Introduction to package nngeo

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Contents

Introduction
Package purpose
Installation
Sample data
Usage examples
The st_nn function
The st_connect function
Dense matrix representation
k-Nearest neighbors where k>0
Distance matrix
Search radius
Spatial join
Another example
Polygons

Introduction

Package purpose

This document introduces the nngeo package. The nngeo package includes functions for spatial join of laters based on *k-nearest neighbor* relation between features. The functions work with spatial layer object defined in package sf, namely classes sfc and sf.

Installation

GitHub version -

```
install.packages("devtools")
devtools::install_github("michaeldorman/nngeo")
```

Sample data

The nngeo package comes with three sample datasets -

- cities
- towns
- water

The cities layer is a **point** layer representing the location of the three largest cities in Israel.

The towns layer is another **point** layer, with the location of all towns in Israel whose name begins with the letter A.

```
#> Simple feature collection with 93 features and 1 field
#> geometry type: POINT
#> dimension:
                 XY
                 xmin: 34.3309 ymin: 30.96493 xmax: 35.83863 ymax: 33.17806
#> bbox:
#> epsq (SRID):
                4326
#> proj4string:
                 +proj=longlat +datum=WGS84 +no_defs
#> First 10 features:
#>
                      geometry
                                                  name
                                               ALUMMOT
#> 1 POINT (35.54639 32.70683)
#> 2 POINT (35.12573 31.65512)
                                         ALLON SHEVUT
#> 3 POINT (35.18041 33.04801)
                                                AVDON
#> 4 POINT (35.48441 32.81265)
                                                 ARBEL
     POINT (35.5824 32.66228) ASHDOT YA'AQOV(ME'UHAD)
#> 6 POINT (35.33804 32.85159)
                                                ARRABE
#> 7 POINT (35.25207 32.866)
                                         ATSMON SEGEV
#> 8 POINT (35.22568 33.08865)
                                               ARAMSHA
#> 9 POINT (35.4369 31.67897)
                                                A VENAT
#> 10 POINT (34.90936 31.89039)
                                                AZARYA
```

The water layer is an example of a **polygonal** layer. This layer contains four polygons of water bodies in Israel.

```
water
#> Simple feature collection with 4 features and 1 field
#> geometry type: POLYGON
#> dimension:
#> bbox:
                  xmin: 34.1388 ymin: 29.45338 xmax: 35.64979 ymax: 33.1164
#> epsq (SRID):
                 4326
#> proj4string:
                  +proj=longlat +datum=WGS84 +no_defs
                name
                                           geometry
            Red Sea POLYGON ((34.96428 29.54775...
#> 2 Mediterranean Sea POLYGON ((35.10533 33.07661...
#> 3 Dead Sea POLYGON ((35.54743 31.37881...
#> 4 Sea of Galilee POLYGON ((35.6014 32.89248,...
```

Figure 1 shows the spatial configuration of the cities, towns and water layers.

```
plot(st_geometry(towns), col = NA)
plot(st_geometry(water), col = "lightblue", add = TRUE)
plot(st_geometry(towns), col = "grey", pch = 1, add = TRUE)
```

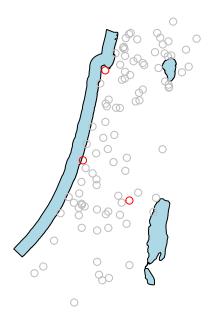


Figure 1: Visualization of the water, towns and cities layers

```
plot(st_geometry(cities), col = "red", pch = 1, add = TRUE)
```

Usage examples

The st_nn function

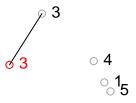
The main function in the nngeo package is st_nn.

The st_nn function accepts two layers, x and y, and returns a list with the same number of elements as x features. Each list element i is an integer vector with all indices j for which x[i] and y[j] are nearest neighbors.

For example, the following expression finds which feature in towns[1:5,] is the nearest neighbor to each feature in cities:

```
nn = st_nn(cities, towns[1:5, ], progress = FALSE)
nn
#> [[1]]
#> [1] 2
#>
#> [[2]]
#> [1] 2
#>
#> [1] 3
```

This output tells us that towns[2,] is the nearest among the five features of towns[1:5,] to cities[1,], etc.



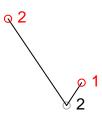


Figure 2: Nearest neighbor match between cities (in red) and towns[1:5,] (in grey)

The st_connect function

The resulting nearest neighbor matches can be visualized using the $st_connect$ function. This function builds a line layer connecting features from two layers x and y based on the relations defined in a list such the one returned by st_nn :

```
1 = st_connect(cities, towns[1:5, ], ids = nn, progress = FALSE)
1
#> Geometry set for 3 features
#> geometry type: LINESTRING
#> dimension: XY
#> bbox: xmin: 34.78177 ymin: 31.65512 xmax: 35.21371 ymax: 33.04801
#> epsg (SRID): 4326
#> proj4string: +proj=longlat +datum=WGS84 +no_defs
#> LINESTRING (35.21371 31.76832, 35.12573 31.65512)
#> LINESTRING (34.78177 32.0853, 35.12573 31.65512)
#> LINESTRING (34.98957 32.79405, 35.18041 33.04801)
```

Plotting the line layer 1 gives a visual demonstration of the nearest neighbors match, as shown in Figure 2.

```
plot(st_geometry(towns[1:5, ]), col = "darkgrey")
plot(st_geometry(l), add = TRUE)
plot(st_geometry(cities), col = "red", add = TRUE)
text(st_coordinates(cities)[, 1], st_coordinates(cities)[, 2], 1:3, col = "red", pos = 4)
text(st_coordinates(towns[1:5, ])[, 1], st_coordinates(towns[1:5, ])[, 2], 1:5, pos = 4)
```

