mme: a package for small area estimation with multinomial mixed models

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Abstract

The mme package for R (R Development Core Team 2010) implements three multinomial area level mixed models for small area estimation. The first model is the area level multinomial mixed model with independent random effects for each category of the response variable (López-Vizcaíno, Lombardía, and Morales 2013a). The second model takes advantage from the availability of survey data from different time periods and uses a multinomial model with independent random effects for each category of the response variable and with independent time and domain random effects. The third model is similar to the second one, but with correlated time and domain random effects (López-Vizcaíno, Lombardía, and Morales 2013b). In all the models the package uses two approaches to estimate the mean square error (MSE), first through an analytical expression and second by bootstrap techniques.

Keywords: small area, R package, multinomial mixed models...

1. Overview

Small area estimation problems appear when the domain simple sizes are small and direct estimates are not precise. In the small area estimation context, an estimator of a parameter in a given domain is direct if it is based only on the sample data of the specific domain. A drawback of these estimators is that they cannot be calculated when there is no sample observations in an area of interest.

Generally small area estimation techniques can be divided into design-based methods and model-based methods. The model-based methods make inference by taking into account the underlying model. The estimators based on these methods are useful because they give to practitioners an idea of how the data generation process is and how the different sources of information are incorporated. Mixed models are suitable for small area estimation due to its flexibility to make an effective combination of different sources of information and to its capacity to describe the various sources of error. These models incorporate random area effects that explain the additional variability that is not explained by the fixed part of the model.

The objective of this manuscript is to present a R package that implements three multinomial area level mixed models for small area estimation. The first model is the area level multinomial mixed model with independent random effects for each category of the response variable (López-Vizcaíno et al. 2013a). The second model takes advantage from the availability of survey data from different time periods and uses a multinomial model with independent random effects for each category of the response variable and with independent time and

domain random effects. The third model is similar to the second one, but with correlated time and domain random effects (López-Vizcaíno et al. 2013b). In all the models the package use two approaches to estimate the mean square error (MSE), first through an analytical expression and second by bootstrap techniques.

2. Models

Let us start by giving some notation and assumptions. Let us use indexes k = 1, ..., q - 1, d = 1, ..., D and t = 1, ..., T for the categories of the target variable, for the D domains and for the T time periods respectively. Let $u_{1,dk}$ and $u_{2,dkt}$ be the random effects associated to the domain d and the category k and to the domain d, the category k and the time instant t respectively. In the third model (Model 3) we write the random effects in the form

$$\begin{array}{rcl} \boldsymbol{u}_1 & = & \mathop{\mathrm{col}}_{1 \leq d \leq D}(\boldsymbol{u}_{1,d}), & \boldsymbol{u}_{1,d} = \mathop{\mathrm{col}}_{1 \leq k \leq q-1}(u_{1,dk}), & \boldsymbol{u}_2 = \mathop{\mathrm{col}}_{1 \leq d \leq D}(\boldsymbol{u}_{2,d}) \\ \boldsymbol{u}_{2,d} & = & \mathop{\mathrm{col}}_{1 \leq k \leq q-1}(\boldsymbol{u}_{2,dk}), & \boldsymbol{u}_{2,dk} = \mathop{\mathrm{col}}_{1 \leq t \leq T}(u_{2,dkt}), & \boldsymbol{u}_{2,dt} = \mathop{\mathrm{col}}_{1 \leq k \leq q-1}(u_{2,dkt}), \end{array}$$

and we suppose that

- 1. u_1 and u_2 are independent,
- 2. $u_1 \sim N(\mathbf{0}, \mathbf{V}_{u_1})$, where $\mathbf{V}_{u_1} = \underset{1 \leq d \leq D}{\text{diag}} (\underset{1 \leq k \leq q-1}{\text{diag}} (\varphi_{1k})), k = 1, \dots, q-1.$
- 3. $\boldsymbol{u}_{2,dk} \sim N(\boldsymbol{0}, \boldsymbol{V}_{u_{2,dk}}), d=1,\ldots,D, k=1,\ldots,q-1,$ are independent with covariance matrix AR(1), i.e. $\boldsymbol{V}_{u_{2,dk}} = \varphi_{2k}\Omega_d(\phi_k)$ and

