diveMove: dive analysis in R

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1 Introduction

Dive analysis usually involves handling of large amounts of data, as new instruments allow for frequent sampling of variables over long periods of time. The aim of this package is to make this process more efficient for summarizing and extracting information gathered by time-depth recorders (TDRs, hereafter). The principal motivation for developing diveMove was to provide more flexibility during the various stages of

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Table 1. Sample 1DR me structure.					
date	time	depth	light	temperature	speed
16/02/2004	14:30:00	12	200	8.4	1.44
16/02/2004	14:30:05	15	180	8.0	1.75
16/02/2004	14:30:10	19	170	7.6	1.99

Table 1. Sample TDR file structure

analysis than that offered by popular commercial software. This is achieved by making the results from intermediate calculations easily accessible, allowing the user to make his/her own summaries beyond the default choices the package provides. The following sections of this vignette illustrate a typical work flow during analysis of TDR data, using the dives data available in diveMove as an example.

2 Starting up

As with other packages in R, to use the package we load it with the funtion library:

> library(diveMove)

This makes the objects in the package available in the current R session. A short overview of the most important functions can be seen by running the examples in the package's help page:

> example(diveMove)

3 Reading Input Files

Input files must be simple, comma-delimited text files¹. The order of columns is not significant, as the column numbers indicating the variables of interest can be supplied as arguments. Table 1 shows the file structure that readTDR assumes by default, which is a standard structure of files from common TDR models.

Depending on the TDR model, speed may be omitted.

To read the file into R, use the function readTDR:

¹The extension does not matter, but conventionally these files have a .csv extension

Read the help page for readTDR using ?readTDR following common R help facilities. Thus, data could have been subsampled at a larger interval than that in the original file, so that the time interval between readings is 10 s:

But since the original 5 s interval (which is the default value for *subsamp*) is what will be used for the subsequent sections, it is recreated it here:

The format in which date and time should be interpreted can be controlled with the argument *dtformat*. If the data are already available in the R session, e.g. as a data frame, then the function createTDR can be used to convert it to a form that facilitates further analyses.

Both of these functions store the data in an object of class TDR or TDRspeed, which hold information on the source file and sampling interval, in addition to the variables described above. Which of these objects is created is determined by the speed.

4 Extracting Information from TDR and TDRspeed Objects

For convenience, extractor methods are available to access the different slots from objects of these classes. The standard *show* method will display the usual overview information on the object:

> sealX

```
Time-Depth Recorder data -- Class TDRspeed object
  Source File
                          : dives.csv
  Sampling Interval (s)
                          : 5
  Number of Samples
                          : 34199
                          : 2002-01-05 11:32:00
  Sampling Begins
  Sampling Ends
                          : 2002-01-07 11:01:50
  Total Duration (d)
                         : 1.979
  Measured depth range (m): [ -4 , 91 ]
  Other variables
                          : light temperature speed
```

Other extractor methods are named after the component they extract: getTime, get-Depth, getSpeed, and getDtime, where the latter extracts the sampling interval. The plotTDR method brings up a plot of the data covering the entire record, although a tcltk widget provides controls for zooming and panning to any particular time window. Alernatively, the underlying function plotTD provides the same functionality, but takes separate time and depth arguments, rather than a TDR object.

At any time, TDR objects can be coerced to a simple data frame, which can later be exported or manipulated any other way:

- > sealX.df <- as.data.frame(sealX)
 > head(sealX.df)
- time depth light temperature speed 1 2002-01-05 11:32:00 NA NANANA2 2002-01-05 11:32:05 NA NA NA NA3 2002-01-05 11:32:10 NA NA NA NA4 2002-01-05 11:32:15 NA NANA NA 5 2002-01-05 11:32:20 NANΑ NA NA 6 2002-01-05 11:32:25 NA NA NA NA

5 Zero-Offset Depth Correction and Summary of Wet/Dry Periods

One the first steps of dive analysis involves correcting depth for shifts in the pressure transducer, so that surface readings correspond to the value zero. Although some complex algorithms exist for detecting where these shifts occur in the record, the shifts remain difficult to detect and dives are often missed, which a visual examination of the data would have exposed. The trade off is that visually zero-adjusting depth is tedious, but the advantages of this approach far outweigh this cost, as much insight is gained by visually exploring the data. Not to mention the fact that obvious problems in the records are more effectively dealt with in this manner.

That personal rant aside, zero offset correction (ZOC) is done in diveMove using the function zoc. However, a more efficient method of doing this is by using the calibrat-eDepth function, which takes a TDR object (or inheriting from it) to perform three basic tasks. The first is to ZOC the data, using the tcltk package to be able to do it interactively:

> dcalib <- calibrateDepth(sealX)</pre>

This command brings up a plot with tcltk controls allowing to pan and zoom in or out of the data, as well as adjustment of the depth scale. Thus, an appropriate time

window with a unique surface depth value can be displayed. It is important to make the display such that the depth scale is small enough to allow the resolution of the surface value with the mouse. Clicking on the ZOC button waits for two clicks:

- 1. the coordinates of the first click define the starting time for the window to be ZOC'ed, and the depth corresponding to the surface,
- 2. the second click defines the end time for the window (only the x coordinate has any meaning).

This procedure can be repeated as many times as needed. If there is any overlap between time windows, then the last one prevails. However, if the offset is known a priori, there is no need to go through all this procedure, and the value can be provided as the argument *offset* to calibrateDepth.

Once depth has been ZOC'ed, calibrateDepth will identify dry and wet periods in the record. Wet periods are those where a depth reading is available, dry periods are those without a depth reading. Records often have abherrant missing depth that should not be considered dry periods, as they are often of very short duration. Likewise, there may be periods of wet activity that are too short to be compared with other wet periods. This can be controlled by setting the arguments dry.thr and wet.thr.

Finally, calibrateDepth identifies all dives in the record, according to a minimum depth criteria given as its *divethres* argument. The result (value) of this function is an object of class *TDRcalibrate*, where all the information obtained during the tasks described above are stored. Again, an appropriate *show* method is available to display a short overview of such objects:

> dcalib

Depth calibration -- Class TDRcalibrate object

Source file : dives.csv

Number of dry phases : 4

Number of aquatic phases : 3

Number of dives detected : 317

Dry threshold used (s) : 70

Aquatic theshold used (s) : 3610

Dive threshold used (s) : 4

Speed calibration coefficients : a = 0 ; b = 1

6 Access to Elements from TDRcalibrate Objects

Extractor methods are also available to access the information stored in TDRcalibrate objects. These include: getTDR, getGAct, getDAct, getDPhaseLab, and getSpeedCoefs.

