# Package 'utilityFunctionTools'

August 20, 2025

Type Package
Title P-Spline Regression for Utility Functions and Derived Measures
Description Predicts a smooth and continuous (individual) utility function from utility points, and computes measures of intensity for risk and higher-order risk measures (or any other measure computed with user-written function) based on this utility function and its derivatives according to the method introduced in Schneider (2017) <a href="http://hdl.handle.net/21.11130/00-1735-0000-002E-E306-0">http://hdl.handle.net/21.11130/00-1735-0000-002E-E306-0</a> .
Version 1.0
Maintainer Sebastian O. Schneider <sschneider@coll.mpg.de></sschneider@coll.mpg.de>
URL https://www.sebastianoschneider.com
License GPL-3
Imports spatstat.geom
Encoding UTF-8
RoxygenNote 7.3.2
Contents
bbase
compute_function
compute_higher_order_risk_preferences
compute_measures
derivative
estimate_model
evaluate_cross_validation
find_optimal_lambda
tpower
Index 1

2 compute\_function

bbase	Constructs a B-spline basis of degree 'deg' (Code by Paul Eilers, Pack-
	age JOPS, http://statweb.lsu.edu/faculty/marx/JOPS_0.1.0.tar.gz).

## **Description**

Constructs a B-spline basis of degree 'deg' (Code by Paul Eilers, Package JOPS, http://statweb.lsu.edu/faculty/marx/JOPS

## Usage

```
bbase(x, xl = min(x), xr = max(x), ndx = 20, deg = 6)
```

## **Arguments**

X	values for the x axis.
xl	minimum value, default is the minimum value of the x-values.
xr	maximum value, default is maximum value of the x-values.
ndx	number of intervals to partition the distance between xl and xr.
deg	degree of the B-spline basis.

#### Value

a B-spline basis of degree deg and ndx + 1 internal knots.

## **Examples**

```
x_{finegrid} \leftarrow seq(0.001, 1.0, (1.0 - 0.001) / 1000) bbase(x_{finegrid})
```

 $compute\_function$ 

Computes a continuous and smooth utility function from the given utility points

## Description

Computes a continuous and smooth utility function from the given utility points

## Usage

```
compute_function(
    x,
    y,
    ids = NULL,
    mode = 1,
    penalty_order = 4,
    lambda_max = 10000,
    current_lambda = 1,
    ndx = 20,
    deg = 6,
    verbose = 0
```

## **Arguments**

X	a matrix or dataframe containing the certainty equivalents (x-values of utility points) for a given participant in each use case.
У	can be a vector or a matrix representing the corresponding utility values (y-values of utility points).
ids	a list containing the IDs of the participants. If not given, a list with IDs from 1 to $n_{observations}$ will be created.
mode	an integer between 0, 1, 2 representing the three possible modes: multiple imputation, optimal classification or 'weak' classification. Default is optimal classification (1).
penalty_order	highest dimension (i.e., derivative) to penalize. Must be lower than deg.
lambda_max	maximum lambda used for computing the optimal lambda. It is used only in multiple imputation (mode = $0$ ) and optimal (mode = $1$ ). The default value is $10000$ .
current_lambda	lambda considered in the current iteration. Only used in multiple imputation (mode $= 0$ ) to create the combinations and as actual lambda value in 'weak' classification mode (mode $= 2$ ). The default value is 1.
ndx	number of intervals to partition the distance between the lowest and highest x-values of the utility points.
deg	degree of the B-spline basis. Determines the degree of the function to be estimated. If deg = 2, the estimated utility function will consist of quadratic functions.
verbose	shows some information while the program is running.

## Value

A smooth and continuous utility function.

## **Examples**

```
compute_higher_order_risk_preferences
```

Computes a continuous and smooth function according to the given utility points

## Description

Computes a continuous and smooth function according to the given utility points

#### Usage

```
compute_higher_order_risk_preferences(
    x,
    y,
    ids = NULL,
    mode = 1,
    penalty_orders = c(4),
    ndx = 20,
    deg = 6,
    measures = c("risk-arrow-pratt", "crainich-eeckhoudt", "denuit-eeckhoudt"),
    ...,
    root_filename = NULL,
    verbose = 0
)
```

## Arguments

х	a matrix or dataframe containing the certainty equivalents (x-values of utility points) for a given participant in each use case.
у	can be a vector or a matrix representing the corresponding utility values (y-values of utility points).
ids	a list containing the IDs of the participants. If not given, a list with IDs from 1 to n_observations will be created.
mode	an integer between 0, 1, 2 representing the three possible modes: multiple imputation, optimal classification or 'weak' classification. Default is optimal classification (1).
penalty_orders	vector or constant that contains the derivates that will be smoothened. The values in this vector should not be larger than 4.
ndx	number of intervals to partition the distance between the lowest and highest x-values of the utility points.
deg	degree of the B-spline basis. Determines the degree of the function to be estimated. If deg = 2, the estimated utility function will consist of quadratic functions.
measures	the utility based (intensity) measures to be computed.
	additional parameters for user-defined measures.
root_filename	filename containing the location of where the output files are going to be saved.
verbose	shows some information while the program is running.

