (send_data, "%s\r", "");
        printf("Time-out error\n");
            exit();
         if (strcmp("-> ", read_data)) {
            printf("Incorrect promt\n");
            exit();
                                   // Master Clear
         If (a_cnt == 0) sprintf (send_data, "%s\r", dq_master_clr);
If (a_cnt == 1) sprintf (send_data, "%s\r", io_master_clr);
         PutString(port,send_data);
    }
// Configure DIO-MATE, port direction
sprintf (a_str, "%s\r", "00000000"); // output direction
for (a_cnt = 0; a_cnt <= 5; a_cnt++) {
    sprintf (send_data, "%s%d\r", set_dio_port, a_cnt);
}
        Spiriti (Serid_adat, %s/wui , set_dio_poit, a_dii), PutString(io_port,send_data); sprintf (send_data, "%s/sws\", set_dio_dir, a_str); PutString(io_port,send_data); sprintf (send_data, "%s/sws\", set_dio_byte, a_str); PutString(io_port,send_data);
```

```
a_ch = 1;
first shift = False;
     for (a_cnt = 1; a_cnt <= 16; a_cnt++) {
          idx = 0;
              { // Measure LED color & intensity and store to file.
a num = 0;
              Shift_dio(); // select LED sprintf (file_name, "%s","C:\\LEDTEST.TXT"); fp=fopen(file_name, "a+");
                    \frac{1}{if (a_num == 0) sprintf (a_str, "%s\r", "S01");// 0-5\/dc, single-ended if (a_num == 1) sprintf (a_str, "%s\r", "S03");// 0-10\/dc, single-ended sprintf (send_data, "%s\%02d\%s\r", set_adc_ch, a_cnt, a_str);
                    Splint (Serid_data, %s/w/20/%sii , set_auc_dii, a_sti),
PulString(dq_port,send_data);
SetString(dq_port,send_data);
GetString(dq_port,sizeof(read_data),read_data);
if (a_num == 0) sprintf(a_str_1, "%s", read_data); // get color
if (a_num == 1) sprintf(a_str_2, "%s", read_data); // get intensity
                     a_num++;
                     a ch++;
              } while (a num < 2):
              sprintf(a_str, "LED# %d - %s%s\r\n", a_cnt, a_str_1, a_str_2);
              fprintf(fp, a_str);
              fclose(fp);
              idy++
        } while (idx < 3);
    printf ("Test Complete\r\n"):
                    // Shift a logic '1' through 48 bits
void Shift dio(void) {
     int dio_bit_cnt, dio_bit_num, dio_idx, dio_port;
     char dio bits[50];
    If (first_shift==False) {
          sprinf (dio_bits, "%s'
                      first shift = True;
         for (dio_bit_cnt = 47; dio_bit_cnt >=1; dio_bit_cnt-) {
    if (dio_bits[dio_bit_cnt] == '1') {
                   dio_bits[dio_bit_cnt] = '0';
                   dio_bits[dio_bit_cnt-1] = '1';
    dio_bit_num = 47;
for (dio_port = 0; dio_port <= 5; dio_port++) {
    for (dio_idx = 7; dio_idx >= 0; dio_idx--) {
                                                                                    // extract DIO byte
              dio_byte[dio_idx] = dio_bits[dio_bit_num];
dio_bit_num--;
         dio_byte[8] = '\0';
sprintf (send_data, "%s%d\r", set_dio_port, dio_port); // select DIO port
