

Basis

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Outline

- What is a basis for a subspace?
- Confirming that a set is a basis for a subspace
- Reference: Textbook 4.2

What is Basis?

Any set

Basis

Why nonzero?

- Let V be a nonzero subspace of \mathbb{R}^n . A **basis** B for V is a **linearly independent generation set** of V .

$\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_n\}$ is a basis for \mathbb{R}^n .

- $\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_n\}$ is independent
- $\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_n\}$ generates \mathbb{R}^n .

$\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$ is a basis for \mathbb{R}^2

$\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \end{bmatrix} \right\} \left\{ \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \begin{bmatrix} -3 \\ 1 \end{bmatrix} \right\} \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}$ any two independent vectors form a basis for \mathbb{R}^2

Basis

- The pivot columns of a matrix form a basis for its columns space.

$$\begin{bmatrix} \boxed{1} & 2 & \boxed{-1} & \boxed{2} & 1 & 2 \\ \boxed{-1} & -2 & \boxed{1} & \boxed{2} & 3 & 6 \\ 2 & 4 & -3 & 2 & 0 & 3 \\ \boxed{-3} & -6 & \boxed{2} & \boxed{0} & 3 & 9 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} \boxed{1} & 2 & \boxed{0} & \boxed{0} & -1 & -5 \\ \boxed{0} & 0 & \boxed{1} & \boxed{0} & 0 & -3 \\ \boxed{0} & 0 & \boxed{0} & \boxed{1} & 1 & 2 \\ \boxed{0} & 0 & \boxed{0} & \boxed{0} & 0 & 0 \end{bmatrix}$$

pivot columns

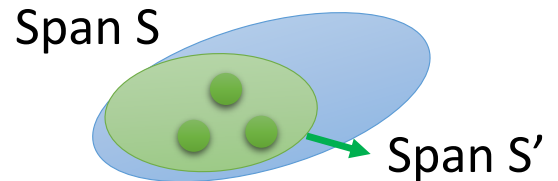
$$\text{Col A} = \text{Span} \left\{ \begin{bmatrix} 1 \\ -1 \\ 2 \\ -3 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ -3 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 2 \\ 0 \end{bmatrix} \right\}$$

Property

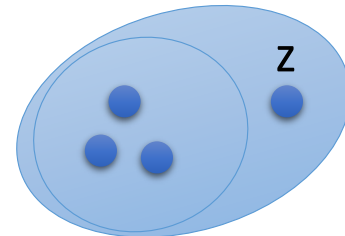
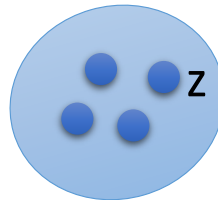
- (a) S is contained in $\text{Span } S$

Basis is always in its subspace

- (b) If a finite set S' is contained in $\text{Span } S$, then $\text{Span } S'$ is also contained in $\text{Span } S$
 - Because $\text{Span } S$ is a subspace



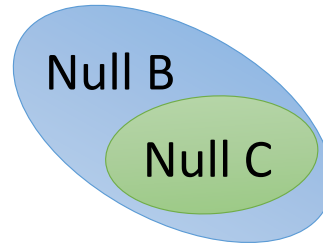
- (c) For any vector z , $\text{Span } S = \text{Span } S \cup \{z\}$ if and only if z belongs to the $\text{Span } S$



Theorem

- 1. A basis is the **smallest** generation set.
- 2. A basis is the **largest** independent vector set in the subspace.
- 3. Any two bases for a subspace **contain the same number of vectors**.
 - The number of vectors in a basis for a nonzero subspace V is called **dimension** of V ($\dim V$).

Theorem 3



- Any two bases of a subspace V contain the same number of vectors

Suppose $\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$ and $\{\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_p\}$ are two bases of V .

Let $A = [\mathbf{u}_1 \ \mathbf{u}_2 \ \dots \ \mathbf{u}_k]$ and $B = [\mathbf{w}_1 \ \mathbf{w}_2 \ \dots \ \mathbf{w}_p]$.

Since $\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$ spans V , $\exists \mathbf{c}_i \in \mathcal{R}^k$ s.t. $A\mathbf{c}_i = \mathbf{w}_i$ for all i

$$\Rightarrow A[\mathbf{c}_1 \ \mathbf{c}_2 \ \dots \ \mathbf{c}_p] = [\mathbf{w}_1 \ \mathbf{w}_2 \ \dots \ \mathbf{w}_p] \Rightarrow AC = B$$

$$\text{Now } C\mathbf{x} = \mathbf{0} \text{ for some } \mathbf{x} \in \mathcal{R}^p \Rightarrow AC\mathbf{x} = B\mathbf{x} = \mathbf{0}$$

B is independent vector set $\Rightarrow \mathbf{x} = \mathbf{0} \Rightarrow \mathbf{c}_1 \ \mathbf{c}_2 \ \dots \ \mathbf{c}_p$ are independent

