A User's Guide to the evd Package (Version 2.0)

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1 Introduction

1.1 What is the evd package?

The evd (extreme value distributions) package is an add-on package for the R (Ihaka and Gentleman, 1996) statistical computing system. The package contains the following (user-level) functions.

Univariate Distributions. Density, distribution, simulation and quantile (inverse distribution) functions for univariate distributions associated with extreme value theory.

```
dgev dgumbel drweibull dfrechet dextreme dorder pgev pgumbel prweibull pfrechet pextreme porder rgev rgumbel rrweibull rfrechet rextreme rorder qgev qgumbel qrweibull qfrechet qextreme
```

Bivariate and Multivariate Extreme Value Distributions. Density, distribution and simulation functions for bivariate and multivariate parametric extreme value models. Eight bivariate models and two multivariate models are implemented.

```
dbvevd dmvevd pbvevd pmvevd rbvevd rmvevd
```

Dependence Functions for Bivariate and Trivariate Extreme Value Distributions. Calculate and plot dependence functions for bivariate and trivariate extreme value distributions; either non-parametric estimates, or parametric models, at specified parameter values.

```
abvnonpar abvpar atvnonpar atvpar
```

Stochastic Processes. Generate stochastic processes associated with extreme value theory; max autoregressive moving average processes and first order Markov chains with bivariate extreme value dependence structures.

```
evmc marma mar mma
```

Fitting Models. Obtain maximum likelihood estimates for models used in extreme value theory, including eight parametric bivariate extreme value models.

```
fbvevd fgev forder fextreme
```

Model Diagnostics. Model diagnostics for fitted models; diagnostic plots and analysis of deviance. plot.gev plot.bvevd anova.evd

Profile deviances. Obtain profile traces, plot profile deviances and obtain profile confidence intervals from fitted models.

```
profile.evd plot.profile.evd profile2d.evd plot.profile2d.evd
```

The following datasets are also included in the package.

```
failure fox lisbon ocmulgee oldage oxford portpirie sask sealevel uccle venice
```

1.2 Obtaining the package/guide

The evd package can be downloaded from CRAN (The Comprehensive R Archive Network) at http://cran.r-project.org/. This guide (in pdf) will be in the directory evd/doc/underneath wherever the package is installed. It can also be downloaded directly from http://www.maths.lancs.ac.uk/~stephena/ (in postscript or pdf).

1.3 Contents

This guide contains examples on the use of the evd package. The examples do not include any theoretical justification. See Coles (2001) for an introduction to the statistics of extreme values. See Kotz and Nadarajah (2000) for a theoretical treatment of univariate and multivariate extreme value distributions.

Section 2 covers the standard (non-fitting) functions for univariate distributions. Sections 3 and 4 do the same for bivariate and multivariate extreme value models. Dependence functions of extreme value distributions are discussed in Section 5. Stochastic processes are discussed in Section 6. Maximum likelihood fitting of univariate and bivariate models is discussed in Sections 7 and 8 respectively. Two extended examples, one univariate and one bivariate, using the data sets oxford and sealevel (both included in the package), are given in Sections 9 and 10.

This guide should not be viewed as an alternative to the documentation files included within the package. These remain the definitive source of information. A reference manual containing all the documentation files can be downloaded from http://www.maths.lancs.ac.uk/~stephena/ or from CRAN.

All of the examples presented in this guide are called with options(digits = 4), and with the option show.signif.stars set to FALSE.

1.4 Citing the package/guide

Volume 2/2 of R-News (the newsletter of the R-project) contains an article that describes (an earlier version of) the evd package. To cite the package in publications please cite the R-News article. The article and the corresponding citation can be downloaded from http://www.cran.r-project.org/doc/Rnews/.

To cite this guide in publications please use the following bibliographic database entry.

```
@manual{key,
   title = {A User's Guide to the evd Package (Version 2.0)},
   author = {Stephenson, A. G.},
   year = {2003},
   month = {January},
   url = {http://www.maths.lancs.ac.uk/\textasciitilde stephena/}
}
```

1.5 Caveat

I have checked these functions as best I can but, as ever, they may contain bugs. If you find a bug or suspected bug in the code or the documentation please report it to me at a.stephenson@lancaster.ac.uk. If you do find a bug and are the first person to report it, I guarantee to buy you the drink of your choice. If you ever manage to find me.

1.6 Legalese

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1.7 Acknowledgments

Thanks to Paulo Ribeiro Jr. for much needed advice.

2 Univariate Distributions

The Gumbel, Fréchet and (reversed) Weibull distribution functions are respectively given by

$$G(z) = \exp\left\{-\exp\left[-\left(\frac{z-a}{b}\right)\right]\right\}, \quad -\infty < z < \infty$$
 (1)

$$G(z) = \begin{cases} 0, & z \le a, \\ \exp\left\{-\left(\frac{z-a}{b}\right)^{-\alpha}\right\}, & z > a, \end{cases}$$
 (2)

$$G(z) = \begin{cases} \exp\left\{-\left[-\left(\frac{z-a}{b}\right)\right]^{\alpha}\right\}, & z < a, \\ 1, & z \ge a, \end{cases}$$
(3)

where a is a location parameter, b > 0 is a scale parameter and $\alpha > 0$ is a shape parameter. The distribution (3) is often referred to as the Weibull distribution. To avoid confusion I will call this the reversed Weibull, since it is related by a change of sign to the three parameter Weibull distribution used in survival analysis.

The GEV (Generalized Extreme Value) distribution function is given by

$$G(z) = \exp\left\{-\left[1 + \xi (z - \mu) / \sigma\right]_{+}^{-1/\xi}\right\},$$
 (4)

where (μ, σ, ξ) are the location, scale and shape parameters respectively, $\sigma > 0$ and $h_+ = \max(h, 0)$. When $\xi > 0$ the GEV distribution has a finite lower end point, given by $\mu - \sigma/\xi$. When $\xi < 0$ the GEV distribution has a finite upper end point, also given by $\mu - \sigma/\xi$. The parametric form of the GEV encompasses that of the Gumbel, Frèchet and reversed Weibull distributions. The Gumbel distribution is obtained in the limit as $\xi \to 0$. The Fréchet and Weibull distributions are obtained when $\xi > 0$ and $\xi < 0$ respectively. To recover the parameterization of the Fréchet distribution (2) set $\xi = 1/\alpha > 0$, $\sigma = b/\alpha > 0$ and $\mu = a + b$. To recover the parameterization of the reversed Weibull distribution (3) set $\xi = -1/\alpha < 0$, $\sigma = b/\alpha > 0$ and $\mu = a - b$.

It is standard practice within R to concatenate the letters r, p, q and d with an abbreviated distribution name to yield the names of the corresponding simulation, distribution, quantile (inverse distribution) and density functions respectively. The evd package follows this convention. Each of the four distributions defined above has an associated set of functions, as given in Section 1.1. Some examples are given below. They should be familiar to those who have had previous experience with R.

```
> rgev(6, loc = c(20,1), scale = .5, shape = 1)
[1] 23.7290  1.2492 19.6680  0.8662 19.7939  2.6512
> qrweibull(seq(0.1, 0.4, 0.1), 2, 0.5, 1, lower.tail = FALSE)
> qrweibull(seq(0.9, 0.6, -0.1), loc = 2, scale = 0.5, shape = 1)
# Both give
[1] 1.947 1.888 1.822 1.745

> pfrechet(2:6, 2, 0.5, 1)
[1] 0.0000 0.6065 0.7788 0.8465 0.8825
> pfrechet(2:6, 2, 0.5, 1, low = FALSE)
[1] 1.0000 0.3935 0.2212 0.1535 0.1175

> drweibull(-1:3, 2, 0.5, log = TRUE)
[1] -5.307 -3.307 -1.307 -Inf -Inf
> dgumbel(-1:3, 0, 1)
[1] 0.17937 0.36788 0.25465 0.11820 0.04737
```

Let F be an arbitrary distribution function, and let X_1, \ldots, X_m be a random sample from F. Define $U_m = \max\{X_1, \ldots, X_m\}$ and $L_m = \min\{X_1, \ldots, X_m\}$. The distributions of U_m and L_m are given by

$$\Pr(U_m \le x) = [F(x)]^m \tag{5}$$

$$\Pr(L_m \le x) = 1 - [1 - F(x)]^m. \tag{6}$$

Simulation, distribution, quantile and density functions for the distributions of U_m and L_m , given an integer m and an arbitrary distribution function F, are provided by rextreme, pextreme, qextreme and dextreme respectively. The integer m should be given to the argument mlen. The distribution F is most easily specified by passing an abbreviated distribution name to the argument distribution of U_m is required the argument largest should be set to TRUE (the default). If the distribution of L_m is required largest should be set to FALSE. Some examples should make this clear.

```
> rextreme(1, distn = "norm", sd = 2, mlen = 20, largest = FALSE)
> min(rnorm(20, mean = 0, sd = 2))
# Both simulate from the same distribution
[1] -2.612
> rextreme(4, distn = "exp", rate = 1, mlen = 5)
> rextreme(4, distn = "exp", mlen = 5)
# Both simulate from the same distribution
[1] 2.2001 0.8584 4.5595 3.9397
> pextreme(c(.4, .5), distn = "norm", mean = 0.5, sd = c(1, 2), mlen = 4)
[1] 0.04484 0.06250
> dextreme(c(1, 4), distn = "gamma", shape = 1, scale = 0.3, mlen = 100)
[1] 0.3261328 0.0005398
```

Let $X_{(1)} \geq X_{(2)} \geq \cdots \geq X_{(m)}$ be the order statistics of the random sample X_1, \ldots, X_m . The distribution of the jth largest order statistic, for $j = 1, \ldots, m$, is

$$\Pr(X_{(j)} \le x) = \sum_{k=0}^{j-1} {m \choose k} [F(x)]^{m-k} [1 - F(x)]^k.$$
 (7)

The distribution of the jth smallest order statistic is obtained by setting j=m+1-j. Simulation, distribution and density functions for the distribution of $X_{(j)}$, for given integers m and $j \in \{1,\ldots,m\}$, and for an arbitrary distribution function F, are provided by rorder, porder and dorder respectively. The integer m should again be given to the argument mlen. If the argument largest is TRUE (the default) the distribution of the jth largest order statistic $X_{(j)}$ is used. If largest is FALSE the distribution of the jth smallest order statistic $X_{(m+j-1)}$ is used. Some examples are given below.

```
> rorder(1, distn = "norm", mlen = 20, j = 2)
[1] 2.284
> porder(c(1, 2), distn = "gamma", shape = c(.5, .7), mlen = 10, j = 2)
[1] 0.5177 0.8259
> dorder(c(1, 2), distn = "gamma", shape = c(.5, .7), mlen = 10, j = 2)
[1] 0.7473 0.3081
```

3 Bivariate Extreme Value Distributions

The evd package contains functions associated with eight parametric bivariate extreme value distributions. The univariate marginal distributions in each case are GEV, with marginal parameters (μ_1, σ_1, ξ_1) and (μ_2, σ_2, ξ_2) .

