



A Unified Framework for Mixed-Integer Optimization: Nonlinear Formulations and Scalable Algorithms

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August 2019

ORC, Massachusetts Institute of Technology Joint work with Dimitris Bertsimas and Jean Pauphilet Preprint available at: ryancorywright.github.io

Motivation: Best Subset Selection

In high-dimensional regression, desirable to fit a parsimonious model which uses at most k features. Achieved via best subset selection

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A problem with logical structure: x = 0 if z = 0 for z binary.

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- Facility Location:

$$\min_{\mathbf{z} \in \{0,1\}^n} \min_{\mathbf{X} \in \mathbb{R}_+^{n \times m}} \mathbf{c}^\top \mathbf{z} + \sum_{j=1}^m \sum_{i=1}^n C_{ij} X_{ij}$$
s.t.
$$\sum_{j=1}^m X_{ij} \le U_i, \ \forall i \in [n], \ \sum_{i=1}^n X_{ij} = d_j, \ \forall j \in [m],$$

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 Many others: Sparse Portfolio Selection, Network Design, Unit Commitment, Scheduling.

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State-of-the-art methods are either heuristics or too slow. Alternatives are needed.

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- We show that adding a $\frac{1}{2\gamma} ||\mathbf{x}||_2^2$ ridge regularizer to the objective is a viable and often more scalable alternative to big-M.

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- By using strong duality, we derive a saddle-point reformulation, which is exactly solvable via an outer-approximation procedure.
- We obtain provably near-optimal solutions in polynomial time by solving a Boolean relaxation efficiently.
- Our approach is scalable: it solves sparse regression problems with 100,000s of covariates, sparse portfolio selection problems with 1000s of securities, network design problems with 100s of nodes.

The Unified Framework

$$\min_{\boldsymbol{z} \in \mathcal{Z}, \ \boldsymbol{x} \in \mathbb{R}^n} \ \boldsymbol{c}^\top \boldsymbol{z} + \underbrace{g(\boldsymbol{x})}_{\text{convex function}} + \underbrace{\Omega(\boldsymbol{x})}_{\text{regularizer}} \text{ s.t. } \underbrace{x_i = 0 \text{ if } z_i = 0}_{\text{logical constraint}}, \ \forall i,$$

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where:

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- We model convex constraints $x \in \mathcal{X}$ via $g(x) = +\infty$ if $x \notin \mathcal{X}$.
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- The regularizer $\Omega(\cdot)$ convexifies the logical constraints. It is one of:
 - 1. A big-M penalty: $\Omega(x) = 0$ if $||x||_{\infty} \leq M$ and $+\infty$ otherwise.
 - 2. A ridge penalty: $\Omega(\mathbf{x}) = \frac{1}{2\gamma} ||\mathbf{x}||_2^2$.

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All six problems on the second slide fit into this framework!

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Allows us to solve all six problems using the same piece of code.

We rewrite the problem as

$$\min_{\mathbf{z}\in\mathcal{Z}} f(\mathbf{z}),$$

$$f(z) = \min_{\mathbf{x}} \ \mathbf{c}^{\top} \mathbf{z} + \underbrace{g(\mathbf{x})}_{\text{convex}} + \underbrace{\Omega(\mathbf{x})}_{\text{regularizer}} \text{ s.t. } \underbrace{x_i = 0 \text{ if } z_i = 0}_{\text{logical constraint}}, \ \forall i,$$

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$$= \min_{\mathbf{x}} \ \mathbf{c}^{\top} \mathbf{z} + g(\mathbf{z} \circ \mathbf{x}) + \Omega(\mathbf{z} \circ \mathbf{x})$$
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$$= \max_{\alpha} \ \mathbf{c}^{\top} \mathbf{z} + \underbrace{h(\alpha)}_{\text{consequence}} - \sum_{i} z_i \Omega^{\star}(\alpha_i) \qquad \text{strong duality}^1$$

¹Assuming that $\forall z \in \mathcal{Z}$, either the problem generated by f(z) is infeasible or strong duality holds. True for all six problems on slide 2, and generally holds under a CQ.

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which proves f(z) is convex!

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The Saddle-Point Reformulation

$$f(\mathbf{z}) = \max_{\alpha} \ \mathbf{c}^{\top} \mathbf{z} + \underbrace{h(\alpha)}_{\text{concave}} - \sum_{i} z_{i} \Omega^{*}(\alpha_{i}),$$

- $h(\cdot)$ is concave; the Fenchel conjugate of $g(\cdot)$ (up to a minus sign).
- $\Omega^*(\alpha) = M|\alpha|$ for the big-M penalty.
- $\Omega^{\star}(\alpha) = \gamma/2\alpha^2$ for the ridge penalty.

So What?

