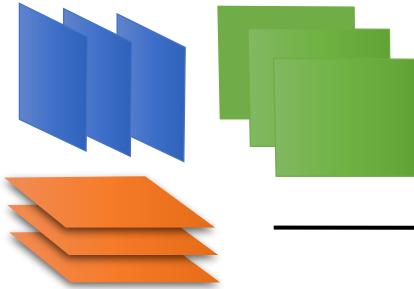




UNIVERSIDADE
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Overview of tensor decompositions and applications to wireless communications

André L. F. de Almeida

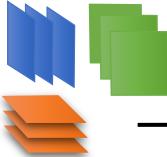
Federal University of Ceará, Brazil

Workshop on Low-Rank Approximations and
their Interactions with Neural Networks

[LoRAINNE'24](#)

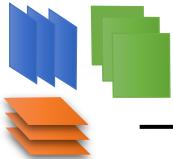
26 November 2024

A bit of many things..



Some history facts

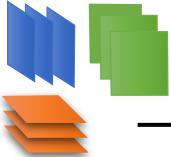
- From the 60s: Tensor decompositions used for analyzing collections of data matrices viewed as three-way arrays:
 - 1966: **Tucker decomposition** in psychometrics
 - 1970: **PARAFAC** (*parallel factor*) decomposition by Harshman in phonetics, **CANDECOMP** (*canonical decomposition*) by Carroll & Chang in psychometrics, a.k.a. **CP** (*CANDECOMP/PARAFAC*) by Kiers (2000)
- PARAFAC/CP invented by Hitchcock in 1927: seminal idea of polyadic form of a tensor (sum of rank-one components)
→ *canonical polyadic decomposition* (**CPD**)



Some history facts (cont'd)

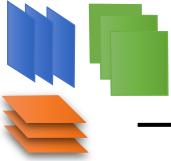
- **From the 90s:** Tensor decompositions were used in:
 - Chemistry, especially in **chemometrics** (Bro's Ph.D. thesis, 1998)
 - **Signal processing** (blind source separation (BSS) using cumulant tensors (J.F. Cardoso, P. Comon, 1990, L. De Lathauwer, 1997)
- **Since 2000:** Tensor decompositions introduced in wireless communication problems (N. Sidiropoulos et al., 2000), and image analysis (Vasilescu & Terzopoulos, 2002)
- **Last two decades:** Tensor-based signal processing (wireless communications, antenna array processing, image, speech processing, big data processing/analysis)
- **More recently:** Numerous applications in machine learning/artificial intelligence (ML/AI)

- Separation of data sets into components/factors to extract the multimodal structure of data and useful information from noisy measurements
- Dimensionality reduction of multidimensional data
 - ⇒ Approximate low-rank tensor decompositions/models
 - ⇒ Tensor train decompositions (massive datasets)
- Completion of data tensors in presence of missing data
 - ⇒ New optimization problems and tensor-based algorithms
- Dynamic/streaming tensor analysis
 - ⇒ Tensor factorization algorithms for high-order/large-scale tensors in distributed setup (parallel computing, tensor tracking, etc.)

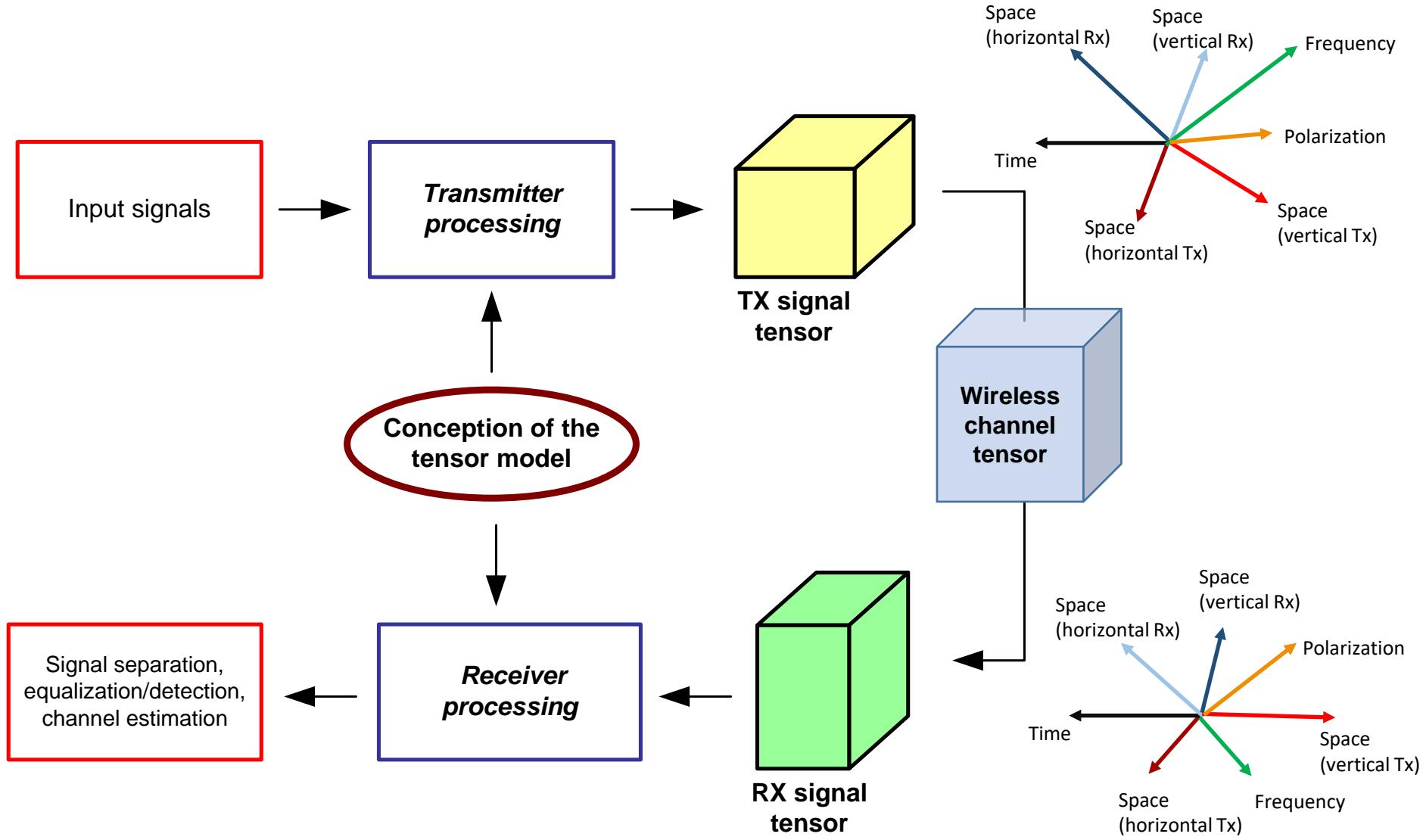


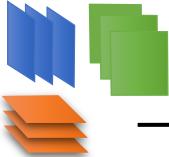
Motivation (signal processing & communications)

- Exploit the multidimensional nature of the wireless channel and its multiple forms of diversity
- Blind/semi-blind channel estimation & symbol detection under more relaxed conditions (compared to matrix-based SP)
- Complexity reduction of large-scale filter optimizations (e.g. massive antenna arrays, equalizers, nonlinear filtering, neural network structures)
- Noise-relisient & robust multilinear modulation (low-rank tensor construction of the transmitted signals)



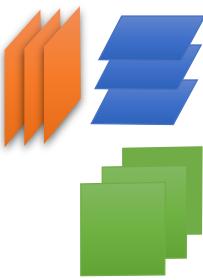
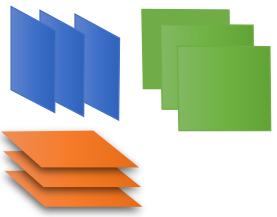
Tensor perspective to wireless communications





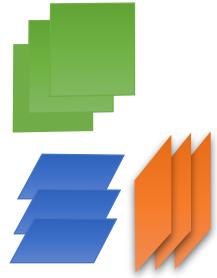
Motivation (signal processing & communications)

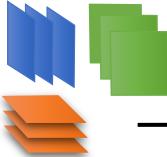
- Exploit the multidimensional nature of the wireless channel and its multiple forms of diversity
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PART 1

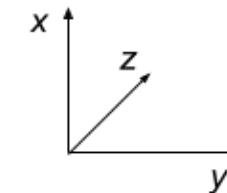
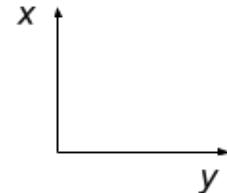
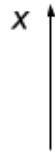
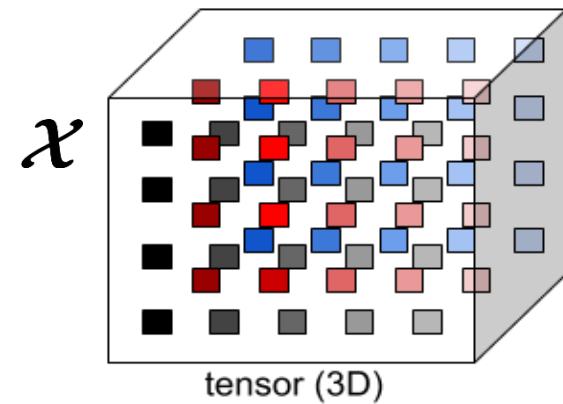
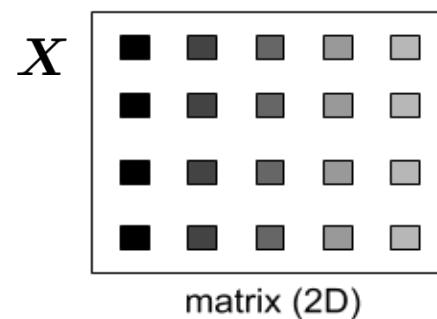
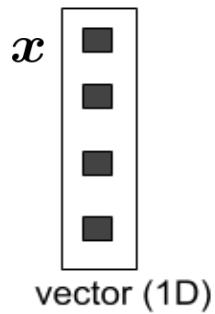
Tensor decompositions

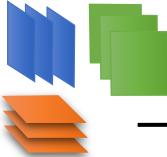




What is a Tensor?

- An intuitive definition...





What is a tensor?

- A “nicer” mathematical definition 😊

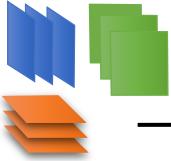
$$\mathcal{X} = \sum_{i=1}^I \sum_{j=1}^J \sum_{k=1}^K x_{i,j,k} (\underbrace{\mathbf{e}_i^{(I)} \circ \mathbf{e}_j^{(J)} \circ \mathbf{e}_k^{(K)}}_{(i,j,k)\text{-th coordinate}})$$

$$\mathbf{e}_i^{(I)} = \begin{bmatrix} 0 \\ \vdots \\ 1 \xleftarrow{i\text{-th position}} \\ \vdots \\ 0 \end{bmatrix}$$

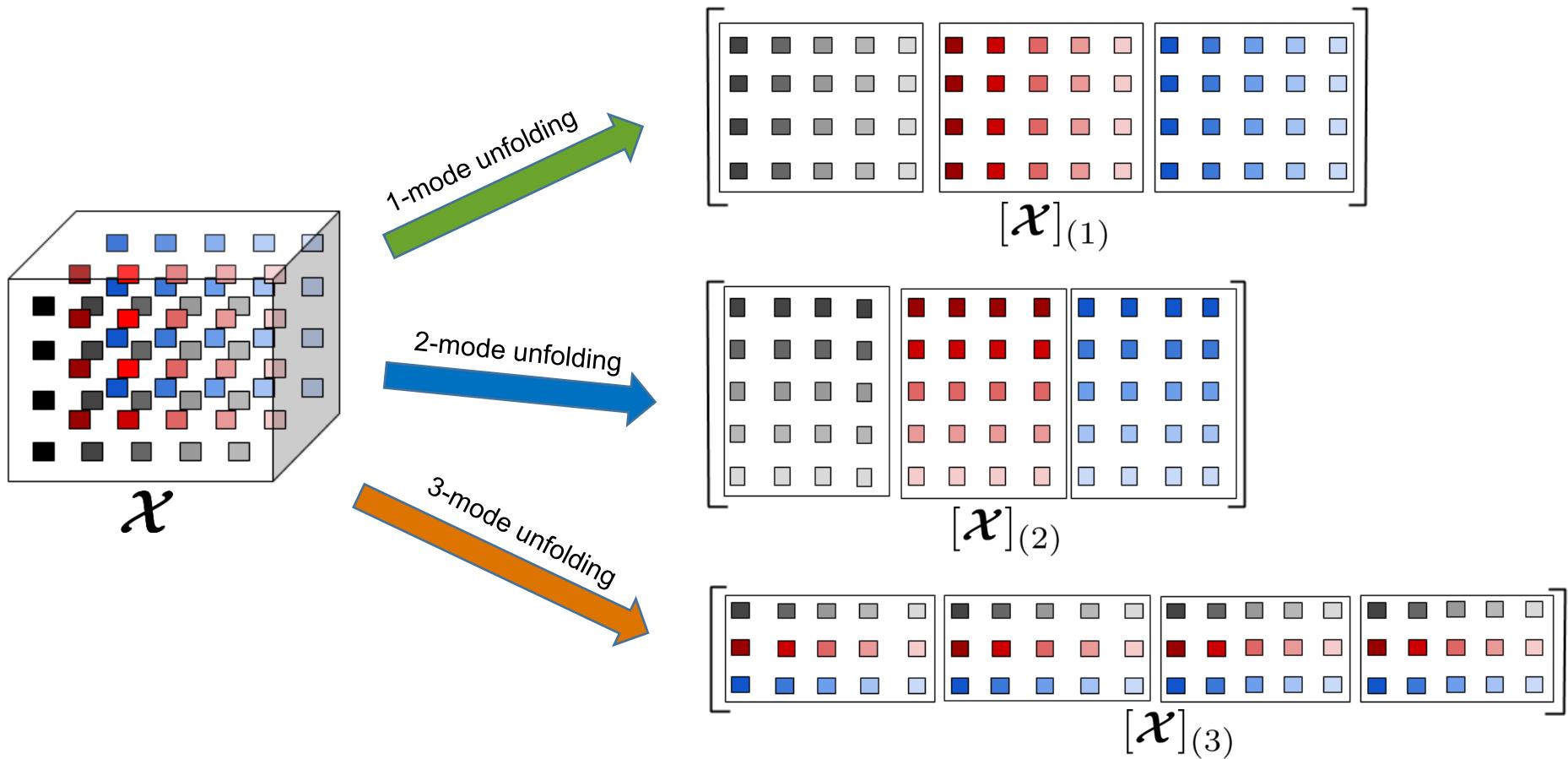
○ : outer product

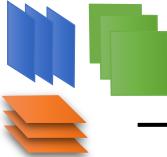
- Tensor as a multi-linear mapping

$$T(\mathbf{U}, \mathbf{V}, \mathbf{W}) = \sum_{i=1}^I \sum_{j=1}^J \sum_{k=1}^K x_{i,j,k} (\mathbf{u}_i \circ \mathbf{v}_j \circ \mathbf{w}_k) \quad \mathbf{U} = [\mathbf{u}_i] \\ \mathbf{V} = [\mathbf{v}_j] \\ \mathbf{W} = [\mathbf{w}_k]$$



Unfolding a tensor into matrices





An useful operator: The n -mode product

- Defines a product between a tensor and a matrix (or vector)

$$\mathcal{Y} = \mathcal{X} \times_n A \quad \leftrightarrow \quad [\mathcal{Y}]_{(n)} = A[\mathcal{X}]_{(n)},$$

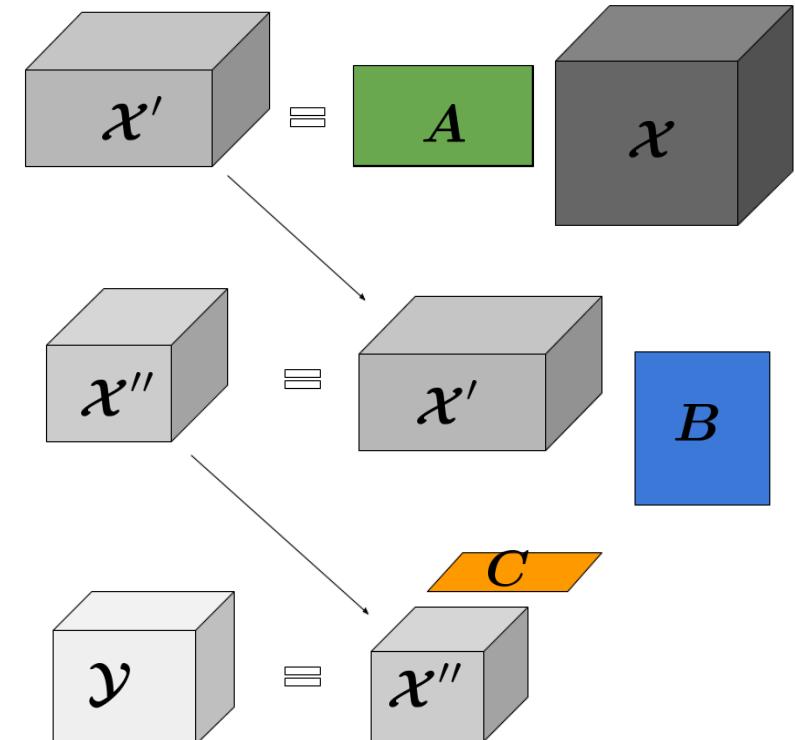
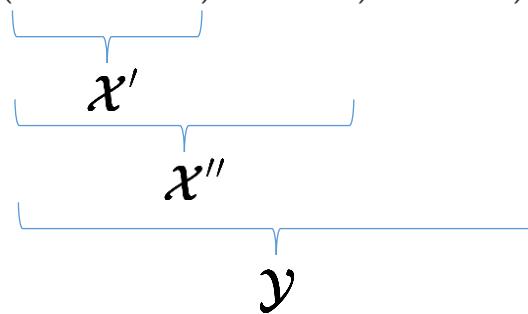
$\forall n$

