# Spatial Coverage Sampling by k-means: the spcosa-package\*

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### 1 Introduction

The spcosa-package implements algorithms for spatial coverage sampling and for random sampling from compact geographical strata based on the k-means algorithm (de Gruijter et al., 2006). Spatial coverage sampling is known to be an efficient sampling method for model-based mapping (kriging). Random sampling from compact geographical strata is recommended for design-based estimation of spatial means, proportions, etc.. In this vignette, the usage of the package will be demonstrated by means of several examples. In addition to spatial coverage sampling also stratified simple random sampling of compact strata will be treated in this vignette.

The spocsa-package can be loaded by means of

# > library(spcosa)

Although the implemented optimisation algorithms are deterministic in nature, they use random initial configurations to minimise the risk of ending up in an unfavourable local optimum. In order to be able to reproduce the sampling patterns in a later stage, the built-in pseudo random number generator has to be initialised:

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```
> set.seed(314)
```

The spcosa-package depends on the sp-package (Pebesma and Bivand, 2005) for storing spatial information, and the ggplot2-package (Wickham, 2008) for visualisation. A basic knowledge of the sp-package is highly recommended. See the sp-package vignette for more information. Knowledge of the ggplot2-package is only needed for fine-tuning spcosa graphics. Consult the superb ggplot2-website for details and illustrative examples.

# 2 Algorithms

The basic idea is to distribute sampling points evenly over the study area by selecting these points in compact spatial strata. Compact strata can be obtained by k-means clustering of the cells making up a fine grid representing the study area of interest. Two k-means algorithms have been implemented in the spcosa-package: a transfer algorithm and a swopping algorithm. The transfer algorithm obtains compact clusters (strata) by transferring cells from one cluster to the other, whereas the swopping algorithm achieves this by swopping cells between clusters. The first algorithm results in compact clusters, whereas the second algorithm results in compact clusters of equal size. For reasons of efficiency, both algorithms have been implemented in the Java language and communicate with R (R Development Core Team, 2008) by means of the rJava-package (Urbanek, 2008).

# 3 Examples

In this section, the spcosa-package will be demonstrated by means of several examples.

### 3.1 Spatial coverage sampling without prior points

In the first example, spatial coverage sampling will be applied to map the clay content in the study area by means of ordinary point kriging.

First, a vector or raster representation of the study area has to be loaded. As an example, the ASCII-grid demoGrid.asc residing in the maps directory of the spcosa-package will be read by means of the readGDAL-function of the rgdal-package (Keitt et al., 2008).

```
> filename <- system.file("maps", "demoGrid.asc", package = "spcosa")
> myAsciiGrid <- readGDAL(fname = filename, silent = TRUE)</pre>
```

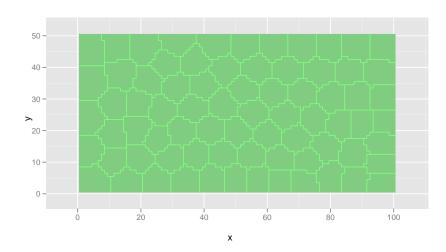
To obtain a uniform distribution of sampling points over the study area, the sampling points will be selected at the centroids of compact spatial strata. Compact strata can be constructed by invoking the stratify method:

```
> myStratification <- stratify(myAsciiGrid, nStrata = 75, nTry = 10)
> myStratification

Object of class "CompactStratification"
number of strata: 75
```

In this example, the study area has been partitioned into 75 compact strata. The resulting stratification can be plotted by means of:

```
> print(plot(myStratification))
```



Note that throughout this vignette, plot statements are encapsulated in print statements. The reason for this is explained in the online Sweave FAQ. The print statements can be omitted during an ordinary interactive R-session.

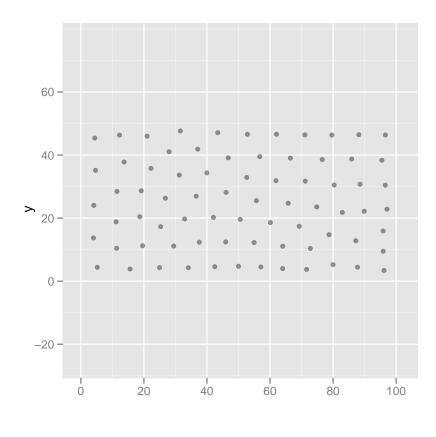
The spsample-method, an overloaded method from the sp-package, can be used to select the centroid of each stratum:

- > mySamplingPattern <- spsample(myStratification)
- > mySamplingPattern

Object of class "SamplingPatternCentroids" sample size: 75

The plot-method can be used to visualise the resulting sampling pattern:

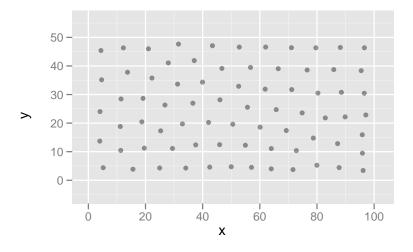
> print(plot(mySamplingPattern))



Note that the plot-method creates maps with equally scaled axes to prevent distortion. Unfortunately, this may occasionally lead to wide margins, as in the example above. This can be corrected by specifying the proper aspect ratio:

Χ

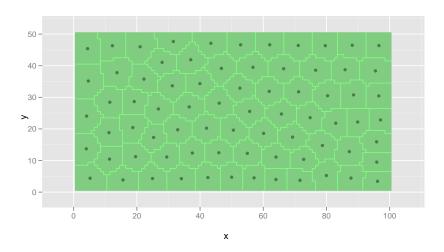
> print(plot(mySamplingPattern) + coord\_equal(ratio = 3/5))



Indeed, each plot can be modified by adding ggplot2-functions, like coord\_equal, to the plot-method.

The sampling pattern can also be plotted on top of the stratification:

#### > print(plot(myStratification, mySamplingPattern))



Sampling points can be extracted by means of a simple type cast to class data.frame:

```
> mySamplingPoints <- as(mySamplingPattern, "data.frame")
```

Next, field work will be done to acquire data at these locations. In this vignette, however, we simulated data on clay and soil organic matter contents by calling the function doFieldWork. The doFieldWork-function is not part of the spcosa-package, it only 'lives' in this vignette.

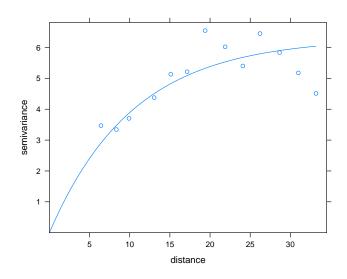
Spatial coverage sampling is a purposive sampling method. Therefore, model-based inference will be applied to predict clay contents. Model-based inference is not implemented in the spcosapackage, because other add-on packages already provide excellent support for it. See for instance, gstat (Pebesma, 2004), spatial (Venables and Ripley, 2002), and geoR (Ribeiro Jr and Diggle, 2001).

As an example, we will use the gstat package for predicting clay contents by means of ordinary point kriging. First, the observations and sampling pattern will be combined in a single object of class SpatialPointsDataFrame:

```
> spData <- data.frame(mySamplingPoints, myData)
> coordinates(spData) <- ~x * y</pre>
```

Next, the semivariogram model for clay has to be estimated:

### > print(plot(sampleVariogram, model = variogramModel))



Finally, ordinary point kriging predictions can be obtained by means of:

```
> g <- gstat(id = "clay", formula = clay ~ 1, data = spData, model = variogramModel)
> yHat <- predict(g, newdata = myAsciiGrid)</pre>
```

[using ordinary kriging]

> summary(yHat)

 ${\tt Object\ of\ class\ SpatialGridDataFrame}$ 

Coordinates:

min max

x 0.5 100.5

y 0.5 50.5

Is projected: NA
proj4string : [NA]

Number of points: 2

Grid attributes:

cellcentre.offset cellsize cells.dim x 1 1 100 y 1 1 50

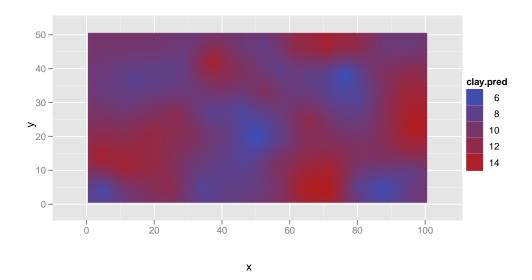
y Data attributes:

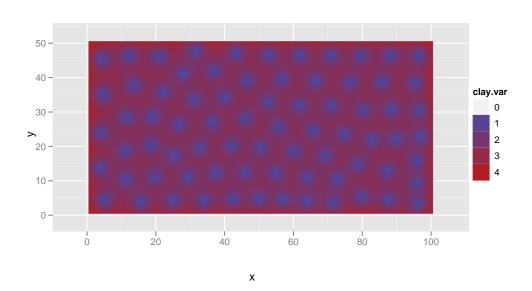
clay.pred clay.var

Min. : 5.305 Min. :2.519e-32 1st Qu.: 8.810 1st Qu.:1.907e+00 Median : 9.805 Median :2.260e+00

Mean : 9.995 Mean :2.154e+00 3rd Qu.:11.181 3rd Qu.:2.446e+00 Max. :14.931 Max. :4.261e+00

The resulting predictions and variances of the prediction error are given in the figures below:





# 3.2 Spatial coverage sampling with prior points

Sometimes, samples from previous sampling campaigns are available. In these situations, spatial infill sampling may be performed. This type of spatial coverage sampling aims to distribute new sampling points evenly over the study area, while taking the locations of existing sampling points into account. Suppose a data.frame is available containing the coordinates of 50 existing sampling points:

## > str(priorPoints)

```
'data.frame': 50 obs. of 2 variables:

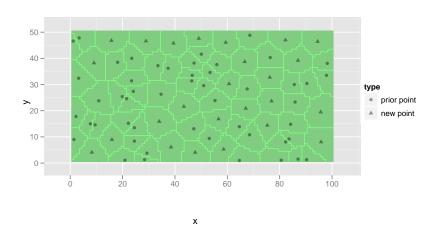
$ x: num 9.5 53.1 18.1 56 64.6 90.3 83.6 76.4 1.4 24.1 ...

$ y: num 14.6 9.4 38.5 37.6 1 1.3 9.2 40.3 9 27.4 ...
```

Twenty-five new points can be assigned to sparsely sampled regions by means of:

Note that the total number of strata, and therefore the total number of points, equals 50+25=75. In addition, also note that the nTry argument has been set to 100. The algorithm will now use 100 random starting configurations and keeps the best solution to minimise the risk of ending up in an unfavourable local optimum.

#### > print(plot(myStratification, mySamplingPattern))



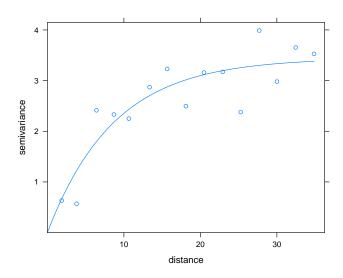
Note that prior points and new points are represented by different symbols.

A map of clay contents can be obtained by means of ordinary point kriging. First, some field and laboratory work has to be done to obtain clay contents for the 25 new points:

```
> mySamplingPoints <- as(mySamplingPattern, "data.frame")
> myData <- doFieldWork(mySamplingPoints)</pre>
> spData <- data.frame(mySamplingPoints, myData["clay"])</pre>
> coordinates(spData) <- ~x * y
> summary(spData)
Object of class SpatialPointsDataFrame
Coordinates:
 min max
x 1.1 98.2
y 1.0 48.8
Is projected: NA
proj4string : [NA]
Number of points: 75
Data attributes:
   Min. 1st Qu.
                 Median
                            Mean 3rd Qu.
                                             Max.
   5.00
           8.85
                  10.00
                           10.02
                                    11.40
                                            15.00
```

Again, we will use gstat for model-based inference:

> print(plot(sampleVariogram, model = variogramModel))



> g <- gstat(id = "clay", formula = clay ~ 1, data = spData, model = variogramModel)> yHat <- predict(g, newdata = myAsciiGrid)

[using ordinary kriging]

> summary(yHat)

Object of class SpatialGridDataFrame

Coordinates:

min max

x 0.5 100.5

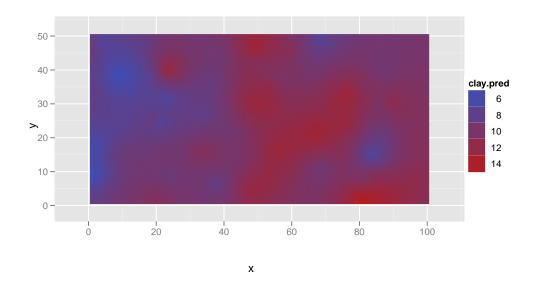
y 0.5 50.5

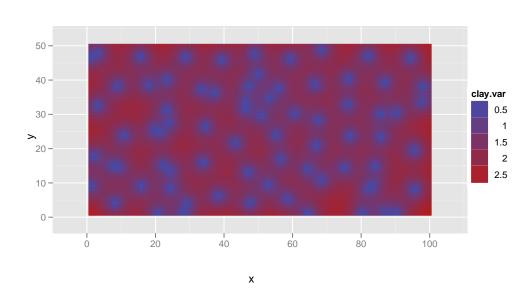
Is projected: NA proj4string: [NA] Number of points: 2 Grid attributes:

Data attributes:

clay.pred clay.var : 5.124 :0.05476 Min. Min. 1st Qu.: 9.030 1st Qu.:1.24923 Median : 9.969 Median :1.56104 Mean : 9.928 :1.49111 Mean 3rd Qu.:11.028 3rd Qu.:1.76897 Max. :14.802 Max. :2.83482

The resulting predictions and variances of the prediction error are given in the figures below:



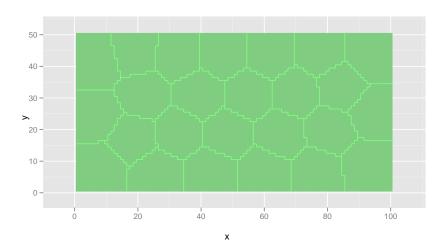


# 3.3 Random sampling from compact geographical strata

In this section the global mean clay and organic matter contents of the study area will be estimated by means of stratified simple random sampling. Again, we will use myAsciiGrid as a representation of the study area. The study area will be partitioned into 25 compact strata:

```
> myStratification <- stratify(myAsciiGrid, nStrata = 25, nTry = 10)
> myStratification

Object of class "CompactStratification"
number of strata: 25
> print(plot(myStratification))
```

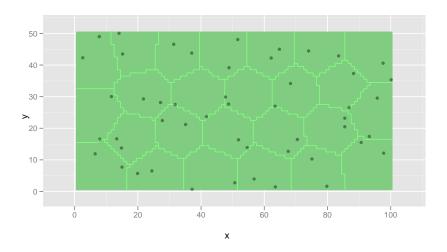


The <code>spsample-method</code> can be used to randomly sample two sampling units per stratum:

- > mySamplingPattern <- spsample(myStratification, n = 2)
- > mySamplingPattern

Object of class "SamplingPatternRandomSamplingUnits" sample size: 50

> print(plot(myStratification, mySamplingPattern))



Sampling points can be extracted by means of a type cast to class data.frame:

- $\verb| > mySamplingPoints <- as(mySamplingPattern, "data.frame")|\\$
- > mySamplingPoints[1:5, ]

x

1 63.48984 1.449016

2 56.78113 3.942664

3 48.70803 27.649526

4 47.73079 29.879614

5 14.98596 7.704725

Next, some field work has to be done:

```
> myData <- doFieldWork(mySamplingPoints)</pre>
> str(myData)
'data.frame':
                    50 obs. of 2 variables:
 $ clay: num 10.4 9.5 14.7 14.1 10.3 8.4 10.5 10.9 11.5 8.9 ...
 $ SOM : num 5.7 4.7 7.1 6.7 5.5 3.8 4.9 5.2 5.6 4.3 ...
```

The spatial mean clay and soil organic matter contents can be estimated by (de Gruijter et al., 2006):

```
> estimate("spatial mean", myStratification, mySamplingPattern,
      myData)
    clay
              SOM
10.20568 5.05320
```

In estimating the spatial mean, differences in surface area of the strata are taken into account. Note, that the spatial mean is estimated for all columns in myData. The standard error can be estimated in a similar way:

```
> estimate("standard error", myStratification, mySamplingPattern,
      myData)
                SOM
     clay
0.2050475 0.1148747
```

The spatial cumulative distribution function (SCDF) (see de Gruijter et al., 2006) can be estimated by means of

```
> mySCDF <- estimate("scdf", myStratification, mySamplingPattern,
      myData)
```

The SCDFs are returned as a list of matrices, *i.e.* one matrix for each property:

```
> lapply(X = mySCDF, FUN = head, n = 4)
```

\$clay

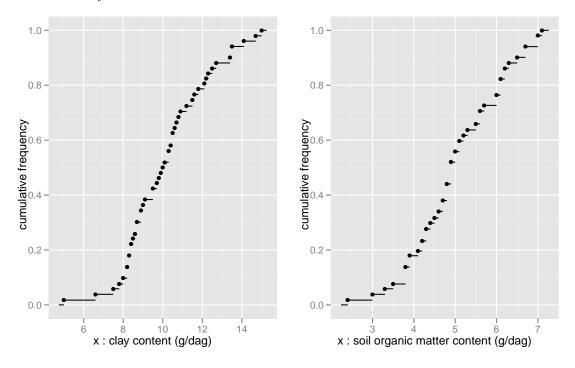
```
value cumFreq
      5.0 0.0000
[1,]
      6.6 0.0173
[2,]
[3,]
      7.5 0.0385
[4,]
      7.8 0.0587
```

```
$SOM
    value cumFreq
[1,]
      2.4 0.0000
[2,]
      3.0 0.0173
[3,]
      3.3 0.0385
[4,]
      3.5 0.0587
```

> lapply(X = mySCDF, FUN = tail, n = 4)

#### \$clay value cumFreq [38,] 13.5 0.9008 [39,] 0.9412 14.1 [40,] 14.7 0.9606 [41,] 15.0 0.9800 \$SOM value cumFreq [27,] 6.5 0.8811 [28,] 6.7 0.9015 [29,] 0.9406 7.0 [30,] 7.1 0.9806

The SCDFs for clay and SOM are visualised below.



# 3.4 Stratified simple random sampling for composites

In this example the aim is to estimate the global mean clay and organic matter contents of a field. To reduce laboratory costs, the soil aliquots collected at the sampling locations will be bulked into composite samples. The study area is a field near the village of Farmsum, in the North-East of the Netherlands. An ESRI shape file of this field is available in the maps directory of the spcosapackage. It can be loaded by means of readOGR, a function in the rgdal-package (Keitt et al., 2008):

```
> directory <- system.file("maps", package = "spcosa")
> shpFarmsum <- readOGR(dsn = directory, layer = "farmsum", verbose = FALSE)</pre>
```

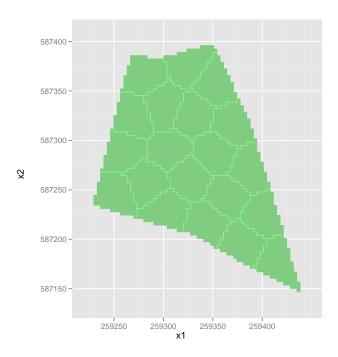
First, the field will be stratified into, say, 20 compact strata of equal size. Strata of equal size are desirable to simplify fieldwork, *i.e.* equal masses (or volumes) of soil can be collected at the sampling locations (Brus et al., 1999; de Gruijter et al., 2006).

```
> myStratification <- stratify(shpFarmsum, nStrata = 20, equalArea = TRUE,
```

- + nTry = 10)
- > myStratification

Object of class "CompactStratificationEqualArea" number of strata: 20

> print(plot(myStratification))

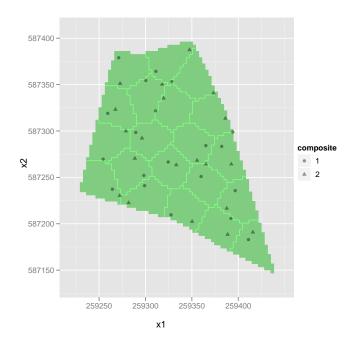


Next, two sampling units will be selected at random in each stratum. At least two sampling units per stratum are required to estimate the sampling variance of the estimated mean.