These are all generic functions² that access the (depth) calibrated TDR object, details from wet/dry periods, dives, dive phases, and speed calibration coefficients (see Section 7), respectively. Below is a short explanation of these methods.

getTDR This method simply takes the TDR calibrate object as its single argument and extracts the TDR object³:

> getTDR(dcalib)

Time-Depth Recorder data -- Class TDRspeed object

Source File : dives.csv

Sampling Interval (s) : 5 Number of Samples : 34199

Sampling Begins : 2002-01-05 11:32:00 Sampling Ends : 2002-01-07 11:01:50

Total Duration (d) : 1.979
Measured depth range (m): [0 , 88]

Other variables : light temperature speed

getGAct There are two methods for this generic, allowing access to a list with details about all wet/dry periods found. One of these extracts the entire *list* (output omitted for brevity):

> getGAct(dcalib)

The other provides access to particular elements of the *list*, by their name. For example, if we are interested in extracting only the vector that tells us to which period number every row in the record belongs to, we would issue the command:

> getGAct(dcalib, "phase.id")

Other elements that can be extracted are named "activity", "begin", and "end", and can be extracted in a similar fashion. These elements correspond to the activity performed for each reading (see ?detPhase for a description of the labels for each activity), the beginning and ending time for each period, respectively.

getDAct This generic also has two methods; one to extract an entire data frame with details about all dive and postdive periods found (output omitted):

> getDAct(dcalib)

²A few of them with more than one method

³In fact, a *TDRspeed* object in this example

The other method provides access to the columns of this data frame, which are named "dive.id", "dive.activity", and "postdive.id". Thus, providing any one of these strings to getDAct, as a second argument will extract the corresponding column.

getDPhaseLab This generic function extracts a factor identifying each row of the record to a particular dive phase (see ?detDive for a description of the labels of the factor identifying each dive phase). Two methods are available; one to extract the entire factor, and the other to select particular dive(s), by its (their) number, respectively (output omitted):

```
> getDPhaseLab(dcalib)
> getDPhaseLab(dcalib, 20)
> dphases <- getDPhaseLab(dcalib, c(100:300))</pre>
```

The latter method is useful for visually inspecting the assignment of points to particular dive phases. Before doing that though, this is a good time to introduce another generic function that allows the subsetting of the original TDR object to a single a dive or group of dives' data:

```
> subSealX <- extractDive(dcalib, diveNo = c(100:300))
> subSealX
Time-Depth Recorder data -- Class TDRspeed object
  Source File
                          : dives.csv
  Sampling Interval (s)
                          : 5
  Number of Samples
                         : 2410
 Sampling Begins
                          : 2002-01-06 00:45:15
  Sampling Ends
                          : 2002-01-07 03:27:10
  Total Duration (d)
                          : 1.112
 Measured depth range (m): [ 0 , 88 ]
                          : light temperature speed
  Other variables
```

As can be seen, the function takes a TDRcalibrate object and a vector indicating the dive numbers to extract, and returns a TDR object containing the subsetted data. Once a subset of data has been selected, it is possible to plot them and pass the factor labelling dive phases as the argument phaseCol to the plotTDR method⁴:

> plotTDR(subSealX, phaseCol = dphases)

⁴The function that the method uses is actually plotTD, so all the possible arguments can be studied by reading the help page for plotTD

7 Speed Calibration

Dry threshold used (s)

Dive threshold used (s)

Aquatic theshold used (s)

Calibration of speed readings is done using the principles described in Blackwell et al. (1999) and Hindell et al. (1999). The function calibrateSpeed performs this operation, and allows the selection of the particular subset of the data that should be used for the calibration:

: 70

: 3610

```
> vcalib <- calibrateSpeed(dcalib, z = 1)

> vcalib

Depth calibration -- Class TDRcalibrate object
   Source file : dives.csv
   Number of dry phases : 4
   Number of aquatic phases : 3
   Number of dives detected : 317
```

Speed calibration coefficients : a = -0.44; b = 1.1

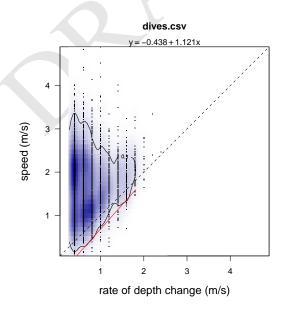


Figure 1. Example speed calibration line from a TDR record.

Using plot=FALSE it is possible to turn off the default side effect of producing a plot displaying the quantile regression fit (Figure 1).

Control is possible by the use of arguments bad, which controls minimum rates of depth change and speeds through which the calibration line should be drawn. To control for the resolution of the TDR, z can be used to include only changes in depth greater than a given value for the construction of the calibration line.

If the calibration coefficients from the implicit quantile regression are known a priori, then these can be supplied to the function via its *coefs* argument. In this case, no plots are created.

8 TDR dive and postdive statistics

> dives <- diveStats(vcalib)</pre>

> head(dives, 3)

Once data have been calibrated and the record broken up at "trip" and "dive" scales, obtaining dive statistics is a trivial call to function diveStats:

```
enddesc
               begdesc
1 2002-01-05 12:20:10 2002-01-05 12:20:10
2 2002-01-05 21:19:40 2002-01-05 21:20:10
3 2002-01-05 21:22:10 2002-01-05 21:23:05
                begasc desctim botttim asctim descdist
1 2002-01-05 12:20:25
                            2.5
                                      15
                                                        3
                                            2.5
2 2002-01-05 21:20:50
                           32.5
                                      40
                                           37.5
                                                       24
3 2002-01-05 21:23:50
                           57.5
                                     45
                                           72.5
                                                       61
  bottdist ascdist desc.tdist desc.mean.speed desc.angle
1
         6
                  3
                                              NA
                             NA
                                                          NA
2
         9
                 25
                          63.62
                                           2.121
                                                       22.16
3
        10
                 67
                          98.08
                                           1.783
                                                       38.46
  bott.tdist bott.mean.speed asc.tdist asc.mean.speed
1
                         2.858
       42.87
                                       NA
                                                       NA
2
       87.59
                         2.190
                                   55.67
                                                    1.591
3
       69.92
                         1.554
                                  108.13
                                                    1.545
  asc.angle divetim maxdep postdive.dur postdive.tdist
1
                           6
                                     32345
                                                 52784.67
         NA
                  20
2
      26.69
                 110
                          29
                                        35
                                                     35.78
3
      38.29
                 175
                          67
                                        75
                                                     89.21
  postdive.mean.speed
1
                 1.638
2
                 1.022
3
                 1.189
```

The function takes a single argument: an object of class *TDRcalibrate*, and returns a data frame with one row per dive in the record, with a suite of basic dive statistics in each column. Please consult ?diveStats for an explanation of each of the variables estimated, although the names of the output data frame should be self explanatory. These variables are thus available for calculating any other derived values, by extracting them using the standard R subscripting facilities.

9 Miscellaneous functions

Other functions are included for handling location data, and these are readLocs, aust-Filter, and distSpeed. These are useful for reading, filtering, and summarizing travel information. For extensive animal movement analyses, refer to package trip.

10 Acknowledgements

Invaluable input and help during development of this package has been offered by John P.Y. Arnould, and regular contributors to R-help.

References

Blackwell, S., Haverl, C., Le Boeuf, B., and Costa, D. (1999). A method for calibrating swim-speed recorders. *Marine Mammal Science*, 15(3):894–905.