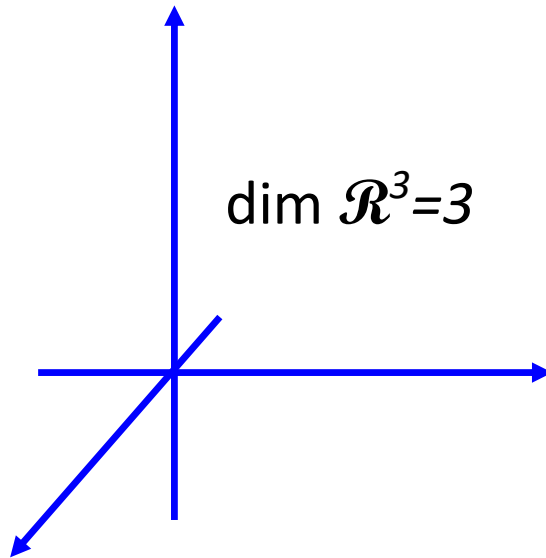
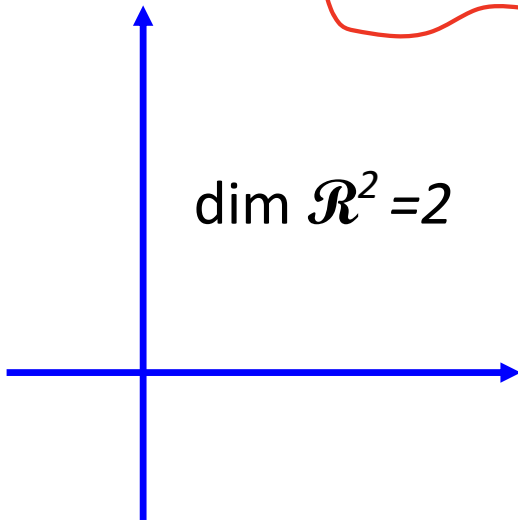
$$\mathbf{c}_i \in \mathcal{R}^k \Rightarrow p \leq k$$

Reversing the roles of the two bases one has $k \leq p \Rightarrow p = k$.

Theorem 3

Every basis of \mathcal{R}^n
has n vectors.

- The number of vectors in a basis for a subspace V is called the dimension of V , and is denoted $\dim V$
 - The dimension of zero subspace is 0



Example

$$V = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \in \mathcal{R}^4 : \cancel{x_1 - 3x_2 + 5x_3 - 6x_4 = 0} \right. \\ \left. x_1 = 3x_2 - 5x_3 + 6x_4 \right\}$$

Find $\dim V$
 $\dim V = 3$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 3x_2 - 5x_3 + 6x_4 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

Basis? Independent vector set that
generates V



Theorem 1

A basis is the smallest generation set.

反例

If there is a generation set S for subspace V ,

The size of basis for V is smaller than or equal to S .

Reduction Theorem

There is a basis containing in any generation set S .

S can be reduced to a basis for V by removing some vectors.

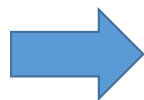
Theorem 1 – Reduction Theorem

所有的 generation set 心中都有一個 basis

S can be reduced to a basis for V by removing some vectors.

Suppose $S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$ is a generation set of subspace V

Subspace $V = \text{Span } S$ Let $A = [\mathbf{u}_1 \ \mathbf{u}_2 \ \cdots \ \mathbf{u}_k]$.
 $= \text{Col } A$



The basis of $\text{Col } A$ is the pivot columns of A Subset of S

Theorem 1 – Reduction Theorem

所有的 generation set 心中都有一個 basis

$$\text{Subspace } V = \text{Span } S = \text{Col } A = \text{Span} \left\{ \begin{bmatrix} 1 \\ -1 \\ 2 \\ -3 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ -3 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 2 \\ 0 \end{bmatrix} \right\}$$

Smallest generation set

$$S = \left\{ \begin{bmatrix} 1 \\ -1 \\ 2 \\ -3 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \\ 4 \\ 6 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ -3 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 6 \\ 3 \\ 9 \end{bmatrix} \right\}$$

Generation set

$$A = \begin{bmatrix} 1 & 2 & -1 & 2 & 1 & 2 \\ -1 & -2 & 1 & 2 & 3 & 6 \\ 2 & 4 & -3 & 2 & 0 & 3 \\ -3 & -6 & 2 & 0 & 3 & 9 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 2 & 0 & 0 & -1 & -5 \\ 0 & 0 & 1 & 0 & 0 & -3 \\ 0 & 0 & 0 & 1 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Theorem 2

A basis is the largest independent set in the subspace.

If the size of basis is k , then you cannot find more than k *independent* vectors in the subspace.

