Package 'geostatsp'

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Description Geostatistical modelling facilities using 'SpatRaster' and 'SpatVector' objects are provided. Non-Gaussian models are fit using 'INLA', and Gaussian geostatistical models use Maximum Likelihood Estimation. For details see Brown (2015) <doi:10.18637 jss.v063.i12="">. The 'RandomFields' package is available at https://www.wim.uni-mannheim.de/schlather/publications/software>.</doi:10.18637>	
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conditionalGmrf

Conditional distribution of GMRF

Description

Distribution of Gaussian Markov Random Field conditional on data observed with noise on the same grid.

Usage

```
conditionalGmrf(param, Yvec, Xmat, NN,
template = NULL, mc.cores = 1,
cellsPerLoop = 10, ...)
```

Arguments

param vector of named parameters

Yvec vector of observed data, or matrix with each column being a realisation.

Xmat Matrix of covariates.

NN nearest neighbour matrix

template Raster on which the GMRF is defined

mc.cores passed to mclapply

cellsPerLoop number of cells to compute simultaneously. Larger values consume more mem-

ory but result in faster computation.

... additional arguments passed to maternGmrfPrec

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Value

Raster image with layers containing conditional mean and standard deviation.

Author(s)

Patrick Brown

See Also

maternGmrfPrec, 1gm

exc	Dra	h
-	110	v

Exceedance probabilities

Description

Calculate exceedance probabilities pr(X > threshold) from a fitted geostatistical model.

Usage

```
excProb(x, threshold=0, random=FALSE, template=NULL, templateIdCol=NULL,
nuggetInPrediction=TRUE)
```

Arguments

X	Output from either the lgm or glgm functions, or a list of two-column matrices
	with columns named x and y containing the posterior distributions of random

effects, as produced by inla.

threshold the value which the exceedance probability is calculated with respect to.

random Calculate exceedances for the random effects, rather than the predicted observa-

tions (including fixed effects).

 $\label{template} Lemplate A SpatRaster or SpatVector object which the results will be contained in.$

 ${\tt templateIdCol} \quad \text{The data column in template corresponding to names of marginals}$

nuggetInPrediction

If TRUE, calculate exceedance probabilities of new observations by adding the nugget effect. Otherwise calculate probabilities for the latent process. Ignored if x is output from glgm.

Details

When x is the output from lgm, pr(Y>threshold) is calculated using the Gaussian distribution using the Kriging mean and conditional variance. When x is from the glgm function, the marginal posteriors are numerically integrated to obtain pr(X > threshold).

Value

Either a vector of exceedance probabilities or an object of the same class as template.

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Examples

```
data('swissRain')
swissRain = unwrap(swissRain)
swissAltitude = unwrap(swissAltitude)
swissBorder = unwrap(swissBorder)
swissFit = lgm("rain", swissRain, grid=30,
boxcox=0.5,fixBoxcox=TRUE,covariates=swissAltitude)
swissExc = excProb(swissFit, 20)
mycol = c("green","yellow","orange","red")
mybreaks = c(0, 0.2, 0.8, 0.9, 1)
plot(swissBorder)
plot(swissExc, breaks=mybreaks, col=mycol,add=TRUE,legend=FALSE)
plot(swissBorder, add=TRUE)
legend("topleft",legend=mybreaks, col=c(NA,mycol))
if(requireNamespace("INLA", quietly=TRUE) ) {
  INLA::inla.setOption(num.threads=2)
  # not all versions of INLA support blas.num.threads
  try(INLA::inla.setOption(blas.num.threads=2), silent=TRUE)
swissRain$sqrtrain = sqrt(swissRain$rain)
swissFit2 = glgm(formula="sqrtrain",data=swissRain, grid=40,
covariates=swissAltitude,family="gaussian")
swissExc = excProb(swissFit2, threshold=sqrt(30))
swissExc = excProb(swissFit2$inla$marginals.random$space, 0,
template=swissFit2$raster)
}
```

 ${\tt gambiaUTM}$

Gambia data

Description

This data-set was used by Diggle, Moyeed, Rowlingson, and Thomson (2002) to demonstrate how the model-based geostatistics framework of Diggle et al. (1998) could be adapted to assess the source(s) of extrabinomial variation in the data and, in particular, whether this variation was spatially structured. The malaria prevalence data set consists of measurements of the presence of malarial parasites in blood samples obtained from children in 65 villages in the Gambia. Other child- and village-level indicators include age, bed net use, whether the bed net is treated, whether or not the village belonged to the primary health care structure, and a measure of 'greenness' using a vegetation index.

Usage

```
data(gambiaUTM)
```

Format

A SpatVector , with column pos being the binary response for a malaria diagnosis, as well as other child-level indicators such as netuse and treated being measures of bed net use and whether the nets were treated. The column green is a village-level measure of greenness. A UTM coordinate reference system is used, where coordinates are in metres.

Source

http://www.leg.ufpr.br/doku.php/pessoais:paulojus:mbgbook:datasets. For further details on the malaria data, see Thomson et al. (1999).

References

Diggle, P. J., Moyeed, R. A., Rowlingson, R. and Thomson, M. (2002). Childhood Malaria in the Gambia: A case-study in model-based geostatistics. Journal of the Royal Statistical Society. Series C (Applied Statistics), 51(4): 493-506.

Diggle, P. J., Tawn, J. A. and Moyeed, R. A. (1998). Model-based geostatistics (with Discussion). Applied Statistics, 47, 299–350.

Thomson, M. C., Connor, S. J., D'Alessandro, U., Rowlingson, B., Diggle, P., Creswell, M. and Greenwood, B. (2004). Predicting malaria infection in Gambian children from satellite data and bed net use surveys: the importance of spatial correlation in the interpretation of results. American Journal of Tropical Medicine and Hygiene, 61: 2-8.

Examples

```
data("gambiaUTM")
gambiaUTM = unwrap(gambiaUTM)

plot(gambiaUTM, main="gambia data")

if(require('mapmisc', quietly=TRUE)) {
    data(worldMap)
    worldMap = unwrap(worldMap)
    gambia = project(worldMap[grep("Gambia", worldMap$NAME), ], crs(gambiaUTM))
    gambiaTiles = openmap(gambia, buffer=100*1000)
    oldpar=map.new(gambia)
    plot(gambiaTiles, add=TRUE)
    plot(gambiaUTM, add=TRUE)
    par(oldpar)
}
```

glgm-methods

Generalized Linear Geostatistical Models

Description

Fits a generalized linear geostatistical model or a log-Gaussian Cox process using inla

Usage

```
## S4 method for signature 'ANY,ANY,ANY,ANY'
glgm(formula, data, grid, covariates, buffer=0, shape=1, prior, ...)
## S4 method for signature 'formula,SpatRaster,ANY,ANY'
glgm(formula, data, grid, covariates, buffer=0, shape=1, prior, ...)
## S4 method for signature 'formula,SpatVector,ANY,ANY'
glgm(formula, data, grid, covariates, buffer=0, shape=1, prior, ...)
## S4 method for signature 'formula,data.frame,SpatRaster,data.frame'
glgm(formula, data, grid, covariates, buffer=0, shape=1, prior, ...)
lgcp(formula=NULL, data, grid, covariates=NULL, border, ...)
```

Arguments

data	An object of class SpatVector containing the data.
grid	Either an integer giving the number of cells in the x direction, or a raster object which will be used for the spatial random effect. If the cells in the raster are not square, the resolution in the y direction will be adjusted to make it so.
covariates	Either a single raster, a list of rasters or a raster stack containing covariate values used when making spatial predictions. Names of the raster layers or list elements correspond to names in the formula. If a covariate is missing from the data object it will be extracted from the rasters. Defaults to NULL for an intercept-only model.
formula	Model formula, defaults to a linear combination of each of the layers in the covariates object. The spatial random effect should not be supplied but the default can be overridden with a f(space,) term. For glgm the response variable defaults to the first variable in the data object, and formula can be an integer or character string specifying the response variable. For lgcp, the formula should be one-sided.
prior	list with elements named range, sd, sd0bs. See Details.
shape	Shape parameter for the Matern correlation function, must be 1 or 2.
buffer	Extra space padded around the data bounding box to reduce edge effects.