Hindell, M., McConnell, B., Fedak, M., Slip, D., Burton, H., Reijnders, P., and McMahon, C. (1999). Environmental and physiological determinants of successful foraging by naive southern elephant seal pups during their first trip to sea. *Canadian Journal of Zoology*, 77:1807–1821.

diveMove

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R topics documented:

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2 austFilter

austFilter Filter satellite locations	austFilter	Filter satellite locations	
---------------------------------------	------------	----------------------------	--

Description

Apply a three stage algorithm to eliminate erroneous locations, based on the procedure outlined in Austin et al. (2003).

Usage

```
austFilter(time, lon, lat, id=gl(1, 1, length(time)),
    speed.thr, dist.thr, window=5)
grpSpeedFilter(x, speed.thr, window=5)
rmsDistFilter(x, speed.thr, window=5, dist.thr)
```

Arguments

```
POSIXct object with dates and times for each point.
time
1 on
                  numeric vectors of longitudes, in decimal degrees.
lat
                  numeric vector of latitudes, in decimal degrees.
id
                  a factor grouping points in different categories (e.g. individuals).
                  speed threshold (m/s) above which filter tests should fail any given point.
speed.thr
                  distance threshold (km) above which the last filter test should fail any given
dist.thr
window
                  integer indicating the size of the moving window over which tests should be
                  carried out.
                  3-column matrix with column 1: POSIXct vector; column 2: numeric longi-
                  tude vector; column 3: numeric latitude vector.
```

Details

These functions implement the location filtering procedure outlined in Austin et al. (2003). grpSpeedFilter and rmsDistFilter can be used to perform only the first stage or the second and third stages of the algorithm on their own, respectively. Alternatively, the three filters can be run sequentially using austFilter.

The first stage of the filter is an iterative process which tests every point, except the first and last two, for travel velocity relative to the preceeding/following two points. If all these four speeds are greater than the specified threshold, the point is marked as failing the first stage. In this case, the next point is tested, removing the failing point from the set of test points.

The second stage runs McConnell et al. (1992) algorithm, which tests all the points that passed the first stage, in the same manner as above. The root mean square of all four speeds is calculated, and if it is greater than the specified threshold, the point is marked as failing the second stage.

The third stage is run simultaneously with the second stage, but if the mean distance of all four pairs of points is greater than the specified threshold, then the point is marked as failing the third stage.

The speed and distance threshold should be obtained separately (see distSpeed).

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Value

grpSpeedFilter returns a logical vector indicating those lines that passed the test.

rmsDistFilter and austFilter return a matrix with 2 or 3 columns, respectively, of logical vectors with values TRUE for points that passed each stage. For the latter, lines that don't pass the first stage do not pass the other stages. The second and third columns returned by austFilter, as well as those returned by rmsDistFilter are independent of one another; i.e. lines that don't pass stage 2 do not necessarily not pass stage 3.

Warning

This function applies McConnell et al.'s filter as described in Austin et al. (2003), but other authors may have used the filter differently. Austin et al. (2003) have apparently applied the filter in a vectorized manner. It is not clear from the original paper whether the filter is applied iteratively or in a vectorized fashion, so authors may be usine it inconsistently.

Author(s)

Sebastian P. Luque (spluque@gmail.com) and Andy Liaw.

References

McConnell BJ, Chambers C, Fedak MA. 1992. Foraging ecology of southern elephant seals in relation to bathymetry and productivity of the Southern Ocean. *Antarctic Science* 4:393-398.

Austin D, McMillan JI, Bowen D. 2003. A three-stage algorithm for filtering erroneous Argos satellite locations. *Marine Mammal Science* 19: 371-383.

See Also

```
distSpeed
```

Examples

4 calibrateDepth

calibrateDepth Co

Calibrate Depth and Generate a "TDRcalibrate" object

Description

Detect periods of major activities in a TDR record, calibrate depth readings, and generate a "TDR-calibrate" object essential for subsequent summaries of diving behaviour.

Usage

Arguments

х	an object of class ${\tt TDR}$ for calibrateDepth or an object of class ${\tt TDR}$ calibrate for calibrateSpeed.	
dry.thr	dry error threshold in seconds. Dry phases shorter than this threshold will be considered as wet.	
wet.thr	wet threshold in seconds. At-sea phases shorter than this threshold will be considered as trivial wet.	
dive.thr	threshold depth below which an underwater phase should be considered a dive.	
offset	argument to zoc. If not provided, the offset is obtained using an interactive plot of the data.	
descent.crit	.q critical quantile of rates of descent below which descent is deemed to have ended.	
ascent.crit.q		
	critical quantile of rates of ascent above which ascent is deemed to have started.	
wiggle.tol	Proportion of maximum depth above which wiggles should not be allowed to define the end of descent. It's also the proportion of maximum depth below which wiggles should be considered part of bottom phase.	

Details

This function is really a wrapper around .detPhase and .detDive, which perform the work on simplified objects. It performs zero-offset correction of depth, wet/dry phase detection, and detection of dives, as well as proper labelling of the latter.

The procedure starts by first creating a factor with value $^{\circ}L^{\circ}$ (dry) for rows with NAs for depth and value $^{\circ}W^{\circ}$ (wet) otherwise. It subsequently calculates the duration of each of these phases of activity. If the duration of an dry phase $(^{\circ}L^{\circ})$ is less than $^{\circ}dry$, $^{\circ}thr$, then the values in the factor for that phase are changed to $^{\circ}W^{\circ}$ (wet). The duration of phases is then recalculated, and if the duration of a phase of wet activity is less than $^{\circ}wet$, thr., then the corresponding value for the factor is changed to $^{\circ}Z^{\circ}$ (trivial wet). The durations of all phases are recalculated a third time to provide final phase durations.

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The next step is to detect dives whenever the zero-offset corrected depth in an underwater phase is below the supplied dive threshold. A new factor with finer levels of activity is thus generated, including 'U' (underwater), and 'D' (diving) in addition to the ones described above.

Once dives have been detected and assigned to a period of wet activity, phases within dives are detected using the descent, ascent and wiggle criteria. This procedure generates a factor with levels "D", "BB", "B", "A", "DA", and "X", breaking the input into descent, descent/bottom, bottom, bottom/ascent, ascent, and non-dive, respectively.

Value

An object of class TDRcalibrate.

Author(s)

Sebastian P. Luque (spluque@gmail.com)

See Also

```
TDRcalibrate, zoc
```

Examples

```
data(divesTDR)
divesTDR

## Consider a 3 m offset, and a dive threshold of 3 m
dcalib <- calibrateDepth(divesTDR, dive.thr=3, offset=3)
## Not run:
plotTDR(dcalib, labels="dive.phase", surface=TRUE)
## End(Not run)</pre>
```

calibrateSpeed

Calibrate and build a "TDRcalibrate" object

Description

These functions create a "TDRcalibrate" object which is necessary to obtain dive summary statistics.

