

ENERGY DATA SCIENCE

Time series analysis: Forecasting

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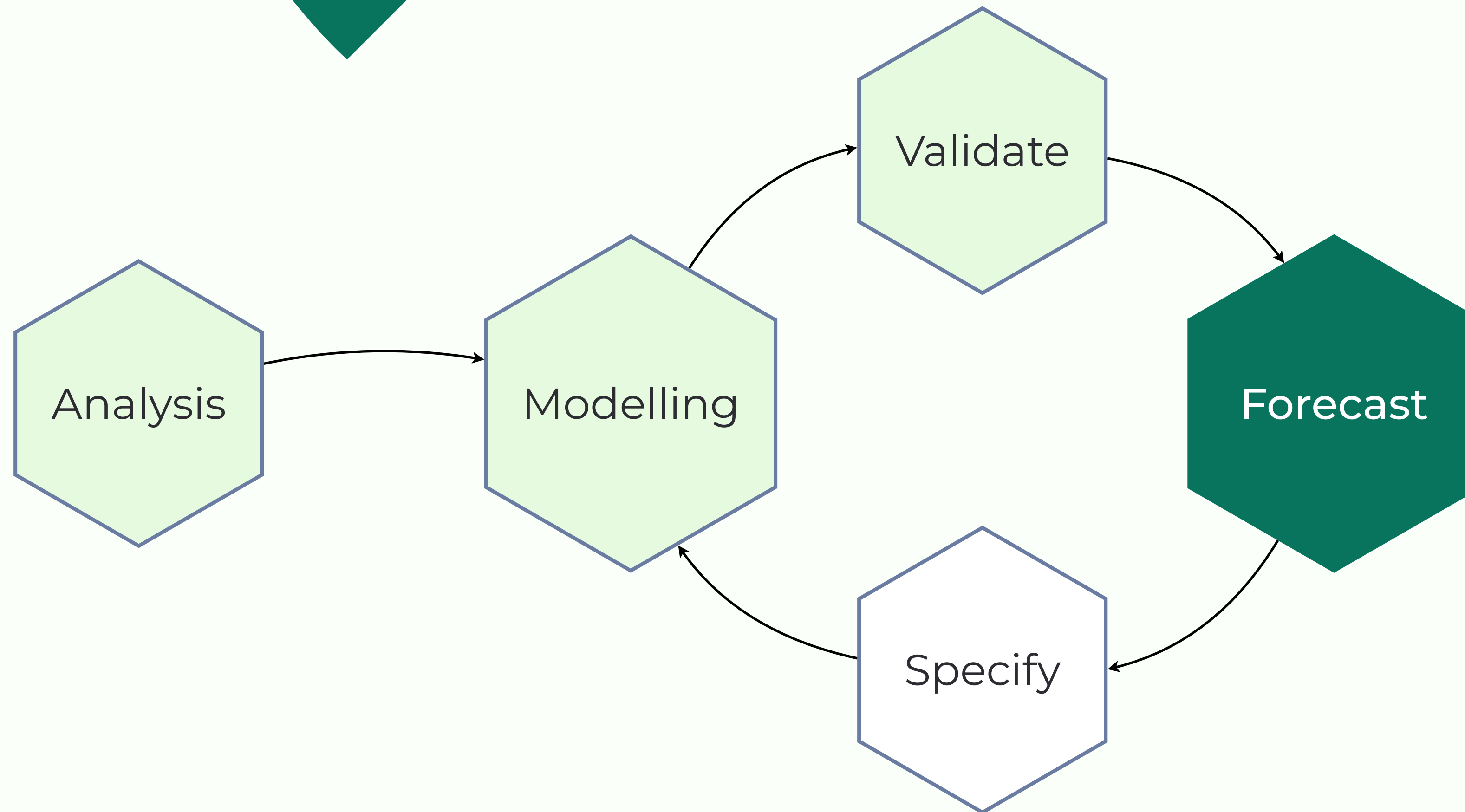
PREVIOUSLY IN COURSE ...

Key takeaways:

- ML and Time series
- RNN, LSTM, LightGBM

Train ML models, evaluate performance, and make predictions.

06 MODELLING



PREDICTING IS DIFFICULT?!

1800



“Rail travel at high speed is not possible, because passengers, unable to breathe, would die of asphyxia.”

Dr. Dionysys Larder, Professor of Natural Philosophy & Astronomy, University College London

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1903



“The horse is here to stay, but the automobile is only a novelty, a fad.”

The president of the Michigan Savings Bank, advising Henry Ford's lawyer not to invest in the Ford Motor Company

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1977



“There is no reason for any individual to have a computer in his home.”

Ken Olson, president, chairman and founder of Digital Equipment Corporation

FORECASTING VS PREDICTING

Forecast:

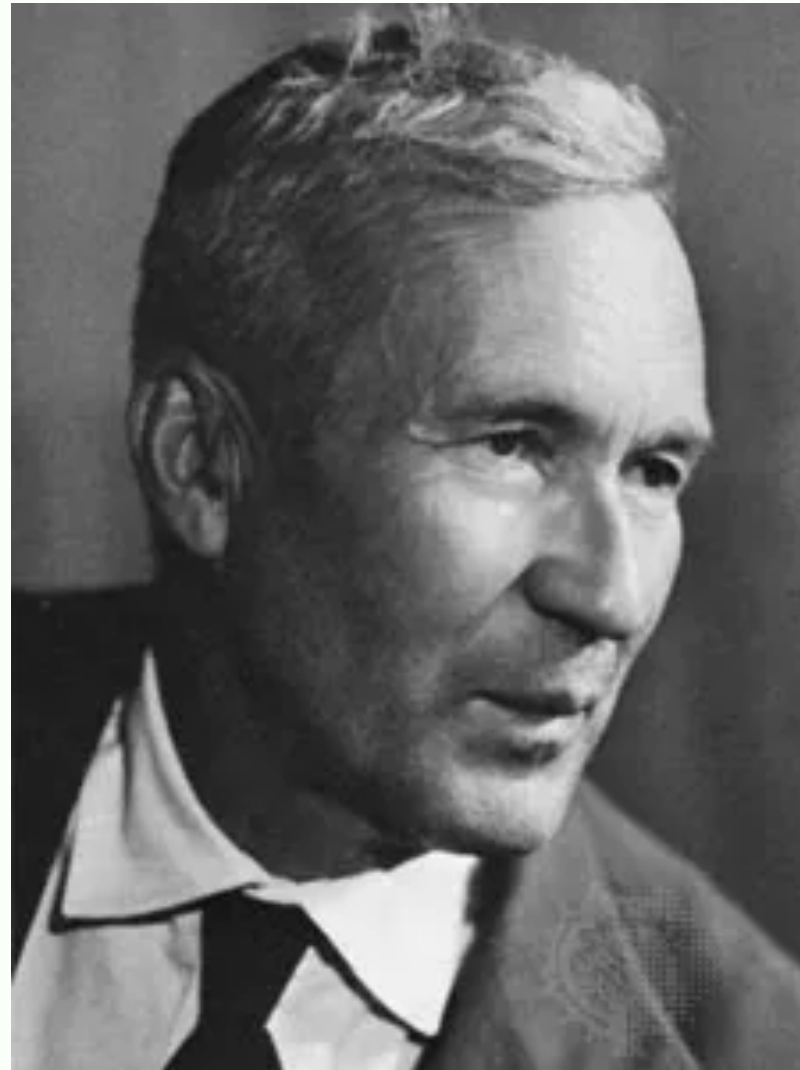
- ✓ systematic
- ✓ methodologically rigorous
- ✓ quantitative
- ✓ formal

Prediction:

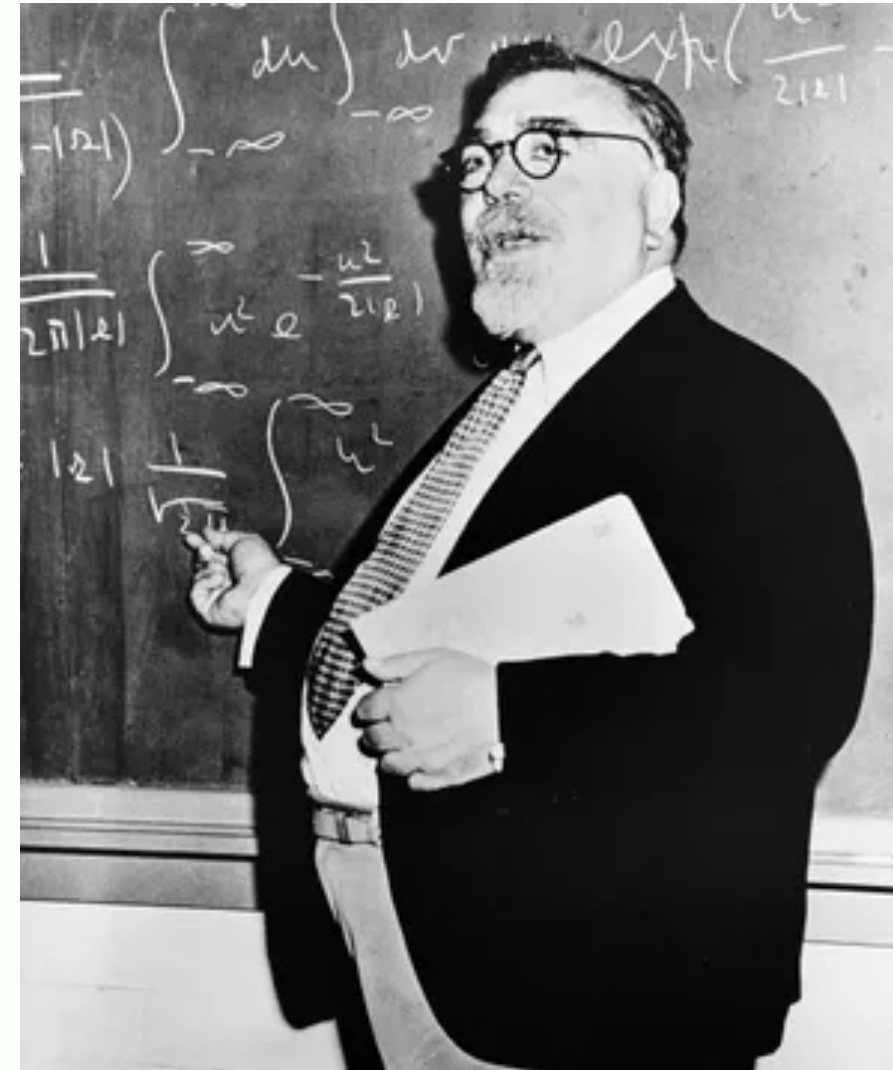
- ✓ broad
- ✓ potentially subjective
- ✓ qualitative or quantitative
- ✓ less formal



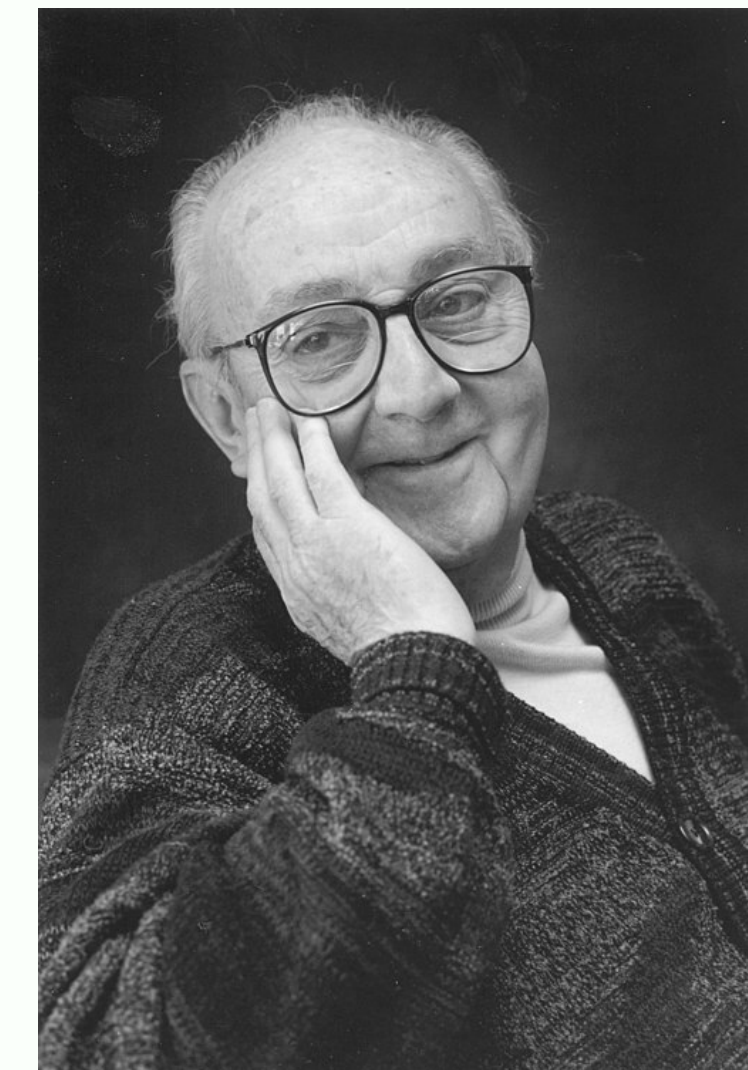
THE ORIGINS



A. N. Kolmogorov
(1903–1987)



N. Wiener
(1894–1964)



G. E.P. Box
(1919–2013)

FORECASTING METHOD

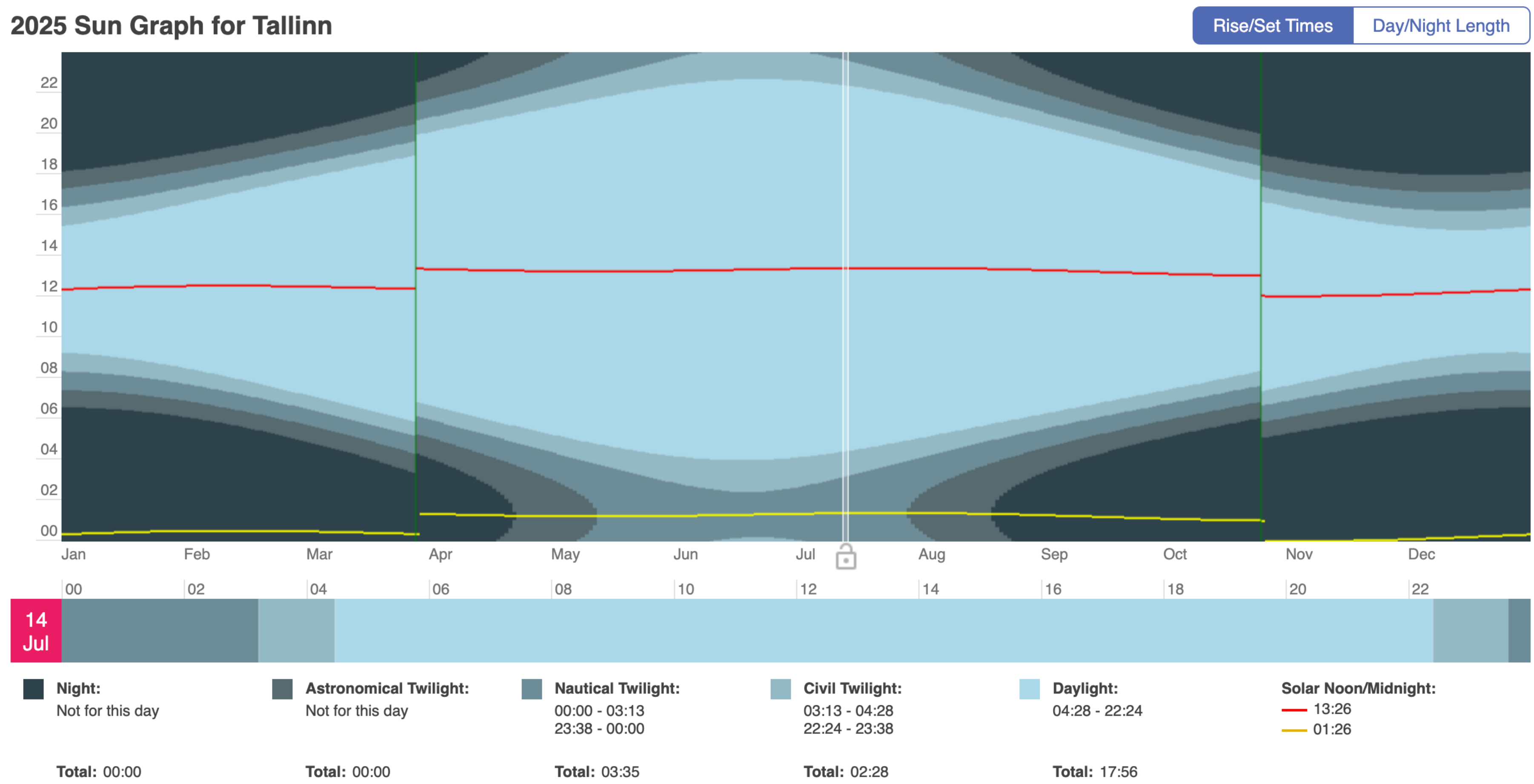
Qualitative forecasting methods are used when there are no numeric data available, or if the data available are not relevant to the forecasts.

Quantitative forecasting can be applied when two conditions are satisfied:

1. numerical information about the past is available;
2. it is reasonable to assume that some aspects of the past patterns will continue into the future.

