Visualization tools in the seqHMM package

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1 Introduction

Visualization is a powerful tool throughout the analysis process from the first glimpses into the data to exploration and finally to presentation of the results. This vignette is supplementary material to the paper Helske and Helske (2019) on the seqHMM package; here we discuss visualization of sequence data and hidden Markov models in more detail and give a more examples on the plotting features of the package.

1.1 Visualizing sequences

There are many options for graphical description of sequence data. Most of them either represent sequences or summarize them. Sequence index plot is the most commonly used example of the former (see an illustration on the left-hand side of Figure ??). Such a graph was proposed by Scherer (2001) to show the observations of each subject in the order they appear, illustrating different states with different colours. The horizontal axis shows the time points while individuals are represented on the vertical axis; thus, each horizontal line shows the sequence of one individual.

When the number of subjects is moderate, sequence index plots give an accurate representation of the data, offering an overview on the timing of transitions and on the durations of different episodes. Sequence index plots get more complex to comprehend when the number of individuals and states increases. Sequence analysis with clustering eases interpretation by grouping similar trajectories together. Piccarreta and Lior (2010) suggested using multidimensional scaling for ordering sequences more meaningfully (similar sequences close to each other). Piccarreta (2012) proposed smoothing techniques that reduce individual noise. Similar sequences are summarized into artificial sequences that are representative to the data. Gabadinho, Ritschard, Müller, and Studer (2011) introduced representative sequence plots where only a few of the most representative sequences (observed or artificial) are shown. A similar approach, relative frequency sequence plot, was introduced by Fasang and Liao (2014). The idea is to find a representative sequence (the medoid) in equal-sized neighbourhoods to represent the relative frequencies in the data.

State distribution plots (also called tempograms or chronograms; Billari and Piccarreta, 2005; Widmer and Ritschard, 2009) summarize information in the whole data. Such graphs show the change in the prevalence of states in the course of time (see the right-hand side of Figure ??). Also here, the horizontal axis represents time but vertical axis is now a percentage scale. These plots simplify the overall patterns but do not give information on transitions between different states. Other summary plots include, e.g., transversal entropy plots (Billari, 2001), which describe how evenly states are distributed at a given time point, and mean time plots (Gabadinho et al., 2011), which show the mean time spent in each state across the time points.

Visualizing multichannel data is not a straightforward task. The TraMineR package (Gabadinho et al., 2011) provides nice plotting options and summaries for simple sequence data, but there are no easy options for multichannel data. Combining states into a single-channel representation often works well if the state space is small and states at each time point are either completely observed or completely missing. In other cases it can be preferable to preserve the multichannel structure. The *stacked sequence plot* shows sequence data plotted separately for each channel (see Figure 1). The order of the subjects is kept the same in each plot and the plots are stacked on top of each other. Since the time axes are horizontally aligned, comparing timing in different life domains should be relatively easy. This approach also protects the privacy of the subjects; even

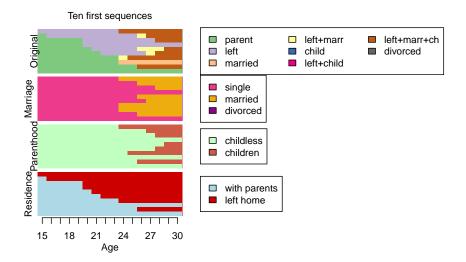


Figure 1: Stacked sequence plot of the first ten individuals in the biofam data. The top plot shows the original sequences, and the three bottom plots show the sequences in the separate channels for the same individuals. The sequences are in the same order in each plot, i.e., the same row always matches the same individual.

though all data are shown, combining information across channels for a single individual is difficult unless the number of subjects is small. State distribution plots can then be used to show information on the prevalence and timing of combined states on a more general level.

1.2 Visualizing hidden Markov models

Markovian models are often visualized as directed graphs where vertices (nodes) present states and edges (arrows, arcs) show transition probabilities between states. We have extended this basic graph in the hidden Markov model framework by presenting hidden states as pie charts, with emission probabilities as slices, and by adjusting the thickness of edges according to transition probabilities. Such graph allows for presenting a complex model in a very efficient way, guiding the viewer to the most important aspects of the model. The graph shows the essence of the hidden states and the dynamics between them.

Figure ?? illustrates a HMM with five hidden states for the multichannel version of the biofam data. Following the common convention, hidden states are presented as vertices and transition probabilities are shown as edges. Initial state probabilities are given below the respective vertices. Almost all individuals (99%) start from the first hidden state of living home unmarried and without children.