         PutString(io_port,send_data);
sprintf (send_data, "%s%s\r", set_dio_byte, dio_byte); // write DIO byte
          PutString(io_port,send_data);
```

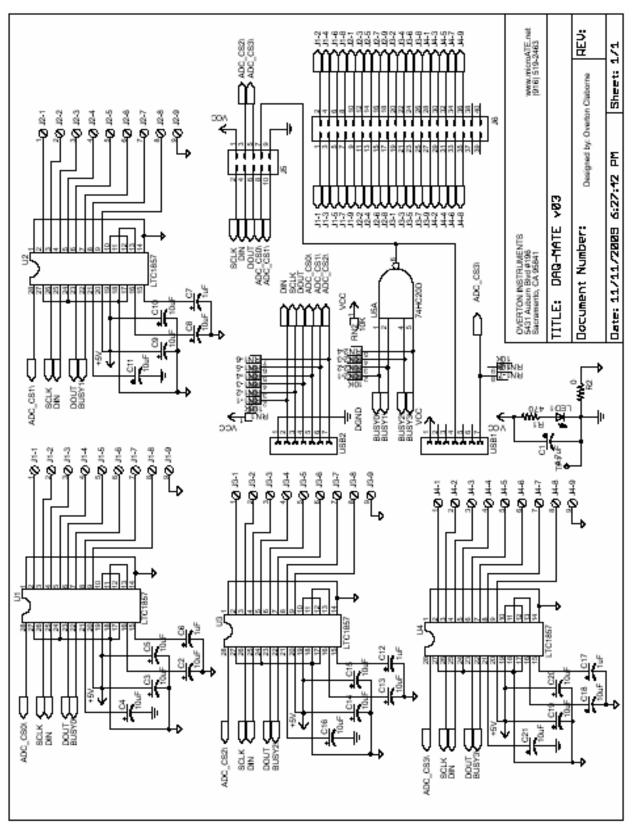
// Execute test sequence

Appendix A. Serial Command Set

To facilitate remote control for the DAQ-MATE, a USB interface is required. When connected to a host PC, the USB connection appears as a "Virtual Com Port", which establishes a serial data communications link between the two. The default protocol is 19200 baud rate, no parity, 1 stop bit and no flow control. The DAQ-MATE will respond to a unique set of ASCII serial data commands (listed below). The first three bytes of the command string starts with the prefix 'DQ_', followed by a code that represents the actual command. All commands are upper case sensitive and are terminated with a carriage-return. If the command is valid, the DAQ-MATE will return either a '<>', or a bracketed result (i.e. '<2108>'. If the DAQ-MATE receives a carriage-return or line-feed alone (without a command), then a '→' is returned (this response is a "prompt" to signal the DAQ-MATE is ready). If the DAQ-MATE detects an incorrect command then one of three error symbols will be generated, (1) invalid command then a '><' is returned, (2) a command that is out-of-limits then a '>>' is returned, and (3) a command that prematurely times-out then a '<<' is returned. In some cases the error symbol will include a bracketed result (i.e. '>1

Command	Function	Response	Description
DQ_BRn	Set baud rate code	<n></n>	Select one of 4 different baud rates by changing -n-code. 0 = 1200, 1 = 2400, 2 = 9600 & 3 = 19200. Baud will remain set. Default code is 3 (19200).
DQ_BR?	Get baud rate code	<n></n>	Get current baud rate code (-n- is the return code 0 to 3).
DQ_ID?	Get module ID	<daq-mate vx.x=""></daq-mate>	Get current identification and version number.
DQ_MR	Master Reset	<>	Reset & initialize the module
DQ_WC	Write configuration	<>	Store current instrument settings in EEPROM. Save settings related to the ADC, DAC and DIO hardware.
DQ_RC	Recall configuration	<>	Retrieve stored instrument settings
CK_CC?	Get ADC Channel Configuration	<cmpr></cmpr>	Get current channel configuration. c = ADC channel number (01 to 32) m = ADC mode ("D" = Differential, "S" = Single) p = ADC polarity (0 = +, 1 = -) r = ADC range (1 = +5V, 2 = ±5V, 3 = 10V, 4 = ±10V)
CK_CCcmpr	Configure ADC Channel	<>	Set channel configuration with following codes. c = ADC channel number (01 to 32) m = ADC mode ("D" = Differential, "S" = Single) p = ADC polarity (0 = +, 1 = -) r = ADC range (1 = +5V, 2 = ±5V, 3 = 10V, 4 = ±10V)
DQ_RV?	Get voltage measurement	<nnnn></nnnn>	Get a voltage measurement based on the current ADC channel and range selection. The measurement contains 4 ASCII bytes representing a 12-bit decimal value (0-4095).

Appendix B. Schematic



Appendix C. Mechanical Dimensions