There are three symmetric models, with distribution functions

$$G(z_1, z_2) = \exp\left\{-(y_1^{1/\alpha} + y_2^{1/\alpha})^{\alpha}\right\}, \quad 0 < \alpha \le 1,$$
 (8)

$$G(z_1, z_2) = \exp\left\{-y_1 - y_2 + (y_1^{-r} + y_2^{-r})^{-1/r}\right\}, \quad r > 0,$$
(9)

$$G(z_1, z_2) = \exp\left(-y_1 \Phi\{\lambda^{-1} + \frac{1}{2}\lambda[\log(y_1/y_2)]\} - y_2 \Phi\{\lambda^{-1} + \frac{1}{2}\lambda[\log(y_2/y_1)]\}\right), \quad \lambda > 0,$$

known as the logistic (Gumbel, 1960), negative logistic (Galambos, 1975) and Hüsler-Reiss (Hüsler and Reiss, 1989) models respectively, where

$$y_j = y_j(z_j) = \{1 + \xi_j(z_j - \mu_j)/\sigma_j\}_+^{-1/\xi_j}$$
(10)

for j=1,2. Independence* is obtained when $\alpha=1,\ r\downarrow 0$ or $\lambda\downarrow 0$. Complete dependence[†] is obtained when $\alpha\downarrow 0,\ r\to\infty$ or $\lambda\to\infty$.

The distributions functions (8) and (9) have asymmetric extensions, given by

$$G(z_1, z_2) = \exp\left\{-(1 - \theta_1)y_1 - (1 - \theta_2)y_2 - [(\theta_1 y_1)^{1/\alpha} + (\theta_2 y_2)^{1/\alpha}]^{\alpha}\right\}, \quad 0 < \alpha \le 1,$$

$$G(z_1, z_2) = \exp\left\{-y_1 - y_2 + [(\theta_1 y_1)^{-r} + (\theta_2 y_2)^{-r}]^{-1/r}\right\}, \quad r > 0,$$
(11)

known as the asymmetric logistic (Tawn, 1988) and asymmetric negative logistic (Joe, 1990) models respectively, where the asymmetry parameters $0 \le \theta_1, \theta_2 \le 1$. For the asymmetric logistic model independence is obtained when either $\alpha = 1$, $\theta_1 = 0$ or $\theta_2 = 0$. Different limits occur when θ_1 and θ_2 are fixed and $\alpha \downarrow 0$. For the asymmetric negative logistic model independence is obtained when either $r \downarrow 0$, $\theta_1 \downarrow 0$ or $\theta_2 \downarrow 0$. Different limits occur when θ_1 and θ_2 are fixed and $r \to \infty$.

^{*}Independence occurs when $G(z_1, z_2) = \exp\{-(y_1 + y_2)\}.$

[†]Complete dependence occurs when $G(z_1, z_2) = \exp\{-\max(y_1, y_2)\}.$

Any bivariate extreme value distribution function can be expressed as (de Haan, 1984)

$$G(z_1, z_2) = \exp\left\{-\int_0^1 \max\{y_1 f_1(x), y_2 f_2(x)\} dx\right\}$$

where (y_1, y_2) are again defined by the transformations (10), and where f_1 and f_2 are density functions with support [0,1].

In particular, if we take the beta densities $f_1(x) = (1 - \alpha)x^{-\alpha}$ and $f_2(x) = (1 - \beta)(1 - x)^{-\beta}$ we obtain

$$G(z_1, z_2) = \exp\left\{-\int_0^1 \max\{y_1(1-\alpha)x^{-\alpha}, y_2(1-\beta)(1-x)^{-\beta}\} dx\right\}, \quad \alpha, \beta < 1.$$

If we further constrain the parameters to be non-negative we obtain the bivariate bilogistic model proposed by Smith (1990), which can also be expressed as

$$G(z_1, z_2) = \exp\left\{-y_1 \gamma^{1-\alpha} - y_2 (1-\gamma)^{1-\beta}\right\}, \quad 0 < \alpha, \beta < 1, \tag{12}$$

where $\gamma = \gamma(y_1, y_2; \alpha, \beta)$ solves $(1 - \alpha)y_1(1 - \gamma)^{\beta} = (1 - \beta)y_2\gamma^{\alpha}$. The logistic model is obtained when $\alpha = \beta$. Independence is obtained as $\alpha = \beta \to 1$, and when one of α, β is fixed and the other approaches one. Different limits occur when one of α, β is fixed and the other approaches zero.

Alternatively, if we constrain both parameters to be non-positive and set $\alpha_0 = -\alpha > 0$ and $\beta_0 = -\beta > 0$ we obtain the negative bilogistic model (Coles and Tawn, 1994), which has the representation

$$G(z_1, z_2) = \exp\left\{-y_1 - y_2 + y_1 \gamma^{1+\alpha_0} + y_2 (1-\gamma)^{1+\beta_0}\right\}, \quad \alpha_0, \beta_0 > 0,$$

where $\gamma = \gamma(y_1, y_2; -\alpha_0, -\beta_0)$. The negative logistic model is obtained when $\alpha_0 = \beta_0$ (with $r = 1/\alpha_0 = 1/\beta_0$). Independence is obtained as $\alpha_0 = \beta_0 \to \infty$, and when one of α_0, β_0 is fixed and the other tends to ∞ . Different limits occur when one of α_0, β_0 is fixed and the other approaches zero.

The Coles-Tawn model[‡] (Coles and Tawn, 1991) is the final model that is considered in the evd package. The distribution function is given by

$$G(z_1, z_2) = \exp\{-y_1[1 - \text{Be}(u; \alpha + 1, \beta)] - y_2 \text{Be}(u; \alpha, \beta + 1)\}, \quad \alpha, \beta > 0,$$

where $u = \alpha y_2/(\alpha y_2 + \beta y_1)$ and Be is the incomplete beta function, given by

$$Be(u; \alpha, \beta) = \frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha)\Gamma(\beta)} \int_0^u x^{\alpha - 1} (1 - x)^{\beta - 1} dx.$$

Complete dependence is obtained in the limit as $\alpha = \beta \to \infty$. Independence is obtained as $\alpha = \beta \to 0$ and when one of α, β is fixed and the other approaches zero. Different limits occur when one of α, β is fixed and the other tends to ∞ .

Density, distribution and simulation functions for each of the eight models are provided by dbvevd, pbvevd and rbvevd respectively. The argument model denotes the specified model, which must be either "log" (the default), "alog", "hr", "neglog", "aneglog", "bilog", "negbilog" or "ct" (or any unique partial match). The first argument in pbvevd and dbvevd should be a vector of length two or a matrix with two columns, so that each row specifies a value for (z_1, z_2) .

[‡]Coles and Tawn (1991) call this the Dirichelet model.

The parameters of the specified model can be passed using one or more of the arguments dep, asy, alpha and beta. The marginal parameters (μ_1, σ_1, ξ_1) and (μ_2, σ_2, ξ_2) can be passed using the arguments mar1 and mar2 respectively. Gumbel marginal distributions are used by default. The arguments mar1 and mar2 can also be matrices with three columns, in which case each column represents a vector of values to be passed to the corresponding marginal parameter. Some examples are given below.

```
> rbvevd(3, dep = .8, asy = c(.4, 1), model = "alog")
                 [,2]
         [,1]
[1,]
     0.07876 -0.7971
[2,]
     0.01091 -0.8113
[3,] -0.10491 -0.8831
> rbvevd(3, alpha = .5, beta = 1.2, model = "negb", mar1 = rep(1, 3))
[1,] 0.7417 1.085
[2,] 0.8391 1.825
[3,] 2.0142 2.280
> pbvevd(c(1, 1.2), dep = .4, asy = c(.4, .6), model = "an", mar1 = rep(1, 3))
[1] 0.173
> tmp.quant <- matrix(c(1,1.2,1,2), ncol = 2, byrow = TRUE)
> tmp.mar <- matrix(c(1,1,1,1.2,1.2,1.2), ncol = 3, byrow = TRUE)
> pbvevd(tmp.quant, dep = .4, asy = c(.4, .6), model = "an", mar1 = tmp.mar)
[1] 0.173 0.175
> dbvevd(c(1, 1.2), alpha = .2, beta = .6, model = "ct", mar1 = rep(1, 3))
[1] 0.1213
> dbvevd(tmp.quant, alpha = 0.2, beta = 0.6, model = "ct", mar1 = tmp.mar)
[1] 0.1213 0.0586
```

4 Multivariate Extreme Value Distributions

Let $z = (z_1, \ldots, z_d)$. The d-dimensional logistic model (Gumbel, 1960) has distribution function

$$G(z) = \exp\left\{-\left(\sum_{j=1}^{d} y_j^{-1/\alpha}\right)^{\alpha}\right\}$$
(13)

where $\alpha \in (0,1]$ and (y_1,\ldots,y_d) is defined by the transformations (10).