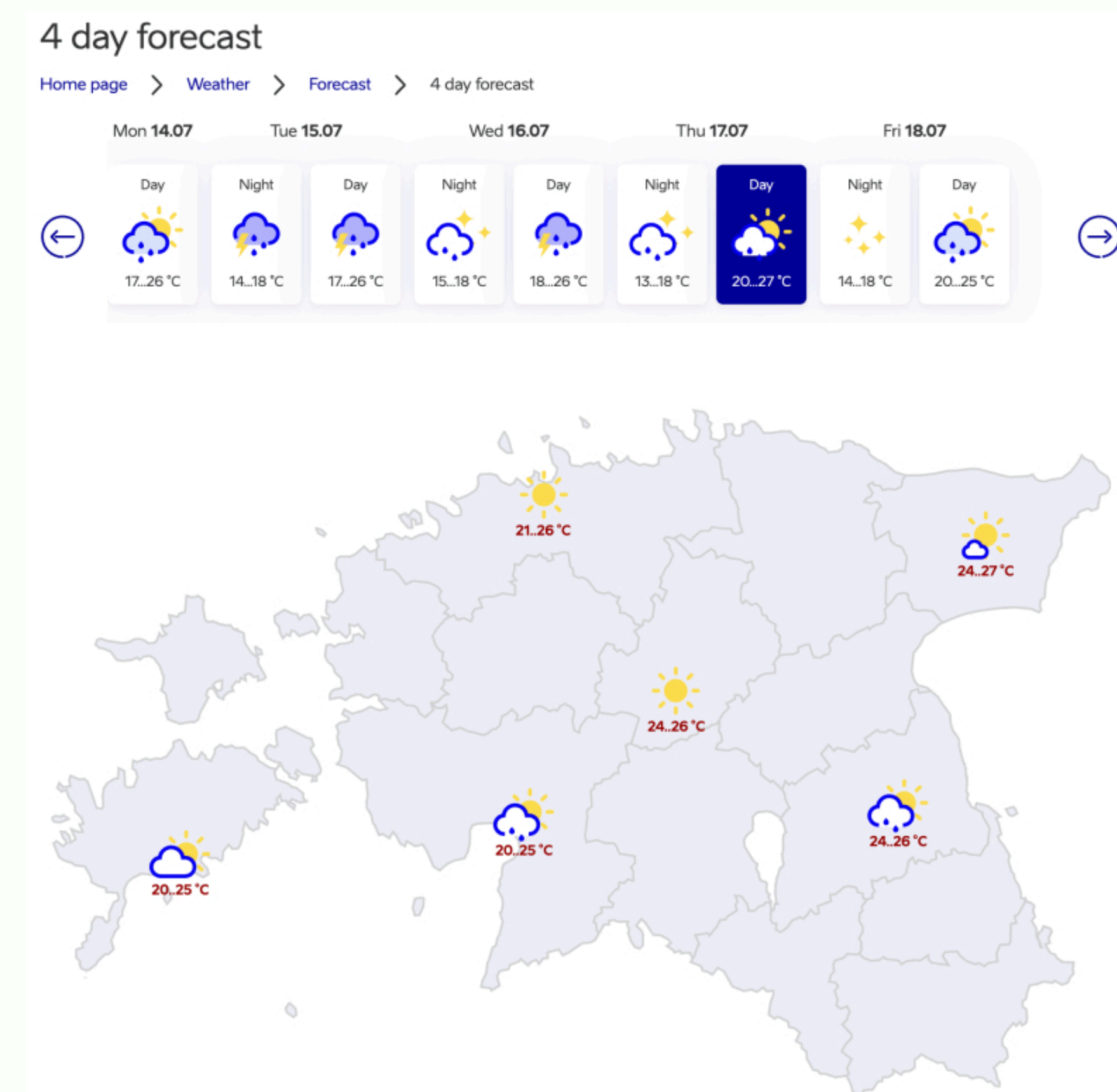
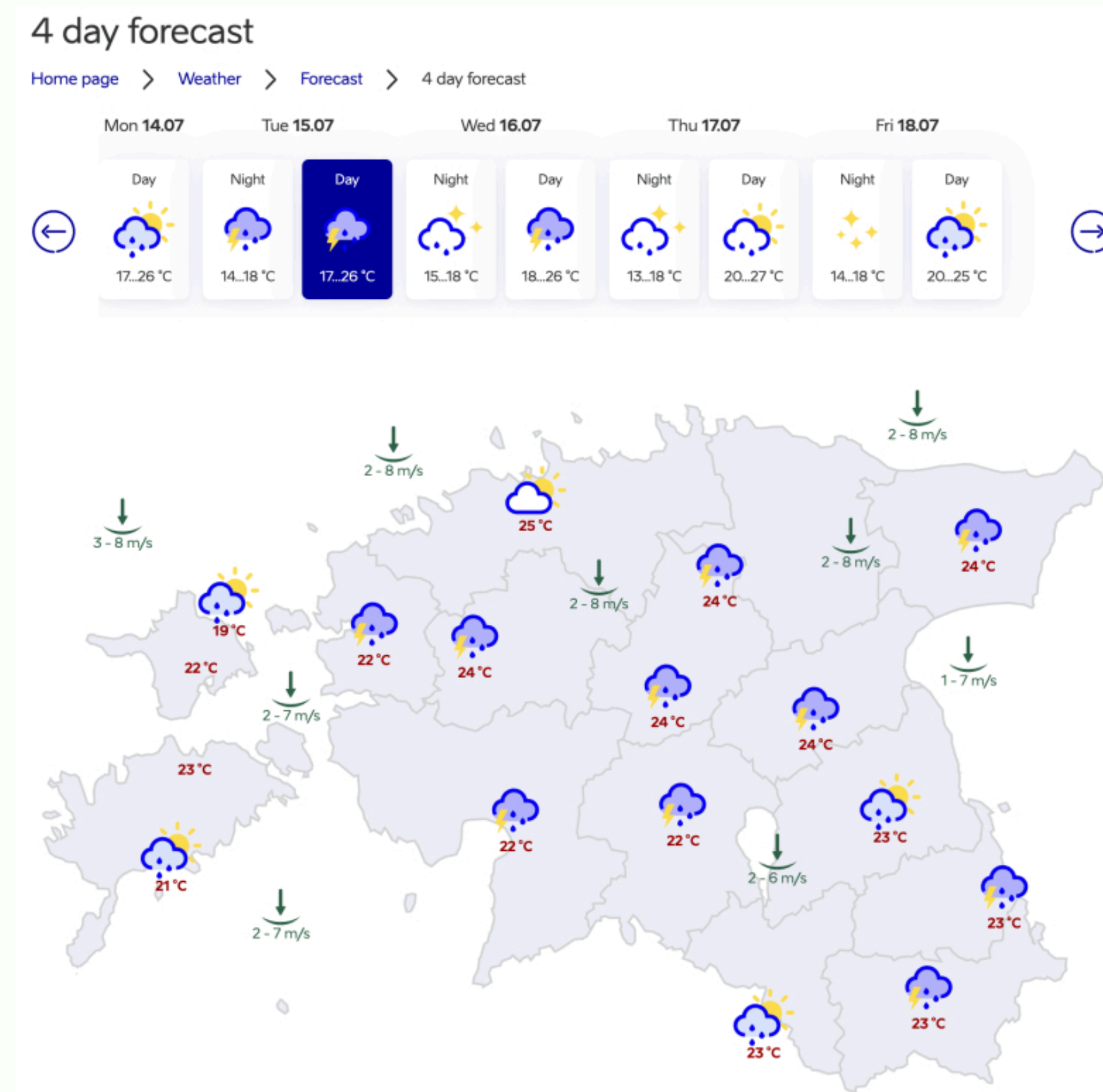
WHAT CAN BE FORECASTED?

Long-term, no uncertainties



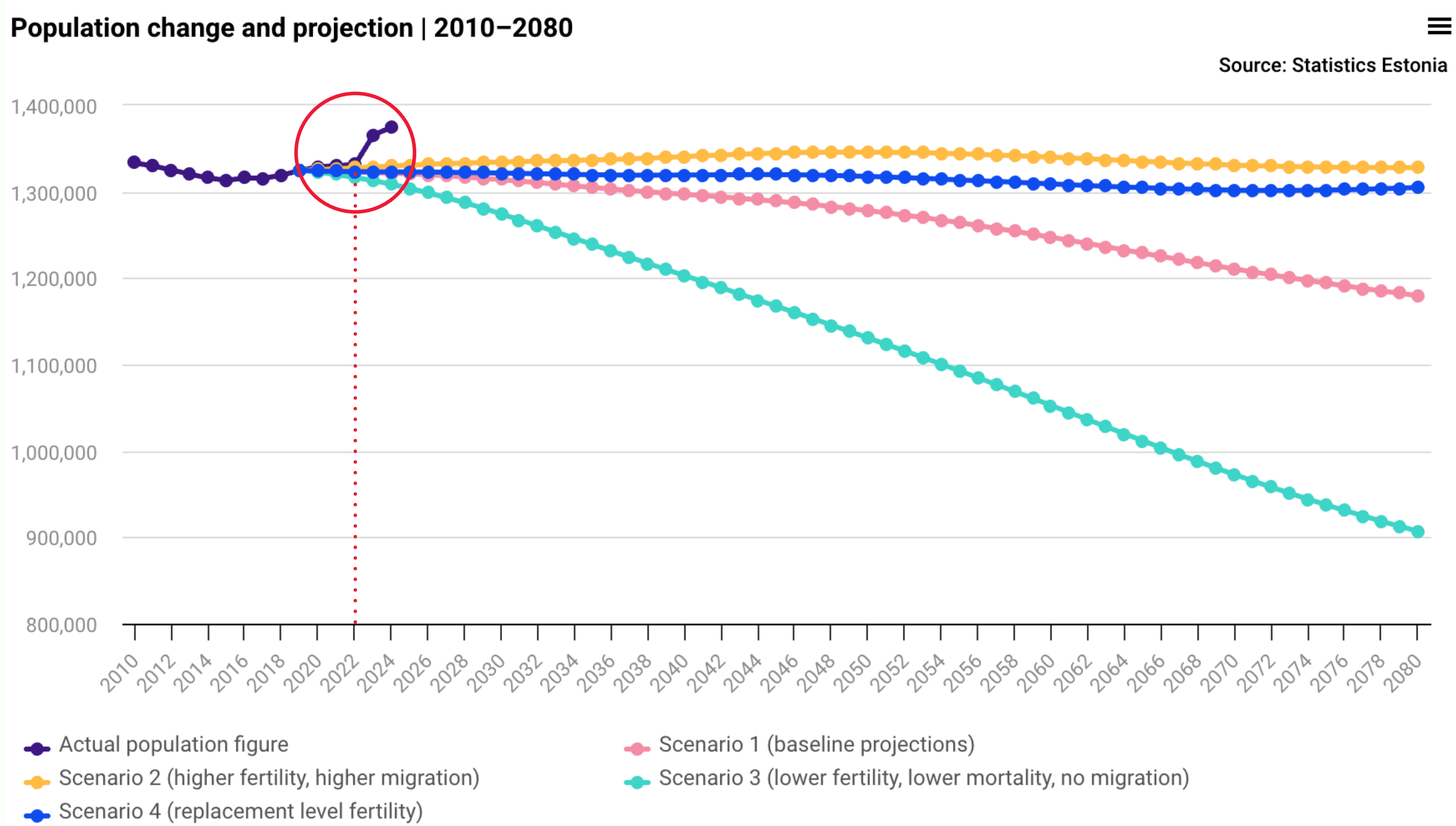
WHAT CAN BE FORECASTED? (2)

Short-term, many uncertainties



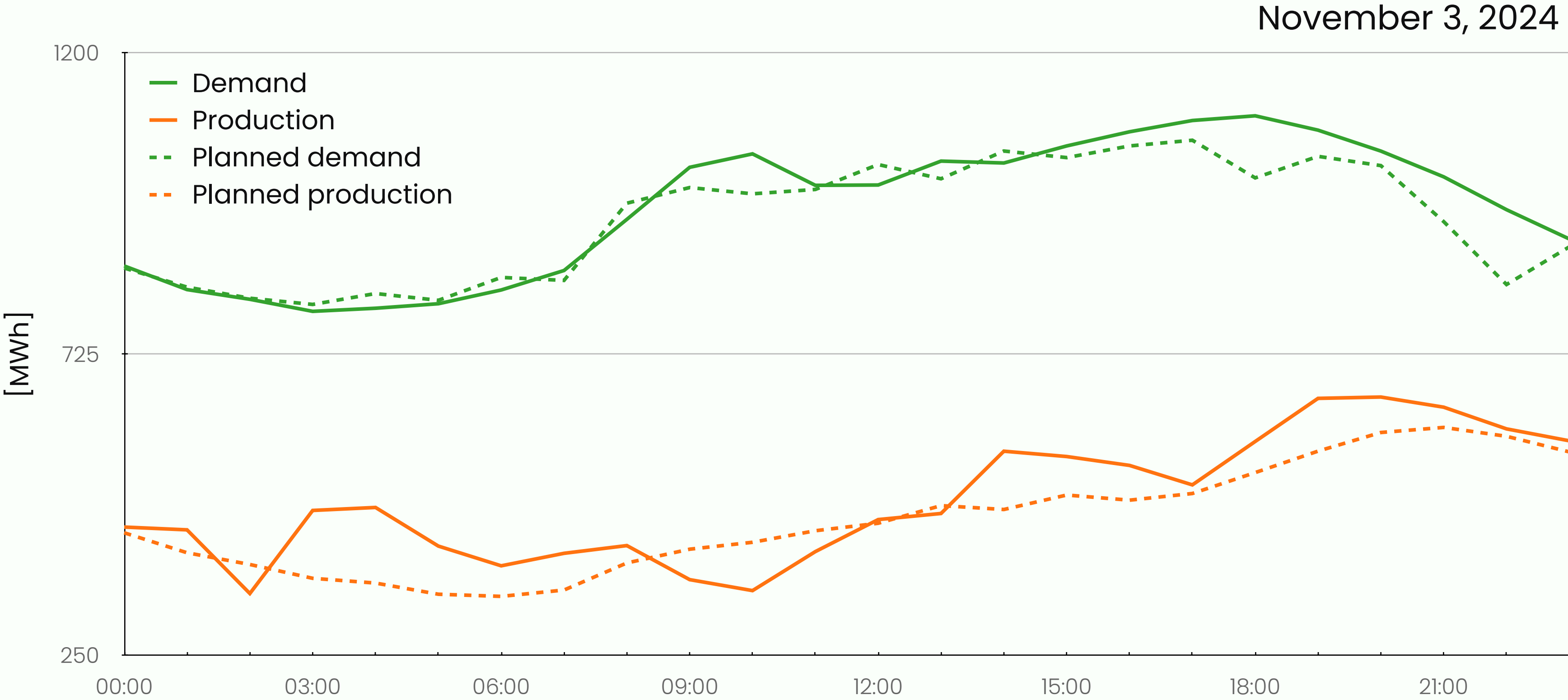
WHAT CAN BE FORECASTED? (3)

Long-term, many uncertainties



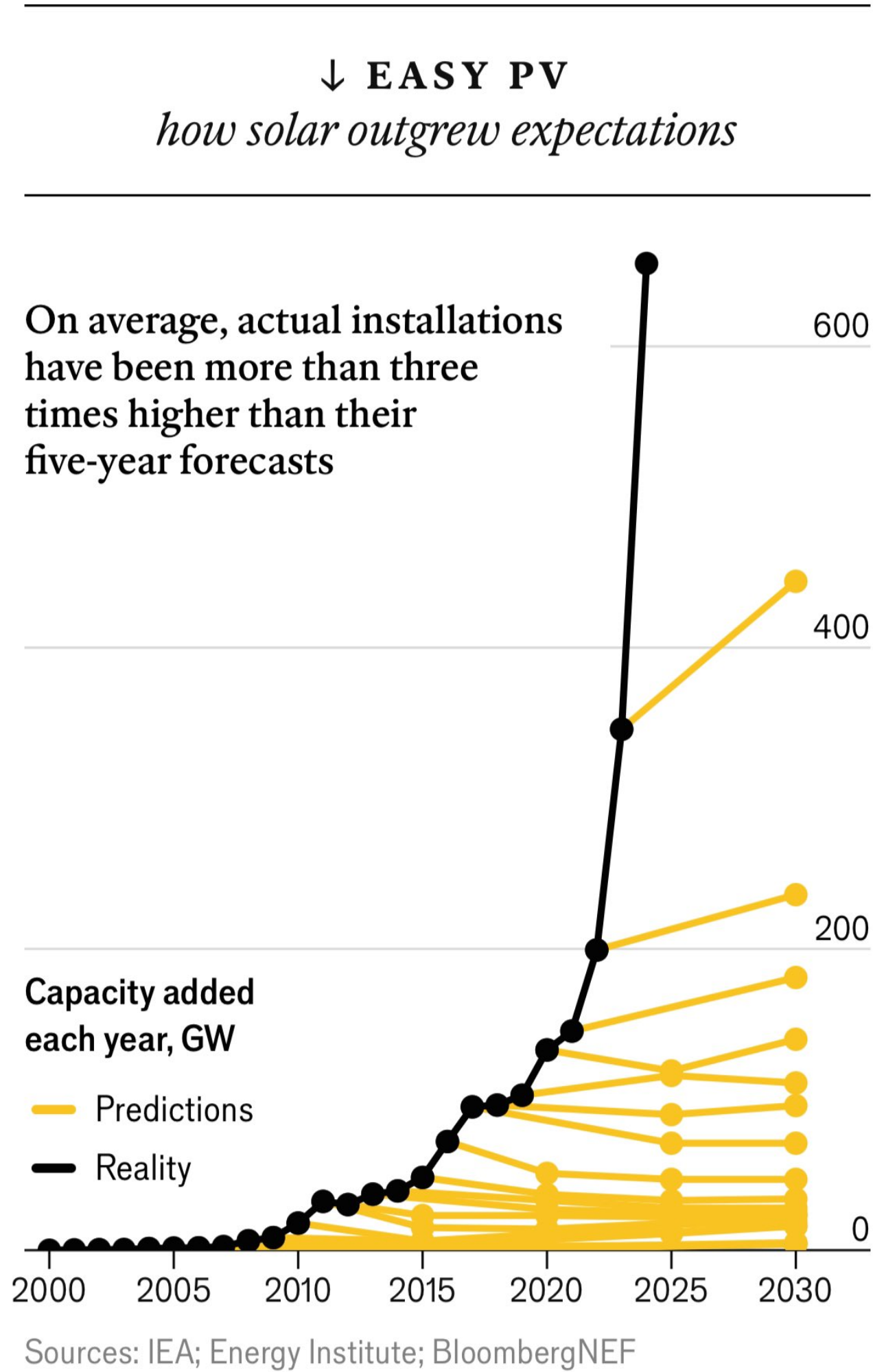
WHAT CAN BE FORECASTED? (4)

Short-term, few uncertainties, independent forecasts



WHAT CAN BE FORECASTED? (5)

Long-term, few uncertainties, dependent forecast



HOW EASY?