Usage

```
calibrateSpeed(x, tau=0.1, contour.level=0.1, z=0, bad=c(0, 0),
    main=slot(getTDR(x), "file"), coefs, plot=TRUE,
    postscript=FALSE, ...)
```

6 calibrateSpeed

Arguments

-	for calibrateSpeed.
tau	quantile on which to regress speed on rate of depth change; passed to rq.
contour.leve	1
	the mesh obtained from the bivariate kernel density estimation corresponding to this contour will be used for the quantile regression to define the calibration line.
Z	only changes in depth larger than this value will be used for calibration.
bad	length 2 numeric vector indicating that only rates of depth change and speed greater than the given value should be used for calibration, respectively.
coefs	known speed calibration coefficients from quantile regression as a vector of length 2 (intercept, slope). If provided, these coefficients are used for calibrating speed, ignoring all other arguments, except x.
main,	arguments passed to rqPlot.
plot	logical indicating whether to plot the results.
postscript	logical indicating whether to produce postscript file output.

an object of class TDR for calibrateDepth or an object of class TDR calibrate

Details

This calibrates speed readings following the procedure outlined in Blackwell et al. (1999).

Value

```
An object of class TDRcalibrate.
```

Author(s)

Sebastian P. Luque (spluque@gmail.com)

References

Blackwell S, Haverl C, Le Boeuf B, Costa D (1999). A method for calibrating swim-speed recorders. Marine Mammal Science 15(3):894-905.

See Also

```
TDRcalibrate
```

Examples

```
data(divesTDRcalibrate)
divesTDRcalibrate

## Calibrate speed using only changes in depth > 2 m
vcalib <- calibrateSpeed(divesTDRcalibrate, z=2)
vcalib</pre>
```

detDive-internal 7

detDive-internal Detect dives from depth readings

Description

Identify dives in TDR records based on a dive threshold.

Usage

```
.detDive(zdepth, act, dive.thr=4, ...)
```

Arguments

zdepth	vector of zero-offset corrected depths.
act	factor as long as \mathtt{depth} coding activity, with levels specified as in . $\mathtt{detPhase}.$
dive.thr	threshold depth below which an underwater phase should be considered a dive.
	the sampling interval in seconds.

Value

A data frame with the following elements for .detDive

```
dive.id numeric vector numbering each dive in the record.

dive.activity
factor with levels 'L', 'W', 'U', 'D', and 'Z', see .detPhase. All levels may be represented.

postdive.id numeric vector numbering each postdive interval with the same value as the preceding dive.
```

Author(s)

```
Sebastian P. Luque (spluque@gmail.com)
```

```
.detPhase, zoc
```

8 detPhase-internal

detPhase-internal Detect phases of activity from depth readings

Description

Functions to identify sections of a TDR record displaying one of three possible activities: dry, wet, and trivial wet.

Usage

```
.detPhase(time, depth, dry.thr, wet.thr, ...)
```

Arguments

```
time POSIXct object with date and time for all depths.

depth numeric vector with depth readings.
dry.thr, wet.thr
Passed from calibrateDepth.
Passed from calibrateDepth; sampling interval in seconds.
```

Details

.detPhase first creates a factor with value 'L' (dry) for rows with NAs for depth and value 'W' (wet) otherwise. It subsequently calculates the duration of each of these phases of activity. If the duration of an dry phase ('L') is less than dry,thr, then the values in the factor for that phase are changed to 'W' (wet). The duration of phases is then recalculated, and if the duration of a phase of wet activity is less than wet,thr, then the corresponding value for the factor is changed to 'Z' (trivial wet). The durations of all phases are recalculated a third time to provide final phase durations.

Value

A list with components:

phase.id	numeric vector identifying each activity phase, starting from $\boldsymbol{1}$ for every input record.
activity	factor with levels 'L' indicating dry, 'W' indicating wet, 'U' for underwater (above dive criterion), 'D' for diving, 'Z' for trivial wet animal activities. Only 'L', 'W', and 'Z' are actually represented.
begin	a POSIXct object as long as the number of unique activity phases identified, indicating the start times for each activity phase.
end	a POSIXct object as long as the number of unique activity phases identified, indicating the end times for each activity phase.

Author(s)

Sebastian P. Luque (spluque@gmail.com) and Andy Liaw.

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See Also

```
.detDive
```

distSpeed Calculate distance and speed between locations

Description

Calculate distance, time difference, and speed between pairs of points defined by latitude and longitude, given the time at which all points were measured.

Usage

```
distSpeed(pt1, pt2, id=gl(1, nrow(pt1)))
```

Arguments

pt1 a matrix or data frame with three columns; the first a POSIXct object with dates and times for all points, the second and third numeric vectors of longitude and latitude for all points, respectively, in decimal degrees.

pt2 a matrix with the same structure as pt1.

id a factor dividing the data in txv into distinct groups.

Details

ptl and pt2 may contain any number of rows. track is essentially a wrapper for distSpeed, taking a data frame, assumed to be ordered chronologically, and calculations are done between all successive rows.

Value

A matrix with three columns: distance (km), time difference (s), and speed (m/s).

Author(s)

Sebastian P. Luque (spluque@gmail.com)

Examples

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```
ringy.travel <- distSpeed(ringy[-nrow(ringy), 3:5], ringy[-1, 3:5])
## Particular quantiles from travel summaries
quantile(ringy.travel[, 4], 0.99, na.rm=TRUE) # speed
quantile(ringy.travel[, 2], 0.99, na.rm=TRUE) # distance
## Travel summary between any two sets of points
distSpeed(ringy[c(1, 5, 10), 3:5], ringy[c(25, 30, 35), 3:5])</pre>
```

```
diveMove-internal Internal diveMove Functions
```

Description

Functions used for very particular tasks within larger functions in diveMove

Usage

```
.diveIndices(diveID, diveNo)
.getInterval(time)
.getSpeedStats(x, vdist)
.night(time, sunrise.time, sunset.time)
.rleActivity(time, act, interval)
.speedCol(x)
```

Arguments

 ${\tt diveID} \qquad \qquad {\tt Numeric \ vector \ of \ all \ dive \ and \ non \ dive \ IDs.}$

diveNo numeric vector of unique dive indices to extract from diveID.

time POSIXct object representing time.

x For .getSpeedStats, a matrix with a dive's section data (time, speed). A single dive's data, a 3-col matrix with time, depth, and speed. For .speedCol, a

data frame where names are searched for strings matching . ${\tt speedNames}$ (see

etans).

vdist Vertical distance travelled during this time. If vdist is missing, then it's all

horizontal movements (no angles).

sunrise.time, sunset.time

Passed from plotTD.

act A numeric vector indicating the activity for every element of time.

interval sampling interval in seconds.

diveMove-package 11

Details

These functions are not meant to be called directly by the user, as he/she could not care less (right?). This may change in the future.

- . speedNames is a character vector with possible names for a speed vector.
- .rleActivity takes a factor indicating different activity phases, their associated time, and the sampling interval to return a factor uniquely identifying each phase of activity, i.e. labelling them. In addition, it returns the duration of each phase, and their beginning and end times.

Value

- .diveIndices returns a numeric vector with the indices of dives (and their beginning/end indices) in diveID.
- .getInterval returns a scalar, the mode of intervals between time readings.
- .getSpeedStats returns a 3-column matrix with total distance, mean speed, and angle for a section of a dive.
- . night returns a list with sunrise and sunset times for dates in time.
- . speedCol returns column number where speed is located in x.
- .rleActivity returns a list with components:
- time.br A factor dividing act into different periods of activity.
- time.peract The duration of each period of activity.

beg.time, end.time

POSIXct objects indicating the beginning and ending times of each period of activity.

Author(s)

Sebastian P. Luque (spluque@gmail.com)

diveMove-package Time depth recorder analysis

Description

This package is a collection of functions for visualizing, and analyzing depth and speed data from time-depth recorders *TDRs*. These can be used to zero-offset correct depth, calibrate speed, and divide the record into different phases, or time budget. Functions are provided for calculating summary dive statistics for the whole record, or at smaller scales within dives.

Author(s)

Sebastian P. Luque (spluque@gmail.com)

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See Also

A vignette with a guide to this package is available by doing 'vignette("diveMove")'. TDR-class, calibrateDepth, calibrateSpeed, timeBudget, stampDive.

Examples