This distribution can be extended to an asymmetric form. Let B be the set of all non-empty subsets of $\{1, \ldots, d\}$, let $B_1 = \{b \in B : |b| = 1\}$, where |b| denotes the number of elements in the set b, and let $B_{(i)} = \{b \in B : i \in b\}$. The multivariate asymmetric logistic model (Tawn, 1990) is given by

$$G(z) = \exp\left\{-\sum\nolimits_{b \in B} \left[\sum\nolimits_{i \in b} (\theta_{i,b} y_i)^{1/\alpha_b}\right]^{\alpha_b}\right\}$$

where the dependence parameters $\alpha_b \in (0,1]$ for all $b \in B \setminus B_1$, and the asymmetry parameters $\theta_{i,b} \in [0,1]$ for all $b \in B$ and $i \in b$. The constraints $\sum_{b \in B_{(i)}} \theta_{i,b} = 1$ for $i = 1, \ldots, d$ ensure that the marginal distributions are GEV. There exists further constraints which arise from the possible redundancy of asymmetry parameters in the expansion of the distributional form. Specifically, if $\alpha_b = 1$ for some $b \in B \setminus B_1$ then $\theta_{i,b} = 0$ for all $i \in b$. Let $b_{-i_0} = \{i \in b : i \neq i_0\}$. If, for some $b \in B \setminus B_1$, $\theta_{i,b} = 0$ for all $i \in b_{-i_0}$, then $\theta_{i_0,b} = 0$. The model contains $2^d - d - 1$ dependence

parameters and $d2^{d-1}$ asymmetry parameters (excluding the constraints). The logistic model (13) can be obtained by setting $\theta_{i,12...d} = 1$ for all i = 1, ..., d (which implies that $\theta_{i,b} = 0$ whenever |b| < d) and $\alpha_{12...d} = \alpha$. The density functions for the symmetric and asymmetric logistic models are given in Appendix A.

Density, distribution and simulation functions for these models are provided by dmvevd, pmvevd and rmvevd respectively. The argument model denotes the specified model, which must be either "log" (the default) or "alog" (or any unique partial match). The argument d denotes the dimension of the model. By default, d = 2. The first argument in pbvevd and dbvevd should be a vector of length d or a matrix with d columns, so that each row specifies a value for (z_1, \ldots, z_d) . The marginal parameters (μ_i, σ_i, ξ_i) , for $i = 1, \ldots, d$, can be passed using the argument mar. Gumbel marginal distributions are used by default. For the symmetric logistic model, the argument dep represents the parameter α . Some examples are given below.

```
> rmvevd(3, dep = .6, model = "log", d = 5)
                [,2]
        [,1]
                        [,3]
                                 [,4] [,5]
[1,]
     0.1335
             0.2878 1.07886 1.55515 1.310
     1.7100 0.9453 1.02070 -0.02553 1.527
[3,] -0.3376 -0.5814 0.07426 0.10906 2.827
> tmp.mar <- matrix(c(1,1,1,1,1,1,5,1,1,2), ncol = 3, byrow = TRUE)
> rmvevd(3, dep = .6, d = 5, mar = tmp.mar)
      [,1]
             [,2]
                    [,3]
                           [,4]
[1,] 2.803 4.6415 1.8531 3.5569 8.854
[2,] 0.751 0.9704 2.3328 2.6537 1.233
[3,] 4.641 1.4321 0.5825 0.6041 2.021
> tmp.quant <- matrix(rep(c(1,1.5,2), 5), ncol = 5)
> pmvevd(tmp.quant, dep = .6, d = 5, mar = tmp.mar)
[1] 0.07233 0.16387 0.21949
> dmvevd(tmp.quant, dep = .6, d = 5, mar = tmp.mar, log = TRUE)
[1] -3.564 -6.610 -9.460
```

For the asymmetric logistic model dep should be a vector of length $2^d - d - 1$ containing the dependence parameters. For example, when d = 4

$$\mathtt{dep} = \mathtt{c}(\alpha_{12}, \alpha_{13}, \alpha_{14}, \alpha_{23}, \alpha_{24}, \alpha_{34}, \alpha_{123}, \alpha_{124}, \alpha_{134}, \alpha_{234}, \alpha_{1234}).$$

The asymmetry parameters should be passed to asy in a list with $2^{d}-1$ elements, where each element is a vector* corresponding to a set $b \in B$, containing $\{\theta_{i,b} : i \in b\}$. For example, when d = 4

```
\begin{split} \mathtt{asy} &= \mathtt{list}(\theta_{1,1}, \theta_{2,2}, \theta_{3,3}, \theta_{4,4}, \mathtt{c}(\theta_{1,12}, \theta_{2,12}), \mathtt{c}(\theta_{1,13}, \theta_{3,13}), \mathtt{c}(\theta_{1,14}, \theta_{4,14}), \mathtt{c}(\theta_{2,23}, \theta_{3,23}), \\ \mathtt{c}(\theta_{2,24}, \theta_{4,24}), \mathtt{c}(\theta_{3,34}, \theta_{4,34}), \mathtt{c}(\theta_{1,123}, \theta_{2,123}, \theta_{3,123}), \mathtt{c}(\theta_{1,124}, \theta_{2,124}, \theta_{4,124}), \\ \mathtt{c}(\theta_{1,134}, \theta_{3,134}, \theta_{4,134}), \mathtt{c}(\theta_{2,234}, \theta_{3,234}, \theta_{4,234}), \mathtt{c}(\theta_{1,1234}, \theta_{2,1234}, \theta_{3,1234}, \theta_{4,1234})). \end{split}
```

All the constraints, including $\sum_{b \in B_{(i)}} \theta_{i,b} = 1$ for $i = 1, \dots, d$, must be satisfied or an error will occur. Some examples are given below.

The dependence parameters used in the following trivariate asymmetric logistic model are $(\alpha_{12},\alpha_{13},\alpha_{23},\alpha_{123})=(.6,.5,.8,.3)$. The asymmetry parameters are $\theta_{1,1}=.4,\ \theta_{2,2}=0,\ \theta_{3,3}=.6,\ (\theta_{1,12},\theta_{2,12})=(.3,.2),\ (\theta_{1,13},\theta_{3,13})=(.1,.1),\ (\theta_{2,23},\theta_{3,23})=(.4,.1)$ and finally $(\theta_{1,123},\theta_{2,123},\theta_{3,123})=(.2,.4,.2)$.

^{*}Including vectors of length one.

The dependence parameters used in the following four dimensional asymmetric logistic model are $\alpha_b = 1$ for $|b| = 2^{\dagger}$ and $(\alpha_{123}, \alpha_{124}, \alpha_{134}, \alpha_{234}, \alpha_{1234}) = (.7, .3, .8, .7, .5)$. The asymmetry parameters are $\theta_{i,b} = 0$ for all $i \in b$ when $|b| \leq 2$, $(\theta_{1,123}, \theta_{2,123}, \theta_{3,123}) = (.2, .1, .2)$, $(\theta_{1,124}, \theta_{2,124}, \theta_{4,124}) = (.1, .1, .2)$, $(\theta_{1,134}, \theta_{3,134}, \theta_{4,134}) = (.3, .4, .1)$, $(\theta_{2,234}, \theta_{3,234}, \theta_{4,234}) = (.2, .2, .2)$ and finally $(\theta_{1,1234}, \theta_{2,1234}, \theta_{3,1234}, \theta_{4,1234}) = (.4, .6, .2, .5)$.

5 Dependence Functions

Let $z = (z_1, \ldots, z_d)$ and $\omega = (\omega_1, \ldots, \omega_d)$. Any d-dimensional extreme value distribution function can be represented in the form

$$G(z) = \exp\left\{-\left\{\sum_{j=1}^{d} y_j\right\} A\left(\frac{y_1}{\sum_{j=1}^{d} y_j}, \dots, \frac{y_d}{\sum_{j=1}^{d} y_j}\right)\right\},\tag{14}$$

where (y_1,\ldots,y_d) is defined by the transformations (10). It follows that $A(\omega)=-\log\{G(y_1^{-1}(\omega_1),\ldots,y_d^{-1}(\omega_d))\}$, defined on the simplex $S_d=\{\omega\in\mathbb{R}_+^d:\sum_{j=1}^d\omega_j=1\}$. $A(\cdot)$ is known as the dependence function. The dependence function characterizes the dependence structure of G. It can be shown that $A(\omega)=1$ when ω is one of the d vertices of S_d (i.e. when one component of ω is equal to one, and all remaining components are equal to zero), and that A is a convex function with $\max(\omega_1,\ldots,\omega_d)\leq A(\omega)\leq 1$ for all $\omega\in S_d$. The lower and upper bounds are obtained at complete dependence and mutual independence respectively. In particular, $A(1/d,\ldots,1/d)$ is equal to 1/d at complete dependence, and 1 at mutual independence.

The dependence function of a bivariate extreme value distribution is a special case (because the sets S_2 and [0,1] are equivalent), and is typically defined as follows. Any bivariate extreme value distribution function can be represented in the form

$$G(z_1, z_2) = \exp\left\{-(y_1 + y_2)A\left(\frac{y_1}{y_1 + y_2}\right)\right\},$$
 (15)

[†]The values taken by α_b when |b|=2 are irrelevant here because $\theta_{i,b}=0$ for all $i\in b$ when |b|=2.

so that $A(\omega) = -\log\{G(y_1^{-1}(\omega), y_2^{-1}(1-\omega))\}$, defined on $0 \le \omega \le 1$.* It follows that A(0) = A(1) = 1, and that $A(\cdot)$ is a convex function with $\max(\omega, 1-\omega) \le A(\omega) \le 1$ for all $0 \le \omega \le 1$. At independence A(1/2) = 1. At complete dependence A(1/2) = 0.5.