... Additional options passed to inla

Details

border

This function performs Bayesian inference for generalized linear geostatistical models with INLA. The Markov random field approximation on a regular lattice is used for the spatial random effect. The range parameter is the distance at which the correlation is 0.13, or

boundary of the region on which an LGCP is defined, passed to mask

$$cov[U(s+h),U(s)] = (2^{1-\nu}/Gamma(\nu))d^{\nu}besselK(d,\nu)$$

$$d = |h|\sqrt{8\nu}/range$$

where ν is the shape parameter. The range parameter produced by glgm multiplies the range parameter from INLA by the cell size.

Elements of prior can be named range, sd, or sd0bs. Elements can consist of:

• a single value giving the prior median for penalized complexity priors (exponential on the sd or 1/range).

• a vector c(u=a, alpha=b) giving an quantile and probability for pc priors. For standard deviations alpha is an upper quantile, for the range parameter b = pr(1/range > 1/a).

- a vector c(lower=a, upper=b) giving a 0.025 and 0.975 quantiles for the sd or range.
- a list of the form list(prior='loggamma', param=c(1,2)) passed directly to inla.
- a two-column matrix of prior densities for the sd or range.

Value

A list with two components named inla, raster, and parameters. inla contains the results of the call to the inla function. raster is a raster stack with the following layers:

random. mean, sd, X0.0??quant: Posterior mean, standard deviation, and quantiles of the random effect

predict. mean, sd, X0.0??quant: same for linear predictors, on the link scale

predict.exp posterior mean of the exponential of the linear predictor

predict.invlogit

Only supplied if a binomial response variable was used.

parameters contains a list with elements:

summary a table with parameter estimates and posterior quantiles

prior and posterior distributions of range and standard deviations

See Also

range, sd

```
inla, https://www.r-inla.org
```

```
# geostatistical model for the swiss rainfall data
if(requireNamespace("INLA", quietly=TRUE) ) {
  INLA::inla.setOption(num.threads=2)
  # not all versions of INLA support blas.num.threads
  try(INLA::inla.setOption(blas.num.threads=2), silent=TRUE)
}
require("geostatsp")
data("swissRain")
swissRain = unwrap(swissRain)
swissAltitude = unwrap(swissAltitude)
swissBorder = unwrap(swissBorder)
swissRain$lograin = log(swissRain$rain)
swissFit = glgm(formula="lograin", data=swissRain,
grid=30,
covariates=swissAltitude, family="gaussian",
buffer=2000,
prior = list(sd=1, range=100*1000, sd0bs = 2),
control.inla = list(strategy='gaussian')
if(!is.null(swissFit$parameters) ) {
```

```
swissExc = excProb(swissFit, threshold=log(25))
swissExcRE = excProb(swissFit$inla$marginals.random$space,
log(1.5),template=swissFit$raster)
swissFit$parameters$summary
matplot(
swissFit$parameters$range$postK[,'x'],
swissFit$parameters$range$postK[,c('y','prior')],
type="1", lty=1, xlim = c(0, 1000),
xlab = 'km', ylab='dens')
legend('topright', lty=1, col=1:2, legend=c('post','prior'))
plot(swissFit$raster[["predict.exp"]])
mycol = c("green","yellow","orange","red")
mybreaks = c(0, 0.2, 0.8, 0.95, 1)
plot(swissBorder)
plot(swissExc, breaks=mybreaks, col=mycol,add=TRUE,legend=FALSE)
plot(swissBorder, add=TRUE)
legend("topleft",legend=mybreaks, fill=c(NA,mycol))
plot(swissBorder)
plot(swissExcRE, breaks=mybreaks, col=mycol,add=TRUE,legend=FALSE)
plot(swissBorder, add=TRUE)
legend("topleft",legend=mybreaks, fill=c(NA,mycol))
# a log-Gaussian Cox process example
myPoints = vect(cbind(rbeta(100,2,2), rbeta(100,3,4)))
mycov = rast(matrix(rbinom(100, 1, 0.5), 10, 10), extent=ext(0, 1, 0, 1))
names(mycov)="x1"
if(requireNamespace("INLA", quietly=TRUE) ) {
  INLA::inla.setOption(num.threads=2)
  # not all versions of INLA support blas.num.threads
  try(INLA::inla.setOption(blas.num.threads=2), silent=TRUE)
}
res = lgcp(
formula=~factor(x1),
data=myPoints,
grid=squareRaster(ext(0,1,0,1), 20), covariates=mycov,
prior=list(sd=c(0.9, 1.1), range=c(0.4, 0.41),
control.inla = list(strategy='gaussian'), verbose=TRUE)
)
if(length(res$parameters)) {
plot(res$raster[["predict.exp"]])
```

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```
plot(myPoints,add=TRUE,col="#0000FF30",cex=0.5)
}
```

inla.models

Valid models in INLA

Description

calls the function of the same name in INLA

Usage

```
inla.models()
```

Value

a list

krigeLgm

Spatial prediction, or Kriging

Description

Perform spatial prediction, producing a raster of predictions and conditional standard deviations.

Usage

```
krigeLgm(formula, data, grid, covariates = NULL,
param,
    expPred = FALSE, nuggetInPrediction = TRUE,
    mc.cores=getOption("mc.cores", 1L))
```

Arguments

formula Either a model formula, or a data frame of linear covariates.

data A SpatVector containing the data to be interpolated

grid Either a SpatRaster, or a single integer giving the number of cells in the X

direction which predictions will be made on. If the later the predictions will be

a raster of square cells covering the bounding box of data.

covariates The spatial covariates used in prediction, either a SpatRaster stack or list of

rasters.

param A vector of named model parameters, as produced by likfitLgm

expPred Should the predictions be exponentiated, defaults to FALSE.

nuggetInPrediction

If TRUE, predict new observations by adding the nugget effect. The prediction variances will be adjusted accordingly, and the predictions on the natural scale for logged or Box Cox transformed data will be affected. Otherwise predict

fitted values.

mc.cores passed to mclapply if greater than 1.

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Details

Given the model parameters and observed data, conditional means and variances of the spatial random field are computed.

Value

A raster is returned with the following layers:

fixed Estimated means from the fixed effects portion of the model

random Predicted random effect

krige.var Conditional variance of predicted random effect (on the transformed scale if

applicable)

predict Prediction of the response, sum of fixed and random effects. If exp.pred is

TRUE, gives predictions on the exponentiated scale, and half of krige.var is

added prior to exponentiating

predict.log If exp.pred=TRUE, the prediction of the logged process.

predict.boxcox If a box cox transformation was used, the prediction of the process on the trans-

formed scale.

If the prediction locations are different for fixed and random effects (typically coarser for the random effects), a list with two raster stacks is returned.

prediction A raster stack as above, though the random effect prediction is resampled to the

same locations as the fixed effects.

random the predictions and conditional variance of the random effects, on the same raster

as newdata

See Also

lgm

```
data('swissRain')
swissAltitude = unwrap(swissAltitude)
swissRain = unwrap(swissRain)
swissRain$lograin = log(swissRain$rain)
swissRain[[names(swissAltitude)]] = extract(swissAltitude, swissRain, ID=FALSE)

swissFit = likfitLgm(data=swissRain,
formula=lograin~ CHE_alt,
param=c(range=46500, nugget=0.05, shape=1,
anisoAngleDegrees=35, anisoRatio=12),
paramToEstimate = c("range","nugget",
"anisoAngleDegrees", "anisoRatio")
)
myTrend = swissFit$model$formula
myParams = swissFit$param

swissBorder = unwrap(swissBorder)

swissKrige = krigeLgm(
```

```
data=swissRain,
formula = myTrend,
covariates = swissAltitude,
param=myParams,
grid = squareRaster(swissBorder, 40), expPred=TRUE)
plot(swissKrige[["predict"]], main="predicted rain")
plot(swissBorder, add=TRUE)
```

1gm-methods

Linear Geostatistical Models

Description

Calculate MLE's of model parameters and perform spatial prediction.

Usage

