# R package Rfmtool for handling and fitting fuzzy measures. Version 2.0 User Manual

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Rfmtool partly depends on another package, lpsolve, which is also distributed under Lesser GPL.

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# Chapter 1

### Introduction

This manual describes the programming library Rfmtool, which provides various tools for handling fuzzy measures, calculating various indices, Choquet and Sugeno integrals, as well as fitting fuzzy measures to empirical data. This package is designed for R, but is also includes the C++ source files and this user manual.

Chapter 2 provides some background on fuzzy measures. A more detailed overview can be found in [4,8,12] and references therein. Chapter 3 outlines computational methods used to fit fuzzy measures to empirical data. The description of the programming library Rfmtool is given in Chapter 4. Examples of its usage are provided in Section 4.4.

To cite Rfmtool package, use references [2-4].

#### New in version 2

We added fitting K-maxitive and K-tolerant fuzzy measures, based on linear and mixed integer programming. See functions fittingktolerant and fittingK-maxitive.

We added a method for fitting sub-modular fuzzy measures reported in [3]. Supermodular fuzzy measure can also be fit by using duality: construct dual data set, fit a sub-modular fuzzy measure and then compute its dual. See function FuzzyMeasureFitLP.

We added an extra requirement of preservation of output ordering. See function FuzzyMeasureFitLP.

Fixed many warnings in the lpsolve code.

# Chapter 2

# Background on fuzzy measures

#### 2.1 Preliminaries

**Definition 1 (Aggregation function)** An aggregation function is a function of n > 1 arguments that maps the (n-dimensional) unit cube onto the unit interval  $f: [0,1]^n \to [0,1]$ , with the properties

(i) 
$$f(\underbrace{0,0,\ldots,0}_{n-times}) = 0$$
 and  $f(\underbrace{1,1,\ldots,1}_{n-times}) = 1$ .

(ii) 
$$\mathbf{x} \leq \mathbf{y}$$
 implies  $f(\mathbf{x}) \leq f(\mathbf{y})$  for all  $\mathbf{x}, \mathbf{y} \in [0, 1]^n$ .

A large family of aggregation functions is based on Choquet and Sugeno integrals. The Choquet integral generalizes the Lebesgue integral, and like it, is defined with respect to a measure. We note that measures can be additive (the measure of a set is the sum of the measures of its non-intersecting subsets) or non-additive. Lengths, areas and volumes are examples of additive measures. Lebesgue integration is defined with respect to additive measures. If a measure is non-additive, then the measure of the total can be larger or smaller than the sum of the measures of its components.

Choquet and Sugeno integration are defined with respect to not necessarily additive monotone measures, called fuzzy measures (see Definition 2 below), or *capacities*. In this manual we are interested only in *discrete* fuzzy measures, which are defined on finite discrete subsets. This is because our construction of aggregation functions involves a finite set of inputs.

The main purpose of Choquet integral-based aggregation is to combine the inputs in such a way that not only the importance of individual inputs (as in weighted means), or of their magnitude (as in OWA), are taken into account, but also of their groups (or coalitions). For example, a particular input may not be important by itself, but become very important in the presence of some other inputs. In medical diagnosis, for instance, some symptoms by themselves may not be really important, but may become key factors in the presence of other signs.

A discrete fuzzy measure allows one to assign importances to all possible groups of criteria, and thus offers a much greater flexibility for modeling aggregation. It also turns out that weighted arithmetic means and OWA are special cases of Choquet integrals with respect to additive and symmetric fuzzy measures respectively. Thus we deal with a much broader class of aggregation functions. The uses of Choquet and Sugeno integrals as aggregation functions are documented in [7, 10, 11, 13, 14].

#### 2.2 Basic definitions

**Definition 2 (Fuzzy measure)** Let  $\mathcal{N} = \{1, 2, ..., n\}$ . A discrete fuzzy measure is a set function  $v: 2^{\mathcal{N}} \to [0, 1]$  which is monotonic (i.e.  $v(\mathcal{A}) \leq v(\mathcal{B})$  whenever  $\mathcal{A} \subset \mathcal{B}$ ) and satisfies  $v(\emptyset) = 0$  and  $v(\mathcal{N}) = 1$ .

In the context of aggregation functions, we are interested in the interpretation of the values of a fuzzy measure as the importance of a coalition. In the Definition 2, a subset  $\mathcal{A} \subseteq \mathcal{N}$  can be considered as a *coalition*, so that  $v(\mathcal{A})$  gives us an idea about the importance or the weight of this coalition. The monotonicity condition implies that adding new elements to a coalition does not decrease its weight.

**Definition 3 (Möbius transformation)** Let v be a fuzzy measure. The Möbius transformation of v is a set function defined for every  $A \subseteq \mathcal{N}$  as

$$\mathcal{M}(\mathcal{A}) = \sum_{\mathcal{B} \subseteq \mathcal{A}} (-1)^{|\mathcal{A} \setminus \mathcal{B}|} v(\mathcal{B}).$$

Möbius transformation is invertible, and one recovers v by using its inverse, called  $Zeta\ transform$ ,

$$v(\mathcal{A}) = \sum_{\mathcal{B} \subseteq \mathcal{A}} \mathcal{M}(B) \quad \forall \mathcal{A} \subseteq \mathcal{N}.$$

<sup>&</sup>lt;sup>1</sup>A set function is a function whose domain consists of all possible subsets of  $\mathcal{N}$ . For example, for n=3, a set function is specified by  $2^3=8$  values at  $v(\emptyset)$ ,  $v(\{1\})$ ,  $v(\{2\})$ ,  $v(\{3\})$ ,  $v(\{1,2\})$ ,  $v(\{1,3\})$ ,  $v(\{1,2,3\})$ .

Möbius transformation is helpful in expressing various quantities, like the interaction indices discussed later, in a more compact form. It also serves as an alternative representation of a fuzzy measure, called Möbius representation. That is, one can either use v or  $\mathcal{M}$  to perform calculations, whichever is more convenient. The conditions of monotonicity of a fuzzy measure, and the boundary conditions  $v(\emptyset) = 0, v(\mathcal{N}) = 1$  are expressed, respectively, as

$$\sum_{\mathcal{B}\subseteq A|i\in\mathcal{B}} \mathcal{M}(\mathcal{B}) \geq 0, \quad \text{for all } \mathcal{A}\subseteq \mathcal{N} \text{ and all } i\in\mathcal{A},$$

$$\mathcal{M}(\emptyset) = 0 \text{ and } \sum_{\mathcal{A}\subseteq \mathcal{N}} \mathcal{M}(\mathcal{A}) = 1.$$
(2.1)

There are various special classes of fuzzy measures, which we discuss below. We now proceed with the definition of the Choquet integral—based aggregation functions.

**Definition 4 (Discrete Choquet integral)** The discrete Choquet integral with respect to a fuzzy measure v is given by

$$C_v(\mathbf{x}) = \sum_{i=1}^n x_{(i)} [v(\{j|x_j \ge x_{(i)}\}) - v(\{j|x_j \ge x_{(i+1)}\})], \qquad (2.2)$$

where  $\mathbf{x}_{\nearrow} = (x_{(1)}, x_{(2)}, \dots, x_{(n)})$  is a non-decreasing permutation of the input  $\mathbf{x}$ , and  $x_{(n+1)} = \infty$  by convention.

#### Alternative expressions

• By rearranging the terms of the sum, (2.2) can also be written as

$$C_v(\mathbf{x}) = \sum_{i=1}^n \left[ x_{(i)} - x_{(i-1)} \right] v(H_i).$$
 (2.3)

where  $x_{(0)} = 0$  by convention, and  $H_i = \{(i), \dots, (n)\}$  is the subset of indices of the n - i + 1 largest components of  $\mathbf{x}$ .

• Choquet integral can be expressed with the help of the Möbius transformation as

$$C_v(\mathbf{x}) = \sum_{\mathcal{A} \subset \mathcal{N}} \mathcal{M}(\mathcal{A}) \min_{i \in \mathcal{A}} x_i = \sum_{\mathcal{A} \subset \mathcal{N}} \mathcal{M}(\mathcal{A}) h_{\mathcal{A}}(\mathbf{x}), \tag{2.4}$$

with  $h_{\mathcal{A}}(\mathbf{x}) = \min_{i \in \mathcal{A}} x_i$ .

#### Main properties

- The Choquet integral is a continuous piecewise linear idempotent aggregation function;
- An aggregation function is a Choquet integral if and only if it is homogeneous, shift-invariant and comonotone additive, i.e.,  $C_v(\mathbf{x} + \mathbf{y}) = C_v(\mathbf{x}) + C_v(\mathbf{y})$  for all comonotone  $^2 \mathbf{x}, \mathbf{y}$ ;
- The Choquet integral is uniquely defined by its values at the vertices of the unit cube  $[0,1]^n$ , i.e., at the points  $\mathbf{x}$ , whose coordinates  $x_i \in \{0,1\}$ . Note that there are  $2^n$  such points, the same as the number of values that determine the fuzzy measure v;
- The discrete Choquet integral is a linear function of the values of the fuzzy measure v.
- The class of Choquet integrals includes weighted means and OWA functions, as well as minimum, maximum and order statistics as special cases;
- A linear convex combination of Choquet integrals with respect to fuzzy measures  $v_1$  and  $v_2$ ,  $\alpha C_{v_1} + (1 \alpha)C_{v_2}$ ,  $\alpha \in [0, 1]$ , is also a Choquet integral with respect to  $v = \alpha v_1 + (1 \alpha)v_2$ .

