

Machine Learning Principles

Class3 : Sept. 11

Linear Algebra for ML

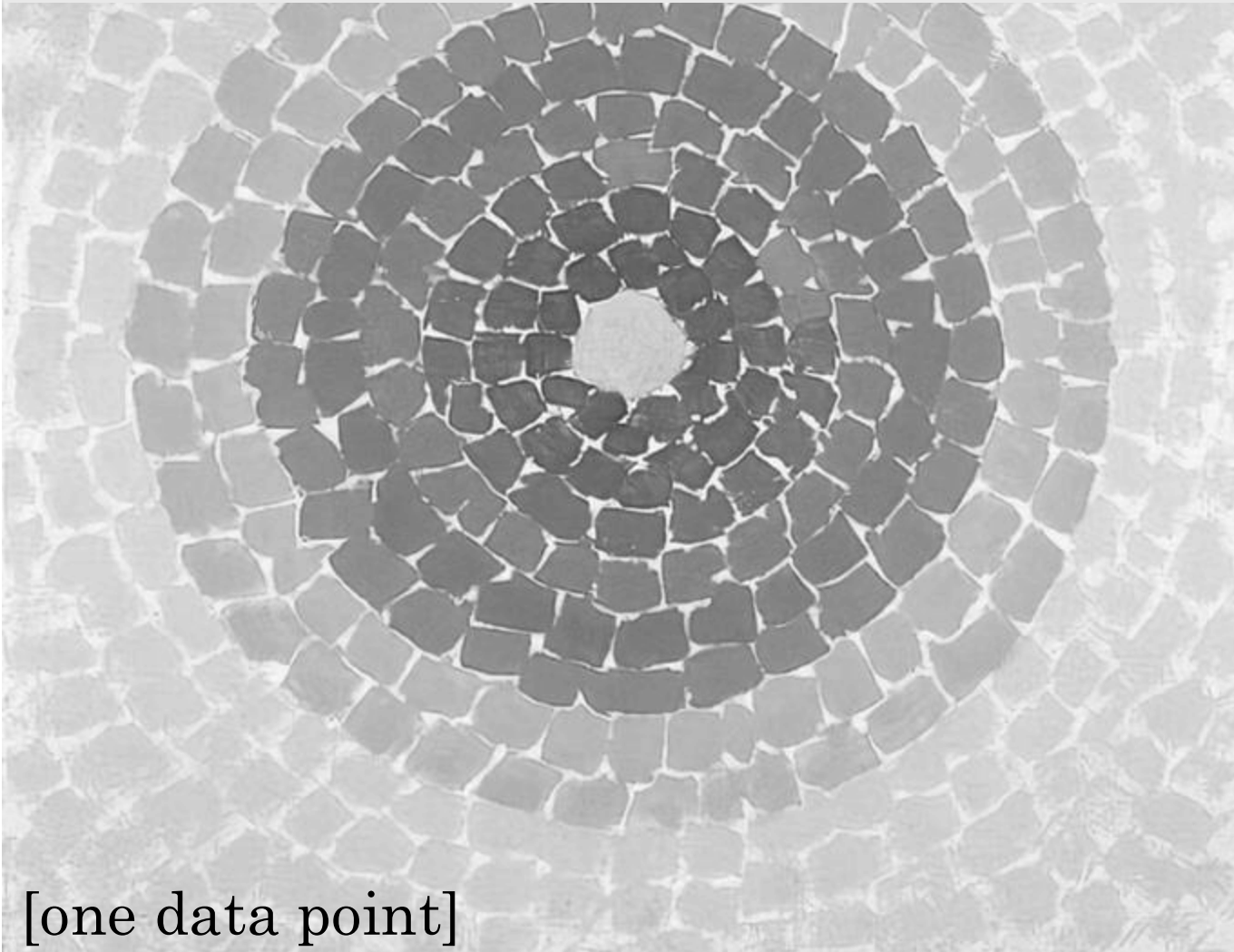
Instructor: Diana Kim

Today's Lecture

- 0. Why Linear Algebra?
- 1. Useful Techniques of Linear Algebra for ML
 - vector space
 - spectral decomposition
 - (1) decorrelation and whitening
 - (2) PCA
 - singular vector decomposition
 - pseudo inverse matrix.

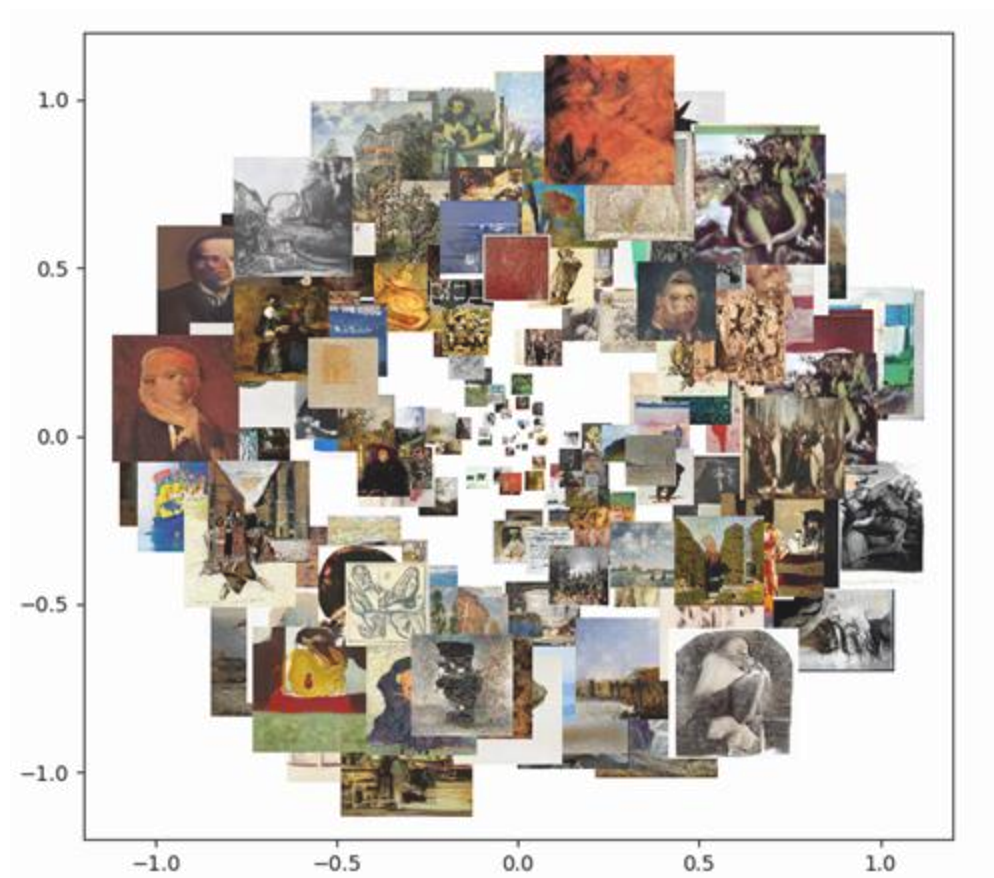
[1] Why Linear Algebra in ML?