## Value

A smooth and continuous function.

## **Examples**

compute\_measures 5

```
# could be used with root_filename argument:
# Linux
# outfile <- paste(dirname(getwd()), "/out", sep="")
# Win
# outfile <- paste(dirname(getwd()), "\out", sep="")
compute_higher_order_risk_preferences(x, y, mode = 2, verbose = 1)</pre>
```

compute\_measures

Given a set of smooth and continuous functions, computes predefined and user-defined measures.

## Description

Given a set of smooth and continuous functions, computes predefined and user-defined measures.

## Usage

```
compute_measures(
  x_grids,
  coeffs,
  ids = NULL,
  ndx = 20,
  deg = 6,
  measures = c("risk-arrow-pratt", "crainich-eeckhoudt", "denuit-eeckhoudt"),
  ...
)
```

#### **Arguments**

x_grids	a dataframe of vectors of x values for a smooth and continuous function.
coeffs	a dataframe of coefficients for a smooth and continous function for each participant.
ids	a list containing the IDs of the participants. If not given, a list with IDs from 1 to $n\_observations$ will be created.
ndx	number of intervals to partition the distance between the lowest and highest $x$ -values of the utility points.
deg	degree of the B-spline basis. Determines the degree of the function to be estimated. If $deg = 2$ , the estimated utility function will consist of quadratic functions.
measures	a vector of measures to be computed.
	additional parameters for user-defined measures.

## Value

A set of measurements.

6 derivative

#### **Examples**

derivative

Computes the derivative of a function

#### **Description**

Computes the derivative of a function

#### Usage

```
derivative(x, coeffs, degree = 1, ndx = 20, deg = 6)
```

#### **Arguments**

x the x values for which the derivative should be computed.

coeffs the coefficient.

degree the degree of the derivative.

ndx number of intervals to partition the distance between the lowest and highest x-

values of the utility points.

degree of the B-spline basis. Determines the degree of the function to be esti-

mated. If deg = 2, the estimated utility function will consist of quadratic func-

tions.

#### Value

the derivative of the specified degree.

#### **Examples**

```
coeffs <- seq(0.000002, 1.0, (1.0 - 0.000002) / 25) x <- seq(0.01, 1.0, (1.0 - 0.01) / 5) derivative(x, coeffs)
```

estimate\_model 7

estimate\_model

Estimates the model

#### **Description**

Estimates the model

#### Usage

```
estimate_model(
   xi,
   yi,
   lambda = 1,
   n_penalty_dimensions = 1,
   penalty_order = 4,
   ndx = 20,
   deg = 6,
   cross_validation_mode = 0,
   return_estimate = 0,
   left_out_xi = c(),
   left_out_yi = c()
)
```

#### **Arguments**

xi a vector containing the certainty equivalents (x-values of utility points) for a

given participant in each use case.

yi can be a vector or a matrix representing the corresponding utility values (y-

values of utility points).

lambda is the penalization weight used to compute the initial estimate. The

default value is 1.

n\_penalty\_dimensions

number of dimensions (i.e., derivatives) to penalize. Possible values are 1 or 2.

The default value is 1.

penalty\_order highest dimension (i.e., derivative) to penalize. Must be lower than deg.

ndx number of intervals to partition the distance between the lowest and highest x-

values of the utility points.

degree of the B-spline basis. Determines the degree of the function to be esti-

mated. If deg = 2, the estimated utility function will consist of quadratic func-

tions.

cross\_validation\_mode

determines which cross validation mode should be used. If 0, then the cross validation method is leave-one-third-out. If 1, then the cross validation method is a theoretical leave-one-out, i.e., based on a formula. The default value is 1.

return\_estimate

parameter that indicates whether or not to return the (initially) estimated coefficients. Default is false.

left\_out\_xi needed for cross validation: the x-values of the points that are left out for fitting

the model, so that they can be predicted

left\_out\_yi needed for cross validation: the y-values of the points that are left out for fitting

the model, so that they can be predicted

#### Value

Returns the sum of residuals of the prediction of the left-out points using cross validation. If specified, additionally returns the estimated coefficients of the utility function (in the B-spline basis).