#### Calculation

Calculation of the discrete Choquet integral is performed using Equation (2.3) using the following procedure. Consider the vector of pairs  $((x_1, 1), (x_2, 2), \ldots, (x_n, n))$ , where the second component of each pair is just the index i of  $x_i$ . The second component will help keeping track of all permutations.

Calculation of  $C_v(\mathbf{x})$ .

1. Sort the components of  $((x_1,1),(x_2,2),\ldots,(x_n,n))$  with respect to the first component of each pair in non-decreasing order. We obtain  $((x_{(1)},i_1),(x_{(2)},i_2),\ldots,(x_{(n)},i_n))$ , so that  $x_{(j)}=x_{i_j}$  and  $x_{(j)} \leq x_{(j+1)}$  for all i. Let also  $x_{(0)}=0$ .

<sup>&</sup>lt;sup>2</sup>Two vectors  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$  are called comonotone if there exists a common permutation P of  $\{1, 2, \ldots, n\}$ , such that  $x_{P(1)} \leq x_{P(2)} \leq \cdots \leq x_{P(n)}$  and  $y_{P(1)} \leq y_{P(2)} \leq \cdots \leq y_{P(n)}$ . Equivalently, this condition is frequently expressed as  $(x_i - x_j)(y_i - y_j) \geq 0$  for all  $i, j \in \{1, \ldots, n\}$ .

2. Let 
$$\mathcal{T} = \{1, ..., n\}$$
, and  $S = 0$ .

- 3. For j = 1, ..., n do
  - (a)  $S := S + [x_{(i)} x_{(i-1)}]v(\mathcal{T});$
  - (b)  $\mathcal{T} := \mathcal{T} \setminus \{i_i\}$
- 4. Return S.

For computational purposes it is convenient to store the values of a fuzzy measure v in an array  $\mathbf{v}$  of size  $2^n$ , and to use the following indexing system, which provides a one-to-one mapping between the subsets  $\mathcal{J} \subseteq \mathcal{N}$  and the set of integers  $I = \{0, \ldots, 2^n - 1\}$ , which index the elements of v. Take the binary representation of each index in I, e.g. j = 5 = 101 (binary). Now for a given subset  $\mathcal{J} \subseteq \mathcal{N} = \{1, \ldots, n\}$  define its characteristic vector  $\mathbf{c} \in \{0, 1\}^n : c_{n-i+1} = 1$  if  $i \in \mathcal{J}$  and 0 otherwise. For example, if n = 5,  $\mathcal{J} = \{1, 3\}$ , then  $\mathbf{c} = (0, 0, 1, 0, 1)$ . Put the value  $v(\mathcal{J})$  into correspondence with  $v_j$ , so that the binary representation of j corresponds to the characteristic vector of  $\mathcal{J}$ . In our example  $v(\{1, 3\}) = v_5$ .

Such an ordering of the subsets of  $\mathcal{N}$  is called binary ordering:

$$\emptyset$$
,  $\{1\}$ ,  $\{2\}$ ,  $\{1,2\}$ ,  $\{3\}$ ,  $\{1,3\}$ ,  $\{2,3\}$ ,  $\{1,2,3\}$ ,  $\{4\}$ , ...,  $\{1,2,...,n\}$ .

The values of v are mapped to the elements of vector  $\mathbf{v}$  as follows

	$v_0$	$v_1$	$v_2$	$v_3$	$v_4$	$v_5$	
	$=v_{(0000)}$	$=v_{(0001)}$	$=v_{(0010)}$	$=v_{(0011)}$	$=v_{(0100)}$	$=v_{(0101)}$	
ſ	$v(\emptyset)$	$v(\{1\})$	$v(\{2\})$	$v(\{1,2\})$	$v({\{3\}})$	$v(\{1,3\})$	

An alternative ordering of the values of v is based on set cardinality:

$$\emptyset, \underbrace{\{1\}, \{2\}, \dots, \{n\}}_{n \text{ singletons}}, \underbrace{\{1, 2\}, \{1, 3\}, \dots, \{1, n\}, \{2, 3\}, \dots, \{n - 1, n\}}_{\binom{n}{2} \text{ pairs}}, \{1, 2, 3\}, \dots$$

Such an ordering is useful when dealing with k-additive fuzzy measures (see Definition 16 and Proposition 1 below), as it allows one to group non-zero values  $\mathcal{M}(\mathcal{A})$  (in Möbius representation) at the beginning of the array.

#### 2.3 Types of fuzzy measures

In this section we present the most important definitions and classes of fuzzy measures.

**Definition 5 (Dual fuzzy measure)** Given a fuzzy measure v, its dual fuzzy measure  $v^*$  is defined by

$$v^*(\mathcal{A}) = 1 - v(\mathcal{A}^c), \text{ for all } \mathcal{A} \subseteq \mathcal{N},$$

where  $\mathcal{A}^c = \mathcal{N} \setminus \mathcal{A}$  is the complement of  $\mathcal{A}$  in  $\mathcal{N}$ .

**Definition 6 (Self-dual fuzzy measure)** A fuzzy measure v is self-dual if it is equal to its dual v\*, i.e.,

$$v(A) + v(A^c) = 1$$
, holds for all  $A \subseteq \mathcal{N}$ .

Definition 7 (Submodular and supermodular fuzzy measure) A fuzzy measure v is called submodular if for any  $A, B \subseteq N$ 

$$v(\mathcal{A} \cup \mathcal{B}) + v(\mathcal{A} \cap \mathcal{B}) \le v(\mathcal{A}) + v(\mathcal{B}). \tag{2.5}$$

It is called supermodular if

$$v(\mathcal{A} \cup \mathcal{B}) + v(\mathcal{A} \cap \mathcal{B}) \ge v(\mathcal{A}) + v(\mathcal{B}). \tag{2.6}$$

Two weaker conditions which are frequently used are called sub- and super-additivity. These are special cases of sub- and supermodularity for disjoint subsets

**Definition 8 (Subadditive and superadditive fuzzy measure)** A fuzzy measure v is called subadditive if for any two nonintersecting subsets  $A, B \subset \mathcal{N}, A \cap B = \emptyset$ :

$$v(\mathcal{A} \cup \mathcal{B}) \le v(\mathcal{A}) + v(\mathcal{B}). \tag{2.7}$$

It is called superadditive if

$$v(\mathcal{A} \cup \mathcal{B}) \ge v(\mathcal{A}) + v(\mathcal{B}). \tag{2.8}$$

**Note 1** A general fuzzy measure may be submodular only with respect to specific pairs of subsets A, B, and supermodular with respect to other pairs.

**Definition 9 (Additive (probability) measure)** A fuzzy measure v is called **additive** if for any  $A, B \subset N$ ,  $A \cap B = \emptyset$ :

$$v(A \cup B) = v(A) + v(B). \tag{2.9}$$

An additive fuzzy measure is called a probability measure.

Note 2 For an additive fuzzy measure clearly  $v(A) = \sum_{i \in A} v(\{i\})$ .

**Note 3** Additivity implies that for any subset  $A \subseteq \mathcal{N} \setminus \{i, j\}$ 

$$v(\mathcal{A} \cup \{i, j\}) = v(\mathcal{A} \cup \{i\}) + v(\mathcal{A} \cup \{j\}) - v(\mathcal{A}).$$

**Definition 10 (Balanced measure)** A fuzzy measure v is called balanced if it holds:

$$|\mathcal{A}| < |\mathcal{B}| \Longrightarrow v(\mathcal{A}) \le v(\mathcal{B}), \text{ for all } \mathcal{A}, \mathcal{B} \subseteq \mathcal{N}.$$

**Definition 11 (Symmetric fuzzy measure)** A fuzzy measure v is called symmetric if the value v(A) depends only on the cardinality of the set A, i.e., for any  $A, B \subseteq \mathcal{N}$ ,

if 
$$|\mathcal{A}| = |\mathcal{B}|$$
 then  $v(\mathcal{A}) = v(\mathcal{B})$ .

Alternatively, one can say that a fuzzy measure v is symmetric if for any  $\mathcal{A}\subseteq\mathcal{N}$  it is

$$v(\mathcal{A}) = Q\left(\frac{|\mathcal{A}|}{n}\right),$$
 (2.10)

for some monotone non-decreasing function  $Q:[0,1]\to [0,1], Q(0)=0$  and Q(1)=1.