“mathematical machinery too to build ML system with data”



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[2] Why Linear Algebra in ML? (data set)

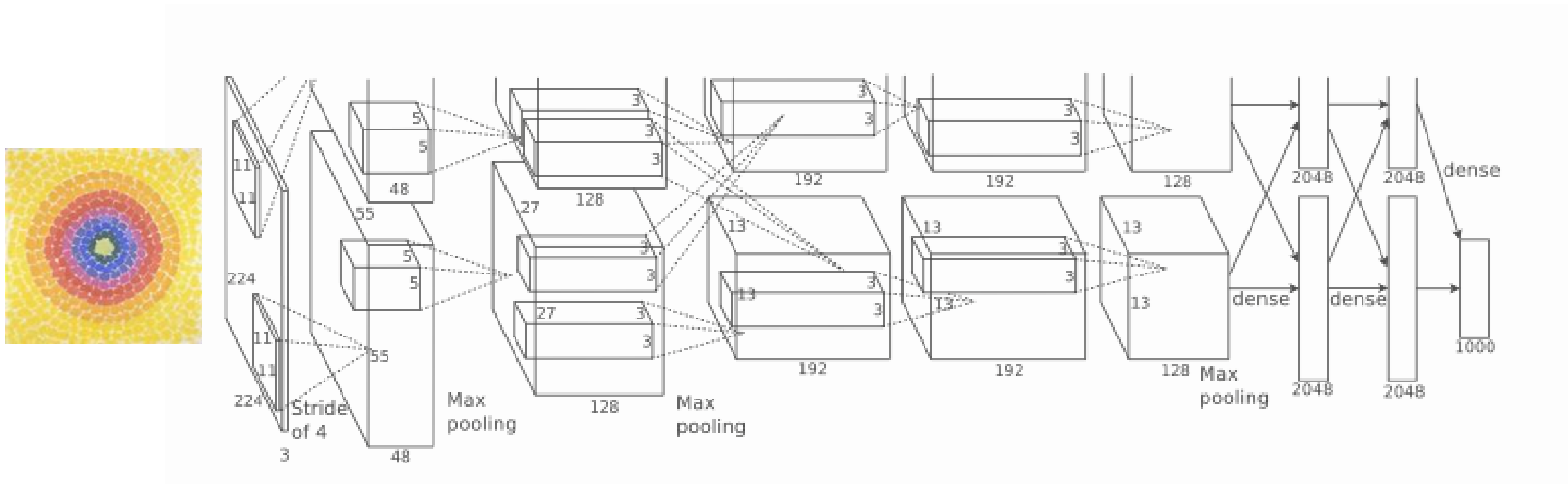


[wikiArt data, ~80,000 images]



- How can you define a random variable to represent the data?

[3] Why Linear Algebra in ML? (transformation)

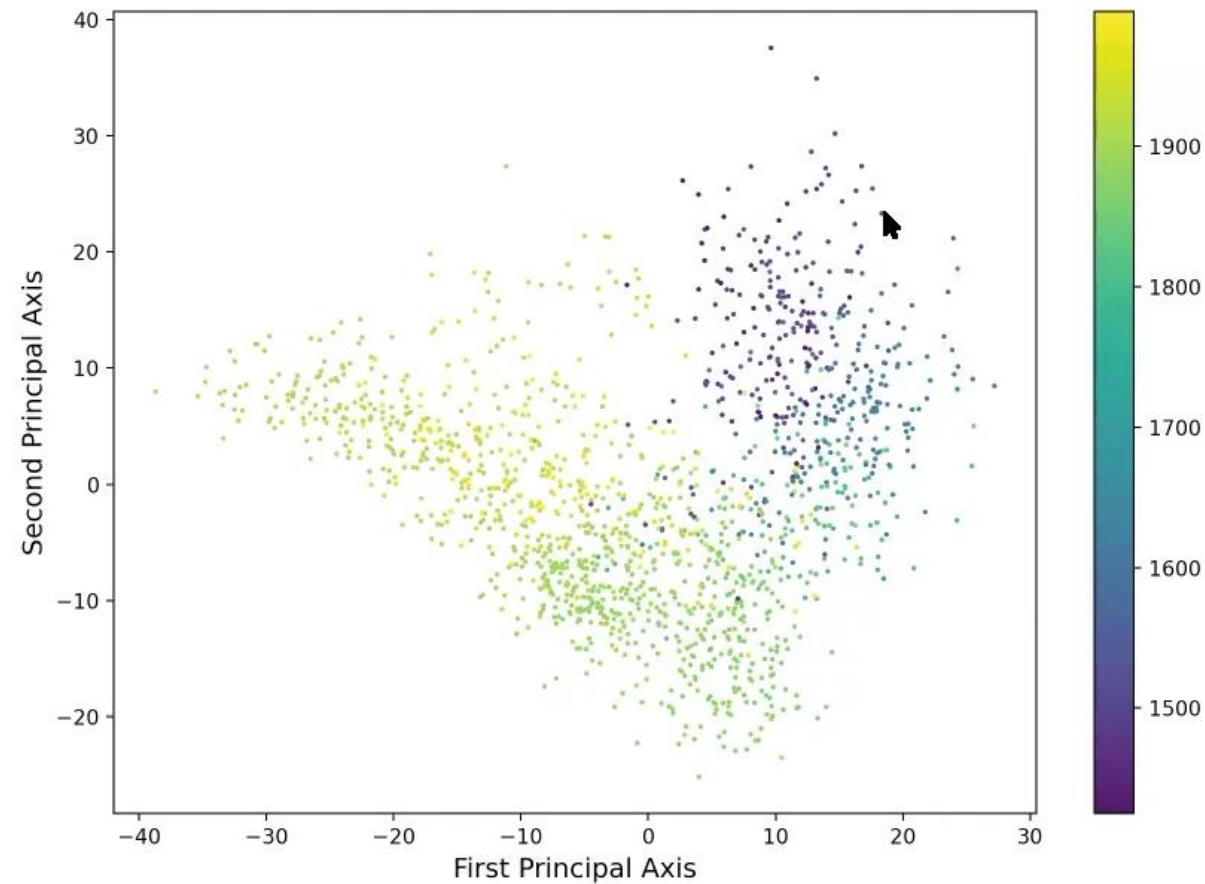


- ML system with data : linear / non-linear transformation.