$$\Omega_{d}(\phi_{k}) = \Omega_{d,k} = \frac{1}{1 - \phi_{k}^{2}} \begin{pmatrix} 1 & \phi_{k} & \dots & \phi_{k}^{T-2} & \phi_{k}^{T-1} \\ \phi_{k} & 1 & \ddots & & \phi_{k}^{T-2} \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \phi_{k}^{T-2} & & \ddots & 1 & \phi_{k} \\ \phi_{k}^{T-1} & \phi_{k}^{T-2} & \dots & \phi_{k} & 1 \end{pmatrix}_{T \times T}$$

It holds that $\boldsymbol{V}_u = \text{var}(\boldsymbol{u}) = \text{diag}(\boldsymbol{V}_{u_1}, \boldsymbol{V}_{u_2})$, where $\boldsymbol{V}_{u_2} = \text{var}(\boldsymbol{u}_2) = \text{diag}(\text{diag}_{1 \leq d \leq D} (\boldsymbol{V}_{u_2,dk}))$. We also assume that the response vectors $\boldsymbol{y}_{dt} = \underset{1 \leq k \leq q-1}{\text{col}}(y_{dkt})$, conditioned to $\boldsymbol{u}_{1,d}$ and $\boldsymbol{u}_{2,dt}$, are independent with multinomial distributions

$$y_{dt}|_{u_{1,d},u_{2,dt}} \sim M(\nu_{dt}, p_{d1t}, \dots, p_{dq-1t}), \ d = 1, \dots, D, \ t = 1, \dots, T.$$
 (1)

where the ν_{dt} 's are known integer numbers. The covariance matrix of \boldsymbol{y}_{dt} conditioned to $\boldsymbol{u}_{1,d}$ and $\boldsymbol{u}_{2,dt}$ is $\operatorname{var}(\boldsymbol{y}_{dt}|\boldsymbol{u}_{1,d},\boldsymbol{u}_{2,dt}) = \boldsymbol{W}_{dt} = \nu_{dt}[\operatorname{diag}(\boldsymbol{p}_{dt}) - \boldsymbol{p}_{dt}\boldsymbol{p}_{dt}']$, where $\boldsymbol{p}_{dt} = \operatorname{col}_{1 \leq k \leq q-1}(p_{dkt})$ and $\operatorname{diag}(\boldsymbol{p}_{dt}) = \operatorname{diag}_{1 \leq k \leq q-1}(p_{dkt})$. For the natural parameters $\eta_{dkt} = \log \frac{p_{dkt}}{p_{dqt}}$, we assume the model

$$\eta_{dkt} = \mathbf{x}_{dkt} \boldsymbol{\beta}_k + u_{1,dk} + u_{2,dkt}, \quad d = 1, \dots, D, \ k = 1, \dots, q - 1, \ t = 1, \dots, T,$$
(2)

where
$$\mathbf{x}_{dkt} = \underset{1 \le r \le p_r}{\text{col}'}(x_{dktr}), \, \boldsymbol{\beta}_k = \underset{1 \le r \le p_k}{\text{col}}(\beta_{kr}) \text{ and } p = \sum_{k=1}^{q-1} p_k.$$

We also consider two simpler models. Model 2 is the restriction of Model 3 to $\phi_1 = \ldots = \phi_{q-1} = 0$. Model 1 is obtained by restricting Model 2 to one time period (T=1) and by considering only the random effect u_1 . This is the model studied by López-Vizcaíno *et al.* (2013a). For the sake of brevity we skip formulas for Models 1-2. In matrix notation, Model 3 is