#### **Examples**

evaluate\_cross\_validation

Evaluates the cross validation function.

## **Description**

Evaluates the cross validation function.

## Usage

```
evaluate_cross_validation(
   xi,
   yi,
   lambda = 1,
   n_penalty_dimensions = 1,
   penalty_order = 4,
   ndx = 20,
   deg = 6,
   cross_validation_mode = 0
)
```

#### **Arguments**

xi a vector containing the certainty equivalents (x-values of utility points) for a

given participant in each use case.

yi can be a vector or a matrix representing the corresponding utility values (y-

values of utility points).

lambda is the penalization weight used to compute the initial estimate. The

default value is 1.

n\_penalty\_dimensions

number of dimensions (i.e., derivatives) to penalize. Possible values are 1 or 2.

The default value is 1.

penalty\_order highest dimension (i.e., derivative) to penalize. Must be lower than deg.

ndx number of intervals to partition the distance between the lowest and highest x-

values of the utility points.

degree of the B-spline basis. Determines the degree of the function to be esti-

mated. If deg = 2, the estimated utility function will consist of quadratic func-

tions.

cross\_validation\_mode

determines which cross validation mode should be used. If 0, then the cross validation method is leave-one-third-out. If 1, then the cross validation method is a theoretical leave-one-out, i.e., based on a formula. The default value is 1.

find\_optimal\_lambda 9

#### Value

Returns, for the given utility points and (possibly default) settings, the predictive quality of the estimated utility function according to cross validation as a function of a specified penalty weight lambda

#### **Examples**

```
x \leftarrow c(0.0000000, 0.2819824, 0.3007812, 0.4375000, 0.5231934, 0.7784882, 0.8945312, 1.0000000) y \leftarrow c(0.0000, 0.1250, 0.2500, 0.5000, 0.6250, 0.6875, 0.7500, 1.0000) evaluate_cross_validation(x, y, .5)
```

 ${\tt find\_optimal\_lambda}$ 

Finds an optimal penalty weight lambda given the parameters

## **Description**

Finds an optimal penalty weight lambda given the parameters

#### Usage

```
find_optimal_lambda(
    xi,
    yi,
    lambda_max = 10000,
    n_penalty_dimensions = 1,
    penalty_order = 4,
    ndx = 20,
    deg = 6,
    cross_validation_mode = 0,
    grid_dim = 5
)
```

## **Arguments**

xi	a vector	containing	the certainty	equivalents	(x-values of	of utility	points) fo	r a

given participant in each use case.

yi can be a vector or a matrix representing the corresponding utility values (y-

values of utility points).

lambda\_max maximum lambda used for computing the optimal lambda. The default value is

10000.

n\_penalty\_dimensions

number of dimensions (i.e., derivatives) to penalize. Possible values are 1 or 2.

The default value is 1.

penalty\_order highest dimension (i.e., derivative) to penalize. Must be lower than deg.

ndx number of intervals to partition the distance between the lowest and highest x-

values of the utility points.

degree of the B-spline basis. Determines the degree of the function to be esti-

mated. If deg = 2, the estimated utility function will consist of quadratic func-

tions.

10 tpower

cross\_validation\_mode

determines which cross validation mode should be used. If 0, then the cross validation method is leave-one-third-out. If 1, then the cross validation method is a theoretical leave-one-out, i.e., based on a formula. The default value is 1.

grid\_dim

dimension of the search grid for the initial grid search before the actual optimization. Default value is 5.

#### Value

the optimal lambda for the given set of utility points and (possibly default) settings according to the specified cross validation method.

## **Examples**

tpower

Truncated p-th power function. Helper function for creating the B-Spline basis (Code by Paul Eilers, Package JOPS, http://statweb.lsu.edu/faculty/marx/JOPS\_0.1.0.tar.gz)

#### **Description**

Truncated p-th power function. Helper function for creating the B-Spline basis (Code by Paul Eilers, Package JOPS, http://statweb.lsu.edu/faculty/marx/JOPS\_0.1.0.tar.gz)

#### Usage

```
tpower(x, t, p)
```

## **Arguments**

x Function value.t Point of truncation.

p degree of the truncated polynomial function.

#### Value

Returns a piece-wise defined basis functions for x > t.

## **Examples**

```
tpower(1, 2, 3)
```

## **Index**