Vertices are drawn as pie charts where the slices represent emitted obser-

vations or – in a multichannel case – combinations of observed states across channels. The size of the slice is proportional to the emission probability of the observed state (or in a multichannel model, the product of the emission probabilities across channels). In this model, the hidden states are very close to observed states, the largest emission probabilities for the combined observations are 0.94 or higher in all states. For emphasizing the relevant information, observations with small emission probabilities can be combined into one category – here we've combined states with emission probabilities less than 2%.

The width of the edge depends on the probability of the transition; the most probable transitions are thus easy to detect. Here the most probable transition between two hidden states is the transition into parenthood (typically married/childless/left home \rightarrow married/children/left home) with a probability of 0.19.

1.3 Example data

As an example we use the biofam data available in the TraMineR package (Gabadinho et al., 2011). It is a sample of 2000 individuals born in 1909–1972, constructed from the Swiss Household Panel survey in 2002 (Müller, Studer, and Ritschard, 2007). The data set contains sequences of annual family life statuses from age 15 to 30. Eight observed states are defined from the combination of five basic states: living with parents, left home, married, having children, and divorced. To show a more complex example, we have split the original data into three separate channels representing different life domains: marriage, parenthood, and residence. The data for each individual now includes three parallel sequences constituting of two or three states each: single/married/divorced, childless/parent, and living with parents / having left home. This three-channel version of the data is stored as a new data object called biofam3c.

2 Tools for visualizing multichannel sequence data

2.1 ssplot: stacked sequence plots

The ssplot function is the simplest way of plotting multichannel sequence data in seqHMM. It can be used to illustrate state distributions or sequence index plots. The former is the default option, since index plots can take a lot of time and memory if data are large.

Data types. The ssplot function accepts two types of objects, either state sequence objects of type stslist from the seqdef function or a hidden Markov model object of class hmm from the build_hmm function.

As an example of the former, we start by preparing three state sequence objects from the biofam3c data. Here we set the start of the sequence at age 15 and define the states in each channel with the alphabet argument. The colour palette is stored as an attribute and may be modified accordingly.

The ssplot function is designed for multichannel data but also works for single-channel sequences. For multichannel data, when using stslist objects the different channels are given as a list. Figure 2 illustrates a default plot.

Observed and hidden state sequences. The ssplot function may be asked to plot observed sequences, hidden state sequences, or both. In the case of hmm objects, the most probable hidden state sequences are computed from the data Choosing plots. The ssplot function is able to also hidden state paths in addition to or instead of observed sequences. The type of sequences is set with the plots argument. Figure 3 shows state distributions for the observations as well as hidden states.

```
data("hmm_biofam")
ssplot(x = hmm_biofam, plots = "both")
```

Sequence index plots are called with the type = "I" argument in a similar way to the sequence in TraMineR. This type of plot shows the sequences as a whole. As the index plot is often difficult to interpret as such, sequences may be ordered in a more meaningful way.

Sorting. The sortv argument may be given a sorting variable or a sorting method. A sorting method may be one of from.start, from.end, mds.obs,

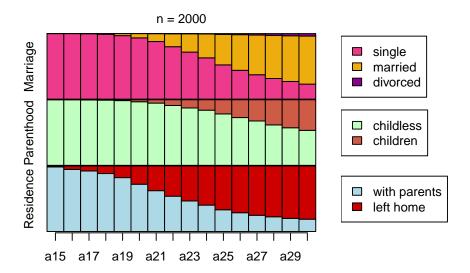


Figure 2: Stacked sequence plot of annual state distributions in the three-channel biofam data. This is the default output of the ssplot function.

and mds.hidden. The from.start and from.end arguments sort the sequences by the elements of the alphabet in the channel defined by the sort.channel argument (the first channel by default), starting from the start of the end of the sequences. The mds.obs and mds.hidden arguments sort the sequences according to the scores of multidimensional scaling for the observed data or hidden states paths, respectively. The tlim argument may be used to select only certain subjects for the plot. Figure 4 shows sequences sorted by the third channel, residence.

```
ssplot(
  hmm_biofam, type = "I", sortv = "from.start", sort.channel = 3)
```

The labels and positions of the ssplot may be modified in many ways.

Title. By default, the function shows the number of subjects in the plot. Additional title printed in front of this is given with the title argument. This may be suppressed by title.n = FALSE.