```
## S4 method for signature 'missing, ANY, ANY, ANY'
lgm(
formula, data, grid, covariates,
buffer=0, shape=1, boxcox=1, nugget = 0,
expPred=FALSE, nuggetInPrediction=TRUE,
reml=TRUE,mc.cores=1,
aniso=FALSE,
fixShape=TRUE,
fixBoxcox=TRUE,
fixNugget = FALSE,
...)
## S4 method for signature 'numeric, ANY, ANY, ANY'
lgm(
formula, data, grid, covariates,
buffer=0, shape=1, boxcox=1, nugget = 0,
expPred=FALSE, nuggetInPrediction=TRUE,
reml=TRUE,mc.cores=1,
aniso=FALSE,
fixShape=TRUE,
fixBoxcox=TRUE,
fixNugget = FALSE,
...)
## S4 method for signature 'character, ANY, ANY, ANY'
lgm(
formula, data, grid, covariates,
buffer=0, shape=1, boxcox=1, nugget = 0,
expPred=FALSE, nuggetInPrediction=TRUE,
reml=TRUE,mc.cores=1,
aniso=FALSE,
fixShape=TRUE,
```

```
fixBoxcox=TRUE,
fixNugget = FALSE,
...)
## S4 method for signature 'formula, SpatVector, numeric, ANY'
formula, data, grid, covariates,
buffer=0, shape=1, boxcox=1, nugget = 0,
expPred=FALSE, nuggetInPrediction=TRUE,
reml=TRUE,mc.cores=1,
aniso=FALSE,
fixShape=TRUE,
fixBoxcox=TRUE,
fixNugget = FALSE,
...)
## S4 method for signature 'formula, SpatVector, SpatRaster, missing'
lgm(
formula, data, grid, covariates,
buffer=0, shape=1, boxcox=1, nugget = 0,
expPred=FALSE, nuggetInPrediction=TRUE,
reml=TRUE,mc.cores=1,
aniso=FALSE,
fixShape=TRUE,
fixBoxcox=TRUE,
fixNugget = FALSE,
...)
## S4 method for signature 'formula,SpatVector,SpatRaster,list'
formula, data, grid, covariates,
buffer=0, shape=1, boxcox=1, nugget = 0,
expPred=FALSE, nuggetInPrediction=TRUE,
reml=TRUE,mc.cores=1,
aniso=FALSE,
fixShape=TRUE.
fixBoxcox=TRUE,
fixNugget = FALSE,
...)
## S4 method for signature 'formula, SpatVector, SpatRaster, SpatRaster'
formula, data, grid, covariates,
buffer=0, shape=1, boxcox=1, nugget = 0,
expPred=FALSE, nuggetInPrediction=TRUE,
reml=TRUE,mc.cores=1,
aniso=FALSE,
fixShape=TRUE,
fixBoxcox=TRUE,
fixNugget = FALSE,
...)
## S4 method for signature 'formula, SpatVector, SpatRaster, data.frame'
lgm(
formula, data, grid, covariates,
buffer=0, shape=1, boxcox=1, nugget = 0,
expPred=FALSE, nuggetInPrediction=TRUE,
```

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```
reml=TRUE, mc.cores=1,
aniso=FALSE.
fixShape=TRUE,
fixBoxcox=TRUE,
fixNugget = FALSE,
...)
## S4 method for signature 'formula, SpatRaster, ANY, ANY'
lgm(
formula, data, grid, covariates,
buffer=0, shape=1, boxcox=1, nugget = 0,
expPred=FALSE, nuggetInPrediction=TRUE,
reml=TRUE, mc.cores=1,
aniso=FALSE,
fixShape=TRUE,
fixBoxcox=TRUE,
fixNugget = FALSE,
...)
## S4 method for signature 'formula,data.frame,SpatRaster,data.frame'
lgm(
formula, data, grid, covariates,
buffer=0, shape=1, boxcox=1, nugget = 0,
expPred=FALSE, nuggetInPrediction=TRUE,
reml=TRUE,mc.cores=1,
aniso=FALSE,
fixShape=TRUE,
fixBoxcox=TRUE,
fixNugget = FALSE,
...)
```

Arguments

formula	A model formula for the fixed effects, or a character string specifying the response variable.
data	A SpatVector or SpatRaster layer, brick or stack containing the locations and observations, and possibly covariates.
grid	Either a SpatRaster, or a single integer giving the number of cells in the X direction which predictions will be made on. If the later the predictions will be a raster of square cells covering the bounding box of data.
covariates	The spatial covariates used in prediction, either a SpatRaster stack or list of rasters. Covariates in formula but not in data will be extracted from covariates.
shape	Order of the Matern correlation

boxcox Box-Cox transformation parameter (or vector of parameters), set to 1 for no

transformation.

nugget Value for the nugget effect (observation error) variance, or vector of such values.

expPred Should the predictions be exponentiated, defaults to FALSE.

nuggetIn Prediction

If TRUE, predict new observations by adding the nugget effect. The prediction variances will be adjusted accordingly, and the predictions on the natural scale for logged or Box Cox transformed data will be affected. Otherwise predict fitted values.

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reml	If TRUE (the default), use restricted maximum likelihood.					
mc.cores	If mc.cores>1, this argument is passed to mclapply and computations are done in parallel where possible.					
aniso	Set to TRUE to use geometric anisotropy.					
fixShape	Set to FALSE to estimate the Matern order					
fixBoxcox	Set to FALSE to estimate the Box-Cox parameter.					
fixNugget	Set to FALSE to estimate the nugget effect parameter.					
buffer	Extra distance to add around grid.					
•••	Additional arguments passed to likfitLgm. Starting values can be specified with a vector param of named elements.					

with a vector param of named elements

Details

When data is a SpatVector, parameters are estimated using optim to maximize the log-likelihood function computed by likfitLgm and spatial prediction accomplished with krigeLgm.

With data being a Raster object, a Markov Random Field approximation to the Matern is used (experimental). Parameters to be estimated should be provided as vectors of possible values, with optimization only considering the parameter values supplied.

Value

A list is returned which includes a SpatRaster named predict having layers:

fixed	Estimated means from the fixed effects portion of the model
random	Predicted random effect
krigeSd	Conditional standard deviation of predicted random effect (on the transformed scale if applicable)
predict	Prediction of the response, sum of predicted fixed and random effects. For Box-Cox or log-transformed data on the natural (untransformed) scale.
predict.log	If exp.pred=TRUE, the prediction of the logged process.
predict.boxcox	If a box cox transformation was used, the prediction of the process on the trans-

formed scale. In addition, the element summery contains a table of parameter estimates and confidence intervals.

optim contains the output from the call to the optim function.

See Also

```
likfitLgm, krigeLgm
```

```
data("swissRain")
swissRain = unwrap(swissRain)
swissAltitude = unwrap(swissAltitude)
swissBorder = unwrap(swissBorder)
swissRes = lgm( formula="rain",
data=swissRain[1:60,], grid=20,
covariates=swissAltitude, boxcox=0.5, fixBoxcox=TRUE,
shape=1, fixShape=TRUE,
```

```
aniso=FALSE, nugget=0, fixNugget=FALSE,
nuggetInPrediction=FALSE
)
swissRes$summary
plot(swissRes$predict[["predict"]], main="predicted rain")
plot(swissBorder, add=TRUE)
```

likfitLgm

Likelihood Based Parameter Estimation for Gaussian Random Fields

Description

Maximum likelihood (ML) or restricted maximum likelihood (REML) parameter estimation for (transformed) Gaussian random fields.

Usage

```
likfitLgm(formula, data,
paramToEstimate = c("range","nugget"),
reml=TRUE,
coordinates=data,
param=NULL,
upper=NULL,lower=NULL, parscale=NULL,
verbose=FALSE)

loglikLgm(param,
data, formula, coordinates=data,
reml=TRUE,
minustwotimes=TRUE,
moreParams=NULL)
```

Arguments

formula	A i	formula for	the fixed	l effects	portion of	f the r	nodel,	specifying	a response	and
---------	-----	-------------	-----------	-----------	------------	---------	--------	------------	------------	-----

covariates. Alternately, data can be a vector of observations and formula can

be a model matrix.

data An object of class SpatVect, a vector of observations, or a data frame containing

observations and covariates.

coordinates A SpatVect object containing the locations of each observation, which defaults

to data. Alternately, coordinates can be a symmetricMatrix-class or dist object reflecting the distance matrix of these coordinates (though this is only

permitted if the model is isotropic).

param A vector of model parameters, with named elements being amongst range,

nugget, boxcox, shape, anisoAngleDegrees, anisoAngleRadians, anisoRatio, and possibly variance (see matern). When calling likfitLgm this vector is a combination of starting values for parameters to be estiamated and fixed values

of parameters which will not be estimated. For loglikLgm, it is the covariance

parameters for which the likelihood will be evaluated.

reml Whether to use Restricted Likelihood rather than Likelihood, defaults to TRUE.

paramToEstimate

Vector of names of model parameters to estimate, with parameters excluded from this list being fixed. The variance parameter and regression coefficients

are always estimated even if not listed.

lower Named vector of lower bounds for model parameters passed to optim, defaults

are used for parameters not specified.

upper Upper bounds, as above.

parscale Named vector of scaling of parameters passed as control=list(parscale=parscale)

to optim.

minustwotimes Return -2 times the log likelihood rather than the likelihood

moreParams Vector of additional parameters, combined with param. Used for passing fixed

parameters to loglikLgm from within optim.

verbose if TRUE information is printed by optim.