Easier to forecast if:

- We understand the key factors.
- Lots of data.
- There similarities with the past behaviour (patterns).
- The forecast cannot affect the thing we are trying to forecast.

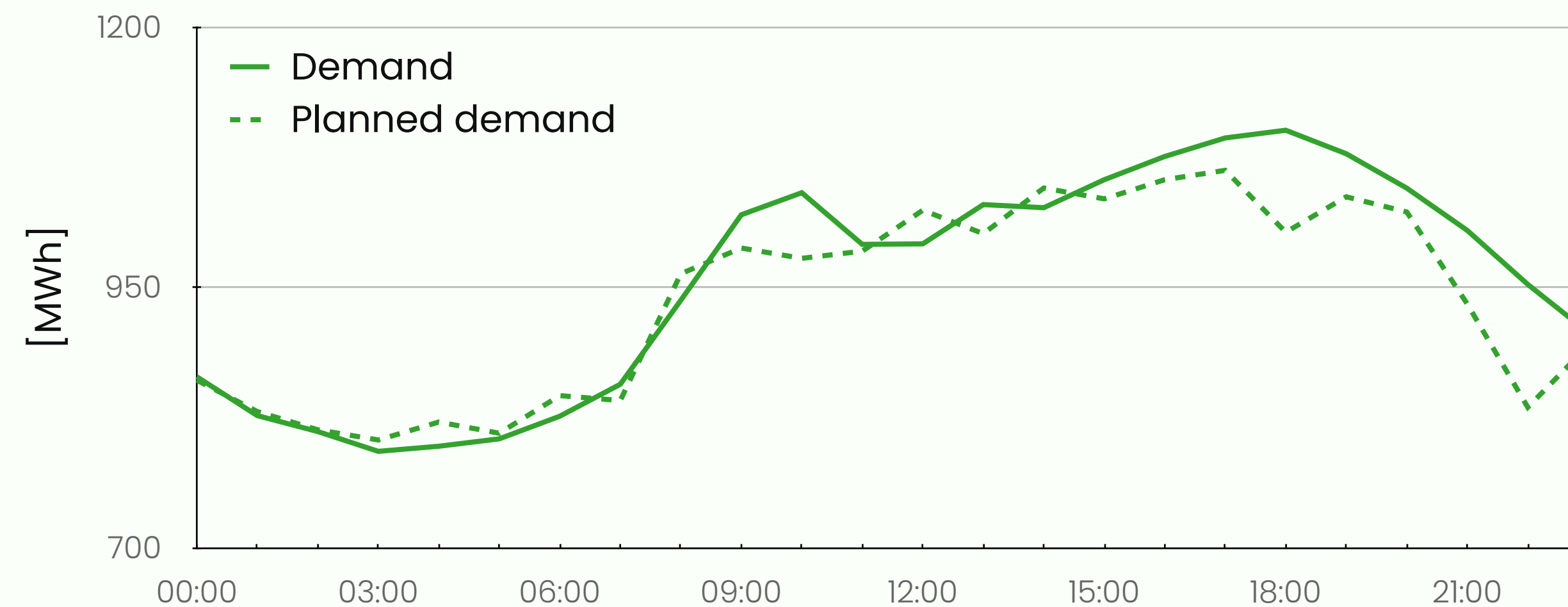
EXAMPLE: *EASY*

Important factors: temperature and calendar.

Data: long history of past demand and weather measurements.

Patterns: seasonality in the data.

Effect: fixed-fee clients are not affected. But for open market clients ...



EXAMPLE: *HARD*

- Important factors: too many.
- Data: long history is available.
- Patterns: economy cycles, technical analysis (indicators).
- Effect: buy low / sell high.

SolarEdge Technologies (SEDG)
(Delayed Data from NSDQ)
\$48.01 USD
-0.98 (-2.00%)
Updated Jun 3, 2024 04:00 PM ET
Pre-Market: \$48.20 +0.19 (0.40%) 8:44 AM ET

Zacks Rank: ⓘ
3-Hold

Style Scores: ⓘ
F Value I F Growth I F Momentum I F VGM

Industry Rank: ⓘ
Bottom 12% (218 out of 249)
Industry: Solar

 View All Zacks #1 Ranked Stocks

Add To Portfolio

NVIDIA (NVDA)
(Delayed Data from NSDQ)
\$1,150.00 USD
+53.67 (4.90%)
Updated Jun 3, 2024 04:00 PM ET
Pre-Market: \$1,147.91 -2.09 (-0.18%) 8:46 AM ET

Zacks Rank: ⓘ
1-Strong Buy

Style Scores: ⓘ
F Value I A Growth I B Momentum I C VGM

Industry Rank: ⓘ
Top 37% (92 out of 249)
Industry: Semiconductor - General

 View All Zacks #1 Ranked Stocks

Add To Portfolio

[Accessed June 6, 2024], <https://www.zacks.com/stock/quote/SEDG>
<https://www.zacks.com/stock/quote/NVDA>

15 / 55

THE IDEA

Good forecasts capture **patterns** and **relationships** which exist in the historical data, but do not replicate past events that will not occur again.

FORECASTING FOR DECISION MAKING

Forecasting:

the future, given all of the information available.

Goals:

what has to happen? Linked to forecasts and plans.

Planning:

response to forecasts and goals. Determine actions to make forecasts match goals.

FORECASTING FOR DECISION MAKING (2)

Forecast:

Increasing number of electric vehicles.

Goals:

Building new charging stations.

Planning:

Planning infrastructural developments – where and how many.

FORECASTING: THE BEGINNING

- Decide what should be forecasted.
- Consider forecasting horizon: short- medium-, or long-term.
- Frequency of the forecast.
- Collect the data.

DATA WINDOWS: ROLLING VS RECURSIVE

The **rolling** approach makes use of fixed windows of data to *re-estimate* the parameters over the out-of-sample period, whereas the **recursive** approach makes use of an increasing window to *re-estimate* the models.

Training data

Forecast

Recursive window

	1	...	T-1	T	T+1	T+2	...
Step 1							
Step 2							
...							

Rolling window

	1	2	...	T-1	T	T+1	T+2	...
Step 1								
Step 2								
...								

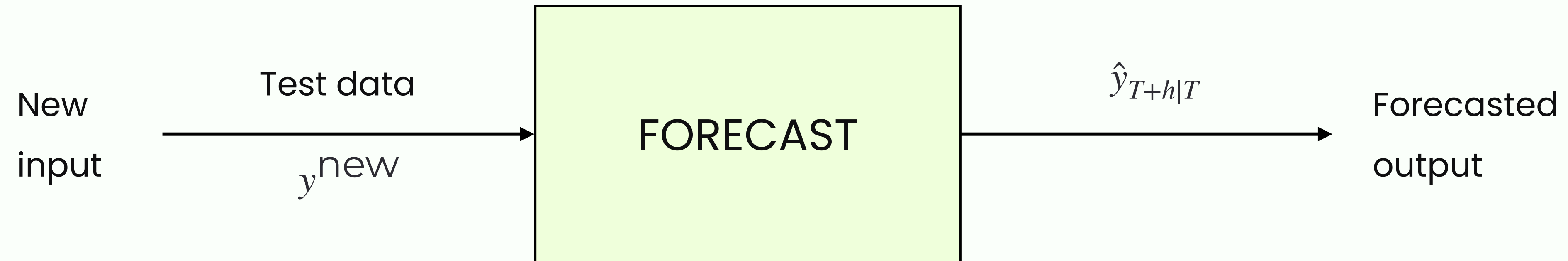
LENGTH OF THE TIME SERIES

Rule of thumb: more data is better than less data.

But do we always need all of the data available?



MATHEMATICALLY SPEAKING



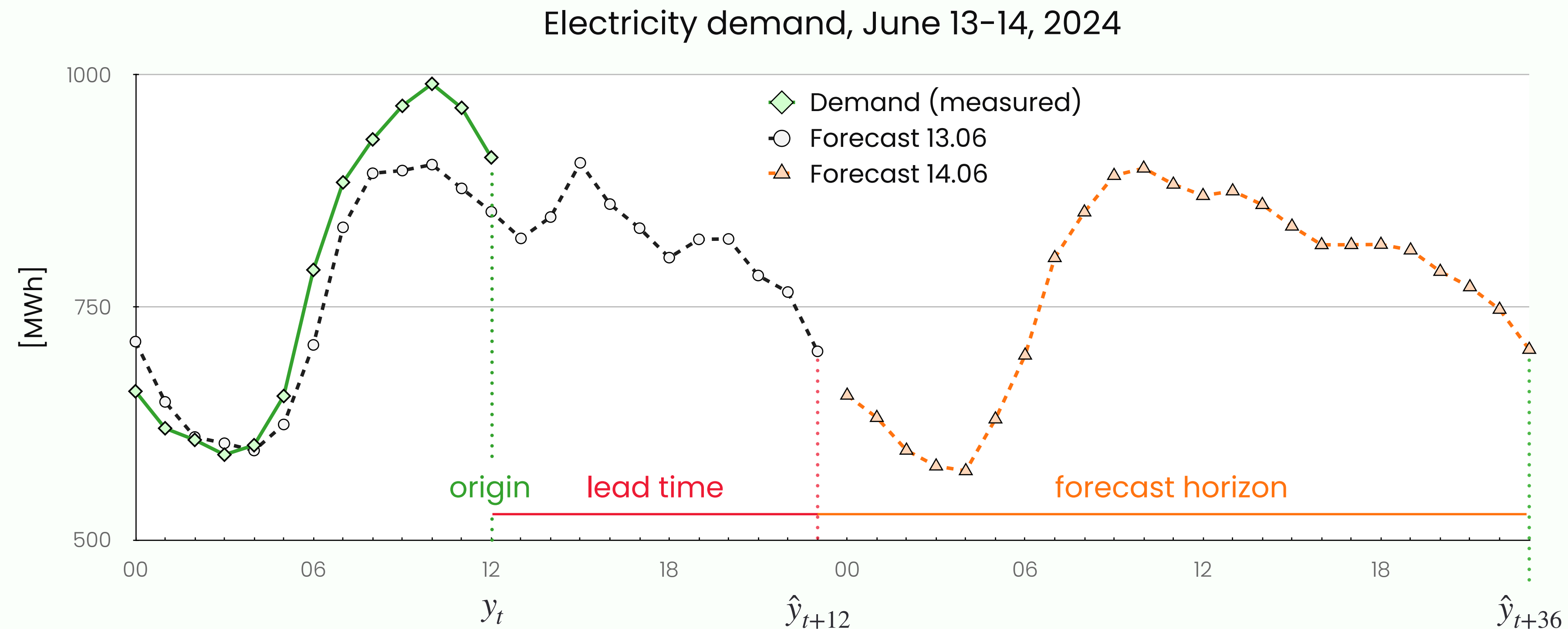
Notation $\hat{y}_{T+h|T}$ means forecast of y_{T+h} taking account (y_1, \dots, y_T) (i.e., an h -step forecast using all observations up to time T).

TERMINOLOGY

The forecast **origin** is time at which you are making a forecast.

The forecast **horizon** is the time for which you are making a forecast.

The time between the origin and the horizon is the **lead** time (or latency) of the forecast.



TYPES OF FORECAST

Forecasts can be either *in-sample* or *out-of-sample*.

In-sample (training/validation data)					Out-of-sample (test data)			
1	...	T-6	T-5	T-4	T-3	T-2	T-1	T

Out-of-sample forecasts are a better test of how well the model works, as the forecast uses data not included in the estimation of the model.

TYPES OF FORECAST (2)

A **one**-step-ahead is a forecast for the next observation only (i.e., $h = 1$).

A **multi**-step-ahead forecast is for $h > 1$ steps ahead.

Four multi-step Forecasting strategies

DIRECT

Train a separate model for each step in the horizon:

- model $\phi_1()$ forecasts 1-step ahead,
- model $\phi_2()$ forecasts 2-steps ahead,
- ...
- model $\phi_h()$ forecasts h -steps ahead.

$$\hat{y}_{t+1} = \phi_1(y_t, y_{t-1}, \dots, y_{t-n})$$

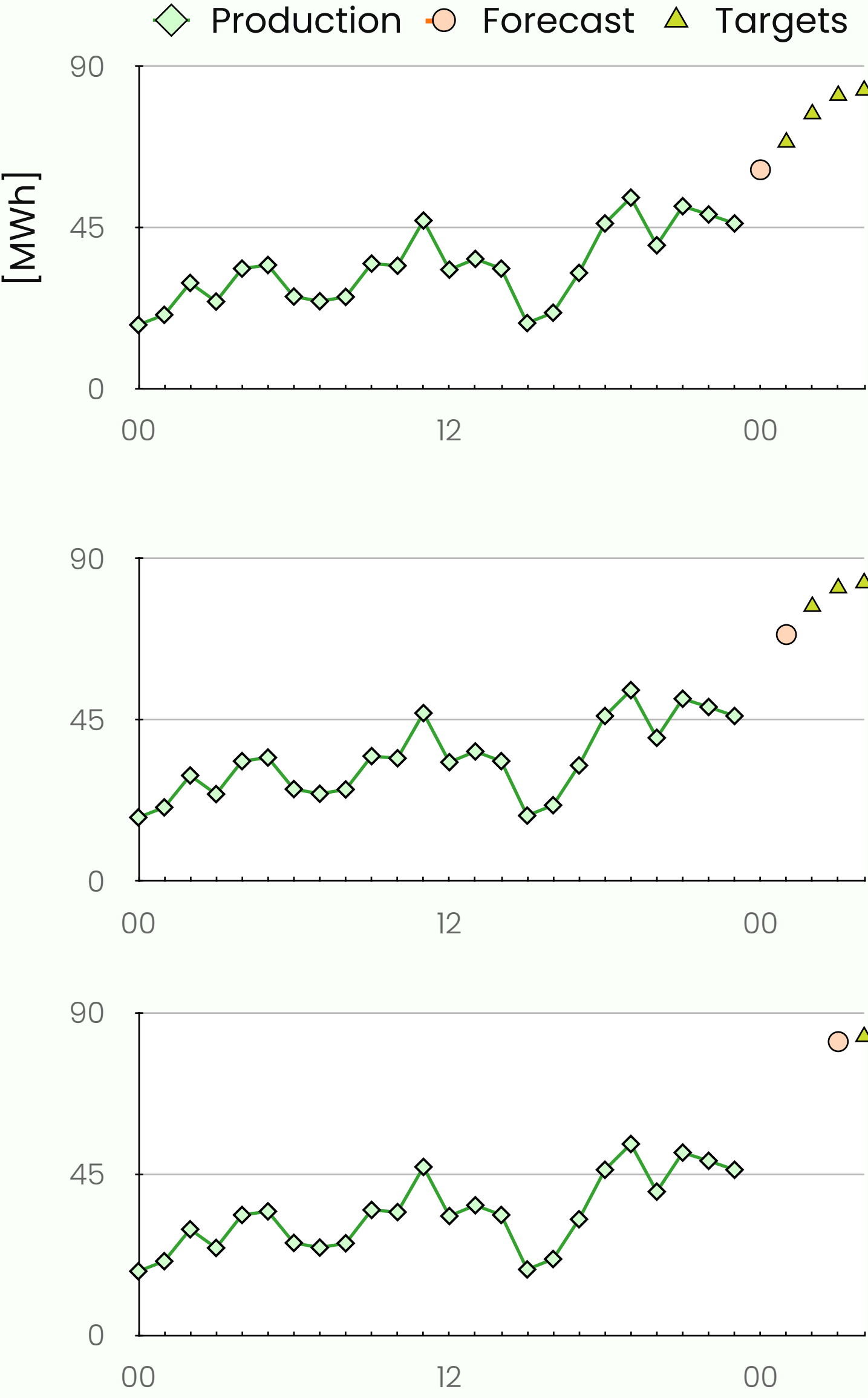
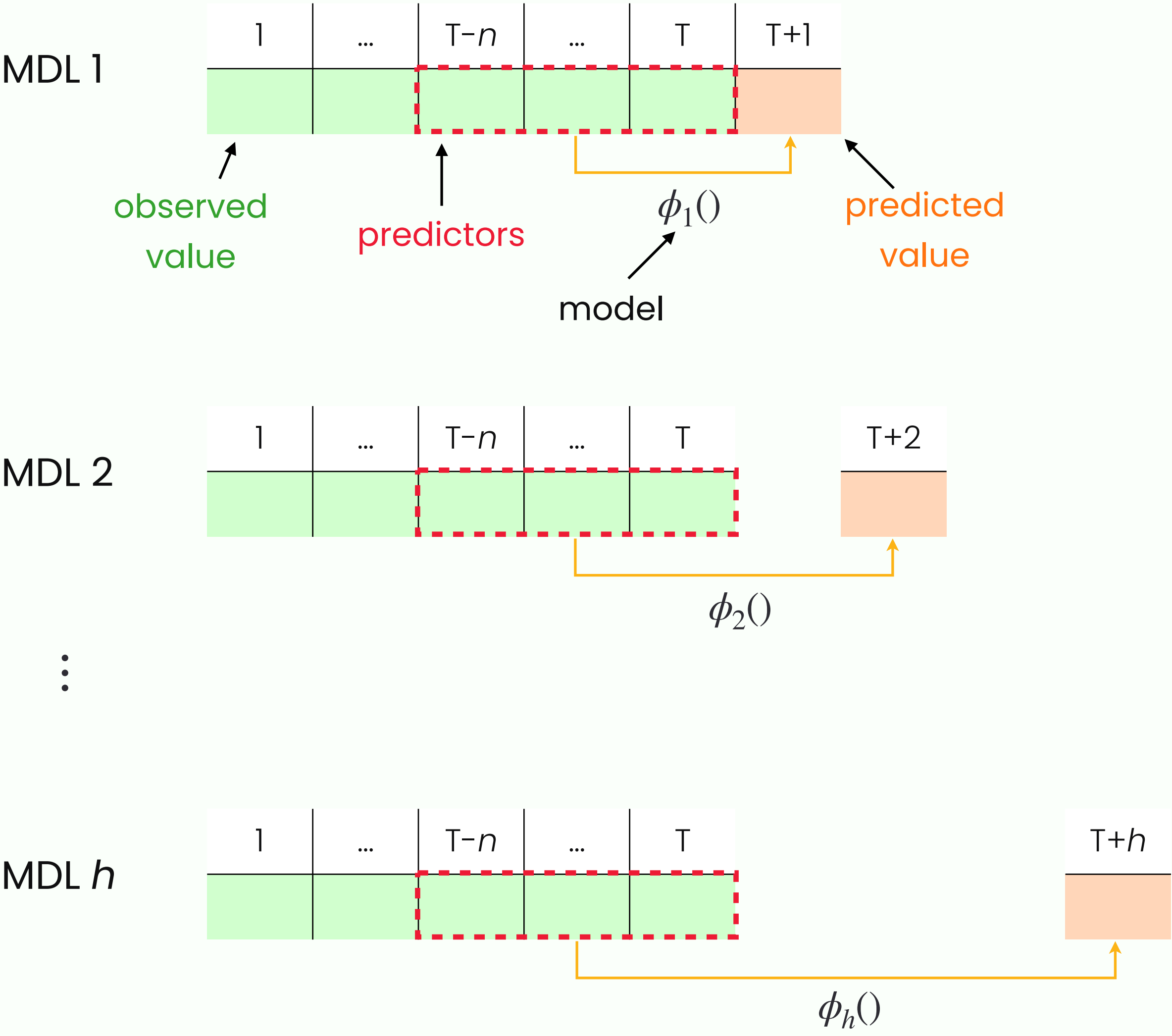
$$\hat{y}_{t+2} = \phi_2(y_t, y_{t-1}, \dots, y_{t-n})$$

