Use of the package nlstools to help the fit and assess the quality of fit of a gaussian nonlinear model

Marie Laure Delignette-Muller and Florent Baty

December 2012

The package nlstools provides several tools that help to fit of a gaussian nonlinear model [1] using the fonction nls and to assess its quality of fit.

$$y = f(\theta, x) + \varepsilon, \quad \varepsilon \sim \mathcal{N}(0, \sigma)$$

The aim of this document is to provide examples showing how to use these tools that help to fit a model to data using the fonction nls, to check the validity of the assumptions of the model, to assess its quality of fit, to evaluate the precision of parameters estimates by use of confidence intervals or regions, ... For details, see the documentation of each function, using the R help command (e.g. ?nlsResiduals). Do not forget to load the library using the function library before testing the following examples.

> library(nlstools)

Contents

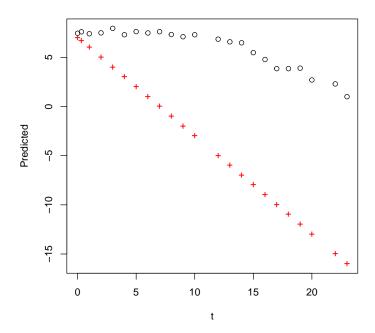
1	Help	o to fit a model	2
	1.1	to fit a model Help to define starting values for parameters	2
	1.2		4
2	Analysis of residuals		
	2.1	Graphics of residuals	7
	2.2	Residuals tests	8
3	Confidence region		
	3.1	Residual sum of squares contours or likelihood contours	9
	3.2	Projections of the 95 percent Beale's confidence region	9
	3.3		13
4	Resampling 14		
	4.1	Jackknife	14
	4.2	Bootstrap	15

1 Help to fit a model

1.1 Help to define starting values for parameters

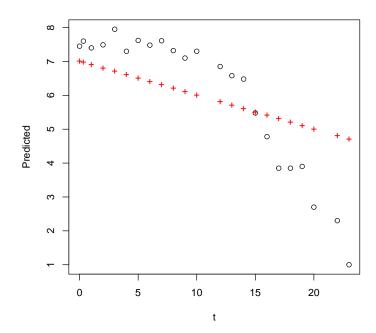
To fit a nonlinear model, it is necessary to specify starting estimates for parameters. The function preview may be used to facilitate the choice of these values. It provides a superimposed plot of observed (black circles) and predicted (red crosses) values of the dependent variable versus one of the independent variables with the model evaluated at specified values of the parameters. The residual sum-of-squares (RSS) give an indication of the distance between observed and predicted values (the lower, the better). It is then easy to use it repeatedly to reach a good approximation of the starting estimates as in the following example. This example uses a dataset and a model available in the package nlstools.

• First iteration with arbitrary values of parameters



• Second iteration with adjusted values of parameters

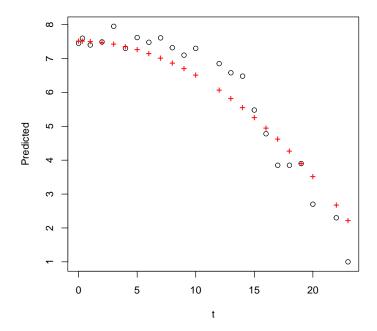
RSS: 45.1



 \bullet Last iteration with reasonable approximate values of parameters

> preview(formula = mafart, data = survivalcurve2, start = list(p = 2, delta = 10, LOG10N0 = 7.5))

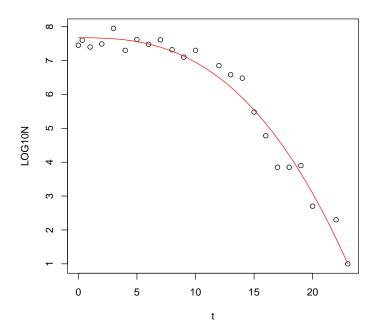
RSS: 7.11



1.2 Fit and plot of fit

When reasonable starting estimates are available for parameters, the model may be fitted using the function nls, and the fitted model may be plotted together with the observed data points using the function plotfit. Its argument smooth enables to draw a smooth line for the fitted model.