```
> mySamplingPattern <- spsample(myStratification, n = 2, type = "composite") > mySamplingPattern
```

Object of class "SamplingPatternRandomComposite" sample size: 2

> print(plot(myStratification, mySamplingPattern))



Sampling points can be extracted means of:

```
> mySamplingPoints <- as(mySamplingPattern, "data.frame")</pre>
```

> mySamplingPoints[1:5, ]

```
composite
                  x1
1
          1 259365.0 587284.3
2
          2 259355.6 587268.2
3
          1 259324.5 587266.6
4
          2 259333.1 587263.4
          1 259289.5 587298.4
```

Note that an extra column has been added specifying the sampling units to be bulked into each composite. A composite sample is formed by bulking one aliquot (sampling unit) per stratum. Field work now results in a composite sample of size two:

```
> myData <- doFieldWork(mySamplingPoints, composite = TRUE, n = 2)
> myData
  clay SOM
1 9.2 4.7
2 8.9 4.5
```

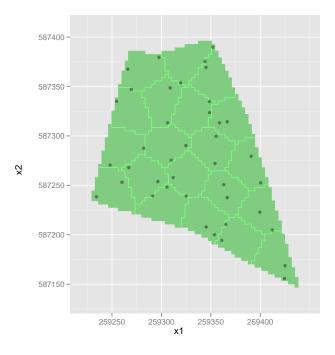
The spatial mean and its standard error can be estimated by means of:

```
> estimate("spatial mean", myStratification, mySamplingPattern,
      myData)
clay SOM
9.05 4.60
> estimate("standard error", myStratification, mySamplingPattern,
      myData)
```

```
clay SOM 0.0225 0.0100
```

If we do not want to bulk soil aliquots, the same stratification can be used to select a sample of  $20 \times 2$  sampling locations:

> print(plot(myStratification, mySamplingPattern))



# 4 Special cases

### 4.1 Map projections

In the examples above, the maps didn't have projection attributes. At field scale, projection attributes are not really necessary. However, at continental and global scale, for example, projection attributes can't be ignored. The spcosa-package is capable of handling projection attributes of class CRS. More information on projections is available at the 'PROJ.4' project website and in the rgdal-package documentation (Keitt et al., 2008).

To illustrate the effect of stratification on smaller spatial scales, consider two grids covering the entire Northern Hemisphere.

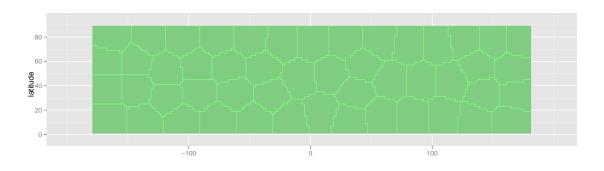
```
> grd1 <- expand.grid(longitude = seq(from = -178, to = 180, by = 2),
+ latitude = seq(from = 2, to = 88, by = 2))
> coordinates(grd1) <- ~longitude * latitude
> gridded(grd1) <- TRUE
> grd2 <- grd1
> proj4string(grd2) <- CRS("+proj=longlat +ellps=WGS84")</pre>
```

Note that grd1 is identical to grd2, except that grd2 has projection attributes. If no projection attributes are available, the algorithms in the spcosa-package use squared Euclidean distances in the k-means algorithms. However, if projection attributes have been set, the coordinates will be transformed to lat/long format (latitude/longitude) and squared great circle distances will be used instead.

Both grids will be partitioned into 50 compact strata:

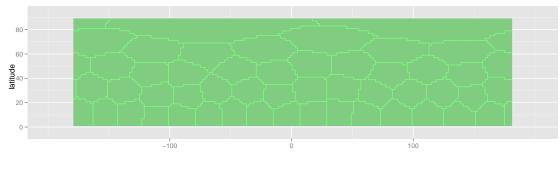
```
> myStratification1 <- stratify(grd1, nStrata = 50)
> myStratification2 <- stratify(grd2, nStrata = 50)</pre>
```

> print(plot(myStratification1) + coord\_equal(ratio = 90/360))



longitude

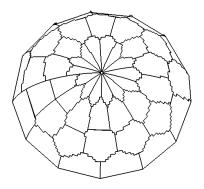
> print(plot(myStratification2) + coord\_equal(ratio = 90/360))

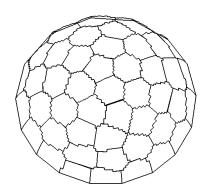


longitude

Note that grd1 seems to have more compact strata near the geographic north pole than grd2. However, the contrary is true. This becomes evident when both stratifications are projected on a

sphere (see below). The left figure corresponds to grd1 and the right figure to grd2. The strata of grd2 are clearly more compact than those of grd1. In addition, grd1 suffers from pronounced edge effects near the poles and at 180° longitude. The strata are discontinuous at this meridian, i.e., two points on opposite sides of the meridian are treated as very distant when squared Euclidean distances are used. The strata of grd2, on the other hand, have been optimised on a sphere by using squared great circle distances, and don't suffer from edge effects at all, i.e., the distance between two points on opposite sides of this meridian is very small.

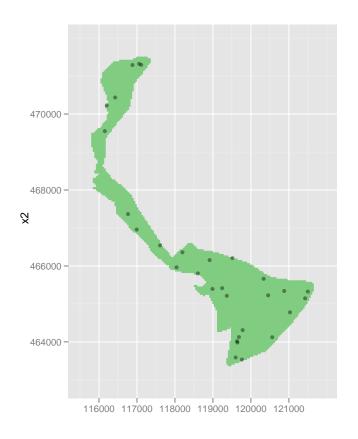




# 4.2 Simple random sampling

Although this package is about sampling from compact strata, it can also be used for simple random sampling, by setting nStrata = 1:

```
> shpMijdrecht <- readOGR(dsn = system.file("maps", package = "spcosa"),
+ layer = "mijdrecht", verbose = FALSE)
> myStratification <- stratify(shpMijdrecht, nStrata = 1, nGridCells = 5000)
> mySamplingPattern <- spsample(myStratification, n = 30)
> print(plot(myStratification, mySamplingPattern))
```



x1

```
> mySamplingPoints <- as(mySamplingPattern, "data.frame")
> myData <- doFieldWork(mySamplingPoints)
> str(myData)
```

'data.frame': 30 obs. of 2 variables: \$ clay: num 6.3 13.3 8.2 6.4 6.2 5.9 5 8.1 5.2 15 ... \$ SOM : num 3.3 6.9 4 3 2.9 2.8 2.8 4.2 3.2 7.5 ...

The spatial mean and its standard error can be estimated by:

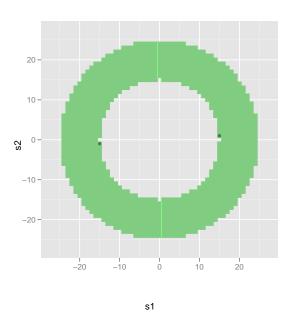
- > estimate("spatial mean", myStratification, mySamplingPattern,
  + myData)
- clay SOM
- 7.876667 3.930000
- $\verb|> estimate("standard error", myStratification, mySamplingPattern,\\$
- + myData)

clay SOM 0.6172554 0.3246979

### 4.3 Sampling of non-convex areas

In case of spatial coverage sampling (e.g., Sections 3.1 and 3.2), sampling the centroid of each cluster may become problematic in case of non-convex areas. A centroid may be situated well outside the area of interest. If this happens, the sampling point will be relocated to the nearest grid cell that is part of the target universe. This pragmatic solution usually gives reasonable results. However, in some extreme situations the solution may be less desirable. As an example, consider the 'doughnut'-shaped field below.

- > myStratification <- stratify(doughnut, nStrata = 2, nTry = 100)
- > mySamplingPattern <- spsample(myStratification)</pre>
- > print(plot(myStratification, mySamplingPattern))



Note that this problem does not arise in random sampling from compact geographical strata (e.g., Sections 3.3 and 3.4).

#### References

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- T. H. Keitt, R. Bivand, E. Pebesma, and B. Rowlingson. rgdal: Bindings for the Geospatial Data Abstraction Library, 2008. URL http://www.gdal.org,http://rgdal.sourceforge.net/,http://sourceforge.net/projects/rgdal/. R package version 0.5-33.
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# A Class hierarchies

The spcosa-package uses S4-type classes and methods. The class hierarchies are visualised below.