[De Lathauwer et al. '2000]

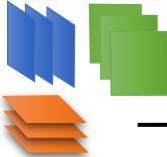
[Kolda & Bader, 2009]

- Multiple n -mode products

$$\mathcal{Y} = (((\mathcal{X} \times_1 A) \times_2 B) \times_3 C)$$

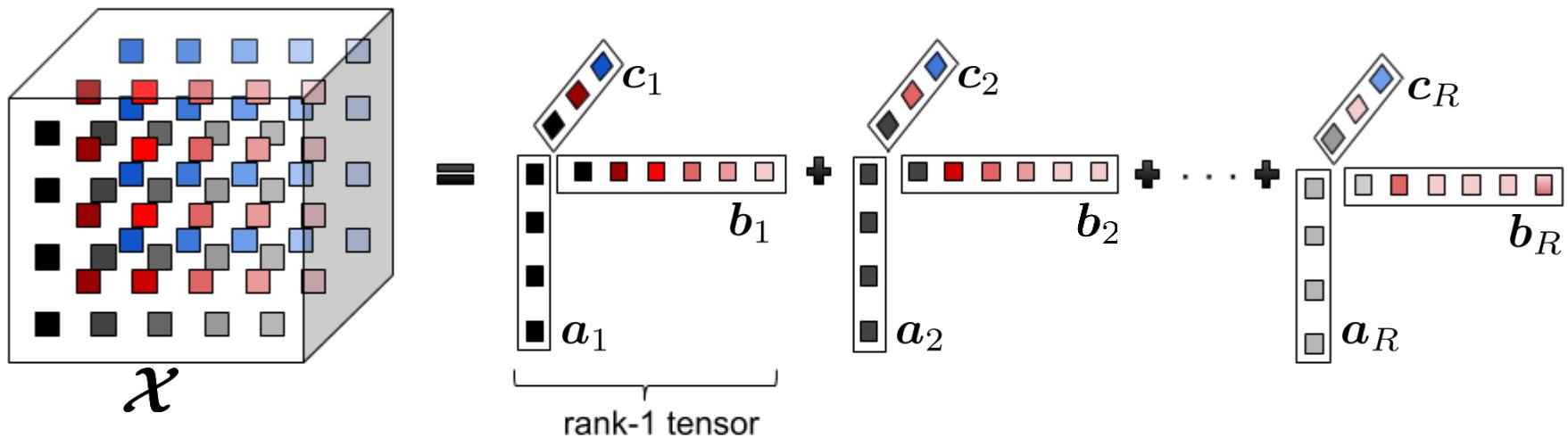


Concept of "multi-linear compression"



The “canonical” tensor decomposition

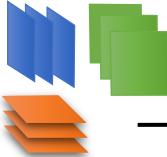
- Decomposition in a mimimal sum of rank-1 components



Also known as:

- Canonical polyadic decomposition (CPD) [Hitchcock'1927]
- Parallel Factor decomposition (PARAFAC) [Harshman'1970] [Carroll & Chang'1970]

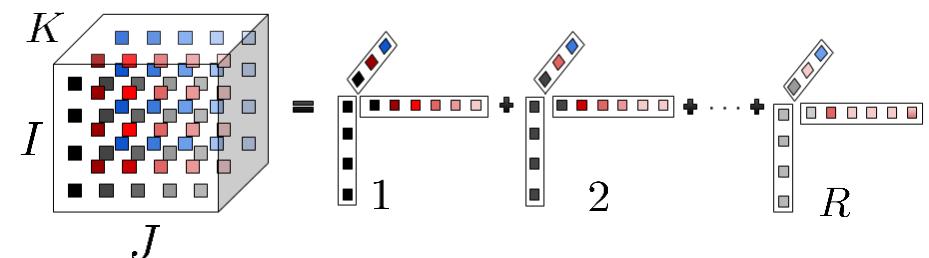
Tensor rank $R \rightarrow$ minimum # of rank-1 tensors yielding χ in a combination



Canonical polyadic decomposition (CPD)

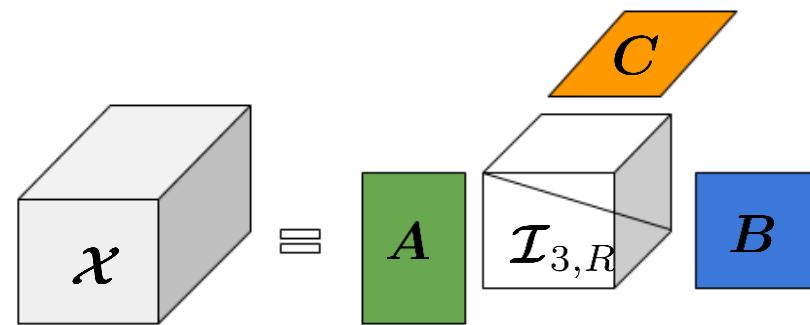
- Outer-product notation

$$\mathcal{X} = \sum_{r=1}^R \mathbf{a}_r \circ \mathbf{b}_r \circ \mathbf{c}_r$$



- n-mode product notation

$$\mathcal{X} = \mathcal{I}_{3,R} \times_1 \mathbf{A} \times_2 \mathbf{B} \times_3 \mathbf{C}$$



- “Vectorized” form

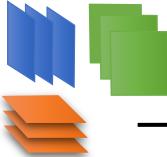
$$\mathbf{x} = (\mathbf{A} \diamond \mathbf{B} \diamond \mathbf{C}) \mathbf{1}_R$$

\diamond : Khatri-Rao product

$$\mathbf{A} = [\mathbf{a}_r]$$

$$\mathbf{B} = [\mathbf{b}_r]$$

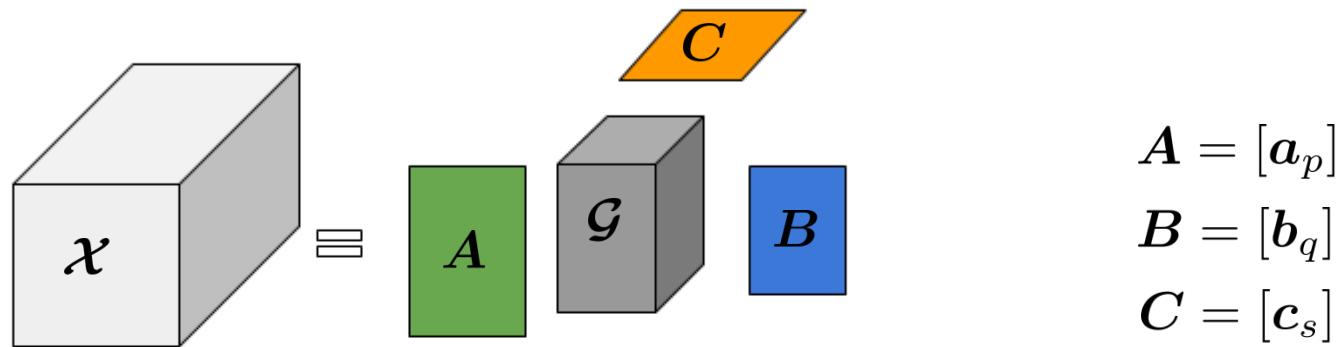
$$\mathbf{C} = [\mathbf{c}_r]$$



Tucker decomposition

Full multi-linear map $\mathcal{X} = \sum_{p=1}^P \sum_{q=1}^Q \sum_{s=1}^S g_{p,q,s}(\mathbf{a}_p \circ \mathbf{b}_p \circ \mathbf{q}_s)$

[Tucker'1966]

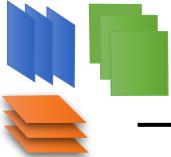


- n -mode product notation

$$\mathcal{X} = \mathcal{G} \times_1 \mathbf{A} \times_2 \mathbf{B} \times_3 \mathbf{C}$$

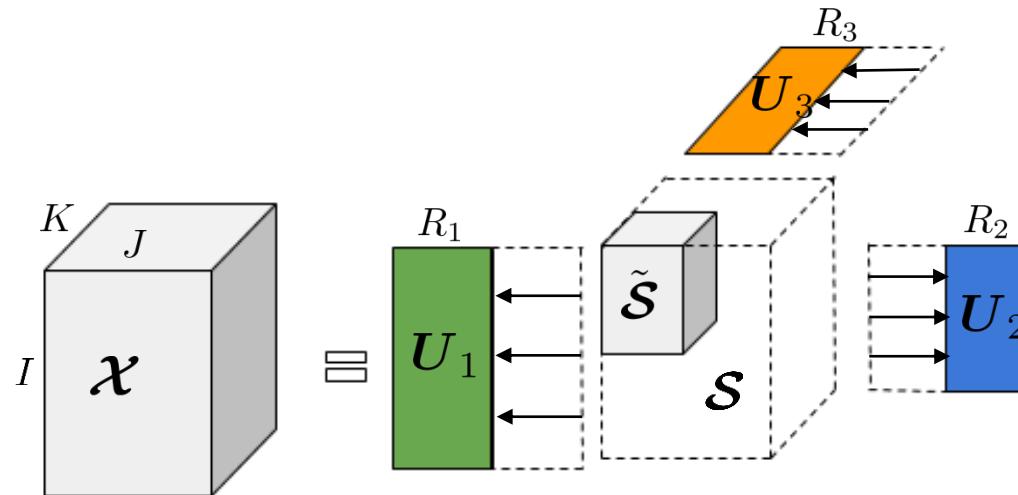
- “Vectorized” form

$$x = (\mathbf{A} \otimes \mathbf{B} \otimes \mathbf{C})\mathbf{g}$$

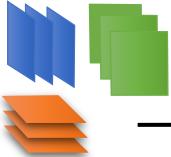


High-order SVD (HOSVD)

- Generalization of matrix SVD to tensors [De Lathauwer et al. '2000]

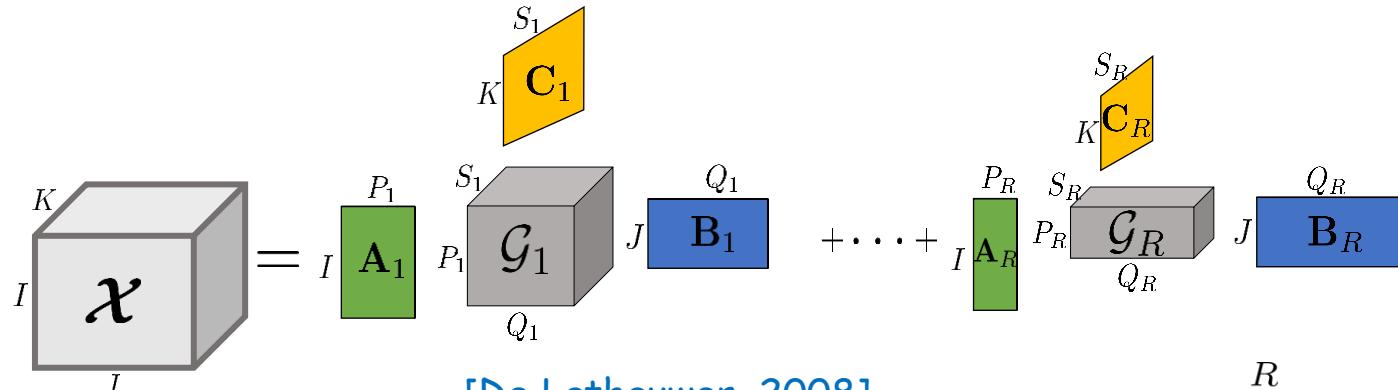


$$\tilde{\mathcal{X}} = \tilde{\mathcal{S}} \times_1 U_1 \times_2 U_2 \times_3 U_3$$



Block term decomposition (BTD)

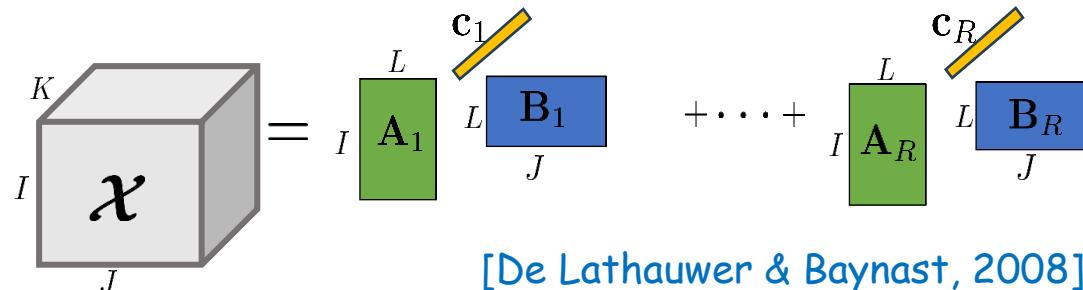
- Decomposition of a tensor into a sum of tensor “blocks” having lower multilinear ranks



[De Lathauwer, 2008]

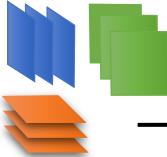
$$\mathcal{X} = \sum_{r=1}^R \mathcal{G}_r \times_1 \mathbf{A}_r \times_2 \mathbf{B}_r \times_3 \mathbf{C}_r$$

Special case: decomposition into rank- $(L, L, 1)$ blocks



[De Lathauwer & Baynast, 2008]

$$\mathcal{X} = \sum_{r=1}^R (\mathbf{A}_r \mathbf{B}_r) \circ \mathbf{c}_r$$



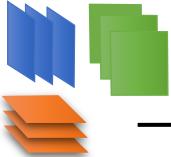
N-th order Tucker & Tucker-(N1,N)

- General expression:

$$x_{i_1, \dots, i_N} = \sum_{r_1=1}^{R_1} \cdots \sum_{r_N=1}^{R_N} g_{r_1, \dots, r_N} \prod_{n=1}^N a_{i_n, r_n}^{(n)} \rightarrow \mathcal{X} = \mathcal{G} \times_{n=1}^N A^{(n)}$$

- Tucker-(N1,N):

$$\begin{aligned} x_{i_1, \dots, i_N} &= \sum_{r_1=1}^{R_1} \cdots \sum_{r_{N_1}=1}^{R_{N_1}} g_{r_1, \dots, r_{N_1}, i_{N_1+1}, \dots, i_N} \prod_{n=1}^{N_1} a_{i_n, r_n}^{(n)} \\ \mathcal{X} &= \mathcal{G} \times_1 A^{(1)} \times_2 \cdots \times_{N_1} A^{(N_1)} \times_{N_1+1} I_{N_1+1} \times_{N_1+2} \cdots \times_N I_N \\ &= \mathcal{G} \times_{n=1}^{N_1} A^{(n)} \end{aligned}$$

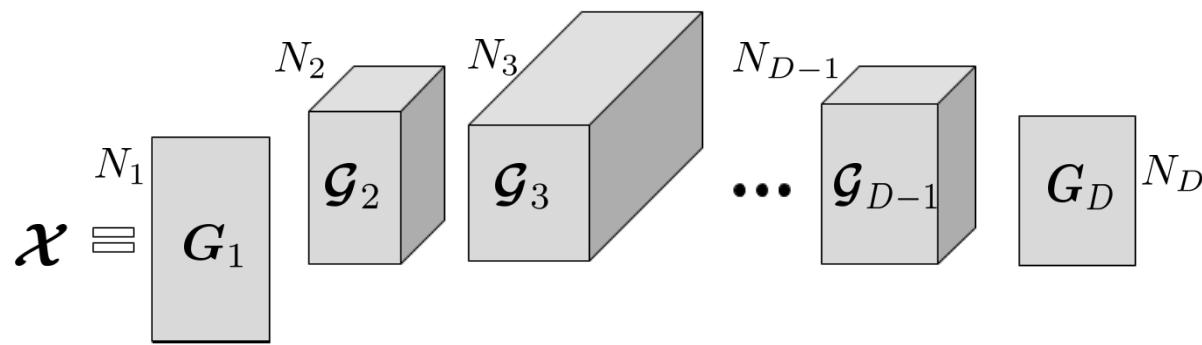


Tensor Train (TT) decomposition

- D -dimensional tensor as a “train” of smaller 3D tensors

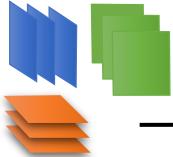
$$\mathcal{X} \in \mathbb{C}^{I_1 \times \dots \times I_N}$$

[Oseledets, 2011]