$$\vdots$$

$$\hat{y}_{t+h} = \phi_h(y_t, y_{t-1}, \dots, y_{t-n})$$

NB! Training lots of models can be computationally expensive.

DIRECT (2)



RECURSIVE

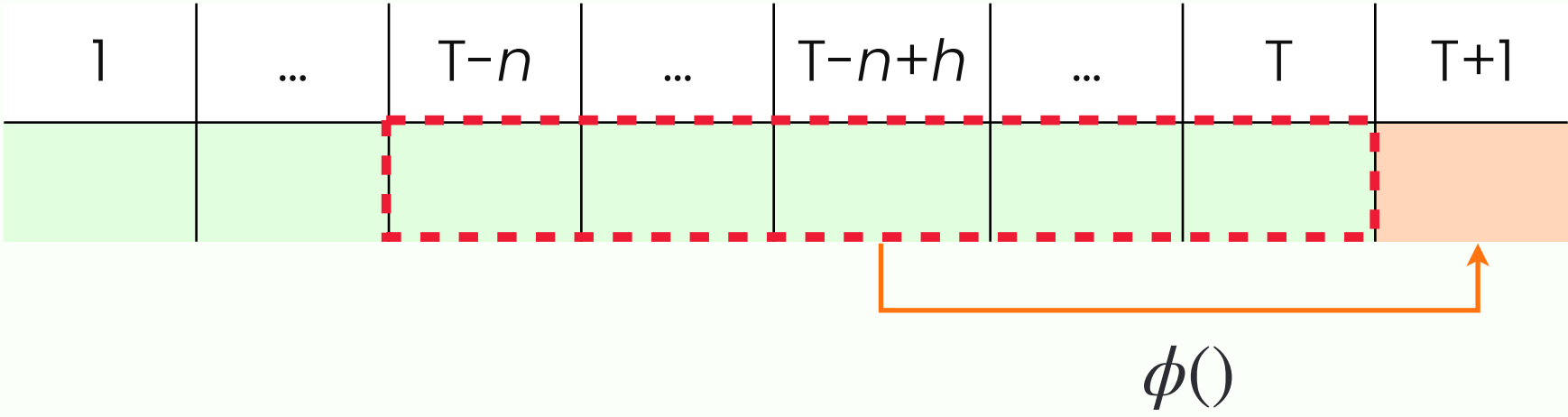
Train a single 1-step model and use its forecasts to update the lag features for the next step.

NB! We only need to train one model $\phi()$, but since errors will propagate from step to step, forecasts can be inaccurate for long horizons.

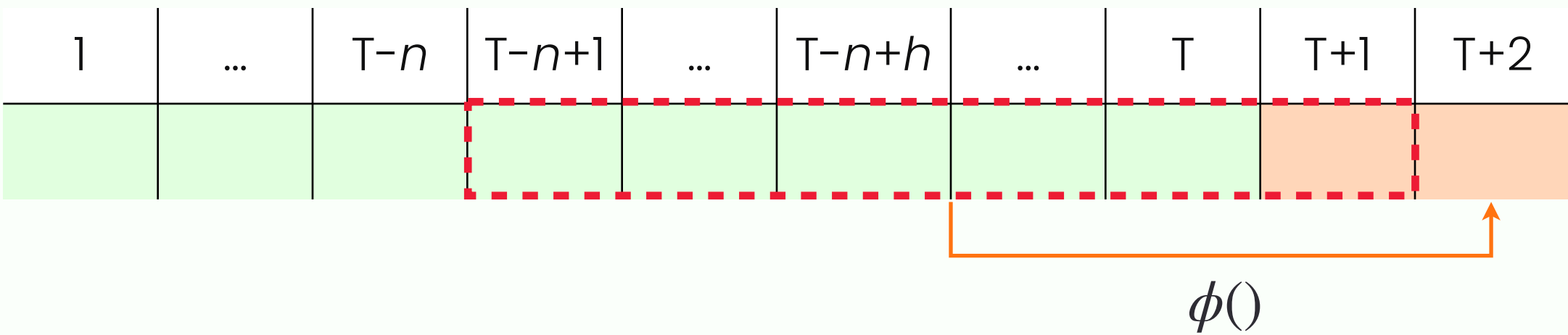
$$\begin{aligned}\hat{y}_{t+1} &= \phi(y_t, y_{t-1}, \dots, y_{t-n}), \\ \hat{y}_{t+2} &= \phi(\hat{y}_{t+1}, y_t, \dots, y_{t-n+1}), \\ &\vdots \\ \hat{y}_{t+h} &= \phi(\hat{y}_{t+h-1}, \dots, y_{t-n+h})\end{aligned}$$

RECURSIVE (2)

ITER 1

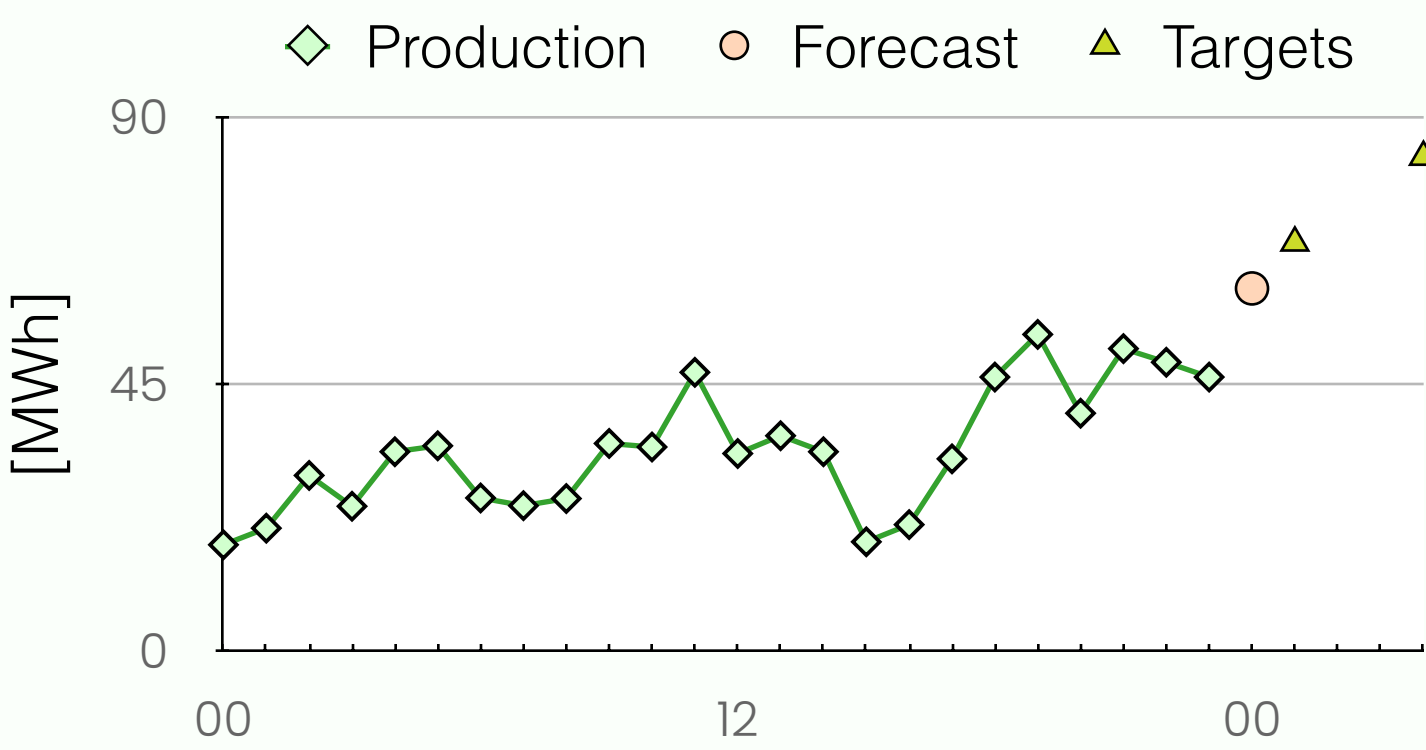
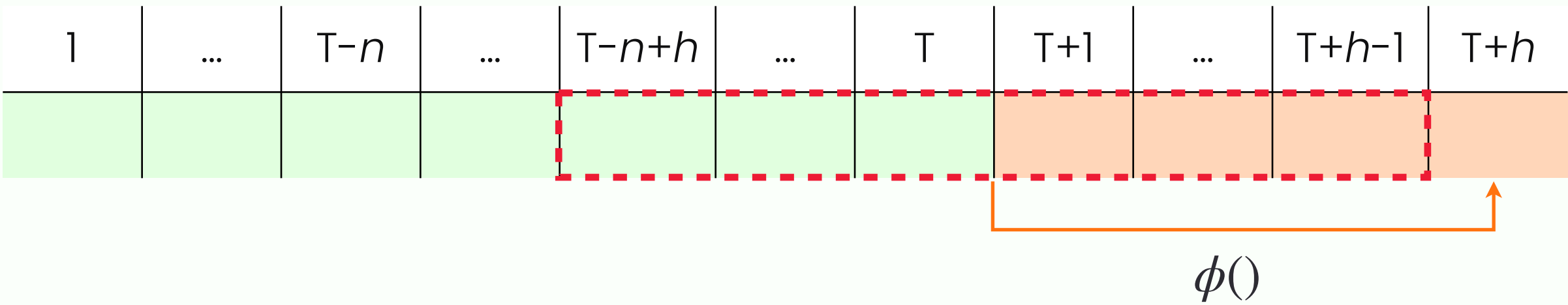