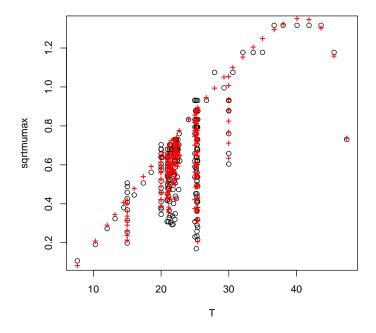
```
> nlsmaf <- nls(mafart, survivalcurve2, list(p = 2, delta = 10,
+ LOG10N0 = 7.5))
> plotfit(nlsmaf, smooth = TRUE)
```



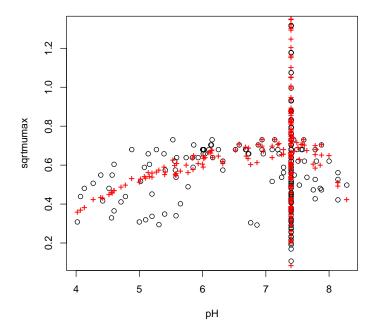
Previous example uses a model predefined in nlstools. However, any model may be fitted by explicitly defining its formula. Beware that the names of variables in the model formula must exactly match those in the dataset.

```
> model <- LOG10N ~ LOG10N0 - (t/delta)^p
> nlsmaf <- nls(model, survivalcurve2, list(p = 2, delta = 10,
+ LOG10N0 = 7.5))</pre>
```

For the plot of a model with more than one independent variable, it is necessary to specify the argument variable of the function plotfit to indicate which variable is plotted on the x-axis. In that case, it is not possible to use the argument smooth to plot a smooth line for the fitted model. In the following example, a model with 4 independent variables is fitted and the dependent variable is plotted first versus the first independent variable, and then versus the second one.



> plotfit(nls6, variable = 2)



An extended summary of the fit (giving more information than $\mathtt{summary(nls)}$)

```
may be printed using the function {\tt overview}, as below.
```

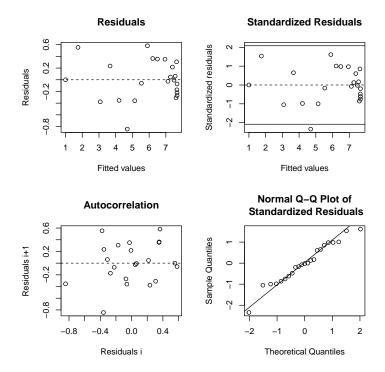
```
> overview(nlsmaf)
Formula: LOG10N ~ LOG10N0 - (t/delta)^p
Parameters:
        Estimate Std. Error t value Pr(>|t|)
                     0.2256
          2.6690
                              11.83 1.75e-10 ***
р
        11.2956
                     0.6477
delta
                              17.44 1.45e-13 ***
LOG10N0
         7.6717
                     0.1269
                              60.44 < 2e-16 ***
Signif. codes: 0 '*** 0.001 '** 0.01 '* 0.05 '.' 0.1 ' ' 1
Residual standard error: 0.3601 on 20 degrees of freedom
Number of iterations to convergence: 7
Achieved convergence tolerance: 6.195e-06
Residual sum of squares: 2.59
t-based confidence interval:
            2.5%
                     97.5%
        2.198435 3.139585
delta
       9.944589 12.646691
LOG10NO 7.406874 7.936456
Correlation matrix:
                        delta
                                 LOG10N0
        1.0000000 0.9687776 -0.6264922
р
        0.9687776 1.0000000 -0.7327828
delta
LOG10NO -0.6264922 -0.7327828 1.0000000
```

2 Analysis of residuals

2.1 Graphics of residuals

Several plots may help to check the validity of the assumptions of the error model based on the analysis of residuals. The plot of the result of the function nlsResiduals provides, by default, four classic plots of residuals (see following example): non-transformed residuals against fitted values, standardized residuals against fitted values, auto-correlation plot of residuals (i+1th residual against ith residual), and qq-plot of the residuals. See ?nlsResiduals to have more details or view other possibilities.

```
> resmaf <- nlsResiduals(nlsmaf)
> plot(resmaf)
```



2.2 Residuals tests

The normality of residuals may be tested by the Shapiro-Wilk test and their independence by the runs test using the function test.nlsResiduals as below.

```
> test.nlsResiduals(resmaf)
```

Shapiro-Wilk normality test

data: stdres

W = 0.96798, p-value = 0.6407

Runs Test

data: as.factor(run)

Standard Normal = -0.20455, p-value = 0.8379

alternative hypothesis: two.sided

3 Confidence region

The package nltools provides two different methods for the representation of $1 - \alpha$ confidence region for model parameters as defined by Beale [1, 2]:

$$SCE(\theta) < SCE_{min} \left[1 + \frac{p}{n-p} F_{1-\alpha}(p, n-p) \right]$$

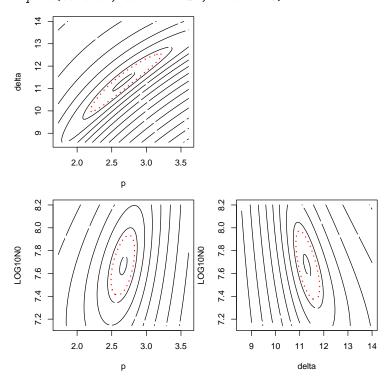
The function nlsContourRSS provides sections of that confidence region on each plane defined by two parameters, while the function nlsConfRegions provides projections of that region on the same planes.