[4] Why Linear Algebra in ML?

- data representation/transformation in a vector space (high dimensional)
- provides tools to understand the geometric shape of high dimensional data (decorrelation: whitening & data compression: PCA)
- linear regression problem can be translated into solving a linear system.
- Linear Algebra plays a role in every stage of machine learning from (1) data preprocessing to (2) modeling and learning.

Demo: Embedding of the Last Hidden Layer of a Deep-CNN Style Classifier (First Two Axes)



[5] Why Linear Algebra in ML? (Linear Regression)

- Linear Regression Model: $aX_1 + bX_2 + cX_3 = Y$
- a, b, c by solving the linear system below

	X_1	X_2	X_3
#1	1.4	2.7	3.2
#2	2.2	3.5	3.3
#3	3.1	5.2	1.2
#4	1.7	1.0	0.2
#5	4.6	1.1	0.9
#6	2.2	4.3	2.7
#7	1.2	2.3	7.6
#8	0.3	0.2	3.2
#9	2.5	0.5	0.9
#10	1.8	1.9	1.1

$$\times \begin{bmatrix} a \\ b \\ c \end{bmatrix} =$$

	Y
#1	1
#2	1.3
#3	0.8
#4	0.3
#5	1
#6	4
#7	3.6
#8	2.9
#9	2.5
#10	0

- Linear Algebra 101: Vector Space

[1] Vector Space & Subspace

A vector space (\mathbb{R}^N) is a set of vectors that is closed by **linear combinations** (vector addition and multiplication by real number).

The vector addition & multiplication by real number follows the eight rules.

1. $x + y = y + x$.

2. $x + (y + z) = (x + y) + z$.

3. There is a unique “zero vector” such that $x + 0 = x$ for all x .

[additive identity]

4. For each x there is a unique vector $-x$ such that $x + (-x) = 0$.

5. $1x = x$.

6. $(c_1 c_2)x = c_1(c_2 x)$.

7. $c(x + y) = cx + cy$.

8. $(c_1 + c_2)x = c_1 x + c_2 x$.

[2] Vector Space & Subspace

- vector space: closed under linear combination

 \Leftrightarrow if V is a vector space,
then if $v_1 \in V$ and $v_2 \in V$ then $av_1 + bv_2 \in V, \forall a$ and $b \in \mathbb{R}$.

Q: simplest vector space?

Q: $V = \{[0], [1]\}$ is this a vector space?

[3] Vector Space & Subspace

A subspace of a vector space is a subset that satisfies the requirements for a vector space.

ex] the examples of subspace

- (1) any line through $(0,0,0)$ in \mathbb{R}^3
- (2) any plane through $(0,0,0)$ in \mathbb{R}^3
- (3) a line does not pass through $(0,0,0)$ in \mathbb{R}^3 ?

- Linear Algebra 101: Matrix's Vector Space
- column & row & null space

[1] Column & Row Space of a Matrix

The column (row) space contains
all linear combinations of the column (row) of matrix A.

ex] describe the **column** / **row** space of the matrix A.

$$A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

(1) column space: \mathbb{R}^2

(2) row space: a plane spanned by $[1 \ 0 \ 1]$ and $[0 \ 1 \ 1]$

$$: x + y - z = 0$$

: a subspace in \mathbb{R}^3

[2] Dimension of the column/ row space

The dimension of row / columns space = # independent vectors.

The dimension is called **the “rank” of a matrix.**

The dimension of row space and column space of a matrix is the same!

ex] describe the column / row space of the matrix A.

$$A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

(1) column space: \mathbb{R}^2

(2) row space: a plane spanned by $[1 \ 0 \ 1]$ and $[0 \ 1 \ 1]$

: $x + y - z = 0$

: a subspace in \mathbb{R}^3

[3] Null Space of a Matrix

The null space of a matrix A consists of all vectors x s.t. $Ax = 0$

Null space is orthogonal to the row space of A .

$\text{rank}(\text{row}) + \text{rank}(\text{null}) = N$ when row space in \mathbb{R}^N

ex] describe the null space of A . (recitation)

$$A = \begin{bmatrix} 1 & 0 & 1 \\ 5 & 4 & 9 \\ 2 & 4 & 6 \end{bmatrix}$$

- Linear Algebra in ML
 - (1) solving a linear system ($Ax = b$)

