## LGCP with PC priors

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```
library("geostatsp")
data('murder')
data('torontoPop')
murder = unwrap(murder)
torontoBorder = unwrap(torontoBorder)
torontoPdens = unwrap(torontoPdens)
torontoIncome = unwrap(torontoIncome)
```

```
if(requireNamespace("INLA", quietly=TRUE)) {
   INLA::inla.setOption(num.threads=2)
   # not all versions of INLA support blas.num.threads
   try(INLA::inla.setOption(blas.num.threads=2), silent=TRUE)
}
```

### LGCP with priors given by quantiles

### LGCP with penalised complexity prior

```
pr(sd > 1) = 0.05 and pr(phi < 0.2) = 0.95
```

### LGCP with table priors

#### **Parameters**

```
if(!is.null(resG$parameters))
     knitr::kable(resG$parameters$summary[,c(1,3,5)], digits=3)
```

	mean	0.025quant	0.975quant
(Intercept)	-3.178	-10.142	3.801
inc	-1.266	-1.911	-0.623
range/1000	1.691	1.237	2.292
sd	0.836	0.695	0.926

```
if(!is.null(resP$parameters))
     knitr::kable(resP$parameters$summary[,c(1,3,5)], digits=3)
```

	mean	0.025quant	0.975quant
(Intercept)	-3.296	-10.220	3.646
inc	-1.255	-1.896	-0.615
range/1000	1.724	1.252	2.361
sd	0.825	0.687	0.910

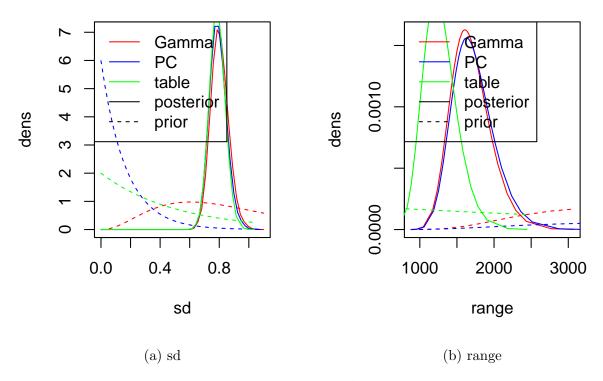


Figure 1: Priors and posteriors

	mean	0.025quant	0.975quant
(Intercept)	-2.449	-9.012	4.073
inc	-1.333	-1.936	-0.726
range/1000	1.276	0.886	1.783
sd	0.820	0.686	0.894

# Maps

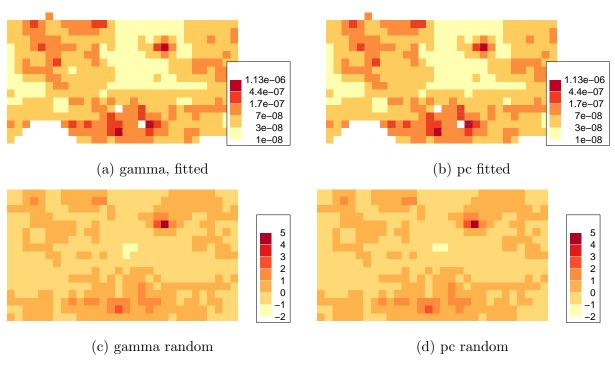


Figure 2: Random effects and fitted values