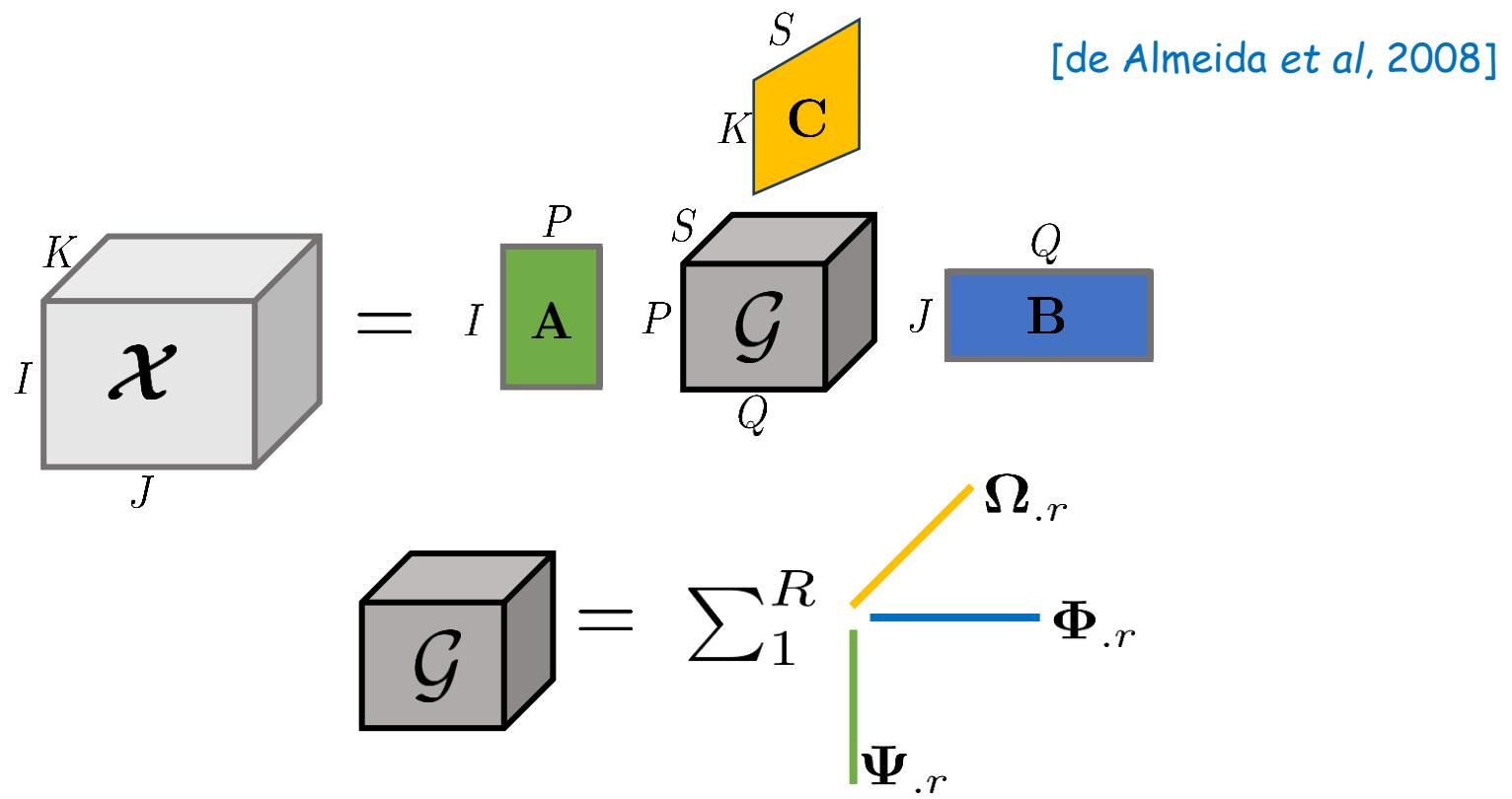


$$\mathcal{X} = \mathbf{G}_1 \times_2^1 \mathbf{G}_2 \times_3^1 \mathbf{G}_3 \times_4^1 \cdots \times_{D-1}^1 \mathbf{G}_{D-1} \times_D^1 \mathbf{G}_D$$

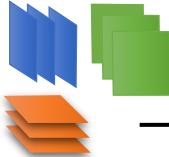
Introduced to tackle the curse of dimensionality
(case of “big data” tensors)



CONstrained FACTor decomposition (CONFAC)



CONFAC decomposition \rightarrow Tucker-3 decomposition with “canonical” core tensor (PARAFAC-core)



CONFAC decomposition (cont'd)

- Scalar writing:

$$x_{i,j,k} = \sum_{p=1}^P \sum_{q=1}^Q \sum_{s=1}^S a_{i,p} b_{j,q} c_{k,s} g_{p,q,s}(\Psi, \Phi, \Omega)$$

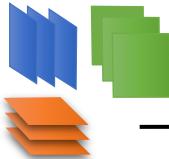
where $g_{p,q,s} = \sum_{r=1}^R \psi_{p,r} \phi_{q,r} \omega_{s,r}$ and $R = \max(P, Q, S)$

Columns of the constraint matrices Ψ , Φ , and Ω are
canonical basis vectors (1's and 0's)

$$\mathcal{X} = \mathcal{G} \times_1 \mathbf{A} \times_2 \mathbf{B} \times_3 \mathbf{C}$$

$$\mathcal{G} = \mathcal{I}_R \times_1 \Psi \times_2 \Phi \times_3 \Omega$$

Tucker-3 with sparse PARAFAC core



CONFAC decomposition (cont'd)

- Interpretation as a rank- R “constrained” CPD

$$\begin{aligned}x_{i,j,k} &= \sum_{p=1}^P \sum_{q=1}^Q \sum_{s=1}^S \left(\sum_{r=1}^R \psi_{p,r} \phi_{q,r} \omega_{s,r} \right) a_{i,p} b_{j,q} c_{k,s} \\&= \sum_{r=1}^R \left(\sum_{p=1}^P a_{i,p} \psi_{p,r} \right) \left(\sum_{q=1}^Q b_{j,q} \phi_{q,r} \right) \left(\sum_{s=1}^S c_{k,s} \omega_{s,r} \right)\end{aligned}$$

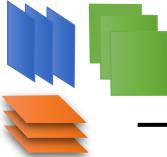


$$\mathcal{X} = \mathcal{I} \times_1 (\mathbf{A}\Psi) \times_2 (\mathbf{B}\Phi) \times_3 (\mathbf{C}\Omega)$$

PARAFAC:

$$\begin{aligned}R_1 &= R_2 = R_3 = F \\ \Psi &= \Phi = \Omega = \mathbf{I}_Q\end{aligned}$$

$$\mathcal{G}(\Psi, \Phi, \Omega) = \mathcal{I}_Q$$



CONFAC decomposition (cont'd)

- Class of PARALIND models [Bro'2009]
- Enjoy partial uniqueness at different levels

[Stegeman & de Almeida '2009] [Miron & Brie, 2015]

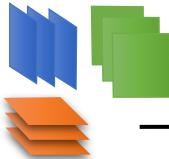
[Guo et al, 2012]

- Essential uniqueness result [Stegeman & de Almeida, 2009]

Assumptions: $\mathbf{A}, \mathbf{B}, \mathbf{C}$ full column rank; $(\boldsymbol{\Phi} \diamond \boldsymbol{\Omega})\boldsymbol{\Psi}^T$ full column rank

$$N^* = \max_r \left(\text{rank}(\boldsymbol{\Phi} \text{diag}(\boldsymbol{\psi}_r^T) \boldsymbol{\Phi}^T) \right)$$

If $\text{rank}(\boldsymbol{\Phi} \text{diag}(\boldsymbol{\Psi}^T \mathbf{d}) \boldsymbol{\Phi}^T) \leq N^*$ implies $\omega(\mathbf{d}) \leq 1 \rightarrow \mathbf{A}$ is unique



PARALIND/CONFAC-(N1,N) decompositions

- Variant of PARALIND/CONFAC with only N1 constrained factor matrices [Favier & de Almeida, 2014]

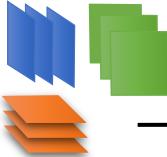
$$x_{i_1, \dots, i_{N_1+1}, \dots, i_N} = \sum_{f=1}^F \sum_{r_1=1}^{R_1} \cdots \sum_{r_{N_1}=1}^{R_{N_1}} \prod_{n=1}^{N_1} a_{i_n, r_n}^{(n)} \phi_{r_n, f}^{(n)} \prod_{n=N_1+1}^N a_{i_n, f}^{(n)}$$



(Tucker-(N1,N) with a “PARAFAC-like” core)

$$\mathcal{X} = \mathcal{I}_{N,R} \times_{n=1}^{N_1} (\mathbf{A}^{(n)} \boldsymbol{\Phi}^{(n)}) \times_{n=N_1+1}^N \mathbf{A}^{(n)}$$

Constraints only affect the first N1 modes while the other are “free” modes



- Block-partitioned version of PARALIND/CONFAC

$$\mathcal{X} = \sum_{p=1}^P \mathcal{X}_p \quad \text{with} \quad \mathcal{X}_p = \mathcal{G}_p \times_{n=1}^N \mathbf{A}_p^{(n)}$$
$$\mathcal{G}_p = \mathcal{I}_{N, R_p} \times_{n=1}^N \Phi_p^{(n)}$$

Special case: Block CONFAC-(1,3)

Fixed constraint in only one mode ($N_1=1$, $N=3$)

$$\mathcal{X} = \mathcal{I}_{N, R} \times_1 (\mathbf{A}\Phi) \times_2 \mathbf{B} \times_3 \mathbf{C} = \sum_{r=1}^R \mathbf{a}_r \circ (\mathbf{B}_r \mathbf{C}_r)$$

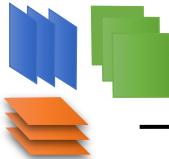
$$\Psi \doteq \text{diag}(\mathbf{1}_{L_1}^T, \dots, \mathbf{1}_{L_P}^T)$$

$$\mathbf{A} \doteq [\mathbf{a}_1, \dots, \mathbf{a}_P]$$

$$\mathbf{B} \doteq [\mathbf{B}_1, \dots, \mathbf{B}_P]$$

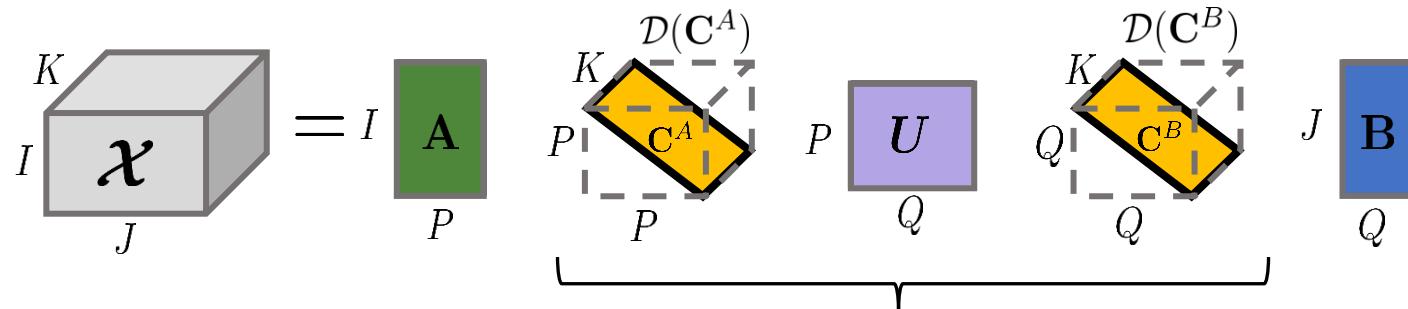
$$\mathbf{C} \doteq [\mathbf{C}_1, \dots, \mathbf{C}_P]$$

Block CONFAC-(1,3) \rightarrow rank-($L_p, L_p, 1$) BTD



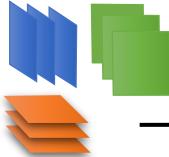
PARATUCK-type decompositions

- The PARATUCK-2 decomposition [Harshman & Lundy, 1996]



$$\begin{aligned} x_{i,j,k} &= \sum_{p=1}^P \sum_{q=1}^Q \underbrace{(u_{p,q} c_{p,k}^A c_{q,k}^B)}_{w_{p,q,k}} a_{i,p} b_{j,q} \\ &= \sum_{p=1}^P \sum_{q=1}^Q u_{p,q} (a_{i,p} c_{p,k}^A) (b_{j,q} c_{q,k}^B) \end{aligned}$$

Interpretation of C^A and C^B : *interaction or allocation* matrices



PARATUCK-type decompositions (cont'd)

- PARATUCK-2 as a hybrid of PARAFAC and Tucker-2

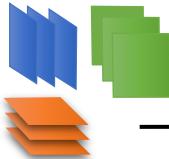
$$x_{i,j,k} = \sum_{p=1}^P \sum_{q=1}^Q \underbrace{(u_{p,q} c_{p,k}^A c_{q,k}^B)}_{w_{p,q,k}} a_{i,p} b_{j,q} \longrightarrow \mathcal{X} = \mathcal{W} \times_1 \mathbf{A} \times_2 \mathbf{B}$$

Where is the PARAFAC structure?

Defining $\left\{ \begin{array}{l} f_{p,q,k} = c_{p,k}^A c_{q,k}^B = \sum_{j=1}^K c_{p,j}^A c_{q,j}^B \delta_{k,j} \\ \updownarrow \\ \mathcal{F} = \mathcal{I}_{3,K} \times_1 \mathbf{C}^A \times_2 \mathbf{C}^B \times_3 \mathbf{I}_K \end{array} \right.$ [Favier & de Almeida, 2014]

$$\mathcal{X} = \underbrace{\mathcal{W}}_U \underset{\{p,q\}}{\odot} \mathcal{F} \times_1 \mathbf{A} \times_2 \mathbf{B}$$

→ PARATUCK-2: Tucker-2 with (hidden) PARAFAC-core tensor



PARATUCK-2 decomposition

- PARATUCK-2 as a “structured” Tucker-3 [Sokal *et al*, 2020]

$$x_{i,j,k} = \sum_{p=1}^P \sum_{q=1}^Q u_{p,q} (a_{i,p} c_{p,k}^A) (b_{j,q} c_{q,k}^B) \quad \begin{cases} c_{k,r}^{AB} \doteq c_{p,k}^A c_{q,k}^B \\ r \doteq (p-1)Q + q \end{cases}$$

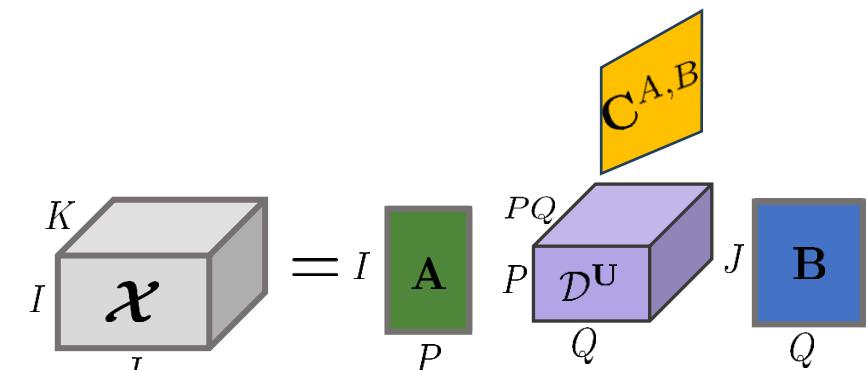
tensorize merge

$$x_{i,j,k} = \sum_{p=1}^P \sum_{q=1}^Q \sum_{r=1}^{PQ} d_{p,q,r}^U a_{i,p} b_{j,q} c_{k,r}^{AB}$$

$$\mathcal{X} = \mathcal{D}^U \times_1 \mathbf{A} \times_2 \mathbf{B} \times_3 \mathbf{C}^{A,B}$$

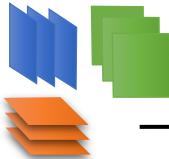
Sparse core tensor

$$[\mathcal{D}^U]_{(3)} \doteq \mathbf{U}^T$$



Khatri-Rao-structured factor matrix

$$\mathbf{C}^{A,B} \doteq [(\mathbf{C}^A)^T \diamond (\mathbf{C}^B)^T]^T$$



PARATUCK-(2,4) and PARATUCK-(N1,N)

- PARATUCK-(2,4) decomposition

$$\begin{aligned} x_{i,j,k,l} &= \sum_{p=1}^P \sum_{q=1}^Q \underbrace{(u_{p,q,l} c_{p,k}^A c_{q,k}^B)}_{w_{p,q,l,k}} a_{i,p} b_{j,q} \\ &= \sum_{p=1}^P \sum_{q=1}^Q u_{p,q,l} (a_{i,p} c_{p,k}^A) (b_{j,q} c_{q,k}^B) \end{aligned}$$

[da Costa et al, 2011]

[de Araújo & de Almeida, 2022]

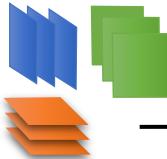
$$\mathcal{X} \in \mathbb{C}^{I \times J \times K \times L}$$

Tucker-(2,4) with
structured core tensor

- PARATUCK-(N1,N) decomposition [Favier & de Almeida, 2014]

$$x_{i_1, \dots, i_{N_1+1}, \dots, i_N} = \sum_{r_1=1}^{R_1} \cdots \sum_{r_{N_1}=1}^{R_{N_1}} u_{r_1, \dots, r_{N_1}, i_{N_1+2}, \dots, i_N} \prod_{n_1=1}^{N_1} a_{i_n, r_n}^{(n)} c_{r_n, i_{N_1+1}}^{(n)}$$

