Overview of Unmarked:

An R Package for the Analysis of Data from Unmarked Animals

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Abstract

Unmarked aims to be a complete environment for the statistical analysis of data from surveys of unmarked animals. Currently, the focus is on hierarchical models that separately model a latent state (or states) and an observation process. Unmarked uses S4 classes to help the user explore and analyze their data in a transparent manner.

1 Overview of unmarked

Unmarked provides methods to estimate site occupancy, abundance, and density of animals (or possibly other oganisms/objects) that cannot be detected with certainty. Numerous models are available that correspond to specialized survey methods such as temporally replicated surveys, distance sampling, removal sampling, and double observer sampling. These data are often associated with metadata related to the design of the study. For example, in distance sampling, the study design (line- or point-transect), distance class break points, transect lengths, and units of measurement need to be accounted for in the analysis. Unmarked uses S4 classes to store data and metadata in a way that allows for easy data manipulation, summarization, and model specification. Table 1 lists the currently implemented models and their associated fitting functions and data classes.

| Model | Fitting Function | Data | Citation |
|---------------------------------|------------------|------------------------------|----------|
| Occupancy | occu | unmarkedFrameOccu | [2] |
| Royle-Nichols | occuRN | unmarked Frame Occu | [6] |
| Point Count | pcount | unmarked Frame PC ount | [4] |
| Distance-sampling | distsamp | ${\bf unmarked Frame DS}$ | [5] |
| Arbitrary multinomial-Poisson | multinomPois | ${\bf unmarked Frame MPois}$ | [3] |
| Colonization-extinction | colext | unmarkedMultFrame | [1] |
| Generalized multinomial-mixture | gmultmix | ${\bf unmarkedFrameGMM}$ | [3] |

Table 1: Models handled by unmarked.

Each data class can be created with a call to the constructor function of the same name as described in the examples below.

2 Typical unmarked session

The first step is to import the data into R. This can be accomplished with either a call to the appropriate type of unmarkedFrame:

```
0 0 0 -1.0336137 -1.192602838 1.280934 -1.832910
        0 0 0 -0.8478392 0.917129237 1.808289 -2.618624
      date.2
               date.3 ivel.1 ivel.2 ivel.3
1 0.3099471 1.3813757 -0.5060353 -0.5060353 -0.5060353
2 -1.0471958 0.5956614 -0.9336151 -0.9907486 -1.1621491
3 -0.4757672 1.4528042 -1.1355754 -1.3388644 -1.6099164
4 -0.6900529 1.2385185 -0.8193481 -0.9272669 -1.1970640
5 0.1670899 1.3813757 0.6375563 0.8803737 1.0422520
6 0.1670899 1.3813757 -1.3288666 -1.0422624 -0.8989603
> y <- wt[, 2:4]
> siteCovs <- wt[, c("elev", "forest", "length")]</pre>
> obsCovs <- list(date = wt[, c("date.1", "date.2",</pre>
                                                 "date.3")],
     ivel = wt[, c("ivel.1", "ivel.2", "ivel.3")])
> wt <- unmarkedFrameOccu(y = y, siteCovs = siteCovs, obsCovs = obsCovs)
> summary(wt)
unmarkedFrame Object
237 sites
Maximum number of observations per site: 3
Mean number of observations per site: 2.81
Sites with at least one detection: 79
Tabulation of y observations:
      1 <NA>
   0
 483 182 46
Site-level covariates:
                                           length
      elev
                       forest
 Min. :-1.436125 Min. :-1.265e+00 Min. :0.1823
 1st Qu.:-0.940726 1st Qu.:-9.744e-01 1st Qu.:1.4351
 Median :-0.166666 Median :-6.499e-02 Median :1.6094
 Mean : 0.007612 Mean : 8.798e-05 Mean :1.5924
 3rd Qu.: 0.994425 3rd Qu.: 8.080e-01 3rd Qu.:1.7750
 Max. : 2.434177 Max. : 2.299e+00 Max. :2.2407
Observation-level covariates:
      date
                         ivel
 Min. :-2.9043386 Min. :-1.753e+00
 Mean :-0.0002173 Mean :-3.008e-11
                    3rd Qu.: 5.493e-01
 3rd Qu.: 1.3099471
 Max. : 3.8099471
                     Max. : 5.980e+00
 NA's :42.0000000 NA's : 4.600e+01
or by using the convenience function csvToUMF:
> wt <- csvToUMF(system.file("csv", "widewt.csv", package = "unmarked"),
     long = FALSE, type = "unmarkedFrameOccu")
```

If not all sites have the same numbers of observations, then manual importation of data in long format can be tricky. csvToUMF seemlessly handles this situation.

```
> pcru <- csvToUMF(system.file("csv", "frog2001pcru.csv",
     package = "unmarked"), long = TRUE, type = "unmarkedFrameOccu")
```

To help stabilize the numerical optimization algorithm, we recommend standardizing the covariates.

```
> obsCovs(pcru) <- scale(obsCovs(pcru))
```

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Occupancy models can then be fit with the occu() function:

```
> fm1 <- occu(~1 ~ 1, pcru)
> fm2 <- occu(~MinAfterSunset + Temperature ~ 1, pcru)</pre>
Call:
occu(formula = ~MinAfterSunset + Temperature ~ 1, data = pcru)
Occupancy:
 Estimate
             SE
                   z P(>|z|)
    1.54 0.292 5.26 1.42e-07
Detection:
               Estimate
                           SE
                                   z P(>|z|)
(Intercept)
                0.2098 0.206 1.017 3.09e-01
MinAfterSunset -0.0855 0.160 -0.536 5.92e-01
                -1.8936 0.291 -6.508 7.60e-11
Temperature
AIC: 356.7591
```

Here, we have specified that the detection process is modeled with the MinAfterSunset and Temperature covariates. No covariates are specified for occupancy here. See ?occu for more details.