```
## read in data and create a TDR object
(sealX <- readTDR(system.file(file.path("data", "dives.csv"),
                              package="diveMove"), speed=TRUE))
## Not run:
plotTDR(sealX) # pan and zoom through the record
## End(Not run)
## detect periods of activity, and calibrate depth, creating
## a 'TDRcalibrate' object
## Not run: dcalib <- calibrateDepth(sealX) # interactively
(dcalib <- calibrateDepth(sealX, offset=3)) # zero-offset correct at 3 m
## Not run:
## plot all readings and label them with the phase of the record
## they belong to, excluding surface readings
plotTDR(dcalib, labels="phase.id", surface=FALSE)
## plot the first 300 dives, showing dive phases and surface readings
plotTDR(dcalib, diveNo=seq(300), labels="dive.phase", surface=TRUE)
## End(Not run)
## calibrate speed (using changes in depth > 1 m and default remaining arguments)
(vcalib <- calibrateSpeed(dcalib, z=1))
## Obtain dive statistics for all dives detected
dives <- diveStats(vcalib)
head(dives)
## Attendance table
att <- timeBudget (vcalib, FALSE) # taking trivial aquatic activities into account
att <- timeBudget(vcalib, TRUE) # ignoring them
## Add trip stamps to each dive
stamps <- stampDive(vcalib)
sumtab <- data.frame(stamps, dives)
head(sumtab)
```

dives

Sample TDR data from a fur seal

Description

This data set is meant to show the typical organization of a TDR *.csv file, suitable as input for readTDR, or to construct a TDR object. divesTDR and divesTDRcalibrate are example TDR and TDRcalibrate objects.

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Format

A comma separated value (csv) file with 69560 TDR readings with the following columns:

date date

time time

depth depth in m

light light level

temperature temperature in C

speed speed in m/s

The data are also provided as a TDR object (*.RData format) for convenience.

Details

The data are a subset of an entire TDR record, so they are not meant to make valid inferences from this particular individual/deployment.

```
divesTDR is a TDR object representation of the data in dives.
```

divesTDRcalibrate is a TDRcalibrate object representing the data in dives, calibrated at default criteria (see calibrateDepth), and 3 m offset.

Source

Sebastian P. Luque, Christophe Guinet, John P.Y. Arnould

See Also

readTDR

diveStats

Per-dive statistics

Description

Calculate dive statistics in TDR records.

Usage

```
diveStats(x)
oneDiveStats(x, interval, speed=FALSE)
stampDive(x, ignoreZ=TRUE)
```

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Arguments

x a TDRcalibrate-class object for diveStats and stampDive, and a

data frame containing a single dive's data for oneDiveStats.

interval sampling interval for interpreting x.

speed logical; should speed statistics be calculated?

ignoreZ logical indicating whether trips should be numbered considering all aquatic ac-

tivities ("W" and "Z") or ignoring "Z" activities.

Details

diveStats calculates various dive statistics based on time and depth for an entire TDR record. oneDiveStats obtains these statistics from a single dive, and stampDive stamps each dive with associated trip information.

Value

A data.frame with one row per dive detected (durations are in s, and linear variables in m):

begdesc A POSIXct object, specifying the start time of each dive.

enddesc A POSIXct object, as begdesc indicating descent's end time.

begasc A POSIXct object, as begdesc indicating the time ascent began.

 ${\tt descent \ duration \ of \ each \ dive.}$

botttim bottom duration of each dive.

asctim ascent duration of each dive.

descdist numeric vector with descent depth.

bottdist numeric vector with the sum of absolute depth differences while at the bottom

of each dive; measure of amount of "wiggling" while at bottom.

ascdist numeric vector with ascent depth.

desc.tdist numeric vector with descent total distance, estimated from speed.

desc.mean.speed

numeric vector with descent mean speed.

desc.angle numeric vector with descent angle.

bott.tdist numeric vector with bottom total distance, estimated from speed.

bott.mean.speed

numeric vector with bottom mean speed.

asc.tdist numeric vector with ascent total distance, estimated from speed.

asc.mean.speed

numeric vector with ascent mean speed.

asc.angle numeric vector with ascent angle.

divetim dive duration.

maxdep numeric vector with maximum depth.

postdive.dur postdive duration.

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```
postdive.tdist
```

numeric vector with postdive total distance, estimated from speed.

```
postdive.mean.speed
```

numeric vector with postdive mean speed.

The number of columns depends on the value of speed.

stampDive returns a data frame with trip number, trip type, and start and end times for each dive.

Author(s)

Sebastian P. Luque (spluque@gmail.com)

See Also

```
.detPhase.zoc.TDRcalibrate-class
```

Examples

```
data(divesTDRcalibrate)
divesTDRcalibrate

tdrX <- diveStats(divesTDRcalibrate)
stamps <- stampDive(divesTDRcalibrate, ignoreZ=TRUE)
tdrX.tab <- data.frame(stamps, tdrX)
summary(tdrX.tab)</pre>
```

```
extractDive-methods
```

Extract Dives from "TDR" or "TDRcalibrate" Objects

Description

Extract data corresponding to a particular dive(s), referred to by number.

Usage

```
## S4 method for signature 'TDR, numeric, numeric':
extractDive(obj, diveNo, id)
## S4 method for signature 'TDRcalibrate, numeric,
## missing':
extractDive(obj, diveNo)
```

Arguments

```
obj "TDR" object.
```

diveNo numeric vector or scalar with dive numbers to extract.

id numeric vector of dive numbers from where diveNo should be chosen.

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Value

An object of class TDR or TDRspeed.

Author(s)

Sebastian P. Luque (spluque@gmail.com)

Examples

```
data(divesTDR)
divesTDR
divesTDRcalibrate)
divesTDRcalibrate

divex <- extractDive(divesTDR, 9, getDAct(divesTDRcalibrate, "dive.id"))
plotTDR(diveX, interact=FALSE)

diveX <- extractDive(divesTDRcalibrate, 5:10)
plotTDR(diveX, interact=FALSE)</pre>
```

labDive-internal Internal Functions used for Detection of Dives

Description

These functions provide information for particular dives.