**Definition 12 (Possibility and necessity measures)** A fuzzy measure is called a possibility, Pos, if for all  $A, B \subseteq \mathcal{N}$  it satisfies

$$Pos(A \cup B) = \max\{Pos(A), Pos(B)\}.$$

A fuzzy measure is called a necessity, Nec, if for all  $A, B \subseteq N$  it satisfies

$$Nec(A \cap B) = \min\{Nec(A), Nec(B)\}.$$

**Note 4** Possibility and necessity measures are dual to each other in the sense of Definition 5, that is, for all  $A \subseteq \mathcal{N}$ 

$$Nec(\mathcal{A}) = 1 - Pos(\mathcal{A}^c).$$

A possibility measure is subadditive. A necessity measure is superadditive.

**Definition 13 (Belief Measure)** A belief measure  $Bel: 2^{\mathcal{N}} \to [0,1]$  is a fuzzy measure that satisfies the following condition: for all m > 1

$$Bel(\bigcup_{i=1}^{m} \mathcal{A}_i) \ge \sum_{\emptyset \ne I \subset \{1,\dots,m\}} (-1)^{|I|+1} Bel(\bigcap_{i \in I} \mathcal{A}_i),$$

where  $\{A_i\}_{i\in\{1,...,m\}}$ , is any finite family of subsets of  $\mathcal{N}$ . <sup>3</sup>

**Definition 14 (Plausibility measure)** A plausibility measure  $Pl: 2^{\mathcal{N}} \rightarrow [0,1]$  is a fuzzy measure that satisfies the following condition: for all m > 1

$$Pl(\bigcap_{i=1}^{m} \mathcal{A}_i) \leq \sum_{\emptyset \neq I \subset \{1,\dots,m\}} (-1)^{|I|+1} Pl(\bigcup_{i \in I} \mathcal{A}_i),$$

where  $\{A_i\}_{i\in\{1,...,m\}}$  is any finite family of subsets of  $\mathcal{N}$ .

**Note 5** A set function  $Pl: 2^{\mathcal{N}} \to [0,1]$  is a plausibility measure if its dual set function is a belief measure, i.e., for all  $A \subseteq \mathcal{N}$ 

$$Pl(\mathcal{A}) = 1 - Bel(\mathcal{A}^c).$$

Any belief measure is superadditive. Any plausibility measure is subadditive.

#### $\lambda$ -fuzzy measures

Additive and symmetric fuzzy measures are two examples of very simple fuzzy measures, whereas general fuzzy measures are sometimes too complicated for applications. As a way of reducing the complexity of a fuzzy measure Sugeno [16] introduced  $\lambda$ -fuzzy measures (also called Sugeno measures).

 $<sup>^3</sup>$ For a fixed  $m \geq 1$  this condition is called m-monotonicity (simple monotonicity for m=1), and if it holds for all  $m \geq 1$ , it is called total monotonicity. For a fixed m, condition in Definition 14 is called m-alternating monotonicity. 2-monotone fuzzy measures are called supermodular (see Definition 7), also called convex, whereas 2-alternating fuzzy measures are called submodular. If a fuzzy measure is m-monotone, its dual is m-alternating and vice versa.

**Definition 15** ( $\lambda$ -fuzzy measure) Given a parameter  $\lambda \in ]-1, \infty[$ , a  $\lambda$ -fuzzy measure is a fuzzy measure v that for all  $A, B \subseteq \mathcal{N}, A \cap B = \emptyset$  satisfies

$$v(\mathcal{A} \cup \mathcal{B}) = v(\mathcal{A}) + v(\mathcal{B}) + \lambda v(\mathcal{A})v(\mathcal{B}). \tag{2.11}$$

Under these conditions, all the values v(A) are immediately computed from n independent values  $v(\{i\}), i = 1, \ldots, n$ , by using the explicit formula

$$v(\bigcup_{i=1}^{m} \{i\}) = \frac{1}{\lambda} \left( \prod_{i=1}^{m} (1 + \lambda v(\{i\})) - 1 \right), \quad \lambda \neq 0.$$

If  $\lambda = 0$ ,  $\lambda$ -fuzzy measure becomes a probability measure. The coefficient  $\lambda$  is determined from the boundary condition  $v(\mathcal{N}) = 1$ , which gives

$$\lambda + 1 = \prod_{i=1}^{n} (1 + \lambda v(\{i\})), \tag{2.12}$$

which can be solved on (-1,0) or  $(0,\infty)$  numerically (note that  $\lambda=0$  is always a solution). Thus a  $\lambda$ -fuzzy measure is characterized by n independent values  $v(\{i\}), i=1,\ldots,n$ .

Note 6 A  $\lambda$ -fuzzy measure is either sub- or supermodular, when  $-1 < \lambda \le 0$  or  $\lambda \ge 0$  respectively.

**Note 7** When  $-1 < \lambda \le 0$ , a  $\lambda$ -fuzzy measure is a plausibility measure, and when  $\lambda \ge 0$  it is a belief measure.

#### k - additive fuzzy measures

Another way to reduce complexity of aggregation functions based on fuzzy measures is to impose various linear constraints on their values. Such constraints acquire an interesting interpretation in terms of interaction indices discussed in the next section. One type of constraints leads to k-additive fuzzy measures.

**Definition 16** (k-additive fuzzy measure) A fuzzy measure v is called k-additive  $(1 \le k \le n)$  if its Möbius transformation verifies

$$\mathcal{M}(\mathcal{A}) = 0$$

for any subset A with more than k elements, |A| > k, and there exists a subset B with k elements such that  $\mathcal{M}(B) \neq 0$ .

**Definition 17 (Possibilistic Möbius transform)** The possibilistic Möbius transform of a fuzzy measure v on  $\mathcal{N}$  is a mapping  $m_p : \mathcal{P}(\mathcal{N}) \to [0,1]$  defined by

$$m_p(\mathcal{A}) = \begin{cases} v(\mathcal{A}) & \text{if } v(\mathcal{A}) > \max_{\mathcal{B} \subset \mathcal{A}} v(\mathcal{B}), \\ 0 & \text{otherwise.} \end{cases}$$
 (2.13)

The possibilistic Zeta transform of  $m_p$  is the mapping  $Z_{m_p}: \mathcal{P}(\mathcal{N}) \to [0,1]$  defined by:

$$\mathcal{Z}_{m_p}(\mathcal{A}) = \max_{\mathcal{B} \subset \mathcal{A}} m_p(\mathcal{B}). \tag{2.14}$$

**Definition 18** (k-maxitive fuzzy measure) A fuzzy measure v is called k-maxitive if its possibilistic Möbius transform satisfies  $m_p(A) = 0$  for any A such that |A| > k and there exists at least one subset A of N of exactly k elements such that  $m_p(A) \neq 0$ .

**Definition 19** (k-tolerant fuzzy measure) Let  $k \in \{1, 2, ..., n\} = \mathcal{N}$ . A fuzzy measure on  $\mathcal{N}$  is k-tolerant if  $v(\mathcal{A}) = 1$  for all  $\mathcal{A} \subseteq \mathcal{N}$  such that  $|\mathcal{A}| \geq k$  and there exists a subset  $\mathcal{B} \subseteq \mathcal{N}$ , with  $|\mathcal{B}| = k - 1$ , such that  $v(\mathcal{B}) \neq 1$ . A fuzzy measure v on  $\mathcal{N}$  is k-intolerant if  $v(\mathcal{A}) = 0$  for all  $\mathcal{A} \subseteq \mathcal{N}$  such that  $|\mathcal{A}| \leq n - k$  and there exists a subset  $\mathcal{B} \subseteq \mathcal{N}$ , with  $|\mathcal{B}| = n - k + 1$ , such that  $v(\mathcal{B}) \neq 0$ .

k-intolerant fuzzy measures can be obtained from k-tolerant measures by using duality. The Choquet integral with respect to a k-tolerant capacity is independent of the first n-k smallest inputs.

#### 2.4 Interaction, importance and other indices

When dealing with multiple criteria, it is often the case that these are not independent, and there is some interaction (positive or negative) among the criteria. For instance, two or more criteria may point essentially to the same concept, for example criteria such as "learnability" and "memorability" that are used to evaluate software user interface. If the criteria are combined by using, e.g., weighted means, their scores will be double counted. In other instances, contribution of one criterion to the total score by itself may be small, but sharply rise when taken in conjunction with other criteria (i.e., in a "coalition").

Thus to measure such concepts as the importance of a criterion and interaction among the criteria, we need to account for contribution of these criteria in various coalitions. To do this we will use the concepts of Shapley value, which measures the importance of a criterion i in all possible coalitions, and the interaction index, which measures the interaction of a pair of criteria i, j in all possible coalitions [8, 9].

**Definition 20 (Shapley value)** Let v be a fuzzy measure. The Shapley index for every  $i \in \mathcal{N}$  is

$$\phi(i) = \sum_{\mathcal{A} \subseteq \mathcal{N} \setminus \{i\}} \frac{(n - |\mathcal{A}| - 1)! |\mathcal{A}|!}{n!} [v(\mathcal{A} \cup \{i\}) - v(\mathcal{A})].$$

The Shapley value is the vector  $\phi(v) = (\phi(1), \dots, \phi(n))$ .