Dependence functions for parametric bivariate and trivariate extreme value models can be calculated and plotted, at given parameter values, using the functions abvpar and atvpar. Some examples are given at the end of this section. Non-parametric estimators of dependence functions can also be calculated and plotted, using the functions abvnonpar and atvnonpar. Non-parametric estimators of dependence functions of bivariate extreme value models are constructed as follows.

Suppose (z_{i1}, z_{i2}) for i = 1, ..., n are n bivariate observations that are passed to abvnonpar using the argument data. The marginal parameters are estimated (under the assumption of independence) and the data is transformed using

$$y_{i1} = \{1 + \hat{\xi}_1(z_{i1} - \hat{\mu}_1)/\hat{\sigma}_1\}_{+}^{-1/\hat{\xi}_1}$$

$$y_{i2} = \{1 + \hat{\xi}_2(z_{i2} - \hat{\mu}_2)/\hat{\sigma}_2\}_{+}^{-1/\hat{\xi}_2}$$
(16)

for i = 1, ..., n, where $(\hat{\mu}_1, \hat{\sigma}_1, \hat{\xi}_1)$ and $(\hat{\mu}_2, \hat{\sigma}_2, \hat{\xi}_2)$ are the maximum likelihood estimates for the location, scale and shape parameters on the first and second margins. If non-stationary fitting is implemented using the nsloc1 or nsloc2 arguments (see Sections 7 and 8) the marginal location parameters may depend on i.

The estimator is specified using the argument model, which must be either "pickands", "deheuvels", "cfg" (the default), "tdo" or "hall" (or any unique partial match). These estimators are respectively defined (on $0 \le \omega \le 1$) as follows.

Pickands (1981)

$$A_p(\omega) = n \left\{ \sum_{i=1}^n \min \left(\frac{y_{i1}}{\omega}, \frac{y_{i2}}{1-\omega} \right) \right\}^{-1}$$

Deheuvels (1991)

$$A_d(\omega) = n \left\{ \sum_{i=1}^n \min\left(\frac{y_{i1}}{\omega}, \frac{y_{i2}}{1-\omega}\right) - \omega \sum_{i=1}^n y_{i1} - (1-\omega) \sum_{i=1}^n y_{i2} + n \right\}^{-1}$$

Capéraà et al. (1997)

$$A_c(\omega) = \exp\left\{\left\{1 - p(\omega)\right\} \int_0^\omega \frac{H_n(x) - x}{x(1 - x)} dx - p(\omega) \int_\omega^1 \frac{H_n(x) - x}{x(1 - x)} dx\right\}$$

Tiago de Oliveira (1997)

$$A_t(\omega) = 1 - \frac{1}{1 + \log n} \sum_{i=1}^n \min\left(\frac{\omega}{1 + ny_{i1}}, \frac{1 - \omega}{1 + ny_{i2}}\right)$$

Hall and Tajvidi (2000)

$$A_h(\omega) = n \left\{ \sum_{i=1}^n \min \left(\frac{y_{i1}}{\bar{y}_1 \omega}, \frac{y_{i2}}{\bar{y}_2 (1 - \omega)} \right) \right\}^{-1}$$

^{*}Some authors (e.g. Pickands, 1981) use $A(\omega) = -\log\{G(y_1^{-1}(1-\omega), y_2^{-1}(\omega))\}$.

In the estimator of Capéraà et al. (1997), $H_n(x)$ is the empirical distribution function of x_1, \ldots, x_n , where $x_i = y_{i1}/(y_{i1} + y_{i2})$ for $i = 1, \ldots, n$, and $p(\cdot)$ is any bounded function on [0, 1], which can be specified using the argument wf. By default $p(\cdot)$ is the identity function. In the estimator of Hall and Tajvidi (2000), $\bar{y}_1 = n^{-1} \sum_{i=1}^n y_{i1}$ and $\bar{y}_2 = n^{-1} \sum_{i=1}^n y_{i2}$. A short simulation study that compares the properties of these estimators is given in Appendix B.

Let $A_n(\cdot)$ be any estimator of $A(\cdot)$. The estimators $A_d(\cdot)$, $A_t(\cdot)$ and $A_h(\cdot)$ all satisfy $A_n(0) = A_n(1) = 1$. $A_c(\cdot)$ satisfies this constraint when p(0) = 0 and p(1) = 1. None of the estimators given above satisfy $\max(\omega, 1 - \omega) \leq A_n(\omega) \leq 1$ for all $0 \leq \omega \leq 1$. An obvious modification is

$$A_n'(\omega) = \min(1, \max\{A_n(\omega), \omega, 1 - \omega\}).$$

This modification is always implemented. Another estimator $A''_n(\omega)$ can be derived by taking the convex minorant of $A'_n(\omega)$. This can be achieved by setting the argument convex to TRUE.

Some examples of the functions described in this section are given below. The last lines of code produce Figure 1.

```
> bvlsm <- rmvevd(100, dep = 0.6, model = "log", d = 2)
> tvlsm <- rmvevd(100, dep = 0.6, model = "log", d = 3)

> abvpar(seq(0,1,0.25), dep = 0.3, asy = c(.7,.9), model = "alog")
[1] 1.0000 0.8272 0.7013 0.7842 1.0000
> abvnonpar(seq(0,1,0.25), data = bvlsm)
[1] 1.0000 0.8634 0.8158 0.8392 1.0000

> abvpar(dep = .3, asy = c(.5, .9), model = "al", plot = TRUE, blty = 1)
> abvpar(alpha = .5, beta = .9, model = "bil", add = TRUE, lty = 2)
> abvpar(dep = 1.05, model = "hr", add = TRUE, lty = 3)

> abvnonpar(data = bvlsm, plot = TRUE, method = "cfg", blty = 1)
> abvnonpar(data = bvlsm, method = "tdo", add = TRUE, lty = 2)
> abvnonpar(data = bvlsm, method = "pick", add = TRUE, lty = 3)

> atvpar(dep = 0.6, model = "log", plot = TRUE, lower = 0.6)
> atvnonpar(data = tvlsm, plot = TRUE, lower = 0.6)
```

6 Stochastic Processes

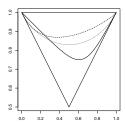
The evd package contains four functions that simulate from stochastic processes associated with extreme value theory. The functions marma, mar and mma generate max autoregressive moving average processes. The function evmc generates Markov chains with extreme value dependence structures.

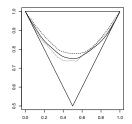
A max autoregressive moving average process $\{X_k\}$, denoted by MARMA(p, q), satisfies

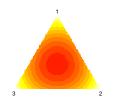
$$X_k = \max\{\phi_1 X_{k-1}, \dots, \phi_p X_{k-p}, \epsilon_k, \theta_1 \epsilon_{k-1}, \dots, \theta_q \epsilon_{k-q}\}\$$

where (ϕ_1, \ldots, ϕ_p) and $(\theta_1, \ldots, \theta_p)$ are vectors of non-negative parameters, and $\{\epsilon_k\}$ is a series of *iid* random variables with a common distribution defined by the argument rand.gen. The standard Fréchet distribution is used by default. A max autoregressive process $\{X_k\}$, denoted by MAR(p), is equivalent to a MARMA(p, 0) process, so that

$$X_k = \max\{\phi_1 X_{k-1}, \dots, \phi_p X_{k-p}, \epsilon_k\}.$$







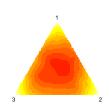


Figure 1: Extreme left: dependence functions for various parametric bivariate extreme value models. The triangular border represents the constraint $\max(\omega, 1 - \omega) \leq A(\omega) \leq 1$ for all $\omega \in [0,1]$. Left: non-parametric estimates of the dependence function using data simulated from a bivariate logistic model with $\alpha = 0.6$. Right: the dependence function of a trivariate logistic model with $\alpha = 0.6$, and (extreme right) a non-parametric estimate using data simulated from that model. The colours represent twelve equally spaced intervals between lower = 0.6 and 1, with darker colours representing stronger dependence (and hence lower values). At the vertex labelled with the value i, the ith component of $\omega \in S_3$ is one (and hence the remaining components are zero).

A max moving average process $\{X_k\}$, denoted by MMA(q), is equivalent to a MARMA(0, q) process, so that

$$X_k = \max\{\epsilon_k, \theta_1 \epsilon_{k-1}, \dots, \theta_q \epsilon_{k-q}\}.$$

The functions mar, mma and marma generate MAR(p), MMA(q) and MARMA(p, q) processes respectively. Examples of calls to these functions are given below. The n.start argument denotes the burn-in period, which can be specified so that the output series is not unduly influenced by the p starting values, which are all zero by default.

```
> marma(100, p = 1, q = 1, psi = 0.75, theta = 0.65)
> mar(100, psi = 0.85, n.start = 20)
> mma(100, q = 2, theta = c(0.75, 0.8))
```

Informally, a first order Markov chain X_1, \ldots, X_n is a stochastic process such that at any given time t the probability distribution of X_{t+1} is independent the past X_1, \ldots, X_{t-1} , given the current state X_t . The evmc function generates a first order Markov chain such that each pair of consecutive values has the dependence structure of one of the parametric bivariate extreme value models given in Section 3. The main arguments of evmc are the same as those of rbvevd. The function evmc also has the argument margin, which denotes the marginal distribution of each value. This must be either "uniform" (the default), "exponential", "frechet" or "gumbel" (or any unique partial match), for the uniform, standard exponential, standard Gumbel and standard Fréchet distributions respectively. Examples of calls to evmc are given below.

```
> evmc(100, alpha = 0.1, beta = 0.1, model = "bilog")
> evmc(100, dep = 10, model = "hr", margins = "exp")
```

7 Fitting Univariate Distributions

This section presents functions that produce maximum likelihood estimates for the distributions introduced in Section 2. Maximum likelihood estimates for bivariate distributions are discussed

in Section 8. For illustrative purposes Sections 7 and 8 use only simulated data. Two extended examples (one univariate and one bivariate) using the data sets oxford and sealevel (both included in the evd package) are given in Sections 9 and 10.