3.1 Residual sum of squares contours or likelihood contours

The function nlsContourRSS enables to plot the Residual Sum of Squares (RSS) contours which also correspond to the likelihood contours for a Gaussian model. One of these contours, plotted in red, corresponds to the section of the 95 percent Beale's confidence region in each plane of two parameters. The argument nlev corresponds to the number of contours to be plotted, in addition to the red one.

> contmaf <- nlsContourRSS(nlsmaf)</pre>

> plot(contmaf, col = FALSE, nlev = 10)



3.2 Projections of the 95 percent Beale's confidence region

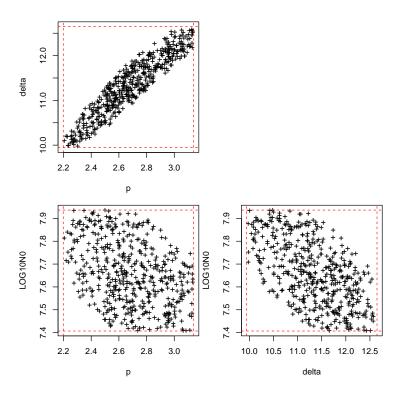
A second method is proposed to represent the 95 percent Beale's confidence region, also named the joint parameter likelihood region [1]. This method first

requires to sample points belonging to this region. The method consists in randomly sampling the parameter values in a hypercube centered on the least squares estimate and to accept only the sampled values whose residual sum of squares verify the Beale criterion. As soon as the specified number of points to draw in the confidence region is reached (corresponding to the argument length of the function nlsConfRegions), the iterative sampling is stopped. The algorithm does converge to the confidence region in a reasonable time only if the hypercube defined for sampling is not to small, in order to contain the whole confidence region, but also not too big, so that the probability of a sampling point to be in the confidence region is not too small.

The confidence region is then plotted by projection of the sampled points in each plane defined by a couple of parameters. The bounds of the hypercube in which random values of parameters are drawn may be plotted in order to check if the true confidence region is totally included in the hypercube defined by default. If not, the hypercube should be expanded (by increasing the argument exp, fixed by default at 1.5) in order to obtain the full confidence region. It is often necessary to make two or three trials for adjusting the value of the argument exp in order to obtain enough points in the whole confidence region in a reasonable time, as in the next example.

In this example, the function nlsConfRegions is first called with the argument exp fixed at 1, which corresponds to a hypercube delimited by the limits of the asymptotic confidence intervals of each parameter. The obtained region is then plotted, fixing the argument bounds at TRUE in order to visualize the sampling hypercube.

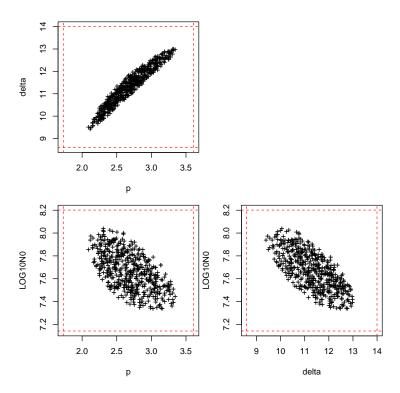
```
> rcmaf <- nlsConfRegions(nlsmaf, length = 500, exp = 1)
> plot(rcmaf, bounds = T)
```



Since the whole region does not seem to be included in the sampling hypercube, the function nlsConfRegions is recalled with the argument exp fixed at 2.

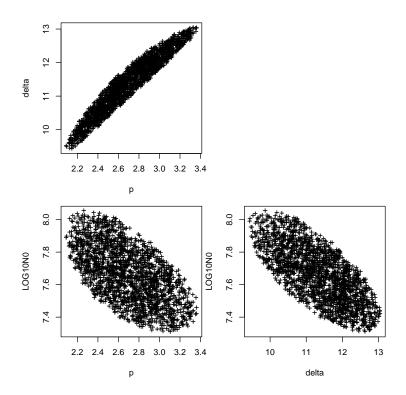
```
> rcmaf <- nlsConfRegions(nlsmaf, length = 500, exp = 2)
```

> plot(rcmaf, bounds = T)



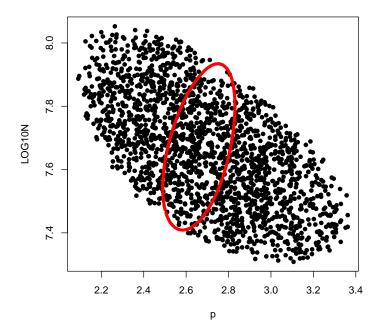
This value of the argument exp seems reasonable. The function nlsConfRegions may be recalled specifying a greater number of points drawn in the region (argument length), and the region may be plotted without showing the bounds of the hypercube.