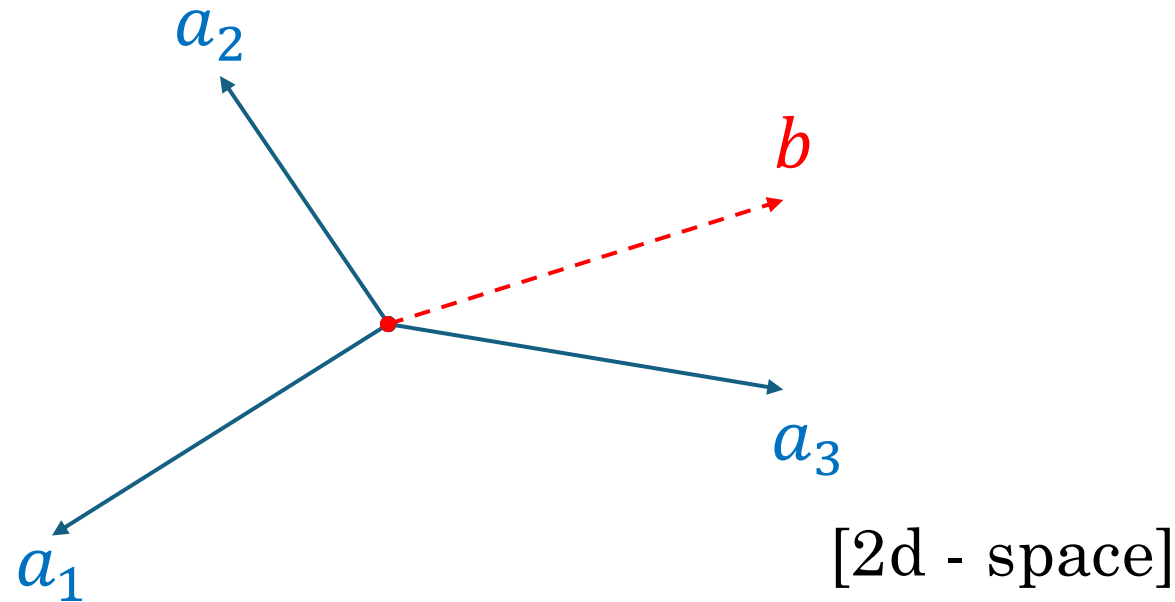
[1] Solution of a Linear System (Existence of Solution)

A solution / multiple solutions of a linear system ($Ax = b$) exist if the vector b is on the column space of A .

$$\text{ex] } \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 5 \end{bmatrix}$$

Q: how can we make this equation to have a solution?
how many solutions exist?

[2] Solution of a Linear System (Existence of Multiple Solutions)



$$\begin{bmatrix} a_1 & a_2 & a_3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = b, \text{ infinite many possible solutions } [x, y, z]$$

infinite many solutions exist if b is on the column space of $\begin{bmatrix} a_1 & a_2 & a_3 \end{bmatrix}$ and the column vectors a_1 a_2 a_3 are not independent.

[3] Solution of a Linear System (no solution)

no solution of a linear system ($Ax = b$) exist if the vector b is on the column space of A .

ex] in linear regression, we aim to solve $[a, b, c]$

	X_1	X_2	X_3
#1	1.4	2.7	3.2
#2	2.2	3.5	3.3
#3	3.1	5.2	1.2
#4	1.7	1.0	0.2
#5	4.6	1.1	0.9
#6	2.2	4.3	2.7
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#8	0.3	0.2	3.2
#9	2.5	0.5	0.9
#10	1.8	1.9	1.1
...			

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} =$$

	Y
#1	1
#2	1.3
#3	0.8
#4	0.3
#5	1
#6	4
#7	3.6
#8	2.9
#9	2.5
#10	0
...	

- the vector for Y is likely be outside of the three-dimensional column space in \mathbb{R}^M ($M: \#data$)

- Linear Algebra in ML
 - (2) Spectral Decomposition of Symmetric Matrix (Covariance)

*symmetric matrices are decomposed into eigenvectors and eigenvalues matrices.

[1] Spectral Decomposition of Symmetric Matrix

A symmetric matrix (Σ) can be represented by the matrix of eigenvectors (E) and eigenvalues (Λ).

$$\Sigma = \begin{bmatrix} | & & | \\ e_1 & e_2 & \dots e_n \\ | & & | \end{bmatrix} \cdot \begin{bmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & & & \\ 0 & \dots & \dots & \lambda_n \end{bmatrix} \cdot \begin{bmatrix} e_1^t \\ e_2^t \\ \dots \\ e_n^t \end{bmatrix}$$

****convention: descending order**

$$\Sigma = \lambda_1 \cdot e_1 e_1^t + \lambda_2 \cdot e_2 e_2^t + \dots + \lambda_n \cdot e_n e_n^t$$

- e_i : eigenvectors, $e_i^t \cdot e_j = 0$ and $\|e_i\| = 1$ (orthonormal)
- λ_i : eigenvalues (# non zeros = #rank)

[2] Spectral Decomposition of Symmetric Matrix (proof)

$$\begin{aligned} \text{proof] } [\Sigma e_1 \quad \Sigma e_2 \quad \dots \quad \Sigma e_n] &= [\lambda_1 e_1 \quad \lambda_1 e_2 \quad \dots \quad \lambda_n e_n] \\ &= [e_1 \quad e_2 \quad \dots \quad e_n] \begin{bmatrix} \lambda_1 & \dots & 0 \\ \dots & \dots & 0 \\ 0 & 0 & \lambda_n \end{bmatrix} \end{aligned}$$

$$\Sigma E = E \Lambda$$

$$\Sigma = E \Lambda E^t \text{ (Spectral Decomposition)}$$

two eigenvectors for the distinct eigenvalues of a symmetric matrix are orthogonal

$$\begin{aligned} e_1^t \Sigma e_2 &= e_1^t \Sigma^t e_2 \\ &= (\Sigma e_1)^t e_2 \\ &= \lambda_1 e_1^t e_2 \end{aligned}$$

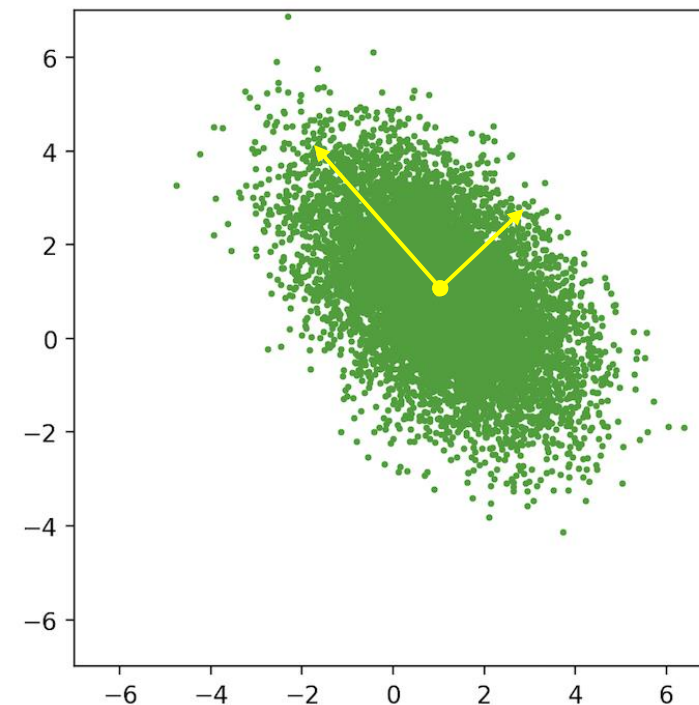
$$\lambda_2 e_1^t e_2 = \lambda_1 e_1^t e_2$$