Value

likfitLgm produces list with elements

parameters Maximum Likelihood Estimates of model parameters varBetaHat Variance matrix of the estimated regression parameters

optim results from optim

trend Either formula for the fixed effects or names of the columns of the model matrix,

depending on trend supplied.

summary a table of parameter estimates, standard errors, confidence intervals, p values,

and a logical value indicating whether each parameter was estimated as opposed

to fixed.

resid residuals, being the observations minus the fixed effects, on the transformed

scale.

loglikLgm returns a scalar value, either the log likelihood or -2 times the log likelihood. Attributes of this result include the vector of parameters (including the MLE's computed for the variance and coefficients), and the variance matrix of the coefficient MLE's.

See Also

1gm

```
n=40
mydat = vect(
cbind(runif(n), seq(0,1,len=n)),
atts=data.frame(cov1 = rnorm(n), cov2 = rpois(n, 0.5))
)

# simulate a random field
trueParam = c(variance=2^2, range=0.35, shape=2, nugget=0.5^2)
set.seed(1)
```

```
oneSim = RFsimulate(model=trueParam,x=mydat)
values(mydat) = cbind(values(mydat) , values(oneSim))
# add fixed effects
mydat Y = -3 + 0.5 mydat cov1 + 0.2 mydat cov2 +
mydat$sim + rnorm(length(mydat), 0, sd=sqrt(trueParam["nugget"]))
plot(mydat, "sim", col=rainbow(10), main="U")
plot(mydat, "Y", col=rainbow(10), main="Y")
myres = likfitLgm(
formula=Y ~ cov1 + cov2,
data=mydat,
param=c(range=0.1,nugget=0.1,shape=2),
paramToEstimate = c("range", "nugget")
myres$summary[,1:4]
# plot variograms of data, true model, and estimated model
myv = variog(mydat, formula=Y ~ cov1 + cov2,option="bin", max.dist=0.5)
# myv will be NULL if geoR isn't installed
if(!is.null(myv)){
plot(myv, ylim=c(0, max(c(1.2*sum(trueParam[c("variance", "nugget")]),myv$v))),
main="variograms")
distseq = seq(0, 0.5, len=50)
lines(distseq,
sum(myres$param[c("variance", "nugget")]) - matern(distseq, param=myres$param),
col='blue', lwd=3)
lines(distseq,
sum(trueParam[c("variance", "nugget")]) - matern(distseq, param=trueParam),
col='red')
legend("bottomright", fill=c("black","red","blue"),
legend=c("data","true","MLE"))
}
# without a nugget
myresNoN = likfitLgm(
formula=Y ~ cov1 + cov2,
data=mydat,
param=c(range=0.1,nugget=0,shape=1),
paramToEstimate = c("range")
myresNoN$summary[,1:4]
# plot variograms of data, true model, and estimated model
myv = variog(mydat, formula=Y ~ cov1 + cov2,option="bin", max.dist=0.5)
if(!is.null(myv)){
plot(myv, ylim=c(0, max(c(1.2*sum(trueParam[c("variance", "nugget")]),myv$v))),
```

```
main="variograms")
distseq = seq(0, 0.5, len=50)
lines(distseq,
sum(myres$param[c("variance", "nugget")]) - matern(distseq, param=myres$param),
col='blue', lwd=3)
lines(distseq,
sum(trueParam[c("variance", "nugget")]) - matern(distseq, param=trueParam),
col='red')
lines(distseq,
sum(myresNoN$param[c("variance", "nugget")]) -
matern(distseq, param=myresNoN$param),
col='green', lty=2, lwd=3)
legend("bottomright", fill=c("black","red","blue","green"),
legend=c("data","true","MLE","no N"))
}
# calculate likelihood
temp=loglikLgm(param=myres$param,
data=mydat,
formula = Y \sim cov1 + cov2,
reml=FALSE, minustwotimes=FALSE)
# an anisotropic example
trueParamAniso = param=c(variance=2^2, range=0.2, shape=2,
nugget=0,anisoRatio=4,anisoAngleDegrees=10, nugget=0)
mydat$U = geostatsp::RFsimulate(trueParamAniso,mydat)$sim
mydat Y = -3 + 0.5 mydat cov1 + 0.2 mydat cov2 +
mydat$U + rnorm(length(mydat), 0, sd=sqrt(trueParamAniso["nugget"]))
par(mfrow=c(1,2))
oldmar = par("mar")
par(mar=rep(0.1, 4))
plot(mydat, col=as.character(cut(mydat$U, breaks=50, labels=heat.colors(50))),
pch=16, main="aniso")
plot(mydat, col=as.character(cut(mydat$Y, breaks=50, labels=heat.colors(50))),
pch=16,main="iso")
par(mar=oldmar)
myres = likfitLgm(
formula=Y ~ cov1 + cov2,
data=mydat,
param=c(range=0.1,nugget=0,shape=2, anisoAngleDegrees=0, anisoRatio=2),
paramToEstimate = c("range","nugget","anisoRatio","anisoAngleDegrees")
```

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```
myres$summary
par(mfrow=c(1,2))
myraster = rast(nrows=30,ncols=30,xmin=0,xmax=1,ymin=0,ymax=1)
covEst = matern(myraster, y=c(0.5, 0.5), par=myres$param)
covTrue = matern(myraster, y=c(0.5, 0.5), par=trueParamAniso)
plot(covEst, main="estimate")
plot(covTrue, main="true")
par(mfrow=c(1,1))
```

loaloa

Loaloa prevalence data from 197 village surveys

Description

Location and prevalence data from villages, elevation an vegetation index for the study region.

Usage

```
data("loaloa")
```

Format

loaloa is a SpatVector containing the data, with columns N being the number of individuals tested and y being the number of positives. elevationLoa is a raster of elevation data. eviLoa is a raster of vegetation index for a specific date. ltLoa is land type. ltLoa is a raster of land types. 1 2 5 6 7 8 9 10 11 12 13 14 15 tempLoa is a raster of average temperature in degrees C.

Source

http://www.leg.ufpr.br/doku.php/pessoais:paulojus:mbgbook:datasets for the loaloa data, https://lpdaac.usgs.gov/data/ for EVI and land type and https://srtm.csi.cgiar.org for the elevation data.

```
data("loaloa")
loaloa = unwrap(loaloa)
plot(loaloa, main="loaloa villages")

# elevation
elevationLoa = unwrap(elevationLoa)
plot(elevationLoa, col=terrain.colors(100), main="elevation")
points(loaloa)

# vegetation index
eviLoa = unwrap(eviLoa)
```

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```
plot(eviLoa, main="evi")
points(loaloa)

tempLoa = unwrap(tempLoa)
plot(tempLoa, main="temperature")
points(loaloa)

# land type, a categorical variable
ltLoa = unwrap(ltLoa)
plot(ltLoa)
if(requireNamespace("mapmisc")){
mapmisc::legendBreaks("bottomleft",ltLoa, bty='n')
}
points(loaloa)
```

matern

Evaluate the Matern correlation function

Description

Returns the Matern covariance for the distances supplied.

Usage

```
matern( x, param=c(range=1, variance=1, shape=1),
type=c('variance','cholesky','precision', 'inverseCholesky'),
## S3 method for class 'SpatVector'
matern(x, param,
type=c('variance','cholesky','precision', 'inverseCholesky'),
y=NULL)
## Default S3 method:
matern(x, param,
type=c('variance','cholesky','precision', 'inverseCholesky'),
y=NULL)
## S3 method for class 'dist'
matern( x, param,
type=c('variance','cholesky','precision', 'inverseCholesky'),
y=NULL)
## S3 method for class 'SpatRaster'
matern( x, param,
type=c('variance','cholesky','precision', 'inverseCholesky'),
y=NULL)
fillParam(param)
```

Arguments

x A vector or matrix of distances, or SpatRaster or SpatVector of locations, see Details below.