The function fgev produces maximum likelihood estimates for the GEV distribution (4). The first argument should be a numeric vector containing data to be fitted. Missing values are allowed. If the argument start is given it should be a named list containing starting values, the names of which should be the parameters over which the likelihood is to be maximized. If start is omitted the routine attempts to find good starting values for the optimization using moment estimators.

If any of the parameters are to be set to fixed values, they can be given as separate arguments. For example, the Gumbel distribution (1) can be fitted using shape = 0. Arguments of the optimization function optim can also be specified. This includes the optimization method, which can be passed using the argument method. Two examples of the fgev function are given below.

```
> data1 < - rgev(1000, loc = 0.13, scale = 1.1, shape = 0.2)
> m1 <- fgev(data1)
> m1
Call: fgev(x = data1)
Deviance: 3650
Estimates
 loc scale shape
0.127 1.125 0.224
Standard Errors
   loc
        scale
                 shape
0.0400 0.0321 0.0248
Optimization Information
  Convergence: successful
 Function Evaluations: 51
 Gradient Evaluations: 12
> m2 <- fgev(data1, loc = 0, scale = 1)
> m2
Call: fgev(x = data1, loc = 0, scale = 1)
Deviance: 3669
Estimates
shape
0.236
Standard Errors
 shape
0.0202
Optimization Information
  Convergence: successful
```

Function Evaluations: 24 Gradient Evaluations: 7

In the first example the likelihood is maximized over (loc, scale, shape). In the second example the likelihood is maximized over shape, with the location and scale parameters fixed at zero and one respectively. The maximum likelihood estimates from model m1 are

```
> fitted(m1)
   loc scale shape
0.1271 1.1251 0.2244
```

The maximum likelihood estimators do not necessarily have the usual asymptotic properties, since the end points of the GEV distribution depend on the model parameters. Smith (1985) shows that the usual asymptotic properties hold when $\xi > -0.5$. When $-1 < \xi \le -0.5$ the maximum likelihood estimators do not have the standard asymptotic properties, but generally exist. When $\xi \le -1$ maximum likelihood estimators do not often exist. This occurs because of the large mass near the upper end point. The likelihood increases without bound as the upper end point is estimated to be closer and closer to the largest observed value. In terms of the reversed Weibull shape parameter α , the usual asymptotic properties hold when $\alpha > 2$, the asymptotic properties are not standard for $1 < \alpha \le 2$, and maximum likelihood estimators do not often exist for $\alpha < 1$.

When the usual asymptotic properties hold (as here) the standard errors of the maximum likelihood estimates, approximated using the inverse of the observed information matrix, can be extracted from the fitted object using

```
> std.errors(m1)
    loc scale shape
0.03999 0.03214 0.02479
```

When the usual asymptotic properties do not hold the std.errors component will still be based on the inverse of the observed information matrix, but these values must be *interpreted with caution* (Smith, 1985).

Likelihood ratio tests can be performed using the function anova. We can compare the two models m1 and m2 to test the null hypothesis that the location parameter is zero and the scale parameter is one.

The deviance difference, deviance(m2) minus deviance(m1), is about 18.8, which yields a p-value of 8.2×10^{-5} when compared with a chi-squared distribution on two degrees of freedom. Diagnostic plots and profile deviances for fitted models can be constructed using the functions plot, profile and profile2d (see Section 9).

By default the maximum likelihood estimates are calculated under the assumption that the data to be fitted are the observed values of independent random variables Z_1, \ldots, Z_n , where

 $Z_i \sim \text{GEV}(\mu, \sigma, \xi)$ for each i = 1, ..., n. The nsloc argument allows non-stationary models of the form $Z_i \sim \text{GEV}(\mu_i, \sigma, \xi)$, where

$$\mu_i = \beta_0 + \beta_1 x_{i1} + \dots + \beta_k x_{ik}.$$

The parameters $(\beta_0, \ldots, \beta_k)$ are to be estimated. In matrix notation $\boldsymbol{\mu} = \boldsymbol{\beta_0} + X\boldsymbol{\beta}$, where $\boldsymbol{\mu} = (\mu_1, \ldots, \mu_n)^T$, $\boldsymbol{\beta_0} = (\beta_0, \ldots, \beta_0)^T$, $\boldsymbol{\beta} = (\beta_1, \ldots, \beta_k)^T$ and X is the $n \times k$ covariate matrix (excluding the intercept) with ijth element x_{ij} .

The nsloc argument must be a data frame containing the matrix X, or a numeric vector which is converted into a single column data frame with column name "trend". The column names of the data frame are used to derive names for the estimated parameters. This allows any of the k+3 parameters $(\beta_0, \ldots, \beta_k, \sigma, \xi)$ to be set to fixed values within the optimization. The covariates must be (at least approximately) centred and scaled, not only for numerical reasons, but also because the starting value (if start is not given) for each corresponding coefficient is taken to be zero. When a linear trend is present in the data, the location parameter is often modelled as

$$\mu_i = \beta_0 + \beta_1 t_i,$$

where t_i is some centred and scaled version of the time of the *i*th observation. Non-stationary models are rarely fitted, but this is probably the most commonly used form of non-stationarity. More complex changes in μ may also be appropriate. For example, a change-point model

$$\mu_i = \beta_0 + \beta_1 x_i$$
 where $x_i = \begin{cases} 0 & i \le i_0 \\ 1 & i > i_0 \end{cases}$,

or a quadratic trend

$$\mu_i = \beta_0 + \beta_1 t_i + \beta_2 t_i^2.$$

See Sections 9 and 10 for examples of non-stationary modelling.

The function fgev also has an argument called prob. If prob = p is passed a value in the interval [0,1], fgev again produces maximum likelihood estimates for the GEV distribution, but the model is re-parameterized from (μ, σ, ξ) to (z_p, σ, ξ) , where z_p is the quantile corresponding to the upper tail probability p. This argument can be used to calculate and plot profile deviances of extreme quantiles (see Section 9). If prob is zero/one, then z_p is defined as the upper/lower end point $\mu - \sigma/\xi$, and ξ is restricted to the negative/positive axis. Under non-stationarity the model is re-parameterized from $(\beta_0, \beta_1, \ldots, \beta_k, \sigma, \xi)$ to $(z_p, \beta_1, \ldots, \beta_k, \sigma, \xi)$, so that z_p is the quantile corresponding to the upper tail probability p for the distribution obtained when all covariates are zero.

The fextreme function produces maximum likelihood estimates for the distributions (5) and (6) given an integer m and an arbitrary distribution function F. The first argument should be a numeric vector containing the data to be fitted, which should represent maxima (if the argument largest is TRUE, the default) or minima (if largest is FALSE). The argument start (which cannot be missing) should be a named list containing starting values, the names of which should be the parameters over which the likelihood is to be maximized. If any of the parameters are to be set to fixed values, they can be given as separate arguments. Arguments of the optimization function optim can also be specified. The example given below produces maximum likelihood estimates for the distribution (5), where m=365 and F is the normal distribution.

- > d2 <- rextreme(100, distn = "norm", mean = 0.56, mlen = 365)
- # Simulate yearly maxima using normal distribution
- > sv <- list(mean = 0, sd = 1)

Bivariate Model	$\operatorname{Constraints}$		
Logistic	$0.1 \le \alpha \le 1$		
Asymmetric Logistic	$0.1 \le \alpha \le 1, \ 0.001 \le \theta_1, \theta_2 \le 1$		
Hüsler-Reiss	$0.2 \le \lambda \le 10$		
Negative Logistic	$0.05 \le r \le 5$		
Asymmetric Negative Logistic	$0.05 \le r \le 5, \ 0.001 \le \theta_1, \theta_2 \le 1$		
Bilogistic	$0.1 \le \alpha, \beta \le 0.999$		
Negative Bilogistic	$0.1 \le \alpha, \beta \le 20$		
Coles-Tawn	$0.001 \le \alpha, \beta \le 30$		

Table 1: For numerical reasons the parameters of each model are subject to the artificial constraints depicted here.

```
> nm <- fextreme(d2, start = sv, distn = "norm", mlen = 365)
> fitted(nm)
mean sd
0.685 0.959
```

The forder function yields maximum likelihood estimates for the distribution (7) given integers m and $j \in \{1, ..., m\}$, and an arbitrary distribution function F. An example is given below, where m = 365, j = 2 and F is the normal distribution.

```
> d3 <- rorder(100, distn = "norm", mean = 0.56, mlen = 365, j = 2)
> sv <- list(mean = 0, sd = 1)
> nm2 <- forder(d3, sv, distn = "norm", mlen = 365, j = 2)
> fitted(nm2)
mean sd
0.483 1.042
```

8 Fitting Bivariate Extreme Value Distributions

The function fbvevd produces maximum likelihood estimates for each of the eight bivariate models introduced in Section 3. The first argument should be a numeric matrix (or a data frame) with two columns containing the data to be fitted. Missing values are allowed. If the argument start is given it should be a named list containing starting values, the names of which should be the parameters over which the likelihood is to be maximized. If start is omitted the routine attempts to find good starting values for the optimization using maximum likelihood estimators under the assumption of independence. If any of the parameters are to be set to fixed values, they can be given as separate arguments. Arguments of the optimization function optim can also be specified.

The nsloc1 and nsloc2 arguments allow non-stationary modelling of the location parameters on the first and second margins respectively. They should be used in the same manner as the nsloc argument of fgev. Examples of bivariate models with non-stationary margins are given in Section 10.

For numerical reasons the parameters of each model are subject to the artificial constraints depicted in Table 1. The scale parameters on each GEV margin are artificially constrained to be greater than or equal to 0.01. These constraints only apply to the functions discussed in this section.