ITER 2



⋮

ITER h



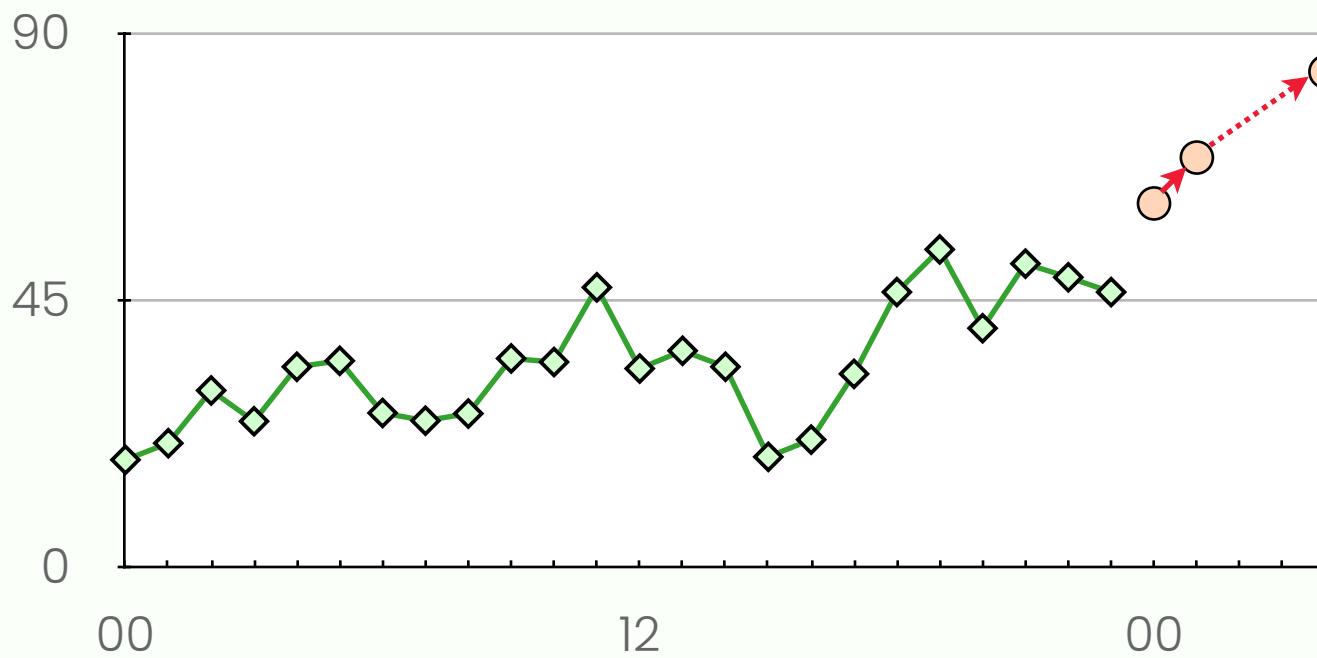
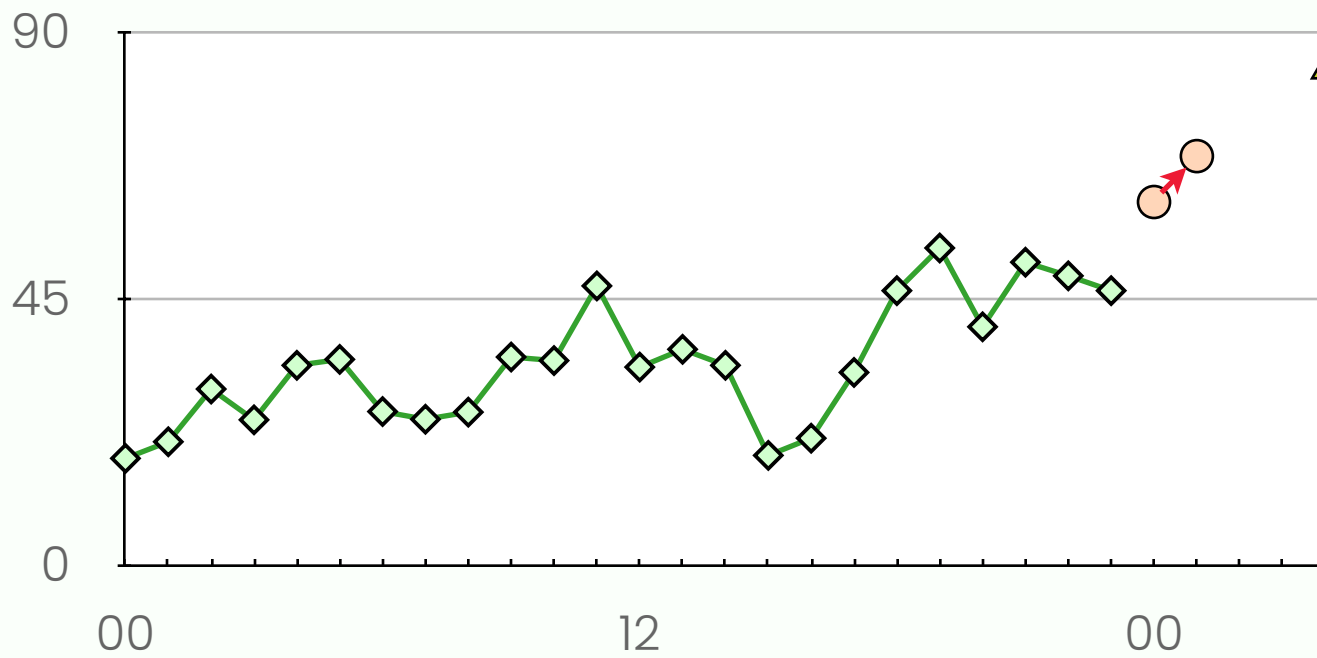
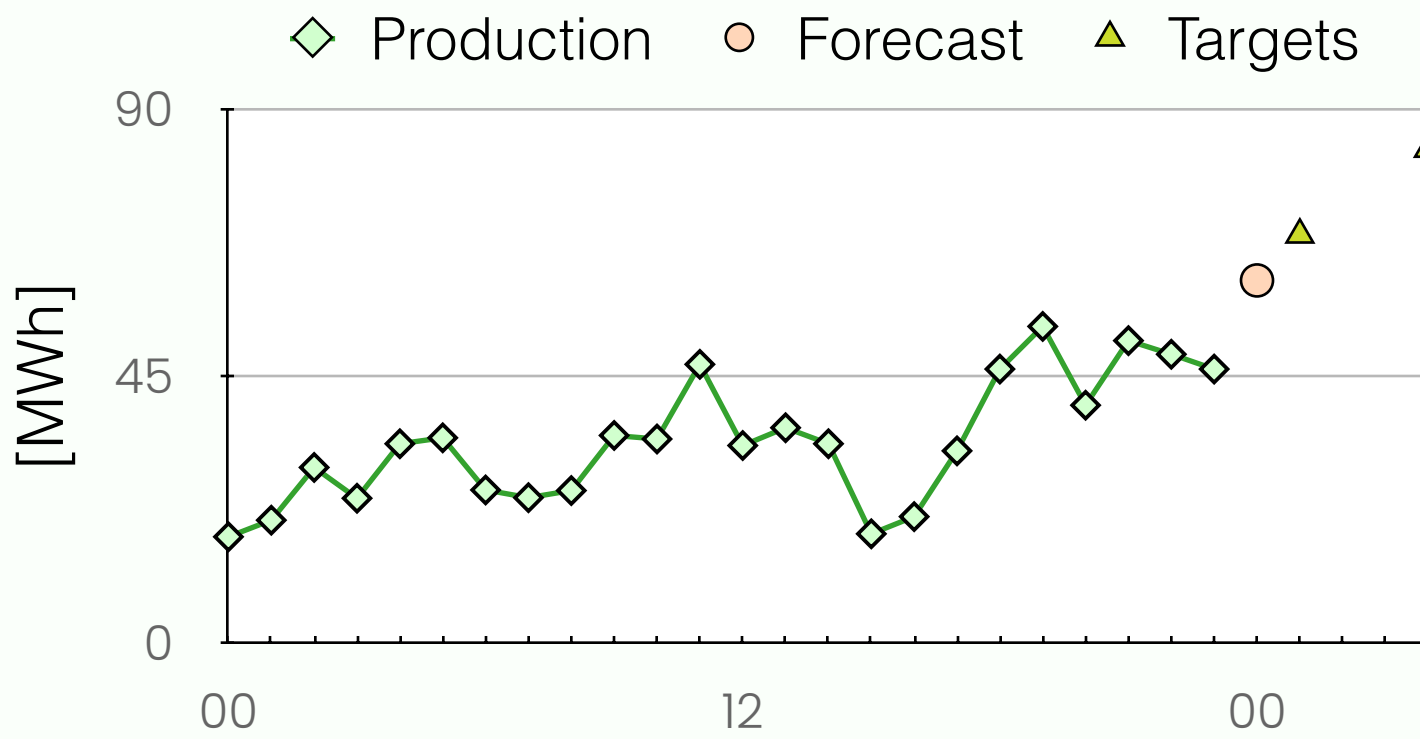
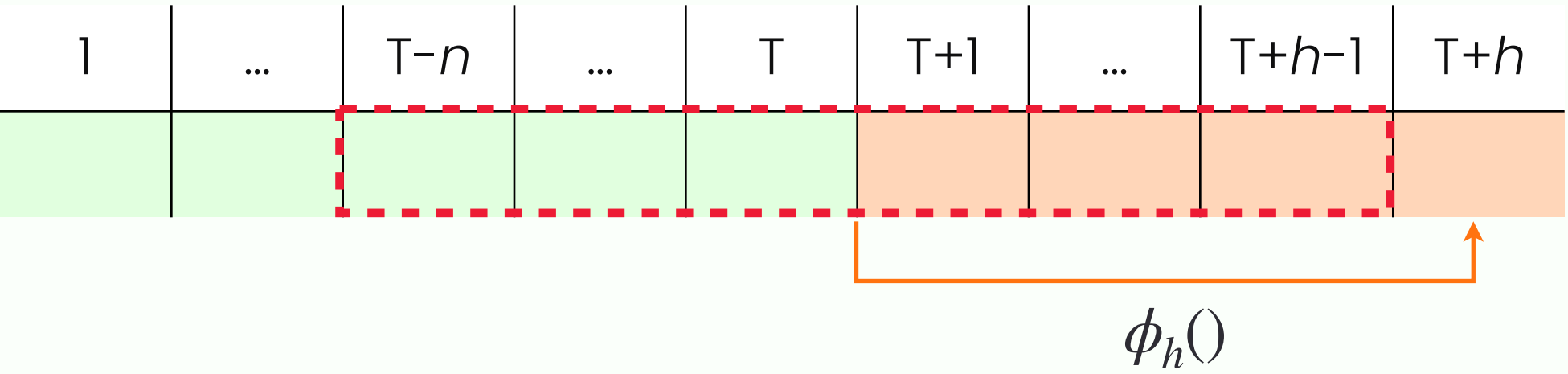
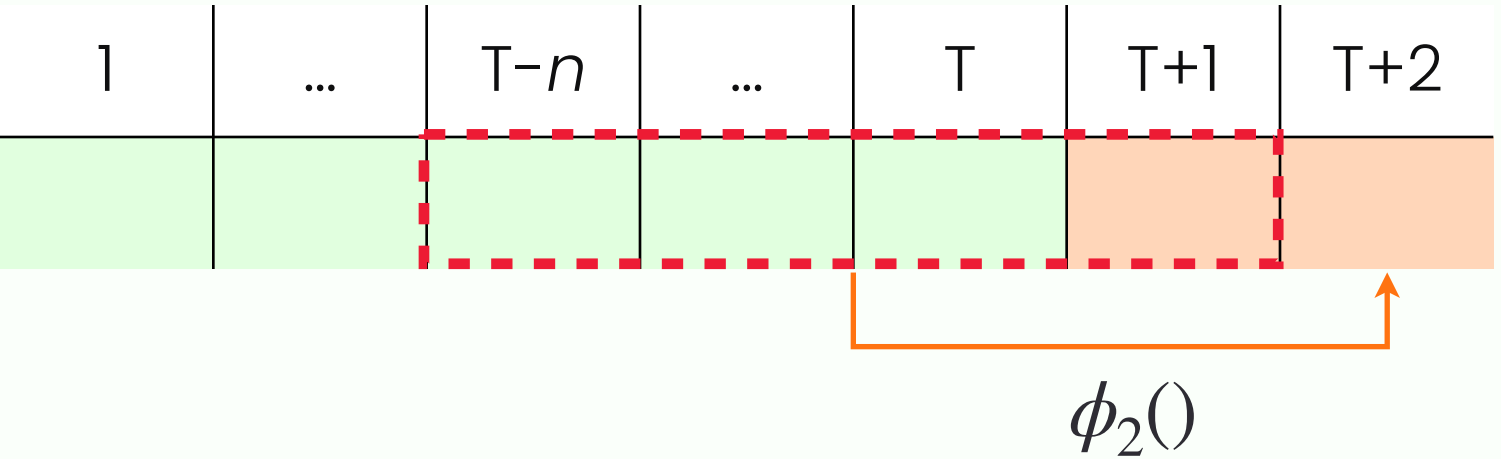
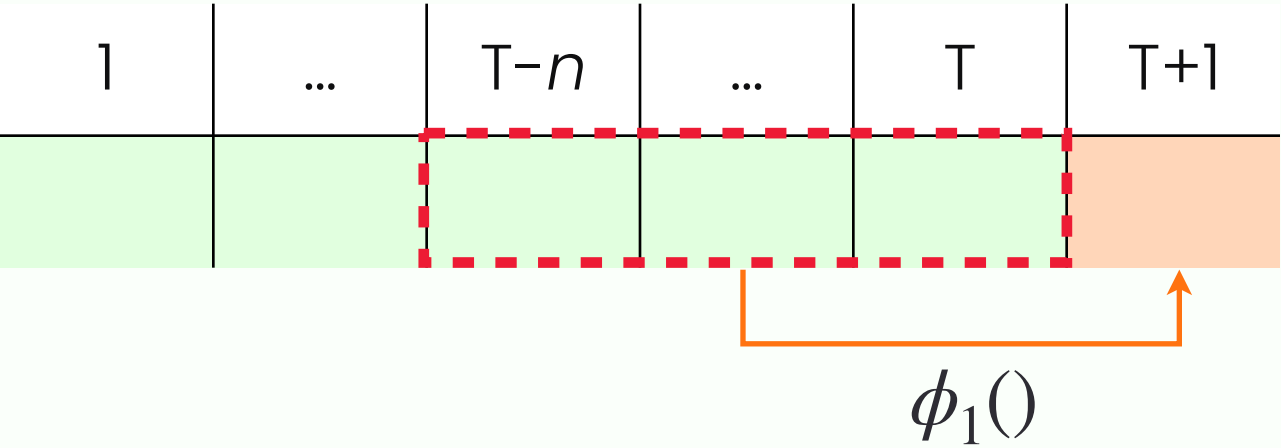
DIRECT + RECURSIVE

Train a model for each step and use forecasts from previous steps as new lag features.

NB! The model may still suffer from error propagation like Recursive.

$$\begin{aligned}\hat{y}_{t+1} &= \phi_1(y_t, y_{t-1}, \dots, y_{t-n}), \\ \hat{y}_{t+2} &= \phi_2(\hat{y}_{t+1}, y_t, \dots, y_{t-n}), \\ &\vdots \\ \hat{y}_{t+h} &= \phi_h(\hat{y}_{t+h-1}, \dots, \hat{y}_{t+1}, y_t, \dots, y_{t-n})\end{aligned}$$

DIRECT + RECURSIVE (2)



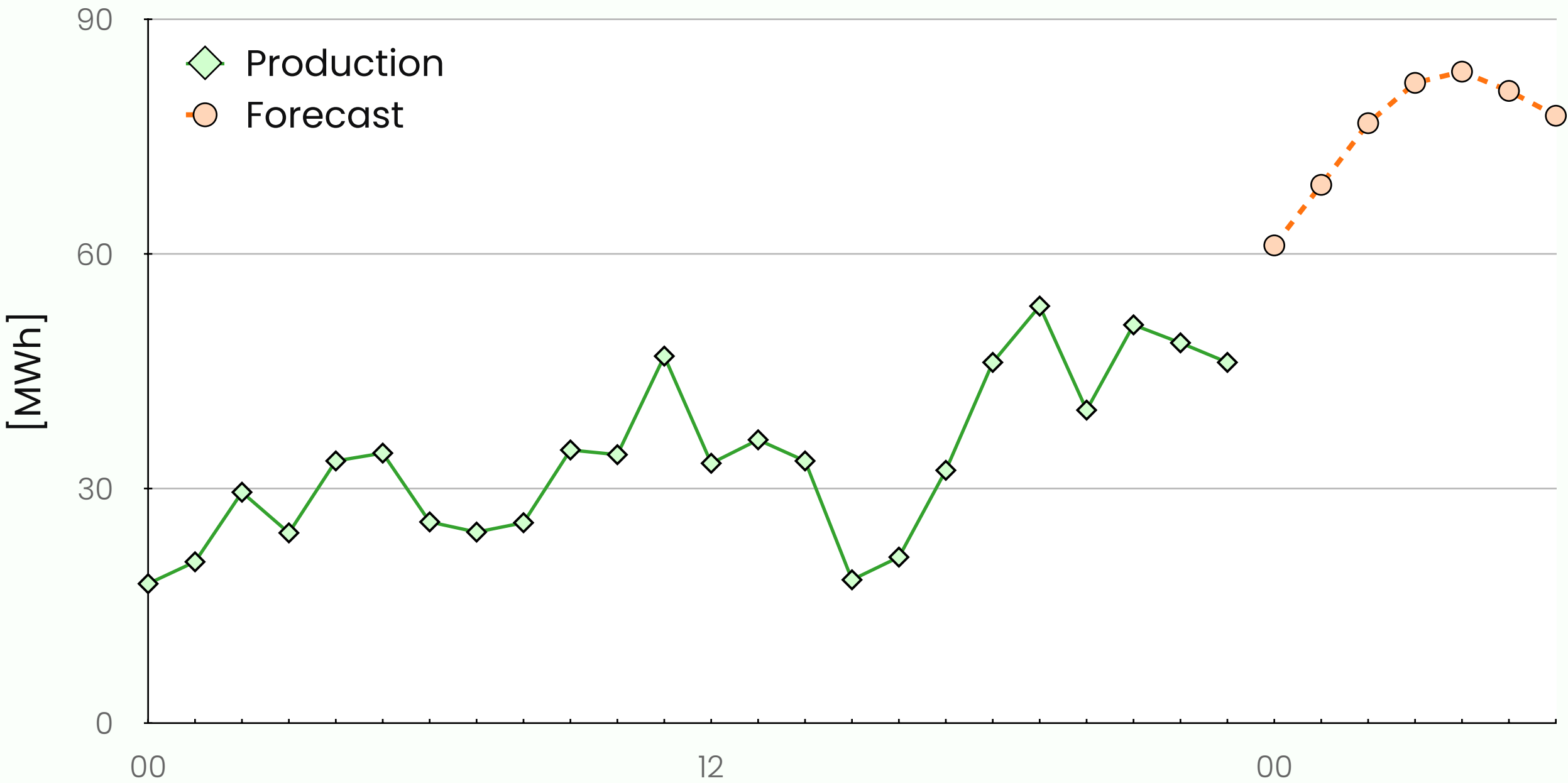
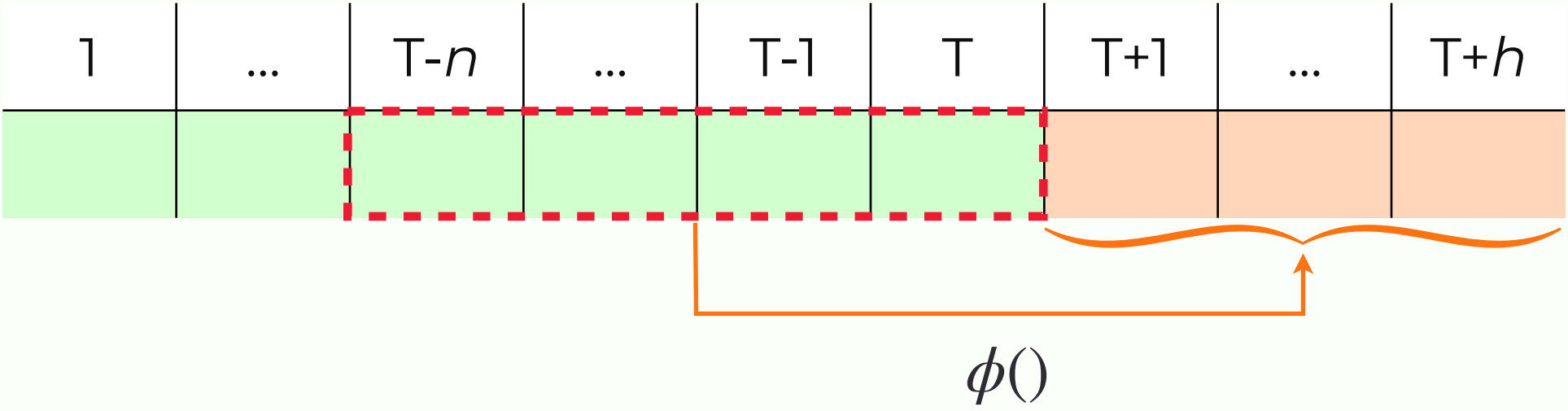
MULTI-OUTPUT

Create a model $\phi()$ that can produce multiple outputs $\hat{y} \in \mathbb{R}^h$.