$$\boldsymbol{\eta} = \boldsymbol{X}\boldsymbol{\beta} + \boldsymbol{Z}_1\boldsymbol{u}_1 + \boldsymbol{Z}_2\boldsymbol{u}_2 = \boldsymbol{X}\boldsymbol{\beta} + \boldsymbol{Z}\boldsymbol{u},$$
 where $\boldsymbol{Z} = (\boldsymbol{Z}_1', \boldsymbol{Z}_2')', \boldsymbol{\eta} = \underset{1 \leq d \leq D}{\operatorname{col}}(\boldsymbol{\eta}_d), \boldsymbol{X} = \underset{1 \leq d \leq D}{\operatorname{col}}(\boldsymbol{X}_d), \boldsymbol{Z}_1 = \underset{1 \leq d \leq D}{\operatorname{diag}}(\boldsymbol{Z}_{1d}), \boldsymbol{Z}_2 = \underset{1 \leq d \leq D}{\operatorname{diag}}(\boldsymbol{Z}_{2d}),$
$$\boldsymbol{\eta}_d = \underset{1 \leq k \leq q-1}{\operatorname{col}}(\underset{1 \leq t \leq T}{\operatorname{col}}(\eta_{dkt})), \quad \boldsymbol{X}_d = \underset{1 \leq k \leq q-1}{\operatorname{diag}}(\underset{1 \leq t \leq T}{\operatorname{col}}(\boldsymbol{x}_{dkt})), \quad \boldsymbol{\beta} = \underset{1 \leq k \leq q-1}{\operatorname{col}}(\boldsymbol{\beta}_k),$$

$$\boldsymbol{Z}_{1d} = \underset{1 \leq k \leq q-1}{\operatorname{diag}}(\boldsymbol{1}_T), \quad \boldsymbol{Z}_{2d} = \underset{1 \leq k \leq q-1}{\operatorname{diag}}(\underset{1 \leq t \leq T}{\operatorname{diag}}(1)) = \boldsymbol{I}_{T(q-1)}, \quad \boldsymbol{1}_T = \underset{1 \leq t \leq T}{\operatorname{col}}(1).$$

To fit the model we combine the PQL method, introduced by Breslow and Clayton (1996) for estimating and predicting the β_{kr} 's, the $u_{1,dk}$'s and the $u_{2,dkt}$'s, with the REML method for estimating the variance components φ_{1k} , φ_{2k} and φ_k , $k = 1, \ldots, q - 1$. The presented method is based on a normal approximation to the joint probability distribution of the vector $(\boldsymbol{y}, \boldsymbol{u})$. The combined algorithm was first introduced by Schall (1991) and later used by Saei and Chambers (2003), Molina, Saei, and Lombardía (2007) and Herrador, Morales, Esteban, Sánchez, Santamaría, Marhuenda, Pérez, and Molina (2009) in applications of generalized linear mixed models to small area estimation problems. We adapt the combined algorithm to Model 3. The algorithm has two parts. In the first part the algorithm updates the values of β , u_1 and u_2 . In the second part it updates the variance components.

For the estimation of the mean squared error (MSE) of model-based small area estimators we adapt the resampling approaches appearing in González-Manteiga, Lombardía, Molina, Morales, and Santamaría (2008) to introduce a parametric bootstrap procedure. We also give an approximation to the MSE based on a Taylor linearization. By applying the ideas of (Prasad and Rao 1990) to the linearized model, the MSE is approximated and an estimator of the given approximation is derived.

3. The package mme

In the mme package we introduced a range of new functions that may be of interest to those conducting applied research. The nine principal new functions are summarized in Table 1. In what follows we provide illustrative examples of the use of the functions describe in Table 1. Many of these functions rely on numerical integration and can be computationally demanding.

4. Example to fit model 1

The following code provides and example to fit the model 1. It is necessary to use a data frame with this variables: area indicator, time indicator, sample, population, categories of the response variable and covariates of each category of the response variable. The package requires two imput parameters: pp is a vector with the number of auxiliary variables in each