$a_{i_n, r_n}^{(n)}, c_{r_n, i_{N_1+1}}^{(n)}$ are entries of the factor matrix $\mathbf{A}^{(n)} \in \mathbb{C}^{I_n \times R_n}$
and the interaction matrix $\mathbf{C}^{(n)} \in \mathbb{C}^{R_n \times I_{N_1+1}}, \forall n = 1, \dots, N_1$



Links with constrained PARAFAC decompositions

- PARATUCK-2 as constrained PARAFAC-3 [Favier & de Almeida, 2014]

$$x_{i,j,k} = \sum_{p=1}^P \sum_{q=1}^Q a_{i,p} b_{j,q} (u_{p,q} \mathbf{c}_{p,k}^A \mathbf{c}_{q,k}^B)$$

Defining $\begin{cases} \boldsymbol{\Psi}^A \doteq \mathbf{I}_P \otimes \mathbf{1}_Q^T \\ \boldsymbol{\Psi}^B \doteq \mathbf{1}_P^T \otimes \mathbf{I}_Q \end{cases}$ → constraint matrices

Equivalent expression:

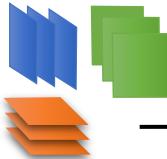
$$x_{i,j,k} = \sum_{r=1}^{PQ} \left(\sum_{p=1}^P a_{i,p} \psi_{p,r}^A \right) \left(\sum_{q=1}^Q b_{j,q} \psi_{q,r}^B \right) (u_{p,q} \mathbf{c}_{p,k}^A \mathbf{c}_{q,k}^B)$$

↑↓

$$\mathbf{x} = \mathcal{I}_{3,PQ} \times_1 (\mathbf{A} \boldsymbol{\Psi}^A) \times_2 (\mathbf{B} \boldsymbol{\Psi}^B) \times_3 \mathbf{F}^{AB}$$

Constrained PARAFAC-3 decomp.
(special CONFAC-(2,3) case)

with $\mathbf{F}^{AB} = [\mathbf{C}^A \diamond \mathbf{C}^B]^T \text{diag}(\text{vec}(\mathbf{U}))$



Links with constrained PARAFAC decompositions

- PARATUCK-(2,4) as constrained PARAFAC-4 [Favier & de Almeida, 2014]

$$x_{i,j,k} = \sum_{p=1}^P \sum_{q=1}^Q a_{i,p} b_{j,q} (u_{p,q,l} \mathbf{c}_{p,k}^A \mathbf{c}_{q,k}^B)$$

Defining $\begin{cases} \boldsymbol{\Psi}^A \doteq \mathbf{I}_P \otimes \mathbf{1}_Q^T \\ \boldsymbol{\Psi}^B \doteq \mathbf{1}_P^T \otimes \mathbf{I}_Q \end{cases}$ and $\mathbf{D} \doteq [\mathcal{U}]_{(3)}(L \times PQ)$

Equivalent expression:

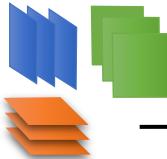
$$x_{i,j,k} = \sum_{r=1}^{PQ} \left(\sum_{p=1}^P a_{i,p} \psi_{p,r}^A \right) \left(\sum_{q=1}^Q b_{j,q} \psi_{q,r}^B \right) (\mathbf{c}_{p,k}^A \mathbf{c}_{q,k}^B) d_{l,r}$$

↑

$$\mathcal{X} = \mathcal{I}_{3,PQ} \times_1 (\mathbf{A} \boldsymbol{\Psi}^A) \times_2 (\mathbf{B} \boldsymbol{\Psi}^B) \times_3 \mathbf{F}^{AB} \times_4 \mathbf{D}$$

with $\mathbf{F}^{AB} = [\mathbf{C}^A \diamond \mathbf{C}^B]^T$

Constrained PARAFAC-4 decomp.
(special CONFAC-(2,4) case)



Links with constrained PARAFAC decompositions

- PARATUCK-(N-2,N) as constrained PARAFAC-N [Favier & de Almeida, 2014]

$$x_{i_1, \dots, i_{N_1+1}, \dots, i_N} = \sum_{r_1=1}^{R_1} \cdots \sum_{r_{N_1}=1}^{R_{N_1}} u_{r_1, \dots, r_{N_1}, i_{N_1+2}, \dots, i_N} \prod_{n_1=1}^{N_1} a_{i_n, r_n}^{(n)} c_{r_n, i_{N_1+1}}^{(n)}$$

Defining $\left\{ \begin{array}{l} \boldsymbol{\Psi}^{(n)} \doteq \mathbf{1}_{R_1}^T \otimes \cdots \otimes \mathbf{1}_{R_{n-1}}^T \otimes \mathbf{I}_{R_n} \otimes \mathbf{1}_{R_{n+1}}^T \otimes \cdots \otimes \mathbf{1}_{R_N}^T \\ \boldsymbol{D} \doteq [\mathcal{U}]_{(N)}(I_N \times R) \\ \boldsymbol{F} = [\diamond_{n=1}^N \boldsymbol{C}^{(n)}]^T \end{array} \right.$

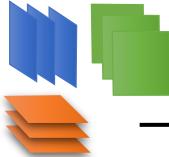
Equivalent expression: $\left\{ \begin{array}{l} r \doteq r_{N_1} + \sum_{n=1}^{N_1-1} (r_n - 1) \prod_{i=n+1}^{N_1} R_i \\ \text{and} \\ R \doteq \prod_{i=1}^{N_1} R_i \end{array} \right.$

$$x_{i_1, \dots, i_N} = \sum_{r=1}^R \left(\prod_{n=1}^{N-2} (a_{i_n, r}^{(n)} \psi_{r_n, r}^{(n)}) \right) f_{i_{N-1}, r} d_{i_N, r}$$



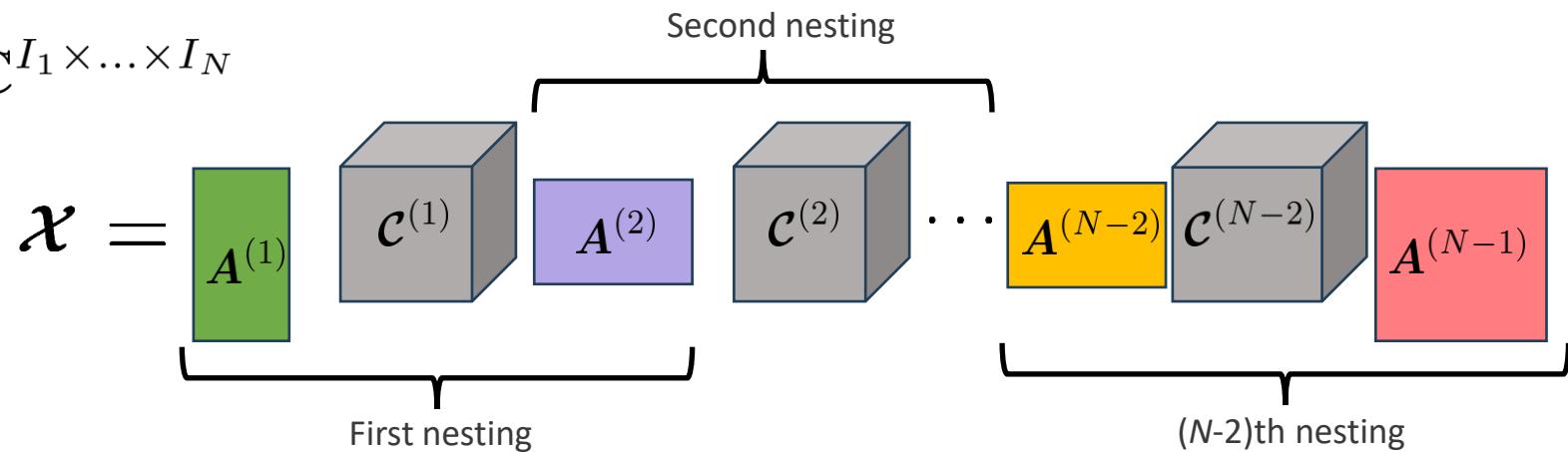
Constrained PARAFAC-N decomp.
(special CONFAC-(N-2,N) case)

$$\boldsymbol{\chi} = \mathcal{I}_{3,R} \times_{n=1}^{N-2} (\boldsymbol{A}^{(n)} \boldsymbol{\Psi}^{(n)}) \times_{N-1} \boldsymbol{F} \times_N \boldsymbol{D}$$



Nested Tucker decomposition (NTD)

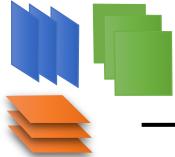
$$\mathcal{X} \in \mathbb{C}^{I_1 \times \dots \times I_N}$$



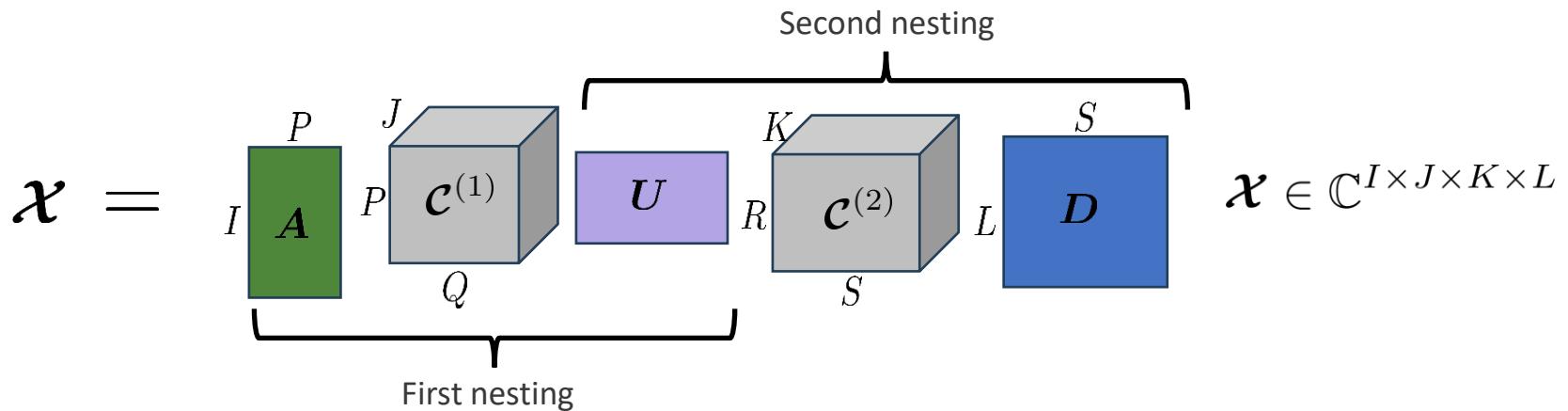
Each third-order tensor $C^{(n)} \in \mathbb{C}^{R_{2n-1} \times I_{n+1} \times R_{2n}}$, $n \in [1, N - 2]$ can be considered as a core tensor of a Tucker-(2, 3) term having $(A^{(n)}, I_{I_{n+1}}, A^{(n+1)})$ as matrix factors, with:

$$A^{(n+1)} \in \mathbb{C}^{R_{2n} \times R_{2n+1}}, n \in [2, N - 2], \quad A^{(1)} \in \mathbb{C}^{I_1 \times R_1}, A^{(N-1)} \in \mathbb{C}^{I_N \times R_{2N-4}}$$

Train of Tucker-(2,3) terms, where two successive terms share a common factor matrix

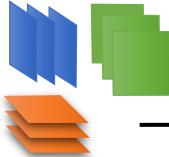


NTD-4 (case of 4th order tensor)

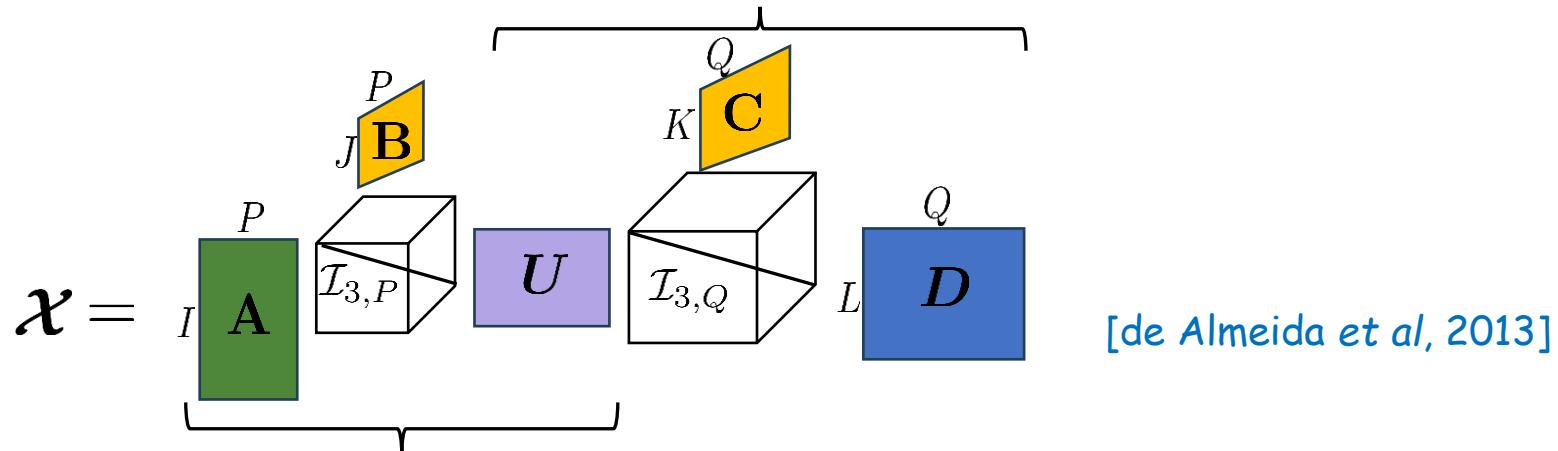


$$\begin{aligned} x_{i,j,k,l} &= \sum_{p=1}^P \sum_{q=1}^Q \sum_{r=1}^R \sum_{s=1}^S \underbrace{a_{i,p} c_{p,j,q}^{(1)} u_{q,r}}_{\text{Tucker-(2,3)}} c_{r,k,s}^{(2)} d_{l,s} \\ &= \sum_{p=1}^P \sum_{q=1}^Q \sum_{r=1}^R \sum_{s=1}^S a_{i,p} c_{p,j,q}^{(1)} \underbrace{u_{q,r} c_{r,k,s}^{(2)} d_{l,s}}_{\text{Tucker-(2,3)}} \end{aligned}$$

Nesting of two Tucker-(2,3) tensors that share a common factor matrix



Nested PARAFAC (case of 4th order tensor)



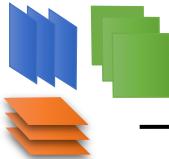
Special case of Nested Tucker (NTD-4) with the following correspondences:

$$(p, q, r, s) \Leftrightarrow (p, p, q, q)$$

$$(\mathbf{A}, \mathcal{C}^{(1)}, \mathbf{U}, \mathcal{C}^{(2)}, \mathbf{D}) \Leftrightarrow (\mathbf{A}, \mathbf{B}, \mathbf{U}, \mathbf{C}, \mathbf{D})$$

$$x_{i,j,k,l} = \sum_{p=1}^P \sum_{q=1}^Q \underbrace{a_{i,p} b_{j,p} u_{p,q}}_{\text{PARAFAC}} c_{k,q} d_{l,q} = \sum_{p=1}^P \sum_{q=1}^Q a_{i,p} b_{j,q} \underbrace{u_{p,q} c_{k,q} d_{l,q}}_{\text{PARAFAC}}$$

Nesting of two PARAFAC tensors that share a common factor matrix



Nested PARAFAC (con't)

Define the tensors $\mathcal{W} \in \mathbb{C}^{K \times L \times P}$, $\mathcal{Z} \in \mathbb{C}^{I \times J \times Q}$ such as

$$w_{k,l,p} = \sum_{q=1}^Q c_{k,q} d_{l,q} u_{p,q}$$

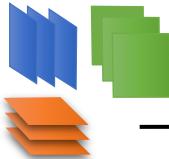
$$z_{i,j,q} = \sum_{p=1}^P a_{i,p} b_{j,p} u_{p,q}$$

or, equivalently in terms of mode- n products

$$\mathcal{W} = \mathcal{I}_{3,Q} \times_1 \mathbf{C} \times_2 \mathbf{D} \times_3 \mathbf{U}$$

$$\mathcal{Z} = \mathcal{I}_{3,P} \times_1 \mathbf{A} \times_2 \mathbf{B} \times_3 \mathbf{U}^T$$

→ \mathcal{W} , \mathcal{Z} satisfy two 3rd order PARAFAC models
that share a common factor matrix



Nested PARAFAC (con't)

