I declare an environment!

Reproducibility with and without Docker

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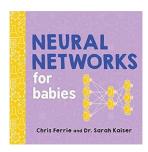
Sr. Developer Advocate @ Microsoft

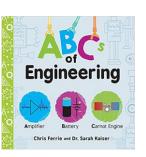




Hiya!

- \$\forall \text{Experimental Physicist by training}\$
- 🦮 Chewie kibble delivery
- Language
 Author of books for all ages
- X Plays anything Final Fantasy
- — Usually floating near Seattle



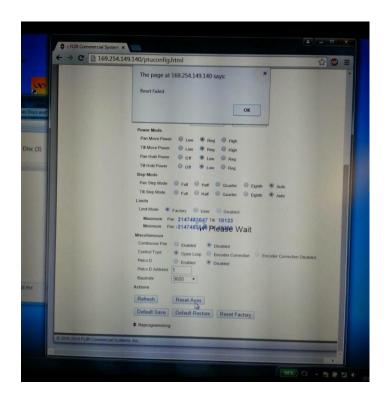






Computers do the darndest things

- Install updates
- Get lost
- Get arrested
- Fall out of orbit
- Get sat on
- Catch on fire





What is the best way to make sure my ____ works tomorrow?

Project, lab, house, car, etc.



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tl;dr

1. Good reproducible environments need declarative and imperative specs.

2. A combination of Docker and Nix can make reproducible Python projects easier!

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Reproducible...



for who?



on what device?



when?



with what resources?

...Environments!



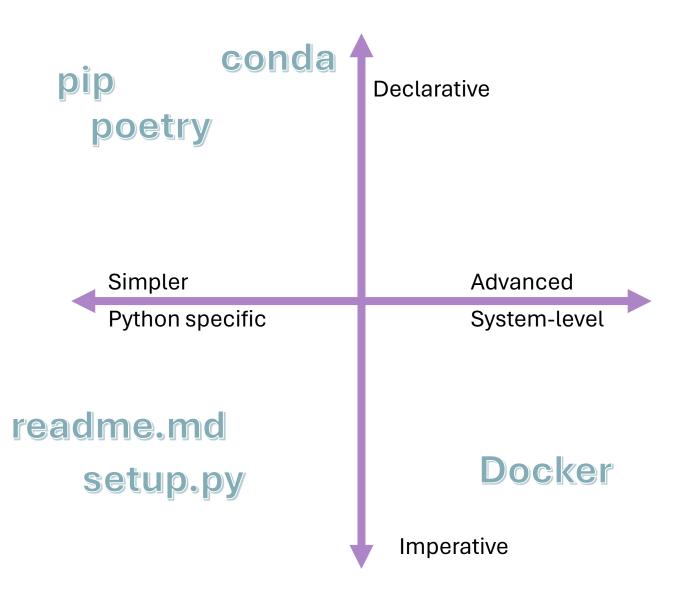
Declarative: Describe the desired final state as completely as possible



Imperative: Provide a

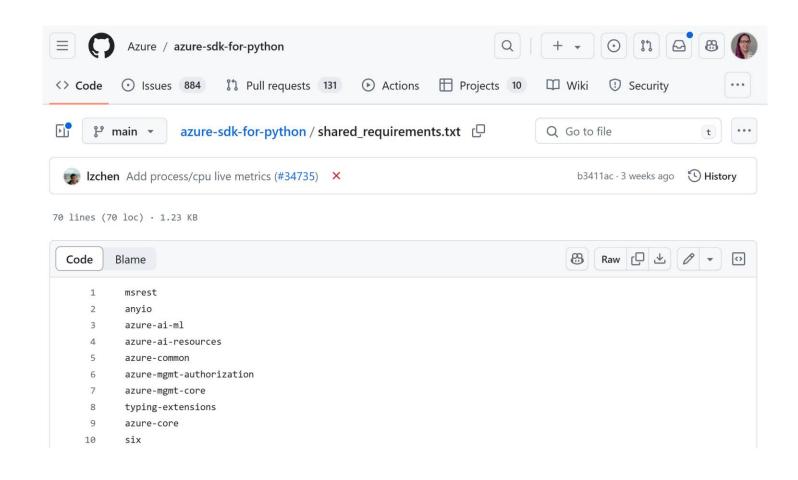
list of steps or actions

What kinds of tools do people use?



