BYM with PC priors

Patrick Brown

April 2016

```
require('diseasemapping')
## Loading required package: diseasemapping
data('kentucky')
```

Incidence rates

```
# get rid of under 10's
larynxRates = larynxRates[grep("_(0|5)$",names(larynxRates), invert=TRUE)]
# compute Sexpected
kentucky = diseasemapping::getSMR(
    popdata=kentucky,
    model = larynxRates,
    casedata=larynx,
    regionCode="County")
```

The BYM model

The Besag, York and Mollie model for Poisson distributed case counts is:

$$Y_i \sim \text{Poisson}(O_i \lambda_i)$$

$$\log(\mu_i) = X_i \beta + U_i$$

$$U_i \sim \text{BYM}(\sigma_1^2, \sigma_2^2)$$

- Y_i is the response variable for region i
- O_i is the 'baseline' expected count, which is specified
- X_i are covariates
- U_i is a spatial random effect with a spatially structured variance parameter σ_1^2 and a spatially independent variance σ_2^2

Gamma priors on precision

```
kBYM = kBYMpc = try(bym(formula = observed ~ offset(logExpected) + poverty, data = kentu
priorCI = list(sdSpatial = c(0.1, 5), sdIndep = c(0.1, 5)), region.id = "County"))
```

Above, Gamma priors are assigned to $1/\sigma_1^2$ and $1/\sigma_2^2$, with the shape and scale parameters set to produce 2.5% to 97.5% prior intervals of (0.1, 5) for each standard deviation parameter.

```
if(!is.null(kBYM$parameters))
     knitr::kable(kBYM$parameters$summary[,c(1,3,5)], digits=3)
```

BYM with penalised complexity prior

'propSpatial = c(u=0.5, alpha=0.8)' means $pr(\phi < 0.5) = 0.8$, which is different from the specification of 'pc.prec'

```
kBYMpc = try(bym(formula = observed \sim offset(logExpected) + poverty, kentucky, prior = Ialpha = 0.05), propSpatial = <math>c(u = 0.5, alpha = 0.8)), verbose = TRUE), silent = TRUE
```

Here penalized complexity priors are used with $pr(\sqrt{\sigma_1^2 + \sigma_2^2} > 1) = 0.05$ and

$$pr(\sigma_1/\sqrt{\sigma_1^2 + \sigma_2^2} < 0.5) = 0.8.$$

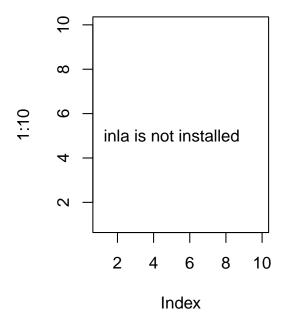


Figure 1: gamma priors sd parameters

map images will be cached in /tmp/RtmpJuUNSP/mapmiscCache

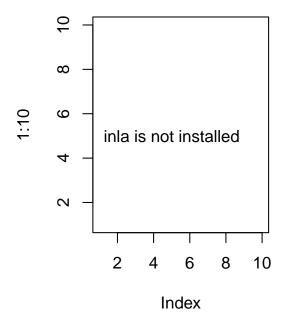


Figure 2: PC priors variance parameters

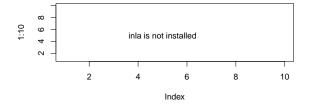


Figure 3: Random effects and fitted values