Unmarked fitting functions return unmarked Fit objects which can be queried to investigate the model fit. Variables can be back-transformed to the unconstrained scale using back Transform. Standard errors are computed using the delta method.

Because the detection component was modeled with covariates, covariate coefficients must be specified to back-transform. Here, we request the probability of detection given a site is occupied and all covariates are set to 0.

```
> backTransform(linearComb(fm2, coefficients = c(1, 0,
     0), type = "det"))
Backtransformed linear combination(s) of Detection estimate(s)
              SE LinComb (Intercept) MinAfterSunset Temperature
 Estimate
    0.552 0.051
                 0.210
                                   1
Transformation: logistic
A predict method also exists.
> newData <- data.frame(MinAfterSunset = 0, Temperature = -2:2)
> predict(fm2, type = "det", newdata = newData, appendData = TRUE)
                     SF.
                                        upper MinAfterSunset
   Predicted
                            lower
1 0.98196076 0.01266193 0.9306044 0.99549474
2 0.89123189 0.04248804 0.7763166 0.95084836
                                                           0
3 0.55225129 0.05102660 0.4514814 0.64890493
                                                           0
4 0.15658708 0.03298276 0.1021713 0.23248007
                                                           0
5 0.02718682 0.01326263 0.0103505 0.06948653
  Temperature
            -2
2
            -1
3
            0
4
            1
            2
5
```

Confidence intervals are requested with confint, using either the asymptotic normal approximation or profiling.

```
> confint(fm2, type = "det")
                      0.025
                                 0.975
p(Int)
                 -0.1946872 0.6142292
p(MinAfterSunset) -0.3985642 0.2274722
p(Temperature) -2.4638797 -1.3233511
> confint(fm2, type = "det", method = "profile")
Profiling parameter 1 of 3 ... done.
Profiling parameter 2 of 3 ... done.
Profiling parameter 3 of 3 ... done.
                      0.025
                                 0.975
                 -0.1929210 0.6208837
p(Int)
p(MinAfterSunset) -0.4044794 0.2244221
p(Temperature)
                 -2.5189984 -1.3789261
```

Model selection and multi-model inference can be implemented after organizing models using the fitList function.

```
> fms <- fitList(Null = fm1, TimeTemp = fm2)
> modSel(fms, nullmod = "Null")
                AIC delta AICwt cumltvWt Rsq
        nPars
TimeTemp
            4 356.76 0.00 1.0e+00 1.00 0.58
                                       1.00 0.00
Null
            2 461.00 104.25 2.3e-23
> predict(fms, type = "det", newdata = newData, appendData = TRUE)
   Predicted
                   SE
                             lower
                                        upper MinAfterSunset
1\ 0.98196076\ 0.01266193\ 0.957143378\ 1.00677814
2 0.89123189 0.04248804 0.807955332 0.97450844
                                                           0
                                                           0
3 0.55225129 0.05102660 0.452239161 0.65226342
4 0.15658708 0.03298276 0.091940874 0.22123328
                                                           0
                                                           0
5 0.02718682 0.01326263 0.001192059 0.05318158
  Temperature
          -2
2
           -1
3
           0
4
           1
5
           2
```

Parametric bootstrapping can be used to check the adequacy of model fit.

```
> pcru.pb <- parboot(fm2, statistic = SSE, nsim = 50)
> pcru.pb
Call: parboot(object = fm2, statistic = SSE, nsim = 50)
Parametric Bootstrap Statistics:
   t0 mean(t0 - t_B) StdDev(t0 - t_B) Pr(t_B > t_D)
SSE 61
                0.972
                                 3.46
                                             0.314
t_B quantiles:
   0% 2.5% 25% 50% 75% 97.5% 100%
SSE 52 54 58 59 62
                        67
t0 = Original statistic compuated from data
t_B = Vector of bootstrap samples
```

This example suggests an adequate fit.

References

[1] Darryl I. MacKenzie, James D. Nichols, James E. Hines, Melinda G. Knutson, and Alan B. Franklin. Estimating site occupancy, colonization, and local extinction when a species is detected imperfectly. Ecology, 84(8):2200-2207, 2003.

- [2] Darryl I. MacKenzie, James D. Nichols, G. B. Lachman, S. Droege, J. A. Royle, and C. A. Langtimm. Estimating site occupancy rates when detection probabilities are less than one. *Ecology*, 83(8):2248–2255, 2002.
- [3] J. A. Royle. Generalized estimators of avian abundance from count survey data. *Animal Biodiversity and Conservation*, 27(1):375–386, 2004.
- [4] J. A Royle. N-mixture models for estimating population size from spatially replicated counts. Biometrics, 60(1):108-115, 2004.
- [5] J. A. Royle, D. K. Dawson, and S. Bates. Modeling abundance effects in distance sampling. *Ecology*, 85(6):1591–1597, 2004.
- [6] J. A. Royle and J. D. Nichols. Estimating abundance from repeated presence-absence data or point counts. *Ecology*, 84(3):777-790, 2003.