The first example given below produces maximum likelihood estimates for the (symmetric) logistic model. The second example constrains the model at independence (where dep = 1). The estimates produced in the second example are the same as those that would be produced if fgev was separately applied to each margin.

```
> bvdata < rbvlog(100, dep = 0.6, mar1 = c(1.2,1.4,0), mar2 = c(1,1.6,0.1))
> m1 <- fbvevd(bvdata, model = "log")</pre>
> m1
Call: fbvevd(x = bvdata, model = "log")
Deviance: 728.5
AIC: 742.5
Estimates
                   shape1
  loc1
         scale1
                              loc2
                                     scale2
                                               shape2
                                                           dep
                                               0.0834
                                                        0.7202
 1.2121
          1.3831 -0.1813
                            0.8404
                                     1.4005
Standard Errors
 loc1 scale1
                shape1
                          loc2 scale2
                                                    dep
0.1540 0.1091
                0.0673 0.1537
                                0.1144
                                        0.0614
                                                0.0624
Dependence Structure
  Dependence One: 0.3526
  Dependence Two: 0.4824
  Asymmetry: 0
Optimization Information
  Convergence: successful
 Function Evaluations: 47
 Gradient Evaluations: 10
> m2 <- fbvevd(bvdata, model = "log", dep = 1)</pre>
> fitted(m2)
    loc1
           scale1
                    shape1
                               loc2
                                      scale2
                                                shape2
 1.22311 1.37763 -0.19140 0.83671
                                     1.40829
                                               0.08683
> std.errors(m2)
  loc1 scale1 shape1
                           loc2 scale2 shape2
0.15429 0.10886 0.07245 0.15646 0.11625 0.06704
> c(logLik(m2), deviance(m2), AIC(m2))
[1] -376 752 764
```

The discussion in Section 7 regarding the properties of maximum likelihood estimators for the GEV distribution also applies to all bivariate models. The usual asymptotic properties hold only when the shape parameters on both margins are greater than -0.5. When the usual asymptotic properties do not hold the std.errors component will still be based on the inverse of the observed information matrix, but these values must be *interpreted with caution* (Smith, 1985).

The AIC (Akaike's Information Criterion) value is the deviance plus twice the number of model parameters. This is a fairly arbitrary criterion which is commonly used to compare non-nested

models. The fitted object also yields three values that summarise the dependence structure of the fitted model. Let $A(\cdot)$ denote the dependence function (15). The three values are given by

Dependence One =
$$\chi = 2\{1 - A(1/2)\}$$

Dependence Two = $\psi_d = 4 \int_0^1 1 - A(x) dx$
Asymmetry = $\psi_a = \frac{4}{3 - 2\sqrt{2}} \int_0^{1/2} A(x) - A(1-x) dx$

The two measures of dependence χ (Coles *et al.*, 1999) and ψ_d are contained in the closed interval [0,1]. At independence $\chi = \psi_d = 0$, and at complete dependence $\chi = \psi_d = 1$. The measure of asymmetry ψ_a is contained in the closed interval [-1,1].* If $A(\cdot)$ is symmetric $\psi_a = 0$. The logistic, Hüsler-Reiss and negative logistic models are always symmetric, and hence always satisfy $\psi_a = 0$. Any value $\psi_a \in (-0.2, 0.2)$ corresponds to a dependence structure that is close to symmetric.

Diagnostic plots and profile deviances for fitted models can be constructed using the functions plot, profile and profile2d (see Section 10). The function anova performs likelihood ratio tests. The null hypothesis of the test performed below specifies that the margins are Gumbel distributions (shape1 = shape2 = 0). The deviance of the constrained model is compared with the deviance of the unconstrained model. The p-value is calculated to be 0.78. The hypothesis would not be rejected at any reasonable significance level.

```
> m3 <- fbvevd(bvdata, model = "log", shape1 = 0, shape2 = 0)
> anova(m1, m3)
Analysis of Deviance Table

M.Df Deviance Df Chisq Pr(>chisq)
m1 7 708
m3 5 708 2 0.5 0.78
```

In the following example I attempt to fit the asymmetric logistic model to the simulated data set used above, which is known to be distributed as symmetric logistic.

```
> m4 <- fbvevd(bvdata, model = "alog")
> fitted(m4)
  loc1 scale1 shape1 loc2 scale2 shape2 asy1 asy2 dep
1.20969 1.39280 -0.18529 0.84210 1.38311 0.07725 0.83313 0.99957 0.69248
```

A boundary of the parameter space has been reached; the maximum likelihood estimate for the second asymmetry parameter is (effectively) one. This may cause difficulties for the optimizer. There are two solutions to this problem: the second asymmetry parameter can be fixed at one, or the L-BFGS-B method can be used. The L-BFGS-B method allows box-constraints using the arguments lower and upper. The following snippet illustrates both approaches.

```
> mb <- fbvevd(bvdata, model = "alog", asy2 = 1)
> round(fitted(mb), 3)
  loc1 scale1 shape1  loc2 scale2 shape2  asy1  dep
1.212  1.385 -0.176  0.834  1.396  0.086  0.867  0.693
```

^{*}Conjecture.

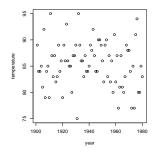


Figure 2: The oxford data.

```
> up <- c(rep(Inf, 6), 1, 1, 1)
> mb <- fbvevd(bvdata, model = "alog", method = "L-BFGS-B", upper = up)
> round(fitted(mb), 3)
  loc1 scale1 shape1  loc2 scale2 shape2  asy1  asy2  dep
  1.212  1.385 -0.176  0.834  1.396  0.086  0.867  1.000  0.693
```

9 Example: Oxford Temperature Data

The numeric vector oxford contains annual maximum temperatures (in degrees Fahrenheit) at Oxford, England, from 1901 to 1980. It is included in the evd package, and can be made available using data(oxford). The data has previously been analysed by Tabony (1983).

I begin by plotting the data. The assumptions of stationarity and independence seem sensible, given the plot generated using the code below, depicted in Figure 2.

```
> data(oxford) ; ox <- oxford
> plot(1901:1980, ox, xlab = "year", ylab = "temperature")
```

The following code fits two models based on the GEV distribution. The first model assumes stationarity. The second model allows for a trend term in the location parameter (even though the plot appears to show that this is unnecessary). The nsloc argument is centred and scaled so that the intercept loc represents the location parameter in 1950 and the trend loctrend represents the increase in the location parameter (or decrease, if negative) over a period of 100 years.

```
> ox.fit <- fgev(ox)
> tt <- (1901:1980 - 1950)/100
> ox.fit.trend <- fgev(ox, nsloc = tt)
> fitted(ox.fit.trend)
     loc loctrend
                     scale
                              shape
83.6617 -1.8812
                    4.2233
                            -0.2841
> std.errors(ox.fit.trend)
     loc loctrend
                     scale
                              shape
0.55566 1.96754 0.36504
                           0.07068
```

The trend term not statistically significant (at any reasonable level). The stationary model ox.fit is retained for further analysis.

> ox.fit

Call: fgev(x = oxford)
Deviance: 457.8

Estimates

loc scale shape 83.839 4.260 -0.287

Standard Errors

loc scale shape 0.5231 0.3658 0.0683

Optimization Information

Convergence: successful Function Evaluations: 29 Gradient Evaluations: 11

The fitted shape is negative, so the fitted distribution is Weibull. It is often of interest to test the hypothesis that the shape is zero (the Gumbel distribution). A 95% confidence interval for the shape parameter can be constructed using $-0.287 \pm 1.96 \times 0.0683$. The corresponding Wald test can be performed by dividing the maximum likelihood estimate by its standard error. The Wald test would be rejected at significance level 0.05 since the 95% confidence interval does not contain zero. A likelihood ratio test is performed in the following snippet. The hypothesis is rejected at any significance level above 0.00053.

```
> ox.fit.gum <- fgev(ox, shape = 0)
> anova(ox.fit, ox.fit.gum)
Analysis of Deviance Table
```

M.Df Deviance Df Chisq Pr(>chisq)

ox.fit 3 458

ox.fit.gum 2 470 1 12 0.00053

Diagnostic plots can be produced using plot. The plots produced by the following line of code, depicted in Figure 3, compare parametric distributions, densities and quantiles to their empirical counterparts (see the documentation for plot.gev for details of the construction of each plot, and for an explanation of the argument jitter).

```
> plot(ox.fit, jitter = TRUE)
```

The horizontal bars on the P-P, Q-Q and return level plots represent simulated (pointwise) 95% confidence intervals. The model ox.prof is seen to be a good fit. The fitted density is close to the non-parametric estimator, and most points lie within the confidence intervals. Profile deviances (minus twice the profile likelihood) of the parameters can be plotted using

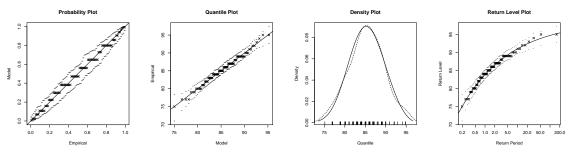


Figure 3: Diagnostic plots for the model ox.fit.

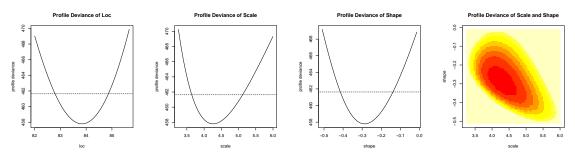


Figure 4: Profile deviance surfaces for the model ox.fit.

```
> ox.prof <- profile(ox.fit)
> pcis <- plot(ox.prof)
> pcis[["scale"]]
  lower upper
  3.643 5.117
```

This produces the first three plots within Figure 4. A horizontal line is (optionally) drawn on each plot so that the intersection of the line with the profile deviance yields a profile confidence interval, with (default) confidence coefficient 0.95. The end points of the intervals can be derived by assigning the expression plot(ox.prof) to an object, as above. The profile confidence intervals for the location and shape parameters are approximately the same as the intervals constructed using their standard errors, since the profile deviances are approximately symmetric. The profile deviance for the scale parameter is asymmetric; both end points of the profile confidence interval (3.64, 5.12) are larger than the corresponding end points of the interval (3.54, 4.98), constructed using the standard error.