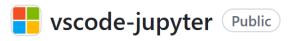
Simple declarative: requirements.txt

- pyproject.toml`, environment.yml`
- May not capture all non-Python requirements
- Can be hard to manage without additional tools

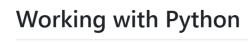


Simple imperative: readme.md

- Easy to write
- Hard to maintain
- Need to test, automation testing can help



Code of conduct



Quick Start

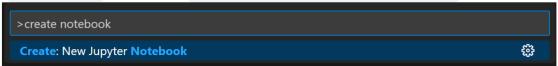
□ README

- Step 1. Install VS Code
- **Step 2.** Install <u>Anaconda/Miniconda</u> or another Python environment in which you've installed the Jupyter package

MIT license

Security

- Since not working with Python, make sure to have a <u>Jupyter Kernel</u> that corresponds to the language you would like to use installed on your machine.
- Step 3. Install the Jupyter Extension and the Python Extension
- **Step 4.** Open or create a notebook file by opening the Command Palette (Ctrl+Shift+P) and select Jupyter: Create New Jupyter Notebook.



• **Step 5.** Select your kernel by clicking on the kernel picker in the top right of the notebook or by invoking the Notebook: Select Notebook Kernel command and start coding!



Advanced Imperative: Dockerfile

```
FROM mcr.microsoft.com/devcontainers/miniconda:0.202.19-3
  RUN conda install -n base -c conda-forge mamba
  COPY environment.yml* .devcontainer/noop.txt /tmp/conda-tmp/
  RUN if [ -f "/tmp/conda-tmp/environment.yml"
    ]; then umask 0002 && /opt/conda/bin/mamba env create -f /tmp/
  conda-tmp/environment.yml; fi && rm -rf /tmp/conda-tmp
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```

Why Docker?

- Pros:
 - Supported most places
 - Easy to hack fixes in
 - Works with Dev Containers!



- Cons:
 - Installing and learning Docker is not trivial
 - Easy to hack fixes in
 - Devices may not support



Something is missing...



. Advanced Declarative: Nix

A language for declarative environments

Nix ecosystem

Nixpkgs

 The largest, most up-to-date software distribution in the world, and written in the Nix language.

NixOS

 Entire operating system that bootstraps from the nix package manager and nix-shell

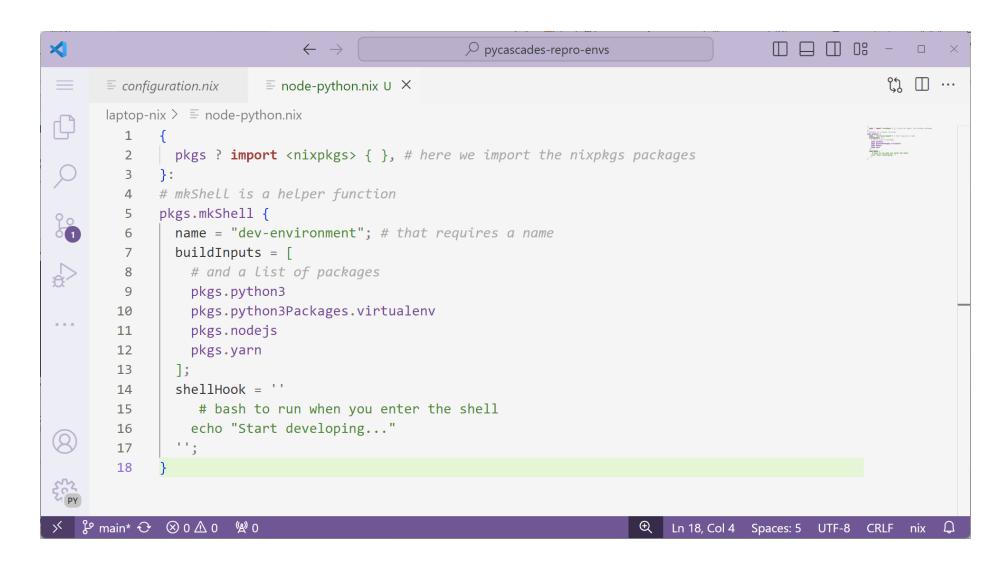
nix-shell

Declarative shell environments

Advanced Declarative: nix-shell