The Shapley value is interpreted as a kind of average value of the contribution of each criterion alone in all coalitions.

**Definition 21 (Interaction index)** Let v be a fuzzy measure. The interaction index for every pair  $i, j \in \mathcal{N}$  is

$$I_{ij} = \sum_{\mathcal{A} \subseteq \mathcal{N} \setminus \{i,j\}} \frac{(n - |\mathcal{A}| - 2)!|\mathcal{A}|!}{(n-1)!} [v(\mathcal{A} \cup \{i,j\}) - v(\mathcal{A} \cup \{i\}) - v(\mathcal{A} \cup \{j\}) + v(\mathcal{A})].$$

The interaction indices verify  $I_{ij} < 0$  as soon as i, j are positively correlated (negative synergy, redundancy). Similarly  $I_{ij} > 0$  for negatively correlated criteria (positive synergy, complementarity).  $I_{ij} \in [-1, 1]$  for any pair i, j.

Note 8 For a submodular fuzzy measure v, all interaction indices verify  $I_{ij} \leq 0$ . For a supermodular fuzzy measure, all interaction indices verify  $I_{ij} \geq 0$ .

**Definition 22 (Interaction index for coalitions)** Let v be a fuzzy measure. The interaction index for every set  $A \subseteq \mathcal{N}$  is

$$I(\mathcal{A}) = \sum_{\mathcal{B} \subset \mathcal{N} \setminus \mathcal{A}} \frac{(n - |\mathcal{B}| - |\mathcal{A}|)! |\mathcal{B}|!}{(n - |\mathcal{A}| + 1)!} \sum_{\mathcal{C} \subset \mathcal{A}} (-1)^{|\mathcal{A} \setminus \mathcal{C}|} v(\mathcal{B} \cup \mathcal{C}).$$

**Note 9** Clearly I(A) coincides with  $I_{ij}$  if  $A = \{i, j\}$ , and coincides with  $\phi(i)$  if  $A = \{i\}$ .

An alternative to the Shapley value is the Banzhaf index [1]. It measures the same concept as the Shapley index, but weights the terms  $[v(A \cup \{i\}) - v(A)]$  in the sum equally.

**Definition 23 (Banzhaf Index)** Let v be a fuzzy measure. The Banzhaf index  $b_i$  for every  $i \in \mathcal{N}$  is

$$b_i = \frac{1}{2^{n-1}} \sum_{\mathcal{A} \subseteq \mathcal{N} \setminus \{i\}} [v(\mathcal{A} \cup \{i\}) - v(\mathcal{A})].$$

**Definition 24 (Banzhaf interaction index for coalitions)** Let v be a fuzzy measure. The Banzhaf interaction index between the elements of  $A \subseteq \mathcal{N}$  is given by

$$J(\mathcal{A}) = \frac{1}{2^{n-|\mathcal{A}|}} \sum_{\mathcal{B} \subset \mathcal{N} \setminus \mathcal{A}} \sum_{\mathcal{C} \subseteq \mathcal{A}} (-1)^{|\mathcal{A} \setminus \mathcal{C}|} v(\mathcal{B} \cup \mathcal{C}).$$

Note 10 Möbius transformation help one to express the indices mentioned above in a more compact form [8, 9, 12, 14], namely

$$\begin{split} \phi(i) &= \sum_{\mathcal{B}|i \in \mathcal{B}} \frac{1}{|\mathcal{B}|} \mathcal{M}(\mathcal{B}), \\ I(\mathcal{A}) &= \sum_{\mathcal{B}|\mathcal{A} \subseteq \mathcal{B}} \frac{1}{|\mathcal{B}| - |\mathcal{A}| + 1} \mathcal{M}(\mathcal{B}), \\ J(\mathcal{A}) &= \sum_{\mathcal{B}|\mathcal{A} \subseteq \mathcal{B}} \frac{1}{2^{|\mathcal{B}| - |\mathcal{A}|}} \mathcal{M}(\mathcal{B}). \end{split}$$

The next result due to Grabisch [8,9] establishes a fundamental property of k-additive fuzzy measures, which justifies their use in simplifying interactions between the criteria in multiple criteria decision making.

**Proposition 1** Let v be a k-additive fuzzy measure,  $1 \le k \le n$ . Then

- I(A) = 0 for every  $A \subseteq \mathcal{N}$  such that |A| > k;
- $I(A) = J(A) = \mathcal{M}(A)$  for every  $A \subseteq \mathcal{N}$  such that |A| = k.

Thus k-additive measures acquire an interesting interpretation. These are fuzzy measures that limit interaction among the criteria to groups of size at most k. For instance, for 2-additive fuzzy measures, there are pairwise interactions among the criteria but no interactions in groups of 3 or more. By limiting the class of fuzzy measures to k-additive measures, one reduces their complexity (the number of values) by imposing linear equality constraints. The total number of linearly independent values is reduced from  $2^n - 1$  to  $\sum_{i=1}^k \binom{n}{i} - 1$ .

#### Orness value

The measure of orness, also called the degree of orness, orness value or attitudinal character, is an important numerical characteristic of averaging aggregation functions. Basically, the measure of orness measures how far a given averaging function is from the max function, which is the weakest disjunctive function. The measure of orness is computed for any averaging function [5,6] using

**Definition 25 (Measure of orness)** Let f be an averaging aggregation function. Then its measure of orness is

$$orness(f) = \frac{\int_{[0,1]^n} f(\mathbf{x}) d\mathbf{x} - \int_{[0,1]^n} \min(\mathbf{x}) d\mathbf{x}}{\int_{[0,1]^n} \max(\mathbf{x}) d\mathbf{x} - \int_{[0,1]^n} \min(\mathbf{x}) d\mathbf{x}}.$$
 (2.15)

Clearly,  $orness(\max) = 1$  and  $orness(\min) = 0$ , and for any f,  $orness(f) \in [0, 1]$ . The calculation of the integrals of max and min functions results in simple equations

$$\int_{[0,1]^n} \max(\mathbf{x}) d\mathbf{x} = \frac{n}{n+1} \text{ and } \int_{[0,1]^n} \min(\mathbf{x}) d\mathbf{x} = \frac{1}{n+1}.$$
 (2.16)

By using the Möbius transform one can calculate the orness of a Choquet integral  $C_v$  with respect to a fuzzy measure v as follows.

**Proposition 2 (Orness of Choquet integral)** [15] For any fuzzy measure v the orness of the Choquet integral with respect to v is

$$orness(C_v) = \frac{1}{n-1} \sum_{\mathcal{A} \subset \mathcal{N}} \frac{n-|\mathcal{A}|}{|\mathcal{A}|+1} \mathcal{M}(\mathcal{A}),$$

where  $\mathcal{M}(A)$  is the Möbius representation of A. In terms of v the orness value is

$$orness(C_v) = \frac{1}{n-1} \sum_{A \subseteq \mathcal{N}} \frac{(n-|\mathcal{A}|)!|\mathcal{A}|!}{n!} v(\mathcal{A}).$$

#### 2.5 Sugeno Integral

Similarly to the Choquet integral, Sugeno integral is also frequently used to aggregate inputs, such as preferences in multicriteria decision making. Various important classes of aggregation functions, such as medians, weighted minimum and weighted maximum are special cases of Sugeno integral.

**Definition 26 (Discrete Sugeno integral)** The Sugeno integral with respect to a fuzzy measure v is given by

$$S_v(\mathbf{x}) = \max_{i=1,\dots,n} \min\{x_{(i)}, v(H_i)\},$$
 (2.17)

where  $\mathbf{x}_{\nearrow} = (x_{(1)}, x_{(2)}, \dots, x_{(n)})$  is a non-decreasing permutation of the input  $\mathbf{x}$ , and  $H_i = \{(i), \dots, (n)\}.$ 

Sugeno integrals can be expressed, for arbitrary fuzzy measures, by means of the Median function in the following way:

$$S_v(\mathbf{x}) = Med(x_1, \dots, x_n, v(H_2), v(H_3), \dots, v(H_n)).$$

Let us denote max by  $\vee$  and min by  $\wedge$  for compactness. We denote by  $\mathbf{x} \vee \mathbf{y} = \mathbf{z}$  the componentwise maximum of  $\mathbf{x}, \mathbf{y}$  (i.e.,  $z_i = \max(x_i, y_i)$ ), and by  $\mathbf{x} \wedge \mathbf{y}$  their componentwise minimum.