[3] Spectral Decomposition of Symmetric Matrix (Geometric Shape)

Covariance matrix shows **the extent** and **direction of data sample dispersion**. The direction and degree can be computed by using spectral decomposition.

$$\Sigma = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} \quad \mu = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

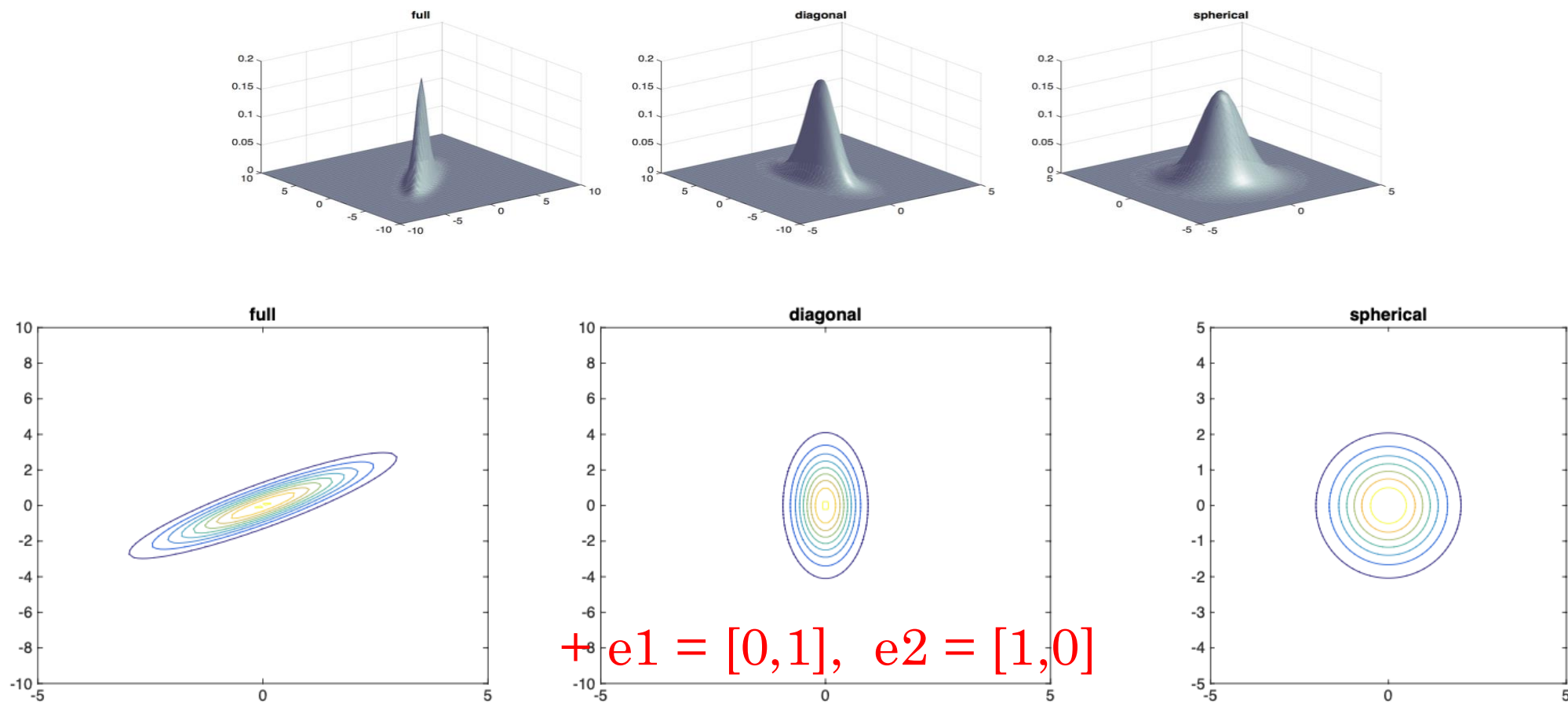
$$\Sigma = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 1 & -1 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 1 & -1 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \longrightarrow$$



[2-d Gaussian Data Samples]

[4] Spectral Decomposition of Symmetric Matrix (Geometric Shape)

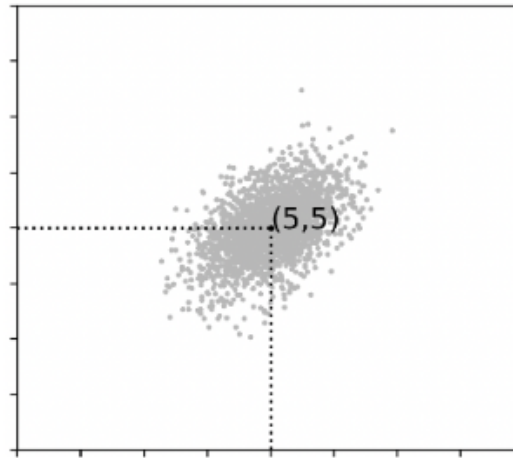
From Murphy Figure 3.5 and 3.6. “An Introduction”



- can we guess the eigenvector & eigenvalues from the gaussian contours?

[5] Spectral Decomposition of Symmetric Matrix (Geometric Shape)

[Quiz Example]