NB! This strategy is simple and efficient, but may require more data and be slower, in general.

$$\hat{y} = \begin{bmatrix} \hat{y}_{t+1} \\ \vdots \\ \hat{y}_{t+h} \end{bmatrix} = \phi(y_t, y_{t-1}, \dots, y_{t-n})$$

MULTI-OUTPUT (2)



SUMMARY

	Direct	Recursive	DirRec	MO
Can be used with scalar models	+	+	+	-
Immune to accumulation of errors	+	-	+	+
Dependency between forecasts	-	+	+	+
# of models	h	1	h	1

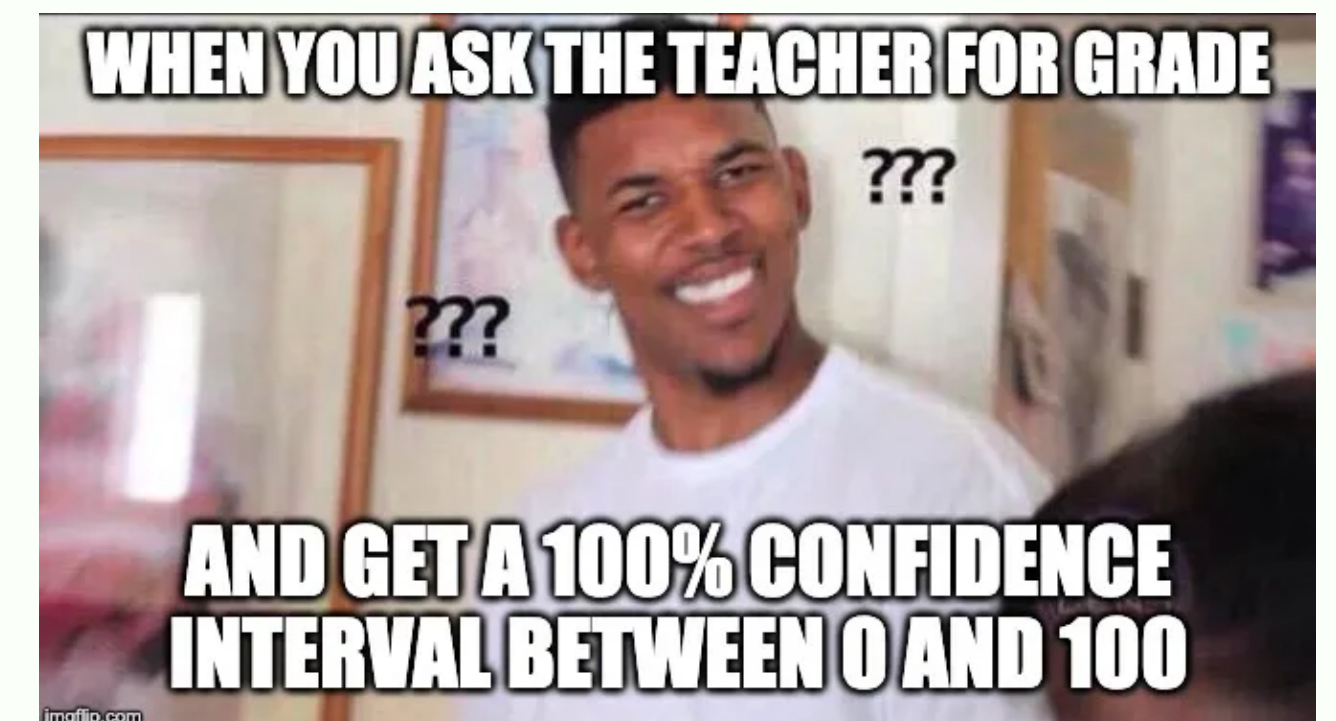
*scalar models refer to models that handle univariate time series data, meaning they work with a single variable over time, e.g., ARMA-family models.

STATISTICAL FORECAST: CI VS PI

- Confidence intervals display the probability that a parameter will fall between a pair of values around the mean.
- Prediction intervals tell you where you can expect to see the next data point.

A prediction interval predicts an individual number, whereas a confidence interval predicts the mean value.

NB! PI is wider than CI.



PREDICTION INTERVALS

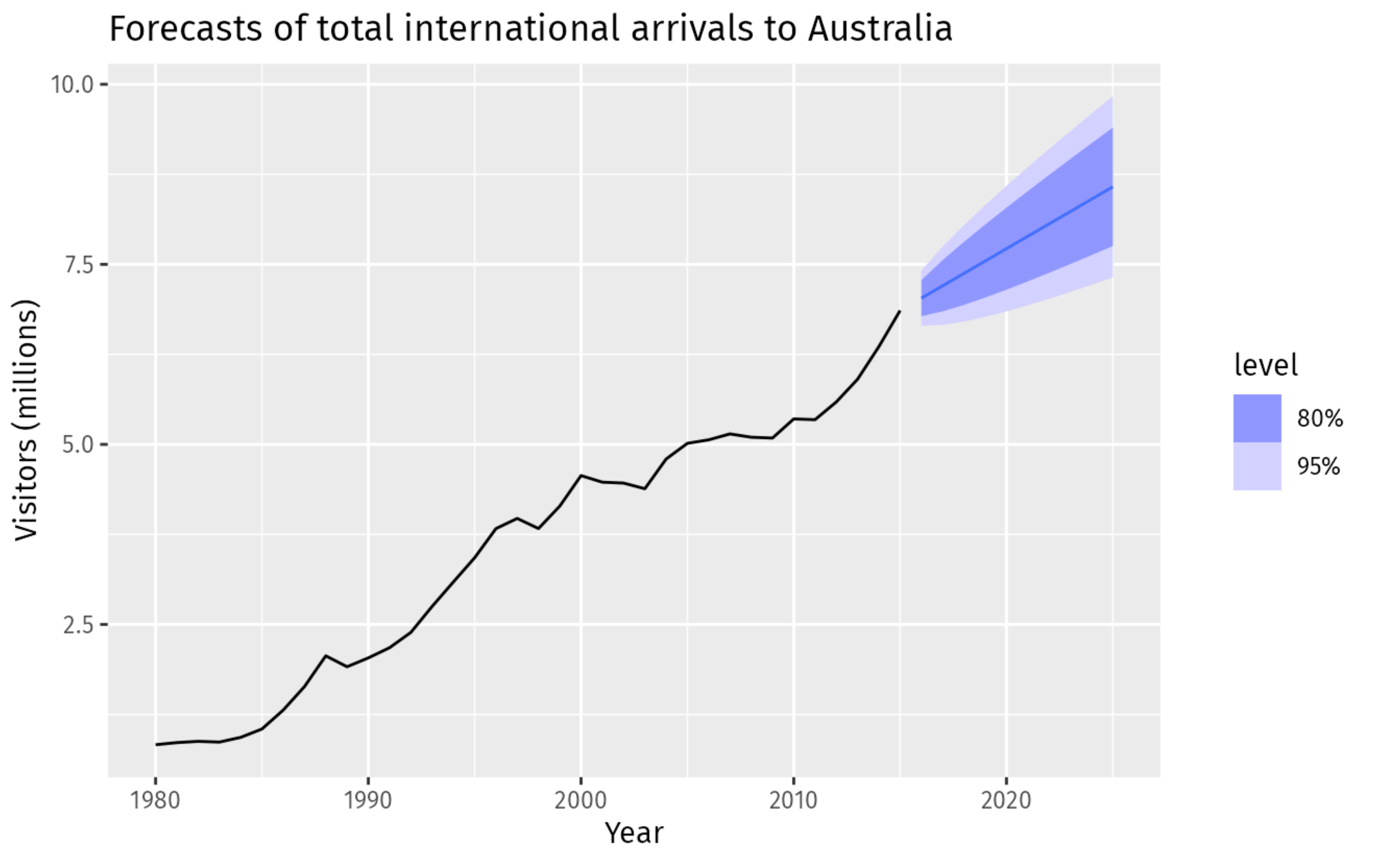
A prediction interval gives an interval within which we expect y_t to lie with a specified probability:

$$\hat{y}_{T+h|T} \pm c\hat{\sigma}_h$$

where $\hat{\sigma}_h$ is an estimate of the standard deviation of the h -step forecast distribution, and c depends on the coverage probability.

Multipliers (c) used for prediction intervals	
Percentage	Multiplier
50	0.67
80	1.28
90	1.64
95	1.96
99	2.58

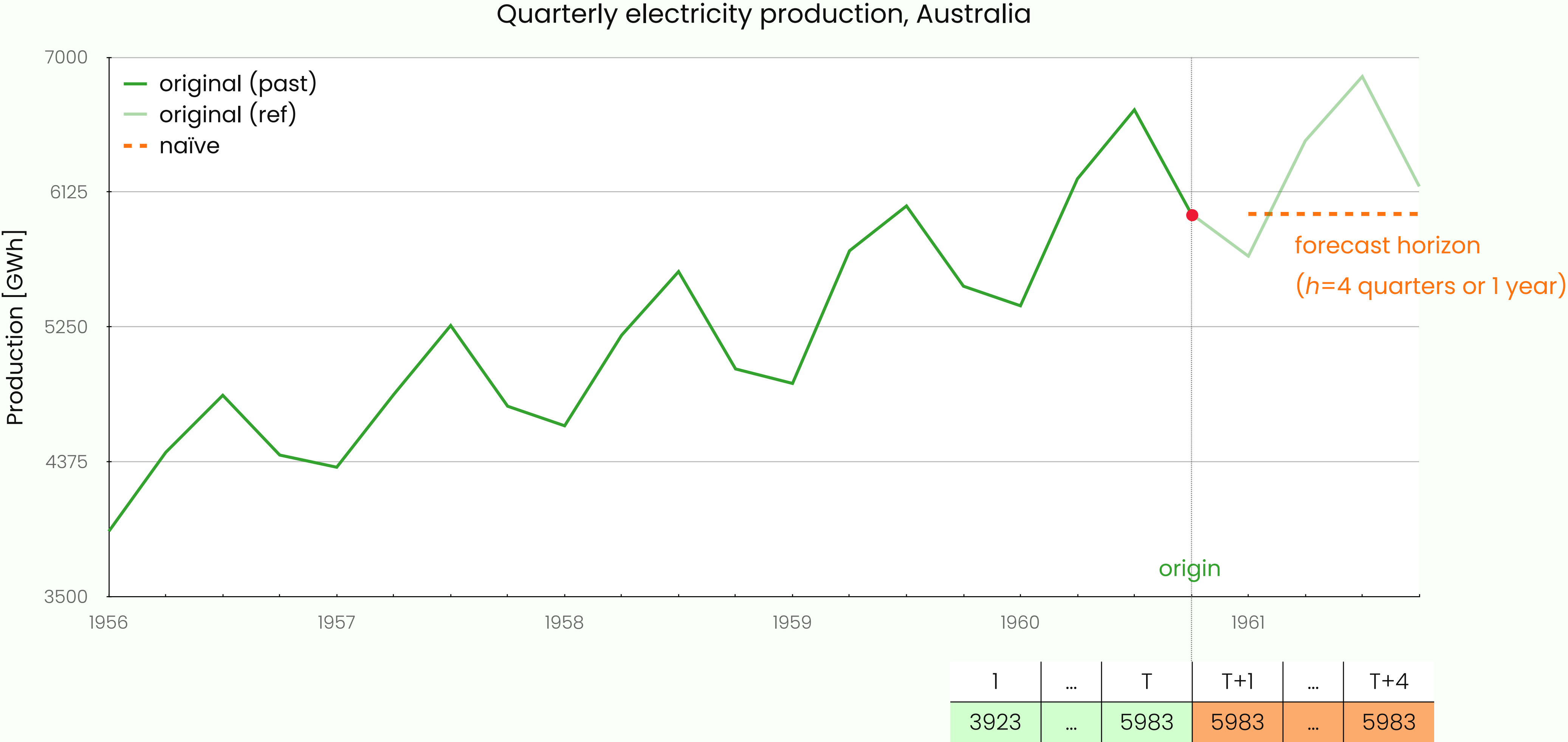
PREDICTION INTERVALS (2)



Set a baseline.
Use simple models!

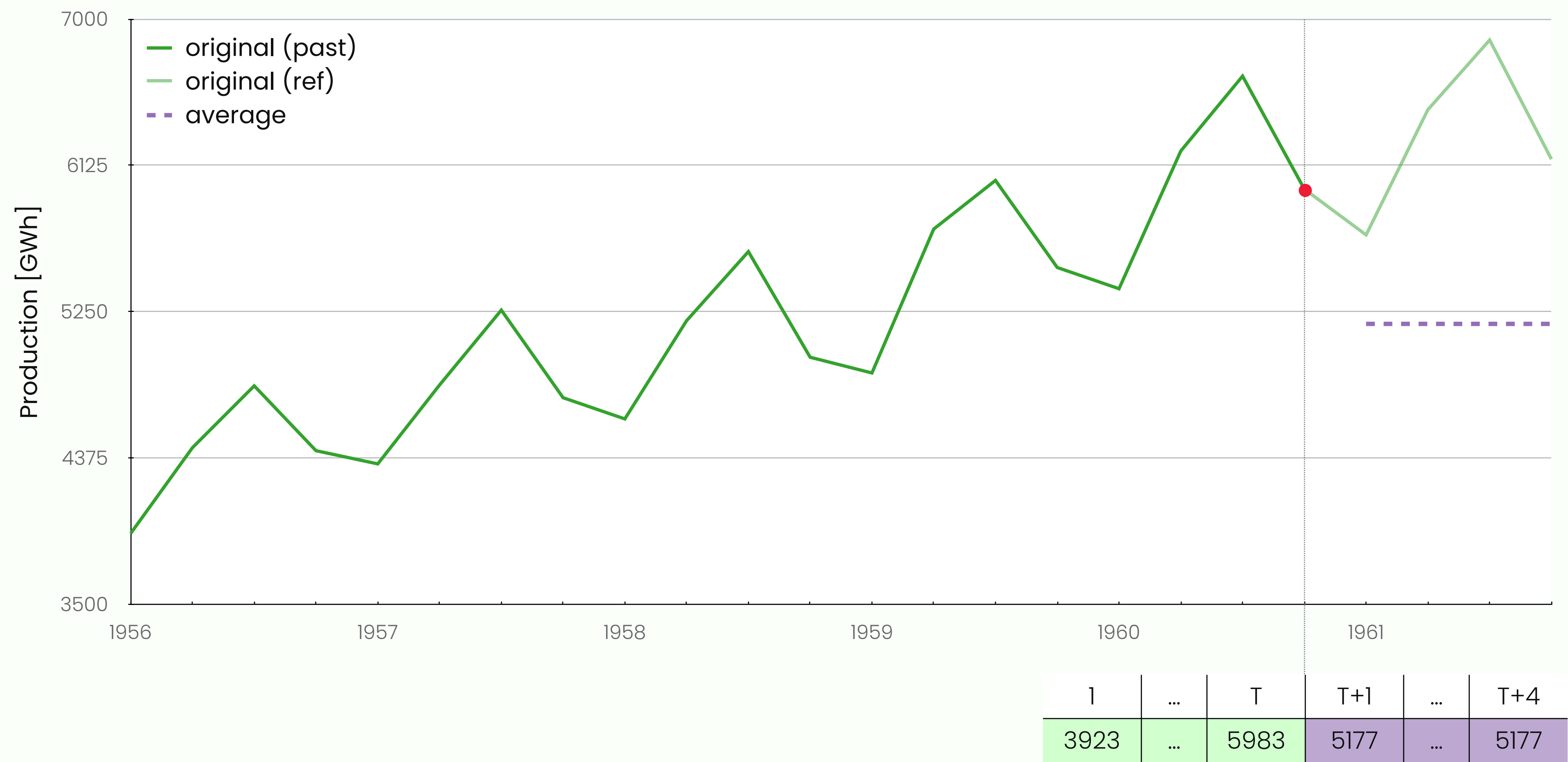
METHOD 1: NAÏVE

All forecasts are equal to the value of the last observation: $\hat{y}_{T+h|T} = y_T$.



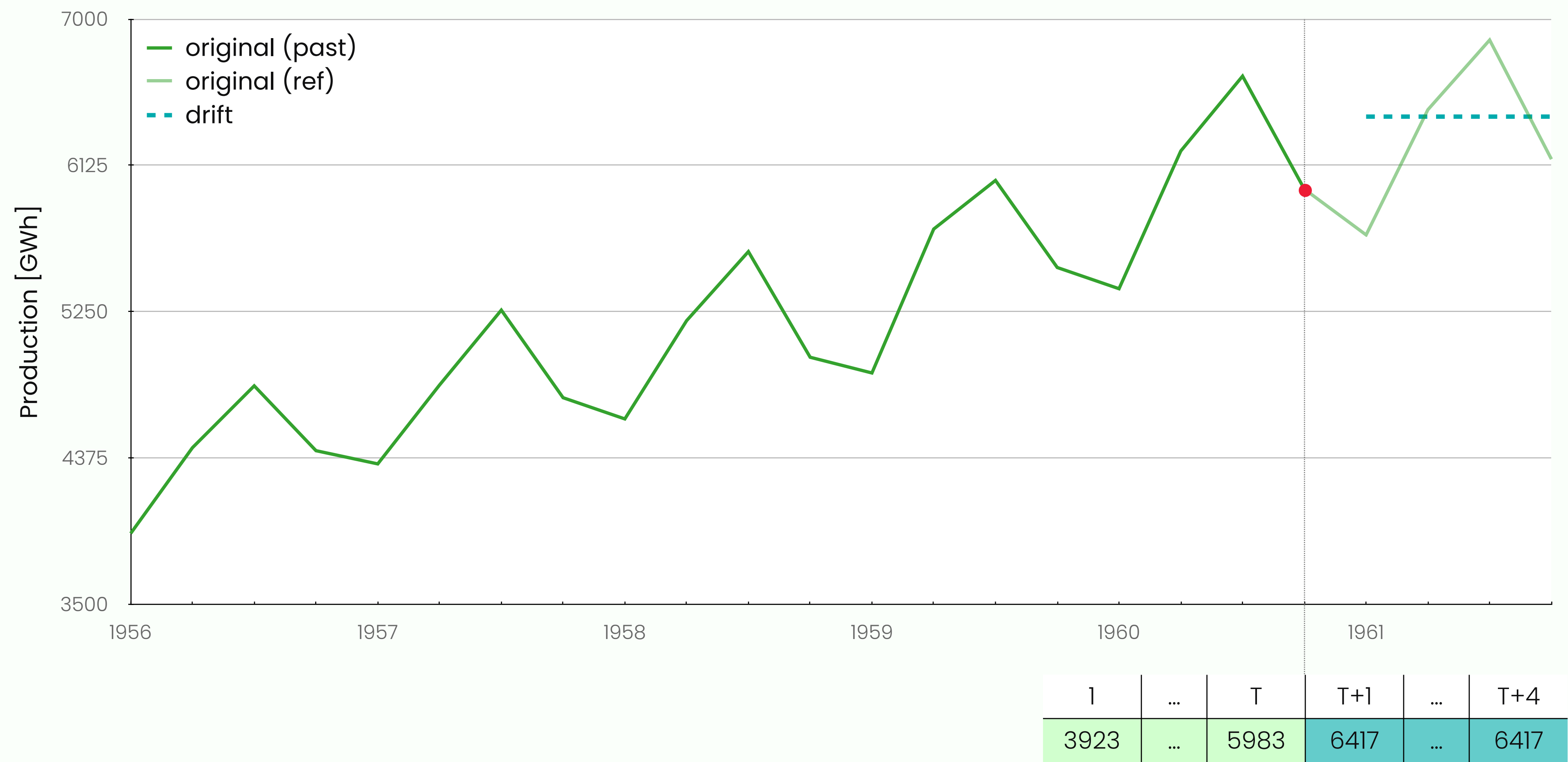
METHOD 2: AVERAGE (OR MEAN)

Forecasts are equal to the average of the historical data: $\hat{y}_{T+h|T} = \frac{y_1 + \dots + y_T}{T}$.