#### Main properties

- Sugeno integral is a continuous idempotent aggregation function;
- An aggregation function is a Sugeno integral if and only if it is minhomogeneous, i.e.,  $S_v(x_1 \wedge r, \ldots, x_n \wedge r) = S_v(x_1, \ldots, x_n) \wedge r$  and maxhomogeneous, i.e.,  $S_v(x_1 \vee r, \ldots, x_n \vee r) = S_v(x_1, \ldots, x_n) \vee r$  for all  $\mathbf{x} \in [0,1]^n, r \in [0,1]$  (See [13], Th. 4.3. There are also alternative characterizations);
- Sugeno integral is comonotone maxitive and comonotone minimitive, i.e.,  $S_v(\mathbf{x} \vee \mathbf{y}) = S_v(\mathbf{x}) \vee S_v(\mathbf{y})$  and  $S_v(\mathbf{x} \wedge \mathbf{y}) = S_v(\mathbf{x}) \wedge S_v(\mathbf{y})$  for all comonotone<sup>4</sup>  $\mathbf{x}, \mathbf{y} \in [0, 1]^n$ .

#### Calculation

Calculation of the discrete Sugeno integral is performed using Equation (2.17) similarly to calculating the Choquet integral on p. 10. We take the vector of pairs  $((x_1, 1), (x_2, 2), \ldots, (x_n, n))$ , where the second component of each pair is just the index i of  $x_i$ . The second component will help keeping track of all permutations.

Calculation of  $S_n(\mathbf{x})$ .

<sup>&</sup>lt;sup>4</sup>See footnote 2 on p. 10.

- 1. Sort the components of  $((x_1,1),(x_2,2),\ldots,(x_n,n))$  with respect to the first component of each pair in non-decreasing order. We obtain  $((x_{(1)},i_1),(x_{(2)},i_2),\ldots,(x_{(n)},i_n))$ , so that  $x_{(j)}=x_{i_j}$  and  $x_{(j)}\leq x_{(j+1)}$  for all i.
- 2. Let  $\mathcal{T} = \{1, ..., n\}$ , and S = 0.
- 3. For j = 1, ..., n do
  - (a)  $S := \max(S, \min(x_{(i)}, v(\mathcal{T})));$
  - (b)  $\mathcal{T} := \mathcal{T} \setminus \{i_j\}$
- 4. Return S.

#### 2.6 Constructing fuzzy measures

This section outlines the problem of fitting fuzzy measures to some sort of empirical data, the observed (or sometimes desired) pairs of input-output values. In the most typical case, the data comes in pairs  $(\mathbf{x}, y)$ , where  $\mathbf{x} \in [0, 1]^n$  is the input vector and  $y \in [0, 1]$  is the desired output. There are several pairs, which will be denoted by a subscript k:  $(\mathbf{x}_k, y_k), k = 1, ..., K$ .

When the data comes from an experiment, it will normally contain some errors, and therefore it is pointless to interpolate the inaccurate values  $y_k$ . In this case our aim is to stay close to the desired outputs without actually matching them.

The goal is to find a fuzzy measure v, such that the function  $f = C_v$  approximates  $y_k$ ,  $f(\mathbf{x}_k) \approx y_k$ . The satisfaction of approximate equalities  $f(\mathbf{x}_k) \approx y_k$  is usually translated into the following minimization problem.

minimize 
$$||\mathbf{r}||$$
 (2.18)  
subject to  $f$  satisfies properties  $\mathcal{P}_1, \mathcal{P}_2, \dots$ ,

where  $||\mathbf{r}||$  is the norm of the residuals, i.e.,  $\mathbf{r} \in R^K$  is the vector of the differences between the predicted and observed values  $r_k = f(\mathbf{x}_k) - y_k$ . There are many ways to choose the norm, and the most popular are the least squares norm

$$||\mathbf{r}||_2 = \left(\sum_{k=1}^K r_k^2\right)^{1/2},$$

the least absolute deviation norm

$$||\mathbf{r}||_1 = \sum_{k=1}^K |r_k|,$$

and the Chebyshev norm

$$||\mathbf{r}||_{\infty} = \max_{k=1,\dots,K} |r_k|.$$

It was also suggested that for decision making problems, the actual numerical value of the output  $f(\mathbf{x}_k)$  was not as important as the ranking of the outputs. For instance, if  $y_k \leq y_l$ , then it should be  $f(\mathbf{x}_k) \leq f(\mathbf{x}_l)$ . Indeed, people are not really good at assigning consistent numerical scores to their preferences, but they are good at ranking the alternatives. Thus a suitable choice of aggregation function should be consistent with the ranking of the outputs  $y_k$  rather than their numerical values. The use of the mentioned fitting criteria does not preserve the ranking of outputs, unless they are interpolated. Preservation of ranking of outputs can be done by imposing the constraints  $f(\mathbf{x}_k) \leq f(\mathbf{x}_l)$  if  $y_k \leq y_l$  for all pairs k, l.

In the case when f is the Choquet integral with respect to a fuzzy measure v,  $C_v$ , our goal is to identify the values of v from the data set  $(\mathbf{x}_k, y_k), k = 1, \ldots, K$ . Identification of the  $2^n - 2$  values from the data (two are given explicitly as  $v(\emptyset) = 0, v(N) = 1$ ) involves the least squares or least absolute deviation problems

minimize 
$$\sum_{k=1}^{K} \left( C_v(x_{1k}, \dots, x_{nk}) - y_k \right)^2, \text{ or }$$

minimize 
$$\sum_{k=1}^{K} |C_v(x_{1k}, \dots, x_{nk}) - y_k|,$$

subject to the conditions of monotonicity of the fuzzy measure (they translate into a number of linear constraints, see below).

We concentrate on the least absolute deviation problem, because a) it is less sensitive to outliers, and b) it can be translated into a linear programming problem, which can be solved quickly and reliably even in the case of a very large number of parameters and constraints. Note that the main difficulty in fitting fuzzy measures is the large number of unknowns, and typically a much smaller number of data [10], for instance when n = 15,  $2^n - 2 = 32766$ .

#### Importance and interaction indices

The interaction indices defined in Section 2.4 are all linear functions of the values of the fuzzy measure. Conditions involving these functions can be expressed as linear equations and inequalities.

One can specify given values of importance (Shapley value) and interaction indices  $\phi(i)$ ,  $I_{ij}$  (see p. 17) by adding linear equality constraints. Of course, these values may not be specified exactly, but as intervals, say, for Shapley value we may have  $a_i \leq \phi(i) \leq b_i$ . In this case we obtain a pair of linear inequalities.

#### k-additivity

Recall that Definition 16 specifies k-additive fuzzy measures through their Möbius transform

$$\mathcal{M}(\mathcal{A}) = 0$$

for any subset  $\mathcal{A}$  with more than k elements. Since Möbius transform is a linear combination of values of v, we obtain a set of linear equalities. By using interaction indices, we can express k-additivity as (see Proposition 1)  $I(\mathcal{A}) = 0$  for every  $\mathcal{A} \subseteq \mathcal{N}$ ,  $|\mathcal{A}| > k$ , which is again a set of linear equalities.

However, these conditions on the fuzzy measures do not reduce the complexity of the least squares or least absolute deviation problems. They only add a number of equality and inequality constraints to these problems. However, it is possible to reduce the complexity of the problem when working in Möbius representation.

As the variables we will use  $m_j = m_A = \mathcal{M}(A)$  such that  $|A| \leq k$  in some appropriate indexing system, such as the one based on cardinality ordering on p. 11. This is a much reduced set of variables  $(\sum_{i=1}^k \binom{n}{i} - 1$  compared to  $2^n - 2$ ). Now, monotonicity of a fuzzy measure, expressed as

$$v(A \cup \{i\}) - v(A) \ge 0, \quad \forall A | i \notin A, i = 1, \dots, n,$$

converts into (2.1), and using k-additivity, into

$$\sum_{\mathcal{B}\subseteq A|i\in\mathcal{B}, |\mathcal{B}|\leq k} m_{\mathcal{B}} \geq 0, \quad \text{ for all } \mathcal{A}\subseteq\mathcal{N} \text{ and all } i\in\mathcal{A}.$$

The (non-redundant) set of non-negativity constraints  $v(\{i\}) \geq 0, i = 1, \ldots, n$ , is a special case of the previous formula when  $\mathcal{A}$  is a singleton, which simply become

$$\sum_{\mathcal{B}=\{i\}} m_{\mathcal{B}} = m_{\{i\}} \ge 0, \ i = 1, \dots, n.$$

Finally, condition  $v(\mathcal{N}) = 1$  becomes  $\sum_{\mathcal{B} \subseteq \mathcal{N} \mid |\mathcal{B}| \le k} m_{\mathcal{B}} = 1$ .