Function	Description	Reference
data.mme	Based on the input data this function gener-	López-Vizcaíno et al. (2013a)
	ates some matrices that are required in sub-	
	sequent calculations and the initial values for	
	the fitting algorithm	
fitmodel1	This function fits the multinomial mixed	López-Vizcaíno et al. (2013a)
	model with one independent random effect per	
	category of the response variable (Model 1)	
fitmodel2	This function fits the multinomial mixed	López-Vizcaíno et al. (2013b)
	model with two independent random effects	
	for each category of the response variable: one	
	domain random effect and another indepen-	
	dent time and domain random effect (Model	
	2)	
fitmodel3	This function fits the multinomial mixed	López-Vizcaíno et al. (2013b)
	model with two independent random effects	
	for each category of the response variable: one	
	domain random effect and another correlated	
	time and domain random effect (Model 3)	
model	This function chooses one of the three models	López-Vizcaíno et al. (2013a) and
		López-Vizcaíno et al. (2013b)
msef	This function calculates the analytic MSE for	López-Vizcaíno et al. (2013a)
	Model 1	
msef.it	This function calculates the analytic MSE for	López-Vizcaíno et al. (2013a)
	Model 2	
msef.ct	This function calculates the analytic MSE for	López-Vizcaíno et al. (2013b)
	Model 3	. , ,
mseb	This function calculates the bias and the MSE	López-Vizcaíno et al. (2013a) and
	for the multinomial mixed effects models using	López-Vizcaíno et al. (2013b)
	parametric bootstrap	

Table 1: New mme functions.

category and k is the number of categories of the response variable. The example uses a data frame with 50 small areas and with 10 periods. However, this example only works with the last period. The response variable has three categories (k=3), and we use one covariate for each category, then pp=c(1,1). The last three columns of the data frame contain the direct estimators of the categories of the response variable.

```
R> datos=as.data.frame(datos)
R> names(datos)

[1] "area"    "time"    "sample"    "population" "y1"
[6] "y2"    "y3"    "x1"    "x2"    "y11"
[11] "y22"    "y33"
```

R> datos1=subset(datos,datos\$time==10)

R> dat=datos1[,1:9]

R> library(mme)

R> k=3 #number of categories of the response variable

```
R>pp=c(1,1) #vector with the number of auxiliary variables in each category
```

R > mod=1 # Model 1

R> #Needed matrix and initial values

R> datar=data.mme(dat,k,pp,mod)

R> #Model fit

R> result=model(datar\$d,datar\$t,pp,datar\$Xk,datar\$X,datar\$Z,datar\$initial,

+ datar\$y[,1:(k-1)],datar\$n,datar\$N,mod)

R> result

Multinomial mixed effects model

Call:

Coefficients

	Estimate	Std.Error	p.value
Intercept	1.817	2.17	0.401
x1	-1.388	1.61	0.387
Intercept	-0.927	2.99	0.756
x2	0.600	1.73	0.729

Random effects

Estimate Std.Error p.value
[1,] 0.975 0.226 0
[2,] 2.541 0.550 0

R> #Fixed effects

R> result\$beta.Stddev.p.value

	Estimate	Std.Error	p.value
Intercept	1.817	2.17	0.401
x1	-1.388	1.61	0.387
Intercept	-0.927	2.99	0.756
x2	0.600	1.73	0.729

R> #Random effects

R> result\$phi.Stddev.p.value

```
Estimate Std.Error p.value
[1,] 0.975 0.226 1.56e-05
[2,] 2.541 0.550 3.83e-06
```

R> #Direct estimators

R> dir1=datos1\$y11

R> dir2=datos1\$y22

R>

The following code will generate Figure 1 that plots direct estimators versus model estimators.

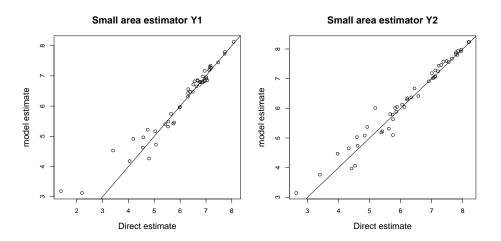


Figure 1: Model estimates versus direct estimates.

```
R> #Model estimator
R> datos1$yest1=result$mean[,1]
R> datos1$yest2=result$mean[,2]
```