Legend. The with.legend argument defines if and where the legend for the states is plotted. The default value "right" creates separate legends for each channel (and hidden states, when relevant) and positiones them on the right-hand side of the plot. Other possible values are "bottom", "right.combined", and "bottom.combined", of which the last two create one combined legend of the states in all channels in the selected position. The legend may be supressed

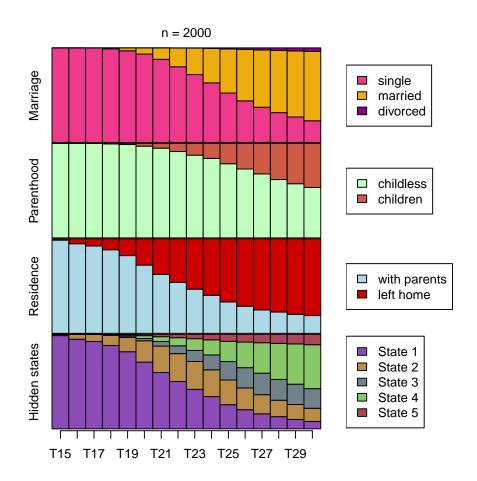


Figure 3: Stacked sequence plot of observations and hidden state paths using a hidden Markov model object.

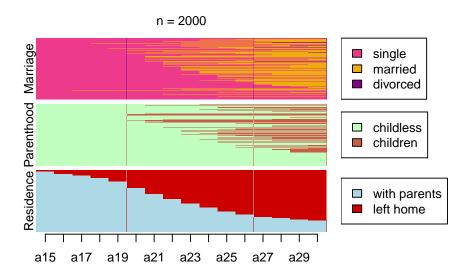


Figure 4: Sequence index plot showing observed sequences sorted by the third channel, residence.

altogether with the value FALSE. The ncol.legend argument gives the number of columns in (each of) the legend(s) and the legend.prop argument sets the proportion of the graphic area that is used for plotting the legend (0.3 by default).

Axes. The user may choose to suppress or plot both the a axis (TRUE by default) and the y axis (FALSE by default). Both may be given optional labels with the xlab and ylab arguments and the distance of the labels from the plot may be modified with the xlab.pos and ylab.pos arguments (note: for hidden states, the label for the y axis is given with the hidden.states.title argument). The labels for the ticks of the x axis are modified with the xtlab argument.

Text sizes. The sizes of the title, legend, axis labels, and axis tick labels are modified with the cex.title, cex.legend, cex.lab, and cex.axis arguments, respectively.

2.2 ssp: saving stacked sequence plots

The user may also pre-define function arguments with the **ssp** function and then use this object for plotting with a simple **plot** method. After defining one ssp, modifications are easy to do with the **update** function (see an example in the next section).

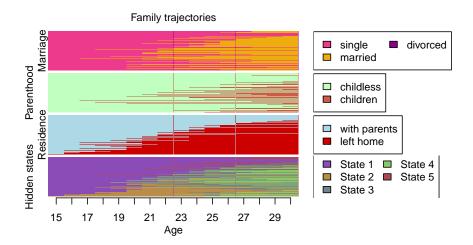


Figure 5: Example on saving ssp objects. Sequences are sorted according to multidimensional scaling scores.

```
ssp_def <- ssp(
  hmm_biofam, plots = "both", type = "I", sortv = "mds.hidden",
  ylab.pos = c(1, 2),
  title = "Family trajectories", title.n = FALSE,
  xtlab = 15:30, xlab = "Age",
  ncol.legend = c(2, 1, 1), legend.prop = 0.37)

plot(ssp_def)</pre>
```

Figure 5 shows the plot from the saved ssp. Here, the sequences were sorted according to multidimensional scaling scores computed from the most probable hidden state sequences. Labels and their positions as well as the legends were also modified.

2.3 gridplot: multiple stacked sequence plots

The gridplot function combines several ssp figures into one. It is useful for showing different features for the same subjects or the same features for different groups. The dimensions of the grid, widths and heights of the cells, and positions of the legends are easily modified.

Figure ?? illustrates an example of a gridplot showing sequence index plots for women and men. Sequences were sorted using multidimensional scaling scores for observations. The legend.pos function defines the position of the legend(s) relative to the whole plot. It may be one of "bottom" or "right" or a numerical vector of grid cells.

Figure ?? shows an example of manual positioning of legends into grid cells 3 and 4.

The gridplot function uses the first list object for defining the legends. If the legends are different for different ssp figures, the common legend may be suppressed with the with.legend = FALSE argument.

2.4 mssplot: ssp for mixture HMMs

The mssplot draws stacked sequence plots of observed sequences and/or most probable hidden state paths for clusters based on a mixture hidden Markov model of class mhmm. The most probable cluster (submodel) for each subject is chosen according to the most probable path of hidden states. By default, the function plots all clusters but the user may choose a subset of clusters with the which.plots argument. This is an interactive plot that shows several plots in a row. The default is to change the plot by pressing Enter. With the ask = TRUE argument the user gets a menu from which to choose the next cluster for plotting.