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param	A vector of named model parameters with, at a minimum names range and shape (see Details), and optionally variance (defaults to 1) and nugget (defaults to zero). For Geometric Anisotropy add anisoRatio and either anisoAngleDegrees or anisoAngleRadians
type	specifies if the variance matrix, the Cholesky decomposition of the variance matrix, the precision matrix, or the inverse of the Cholesky L matrix is returned.
У	Covariance is calculated for the distance between locations in x and y. If y=NULL, covariance of x with itself is produced. However, if x is a matrix or vector it is assumed to be a set of distances and y is ignored.

Details

The formula for the Matern correlation function is

$$M(x) = \frac{variance}{\Gamma(shape)} 2^{1-shape} \left(\frac{x\sqrt{8shape}}{range}\right)^{shape} besselK(x\sqrt{8shape}/range, shape)$$

The range argument is sqrt(8*shape)*phi.geoR, sqrt(8*shape)*scale.whittle.RandomFields, and 2*scale.matern.RandomFields.

Geometric anisotropy is only available when x is a SpatRaster or SpatVector. The parameter 'anisoAngle' refers to rotation of the coordinates anti-clockwise by the specified amount prior to calculating distances, which has the effect that the contours of the correlation function are rotated clockwise by this amount. anisoRatio is the amount the Y coordinates are divided by post rotation prior to calculating distances. A large value of anisoRatio makes the Y coordinates smaller and increases the correlation in the Y direction.

When x or y are rasters, cells are indexed row-wise starting at the top left.

Value

When x is a vector or matrix or object of class dist, a vector or matrix of covariances is returned. With x being SpatVector, y must also be SpatVector and a matrix of correlations between x and y is returned. When x is a Raster, and y is a single location a Raster of covariances between each pixel centre of x and y is returned.

```
param=c(shape=2.5,range=1,variance=1)
u = seq(0, 4, len = 200)
uscale = sqrt(8*param['shape'])* u / param['range']
theMaterns = cbind(
dist=u.
manual= param['variance']* 2^(1- param['shape']) *
( 1/gamma(param['shape']) ) *
uscale^param['shape'] * besselK(uscale , param['shape']),
geostatsp=geostatsp::matern(u, param=param)
head(theMaterns)
matplot(theMaterns[,'dist'],
theMaterns[,c('manual','geostatsp')],
col=c('red','blue'), type='l',
xlab='dist', ylab='var')
legend('topright', fill=c('red','blue'),
legend=c('manual','geostatsp'))
```

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```
# example with raster
myraster = rast(nrows=40,ncols=60,extent=ext(-3, 3,-2,2))
param = c(range=2, shape=2, anisoRatio=2,
anisoAngleDegrees=-25,variance=20)
# plot correlation of each cell with the origin
myMatern = matern(myraster, y=c(0,0), param=param)
plot(myMatern, main="anisortopic matern")
# correlation matrix for all cells with each other
myraster = rast(nrows=4,ncols=6,extent = ext(-3, 3, -2, 2))
myMatern = matern(myraster, param=c(range=2, shape=2))
dim(myMatern)
# plot the cell ID's
values(myraster) = seq(1, ncell(myraster))
mydf = as.data.frame(myraster, xy=TRUE)
plot(mydf$x, mydf$y, type='n', main="cell ID's")
text(mydf$x, mydf$y, mydf$lyr.1)
# correlation between bottom-right cell and top right cell is
myMatern[6,24]
# example with points
mypoints = vect(
cbind(runif(8), runif(8))
# variance matrix from points
m1=matern(mypoints, param=c(range=2, shape=1.4, variance=4, nugget=1))
# cholesky of variance from distances
\verb|c2=matern(dist(crds(mypoints))|, param=c(range=2, shape=1.4, variance=4, nugget=1), type='cholesky'|)|
# check it's correct
quantile(as.vector(m1- tcrossprod(c2)))
# example with vector of distances
distVec = seq(0, 2*range, len=100)
shapeSeq = c(0.5, 1, 2,20)
theCov = NULL
for(D in shapeSeq) {
theCov = cbind(theCov, matern(distVec, param=c(range=range, shape=D)))
matplot(distVec, theCov, type='1', lty=1, xlab='distance', ylab='correlation',
main="matern correlations")
legend("right", fill=1:length(shapeSeq), legend=shapeSeq,title='shape')
# exponential
distVec2 = seq(0, max(distVec), len=20)
points(distVec2, exp(-2*(distVec2/range)),cex=1.5, pch=5)
points(distVec2, exp(-2*(distVec2/range)^2), col='blue',cex=1.5, pch=5)
```

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```
legend("bottomleft", pch=5, col=c('black','blue'), legend=c('exp','gau'))
# comparing to geoR and RandomFields
if (requireNamespace("RandomFields", quietly = TRUE) &
requireNamespace("geoR", quietly = TRUE)
) {
covGeoR = covRandomFields = NULL
for(D in shapeSeq) {
covGeoR = cbind(covGeoR,
geoR::matern(distVec, phi=range/sqrt(8*D), kappa=D))
covRandomFields = cbind(covRandomFields,
RandomFields::RFcov(x=distVec,
model=RandomFields::RMmatern(nu=D, var=1,
scale=range/2) ))
}
matpoints(distVec, covGeoR, cex=0.5, pch=1)
matpoints(distVec, covRandomFields, cex=0.5, pch=2)
legend("topright", lty=c(1,NA,NA), pch=c(NA, 1, 2),
legend=c("geostatsp", "geoR", "RandomFields"))
```

maternGmrfPrec

Precision matrix for a Matern spatial correlation

Description

Produces the precision matrix for a Gaussian random field on a regular square lattice, using a Markov random field approximation.

Usage

```
maternGmrfPrec(N, ...)
## S3 method for class 'dgCMatrix'
maternGmrfPrec(N,
param=c(variance=1, range=1, shape=1, cellSize=1),
    adjustEdges=FALSE,...)
## Default S3 method:
maternGmrfPrec(N, Ny=N,
    param=c(variance=1, range=1, shape=1, cellSize=1),
    adjustEdges=FALSE, ...)
NNmat(N, Ny=N, nearest=3, adjustEdges=FALSE)
## S3 method for class 'SpatRaster'
NNmat(N, Ny=N, nearest=3, adjustEdges=FALSE)
## Default S3 method:
NNmat(N, Ny=N, nearest=3, adjustEdges=FALSE)
```

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Arguments

N	Number of grid cells in the x direction, or a matrix denoting nearest neighbours.
Ny	Grid cells in the y direction, defaults to N for a square grid
param	Vector of model parameters, with named elements: scale, scale parameter for the correlation function; prec, precision parameter; shape, Matern differentiability parameter (0, 1, or 2); and cellSize, the size of the grid cells. Optionally, variance and range can be given in place of prec and scale, when the former are present and the latter are missing the reciprocal of the former are taken.
adjustEdges	If TRUE, adjust the precision matrix so it does not implicitly assume the field takes values of zero outside the specified region. Defaults to FALSE. Can be a character string specifying the parameters to use for the correction, such as 'optimal' or 'optimalShape', with TRUE equivalent to 'theo'
nearest	Number of nearest neighbours to compute
	Additional arguments passed to maternGmrfPrec.dsCMatrix

Details

The numbering of cells is consistent with the terra package. Cell 1 is the top left cell, with cell 2 being the cell to the right and numbering continuing row-wise.

The nearest neighbour matrix N has: N[i,j]=1 if i=j; takes a value 2 if i and j are first 'rook' neighbours; 3 if they are first 'bishop' neighbours; 4 if they are second 'rook' neighbours; 5 if 'knight' neighbours; and 6 if third 'rook' neighbours.