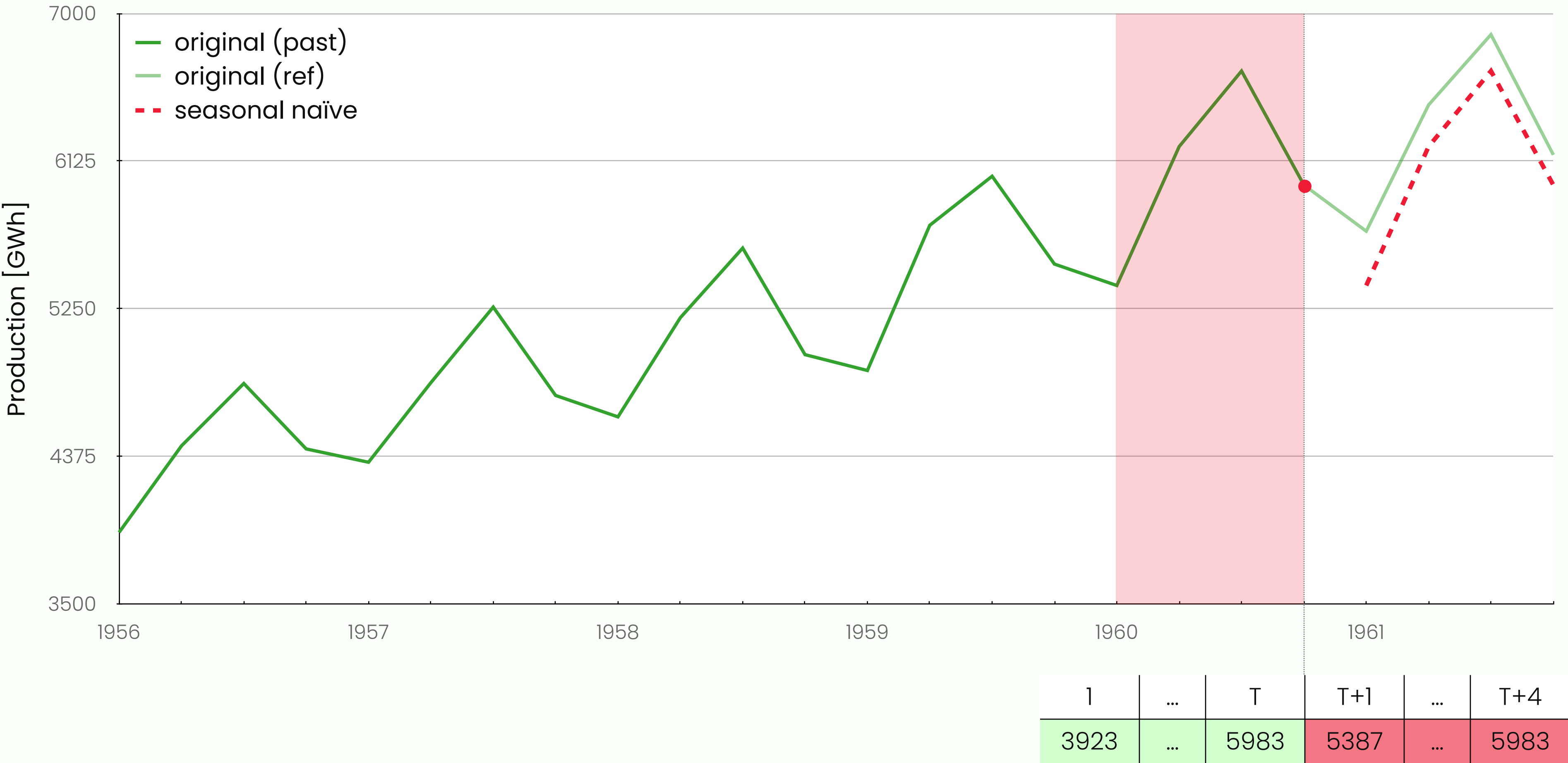
METHOD 3: DRIFT

A variation of the naïve method, forecasts may change (drift) over time: $\hat{y}_{T+h|T} = y_T + \frac{h}{T-1}(y_T - y_1)$.

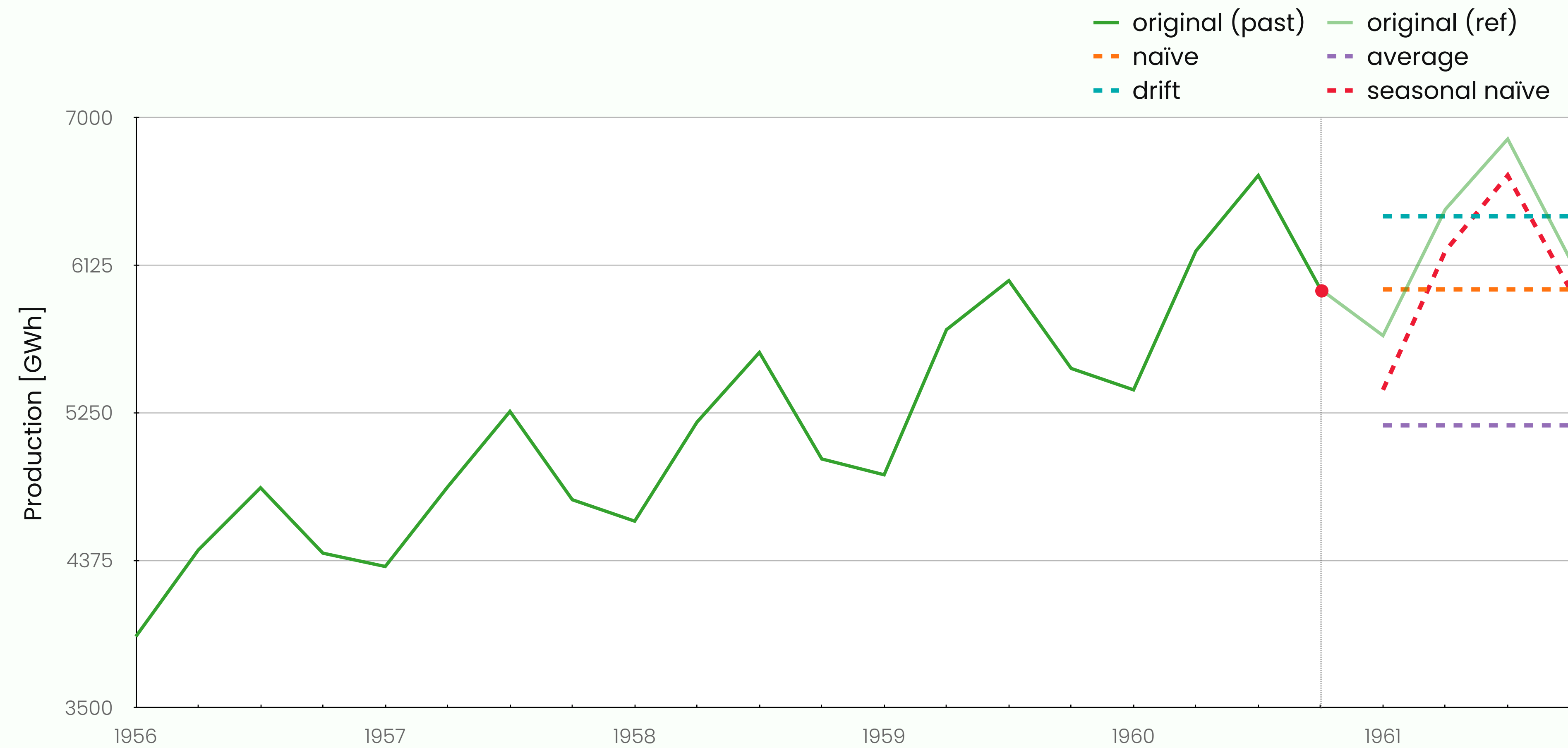


METHOD 4: SEASONAL NAÏVE

Each forecast is equal to the last observed value from the same season: $\hat{y}_{T+h|T} = y_{T+h-m(k+1)}$.
 m is the seasonal period; k is the integer part of $(h - 1)/m$, i.e., the number of complete seasons prior to $T + h$



FORECAST (OUT-OF-SAMPLE)