- Unfoldings of \mathcal{W} , \mathcal{Z} :

$$\mathcal{W} = \mathcal{I}_{3,Q} \times_1 \mathbf{C} \times_2 \mathbf{D} \times_3 \mathbf{U} \longrightarrow [\mathcal{W}]_{(3)} = \mathbf{U}(\mathbf{C} \diamond \mathbf{D})^T$$

$$\mathcal{Z} = \mathcal{I}_{3,P} \times_1 \mathbf{A} \times_2 \mathbf{B} \times_3 \mathbf{U}^T \longrightarrow [\mathcal{Z}]_{(3)} = \mathbf{U}^T(\mathbf{A} \diamond \mathbf{B})^T$$

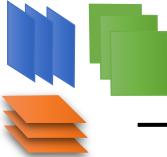
- Merging the last two modes, we get:

$$x_{i,j,t}^{(1)} = \sum_{p=1}^P a_{i,p} b_{j,p} w_{t,p} \quad \leftrightarrow \quad \mathcal{X}^{(1)} = \mathcal{I}_{3,P} \times_1 \mathbf{A} \times_2 \mathbf{B} \times_3 \underbrace{(\mathbf{C} \diamond \mathbf{D}) \mathbf{U}^T}_{[\mathcal{W}]_{(3)}^T}$$

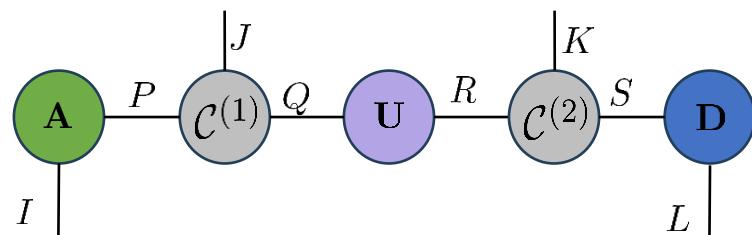
- Merging the first two modes, we get:

$$x_{m,k,l}^{(2)} = \sum_{q=1}^Q z_{m,q} c_{k,q} d_{l,q} \quad \leftrightarrow \quad \mathcal{X}^{(2)} = \mathcal{I}_{3,Q} \times_1 \underbrace{(\mathbf{A} \diamond \mathbf{B}) \mathbf{U}}_{[\mathcal{Z}]_{(3)}^T} \times_2 \mathbf{C} \times_3 \mathbf{D}$$

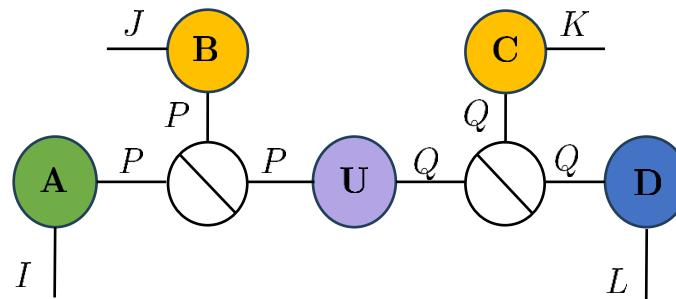
→ $\mathcal{X}^{(1)}$, $\mathcal{X}^{(2)}$ satisfy two nested 3rd-order PARAFAC models



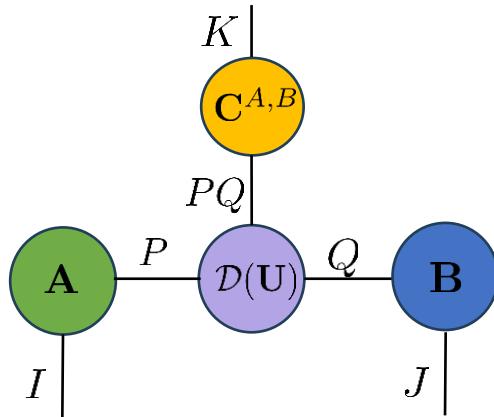
Comparisons using tensor network diagrams



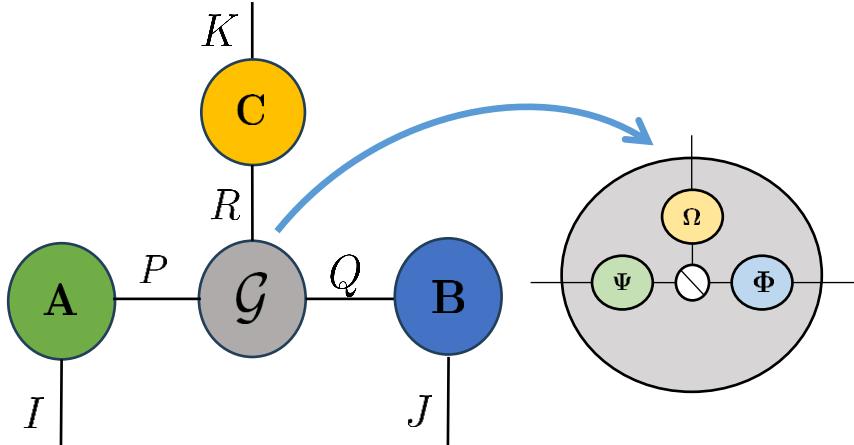
Nested Tucker-(2,4)



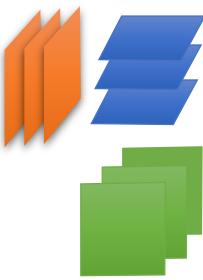
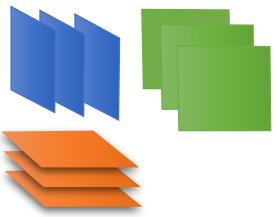
Nested PARAFAC-4



PARATUCK-(2,3)

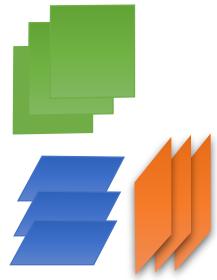


CONFAC-3

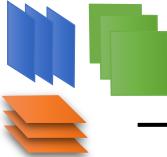


PART 2

Some applications



Modeling/estimation of MIMO channels



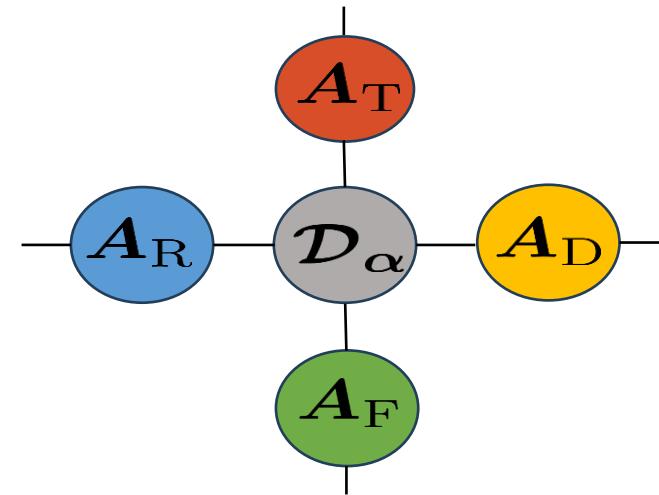
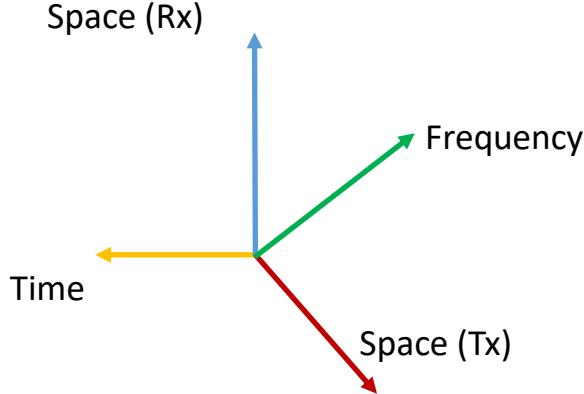
“Tensorizing” the MIMO channel model

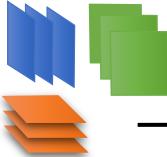
- Usual (matrix) notation

$$\boldsymbol{H}(t, f) = \sum_{\ell=1}^{N_p} \alpha_\ell e^{j2\pi(\nu_\ell t - \tau_\ell f)} \boldsymbol{a}_R(\theta_{R,\ell}, \phi_{R,\ell}) \boldsymbol{a}_T^*(\theta_{T,\ell}, \phi_{T,\ell})$$

- Tensor notation (4D tensor, rank- N_p)

$$\mathcal{H} = \mathcal{D}_{\alpha} \times_1 \boldsymbol{A}_R(\boldsymbol{\theta}_R, \boldsymbol{\phi}_R) \times_2 \boldsymbol{A}_T(\boldsymbol{\theta}_T, \boldsymbol{\phi}_T) \times_3 \boldsymbol{A}_D(\boldsymbol{\nu}) \times_4 \boldsymbol{A}_F(\boldsymbol{\tau})$$





“Tensorizing” the channel model (cont’d)

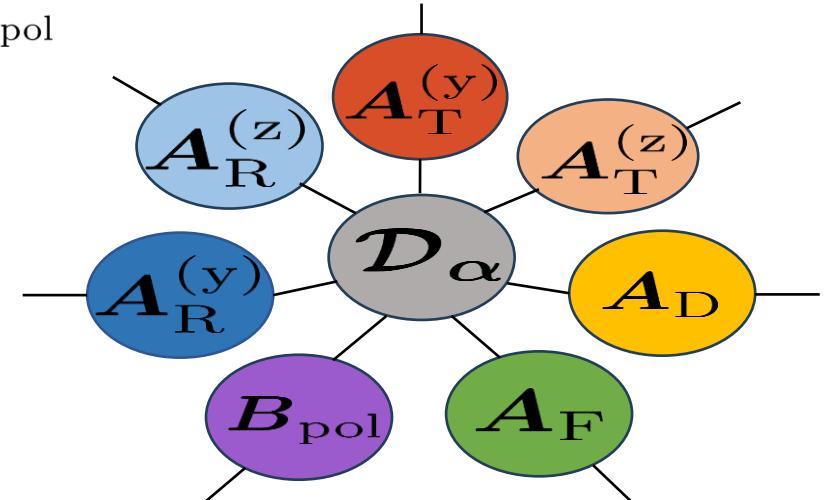
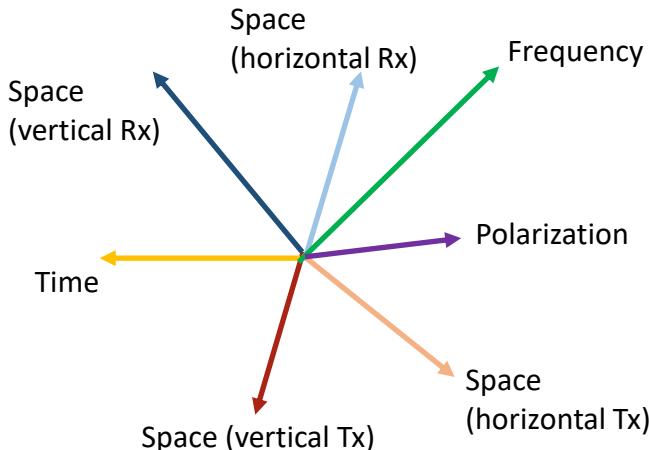
- Expanding the tensor (+ 2D antenna arrays, e.g. URA)

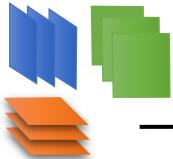
$$A_R(\theta_R, \phi_R) = A_R(\mu_R^{(y)}) \diamond A_R(\mu_R^{(z)}) \quad A_T(\theta_T, \phi_T) = A_T(\mu_T^{(y)}) \diamond A_T(\mu_T^{(z)})$$

$$\mathcal{H} = \mathcal{D}_\alpha \times_1 A_R^{(y)}(\mu_R^{(y)}) \times_2 A_R^{(z)}(\mu_R^{(z)}) \times_3 A_T^{(y)}(\mu_T^{(y)}) \times_4 A_T^{(z)}(\mu_T^{(z)}) \\ \times_5 A_D(\nu) \times_6 A_F(\tau)$$

- Expanding the tensor (+ polarization) → 7 dimensions

$$\mathcal{H} = \mathcal{D}_\alpha \times_1 A_R(\mu_R^{(1)}) \times_2 A_R(\mu_R^{(2)}) \times_3 A_T(\mu_T^{(1)}) \times_4 A_T(\mu_T^{(2)}) \\ \times_5 A_D(\nu) \times_6 A_F(\tau) \times_7 B_{\text{pol}}$$





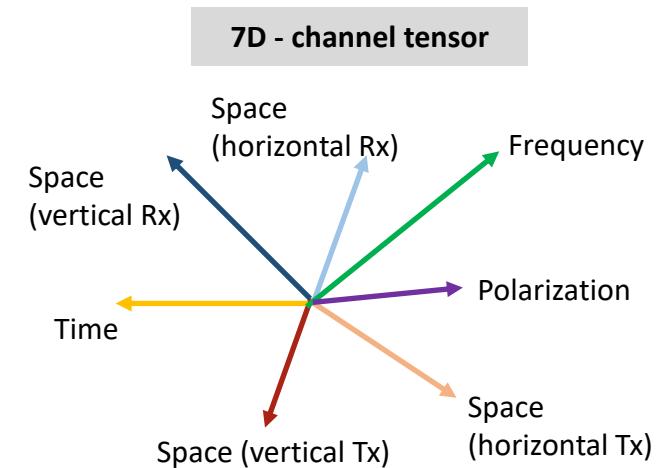
Tensor Train Based Channel Estimation

- MIMO channel (rectangular arrays, dual-polarized antennas)

$$\mathcal{H} = \mathcal{I}_{7, N_p} \times_1 \bar{\mathbf{A}}_R^{(x)} \times_2 \bar{\mathbf{A}}_R^{(y)} \times_3 \bar{\mathbf{A}}_T^{(x)*} \times_4 \bar{\mathbf{A}}_T^{(y)*} \times_5 \bar{\mathbf{A}}_D \times_6 \bar{\mathbf{A}}_F \times_7 \bar{\mathbf{B}}_{\text{pol}}$$

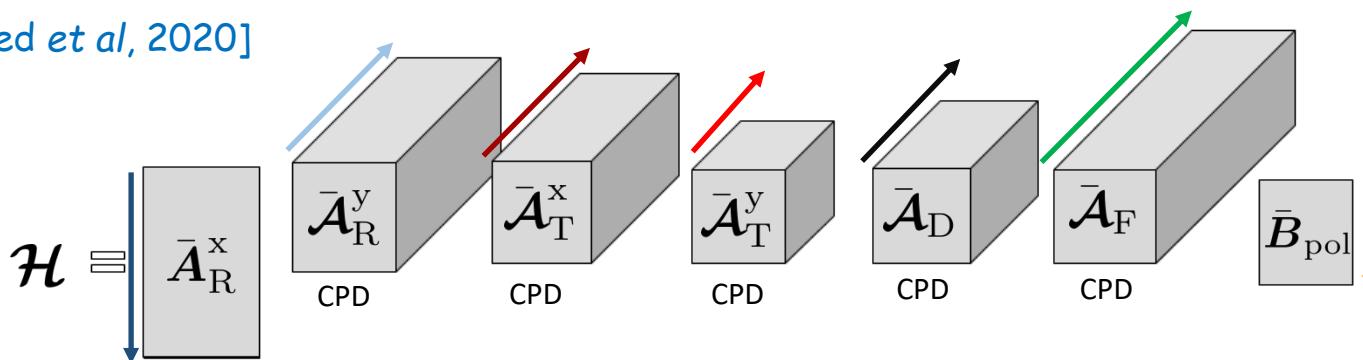
Example: 64 x 32 URA MIMO, T=10, F= 128, 4 polarization pairs
coefficients: 10.485.760 → very large tensor!!

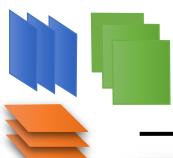
How to reduce complexity of channel representation and estimation ?