	[,1]	[,2]	[,3]	[,4]	[,5]	[,6]	[,7]
[1,]	0	0	0	6	0	0	0
[2,]	0	0	5	4	5	0	0
[3,]	0	5	3	2	3	5	0
[4,]	6	4	2	1	2	4	6
[5,]	0	5	3	2	3	5	0
[6,]	0	0	5	4	5	0	0
[7,]	0	0	0	6	0	0	0

Value

A sparse matrix dsCMatrix-class object, containing a precision matrix for a Gaussian random field or (from the NNmat function) a matrix denoting neighbours.

```
# produces the matrix above
matrix(NNmat(11, 11, nearest=5)[,11*5+6],11, 11)

params=c(range = 3,shape=2, variance=5^2)

myGrid = squareRaster(ext(0,20,0,10), 40)

# precision matrix without adjusting for edge effects
precMat =maternGmrfPrec(N=myGrid, param=params)

attributes(precMat)$info$precisionEntries

midcell = cellFromRowCol(myGrid,
```

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```
round(nrow(myGrid)/2), round(ncol(myGrid)/2)) # the middle cell
edgeCell = cellFromRowCol(myGrid, 5,5)# cell near corner
# show precision of middle cell
precMid=matrix(precMat[,midcell],
nrow(myGrid), ncol(myGrid), byrow=TRUE)
precMid[round(nrow(precMid)/2) + seq(-5, 5),
round(ncol(precMid)/2) + seq(-3, 3)
# and with the adjustment
precMatCorr =maternGmrfPrec(
N = myGrid, param=params,
adjustEdges=TRUE)
# variance matrices
varMat = Matrix::solve(precMat)
varMatCorr = Matrix::solve(precMatCorr)
# compare covariance matrix to the matern
xseq = seq(-ymax(myGrid), ymax(myGrid), len=1000)/1.5
plot(xseq, matern(xseq, param=params),
 type = 'l',ylab='cov', xlab='dist',
 ylim=c(0, params["variance"]*1.1),
main="matern v gmrf")
# middle cell
varMid=matrix(varMat[,midcell],
nrow(myGrid), ncol(myGrid), byrow=TRUE)
varMidCorr=matrix(varMatCorr[,midcell],
nrow(myGrid), ncol(myGrid), byrow=TRUE)
xseqMid = yFromRow(myGrid) - yFromCell(myGrid, midcell)
points(xseqMid, varMid[,colFromCell(myGrid, midcell)],
col='red')
points(xseqMid, varMidCorr[,colFromCell(myGrid, midcell)],
col='blue', cex=0.5)
# edge cells
varEdge=matrix(varMat[,edgeCell],
  nrow(myGrid), ncol(myGrid), byrow=TRUE)
varEdgeCorr = matrix(varMatCorr[,edgeCell],
  nrow(myGrid), ncol(myGrid), byrow=TRUE)
xseqEdge = yFromRow(myGrid) - yFromCell(myGrid, edgeCell)
points(xseqEdge,
varEdge[,colFromCell(myGrid, edgeCell)],
pch=3,col='red')
points(xseqEdge,
  varEdgeCorr[,colFromCell(myGrid, edgeCell)],
  pch=3, col='blue')
legend("topright", lty=c(1, NA, NA, NA, NA),
  pch=c(NA, 1, 3, 16, 16),
col=c('black','black','red','blue'),
legend=c('matern', 'middle','edge','unadj', 'adj')
)
```

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```
# construct matern variance matrix

myraster = attributes(precMat)$raster
covMatMatern = matern(myraster, param=params)

prodUncor = crossprod(covMatMatern, precMat)
prodCor = crossprod(covMatMatern, precMatCorr)

quantile(Matrix::diag(prodUncor),na.rm=TRUE)
quantile(Matrix::diag(prodCor),na.rm=TRUE)

quantile(prodUncor[lower.tri(prodUncor,diag=FALSE)],na.rm=TRUE)
quantile(prodCor[lower.tri(prodCor,diag=FALSE)],na.rm=TRUE)
```

murder

Murder locations

Description

Locations of murders in Toronto 1990-2014

Usage

```
data("murder")
```

Format

murder is a SpatVector object of murder locations. torontoPdens, torontoIncome, and torontoNight are rasters containing population density (per hectare), median household income, and ambient light respectively. torontoBorder is a SpatVector of the boundary of the city of Toronto.

Source

```
Murder data:https://mdl.library.utoronto.ca/collections/geospatial-data/toronto-homicide-data-199
Lights: https://ngdc.noaa.gov/eog/viirs/download_ut_mos.html
Boundary files: https://www150.statcan.gc.ca/n1/en/catalogue/92-160-X
Income: https://www150.statcan.gc.ca/n1/en/catalogue/97-551-X2006007
```

```
data("murder")
murder= unwrap(murder)
torontoBorder = unwrap(torontoBorder)
plot(torontoBorder)
points(murder, col="#0000FF40", cex=0.5)
```

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```
data("torontoPop")
torontoNight = unwrap(torontoNight)
torontoIncome = unwrap(torontoIncome)
torontoPdens = unwrap(torontoPdens)
# light
plot(torontoNight, main="Toronto ambient light")
plot(torontoBorder, add=TRUE)
points(murder, col="#0000FF40", cex=0.5)
# income
plot(torontoIncome, main="Toronto Income")
points(murder, col="#0000FF40", cex=0.5)
plot(torontoBorder, add=TRUE)
# population density
plot(torontoPdens, main="Toronto pop dens")
points(murder, col="#0000FF40", cex=0.5)
plot(torontoBorder, add=TRUE)
```

pcPriorRange

PC prior for range parameter

Description

Creates a penalized complexity prior for the range parameter

Usage

```
pcPriorRange(q, p=0.5, cellSize=1)
```

Arguments

q Lower quantile for the range parameter

p probability that the range is below this quantile, defaults to the median

cellSize size of grid cells, can be a raster.

Details

q is the quantile in spatial units, usually meters, and the scale parameter follows an exponential distribution. A prior PC prior distribution for the range parameter in units of grid cells, which INLA requires, is computed.

Value

A list with

lambda parameter for the exponential distribution (for scale in units of cells), in the same

parametrization as dexp

priorScale matrix with x and y columns with prior of scale parameter

postExp

priorRange matris with x and y columns with prior of range parameter, in meters (or original

spatial units)

inla character string specifying this prior in inla's format

Examples

```
# pr(range < 100km) = 0.1, 200m grid cells
x = pcPriorRange(q=100*1000, p=0.1, cellSize = 200)
rangeSeq = seq(0, 1000, len=1001)
plot(rangeSeq, x$dprior$range(rangeSeq*1000)*1000,
    type='l', xlab="range, 1000's km", ylab='dens')
cat(x$inla)</pre>
```

postExp

Exponentiate posterior quantiles

Description

Converts a summary table for model parameters on the log scale to the natural or exponentiated scale.

Usage

```
postExp(x,
exclude = grep('^(range|aniso|shape|boxcox)', rownames(x)),
invLogit=FALSE)
```

Arguments

x a matrix or data frame as returned by glgm

exclude vector of parameters not transformed, defaults to the range parameter

invLogit Converts intercept parameter to inverse-logit scale when TRUE. Can also be a

vector of parameters to inverse-logit transform.

Value

a summary table for log or exponentially transformed model parameters

```
require("geostatsp")
data("swissRain")
swissRain = unwrap(swissRain)
swissAltitude = unwrap(swissAltitude)

swissRain$lograin = log(swissRain$rain)

if(requireNamespace('INLA', quietly=TRUE)) {
   INLA::inla.setOption(num.threads=2)
   # not all versions of INLA support blas.num.threads
   try(INLA::inla.setOption(blas.num.threads=2), silent=TRUE)
swissFit = glgm(formula="lograin", data=swissRain,
```

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```
grid=20,
covariates=swissAltitude/1000, family="gaussian",
prior = list(sd=1, range=100*1000, sd0bs = 2),
control.inla = list(strategy='gaussian', int.strategy='eb'),
control.mode = list(theta=c(1.6542995, 0.7137123,2.2404179))
)
if(length(swissFit$parameters)) {
postExp(swissFit$parameters$summary)
}
```

profLlgm

Joint confidence regions

Description

Calculates profile likelihoods and approximate joint confidence regions for covariance parameters in linear geostatistical models.

Usage

```
profLlgm(fit, mc.cores = 1, ...)
informationLgm(fit, ...)
```

Arguments

fit Output from the lgm function

mc.cores Passed to mclapply

... For profLlgm, one or more vectors of parameter values at which the profile likelihood will be calculated, with names corresponding to elements of fit\$param.