Extension Theorem

SILS

Given an independent vector set S in the space

S can be extended to a basis by adding more vectors

Theorem 2 – Extension Theorem

Independent set:

我不是一個 basis 就是正在成為一個 basis

There is a subspace V

Given a independent vector set S (elements of S are in V)

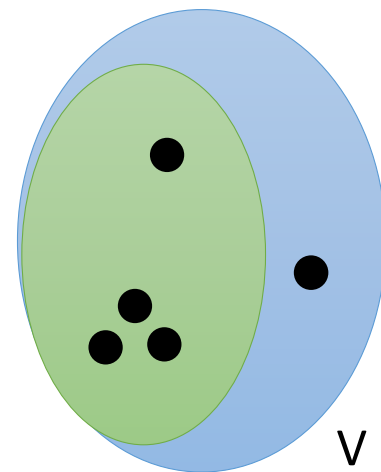
- If $\text{Span } S = V$, then S is a basis
- If $\text{Span } S \neq V$, find v_1 in V , but not in $\text{Span } S$

$S = S \cup \{v_1\}$ is still an independent set

- If $\text{Span } S = V$, then S is a basis
- If $\text{Span } S \neq V$, find v_2 in V , but not in $\text{Span } S$

$S = S \cup \{v_2\}$ is still an independent set

..... You will find the basis in the end.



More from Theorems

A basis is the smallest generation set.

A vector set generates \mathcal{R}^m must contain at least m vectors.

\mathcal{R}^m have a basis $\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_m\}$

Because a basis is the smallest generation set

Any other generation set has at least m vectors.

A basis is the largest independent set in the subspace.

Any independent vector set in \mathcal{R}^m contain at most m vectors.

Summary

雕塑 ... 主要是使用雕（通過減除材料來造型）及塑（通過疊加材料來造型）的方式 (from wiki)



Generation
set

刪去



Basis

Same size

疊加



Independent
vector set

Confirming that
a set is a Basis

Intuitive Way

- Definition: A **basis** B for V is an independent generation set of V .

$$V = \left\{ \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} \in \mathcal{R}^3 : v_1 - v_2 + 2v_3 = 0 \right\} \quad \mathcal{C} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \right\}$$

Is \mathcal{C} a basis of V ?

Independent? **yes**

Generation set? **difficult**

$$\mathcal{C} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \right\} \text{ generates } V$$

Another way

Find a basis for V

- Given a subspace V , assume that we already know that $\dim V = k$. Suppose S is a subset of V with k vectors

If S is independent \longrightarrow S is basis

If S is a generation set \longrightarrow S is basis

$$V = \left\{ \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} \in \mathcal{R}^3 : v_1 - v_2 + 2v_3 = 0 \right\} \quad \mathcal{C} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \right\}$$

$\dim V = 2$ (parametric representation)

Is \mathcal{C} a basis of V ?

\mathcal{C} is a subset of V with 2 vectors
Independent? **yes** \longrightarrow \mathcal{C} is a basis of V

Another way

Assume that $\dim V = k$. Suppose
 S is a subset of V with k vectors

If S is independent  S is basis

By the extension theorem, we can add more vector into S to form a basis.

However, S already have k vectors, so it is already a basis.

If S is a generation set  S is basis

By the reduction theorem, we can remove some vector from S to form a basis.

However, S already have k vectors, so it is already a basis.

Example

- Is \mathcal{B} a basis of V ?

$$V = \left\{ \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix} \in \mathcal{R}^4 : v_1 + v_2 + v_4 = 0 \right\} \quad \mathcal{B} = \left\{ \begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \\ -1 \end{bmatrix} \right\}$$

Independent set in V ? **yes**

Dim $V = ?$ 3  \mathcal{B} is a basis of V .

Example

- Is \mathcal{B} a basis of $V = \text{Span } \mathcal{S}$?

\mathcal{B} is a subset of V with 3 vectors

$$\mathcal{S} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 3 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix} \right\} \quad \mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} \right\}$$

$$A = \begin{bmatrix} 1 & -1 & 3 & 1 \\ 1 & 3 & 1 & 1 \\ 1 & 1 & -1 & -1 \\ 2 & -1 & 1 & -1 \end{bmatrix} \xrightarrow{\text{blue arrow}} R_A = \begin{bmatrix} 1 & 0 & 0 & -2/3 \\ 0 & 1 & 0 & 1/3 \\ 0 & 0 & 1 & 2/3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \text{dim} A = 3$$

$$B = \begin{bmatrix} 1 & 1 & 0 \\ 2 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \xrightarrow{\text{blue arrow}} R_B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{Independent} \xrightarrow{\text{blue arrow}} \mathcal{B} \text{ is a basis of } V.$$

如何求一个 basic?

- ① 将 subspace M 约束化为矩阵 A , 使得 $\text{col } A = \text{subspace}$, 然后对 A 做行初等变换得到 R (REF), 然后对 A 的 pivot column 就是基, 由此也得到了 \dim
- ② 如果已经知道了 \dim , 那就直接找 \dim 个线性无关向量就行

如何证明一个 V 是 basic?

先看 V 是不是线性无关, 再由上述方法①得到 \dim , 看 $|V| = \dim$