Then the least absolute deviation problem is translated into a simplified optimization problem

minimize 
$$\sum_{j=1}^{K} \left| \sum_{|\mathcal{A}| |\mathcal{A}| \leq k} h_{\mathcal{A}}(\mathbf{x}_{j}) m_{\mathcal{A}} - y_{j} \right|, \qquad (2.19)$$
s.t. 
$$\sum_{\mathcal{B} \subseteq A | i \in \mathcal{B}, |\mathcal{B}| \leq k} m_{\mathcal{B}} \geq 0,$$
for all  $\mathcal{A} \subseteq \mathcal{N}, |\mathcal{A}| > 1$ , and all  $i \in \mathcal{A},$ 

$$m_{\{i\}} \geq 0, \ i = 1, \dots, n,$$

$$\sum_{\mathcal{B} \subseteq \mathcal{N}, |\mathcal{B}| \leq k} m_{\mathcal{B}} = 1,$$

where  $h_{\mathcal{A}}(\mathbf{x}) = \min_{i \in \mathcal{A}} x_i$ . Note that only the specified  $m_{\mathcal{B}}$  are non-negative, others are unrestricted. The number of monotonicity constraints is the same for all k-additive fuzzy measures for  $k = 2, \ldots, n$ .

The problem (2.19) will be subsequently converted to a linear programming problem (LP) using the following technique. Let  $r_j = f(x_j) - y_j$  be the j- th residual. We represent it as a difference of a positive and negative parts  $r_j = r_j^+ - r_j^-$ ,  $r_j^+, r_j^- \ge 0$ . The absolute value is  $|r_j| = r_j^+ + r_j^-$ . Now the problem (2.19) is converted into an LP problem with respect to  $\mathbf{m}, \mathbf{r}^+, \mathbf{r}^-$ 

minimize 
$$\sum_{j=1}^{K} (r_j^+ + r_j^-), \qquad (2.20)$$
s.t. 
$$\sum_{\mathcal{A}||\mathcal{A}| \le k} h_{\mathcal{A}}(\mathbf{x}_j) m_{\mathcal{A}} \quad -(r_j^+ - r_j^-) = y_j, \ j = 1, \dots, K$$
other constraints from (2.19),
$$r_j^+, r_j^- \ge 0.$$

Similar problems are set for fitting k-maxitive and k-tolerant fuzzy measures, however fitting k-maxitive fuzzy measures requires solving a mixed integer programming problem MIP, which could be expensive computationally, hence relaxation techniques can be used here for larger n.

In the next Chapter we spell out the exact formulation of the LP problem, in which we also take into account the optional constraints on Shapley values, interaction indices, orness value and preservation of output ordering condition.

# Chapter 3

# Computational methods

#### 3.1 Representations of set functions

When dealing with discrete set functions, like discrete fuzzy measures, on a computer, it is important to encode the  $2^n$  values of such functions  $v_A$  in some array. Typically one uses either binary or cardinality orderings on p.11, and both orderings are best suited for different purposes. It is convenient to use both orderings at the same time, and have a conversion mechanism, for example a lookup table.

A discrete set is conveniently encoded as a binary string, which can be represented by an unsigned integer on a computer (e.g., in C language). The *i*-th bit of such integer indicates the presence or absence of the *i*-th element in a set. Sets of up to 32 elements can be efficiently encoded on 32-bit computers into a single integer, and of course arrays of integers can be used for sets with more elements.

Bitwise operations on integers allow one to calculate easily set union, intersection, complement, determine whether a set is a subset of another one and so on. In Rfmtool library there are a number of routines that perform these operations.

We have also seen in the previous Chapter that the standard and Möbius representations of set functions can be used for various calculation, and sometimes one is preferred to another because of computational efficiency. Thus conversion routines (the Möbius and Zeta transforms) are essential.

#### 3.2 Basic manipulations and tests

Fuzzy measures can be characterized by various indices, such as interaction indices, and can belong to specific classes, such as sub or super-additive. Rfmtool implements a number of calculation routines and tests, in particular:

- 1. Calculation of Shapley values;
- 2. Calculation of Banzhaf indices;
- 3. Calculation of all interaction indices;
- 4. Calculation of all Banzhaf interaction indices;
- 5. Calculation of the dual fuzzy measure;
- 6. Calculation of the orness value of the Choquet integral;
- 7. Calculation of the entropy of the Choquet integral;
- 8. Tests whether a fuzzy measure is:
  - Balanced;
  - Self-dual;
  - Subadditive;
  - Superadditive;
  - Additive;
  - Submodlar;
  - Supermodular;
  - Symmetric;
  - *k*-maxitive.

Tests are performed with a given tolerance. For numerical efficiency reasons, certain quantities (like ordering conversion tables, tables of sets cardinalities and factorials) are pre-computed for a given n, at the initialization stage. Rfmtool uses the formulas presented in Sections 2.3 and 2.4 using the standard and the Möbius representations interchangeably. For Sugeno fuzzy measures it also computes the value of  $\lambda$  (given the values of v at singletons).

Rfmtool also implements an efficient calculation of the Choquet and Sugeno integrals as described on p. 10 and p. 20.

#### 3.3 Fitting fuzzy measures to data

Throughout this section n will denote the dimensionality of the space, and K will denote the size of the data set. We are given a data set representing the values of an unknown function f For example, when n=4 we have

$x_1$	$x_2$	$x_3$	$x_4$	y
$x_{11}$	$x_{12}$	$x_{13}$	$x_{14}$	$y_1$
$x_{21}$	$x_{22}$	$x_{23}$	$x_{24}$	$y_2$
$x_{31}$	$x_{32}$	$x_{33}$	$x_{34}$	$y_3$
:				
$x_{K1}$	$x_{K2}$	$x_{K3}$	$x_{K4}$	$y_K$

The goal is to identify a fuzzy measure v, such that the corresponding Choquet integral  $f = C_v$  predicts the outputs  $y_k$  as close as possible in the least absolute deviation sense. This is done by solving a linear programming problem (2.20). In addition, optional conditions on the bounds of interaction indices, Shapley values or orness value are also incorporated as linear constraints.

The problem is set in Möbius representation. To obtain a standard LP formulation, equality constraints are represented by pairs of inequality constraints, and unconstrained variables (in Möbius representation only the values corresponding to singletons are non-negative) are replaced with pairs of non-negative variables (the positive and negative parts of the unconstrained variable). The decision variables are:

$$\underbrace{r_1^+, \dots, r_K^+, r_1^-, \dots, r_K^-}_{residuals}, \underbrace{m_1, m_2, \dots, m_n}_{singletons}, \underbrace{m_{12}^+, \dots, m_{12...n}^+, m_{12}^-, \dots, m_{12...n}^-}_{positive and negative parts of other values}.$$

If the fuzzy measure is assumed to be k-additive, then in Möbius representation values corresponding to subsets of cardinality greater than k are 0. These decision variables (from the third group) are explicitly excluded from the problem formulation, which is the key to reducing its complexity. For instance, for 2-additive fuzzy measures we will have the decision variables

$$\underbrace{r_1^+, \dots, r_K^+, r_1^-, \dots, r_K^-}_{residuals}, \underbrace{m_1, m_2, \dots, m_n}_{singletons}, \underbrace{m_{12}^+, \dots, m_{n-1,n}^+, m_{12}^-, \dots, m_{n-1,n}^-}_{positive and negative parts of other values, up to  $\{n-1, n\}$$$

An instance of a complete problem formulation is presented in Table.3.1. For numerical efficiency purposes, a dual of this LP problem is actually solved in Rfmtool, because when the fuzzy measure is k-additive, the number of variables is much less than that of constraints.

Fitting k-tolerant fuzzy measures can be done by solving the following LP in the standard representation v (not Möbius).

minimize 
$$\sum_{j=1}^{K} r_j^+ + r_j^-, \tag{3.1}$$
 s.t. 
$$r_j^+ - r_j^- = \sum_{A} v(A) g_A(\mathbf{x}_j) - y_j \qquad \text{data fitting}$$
 
$$v(A) \geq v(A \setminus \{i\}), \forall i \in A \text{ for all } A \subseteq N, |A| \leq k, \text{ monotonicity}$$
 
$$v(A) = 1, \text{ for all } A, |A| \geq k. \text{ k-tolerance},$$

where the functions  $g_A$  are

$$g_A(\mathbf{x}) = \max(0, \min_{i \in A} x_i - \max_{i \in N \setminus A} x_i). \tag{3.2}$$

Fitting k-maxitive fuzzy measure is performed by solving MIP

minimize 
$$\sum_{j=1}^{K} r_j^+ + r_j^-, \tag{3.3}$$
 s.t. 
$$r_j^+ - r_j^- - \sum_A v(A) g_A(\mathbf{x}_j) = -y_j \qquad \text{data fitting}$$
 
$$v(A) - v(A \setminus \{i\}) \geq 0, \forall i \in A \text{ for all } A \subseteq N, \qquad \text{monotonicity}$$
 
$$v(A) - v(A \setminus \{i\}) - c(A, i) \leq 0, \quad \forall i \in A \text{ and } |A| > k, \quad \text{k-maxitivity}$$
 
$$\sum_{i \in A} c(A, i) \leq |A| - 1, \text{ for all } A \subseteq N, |A| > k, \qquad \text{at least one active}$$
 
$$v(N) = 1, \quad c(A, i) \in \{0, 1\}. \qquad \text{constraint.}$$

The binary variables c(A, i) indicate for which i we have equality  $v(A) = v(A \setminus \{i\})$ .