For informationLgm, arguments passed to hessian

Value

one or more vectors

of parameter values

logL A vector, matrix, or multi-dimensional array of profile likelihood values for ev-

ery combination of parameter values supplied.

full Data frame with profile likelihood values and estimates of model parameters

prob, breaks vector of probabilities and chi-squared derived likelihood values associated with

those probabilities

MLE, maxLogL Maximum Likelihood Estimates of parameters and log likelihood evaluated at

these values

basepars combination of starting values for parameters re-estimated for each profile like-

lihood and values of parameters which are fixed.

col vector of colours with one element fewer than the number of probabilities

ci, ciLong when only one parameter is varying, a matrix of confidence intervals (in both

wide and long format) is returned.

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Author(s)

Patrick Brown

See Also

```
lgm, mcmapply, hessian
```

Examples

}

```
# this example is time consuming
# the following 'if' statement ensures the CRAN
# computer doesn't run it
if(interactive() | Sys.info()['user'] =='patrick') {
library('geostatsp')
data('swissRain')
swissRain = unwrap(swissRain)
swissAltitude = unwrap(swissAltitude)
swissFit = lgm(data=swissRain, formula=rain~ CHE_alt,
grid=10, covariates=swissAltitude,
shape=1, fixShape=TRUE,
boxcox=0.5, fixBoxcox=TRUE,
aniso=TRUE,reml=TRUE,
param=c(anisoAngleDegrees=37,anisoRatio=7.5,
range=50000))
x=profLlgm(swissFit,
anisoAngleDegrees=seq(30, 43 , len=4)
plot(x[[1]],x[[2]], xlab=names(x)[1],
ylab='log L',
ylim=c(min(x[[2]]),x$maxLogL),
type='n')
abline(h=x$breaks[-1],
col=x$col,
1wd=1.5)
axis(2,at=x$breaks,labels=x$prob,line=-1.2,
tick=FALSE,
las=1,padj=1.2,hadj=0)
abline(v=x$ciLong$par,
col=x$col[as.character(x$ciLong$prob)])
lines(x[[1]],x[[2]], col='black')
```

RFsimulate 31

|--|

Description

This function simulates conditional and unconditional Gaussian random fields, calling the function in the RandomFields package of the same name.

Usage

```
## S4 method for signature 'ANY, SpatRaster'
RFsimulate(model, x,data=NULL,
 err.model=NULL, n = 1, \ldots)
## S4 method for signature 'numeric,SpatRaster'
RFsimulate(model, x,data=NULL,
 err.model=NULL, n = 1, ...)
## S4 method for signature 'numeric, SpatVector'
RFsimulate(model, x, data=NULL,
err.model=NULL, n = 1, ...)
## S4 method for signature 'RMmodel, SpatRaster'
RFsimulate(model, x, data=NULL,
 err.model=NULL, n = 1, ...)
## S4 method for signature 'RMmodel, SpatVector'
RFsimulate(model, x, data=NULL,
 err.model=NULL, n = 1, ...)
## S4 method for signature 'matrix,SpatRaster'
RFsimulate(model, x, data=NULL,
 err.model=NULL, n = nrow(model), ...)
## S4 method for signature 'matrix,SpatVector'
RFsimulate(model, x,data=NULL,
err.model=NULL, n = nrow(model), ...)
## S4 method for signature 'data.frame, ANY'
RFsimulate(model, x,data=NULL,
err.model=NULL, n = nrow(model), ...)
modelRandomFields(param, includeNugget=FALSE)
```

Arguments

model	object of class RMmodel, a vector of named model parameters, or a matrix where each column is a model parameter
x	Object of type SpatRaster or SpatVector.
data	For conditional simulation and random imputing only. If data is missing, unconditional simulation is performed. Object of class SpatVector; coordinates and response values of measurements in case that conditional simulation is to be performed
err.model	For conditional simulation and random imputing only. Usually err.model=RMnugget(var=var), or not given at all (error-free measurements).
n	number of realizations to generate.

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... for advanced use: further options and control parameters for the simulation that

are passed to and processed by $\ensuremath{\mathsf{RFoptions}}$

param A vector of named parameters

includeNugget If FALSE, the nugget parameter is ignored.

Details

If model is a matrix, a different set of parameters is used for each simulation. If data has the same number of columns as model has rows, a different column i is used with parameters in row i.

Value

An object of the same class as x.

Author(s)

See Also

RFsimulate, RFfit, RFgetModelInfo, RFgui, RMmodel, RFoptions, RFsimulateAdvanced, RFsimulate.more.examp

```
library('geostatsp')
# exclude this line to use the RandomFields package
options(useRandomFields = FALSE)
model1 <- c(var=5, range=1,shape=0.5)</pre>
myraster = rast(nrows=20,ncols=30,extent = ext(0,6,0,4),
crs="+proj=utm +zone=17 +datum=NAD27 +units=m +no_defs")
set.seed(0)
simu <- RFsimulate(model1, x=myraster, n=3)</pre>
plot(simu[['sim2']])
xPoints = suppressWarnings(as.points(myraster))
# conditional simulation
firstSample = RFsimulate(
c(model1, nugget=1),
x=xPoints[seq(1,ncell(myraster), len=100), ],
n=3
)
secondSample = RFsimulate(
model = cbind(var=5:3, range=seq(0.05, 0.25, len=3), shape=seq(0.5, 1.5, len=3)),
 err.model = 1,
x= myraster,
data=firstSample,n=4
```

rongelapUTM 33

```
plot(secondSample)
```

rongelapUTM

Rongelap data

Description

This data-set was used by Diggle, Tawn and Moyeed (1998) to illustrate the model-based geostatistical methodology introduced in the paper. discussed in the paper. The radionuclide concentration data set consists of measurements of γ -ray counts at 157 locations.

Usage

```
data(rongelapUTM)
```

Format

A SpatVector, with columns count being the radiation count and time being the length of time the measurement was taken for. A UTM coordinate reference system is used, where coordinates are in metres.

Source

http://www.leg.ufpr.br/doku.php/pessoais:paulojus:mbgbook:datasets. For further details on the radionuclide concentration data, see Diggle, Harper and Simon (1997), Diggle, Tawn and Moyeed (1998) and Christensen (2004).

References

Christensen, O. F. (2004). Monte Carlo maximum likelihood in model-based geostatistics. Journal of computational and graphical statistics **13** 702-718.

Diggle, P. J., Harper, L. and Simon, S. L. (1997). Geostatistical analysis of residual contamination from nuclea testing. In: *Statistics for the environment 3: pollution assessment and control* (eds. V. Barnet and K. F. Turkmann), Wiley, Chichester, 89-107.

Diggle, P. J., Tawn, J. A. and Moyeed, R. A. (1998). Model-based geostatistics (with Discussion). Applied Statistics, 47, 299–350.

```
data("rongelapUTM")
rongelapUTM = unwrap(rongelapUTM)
plot(rongelapUTM, main="Rongelap island")
if(require('mapmisc')) {
  bgMap = openmap(rongelapUTM, buffer=200)
  plot(bgMap)
  points(rongelapUTM)
  scaleBar(rongelapUTM, 'left')
```

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}

simLgcp

Simulate a log-Gaussian Cox process

Description

Give covariates and model parameters, simulates a log-Gaussian Cox process

Usage

```
simLgcp(param, covariates=NULL, betas=NULL,
offset=NULL,
  rasterTemplate=covariates[[1]], n=1, ...)
simPoissonPP(intensity)
```

Arguments

param	A vector of named model parameters with, at a minimum names range and shape (see Details), and optionally variance (defaults to 1). For Geometric Anisotropy add anisoRatio and either anisoAngleDegrees or anisoAngleRadians
covariates	Either a raster stack or list of rasters and SpatVectors (with the latter having only a single data column).
betas	Coefficients for the covariates
offset	Vector of character strings corresponding to elements of covariates which are offsets
${\tt rasterTemplate}$	Raster on which the latent surface is simulated, defaults to the first covariate.
n	number of realisations to simulate
	additional arguments, see RFsimulate.
intensity	Raster of the intensity of a Poisson point process.