The joint profile deviance of the scale and shape parameters (which are typically negatively correlated) can be plotted using

```
> ox.prof2d <- profile2d(ox.fit, ox.prof, which = c("scale", "shape"))
> plot(ox.prof2d)
```

This produces the image plot in the left panel of Figure 4.* The colours of the image plot represent confidence sets with different confidence coefficients. By default, the lightest colour (ignoring the background colour) represents a confidence set with coefficient 0.995; the darkest colour represents a confidence set with coefficient 0.5.

^{*}Assuming the package **akima** is available. If not, the image plot will look 'blocky', because bivariate interpolation will not be performed.

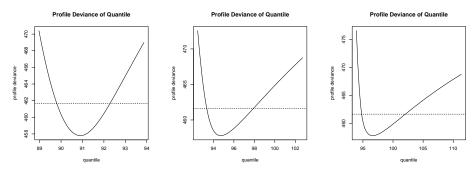


Figure 5: Profile deviance surfaces for $z_{0.1}$, $z_{0.01}$ and $z_{0.001}$.

Let G be the GEV distribution function, and let $G(z_p) = 1 - p$, so that

$$z_p = \begin{cases} \mu - \frac{\sigma}{\xi} [1 - \{ -\log(1-p) \}^{-\xi}] & \xi \neq 0 \\ \mu - \sigma \log\{ -\log(1-p) \} & \xi = 0, \end{cases}$$
 (17)

is the quantile corresponding to the upper tail probability p. The profile deviance for $z_{0.1}$ can be plotted using the following. The argument prob = p reparameterizes the GEV distribution so that fgev produces maximum likelihood estimates for (z_p, σ, ξ) .

```
> ox.qfit <- fgev(ox, prob = 0.1)
> ox.qprof <- profile(ox.qfit, which = "quantile")
> plot(ox.qprof)
```

Figure 5 shows profile deviances for $z_{0.1}$, $z_{0.01}$ and $z_{0.001}$. The extent of the asymmetry in the profile deviance surface increases for decreasing (small) p. This is to be expected, since the data provide increasingly weaker information in the (upper) tail of the fitted distribution. If $\operatorname{prob} = p$ is zero, then z_p is the upper end point of the GEV distribution, given by $\mu - \sigma/\xi$ when $\xi < 0$. The profile deviance for z_0 can be plotted using the following code.

The argument conf of the function profile controls the range of the profile trace. The profile trace is constructed so that profile confidence intervals with confidence coefficients conf or less can be derived from it. By default, conf = 0.999, though a smaller value is often appropriate when the profile deviance exhibits strong asymmetry. The 95% and 99% profile confidence intervals for the upper end point z_0 are derived as (95.8,113.0) and (95.5,131.8) respectively.

10 Example: Sea Level Data

The sealevel data frame (Coles and Tawn, 1990) has two columns containing annual sea level maxima from 1912 to 1992 at Dover and Harwich, two sites on the coast of Britain. It contains

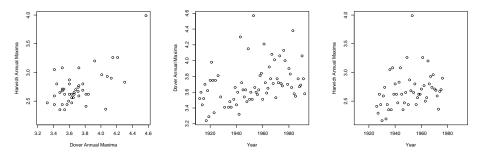


Figure 6: From left to right; Harwich Maxima vs Dover Maxima, Dover Maxima vs Year and Harwich Maxima vs Year.

39 missing maxima in total; nine at Dover and thirty at Harwich. There are three years for which the annual maximum is not available at either site.

I begin by plotting the data, using the code below. The resulting plots are given in Figure 6. The plot of the Harwich maxima against the Dover maxima depicts a reasonable degree of dependence. The outlier corresponds to the 1953 flood resulting from a storm passing over the South-East coast of Britain on 1st February. The Harwich and Dover maxima both appear to increase with time.

```
> data(sealevel) ; sl <- sealevel
> plot(sl, xlab = "Dover Annual Maxima", ylab = "Harwich Annual Maxima")
> plot(1912:1992, sl[,1], xlab = "Year", ylab = "Dover Annual Maxima")
> plot(1912:1992, sl[,2], xlab = "Year", ylab = "Harwich Annual Maxima")
```

The following three expressions fit (symmetric) logistic models. The first model incorporates linear trend terms on both marginal location parameters. The second model incorporates a linear trend on the Dover margin only. The third model assumes stationarity. The nsloc1 and nsloc2 arguments are centred and scaled so that the intercepts loc1 and loc2 represent the marginal location parameters in 1950 and the linear trend parameters loc1trend and loc2trend represent the increase in the marginal location parameters (or decrease, if negative) over a period of 100 years.

```
> tt <- (1912:1992 - 1950)/100
> m1 <- fbvevd(sl, model = "log", nsloc1 = tt, nsloc2 = tt)
> m2 <- fbvevd(sl, model = "log", nsloc1 = tt)
> m3 <- fbvevd(sl, model = "log")</pre>
```

I'll leave you to analyse the models in detail. In particular, notice how the trend terms affect the parameter estimates. Marginal Weibull distributions (negative shapes) are estimated when the trends are not included, but marginal Fréchet distributions (positive shapes) are estimated upon their inclusion.

The maximum likelihood estimates of the parameters can be compared with their standard errors to perform Wald tests or construct confidence intervals. Likelihood ratio tests are performed in the following snippet. The p-values confirm the statistical significance of the linear trend terms.

```
> anova(m1, m2, m3)
```

Analysis of Deviance Table

```
M.Df Deviance Df Chisq Pr(>chisq)
m1 9 -36.5
m2 8 -29.2 1 7.26 0.007
m3 7 -9.7 1 19.56 9.7e-06
```

Quadratic trends for the location parameter on either or both margins can be incorporated using the following code. Further testing, using the models generated below, suggests that a quadratic trend may be implemented for the location parameter on the Harwich margin. Despite this, I retain the model m1 for further analysis.

```
> tdframe <- data.frame(trend = tt, quad = tt^2)
> m4 <- fbvevd(sl, model = "log", nsloc1 = tdframe, nsloc2 = tt)
> m5 <- fbvevd(sl, model = "log", nsloc1 = tt, nsloc2 = tdframe)
> m6 <- fbvevd(sl, model = "log", nsloc1 = tdframe, nsloc2 = tdframe)</pre>
```

The code given below compares two logistic models that are nested within m1. Model m7 assumes independence. The maximum likelihood estimates are the same as those that would be produced if fgev was separately applied to each margin. The deviance increase with respect to model m1 is calculated to be 13.6. The asymptotic distribution of the deviance increase is not chi-squared. The distribution is non-regular because the dependence parameter in the restricted (independence) model is fixed at the edge of the parameter space. Testing for the (symmetric) logistic model within the asymmetric logistic model also leads to non-regular behaviour. Tawn (1988) discusses non-regular testing procedures for bivariate extreme value models. In this case the increase in deviance is clearly too large to consider independence as a viable model.

Model m8 assumes that both marginal shape parameters are zero (or equivalently, that both marginal distributions are Gumbel). A likelihood ratio test of this hypothesis provides a p-value of 0.72. The hypothesis would not be rejected at any reasonable significance level.

```
> m7 <- fbvevd(sl, model = "log", nsloc1 = tt, nsloc2 = tt, dep = 1)
> anova(m1, m7)
# The asymptotic distribution of the deviance difference is non-regular
Analysis of Deviance Table
   M.Df Deviance Df Chisq Pr(>chisq)
      9
           -36.5
m1
m7
      8
           -22.9 1 13.6
                              0.00023
> m8 <- fbvevd(s1, "log", nsloc1 = tt, nsloc2 = tt, shape1 = 0, shape2 = 0)
> anova(m1, m8)
Analysis of Deviance Table
   M.Df Deviance Df Chisq Pr(>chisq)
m1
      9
           -36.5
      7
           -35.8
                                 0.72
m8
                  2 0.67
```

Diagnostic plots for the fitted (generalized extreme value) marginal distributions can be produced using plot with mar = 1 or mar = 2. The plots produced are of the same structure as those given in Section 9. Diagnostic plots for the fitted dependence structure can be produced using plot, as shown in Figure 7 for the model m1.

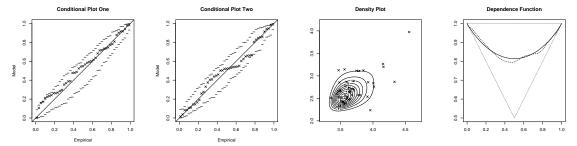


Figure 7: Diagnostic plots for the dependence structure of model m1.

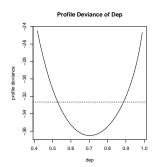


Figure 8: The profile deviance of the dependence parameter from model m1.

```
> plot(m1, mar = 1)
> plot(m1, mar = 2)
> plot(m1)
```

The plots in Figure 7 compare parametric conditional distributions, densities and dependence functions to empirical counterparts (see the documentation for plot.bvevd for details of the construction of each plot). The horizontal bars on the conditional P-P plots represent simulated (pointwise) 95% confidence intervals. The model m1 fits the data reasonably well. There are some minor deviations within the conditional P-P plots, but they do not represent a serious departure of the empirical estimates from the fitted model. The profile deviance (minus twice the profile likelihood) of the dependence parameter can be plotted using the following. The argument xmax denotes the upper bound of the dependence parameter dep.

```
> m1.prof <- profile(m1, which = "dep", xmax = 1)
> pcis <- plot(m1.prof)
> pcis[["dep"]]
   lower upper
   0.5282 0.8865
```

This produces the plot in Figure 8. A horizontal line is (optionally) drawn so that the intersection of the line with the profile deviance yields a profile confidence interval, with (default) confidence coefficient 0.95. The end points of the interval can be derived by assigning the expression plot(m1.prof) to an object, as above.