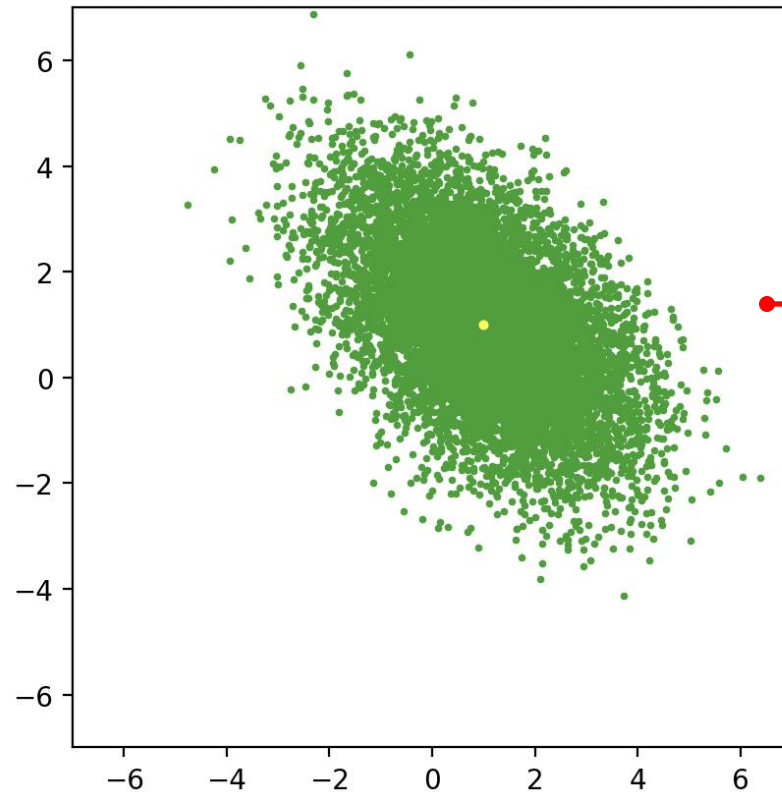
$$e1 = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ 1 \\ \frac{1}{\sqrt{2}} \end{bmatrix} \quad e2 = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ 1 \\ -\frac{1}{\sqrt{2}} \end{bmatrix}$$

$$E[X] = \begin{bmatrix} 5 \\ 5 \end{bmatrix} \quad COV[X, X] = \begin{bmatrix} & \\ & \end{bmatrix} \cdot \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} & \\ & \end{bmatrix}$$

- Linear Algebra in ML
 - (2) Spectral Decomposition of Symmetric Matrix (Covariance)
 - whitening (decorrelation)
 - PCA (data dimensionality reduction)

[1] Spectral Decomposition of Symmetric Matrix (Whitening: mean=0 & COV=I)

ex] how could we whiten the data samples (decorrelation)?

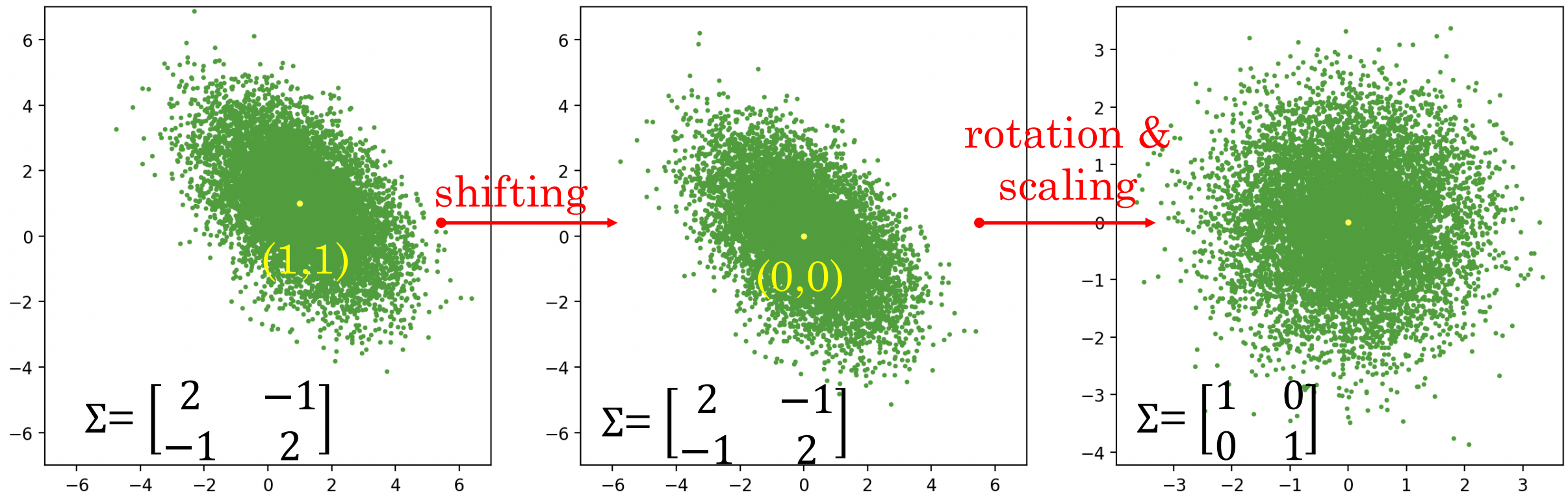


what transform?

$$\Sigma = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}, \mu = [1, 1]$$

[2] Spectral Decomposition of Symmetric Matrix (Whitening: mean=0 & COV=I)

ex] how could we whiten the data samples?



[3] Spectral Decomposition of Symmetric Matrix (Whitening)

Suppose random vector X 's $E[X] = \mu$ and $\text{COV}(X) = \Sigma = E\Lambda E^t$

Define Affine transformation $W = AX + b$ where $E[W] = 0$ and $\text{COV}(W) = I$.

sol)