Usage

```
.cutDive(x, descent.crit.q, ascent.crit.q, wiggle.tol)
.labDive(act, string, interval)
.labDivePhase(x, diveID, descent.crit.q, ascent.crit.q, wiggle.tol)
```

Arguments

x For .labDivePhase, a class 'TDR' object. For .cutDive, a 3-col matrix with subscript in original TDR object, non NA depths, and numeric vector representing POSIXct times.
descent.crit.q, ascent.crit.q, wiqqle.tol

Passed from calibrateDepth.

act Factor with values to label.

 ${\tt string} \qquad \qquad A \ character \ belonging \ to \ a \ level \ of \ {\tt act} \ to \ search \ for \ and \ label \ sequentially.$

 ${\tt interval} \qquad \qquad {\tt The \ sampling \ interval \ in \ seconds.}$

diveID Numeric vector indexing each dive (non-dives should be 0)

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Details

These functions are for internal use and are not meant to be called by the user.

Value

.labDive returns a matrix with as many rows as its first two arguments with two columns: dive.id, and postdive.id, each one sequentially numbering each dive and postdive period.

.labDivePhase returns a factor with levels "D", "DB", "B", "BA", "A", "DA", and "X", breaking the input into descent, descent/bottom, bottom, bottom, ascent, ascent, and non-dive, respectively. If x contains no dives, only level "X" is present for all readings.

.cutDive generates a character vector that breaks a dive into descent, descent/bottom, bottom/ascent, ascent, and/or descent/ascent given a proportion of maximum depth for bottom time. It return a character matrix with or iz D and corresponding label.

Author(s)

Sebastian P. Luque (spluque@gmail.com)

```
plotTDR-methods Methods for plotting objects of class "TDR", "TDRspeed", and "TDR-calibrate"
```

Description

Main plotting method for objects of these classes.

Usage

Arguments

```
x "TDR", "TDRspeed", or "TDRcalibrate"object. concurVars, concurVarTitles, ...
```

arguments passed to plotTD. For the TDRspeed method, concurVars is a matrix with variables to plot, in addition to speed, if any. concurVarTites in this case is a character vector with axis labels for speed and the additional variables supplied in concurVars. For the TDRcalibrate method, concurVars is a character vector indicating which additional components from the concurrent data frame should also be plotted. if any. 18 plotTDR-methods

diveNo numeric vector with dive numbers to plot.

 ${\tt labels} \qquad \qquad {\tt one~of~"phase.id"}~or~"dive. {\tt phase"}, {\tt specifying~whether~to~label~observations~based}$

on the gross phase ID of the "TDR" object, or based on each dive phase, respec-

tively.

surface logical indicating whether to plot surface readings.

Value

If called with the interact argument set to TRUE, returns coordinates from the ZOC procedure (see zoc).

Methods

plotTDR signature(x="TDR"): interactive graphical display of the data, with zooming and panning capabilities.

 $\label{eq:plotTDR} \textbf{plotTDR} \ \ \text{signature} \ (\textbf{x="TDRspeed"}) \colon \ \ \textbf{As the TDR method, but also plots the concurrent speed readings}.$

plotTDR signature(x="TDRcalibrate"): plot the TDR object, labelling identified sections of it (see Usage).

Author(s)

Sebastian P. Luque (spluque@gmail.com)

See Also

zoc

Examples

```
data(divesTDR)
divesTDR
divesTDR(divesTDR, interact=FALSE)

data(divesTDRcalibrate)
divesTDRcalibrate
plotTDR(divesTDRcalibrate, interact=FALSE)
plotTDR(divesTDRcalibrate, diveNo=19:25, interact=FALSE)
plotTDR(divesTDRcalibrate, labels="diven, phase", interact=FALSE)
```

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readLocs	Read comma-delimited file with location data
----------	--

Description

Read a comma delimited (*.csv) file with (at least) time, latitude, longitude readings.

Usage

```
readLocs(file, loc.idCol, idCol, dateCol, timeCol=NULL,
    dtformat="%m/%d/%y %H:&M:%S", tz="GMT",
    classCol, lonCol, latCol, alt.lonCol=NULL, alt.latCol=NULL, ...)
```

Arguments

file	A string indicating the name of the file to read. Provide the entire path if the file is not on the current directory.
loc.idCol	Column number containing location ID.
idCol	Column number containing an identifier for locations belonging to different groups.
dateCol	Column number containing dates, and, optionally, times.
timeCol	Column number containing times.
dtformat	A string, specifying the format in which the date and time columns, when pasted together, should be interpreted (see strptime) in file.
tz	A string indicating the time zone for the date and time readings.
lonCol	Column number containing longitude readings.
latCol	Column number containing latitude readings.
classCol	Column number containing the ARGOS rating for each location.
alt.lonCol	Column number containing alternative longitude readings.
alt.latCol	Column number containing alternative latitude readings.
	Passed to read.csv

Details

The file must have a header row identifying each field, and all rows must be complete (i.e. have the same number of fields). Field names need not follow any convention.

Value

A data frame.

Author(s)

Sebastian P. Luque (spluque@gmail.com)

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Examples

readTDR

Read comma-delimited file with TDR data

Description

Read a comma delimited (*.csv) file containing time-depth recorder (TDR) data from various TDR models. Return a TDR or TDRspeed object. createTDR creates an object of one of these classes from other objects.

Usage

```
readTDR(file, dateCol=1, timeCol=2, depthCol=3, speed=FALSE,
    subsamp=5, concurrentCols=4:6,
    dtformat="%d/%m/%Y %H:%M:%S", tz="GMT")
createTDR(time, depth, concurrentData, speed=FALSE, dtime, file)
```

Arguments

 ${\tt file} \qquad \qquad {\tt a string indicating the path to the file to read.}$

 ${\tt dateCol} \qquad \qquad {\tt column\ number\ containing\ dates,\ and\ optionally,\ times.}$

timeCol column number with times.

depthCol column number containing depth readings.

speed for readTDR: Logical indicating whether speed is included in one of the columns

of concurrentCols

subsamp subsample rows in file with subsamp interval, in s.

concurrentCols

column numbers to include as concurrent data collected.

dt format a string, specifying the format in which the date and time columns, when pasted

together, should be interpreted (see strptime).

tz a string indicating the time zone assumed for the date and time readings.

time a POSIXct object with date and time readings for each reading.

depth numeric vector with depth readings.

concurrentData

data frame with additional, concurrent data collected.

dtime sampling interval used in seconds.

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Details

The input file is assumed to have a header row identifying each field, and all rows must be complete (i.e. have the same number of fields). Field names need not follow any convention. However, depth and speed are assumed to be in m, and $m \cdot s^{-1}$, respectively, for further analyses.

If speed is TRUE and concurrentCols contains a column named speed or velocity, then an object of class TDRspeed is created, where speed is considered the column matching this name.

Value

An object of class 'TDR' or 'TDRspeed'.

Author(s)

Sebastian P. Luque (spluque@gmail.com)

Examples

ringy

Ringed Seal Ringy ARGOS Satellite Location Data

Description

Satellite locations of a ringed seal caught and released in New York.

Format

A data frame with the following information:

time The date and time of the location.

class The ARGOS location quality classification.

lon, lat x and y geographic coordinates of each location.