- Recasting the channel using Tensor Train model

[Znyed et al, 2020]

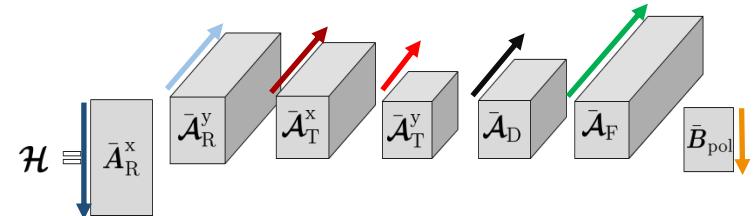




Tensor Train Based Channel Estimation (cont'd)

Tensor Train Representation of Massive MIMO Channels using the Joint Dimensionality Reduction and Factor Retrieval (JIRAFE) Method

Yassine Zniyed, Rémy Boyer, Senior Member, IEEE, André L. F. de Almeida, Senior Member, IEEE, and Gérard Favier



Dimensionality reduction

[Znyed et al., 2020]

Tensor Train – SVD (TT-SVD)

$$[\bar{\mathbf{A}}_R^{(x)}, \bar{\mathbf{A}}_R^{(y)}, \bar{\mathbf{A}}_T^{(x)}, \bar{\mathbf{A}}_T^{(y)}, \bar{\mathbf{A}}_D, \bar{\mathbf{A}}_F, \bar{\mathbf{B}}_{\text{pol}}] \leftarrow \text{TT-SVD}(\mathcal{H}, N_p)$$

Factors retrieval

Coupled LS optimization

$$F_{\text{global}} = \sum_{i=1}^7 F_i$$

CPD's

$$F_1 = \| |\bar{\mathbf{A}}_R^{(x)} - \mathbf{A}_R^{(x)} \mathbf{M}_1^{-1}| \|_F^2$$

$$F_2 = \| |\bar{\mathbf{A}}_R^{(y)} - \mathcal{I}_{3,N_p} \times_1 \mathbf{M}_1 \times_2 \mathbf{A}_R^{(y)*} \times_3 \mathbf{M}_2^{-T}| \|_F^2$$

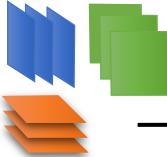
$$F_3 = \| |\bar{\mathbf{A}}_T^{(x)} - \mathcal{I}_{3,N_p} \times_1 \mathbf{M}_2 \times_2 \mathbf{A}_T^{(x)*} \times_3 \mathbf{M}_3^{-T}| \|_F^2$$

$$F_4 = \| |\bar{\mathbf{A}}_T^{(y)} - \mathcal{I}_{3,N_p} \times_1 \mathbf{M}_3 \times_2 \mathbf{A}_T^{(y)*} \times_3 \mathbf{M}_4^{-T}| \|_F^2$$

$$F_5 = \| |\bar{\mathbf{A}}_D - \mathcal{I}_{3,N_p} \times_1 \mathbf{M}_4 \times_2 \mathbf{A}_D \times_3 \mathbf{M}_5^{-T}| \|_F^2$$

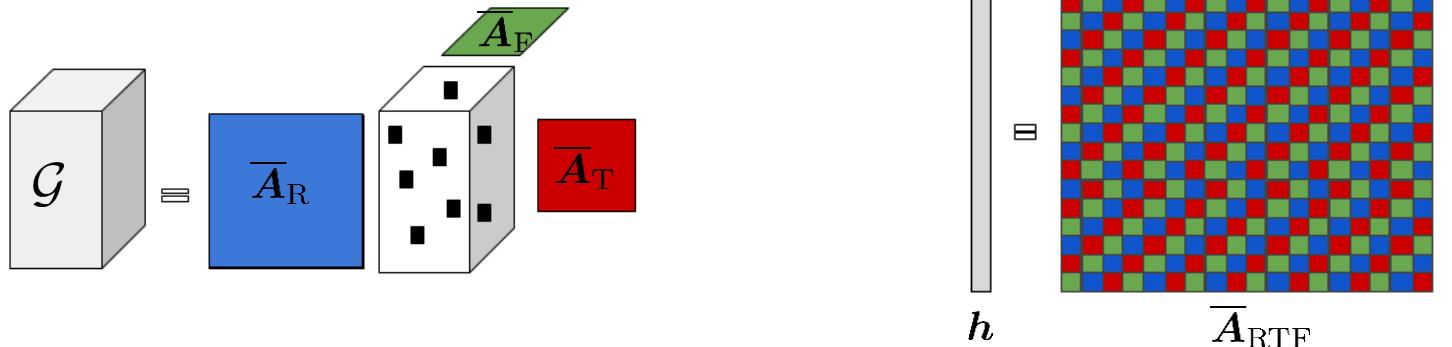
$$F_6 = \| |\bar{\mathbf{A}}_F - \mathcal{I}_{3,N_p} \times_1 \mathbf{M}_5 \times_2 \mathbf{A}_F \times_3 \mathbf{M}_6^{-T}| \|_F^2$$

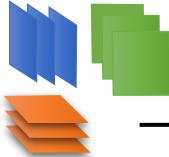
$$F_7 = \| |\bar{\mathbf{B}}_{\text{pol}} - \mathbf{M}_6 \mathbf{B}_{\text{pol}}| \|_F^2$$



Sparse channel modeling & estimation

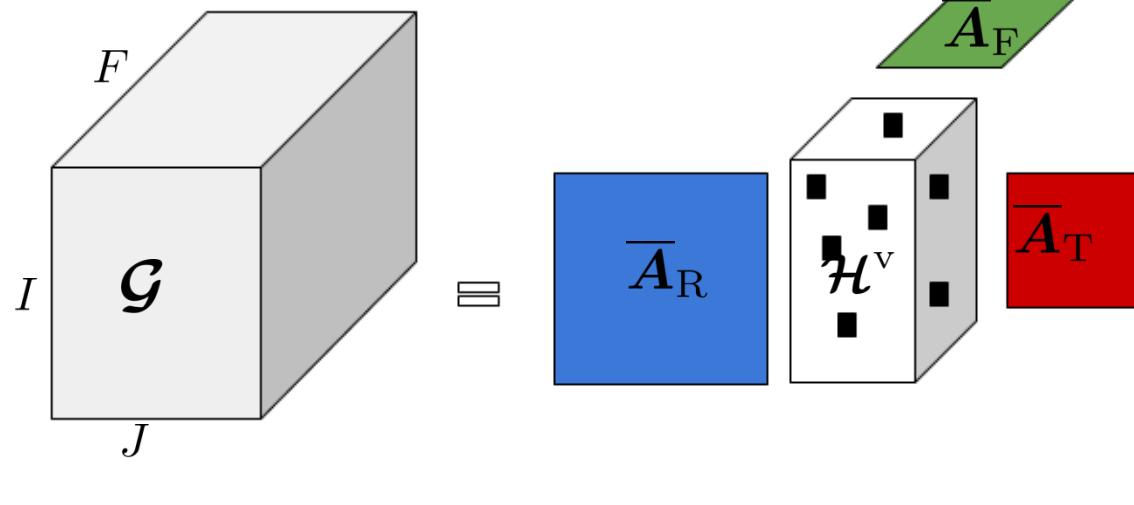
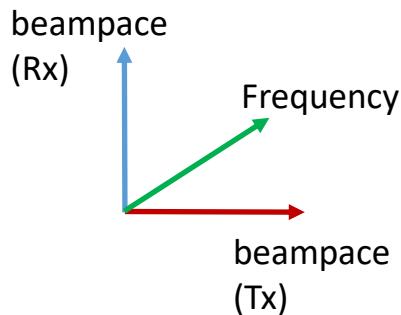
- Realistic channel models are not i.i.d \rightarrow highly structured
- Algebraic channel structure is heterogeneous in different domains (e.g. space, frequency, time, polarization, etc...)
- Multidimensional channel structure is lost when working with vectorized (or “matricized”) versions of the channel



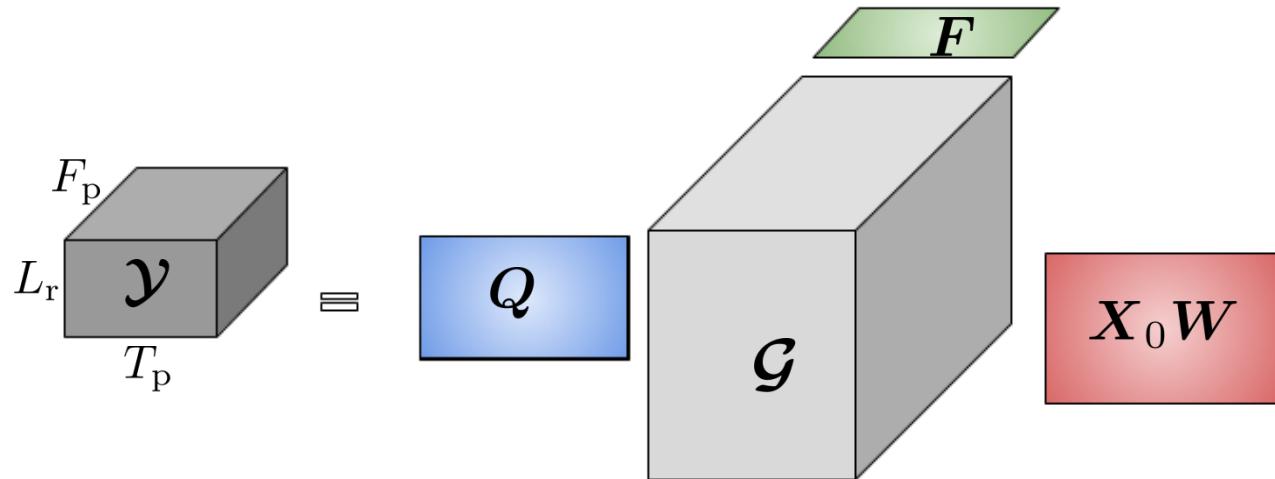
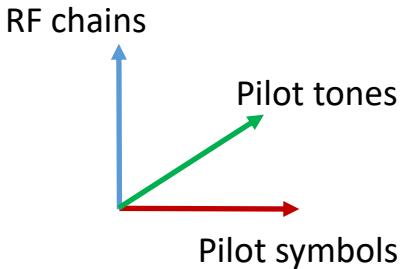


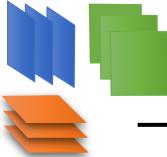
Sparse channel modeling & estimation (cont'd)

Channel tensor (sparse Tucker-3)



Compressed Rx signal tensor





Sparse channel modeling & estimation

- Expanding the 3D sparse channel tensor...

$$\mathcal{Y} = \mathcal{H}^v \times_1 (\mathbf{Q}\overline{\mathbf{A}}_R) \times_2 (\mathbf{X}_0 \mathbf{W}\overline{\mathbf{A}}_T) \times_3 (\mathbf{F}\overline{\mathbf{A}}_F) + \tilde{\mathbf{z}}$$

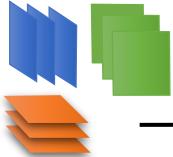
Multi-linear compression !

[Caiafa & Cichocki'2013]
[Friedland, Li, Schonfeld '2014]

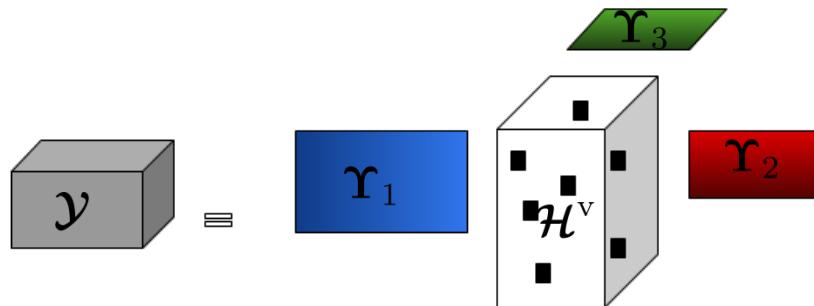
- Equivalent “vectorized” Kronecker- CS model [Duarte & Braniuk'2012]

$$\mathbf{y} = [(\mathbf{F}\overline{\mathbf{A}}_F) \otimes (\mathbf{X}_0 \mathbf{W}\overline{\mathbf{A}}_T) \otimes (\mathbf{Q}\overline{\mathbf{A}}_R)] \mathbf{h}^v + \tilde{\mathbf{z}}$$

$$\mathbf{y} = \text{vec}(\mathcal{Y}), \quad \mathbf{h}^v = \text{vec}(\mathcal{H}^v), \quad \tilde{\mathbf{z}} = \text{vec}(\tilde{\mathbf{Z}})$$



Tensor-CS vs. Vector-CS

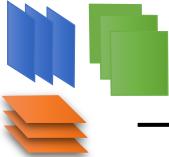


$$O((L_r + T_p + F_p))\log(L_r + T_p + F_p) \leq C \leq O(L_r^3 + T_p^3 + F_p^3)$$

The diagram shows a vertical gray bar labeled y on the left, followed by an equals sign. To its right is a bracketed expression: $\left[\Upsilon_3 \otimes \Upsilon_2 \otimes \Upsilon_1 \right]$. To the right of the bracket is a vertical bar with alternating black and white segments, labeled h^v at the bottom.

Complexity reduction

$$O(L_r T_p F_p \log(L_r T_p F_p)) \leq C \leq O(L_r^3 T_p^3 F_p^3)$$



Exploiting multilinearity + sparsity + low-rankness

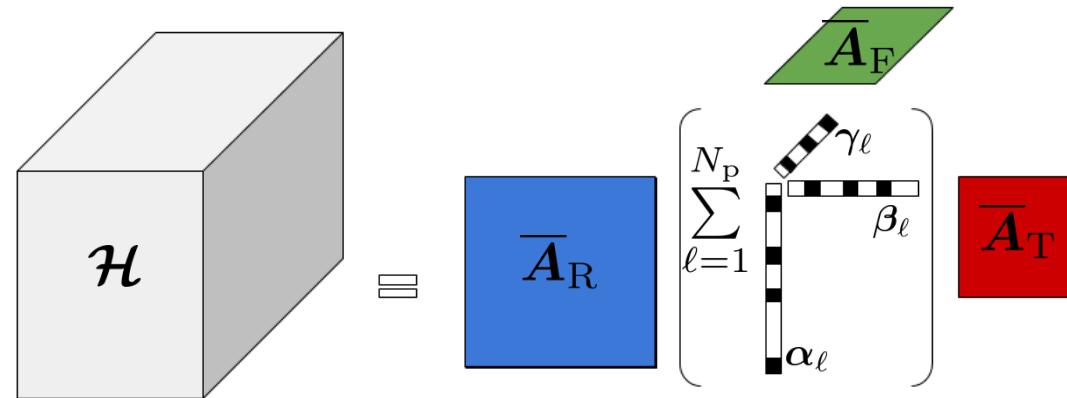
- MIMO channel tensor w/ correlated scattering (angular spread)

$$\mathcal{H} = \sum_{\ell=1}^{N_p} (\mathbf{A}_R^{(\ell)} \boldsymbol{\alpha}_\ell) \circ (\mathbf{A}_T^{(\ell)} \boldsymbol{\beta}_\ell) \circ (\mathbf{A}_F^{(\ell)} \boldsymbol{\gamma}_\ell) \text{ PARAFAC/CPD}$$

$$= \left(\sum_{\ell=1}^{N_p} \boldsymbol{\alpha}_\ell \circ \boldsymbol{\beta}_\ell \circ \boldsymbol{\gamma}_\ell \right) \times_1 \overline{\mathbf{A}}_R \times_2 \overline{\mathbf{A}}_T \times_3 \overline{\mathbf{A}}_F$$

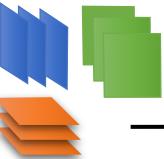
Sparse PARAFAC core

\longrightarrow Basis matrices
(dictionaries)



Tucker-3 model w/ sparse PARAFAC core

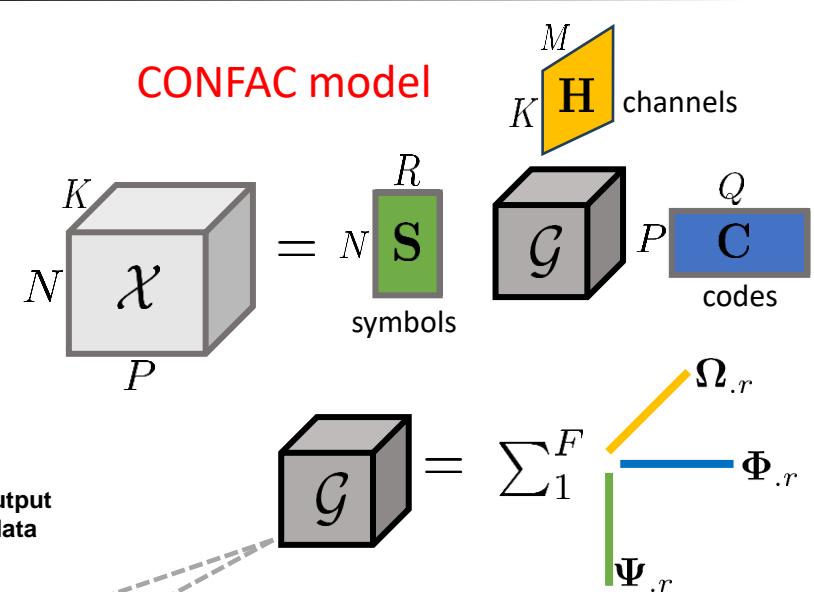
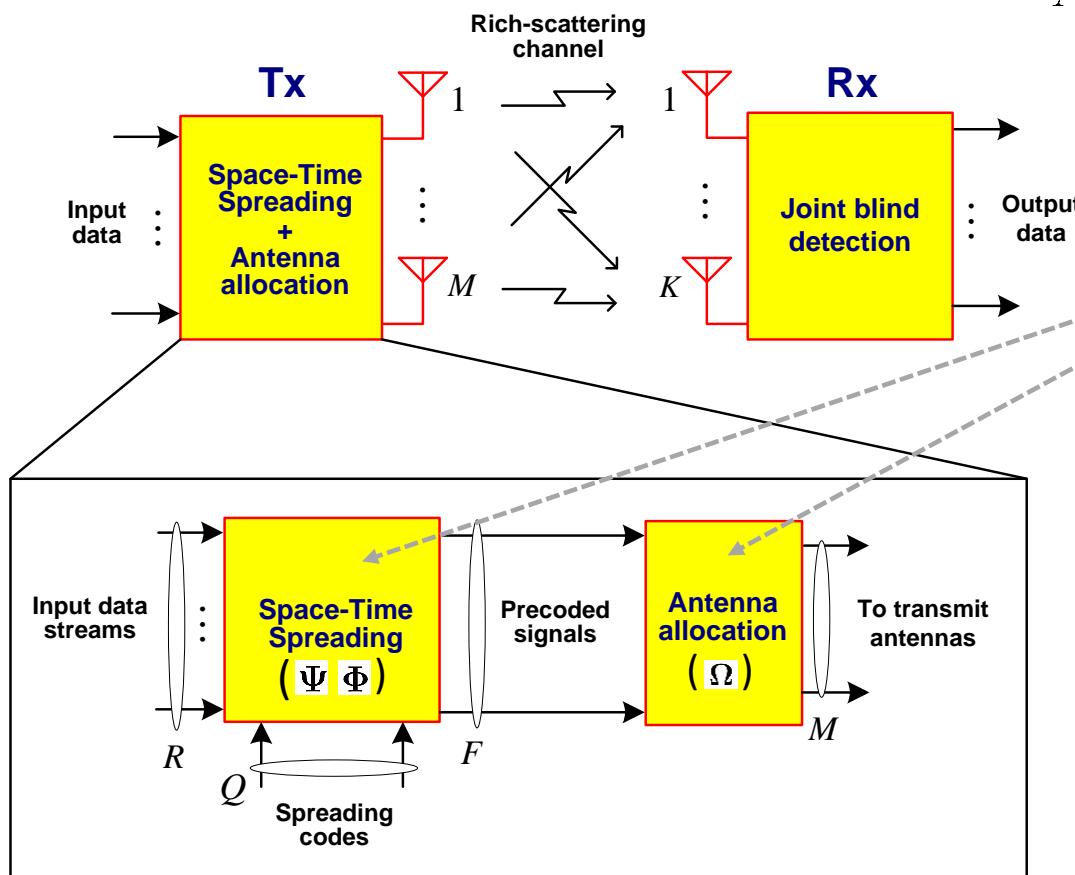
Design of semi-blind MIMO systems



CONFAC based MIMO transceivers

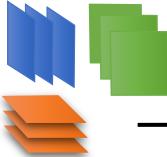
Idea [de Almeida & Favier, 2008]

- Design **flexible space-time MIMO** schemes
- Capitalize on the **CONFAC uniqueness** to jointly estimate channel and symbols at the receiver



- $\Psi \rightarrow$ symbol allocation ($R \times F$)
- $\Phi \rightarrow$ code allocation ($Q \times F$)
- $\Omega \rightarrow$ antenna allocation ($M \times F$)

Designing tensor G defines the transmission scheme!