The following code generates Figure 2 that plots direct estimators and model estimators sorted by sample size.

```
R> #Plot direct estimators and model estimators sorted by sample size
R> dos.ver<-matrix(1:2,1,2)
R> layout(dos.ver)
R> a=datos1[order(datos1[,3]),]
R> g_range <- range(0,45)
R> plot(a$y11/1000,type="b", col="blue",axes=FALSE, ann=FALSE)
R> lines(a$yest1/1000,type="b",pch=4, lty=2, col="red")
R> title(xlab="Sample size")
R> axis(1,at=c(1,10,20,30,40,50),lab=c(a$sample[1],a$sample[10],
```

```
+ a$sample[20],a$sample[30],a$sample[40],a$sample[50]))
R> axis(2, las=1, at=1*0:g_range[2])
R> legend("topleft", c("Direct", "Model"), cex=1, col=c("blue", "red"),
+ lty=1:2,pch=c(1,4), bty="n")
R> title(main="Small area estimator Y1", font.main=1.2,cex.main=1)
R> plot(a$y22/1000,type="b",col="blue",axes=FALSE, ann=FALSE)
R> lines(a$yest2/1000,type="b",pch=4, lty=2, col="red")
R> title(xlab="Sample size")
R> axis(1,at=c(1,10,20,30,40,50),lab=c(a$sample[1],a$sample[10],
+ a$sample[20],a$sample[30],a$sample[40],a$sample[50]))
R> axis(2, las=1, at=1*0:g_range[2])
R> legend("topleft", c("Direct", "Model"), cex=1, col=c("blue", "red"),
+ lty=1:2,pch=c(1,4), bty="n")
R> title(main="Small area estimator Y2", font.main=1.2,cex.main=1)
```

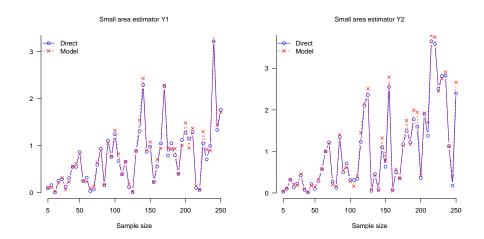


Figure 2: Model estimator and direct estimator sorted by sample size.

The following code calculates the parametric bootstrap BIAS and MSE for the model-based estimators.

```
R> ##Bootstrap parametric BIAS and MSE
R>
R> B=10  #Bootstrap iterations
R> ss=12345 #SEED
R> set.seed(ss)
R> mse.pboot=mseb(pp,datar$Xk,datar$X,datar$Z,datar$n,datar$N,result,B,mod)
R> cv=mse.pboot[[3]]
R>
```

The following code generates Figure 3 that plots the root mean squared error (RMSE) of the model-based estimates.

```
R> dos.ver<-matrix(1:2,1,2)</pre>
R> layout(dos.ver)
R> g_range <- range(0,45)</pre>
R> plot(cv[,1],type="b", col="blue",axes=FALSE, ann=FALSE)
R> title(xlab="Sample size")
R > axis(1,at=c(1,10,20,30,40,50),lab=c(a$sample[1],a$sample[10],
+ a$sample[20],a$sample[30],a$sample[40],a$sample[50]))
R> axis(2, las=1, at=10*0:g_range[2])
R> title(main="RMSE for the estimator of Y1", font.main=1.2,cex.main=1)
R> g_range <- range(0,45)</pre>
R> plot(cv[,2],type="b",col="blue",axes=FALSE, ann=FALSE)
R> title(xlab="Sample size")
R > axis(1,at=c(1,10,20,30,40,50),lab=c(a\$sample[1],a\$sample[10],
+ a$sample[20],a$sample[30],a$sample[40],a$sample[50]))
R> axis(2, las=1, at=10*0:g_range[2])
R> title(main="RMSE for the estimator of Y2", font.main=1.2,cex.main=1)
R>
```

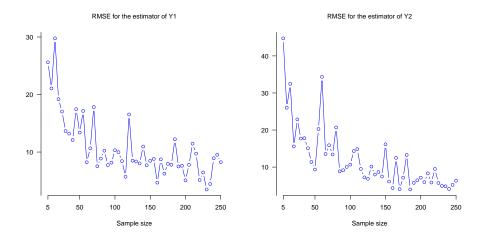


Figure 3: RMSE of model-based estimates

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