We also implemented an alternative MIP relaxation heuristic for n > 6 or n - k > 3 as follows. We solve the problem in two steps. At Step 1 we solve a relaxation to (3.3) in which c(A,i) were not required to be binary (the restriction was  $c(A,i) \in [0,1]$ ). We then used the optimal solution for c(A,i) to fix the k-maxitivity constraints for every A, |A| > k. Namely, for every fixed A we selected  $i \in A$  which corresponded to the smallest value c(A,i) in the optimal solution to the relaxed problem. We then fixed that variable c(A,i) = 0, meaning active constraint  $v(A) = v(A \setminus \{i\})$ . At Step 2 we solved LP (3.3) without requiring c(A,i) to be binary, but fixing some of its values at 0 according to our selection above.

RHS			$y_1\\-y_1$	$y_2$	70	$y_K$ $-y_K$	1 -	0 0		0	$\mathcal{I}_{12}$			ponnoq	ponnog	0	0
	$m_{n-(k-1),,n}^{+}$		$-h_{n-(k-1),,n}$ $h_{n-(k-1),,n}$	$-h_{n-(k-1),\ldots,n}$	$n, \dots, n-(\kappa-1), \dots, n$	$-h_{n-(k-1),,n}$ $h_{n-(k-1),,n}$	-1			÷							
. k	:						: :			7							
cardinality	$m_{12}^-$		$^{-h_{\{12\}}}_{h_{\{12\}}}$	$-h_{\{12\}}$	{77}	$-h_{\{12\}} \ h_{\{12\}}$	T	7 7		-1							
others up to cardinality $k$	$m_{n-(k-1),,n}^{+}$		$h_{n-(k-1),,n} - h_{n-(k-1),,n}$	$h_{n-(k-1),\ldots,n} = h$	$n-(\kappa-1),,n$	$h_{n-(k-1),,n} - h_{n-(k-1),,n}$	1-1			:							
	:		: :	:	:	: :	: :			П	:						
	$m_{12}^{+}$		$h_{\{12\}} - h_{\{12\}}$	$h_{\{12\}} = -b_{\{13\}}$	{71}	$h_{\{12\}} \ -h_{\{12\}}$				П			:	:	:	:	:
ns	$m_n$		$h_{\{n\}}^{h_{\{n\}}}$	$h_{\{n\}}$	{u}.	$h_{\{n\}} \\ -h_{\{n\}}$				:							
singletons			: :	:		: :	: :	⊣		1							
si	$m_1$		$h_{\{1\}} \ -h_{\{1\}}$	$h_{\{1\}}^{h_{\{1\}}}$	{ <sub>1</sub> }	$h_{\{1\}} \\ -h_{\{1\}}$		П		1	:		:	:	:	:	:
	$r_K^-$	1															
	:	:			4												
residuals	$r_1^-$																
resic	:	:				7 -											
	$r_2^+$	1		- 1	4												
	$r_1^+$	1	7 -														
	Variables	Obj. function	i-th datum		Saittâ	Data :	Boundary cond.		Qiojuo	уюшоју	suc	ractio	ətal		Orness	Order	preservation

Table 3.1: Linear program formulation. All the constraints are  $\geq$  and the objective is minimized.

# Chapter 4

# Description of the library

#### 4.1 Installation

Installation of Rfmtool package is standard: the user just needs to install the package from CRAN or from a local file

R CMD INSTALL Rfmtool\_2.0.0.tar.gz

#### 4.2 Description of the functions in R package Rfmtool

fm()

The function prints the list of all functions implemented in the Rfmtool package. fm.test()

This function tests the correctness of installation by running tests for all functions included in the package.

#### Operations on fuzzy measures

The first operation should always be initialisation. The internal structures are precomputed for n variables and saved in the environment variable.

fm.Init(n)

The function computes the internal structures for n variables. The output is passed to the subsequent operations. Example:

env<-fm.Init(3)

The following functions involve the parameters v (the array containing the fuzzy measure in standard representation) or Mob (in Möbius representation), env - the environment variable set to n variables. The values of the fuzzy measure always obey the binary ordering.

fm.Choquet(x, v, env)

The function computes and returns the value of the Choquet integral of x, wrt fuzzy measure v (eq.(2.3)). The environment variable env is precomputed in the fm.Init function.  $x \in [0,1]^n$ ,  $v \in [0,1]^m$ . Example:

 $r \leftarrow fm.Choquet(c(0.6,0.3,0.8),c(0,0.3,0.5,0.6,0.4,0.8,0.7,1),env)$ 

#### fm.ChoquetMob(x, Mob)

The function computes and returns the value of the Choquet integral of x, wrt fuzzy measure given in Möbius representation Mob (eq.(2.4)). Example:

 $r \leftarrow fm.ChoquetMob(c(0.6,0.3,0.8),c(0.0,0.3,0.5,-0.2,0.4,0.1,-0.2,0.1),$  env)

#### fm.Sugeno(x, v, env)

Calculates the value of the Sugeno integral of x, wrt fuzzy measure v (eq.(2.17)). Example:

 $r \leftarrow fm.Sugeno(c(0.6,0.3,0.8),c(0,0.3,0.5,0.6,0.4,0.8,0.7,1), env)$ 

#### fm.SugenoMob(x, Mob, env)

Calculates the value of the Sugeno integral of x, wrt the fuzzy measure in Möbius representation Mob (eq.(2.17)). Example:

 $r \leftarrow fm.SugenoMob(c(0.6,0.3,0.8),c(0.0,0.3,0.5,-0.2,0.4,0.1,-0.2,0.1),$  env)

#### fm.OrnessChoquet(v, env)

Calculates the orness value of the Choquet integral wrt fuzzy measure v in general representation. Example:

 $r \leftarrow fm.OrnessChoquet(c(0,0.3,0.5,0.6,0.4,0.8,0.7,1), env)$ 

#### fm.OrnessChoquetMob(Mob, env)

Calculates the orness value of the Choquet integral wrt fuzzy measure v given its Möbius representation Mob. Example:

 $r \leftarrow fm.OrnessChoquetMob(c(0.0,0.3,0.5,-0.2,0.4,0.1,-0.2,0.1), env)$ 

#### fm.EntropyChoquet(v, env)

Calculates the entropy value of the Choquet integral wrt fuzzy measure v in standard representation. Example:

 $r \leftarrow fm.EntropyChoquet(c(0,0.3,0.5,0.6,0.4,0.8,0.7,1), env)$ 

#### fm.EntropyChoquetMob(Mob, env)

Calculates the entropy value of the Choquet integral wrt fuzzy measure in Möbius representation Mob. Example:

 $r \leftarrow fm.EntropyChoquetMob(c(0.0,0.3,0.5,-0.2,0.4,0.1,-0.2,0.1), env)$ 

#### fm.Mobius(v, env)

Calculates the Möbius representation of v. Example:

Mob <- fm.Mobius(c(0,0.3,0.5,0.6,0.4,0.8,0.7,1), env)

#### fm.Zeta(Mob, env)

Calculates the inverse Möbius representation of a fuzzy measure, i.e. the standard representation. Example:

 $v \leftarrow fm.Zeta(c(0.0,0.3,0.5,-0.2,0.4,0.1,-0.2,0.1), env)$ 

#### fm.Shapley(v, env)

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Calculates the Shapley values of v in standard representation and returns it as an array of size n. Example:

 $x \leftarrow fm.Shapley(c(0,0.3,0.5,0.6,0.4,0.8,0.7,1), env)$ 

#### fm.ShaplevMob(Mob, env)

Calculates the Shapley values of Mob in Möbius representation and returns it as an array of size n. Example:

 $x \leftarrow fm.ShapleyMob(c(0.0,0.3,0.5,-0.2,0.4,0.1,-0.2,0.1), env)$ 

#### fm.Banzhaf(v)

Calculates the Banzhaf values of v in standard representation and returns it as an array of size n. Example:

 $x \leftarrow fm.Banzhaf(c(0,0.3,0.5,0.6,0.4,0.8,0.7,1), env)$ 

#### fm.BanzhafMob(Mob, env)

Calculates the Banzhaf values of Mob in Mobius representation and returns it as an array of size n. Example:

 $x \leftarrow fm.BanzhafMob(c(0.0,0.3,0.5,-0.2,0.4,0.1,-0.2,0.1), env)$ 

#### fm.Interaction(v, env)

Calculates all the interaction indices of fuzzy measure v in standard representation and returns it in an array of size m. Example:

 $w \leftarrow fm.Interaction(c(0,0.3,0.5,0.6,0.4,0.8,0.7,1), env)$ 

#### fm.InteractionMob(v, env)

Calculates all the interaction indices of fuzzy measure Mob in Möbius representation and returns it in an array of size m. Example:

 $w \leftarrow fm.InteractionMob(c(0.0,0.3,0.5,-0.2,0.4,0.1,-0.2,0.1), env)$ 

#### fm.InteractionB(v, env)

Calculates all the Banzhaf interaction indices of fuzzy measure v given in standard representation and returns the result in an array of size m.