Dense matrix representation

The st_nn can also return the complete logical matrix indicating whether each feature in x is a neighbor of y. To get the dense matrix, instead of a list, use sparse=FALSE.

```
nn = st_nn(cities, towns[1:5, ], sparse = FALSE, progress = FALSE)
nn
#> [,1] [,2] [,3] [,4] [,5]
#> [1,] FALSE TRUE FALSE FALSE
#> [2,] FALSE TRUE FALSE FALSE
#> [3,] FALSE FALSE TRUE FALSE FALSE
```

k-Nearest neighbors where k>0

It is also possible to return any **k-nearest** neighbors, rather than just one. For example, setting k=2 returns both the 1st and 2nd nearest neighbors:

```
nn = st_nn(cities, towns[1:5, ], k = 2, progress = FALSE)
nn
#> [[1]]
#> [1] 2 5
#>
#> [[2]]
#> [1] 2 5
#>
#> [[3]]
#> [1] 3 4

nn = st_nn(cities, towns[1:5, ], sparse = FALSE, k = 2, progress = FALSE)
nn
#>        [,1]  [,2]  [,3]  [,4]  [,5]
#> [1,] FALSE TRUE FALSE FALSE TRUE
#> [2,] FALSE TRUE FALSE TRUE
#> [3,] FALSE TRUE TRUE FALSE
#> [3,] FALSE TRUE TRUE FALSE
```

Distance matrix

Using returnDist=TRUE the distances list is also returned, in addition the the neighbor matches, with both componenets now comprising a list:

```
nn = st_nn(cities, towns[1:5, ], k = 2, returnDist = TRUE, progress = FALSE)
nn
#> [[1]]
#> [[1]][[1]]
#> [1] 2 5
#>
#> [[1]][[2]]
#> [1] 2 5
#>
#> [[1]][[3]]
#> [1] 3 4
#>
#>
#> [[2]]
#> [[2]][[1]]
#> [1] 15069.49 105048.39
```

```
#> [[2]] [[2]]

#> [1] 57746.32 98846.89

#>

#> [[2]] [[3]]

#> [1] 33345.18 46392.06
```

Search radius

Finally, the search for nearest neighbors can be limited to a **search radius** using maxdist. In the following example, the search radius is set to 50,000 meters (50 kilometers). Note that no neighbors are found within the search radius for cities[2,]:

```
nn = st_nn(cities, towns[1:5, ], k = 2, maxdist = 50000, progress = FALSE)
nn
#> [[1]]
#> [1] 2
#>
#> [[2]]
#> integer(0)
#>
#> [[3]]
#> [1] 3 4
```

Spatial join

The st_nn function can also be used as a **geometry predicate function** when performing spatial join with sf::st_join. For example, the following expression spatially joins the two nearest towns[1:5,] features to each cities features, using a search radius of 50 km:

```
cities1 = st_join(cities, towns[1:5, ], join = st_nn, k = 2, maxdist = 50000)
```

Here is the resulting layer:

```
#> Simple feature collection with 4 features and 2 fields
#> geometry type: POINT
#> dimension:
#> bbox:
                  xmin: 34.78177 ymin: 31.76832 xmax: 35.21371 ymax: 32.79405
#> epsq (SRID):
                   4326
#> proj4string:
                  +proj=longlat +datum=WGS84 +no_defs
#>
         name.x
                       name.y
                                               geometry
      Jerusalem ALLON SHEVUT POINT (35.21371 31.76832)
#> 1
#> 2
                        <NA> POINT (34.78177 32.0853)
       Tel-Aviv
                        AVDON POINT (34.98957 32.79405)
#> 3
          Haifa
#> 3.1
           Haifa
                        ARBEL POINT (34.98957 32.79405)
```

Another example

Here is another example, finding the 10-nearest neighbor towns features for each cities feature:

```
x = st_nn(cities, towns, k = 10)
l = st_connect(cities, towns, ids = x)
```

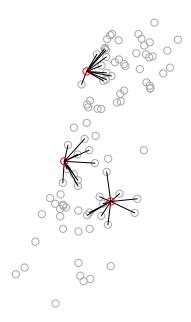


Figure 3: Nearest 10 towns features from each cities feature

The result is visualized in Figure 3.

```
plot(st_geometry(towns), col = "darkgrey")
plot(st_geometry(l), add = TRUE)
plot(st_geometry(cities), col = "red", add = TRUE)
```

Polygons

Nearest neighbor search also works for non-point layers. The following code section finds the 20-nearest towns features for each water body in water[-1,].

```
nn = st_nn(water[-1, ], towns, k = 20, progress = FALSE)
```

Again, we can calculate the respective lines for the above result using st_connect. Since one of the inputs is line/polygon, we need to specify a sampling distance dist, which sets the resolution of connecting points on the shape exterior boundary.

```
1 = st_connect(water[-1, ], towns, ids = nn, progress = FALSE, dist = 100)
```

The result is visualized on Figure 4.

```
plot(st_geometry(water[-1, ]), col = "lightblue", border = "grey")
plot(st_geometry(towns), col = "darkgrey", add = TRUE)
plot(st_geometry(1), col = "red", add = TRUE)
```

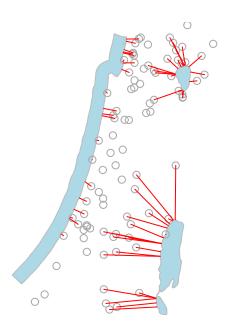


Figure 4: Nearest 20 towns features from each water polygon