Value

A list with a events element containing the event locations and a SpatRaster element containing a raster stack of the covariates, spatial random effect, and intensity.

```
mymodel = c(mean=-0.5, variance=1,
range=2, shape=2)

myraster = rast(nrows=15,ncols=20,xmin=0,xmax=10,ymin=0,ymax=7.5)

# some covariates, deliberately with a different resolution than myraster
covA = covB = myoffset = rast(ext(myraster), 10, 10)
values(covA) = as.vector(matrix(1:10, 10, 10))
```

spatialRoc 35

```
values(covB) = as.vector(matrix(1:10, 10, 10, byrow=TRUE))
values(myoffset) = round(seq(-1, 1, len=ncell(myoffset)))

myCovariate = list(a=covA, b=covB, offsetFooBar = myoffset)

myLgcp=simLgcp(param=mymodel,
covariates=myCovariate,
betas=c(a=-0.1, b=0.25),
offset='offsetFooBar',
rasterTemplate=myraster)

plot(myLgcp$raster[["intensity"]], main="lgcp")
points(myLgcp$events)

myIntensity = exp(-1+0.2*myCovariate[["a"]])
myPoissonPP = simPoissonPP(myIntensity)[[1]]
plot(myIntensity, main="Poisson pp")
points(myPoissonPP)
```

spatialRoc

Sensitivity and specificity

Description

Calculate ROC curves using model fits to simulated spatial data

Usage

```
spatialRoc(fit, rr = c(1, 1.2, 1.5, 2), truth, border=NULL, random = FALSE, prob = NULL, spec = seq(0,1,by=0.01))
```

Arguments

fit	A fitted model from the 1gcp function
rr	Vector of relative risks exceedance probabilities will be calculated for. Values are on the natural scale, with spatialRoc taking logs when appropriate.
truth	True value of the spatial surface, or result from simLgcp function. Assumed to be on the log scale if random=TRUE and on the natural scale otherwise.
border	optional, SpatVector specifying region that calculations will be restricted to.
random	compute ROC's for relative intensity (FALSE) or random effect (TRUE)
prob	Vector of exceedance probabilities
spec	Vector of specificities for the resulting ROC's to be computed for.

Details

Fitted models are used to calculate exceedance probabilities, and a location is judged to be above an rr threshold if this exceedance probability is above a specified probability threshold. Each raster cell of the true surface is categorized as being either true positive, false positive, true negative, and false negative and sensitivity and specificity computed. ROC curves are produced by varying the probability threshold.

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Value

An array, with dimension 1 being probability threshold, dimension 2 being the relative risk threshold, dimension 3 being sensitivity and specificity. If fit is a list of model fits, dimension 4 corresponds to elements of fit.

Author(s)

Patrick Brown

See Also

```
lgcp, simLgcp, excProb
```

squareRaster-methods Create a raster with square cells

Description

Given a raster object, an extent, or a bounding box, a raster of with square cells and having the extent and number of cells specified is returned.

Usage

```
## S4 method for signature 'matrix'
squareRaster(x,cells=NULL, buffer=0)
## S4 method for signature 'SpatRaster'
squareRaster(x,cells=NULL, buffer=0)
## S4 method for signature 'SpatVector'
squareRaster(x,cells=NULL, buffer=0)
## S4 method for signature 'SpatExtent'
squareRaster(x,cells=NULL, buffer=0)
```

Arguments

x A spatial object

cells The number of cells in the x direction. If NULL the number of columns of x is

used.

buffer Additional area to add around the resulting raster

Value

A SpatRaster with square cells

```
myraster = rast(matrix(0,10,10),extent=c(0,10,0,12.3))
squareRaster(myraster)
squareRaster(myraster, buffer=3, cells=20)
```

stackRasterList 37

```
squareRaster(ext(myraster), cells=10)
```

stackRasterList

Converts a list of rasters, possibly with different projections and resolutions, to a single raster stack.

Description

This function is intended to be used prior to passing covariates to krigeLgm in order for the rasters for all covariates to have the same projection and same resolution.

Usage

```
stackRasterList(x, template = x[[1]], method = "near", mc.cores=NULL)
spdfToBrick(x,
    template,
    logSumExpected=FALSE,
    pattern = '^expected_[[:digit:]]+$'
)
```

Arguments

X	A list of SpatRaster or SpatVectors for stackRasterList and spdfToBrick respectively
template	A raster whose projection and resolution all other rasters will be aligned with.
method	The method to use, either "near", or "bilinear". Can be a vector of the same length as x to specify different methods for each raster. If method has names which correspond to the names of x , the names will be used instead of the order to assign methods to rasters.
mc.cores	If non-null, $\operatorname{mclapply}$ is used with this argument specifying the number of cores.
${\tt logSumExpected}$	return the log of the sum of offsets

expression to identify layers to rasterize in x

Value

pattern

A raster brick, with one layer for each variable.

38 swissRain

swissRain

Swiss rainfall data

Description

Data from the SIC-97 project: Spatial Interpolation Comparison.

Usage

```
data("swissRain")
```

Format

swissRain is a SpatVector 100 daily rainfall measurements made in Switzerland on the 8th of May 1986. swissAltitude is a raster of elevation data, and swissLandType is a raster of land cover types.

Source

```
https://wiki.52north.org/AI_GEOSTATS/AI_GEOSTATSData and https://srtm.csi.cgiar.org and https://lpdaac.usgs.gov/data/
```

```
data("swissRain")
swissRain = unwrap(swissRain)
swissAltitude = unwrap(swissAltitude)
swissBorder = unwrap(swissBorder)
swissLandType = unwrap(swissLandType)
plot(swissAltitude, main="elevation")
points(swissRain)
plot(swissBorder, add=TRUE)

# land type, a categorical variable
commonValues = sort(table(values(swissLandType)),decreasing=TRUE)[1:5]
commonValues=commonValues[!names(commonValues)==0]
```

swissRainR 39

```
thelevels = levels(swissLandType)[[1]]$ID
thebreaks = c(-0.5, 0.5+thelevels)
thecol = rep(NA, length(thelevels))
names(thecol) = as.character(thelevels)

thecol[names(commonValues)] = rainbow(length(commonValues))

plot(swissLandType, breaks=thebreaks, col=thecol,legend=FALSE,
main="land type")
points(swissRain)
plot(swissBorder, add=TRUE)

legend("left",fill=thecol[names(commonValues)],
legend=substr(levels(swissLandType)[[1]][
match(as.integer(names(commonValues)),
levels(swissLandType)[[1]]$ID),
"Category"], 1,12),
bg= 'white'
)
```

swissRainR

Raster of Swiss rain data

Description

A raster image of Swiss rain and elevation, and a nearest neighbour matrix corresponding to this raster

Usage

```
data(swissRainR)
```

Format

swissRainR is a RasterBrick of Swiss elevation and precipitation, and swissNN is a matrix of nearest neighbours.

Source

See examples

```
data('swissRainR')
swissRainR = unwrap(swissRainR)
plot(swissRainR[['prec7']])
plot(swissRainR[['alt']])
swissNN[1:4,1:5]
```

40 variog

variog

Compute Empirical Variograms and Permutation Envelopes

Description

These are wrappers for variog and variog.mc.env in the geoR package.

Usage

```
variog(geodata, ...)
## S3 method for class 'SpatVector'
variog(geodata, formula, ...)
## Default S3 method:
variogMcEnv(geodata, ...)
## S3 method for class 'SpatVector'
variogMcEnv(geodata, formula, ...)
```

Arguments

An object of class SpatVector or of a class suitable for variog in the geoR package.

formula

A formula specifying the response variable and fixed effects portion of the model. The variogram is performed on the residuals.

... additional arguments passed to variog in the geoR package.

Value

```
As variog or variog.mc.env
```

See Also

```
variog and variog.mc.env.
```

```
data("swissRain")
swissRain = unwrap(swissRain)
swissRain$lograin = log(swissRain$rain)
swissv= variog(swissRain, formula=lograin ~ 1,option="bin")
swissEnv = variogMcEnv(swissRain, lograin ~ 1, obj.var=swissv,nsim=9)
if(!is.null(swissv)){
plot(swissv, env=swissEnv, main = "Swiss variogram")
}
```

wheat 41

wheat

Mercer and Hall wheat yield data

Description

Mercer and Hall wheat yield data, based on version in Cressie (1993), p. 455.

Usage

```
data(wheat)
```

Format

wheat is a raster where the values refer to wheat yields.

```
data("wheat")
wheat = unwrap(wheat)
plot(wheat, main="Mercer and Hall Data")
```

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