Our saddle-point representation:

$$\min_{\mathbf{z} \in \mathcal{Z}} f(\mathbf{z}) = \min_{\mathbf{z} \in \mathcal{Z}} \max_{\alpha} \mathbf{c}^{\top} \mathbf{z} + h(\alpha) - \sum_{i} z_{i} \Omega^{*}(\alpha_{i})$$

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lends itself to a tractable outer-approximation method.

• Fix z_0 , solve an easy convex program to obtain $\alpha^*(z_0)$ and $f(z_0)$.

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- $f(z) \ge f(z_0) + \nabla f(z_0)^{\top} (z z_0)$ is a valid outer-approximation cut.

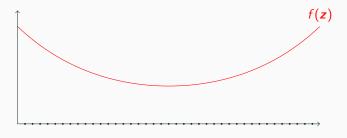
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- Iteratively adding cuts, minimizing piecewise linear underestimator in Julia/CPLEX minimizes f(z). Using Branch-and-Cut with lazy constraints solves entire problem using one branch-and-bound tree.
- As will see in numerical results, solves very large-scale problems.

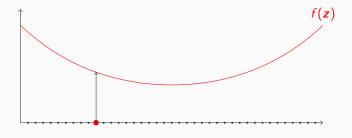
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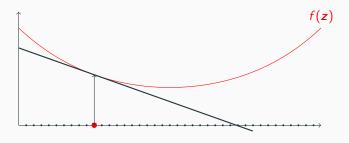
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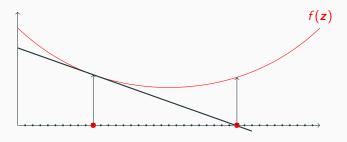
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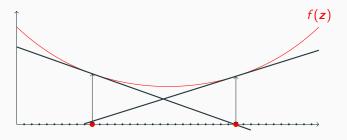
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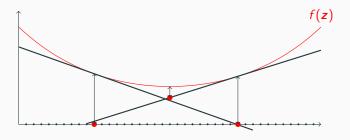
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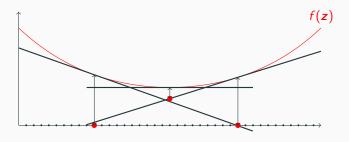
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A Boolean Relaxation

$$\min_{\mathbf{z} \in \operatorname{Conv}(\mathcal{Z})} \max_{\alpha} \ \mathbf{c}^{\top} \mathbf{z} + h(\alpha) - \sum_{i} z_{i} \Omega^{\star}(\alpha_{i})$$

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- Solve by sub-gradient descent method, or transform to SOCP.
- Randomly rounding relaxation z^* according to $z_i \sim \text{Bernoulli}(z_i^*)$ gives a Boolean vector z. How good is it?

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- Solve by sub-gradient descent method, or transform to SOCP.
- Randomly rounding relaxation z^* according to $z_i \sim \text{Bernoulli}(z_i^*)$ gives a Boolean vector z. How good is it?
- Let z be a random rounding of z^* . Then,

$$0 \le f(\mathbf{z}) - f(\mathbf{z}^*) \le \epsilon$$

with probability at least

$$1 - |\mathcal{R}| \exp\left(\frac{-\epsilon^2}{\kappa}\right)$$

- $|\mathcal{R}|$ is number of strictly fractional entries in z^* .
- κ is a function of $|\mathcal{R}|$, problem data.

How does the approach perform on real data?

Sparse Empirical Risk Minimization Scalability

- For regression f(z) is closed form, scales to 100,000s of features.
- For classification, f(z) is cheap, scales to 10,000s of features.
- Outer-approximation algorithm is more accurate than ElasticNet,
 MCP, SCAD, and runtimes are comparable to Lasso.
- Code available: github.com/jeanpauphilet.

Sparse Portfolio Selection Scalability

Solves sparse portfolio selection problems with 1000s of securities².

Reference	Solution method	Size (no. securities)
Frangioni and Gentile ('09)	Perspective cut+SDP	400
Bonami and Lejeune ('09)	Nonlinear Branch-and-Bound	200
Gao and Li (′13)	SOCP relaxation Branch-and-Bound	300
Cui et al. ('13)	SOCP relaxation Branch-and-Bound	300
Zheng et. al. ('14)	SDP Branch-and-Bound	400
Frangioni et. al. ('16)	Aprox. Proj. Perspective Cut	400
Bertsimas and C-W ('18)	OA with γ -regularization	3,200

²See Bertsimas & Cory-Wright ('18), for an in-depth implementation.

Network Design Scalability

- f(z) obtained by solving a quadratic program.
- Approach solves problems with 100s of nodes.
- Objective value 5% better than CPLEX for small problems, 40% better for large problems.

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 a ridge regularizer.
- By using strong duality, we derive a saddle-point reformulation, which is exactly solvable via an outer-approximation procedure.
- Our approach: outer-approximation+warm-start+random rounding is scalable.

Thanks for listening!

Questions?

Preprint available at: ryancorywright.github.io

Supplementary Material

Selected References

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