3 Tools for hidden Markov models

3.1 plot.hmm: plotting hidden Markov models

A basic HMM graph is easily called with the plot method. Figure ?? illustrates the default plot.

A simple default plot is a convenient way of visualizing the models during the analysis process, but for publishing it is often better to modify the plot to get an output that best illustrates the structure of the model at hand.

Layout. The default layout positions hidden states horizontally. This may be changed with the layout argument. The user may choose to position hidden states vertically or use a layout function from the igraph package. It is also possible to position the vertices manually by giving a two-column numerical matrix of x and y coordinates.

Vertices. By default, the vertices are drawn as pie charts showing the emission probabilities as slices. The pies may be omitted with the pie = FALSE argument. Initial probabilities are shown as vertex labels by default. Instead of these, the user may choose to print the names of the hidden states, use own labels, or omit the labels altogether with the vertex.label argument. The distance and the positions of the labels are modified with the vertex.label.dist and vertex.label.pos arguments. The size of the vertices is modified with the vertex.size argument.

The colour palette for (combinations of) observed states is set with the cpal argument. Observations with small emission probabilities may be combined into one state with the combine.slices argument which sets the threshold for

printing observed states. By defafult, observed states with emission probabilities less than 0.05 are combined. The colour and label for the combined state is modified with the combined.slice.color and combined.slice.label arguments, respectively.

Edges. By default, the plotting method draws transition probabilities between different states and omits transitions to same states. Self-loops may be drawn with the loops argument. The edge.curved argument tells the curvature of edges. These may be different for different edges; setting curvature to 0 or FALSE draws straight edges. The widths of the edges are modified with the edge.width and cex.edge.width arguments. The former sets the widths (by default, proportional to transition probabilities) and the latter sets an expansion factor to all edges. The size of the arrows is modified with the edge.arrow.size argument. The trim argument omits edges with transition probabilities less than the specified value (0 by default, i.e., no trimming).

Legend. The with.legend argument defines if and where the legend is plotted. The ltext argument may be used to modify the labels shown in the legend. Similarly to ssp figures, the legend may be modified with the legend.prop, ncol.legend, and cex.legend arguments.

Texts. Font families for labels are modified with the vertex.label.family and edge.label.family arguments. Printing of model parameters may be modified with the label.signif, label.scientific, and label.max.length arguments. The first rounds labels to the specified number of significant digits, the second one defines if scientific notation should be used to describe small numbers, and the last argument sets the maximum number of digits for labels. These three arguments are omitted for user-given labels.

Other modifications. The plotting method also accepts other arguments in the plot.igraph function in the igraph package.

Figure ?? in Section 1.2 is an example of manual positioning of vertices. Here we have modified edge curvature and width, legend properties, and combined slices. The code for creating the figure is shown here.

Figure ?? shows an example of using a layout function from the igraph package. This is based on the same model as the other figures but here we have

omitted pie graphs and instead show the names of the hidden states printed within the circles. This figure also shows the self-loops for transitions. We have omitted transition probabilities smaller than 0.01 and printed labels with three significant digits.

3.2 plot.mhmm: plotting mixture hidden Markov models

The plot.mhmm function shows the submodels of a mhmm object similarly to the mssplot function. Also here the user may choose which submodels to plot with the which.plots argument and ask for a menu from which to choose the next plot with the ask argument. Instead of an interactive mode it is also possible to plot all submodels in the same figure similarly to the gridplot function. Note, however, that such a plot requires opening a large window.

4 Helper tools

4.1 mc_to_sc_data and mc_to_sc: from multichannel to singlechannel

We also provide a function mc_to_sc_data for the easy conversion of multichannel sequence data into a single channel representation. Plotting combined data is often useful in addition to (or instead of) showing separate channels. A similar function called mc_to_sc converts multichannel HMMs into single-channel representations.

4.2 colorpalette: ready-made colour palettes

The colorpalette data is a list of ready-made colour palettes with distinct colours. By default, the seqHMM package uses these palettes when determining colours for new state sequence objects or for plotting. A colour palette with n colours is called with colorpalette[[n]].

4.3 plot_colors: show colours of colour palettes

The plot_colors function plots colors and their labels for easy visualization of a colorpalette. Figure ?? shows an example from colorpalette with seven colours.

4.4 separate_mhmm: reorganize MHMM into a list of HMMs

The separate_mhmm function reorganizes the parameters of an mhmm object into a list where each list component is an object of class hmm consisting of parameters of the corresponding cluster. This gives more possibilities for plotting. For example, the user may define ssp figures for each cluster defined by an MHMM for plotting with the gridplot function.

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