Source

WhaleNet Satellite Tracking Program http://whale.wheelock.edu.

```
readLocs, distSpeed.
```

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rqPlot	Plot of quantile regression for speed calibrations	

Description

Plot of quantile regression for assessing quality of speed calibrations

Usage

```
rqPlot(rddepth, speed, z, contours, rqFit, main="qtRegression",
    xlab="rate of depth change (m/s)", ylab="speed (m/s)",
    colramp=colorRampPalette(c("white", "darkblue")),
    col.line="red", cex.pts=1)
```

Arguments

speed	speed in m/s.
rddepth	numeric vector with rate of depth change.
Z	a list with the bivariate kernel density estimates (1st component the x points of the mesh, 2nd the y points, and 3rd the matrix of densities).
contours	list with components: pts which should be a matrix with columns named x and y , $level$ a number indicating the contour level the points in pts correspond to.
rqFit	object of class "rq" representing a quantile regression fit of rate of depth change on mean speed.
main	string; title prefix to include in ouput plot.
xlab, ylab	axis labels.
colramp	function taking an integer n as an argument and returning n colors.
col.line	color to use for the regression line.
cex.pts	a numerical value specifying the amount by which to enlarge the size of points.

Details

The dashed line in the plot represents a reference indicating a one to one relationship between speed and rate of depth change. The other line represent the quantile regression fit.

Author(s)

Sebastian P. Luque (spluque@gmail.com)

```
diveStats
```

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TDR-accessors

Coerce, Extractor, and Replacement methods for class "TDR" objects

Description

Basic methods for manipulating objects of class "TDR".

Show Methods

```
show signature (object="TDR"); print an informative summary of the data.
```

Coerce Methods

```
as.data.frame signature (x="TDR"): Coerce object to data.frame. This method returns a
data frame, with attributes 'file' and 'dtime' indicating the source file and the interval between
samples.
```

```
as.data.frame signature(x="TDRspeed"): Coerce object to data.frame. Returns an object
as for TDR objects.
```

[signature (x="TDR"): Subset a TDR object; these objects can be subsetted on a single index

```
as.TDRspeed signature (x="TDR"): Coerce object to TDRspeed class.
```

Extractor Methods

```
i. Selects given rows from object.
getDepth signature(x = "TDR"): depth slot accessor.
getCCData signature(x="TDR", y="missing"): concurrentData slot accessor.
getCCData signature(x="TDR", y="character"): access component named y in x.
getDtime signature(x = "TDR"): sampling interval accessor.
getFileName signature(x="TDR"): source file name accessor.
getTime signature(x = "TDR"): time slot accessor.
getSpeed signature(x = "TDR"): speed accessor for TDRspeed objects.
```

Replacement Methods

```
depth<- signature(x="TDR"): depth replacement.
speed<- signature(x="TDR"): speed replacement.
ccData<- signature(x="TDR"): concurrent data frame replacement.</pre>
```

Author(s)

```
Sebastian P. Luque (spluque@gmail.com)
```

```
extractDive, plotTD.
```

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Examples

```
data(divesTDR)
## Retrieve the name of the source file
getFileName(divesTDR)
## Retrieve concurrent temperature measurements
temp <- getCCData(divesTDR, "temperature")

## Coerce to a data frame
dives.df <- as.data.frame(divesTDR)
head(dives.df)

## Replace speed measurements
newspeed <- getSpeed(divesTDR) + 2
speed(divesTDR) - newspeed</pre>
```

TDRcalibrate-accessors

Methods to Show and Extract Basic Information from "TDRcalibrate" Objects

Description

Plot, print summaries and extract information from "TDRcalibrate" objects.

Usage

```
## S4 method for signature 'TDRcalibrate, missing':
getDAct(x)
## S4 method for signature 'TDRcalibrate, character':
getDAct(x, y)
## S4 method for signature 'TDRcalibrate, missing':
getDPhaseLab(x)
## S4 method for signature 'TDRcalibrate, numeric':
getDPhaseLab(x, diveNo)
## S4 method for signature 'TDRcalibrate, missing':
getGAct(x)
## S4 method for signature 'TDRcalibrate, character':
getGAct(x, y)
```

Arguments

```
x "TDRcalibrate" object.

diveNo numeric vector with dive numbers to plot.

y string; "dive.id", "dive.activity", or "postdive.id" in the case of getDAct, to extract the numeric dive ID, the factor identifying dive phases in each dive, or the numeric postdive ID, respectively. In the case of getGAct it should be
```

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one of "phase.id", "activity", "begin", or "end", to extract the numeric phase ID for each observation, a factor indicating what major activity the observation corresponds to, or the beginning and end times of each phase in the record, respectively.

Value

The extractor methods return an object of the same class as elements of the slot they extracted.

Show Methods

```
show signature (object="TDRcalibrate"): prints an informative summary of the data.
```

Extractor Methods

```
getDAct signature(x="TDRcalibrate", y="missing"): this accesses the dive.activity
slot of TDRcalibrate objects. Thus, it extracts a data frame with vectors identifying all
readings to a particular dive and postdive number, and a factor identifying all readings to a
particular activity.
```

```
getDAct signature(x="TDRcalibrate", y = "character"): as the method for miss-
ing y, but selects a particular vector to extract. See TDRcalibrate for possible strings.
```

```
getDPhaseLab signature(x="TDRcalibrate", diveNo = "missing"): extracts a
factor identifying all readings to a particular dive phase. This accesses the dive.phases slot of
TDRcalibrate objects, which is a factor.
```

```
getDPhaseLab signature(x="TDRcalibrate", diveNo = "numeric"): as the method
for missing y, but selects data from a particular dive number to extract.
```

```
getGAct signature(x="TDRcalibrate", y="missing"): this accesses the gross.activity
slot of TDRcalibrate objects, which is a named list. It extracts elements that divide the
data into major wet and dry activities.
```

```
getGAct signature(x="TDRcalibrate", y="character"): as the method for missing y, but extracts particular elements.
```

```
getTDR signature(x="TDRcalibrate"): this accesses the tdr slot of TDRcalibrate
  objects, which is a TDR object.
```

getSpeedCoef signature(x="TDRcalibrate"): this accesses the speed.calib.coefs
slot of TDRcalibrate objects; the speed calibration coefficients.

Author(s)

Sebastian P. Luque (spluque@gmail.com)

Examples

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```
getGAct(divesTDRcalibrate, "begin")
## Factor of dive IDs
dids <- getDAct(divesTDRcalibrate, "dive.id")
table(dids[dids > 0])  # samples per dive
## Factor of dive phases for given dive
getDPhaseLab(divesTDRcalibrate, 19)
```

TDRcalibrate-class Class "TDRcalibrate" for dive analysis

Description

This class holds information produced at various stages of dive analysis. Methods are provided for extracting data from each slot.

Details

This is perhaps the most important class in diveMove, as it holds all the information necessary for calculating requested summaries for a TDR.

Objects from the Class

Objects can be created by calls of the form new ("TDRcalibrate", ...). The objects of this class contain information necessary to divide the record into sections (e.g. dry/water), dive/surface, and different sections within dives. They also contain the parameters used to calibrate speed and criteria to divide the record into phases.

Slots

```
tdr: Object of class "TDR".
```

This slot contains the time, zero-offset corrected depth, and possibly a data frame. If the object is also of class "TDRspeed", then the data frame might contain calibrated or uncalibrated speed. See readTDR and the accessor function getTDR for this slot.