CHECKPOINT

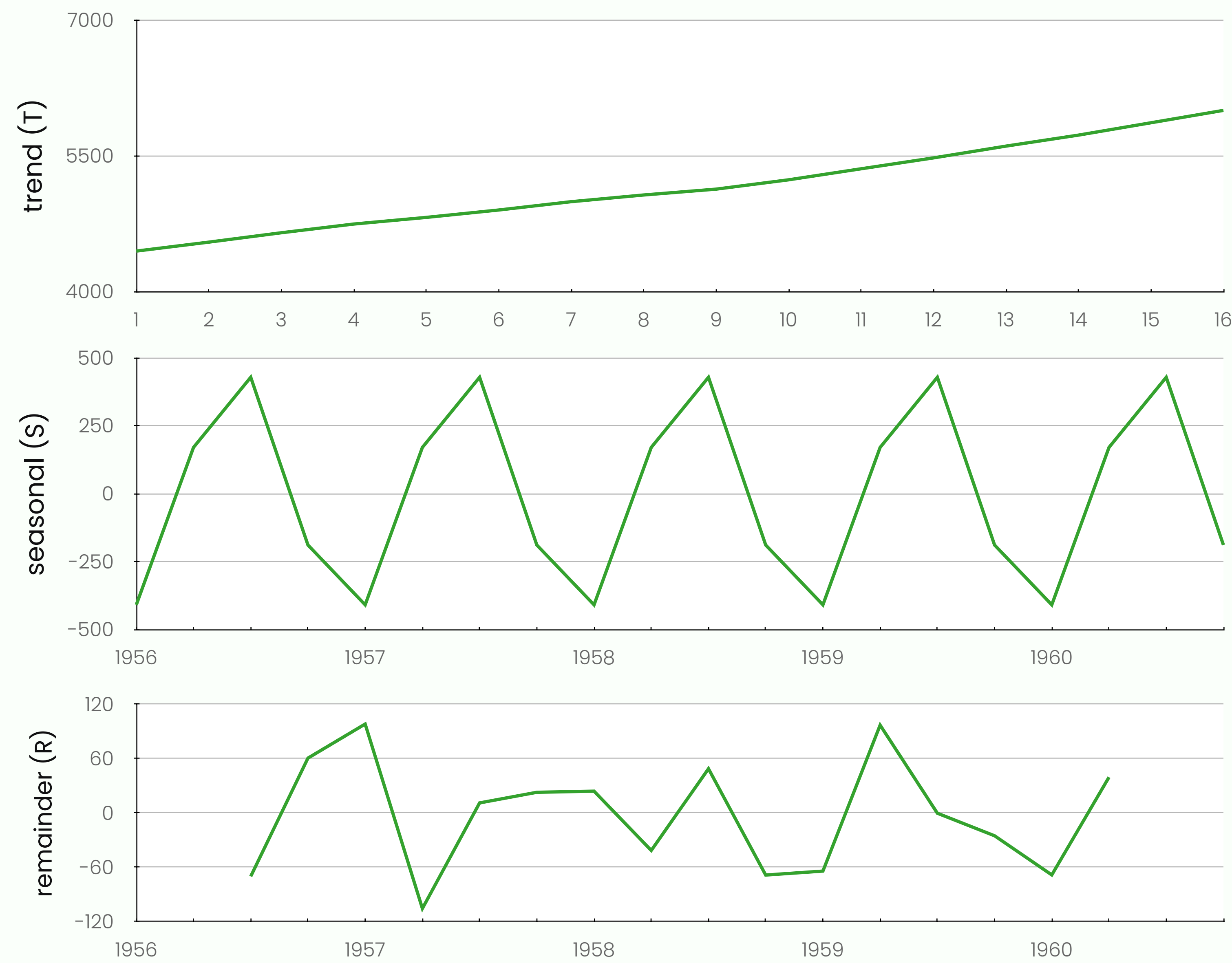
Performance of the forecasting models

	Naïve	Average	Drift	Seasonal naïve
MAE	455	1124	365	241
RMSE	531	1202	440	246

Let's be a bit more
advanced

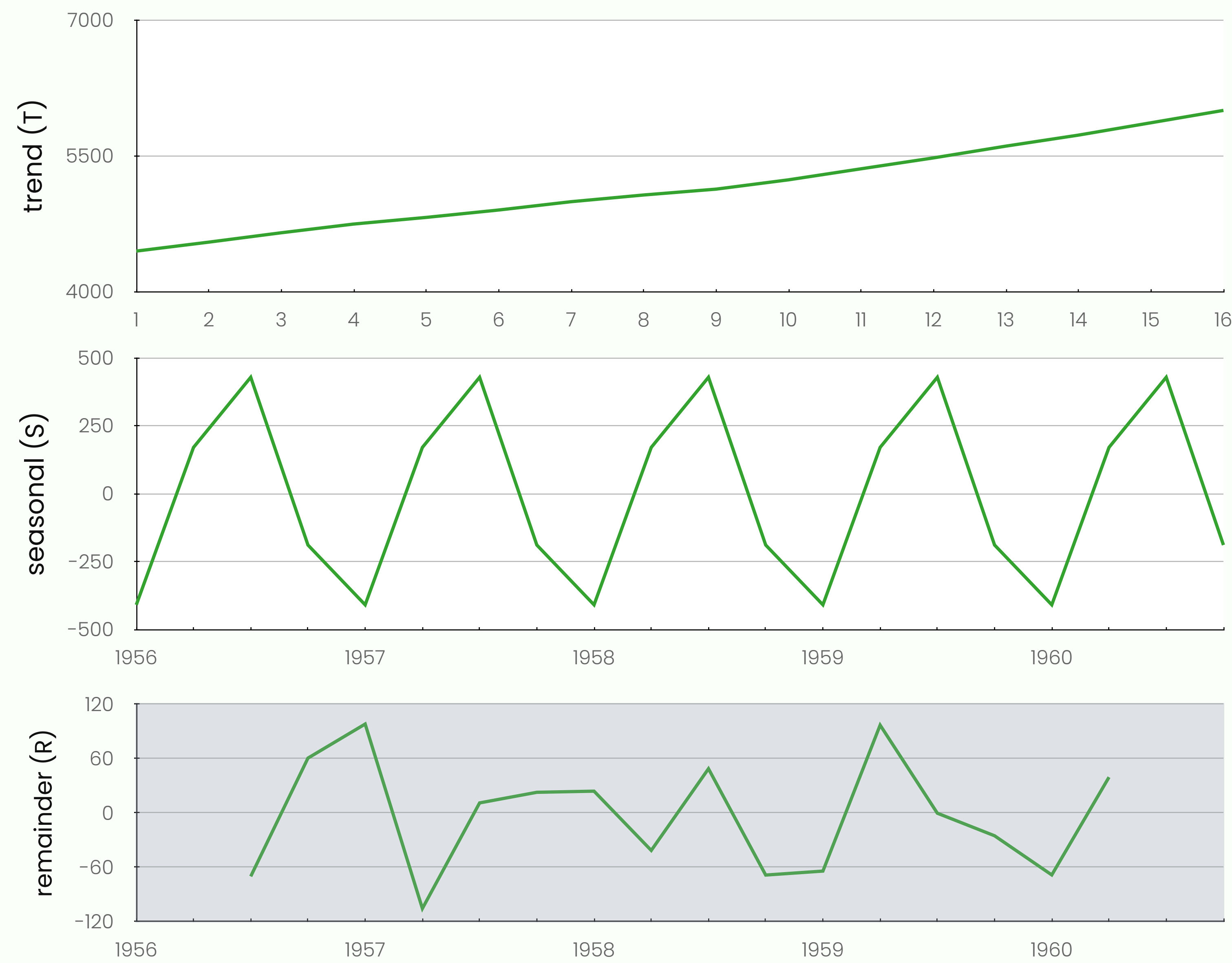
METHOD 5: CLASSICAL DECOMPOSITION, L9

$$y_t = \hat{T}_t + \hat{S}_t + \hat{R}_t$$



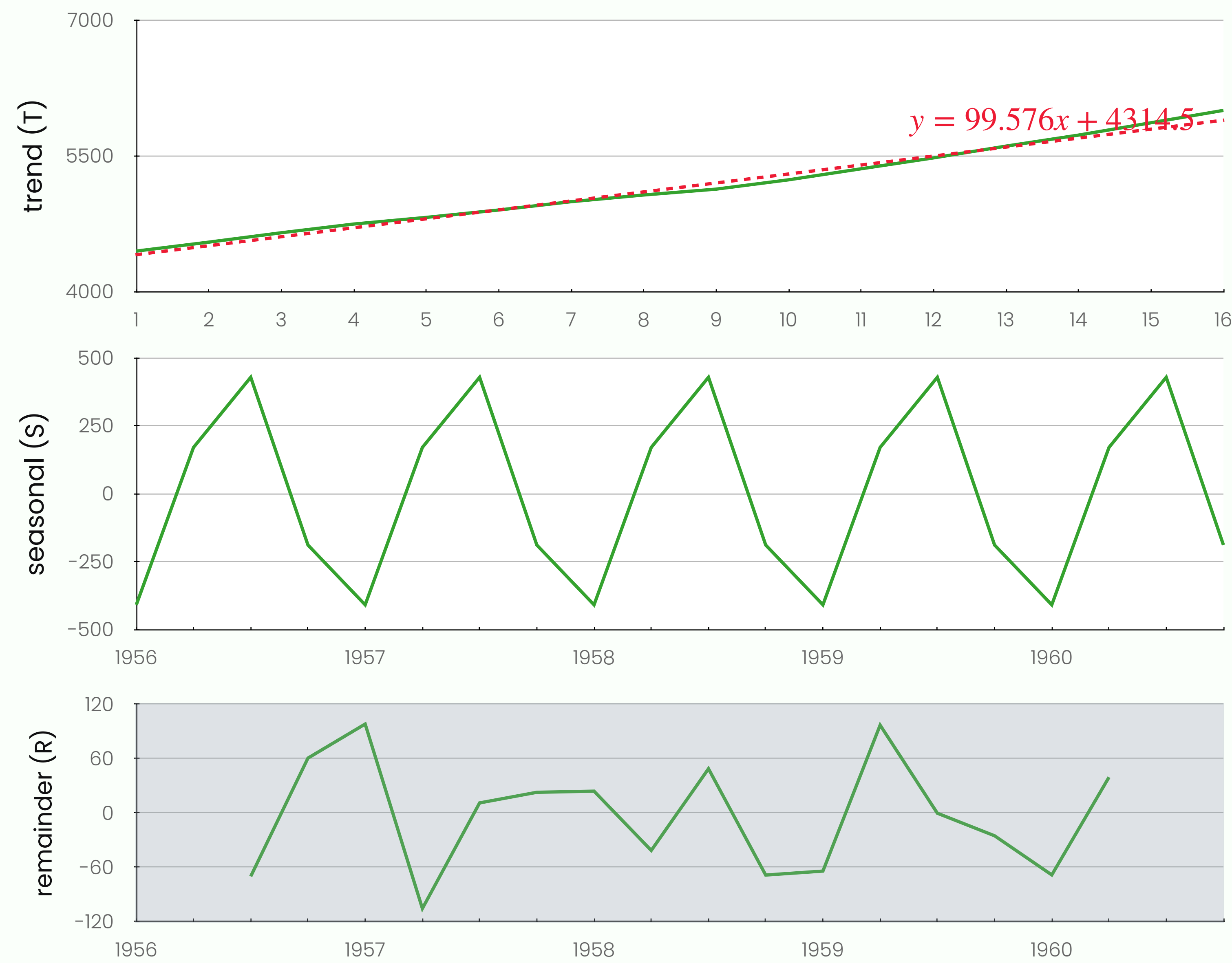
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NB! x is index
(not a year):

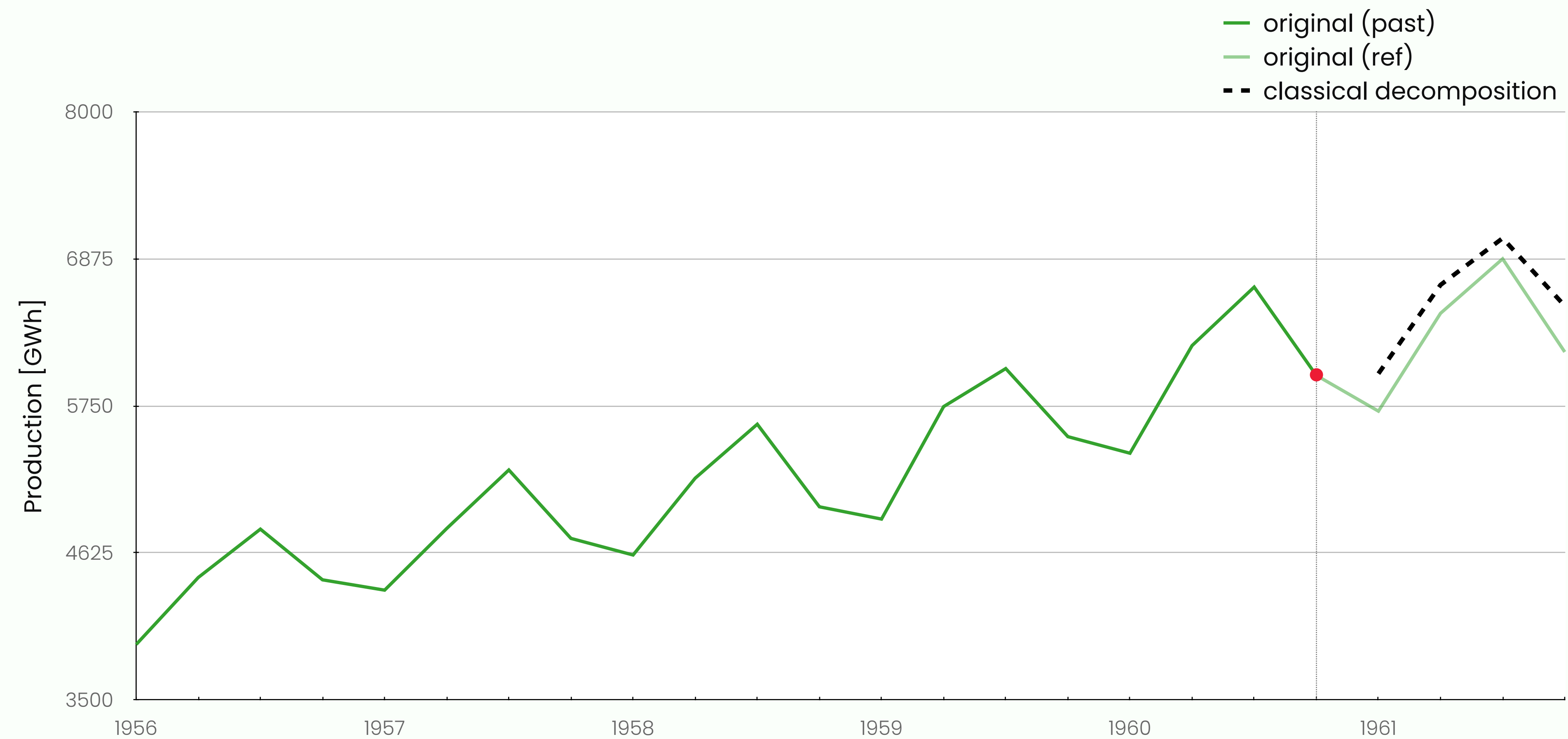
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NB! x is index
(not a year):

CLASSICAL DECOMPOSITION (2)



METHOD 6: SEASONAL ARIMA MODEL

SARIMA

$$(p, d, q)$$



Non-seasonal
part of the model

$$(P, D, Q)_m$$



Seasonal part
of the model

SARIMA (2)

SARIMAX Results

Dep. Variable:electricity

No. Observations:20

Model:SARIMAX(0, 1, 1)x(1, 0, [], 4)

Log Likelihood-122.022

Date:Tue, 15 Jul 2025

AIC252.044

Time:08:22:44

BIC255.821

Sample:03-01-1956

HQIC252.683

- 12-01-1960

Covariance Type:opg

	coef	std err	z	P> z	[0.025	0.975]
intercept	4.2971	6.424	0.669	0.504	-8.294	16.888
ma.L1	-0.6389	0.202	-3.157	0.002	-1.036	-0.242
ar.S.L4	0.9575	0.047	20.470	0.000	0.866	1.049
sigma2	1.002e+04	4191.820	2.390	0.017	1801.054	1.82e+04

Ljung-Box (L1) (Q):0.33

Jarque-Bera (JB):0.80

Prob(Q):0.57

Prob(JB):0.67

Heteroskedasticity (H):0.76

Skew:0.30

Prob(H) (two-sided):0.74

Kurtosis:2.20

Seasonal

AR(1)

Non-seasonal

difference

Non-seasonal

MA(1)

$$(1 - 0.9575B^4)(1 - B)\hat{y}_t = (1 - 0.6389B)\epsilon_t$$

SARIMA (2)

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No. Observations:

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Model:

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Log Likelihood

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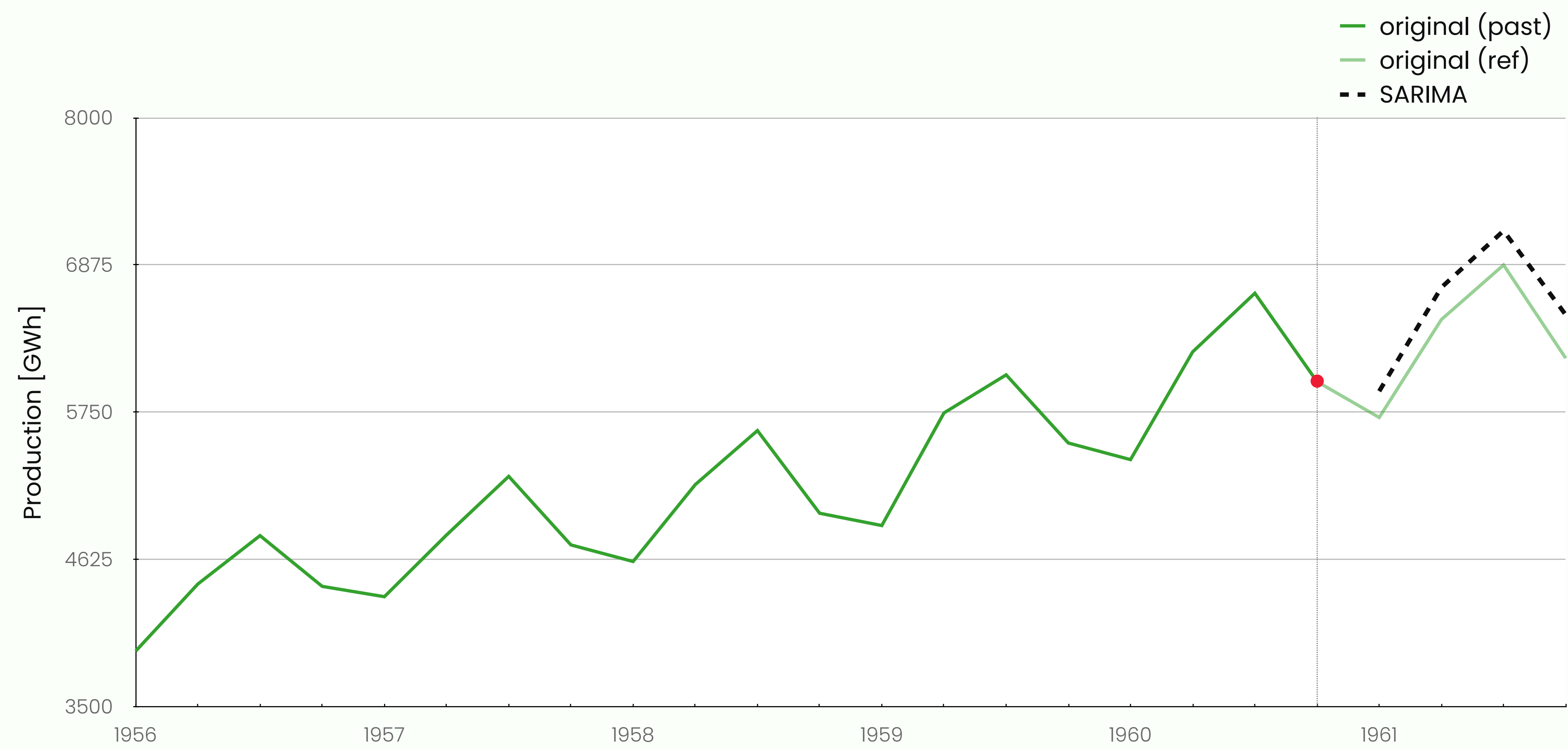
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Non-seasonal

MA(1)

$$(1 - 0.9575B^4)(1 - B)\hat{y}_t = (1 - 0.6389B)\epsilon_t$$

SARIMA (3)



CHECKPOINT 2

Performance of the forecasting models

	Naïve	Average	Drift	Seasonal naïve	Classical decomposition	SARIMA
MAPE	7.01	17.47	5.96	3.88	4.11	4.13
RMSE	531	1202	440	246	264	264

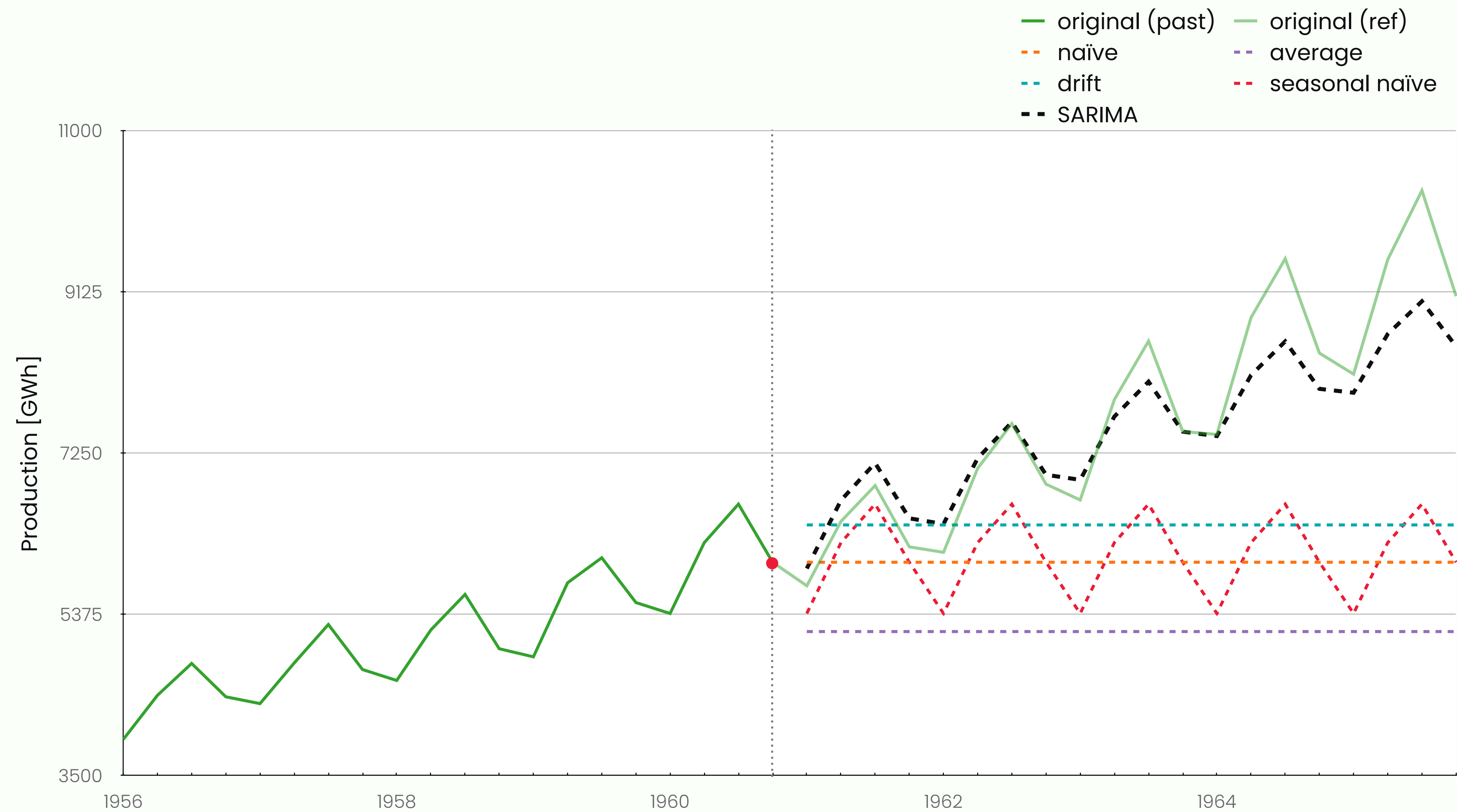
CHECKPOINT 2

Performance of the forecasting models

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MAPE	7.01	17.47	5.96	3.88	4.11	4.13
RMSE	531	1202	440	246	264	264

Any remarks?

LONGER FORECAST!?



HOME ACTIVITIES

- *Try to improve the forecast from seasonal decomposition by using a more accurate method to estimate the trend.
- *Experiment with the window length and see how it affects the quality of the forecast.
- *Try other metrics to validate the forecast. Are they more informative?

Thank you!

Questions?