```
[nix-shell:~]$ nix-shell -p python3
this path will be fetched (11.42 MiB download, 62.64 MiB unpacked):
    /nix/store/pwy30a7siqrkki9r7xd1lksyv9fg4l1r-python3-3.10.11
copying path '/nix/store/pwy30a7siqrkki9r7xd1lksyv9fg4l1r-python3-3.10.11'
from 'https://cache.nixos.org' ...
[nix-shell:~]$ python --version
Python 3.10.11
```

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Software

KDE Plasma Version: 5.23.3

KDE Frameworks Version: 5.87.0

Qt Version: 5.15.3

Kernel Version: 5.10.117 (64-bit)

Graphics Platform: Wayland

Hardware

inboard

Processors: 2 × Intel® Core™ i5-3427U CPU @ 1.80

Memory: 1.9 GiB of RAM

Graphics Processor: SVGA3D; build: RELEASE; LLVM;

Why Nix?

• Pros:

- Package manager covers whole system
- Uses similar container infra to Docker so it can interoperate
- Efficient cache management

• Cons:

- Not as widespread in Python community
- Can be harder to write in the first place to get it just right

Ok, what should I choose?



In a vacuum, I would go fully declarative via Nix.

In real life, why not both?!

Start with Nix:

- Make a shell.nix to specify a project environment
- Add Python and any other tools needed (e.g.: LLVM, Clang, Fortran, etc.)
- Use direnv/pipenv to activate a Nix environment when you enter a directory

add Docker when it gets hard:

- -Use nix-shell in a Docker container for portability
- -Describe the steps that are hard to make declarative
- Export nix package to an OCI images for interoperability

Sample python project config

de Case study:

My home lab



Requirements:

- Needs to be portable across devices/hardware
- Runs/hosts Docker containers and local services
 - Home Assistant
 - PiHole
 - Wiki
 - Networking
 - Etc.
- Easy to maintain and back up





The NixOS experiment

- Declare the entire operating system and put it in source control
- Needed to use docker to hack some pieces in we couldn't get to work right
- We are still learning 😜

Sample NixOS file: Hardware

```
{ config, pkgs, ... }:
  imports =
    [ # Include the results of the hardware scan.
      ./hardware-configuration.nix
      <home-manager/nixos>
    ];
 # BootLoader.
  boot.loader.systemd-boot.enable = true;
  boot.loader.efi.canTouchEfiVariables = true;
 # Define your hostname.
  networking.hostName = "nixos-demo";
 # Enable networking
 networking.networkmanager.enable = true;
  services.tailscale.enable = true;
  services.flatpak.enable = true;
 # Set your time zone.
 time.timeZone = "America/Los_Angeles";
```

Sample NixOS file: Users

```
# Define a user account.
 users.users.demouser = {
    isNormalUser = true;
    description = "demouser";
    extraGroups = [ "networkmanager" "wheel"
"docker"];
    packages = with pkgs; [
        discord
        slack
        signal-desktop
        element-desktop
        hyper
   ];
```

Sample NixOS file: Home manager

```
home-manager.users.demouser = { pkgs, ... }:
  home.packages = [ pkgs.atool pkgs.httpie ];
  programs.bash.enable = true;
  programs.nushell.enable = true;
  programs.starship.enable = true;
  programs.starship.settings = {
   username = {
      show always = true;
      style user = "bg:purple";
      style_root = "bg:purple";
      format = "[ | ]($style)";
   directory = {
      style = "bg:red";
      format = "[ $path ]($style)";
      truncation_length = 3;
      truncation_symbol = ".../";
   };
 home.stateVersion = "23.11";
```

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Conclusions

Reproducable Environments

We need **declarative** and **imperative** descriptions of our projects

Docker containers are great, but can be hard to maintain

Nix is a declarative language for environments that can improve reproducibility



Thanks!



aka.ms/pycascades-repro-envs

aka.ms/pyc24

aka.ms/python-discord

mathstodon.xyz/@crazy4pi314

sckaiser.com