CONFAC-based MIMO system

Key features

- **Variable antenna allocation patterns:** Multiple data streams per transmit antenna
 - **Variable spreading code reuse patterns:** Spreading codes can be reused by TX antennas
 - **Transmission flexibility:** Several schemes possible by adjusting the allocation matrices
- Received signal (n -th symbol, p -th chip, k -th Rx antenna):

$$x_{k,n,p} = \sum_{m=1}^M \sum_{r=1}^R s_{n,r} c_{p,q} h_{k,m} g_{r,q,m} (\Psi, \Phi, \Omega)$$

Resource allocation tensor

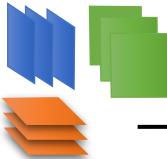
with $F \geq \max(R, Q, M)$

PARAFAC DS-CDMA model

[Sidiropoulos et al, 2000]

Note: columns of Ψ , Φ , and Ω are canonical basis vectors (1's and 0's)

$$\begin{aligned}\Psi &= \Phi = \Omega = \mathbf{I}_F \\ \mathcal{G}(\Psi, \Phi, \Omega) &= \mathcal{I}_F\end{aligned}$$



Tensor Space-Time-Frequency (T-STF) Coding

Idea [de Almeida and Favier, 2014]

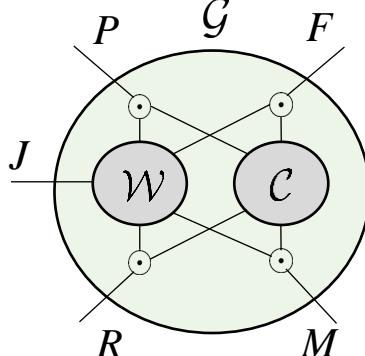
- Design generalized STF coding scheme with **allocation flexibility** over different STF domains (**MIMO-OFDM-CDMA**)

• Received signal (noiseless case)

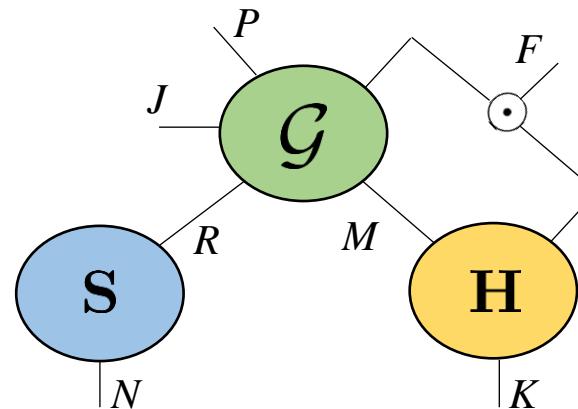
$$\mathcal{X} = \mathcal{G} \times_1 \mathcal{H} \times_2 \mathbf{S} \rightarrow \text{Tucker-(2-5) model}$$

with $\mathcal{G} = \mathcal{W} \odot_{\{m,r,f,p\}} \mathcal{C}$

spreading tensor allocation tensor



Coding tensor diagram

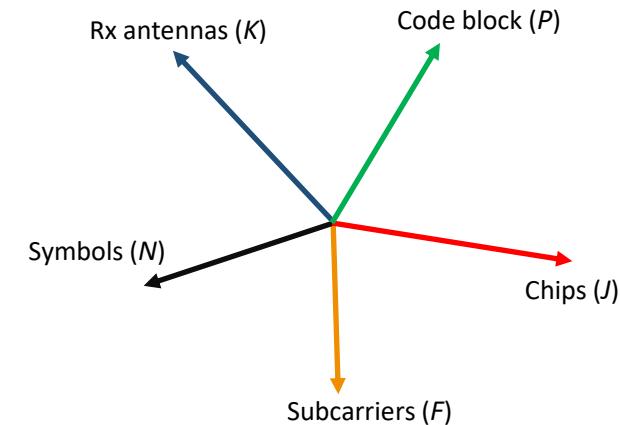


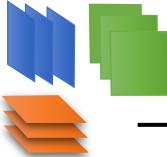
Received signal tensor diagram

• T-STF coding model (5D)

$$x_{k,n,f,p,j} = \sum_{m=1}^M \sum_{r=1}^R g_{m,r,f,p,j} h_{k,m,f} s_{n,r}$$

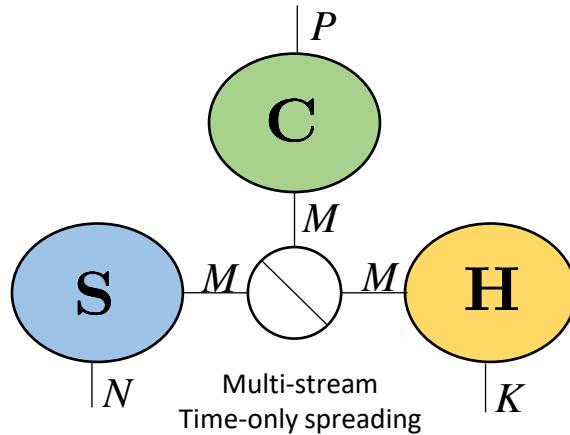
↓ ↓ ↓
Code tensor Channel tensor Symbol matrix



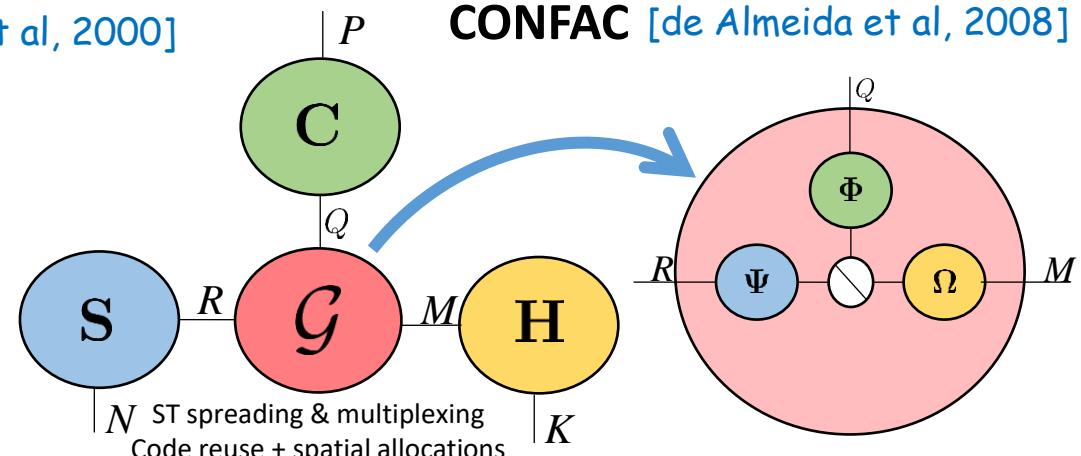


T-STF vs. CONFAC vs. PARAFAC schemes

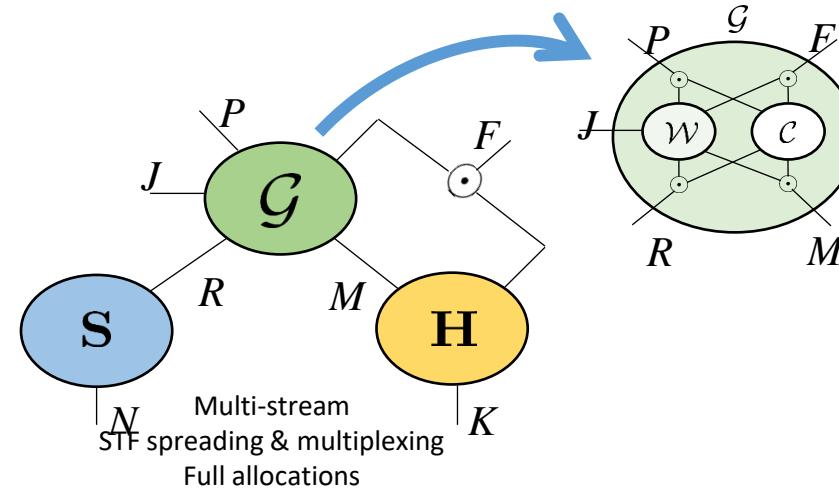
PARAFAC [Sidiropoulos et al, 2000]



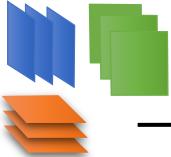
CONFAC [de Almeida et al, 2008]



T-STF [de Almeida & Favier, 2014]



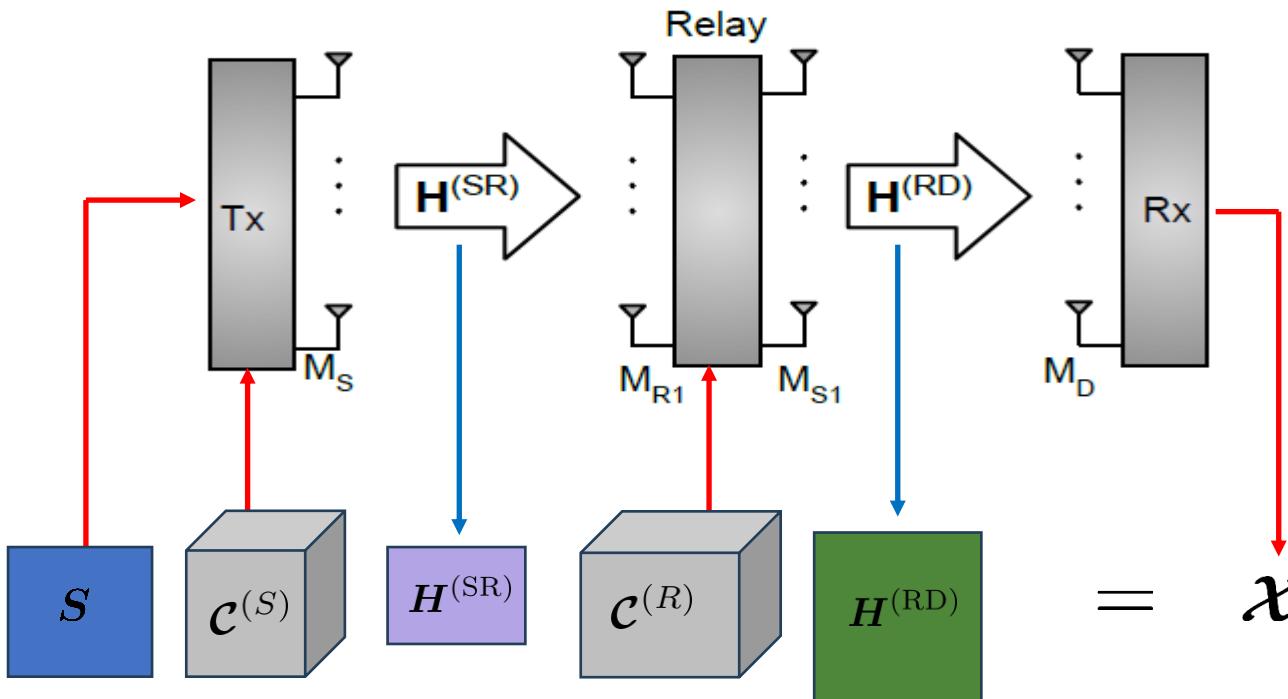
MIMO Relay Systems



Semi-Blind MIMO Relay Systems

Idea: Use tensor coding at source and relay to jointly estimate the involved channels (source-relay and relay-destination)

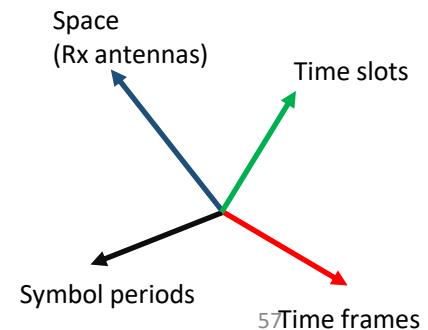
[Ximenes et al, 2015]
[Fernandes et al, 2016]
[Znyed et al, 2018]
[Sokal et al, 2020]



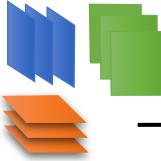
Nested Tucker-(2,4) model

$$\mathcal{X} = (\mathcal{C}^{(S)} \times_2^1 \mathbf{H}^{(\text{SR})} \times_2^1 \mathcal{C}^{(R)}) \times_1 \mathbf{S} \times_2 \mathbf{H}^{(\text{RD})}$$

$$\mathcal{X} \in \mathbb{C}^{T \times P \times J \times M_R}$$

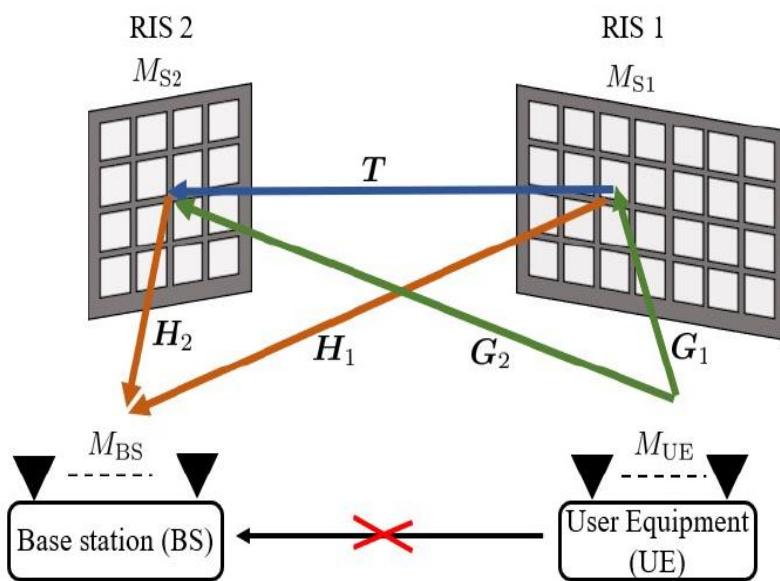


Reconfigurable Intelligent Surfaces



Channel estimation with Reconfigurable Surfaces

Problem: Jointly estimate multiple channels in a communication system aided by **reconfigurable surfaces** [de Almeida et al, 2024]



Single reflection links (PARAFAC):

$$\mathcal{Y}_{\text{RIS}_1} = \mathcal{I}_{3,M_{S1}} \times_1 \mathbf{H}_1 \times_2 \mathbf{G}_1^T \times_3 \boldsymbol{\Theta}_1$$

and

$$\mathcal{Y}_{\text{RIS}_2} = \mathcal{I}_{3,M_{S1}} \times_1 \mathbf{H}_2 \times_2 \mathbf{G}_2^T \times_3 \boldsymbol{\Theta}_2$$

Double reflection links (Nested PARAFAC):

$$\mathcal{Y}_{\text{RIS}_{12}}^{(1)} = \mathcal{I}_{3,M_{S2}} \times_1 \mathbf{H}_2 \times_2 [\boldsymbol{\Theta}_1 \diamond \mathbf{G}_1^T] \mathbf{T}^T \times_3 \boldsymbol{\Theta}_2$$

or

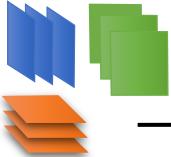
$$\mathcal{Y}_{\text{RIS}_{12}}^{(2)} = \mathcal{I}_{3,M_{S1}} \times_1 [\boldsymbol{\Theta}_2 \diamond \mathbf{H}_2] \mathbf{T} \times_2 \mathbf{G}_1^T \times_3 \boldsymbol{\Theta}_1$$

Combine $\mathcal{Y}_{\text{RIS}_1}$ and $\mathcal{Y}_{\text{RIS}_{12}}^{(2)}$ to estimate \mathbf{G}_1

→ Coupled Nested PARAFAC decomp.