- > rcmaf <- nlsConfRegions(nlsmaf, length=2000, exp=2)
- > plot(rcmaf, bounds = F)



3.3 Comparison of both representations of the confidence region

It must be noticed that the representation of the confidence region in sections using nlsContourRSS does not give the same information as its representation by projections using nlsConfRegions when the number of parameters is greater than two. Sections of multidimensional (at least 3D) objects are smaller than projections and the representation of a confidence region in sections tends to underestimate its size in comparison to its representation by projections. The perception of structural correlations between parameters from graphical representation of the confidence region may also be very different between both representations. Let us see below such a difference with the previous example, for which both the section and the projection of the confidence region was plotted on the same plane.



We recommend to use the representation of RSS contours to detect non linearities and/or the presence of more than one minimum in the neighbourhood of the estimate, and the representation of projections of the confidence region to evaluate the uncertainty on the estimated parameters and to judge of their structural correlations.

4 Resampling

4.1 Jackknife

The function nlsJack may be used to obtain, for a data set with n observations, n resampled data sets of n-1 observations and the n corresponding new estimations for each parameter of the model. The jackknife estimates with confidence intervals are then calculated as described by Seber and Wild [3].

p 2.632607 0.036402594 delta 11.260269 0.035370606 LOG10N0 7.669289 0.002376069

```
Jackknife confidence intervals

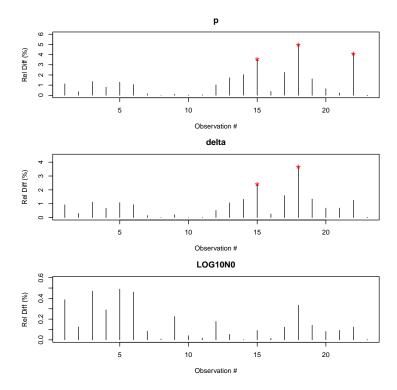
Low Up
p 2.155147 3.110067
delta 9.916903 12.603636
LOG10N0 7.497482 7.841096
```

Influential values

- * Observation 15 is influential on p
- * Observation 18 is influential on p
- * Observation 22 is influential on p
- * Observation 15 is influential on delta
- * Observation 18 is influential on delta

The leave-one-out procedure may also be employed to assess the influence of each observation on each parameter estimate, as in the end of the previous summary or in the following representation.

> plot(jackmaf)



4.2 Bootstrap

The function nlsBoot uses non-parametric bootstrapping of mean centered residuals [3] to obtain a chosen number (argument niter) of bootstrap estimates. Ponctual estimations (resp. confidence intervals) of parameters are then provided using medians (resp. the 2.5 and 97.5 percentiles) of the bootstrap sample of estimates.

```
> boomaf <- nlsBoot(nlsmaf, niter = 2000)</pre>
```

> summary(boomaf)

Bootstrap statistics

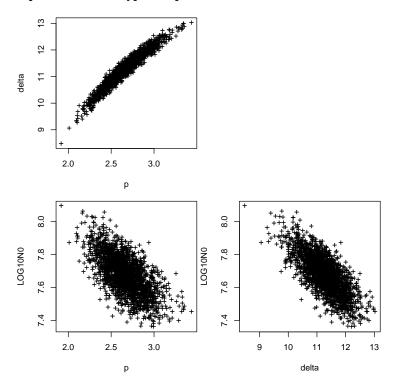
Estimate Std. error p 2.662847 0.2057592 delta 11.254373 0.5978501 LOG10N0 7.677784 0.1174085

Median of bootstrap estimates and percentile confidence intervals

Median2.5%97.5%p2.6582672.2744273.064734delta11.27574610.03375312.369891LOG10N07.6770287.4533177.908328

The boostrap sample of estimates may be visualized by projection on each plane defined by a couple of parameters, as below. This representation is generally close to the representation of the 95 percent Beale's confidence region provided by nlsConfRegions.

> plot(boomaf, type = "pairs")



References

- [1] Bates D.M. and Watts D.G. (1988) Nonlinear regression analysis and its applications. Wiley, Chichester, UK.
- [2] Beale E.M.L. (1960) Confidence regions in non-linear estimations. *Journal of the Royal Statistical Society*, 22B, 41-88.
- [3] Seber G.A.F., Wild C.J. (1989) Nonlinear regression. Wiley, New York.
- [4] Huet S., Bouvier A., Poursat M.A., Jolivet E. (2003) Statistical tools for nonlinear regression: a practical guide with S-PLUS and R examples. Springer, Berlin, Heidelberg, New York.