$$E[W] = E[Ax + b] = 0$$

$$b = -A\mu_x$$

$$W = A(x - \mu_x) \quad \blacksquare \text{ [shifting]}$$

$$\text{COV}(W) = E[WW^t] = I$$

$$= E[A(x - \mu_x)(x - \mu_x)^t A^t]$$

$$= AE[(x - \mu_x)(x - \mu_x)^t]A^t$$

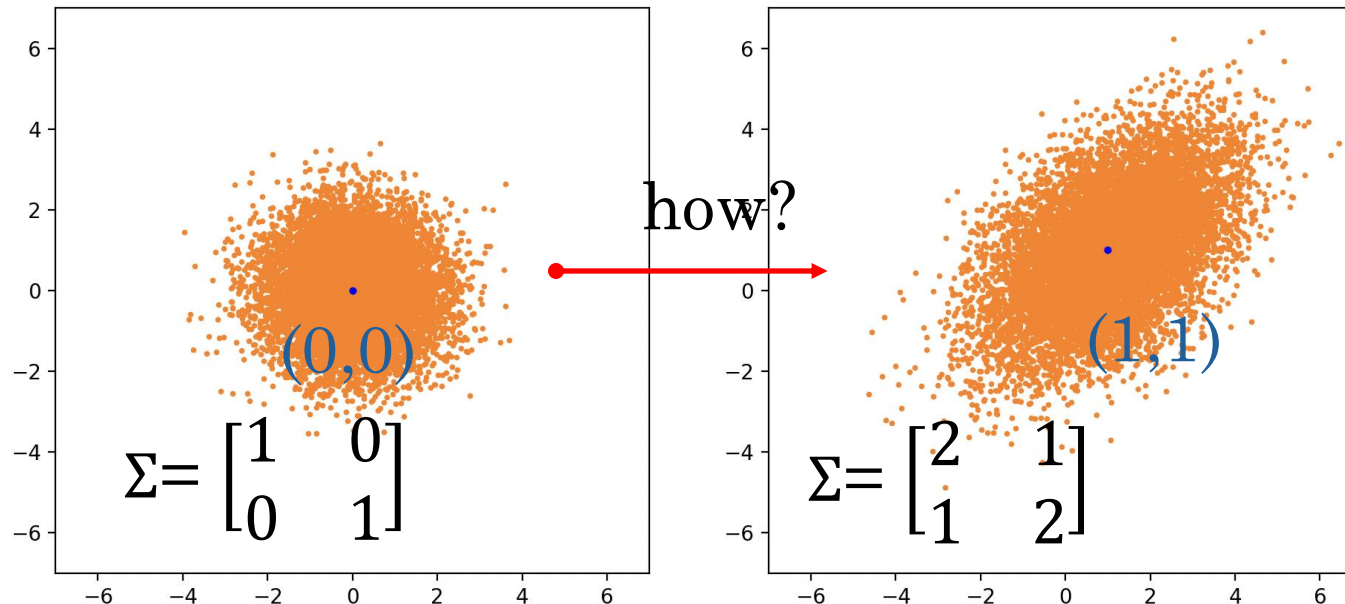
$$= A \cdot \text{COV}(X)A^t = I$$

$$A = \Lambda^{-1/2}E^t \quad \blacksquare \text{ [rotation \& scaling]}$$

[4] Spectral Decomposition of Symmetric Matrix (Gaussian Generation, **recitation**)

ex] how can we generate the Gaussian random vector $X \sim N(\mu, \Sigma)$ from $W \sim N(0, I)$?

$$\Sigma^* = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 1 & -1 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \cdot \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 1 & -1 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \quad \mu = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$



$$A = A W + b, \quad A? b?$$

This problem will be covered in detail during the recitation.

Q: How do eigenvectors determine the direction of maximum / minimum variance of data?

1. we know spectral decomposition (eigenvectors and eigenvalues)

$$\Sigma = \begin{bmatrix} | & & | \\ e_1 & e_2 & \dots e_n \\ | & & | \end{bmatrix} \cdot \begin{bmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & & & \\ 0 & \dots & \dots & \lambda_n \end{bmatrix} \cdot \begin{bmatrix} e_1^t \\ e_2^t \\ \dots \\ e_n^t \end{bmatrix}$$

2. for $n = 2$, data variance at a certain direction can be computed by

$$\begin{aligned} E[P^t \cdot X \cdot X^t \cdot P] &= P^t E[X \cdot X^t] P = P^t \text{COV}(X) P \text{ where } P = a\overrightarrow{e_1} + b\overrightarrow{e_2} \\ &\text{and } ||P|| = 1 \text{ (} a^2 + b^2 = 1 \text{)} \\ &= a^2 \lambda_1 + b^2 \lambda_2 \end{aligned}$$

$$3. \lambda_{\min} \leq a^2 \lambda_1 + b^2 \lambda_2 \leq \lambda_{\max}$$

*Spectral Decomposition of Symmetric Matrix (Singular)

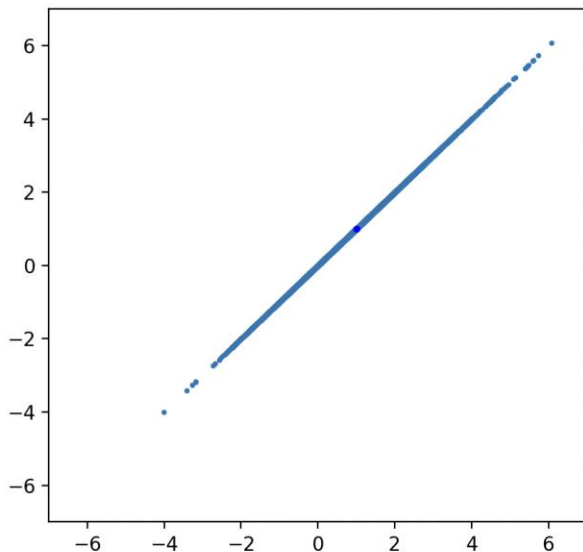
ex] how would the shape of a 2d scatter plot look like when the covariance matrix singular?

$$\Sigma = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 1 & -1 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \cdot \begin{bmatrix} 3 & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 1 & -1 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \quad \mu = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

* Spectral Decomposition of Symmetric Matrix (Singular)

ex] how would the shape of a 2d scatter plot look like when the covariance matrix singular?

$$\Sigma = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 1 & -1 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \cdot \begin{bmatrix} 3 & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 1 & -1 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \quad \mu = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$



- Principal Component Analysis (PCA)

representation of data manifolds in a high-dimensional space
into a subspace (“approximation”)

[**] previous slide: Spectral Decomposition of Symmetric Matrix

Suppose random vector X 's $E[X] = \mu$ and $\text{COV}(X) = \Sigma = E\Lambda E^t$

Define Affine transformation $W = AX + b$ where $E[W] = 0$ and $\text{COV}(W) = I$.

