Crash Introduction to markovchain R package

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Intro

- ► The markovchain package (Spedicato 2016) will be introduced.
- ► The package is intended to provide S4 classes to perform probabilistic and statistical analysis of Discrete Time Markov Chains (DTMC). See (Brémaud 1999) for a theoretical review of the mathematics underlying the DTMC models.
- ► The vignette will show: how to load the package and create a DTMC, how to manage a DTMC, how to perform basic probabilistic analysis, how to fit a DTMC.

- ▶ The package is on Cran since Summer 2013.
- ▶ It requires a recent version of R (>=3.0). Since version 0.2 parts of code have been moved to Rcpp (Eddelbuettel 2013).
- ► The package won a slot in Google Summer of Code 2015 for optimizing internals and expanding functionalities.

First moves into the markovchain package

Loading the package

► The package is loaded using

```
#load the package
library(markovchain)
```

Creating a DTMC

▶ DTMC can be easily create following standard S4 classes syntax. The show method displays it.

```
## MarkovChain A
## A 3 - dimensional discrete Markov Chain defined by the
## a, b, c
## The transition matrix (by rows) is defined as follows
## a b c
## a 0.0 0.5 0.5
## b 0.5 0.0 0.5
## c 0.5 0.5 0.0
```

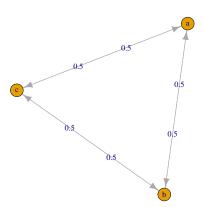
▶ Otherwise, it can also be created directly coercing a matrix.

```
dtmcA2<-as(tmA, "markovchain") #using coerce from matrix
states(dtmcA2) #note default names assigned to states</pre>
```

```
## [1] "s1" "s2" "s3"
```

▶ It is also possible to display a DTMC, using igraph package (Csardi and Nepusz 2006) capabilities

plot(dtmcA)



Probabilistic analysis

The basic

- It is possible to access transition probabilities and to perform basic operations.
- ▶ Similarly, it is possible to access the conditional distribution of states, $Pr(X_{t+1}|X_t = s)$

```
dtmcA[2,3] #using [ method
```

```
## [1] 0.5
```

[1] 0.5

```
conditionalDistribution(dtmcA, "b")
```

▶ It is possible to simulate states distribution after n-steps

```
initialState<-c(0,1,0)
steps<-4
finalState<-initialState*dtmcA^steps #using power operator
finalState</pre>
```

```
## a b c
## [1,] 0.3125 0.375 0.3125
```

As well as steady states distribution

```
steadyStates(dtmcA) #S4 method
```

```
## a b c
## [1,] 0.3333333 0.3333333 0.3333333
```

Advanced

► We use an example found on Mathematica Web page, (Wolfram Research 2013)

The summary method shows the proprieties of the DTCM

summary(mcMathematica)

```
## Mathematica Markov chain that is composed by:
## Closed classes:
## a b c d
## Recurrent classes:
## {a,b,c,d}
## Transient classes:
## NONE
## The Markov chain is irreducible
## The absorbing states are: NONE
```

Estimation and simulation

The package permits to fit a DTMC estimating the transition matrix from a sequence of data. - createSequenceMatrix returns a function showing previous vs actual states from the pairs in a given sequence.

```
#using Alofi rainfall dataset
data(rain)
mysequence<-rain$rain
createSequenceMatrix(mysequence)</pre>
```

```
## 0 1-5 6+
## 0 362 126 60
## 1-5 136 90 68
## 6+ 50 79 124
```

markovchainFit function allows to obtain the estimated transition matric and the confidence levels (using elliptic MLE hyphotesis).

```
myFit<-markovchainFit(data=mysequence,confidencelevel = .9;
myFit</pre>
```

```
## $estimate

## MLE Fit

## A 3 - dimensional discrete Markov Chain defined by the

## 0, 1-5, 6+

## The transition matrix (by rows) is defined as follows

## 0 1-5 6+

## 0 0.6605839 0.2299270 0.1094891

## 1-5 0.4625850 0.3061224 0.2312925

## 6+ 0.1976285 0.3122530 0.4901186

##
```

\$standardError

##

0 1-5 (6+ (3) (2) (2) (4)

See the vignettes for further fitting methods as well as for functionalities targeted on non - homogeneous Markov chains.

```
alofiMc<-myFit$estimate
alofiMc</pre>
```

```
## MLE Fit

## A 3 - dimensional discrete Markov Chain defined by the

## 0, 1-5, 6+

## The transition matrix (by rows) is defined as follows

## 0 1-5 6+

## 0 0.6605839 0.2299270 0.1094891

## 1-5 0.4625850 0.3061224 0.2312925

## 6+ 0.1976285 0.3122530 0.4901186
```

Bibliography I

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Csardi, Gabor, and Tamas Nepusz. 2006. "The Igraph Software Package for Complex Network Research." *InterJournal* Complex Systems: 1695. http://igraph.sf.net.

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