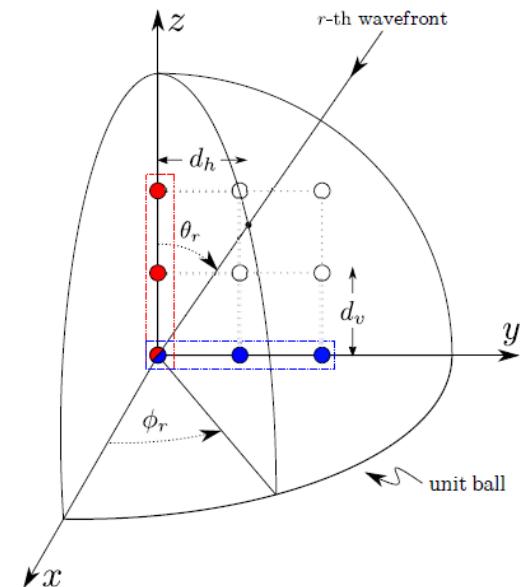
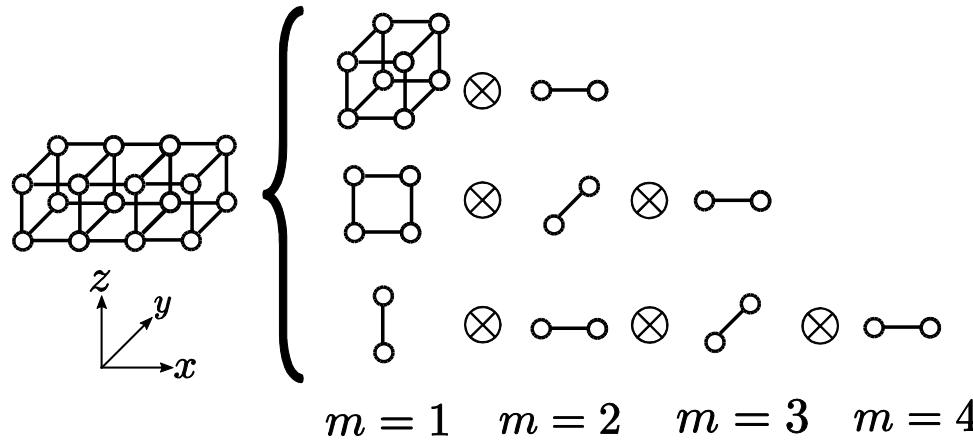
Combine $\mathcal{Y}_{\text{RIS}_2}$ and $\mathcal{Y}_{\text{RIS}_{12}}^{(1)}$ to estimate \mathbf{H}_2

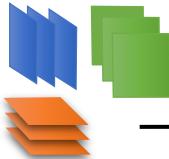
Multi-Linear Beamforming



Why multi-linear beamforming?

- As the size of a sensor array grows, the beamforming operation needs more...
 - ❖ Samples to estimate statistics
 - ❖ Computation time to obtain weights
- **Idea:** Exploit the algebraic structure of separable arrays → multi-linearity property





Multi-linear filtering

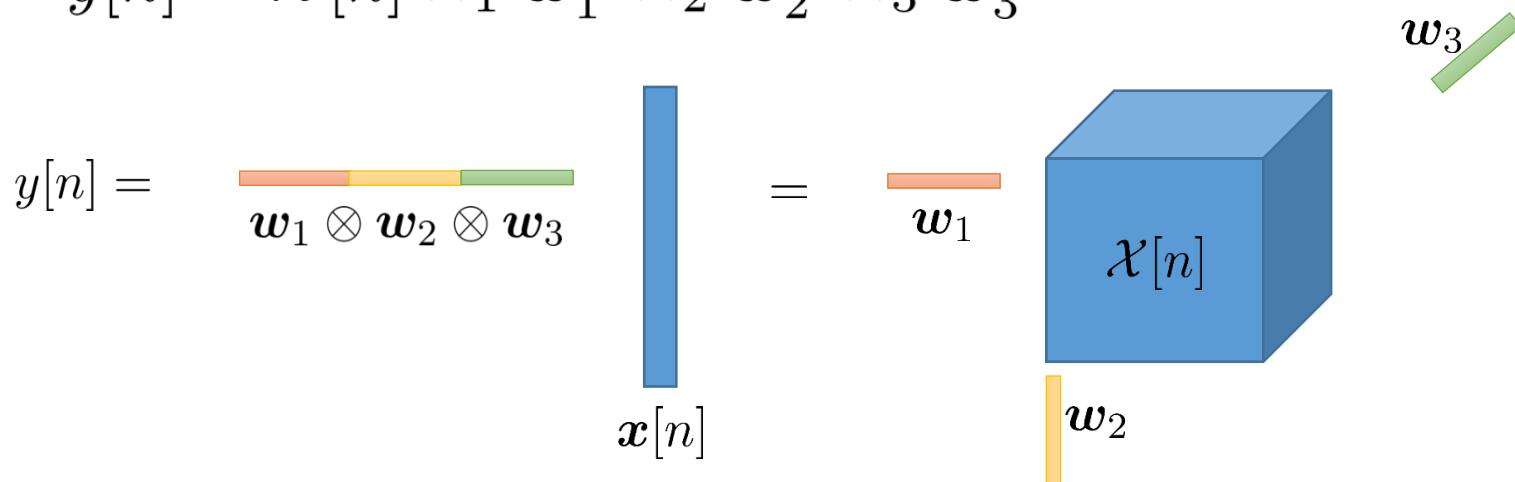
Idea: Kronecker filters as multilinear maps

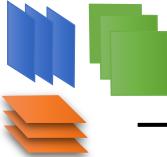
- Consider the trilinear filter:

$$y[n] = \mathbf{w}^H \mathbf{x}[n] = (\mathbf{w}_1 \otimes \mathbf{w}_2 \otimes \mathbf{w}_3)^H \mathbf{x}[n]$$

- Reshape the input signal vector into a 3d tensor:

$$y[n] = \mathcal{X}[n] \times_1 \mathbf{w}_1^H \times_2 \mathbf{w}_2^H \times_3 \mathbf{w}_3^H$$





Multi-linear filtering (cont'd)

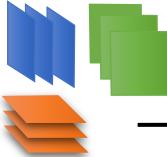
- From tensor algebra, the trilinear filter output can be written as

$$\begin{aligned} y[n] &= \mathbf{w}_1^H \mathbf{X}_{(1)}[n] (\mathbf{w}_3 \otimes \mathbf{w}_2)^* = \mathbf{w}_1^H \mathbf{u}_1[n] \\ &= \mathbf{w}_2^H \mathbf{X}_{(2)}[n] (\mathbf{w}_3 \otimes \mathbf{w}_1)^* = \mathbf{w}_2^H \mathbf{u}_2[n] \\ &= \mathbf{w}_3^H \mathbf{X}_{(3)}[n] (\mathbf{w}_2 \otimes \mathbf{w}_1)^* = \mathbf{w}_3^H \mathbf{u}_3[n] \end{aligned}$$

Keep fixed Linear w.r.t. each subfilter

Idea:

- Design each “subfilter” instead of full filter
- Computational complexity reduction



Tensor beamforming algorithms

- Alternating optimization approaches

- ❖ Tensor LMS [Rupp & Schwarz'2015]
- ❖ Tensor GSC [Miranda et al'2015]
- ❖ **Tensor MMSE** [Ribeiro et al'2016, Ribeiro et al'2019]
- ❖ **Tensor LCMV** [Ribeiro et al'2019]
- ❖ **Tensor Frost** [Ribeiro et al'2019]

**N -dimensional filter
with $N = N_1 N_2 N_3$**

- Example: Trilinear filter design $w = w_1 \otimes w_2 \otimes w_3$

1. Random initialization for w_1, w_2, w_3 $N_1 \quad N_2 \quad N_3$
2. Optimize for w_1 with w_2, w_3 fixed – $O(N_1^3)$ multiplications
3. Optimize for w_2 with w_1, w_3 fixed – $O(N_2^3)$ multiplications
4. Optimize for w_3 with w_1, w_2 fixed – $O(N_3^3)$ multiplications
5. Has converged? If not, go back to step 2

$O(N_1^3 + N_2^3 + N_3^3)$ vs. $O(N^3)$

Each filter is updated with alternating optimization methods

Multi-linear Constellation Designs

Multi-linear constellation design

Principle

Any M -PSK constellation can be factorized into $P \leq \log_2 M$ different constellation sets:

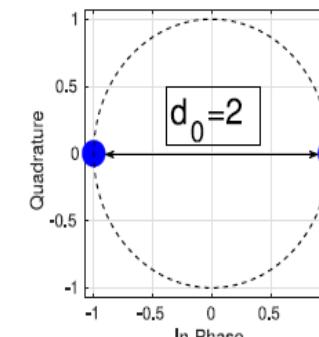
$$\Phi = \Phi_0 \otimes \Phi_1 \cdots \otimes \Phi_{P-1}$$

Signal model

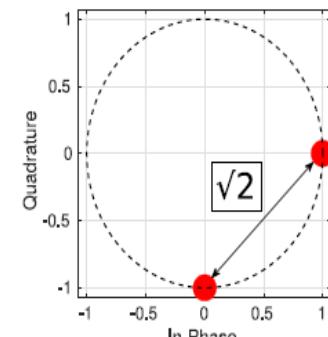
$$\mathbf{y}[k] = h[k]\mathbf{x}[k] + \mathbf{n}[k]$$

with

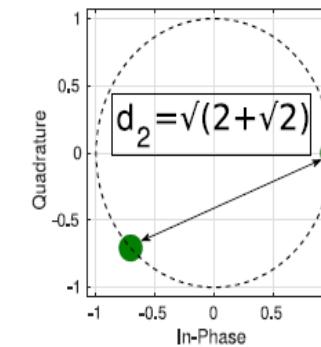
$$\mathbf{x}[k] = \mathbf{s}_N[k] \otimes \cdots \otimes \mathbf{s}_1[k]$$



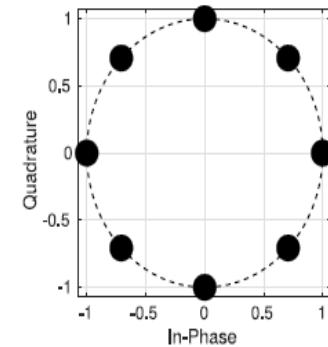
(a) $\Phi_0 \in \text{BPSK}$



(b) Φ_1

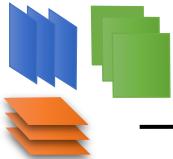


(c) Φ_2

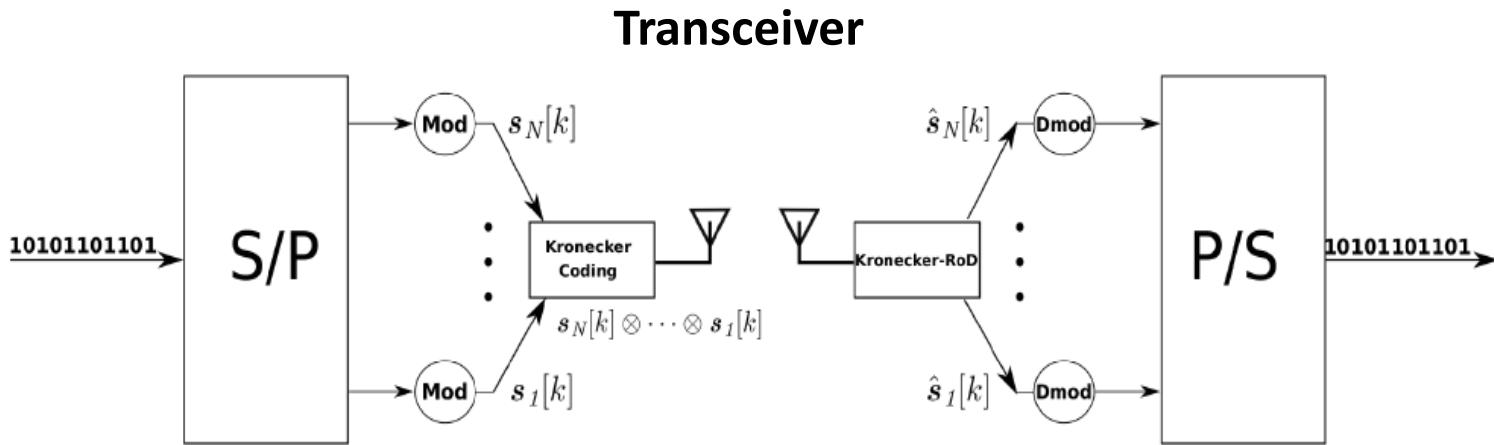


(d) $\Phi = \Phi_0 \otimes \Phi_1 \otimes \Phi_2$

Multi-linear M -PSK constellation



Multi-linear constellation design



- Received signal after matched filtering (MF)
$$\hat{\mathbf{y}}[k] = h^*[k]\mathbf{y}[k]$$
- Decoding as N -th order rank-one tensor approx. problem
$$\min_{\mathbf{s}_1, \dots, \mathbf{s}_N} \left\| \hat{\mathcal{Y}} - \mathbf{s}_1 \circ \dots \circ \mathbf{s}_N \right\|_F^2$$
- Equivalent solution: maximize the tensor Rayleigh quotient

$$T(\mathbf{s}_1, \dots, \mathbf{s}_N) = \frac{|(\mathbf{s}_N \otimes \dots \otimes \mathbf{s}_1)^T \text{vec}(\hat{\mathcal{Y}})|}{\|\mathbf{s}_1\|_2 \dots \|\mathbf{s}_N\|_2}$$

Multi-linear constellation design

1420

IEEE SIGNAL PROCESSING LETTERS, VOL. 27, 2020

Rank-One Detector for Kronecker-Structured Constant Modulus Constellations

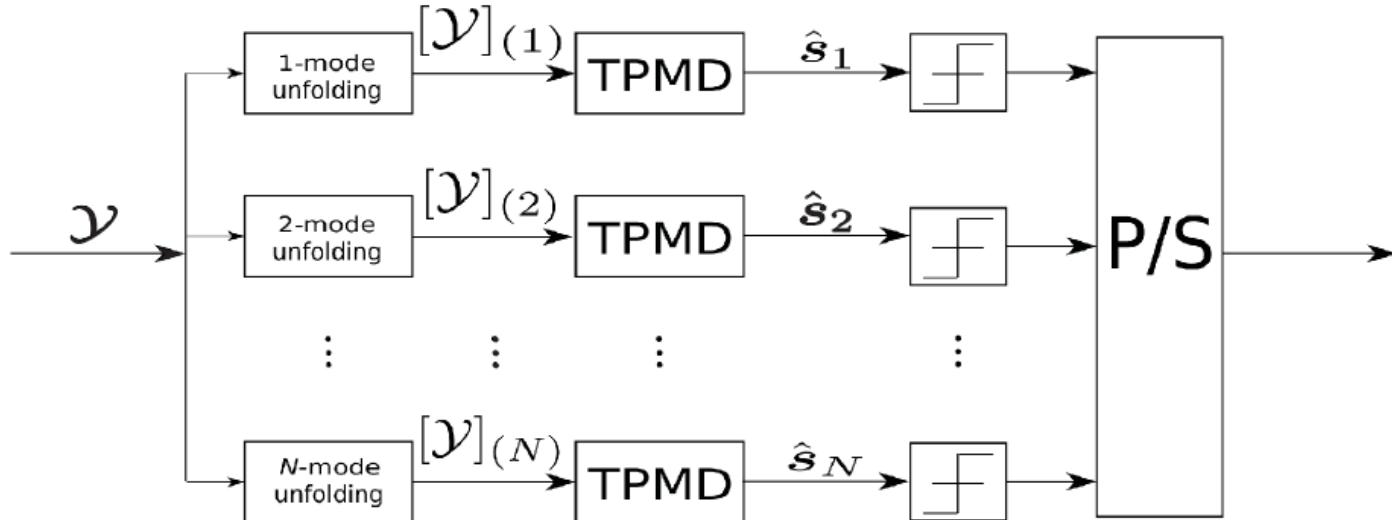
Fazal- E-Asim , Student Member, IEEE, André L. F. de Almeida , Senior Member, IEEE,
Martin Haardt , Fellow, IEEE, Charles C. Cavalcante , Senior Member, IEEE,
and Josef A. Nossek , Life Fellow, IEEE

Abstract—To achieve a reliable communication with short data blocks, we propose a novel decoding strategy for Kronecker-

codes and has good performance in additive white Gaussian noise (AWGN) channels. The constellation rotation angle

Receiver processing

Kronecker Rank-One Detector (Kronecker-RoD)



Note: Decoding can be parallelized → reduced latency

Thank you!

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-  Fortaleza, Brazil