 $w \leftarrow fm.InteractionB(c(0,0.3,0.5,0.6,0.4,0.8,0.7,1), env)$ 

#### fm.InteractionBMob(Mob, env)

Calculates all the Banzhaf interaction indices of fuzzy measure Mob in Möbius representation and returns the result in an array of size m.

 $w \leftarrow fm.InteractionBMob(c(0.0,0.3,0.5,-0.2,0.4,0.1,-0.2,0.1), env)$ 

#### fm.dualm(v, env)

Calculates the dual of fuzzy measure v in standard representation and returns it in an array of size m. Example:

 $w \leftarrow fm.dualm(c(0,0.3,0.5,0.6,0.4,0.8,0.7,1), env)$ 

#### fm.dualmMob(Mob, env)

Calculates the dual of fuzzy measure Mob in Möbius representation and returns it in an array of size m. Example:

 $w \leftarrow fm.dualm(c(0.0,0.3,0.5,-0.2,0.4,0.1,-0.2,0.1), env)$ 

#### fm.ConstructLambdaMeasure(singletons, env)

Given the values of a fuzzy measure at singletons, finds the value of  $\lambda$ , computes all other values of the fuzzy measure in standard representation, and returns the

pair  $(\lambda, v)$ , where v is an array of size m. The input array singletons is an array of size n of the values of fuzzy measure at singletons. Example:

(lambda, v) <- fm.ConstructLambdaMeasure(c(0, 0.3, 0.5), env)

fm.ConstructLambdaMeasureMob(Mob, env)

Given the values of a fuzzy measure at singletons, finds the value of  $\lambda$ , computes all other values of the fuzzy measure in Möbius representation, and returns the pair  $(\lambda, Mob)$ , where v is an array of size m. The input array singletons is an array of size n of the values of fuzzy measure at singletons. Example:

(lambda, Mob) <- fm.ConstructLambdaMeasure(c(0, 0.3, 0.5), env)

The following routines are self-explanatory. They return 1 if yes, 0 if no. The input parameters are: fuzzy measure v in standard representation and fuzzy measure Mob in Möbius representation.

IsMeasureAdditive(v, env) IsMeasureAdditiveMob(Mob, env) IsMeasureBalanced(v, env) IsMeasureBalancedMob(Mob, env) IsMeasureSelfdual(v, env) IsMeasureSelfdualMob(Mob, env) IsMeasureSubadditive(v, env) IsMeasureSubadditiveMob(v, env) IsMeasureSubmodular(v, env) IsMeasureSubmodularMob(Mob, env) IsMeasureSuperadditive(v, env) IsMeasureSuperadditiveMob(Mob, env) IsMeasureSupermodular(v, env) IsMeasureSupermodularMob(Mob, env) IsMeasureSymmetric(v, env) IsMeasureSymmetricMob(Mob, env) IsMeasureKmaxitive(v, env) (returns k): IsMeasureKmaxitiveMob(Mob, env) (returns k).

#### 4.3 Description of fuzzy measure fitting routines

The package contains six functions taking taking the empirical data, some options, and returning the (k-additive) fuzzy measure

fm.fitting([emprical data], [env], [k-additive])

Returns fuzzy measure fitted to data in standard representation.

fm.fittingMob([emprical data], [env], [k-additive])

Returns fuzzy measure fitted to data in Möbius representation.

fm.FuzzyMeasureFitLP([emprical data], [env], [k-additive], [other options]) Returns fuzzy measure fitted to data in standard representation, with optional constraints on the orness measure and the upper and lower values of Shapley values and interaction indices.

fm.FuzzyMeasureFitLPMob([emprical data], [env], [k-additive], [other options])

Returns fuzzy measure in Möbius representation fitted to data in standard representation, with optional constraints on the orness measure and the upper and lower values of Shapley values and interaction indices.

#### fm.fittingKtolerant([emprical data], [env], [k-tolerant])

Returns k-tolerant fuzzy measure fitted to data in standard representation, with no optional constraints.

#### fm.fittingKmaxitive([emprical data], [env], [k-maxitive])

Returns k-maxitive fuzzy measure fitted to data in standard representation, with no optional constraints.

#### fm.fittingOWA([emprical data], [env])

Returns symmetric fuzzy measure fitted to data. The vector of OWA weights is returned as in this case the Choquet integral becomes the OWA function.

#### fm.fittingWAM([emprical data], [env])

Returns additive fuzzy measure fitted to data. The vector of WAM weights is returned as in this case the Choquet integral becomes the WAM function.

List of parameters and options of the FuzzyMeasureFitLP function.

data - an array of size  $K \times (n+1)$ , where each row is the pair  $(\mathbf{x}_k, y_k)$ ,  $\mathbf{x}_k \in [0, 1]^n$ ,  $y_k \in [0, 1]$ , K data altogether.

Kadd - k in k-additive fuzzy measures, 1 < Kadd < n+1, if Kdd = n - f.m. is unrestricted.

options (default value is 0)

- 1 lower bounds on Shapley values supplied in *indexlow*
- 2 upper bounds on Shapley values supplied in *indexhigh*
- ullet 3 lower and upper bounds on Shapley values supplied in indexlow and indexhigh
- 4 lower bounds on all interaction indices supplied in *indexlow*
- $\bullet\,$  5 upper bounds on all interaction indices supplied in indexhigh
- 6 lower and upper bounds on all interaction indices supplied in *indexlow* and *indexhigh*.

all these value will be treated as additional constraints in the LP.

indexlow, indexhigh - array of size n (options =1,2,3) or m (options=4,5,6) containing the lower and upper bounds on the Shapley values or interaction indices options1 (default 0) is a flag whose bits indicate which additional properties are needed. If the first bit is set then the desired interval of orness values specified in array orness will be used. If the second bit is set, then the f.m. will be forced to

array orness will be used. If the second bit is set, then the f.m. will be forced to be balanced (currently not implemented). If the third bit is set, then in addition to fitting the data, the order of output values will be preserved.

If the fourth bit is set, the fuzzy measure will be forced to be sub-modular. This option is new in version 1.2.

Note that this constraint may lead to inconsistent set of conditions, in which case the problem will have no solution (and no output vector returned).

orness - array of size 2 which contains the lower and the upper bounds on the orness value. These values should be from [0,1], and could coincide if an exact orness value is needed. If the bounds are 0 and 1 respectively they are ignored. Only used if the first bit of options1 is set.

Notes: 1. arrays indexlow and indexhigh are 0-based if they contain Shapley values (i.e., the bound on Shapley value of the first input is in indexlow[0], etc. but when these arrays contain interaction indices, these are 1-based (since there is a non-zero value of the interaction index corresponding to empty set). In this case the bounds are arranged in cardinality order, i.e., the bounds correspond to the sets in this ordering (for n=3)  $\emptyset$ {1}{2}{3}{12}{13}{23}{12}.

- 2. If an exact value of some index or Shapley value is needed, use indexlow[i] = indexhigh[i] = this value if no value for some index is required, use indexlow[i] = -1, indexhigh[i] = 1.
- 3. Note that Shapley values have range [0,1], whereas interaction indices have range [-1,1].

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#### 4.4 Examples

```
library("Rfmtool")
#initialisation for dimension 3
env<-fm.Init(3)
#prepare some data
dco1<-3
drow<-10
mydata<-matrix(runif(dcol*drow,0,1),drow,dcol)</pre>
#generate some lambda fuzzy measure
mymeasure<-fm.ConstructLambdaMeasure(c(0.1,0.1,0.9),env)</pre>
# calculate choquet integrals of the data
mych<-apply(mydata,1,function(x) fm.Choquet(x, mymeasure$measure, env))</pre>
datafit<-cbind(mydata,mych)</pre>
# now fit the measure to the data (we should get back the same
# fuzzy measure we used as a model)
fittedm<-fm.fitting(datafit,env);</pre>
mymeasure
fittedm
#check some properties of fuzzy measures
fm.IsMeasureAdditive(fittedm,env);
fm.IsMeasureSubadditive(fittedm,env);
# alternative fitting calls
fittedowa<-fm.fittingOWA(datafit,env);</pre>
fittedkmax<-fm.fittingKmaxitive(datafit,env,2);</pre>
fittedktol<-fm.fittingKtolerant(datafit,env,2);</pre>
```

#### 4.5 Where to get help

The software library rfmtool and its components, are distributed by G.Beliakov AS IS, with no warranty, explicit or implied, of merchantability or fitness for a particular purpose. G.Beliakov, at his sole discretion, may provide advice to registered users on the proper use of rfmtool and its components.

Any queries regarding technical information, sales and licensing should be directed to gleb@deakin.edu.au. I am interested to learn about your experiences using fmtool, bugs, suggestions, its usefulness, applying it in practice and so on.

If you want to cite Rfmtool package, use references [2-4].

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