```
gross.activity: Object of class "list".
```

This slot holds a list of the form returned by .detPhase, composed of 4 elements. It contains a vector (named phase.id) numbering each major activity phase found in the record, a factor (named activity) labelling each row as being dry, wet, or trivial wet activity. These two elements are as long as there are rows in tdr. This list also contains two more vectors, named begin and end: one with the beginning time of each phase, and another with the ending time; both represented as POSINCt objects. See .detPhase.

```
dive.activity: Object of class "data.frame".
```

This slot contains a data.frame of the form returned by _detDive, with as many rows as those in tdr, consisting of three vectors named: dive_id, which is an integer vector, sequentially numbering each dive (rows that are not part of a dive are labelled 0), dive.activity is

TDR-class 27

a factor which completes that in activity above, further identifying rows in the record belonging to a dive. The third vector in dive.activity is an integer vector sequentially numbering each postdive interval (all rows that belong to a dive are labelled 0). See .detDive, and getDAct to access all or any one of these vectors.

dive.phases: Object of class "factor". must be the same as value returned by .labDivePhase.
This slot is a factor that labels each row in the record as belonging to a particular phase of a dive. It has the same form as objects returned by .labDivePhase.

dry.thr: Object of class "numeric" the temporal criteria used for detecting dry periods that should be considered as wet.

wet.thr: Object of class "numeric" the temporal criteria used for detecting periods wet that should not be considered as foraging time.

dive.thr: Object of class "numeric" the criteria used for defining a dive.

speed.calib.coefs: Object of class "numeric" the intercept and slope derived from the speed calibration procedure. Defaults to c(0, 1) meaning uncalibrated speeds.

Author(s)

Sebastian P. Luque (spluque@gmail.com)

See Also

TDR for links to other classes in the package. TDRcalibrate-methods for the various methods available.

TDR-class

Classes "TDR" and "TDRspeed" for representing TDR information

Description

These classes store information gathered by time-depth recorders.

Details

Since the data to store in objects of these clases usually come from a file, the easiest way to construct such objects is with the function readTDR to retrieve all the necessary information. The methods listed above can thus be used to access all slots.

Objects from the Class

Objects can be created by calls of the form new("TDR", ...) and new("TDRspeed", ...).

TDR objects contain concurrent time and depth readings, as well as a string indicating the file the data originates from, and a number indicating the sampling interval for these data. TDRspeed extends TDR objects containing additional concurrent speed readings.

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Slots

In class TDR.

file: Object of class "character", string indicating the file where the data comes from.

dtime: Object of class "numeric", sampling interval in seconds.

time: Object of class "POSIXct", time stamp for every reading.

depth: Object of class "numeric", depth (m) readings.

concurrentData: Object of class "data.frame", optional data collected concurrently.

Class TDRspeed must also satisfy the condition that a component of the concurrentData slot is named speed or velocity, containing the measured speed, a vector of class "numeric" containing speed measurements in (m/s) readings.

Author(s)

Sebastian P. Luque (spluque@gmail.com)

See Also

```
readTDR, TDRcalibrate.
```

timeBudget-methods Describe the Time Budget of Major Activities from "TDRcalibrate" object.

Description

Summarize the major activities recognized into a time budget.

Usage

```
## $4 method for signature 'TDRcalibrate, logical':
timeBudget(obj, ignoreZ)
```

Arguments

```
obj "TDRcalibrate" object.
ignoreZ logical indicating whether to ignore trivial aquatic periods.
```

Details

Ignored trivial aquatic periods are collapsed into the enclosing dry period.

Value

A data frame.

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Author(s)

Sebastian P. Luque (spluque@gmail.com)

Examples

```
data(divesTDRcalibrate)
timeBudget(divesTDRcalibrate, TRUE)
```

Z.O.C

Interactive zero-offset correction of TDR data

Description

Correct zero-offset in TDR records, with the aid of a graphical user interface (GUI), allowing for dynamic selection of offset and multiple time windows to perform the adjustment.

Usage

```
zoc(time, depth, offset)
plotTD(time, depth, concurVars=NULL, xlim=NULL, depth.lim=NULL,
    xlab="time (dd-mmm hh:mm)", ylab.depth="depth (m)",
    concurVarTitles=deparse(substitute(concurVars)),
    xlab.format="%d-%b %H:%M", sunrise.time="06:00:00",
    sunset.time="18:00:00", night.col="gray60",
    phaseCol=NULL, interact=TRUE, key=TRUE)
```

Arguments

time POSIXct object with date and time. numeric vector with depth in m. depth offset known amount of meters to subtract for zero-offset correcting depth throughout the entire TDR record. matrix with additional variables in each column to plot concurrently with depth. concurVars xlim vector of length 2, with lower and upper limits of time to be plotted. numeric vector of length 2, with the lower and upper limits of depth to be plotted. depth.lim xlab, ylab.depth strings to label the corresponding y-axes. concurVarTitles character vector of titles to label each new variable given in concurVars.

xlab.format format string for formatting the x axis; see strptime.

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```
sunrise.time, sunset.time
```

character string with time of sunrise and sunset, respectively, in 24 hr format.

This is used for shading night time.

night.col color for shading night time.

phaseCol factor dividing rows into sections.

interact Logical; whether to provide interactive teltk controls and access to the associated

ZOC functionality.

key logical indicating whether to dray a key.

Details

These functions are used primarily to correct, visually, drifts in the pressure transducer of TDR records. zoc calls plotDive, which plots depth and, optionally, speed vs. time with the possibility zooming in and out on time, changing maximum depths displayed, and panning through time. The option to zero-offset correct sections of the record gathers x and y coordinates for two points, obtained by clicking on the plot region. The first point clicked indicates the offset and beginning time of section to correct, and the second one indicates the ending time of the section to correct. Multiple sections of the record can be corrected in this manner, by panning through the time and repeating the procedure. In case there's overlap between zero offset corrected windows, the last one prevails.

Once the whole record has been zero-offset corrected, remaining points with depth values lower than zero, are turned into zeroes, as these are assumed to be values at the surface.

Value

zoc returns a numeric vector, as long as depth of zero-offset corrected depths.

plotDive returns a list with as many components as sections of the record that were zero-offset corrected, each consisting of two further lists with the same components as those returned by locator.

Author(s)

Sebastian P. Luque (spluque@gmail.com), with many ideas from CRAN package sfsmisc.

See Also

```
calibrateDepth
```

Examples

```
data(divesTDR)
plotTDR(divesTDR, interact=FALSE)

## Use interact=RUE (default) to set the offset interactively
depth.zoc <- zoc(getTime(divesTDR), getDepth(divesTDR), offset=3)
plotTD(getTime(divesTDR), depth.zoc, interact=FALSE)</pre>
```

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