Further analysis with models other than the (symmetric) logistic yields the following conclusions. The two models in Section 3 that include three parameters with which to describe the dependence structure (the asymmetric logistic and asymmetric negative logistic) are inappropriate. In both

cases, the maximum likelihood estimate for the parameter dep is at an artificial boundary, because the fitted model is close to a distribution (obtained in the limit) which contains a singular component. This is clearly illustrated in the density plots of the fitted models, which both depict a ridge of mass extending towards the 1953 outlier. The logistic and the bilogistic models have the lowest deviance of all one and two parameter models respectively. The fitted bilogistic model has $\psi_a = -0.02$, so the fitted dependence structure is almost symmetric, and hence the logistic model would appear to be preferable. In fact, the fitted bilogistic model (12) is almost logistic, because the α and β parameter estimates are almost equal, and hence the difference between the model deviances is less than 0.01.

Appendix A: Multivariate Extreme Value Densities

Let $z = (z_1, \ldots, z_d)$. Recall that the *d*-dimensional distribution function of the logistic model is given by

$$G(z) = \exp\left\{-\left(\sum_{j=1}^{d} y_j^{-1/\alpha}\right)^{\alpha}\right\},$$

where $\alpha \in (0, 1]$ and (y_1, \dots, y_d) is defined by the transformations (10). The density function, reproduced from Shi (1995), is given by

$$g(z) = \left(\prod_{i=1}^d rac{y_i^{1/lpha+\xi_i}}{\sigma_i}
ight) v^{d(1-1/lpha)} Q_d(v,lpha) \exp(-v),$$

where

$$v = v(z) = \left(\sum_{j=1}^{d} y_j^{-1/\alpha}\right)^{\alpha},$$

and

$$Q_d(v,\alpha) = v^{1-d}(c_{1,d} + c_{2,d}v + \dots + c_{d,d}v^{d-1})$$
(18)

so that $v^{d-1}Q_d(v,\alpha)$ is a polynomial in v, of order d-1, with coefficients defined by the recurrence relations

$$c_{1,d} = \frac{\Gamma(d-\alpha)}{\alpha^{d-1}\Gamma(1-\alpha)},$$

$$c_{i,d} = \left(\frac{d-1}{\alpha} - i\right)c_{i,d-1} + c_{i-1,d-1}, \qquad i = 2, \dots, d-1,$$

$$c_{d,d} = 1.$$

Let B be the set of all non-empty subsets of $\{1, \ldots, d\}$ and let $B_1 = \{b \in B : |b| = 1\}$, where |b| denotes the number of elements in the set b. Recall that the d-dimensional distribution function of the asymmetric logistic model is given by

$$G(z) = \exp\left\{-\sum_{b \in B} \left[\sum_{i \in b} (\theta_{i,b} y_i)^{1/\alpha_b}\right]^{\alpha_b}\right\},$$

where the dependence parameters $\alpha_b \in (0,1]$ for all $b \in B \setminus B_1$, and the asymmetry parameters $\theta_{i,b} \in [0,1]$ for all $b \in B$ and $i \in b$. The remaining constraints on the parameters are given in Section 4. For ease of notation, define $\alpha_b = 1$ whenever $b \in B_1$, so that $\alpha_1 = \cdots = \alpha_d = 1$, and define $v = v(z) = \sum_{b \in B} v_b$, where

$$v_b = \left[\sum_{i \in b} (\theta_{i,b} y_i)^{1/\alpha_b}\right]^{\alpha_b}$$

for each $b \in B$. Then the density function is given by

$$g(z) = \left(\prod_{i=1}^d \frac{y_i^{\xi_i}}{\sigma_i}\right) \left(\sum_{\{b_1, \dots, b_d\}} \prod_{i=1}^d \left(\theta_{i, b_i} y_i\right)^{1/\alpha_{b_i}} v_{b_i}^{1-1/\alpha_{b_i}} Q_{p_i}(v_{b_i}, \alpha_{b_i})^{1/p_i}\right) \exp(-v),$$

where the sum is over all $2^{d(d-1)}$ sequences of sets b_1, \ldots, b_d such that, for each $i = 1, \ldots, d$, $i \in b_i$ and $b_i \in B$, and where $p_i \in \{1, \ldots, d\}$ is the number of times that the set b_i appears in the sequence b_1, \ldots, b_d . The function Q is again given by expression (18).

Appendix B: Simulation Study

Section 3 defines five non-parametric estimators for the dependence function $A(\cdot)$ of the bivariate extreme value distribution. In this Appendix we use the tools in the package to examine the small sample properties of these estimators.

Simulation studies of this form (e.g. Hall and Tajvidi, 2000) typically use the known marginal parameters $(\mu_1, \sigma_1, \xi_1, \mu_2, \sigma_2, \xi_2)$ within the transformations (16). In practice, these parameters need to be estimated. In this study we seek to replicate the behaviour of the estimators when applied to real data, and we have therefore estimated the marginal parameters by maximum likelihood.

Figure 9 depicts the behaviour of the estimators A_c (the default), A_p and A_t . The estimators A_d and A_h are not considered, as they produce plots that are indistinguishable from those of A_p . The first, second and third columns of the figure employ simulations from (symmetric) logistic distributions, with α equal to 0.5, 0.75 and 1 respectively. Standard Gumbel marginal distributions were used in each case. The figure shows that the estimator A_t is abysmal when estimating dependence functions with very strong ($\alpha = 0.5$) or very weak ($\alpha = 1$) levels of dependence. The estimators A_c and A_p give more consistent performances across different levels of dependence. The estimator A_c appears to outperform A_p , as the estimates of the former appear to cluster more tightly around the true dependence function for each $\alpha = 0.5, 0.75, 1$. The plots can easily be generated, using e.g.

```
> dep <- 0.5 ; method <- "cfg"
> abvpar(dep = dep, plot = TRUE, lty = 0)
> set.seed(44)
> for(i in 1:50) {
    sdt <- rbvevd(100, dep = dep)
    abvnonpar(data = sdt, add = TRUE, method = method, col = "grey")
}
> abvpar(dep = dep, add = TRUE, lwd = 3)
```

which generates the plot in the top left corner. Only the first line of code needs to be changed in order to produce the remaining plots. The second line of code establishes the plotting region. The simulation is performed in the for loop, and the last line adds the true dependence function to the plot. The set.seed function sets the seed of the random generator, which ensures that the simulated data sets used for each plot are comparable.

Let $A_n(\cdot)$ be any estimator of $A(\cdot)$. Table 2 gives median integrated absolute errors for various non-parametric dependence function estimators. The table was constructed as follows. For $\alpha = 0.5, 0.75, 1$ we simulated 1000 datasets containing n = 25, 100 bivariate observations, using standard Gumbel margins. Then for each of the 1000 datasets we estimated the integrated

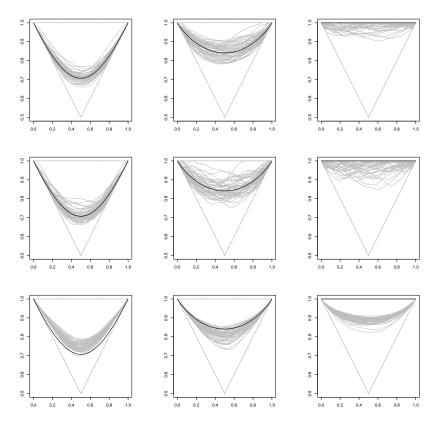


Figure 9: Simulated non-parametric dependence function estimates. The grey lines represent estimates derived using the estimators A_c (top row), A_p (middle row) and A_t (bottom row). The thick black lines represent the true dependence functions, which are (symmetric) logistic models with dependence parameters 0.5 (first column), 0.75 (second column) and 1 (third column).

	n = 25			n = 100		
	$\alpha = 0.5$	$\alpha = 0.75$	$\alpha = 1$	$\alpha = 0.5$	$\alpha = 0.75$	$\alpha = 1$
A_c	210	415	110	104	198	62
A_c^*	205	363	340	103	194	168
A_p	243	469	211	134	242	113
A_p^*	218	357	554	126	215	285
A_t^r	393	189	983	334	155	830

Table 2: Median integrated absolute errors $\times 10^4$ for non-parametric estimates of the dependence function of the bivariate extreme value distribution, using datasets containing n=25,100 bivariate observations, simulated from the (symmetric) logistic model with dependence parameter $\alpha=0.5,0.75,1$. The estimators A_c^* and A_p^* are the convex minorants of A_c and A_p respectively.

absolute error $\int_0^1 |A_n(x) - A(x)| dx$. The table contains the median of the 1000 values, for each value of α and n. We have extended the number of estimators to include the convex minorants of A_c and A_p , which we denote by A_c^* and A_p^* . The convex minorant of A_t is identical to A_t , because A_t is always convex. The estimators A_d and A_h are again not considered, as they produce virtually identical results to those of A_p .

The table again shows the poor performance of A_t when $\alpha=0.5$, and particularly when $\alpha=1$. A_t is the best estimator when $\alpha=0.75$, which is not surprising given that the estimator only yields adequate estimates at mid-range levels of dependence. The estimator A_c outperforms A_p , confirming the impression given by Figure 9. Taking the convex minorant of A_c or A_p leads to an improvement for $\alpha=0.5$ and $\alpha=0.75$, but a considerable worsening for $\alpha=1$. This worsening is expected, since taking the convex minorant always leads to estimates of stronger dependence. The values in the table can be generated using e.g.

```
> dep <- 0.5 ; n <- 25 ; method <- "cfg" ; cv <- FALSE
> nn <- 100 ; x <- (1:nn)/(nn + 1)
> a <- abvpar(x, dep = dep)
> iae <- numeric(1000)
> set.seed(44)
> for(i in 1:1000) {
    sdt <- rbvevd(n, dep = dep)
    anp <- abvnonpar(x, data = sdt, method = method, convex = cv)
    iae[i] <- sum(abs(a - anp))/nn
}
> round(10^4 * median(iae))
```

which generates the value in the top left corner. Only the first line of code needs to be changed in order to produce the remaining values. The integrated absolute error is estimated by evaluating the absolute difference between true dependence function and the non-parametric estimate at nn = 100 equally spaced points in the interval [0,1]. The function numeric merely initializes the object iae to be a vector of 1000 zeros.

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