sol)

$$E[W] = E[AX + b] = 0$$

$$b = -A\mu_x$$

$$W = A(x - \mu_x) \quad \blacksquare \text{ [shifting]}$$

$$W = \Lambda^{-\frac{1}{2}} E^t (X - \mu_x)$$

$$\text{COV}(W) = E[WW^t] = I$$

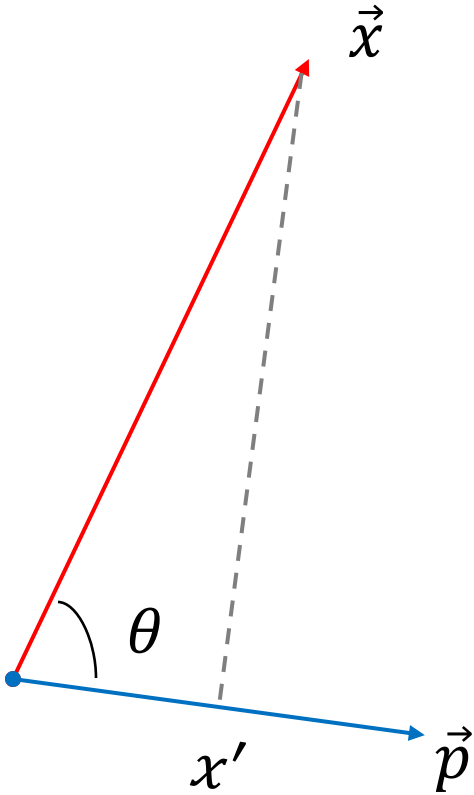
$$= E[A(x - \mu_x)(x - \mu_x)^t A^t]$$

$$= AE[(x - \mu_x)(x - \mu_x)^t]A^t$$

$$= A \cdot \text{COV}(X)A^t = I$$

$$A = \Lambda^{-1/2} E^t \quad \blacksquare \text{ [rotation \& scaling]}$$

****projection**** (a vector to a scalar/ a vector)




- \vec{x} projection to $\vec{p} = \vec{p}^t \cdot \vec{x}$ (to a scalar)
 $= \frac{\|\vec{p}\| \cdot \|\vec{x}\| \cos \theta}{\|\vec{p}\|^2} \vec{p}$

[1] Principal Component Analysis (Data Compression)

PCA is to compute **data approximation** \widetilde{x}_n that minimize

$$J = \frac{1}{N} \sum_{n=1}^N ||x_n - \widetilde{x}_n||^2$$

$$\widetilde{X}_n = \bar{x} + U_M U_M^t (x_n - \bar{x})$$


shift?

projection & make variance zero
for the small eigenvalue direction



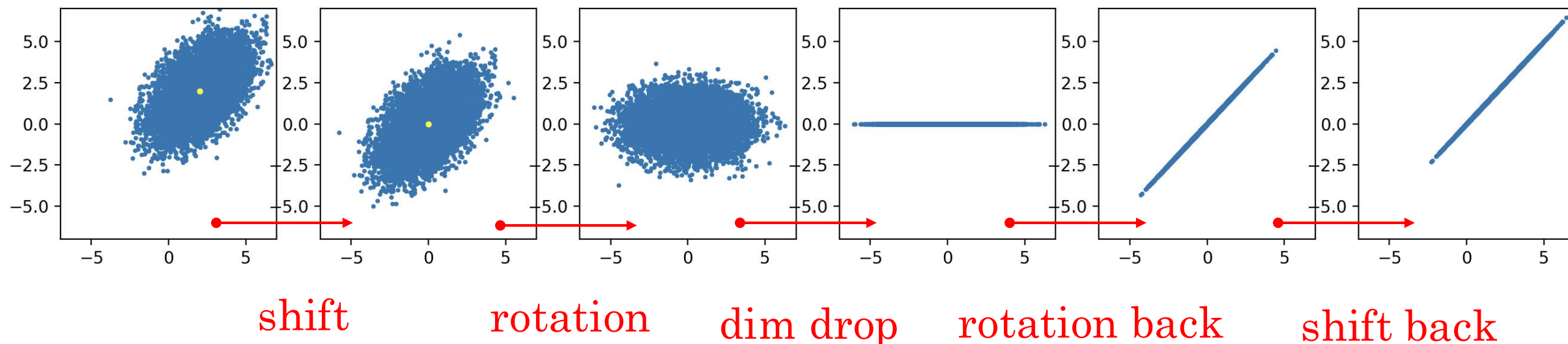
Q: what if $M = N$?

linear combination and shift back

[2] Principal Component Analysis (Data Compression)

$$\widetilde{X}_n = \bar{x} + U_M U_M^t (x_n - \bar{x})$$

$$\Sigma^* = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 1 & -1 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \cdot \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 1 & -1 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \quad \mu = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$$



[PCA process: still in 2d but 1d subspace]

[3] Principal Component Analysis (Data Compression)

[Different PCA Approximation for $M = 1$, $M = 10$, $M = 50$, $M = 250$]

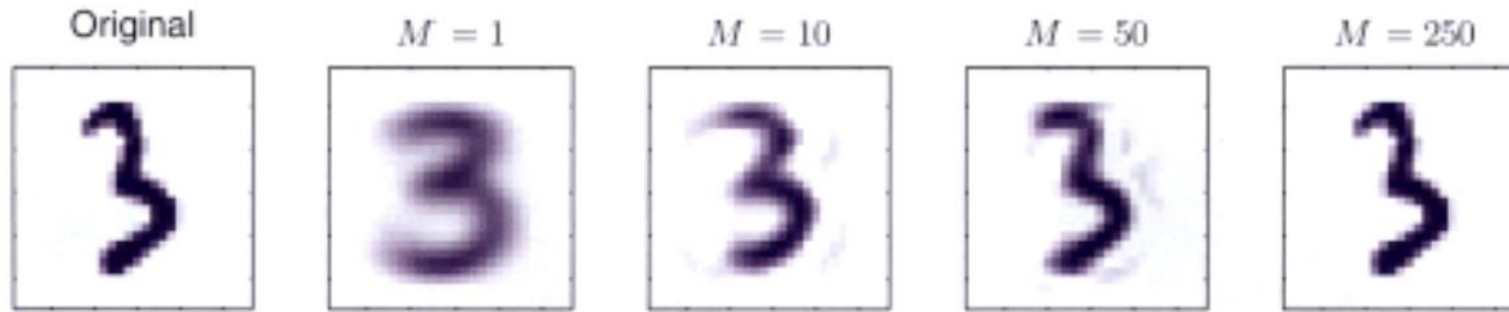


Figure 12.5 An original example from the off-line digits data set together with its PCA reconstructions obtained by retaining M principal components for various values of M . As M increases the reconstruction becomes more accurate and would become perfect when $M = D = 28 \times 28 = 784$.

From Bishop Chap. 12

$$\widetilde{X}_n = \bar{x} + U_M U_M^t (x_n - \bar{x})$$

[4] Principal Component Analysis (Data Compression)

[Visualization of Eigenvectors]

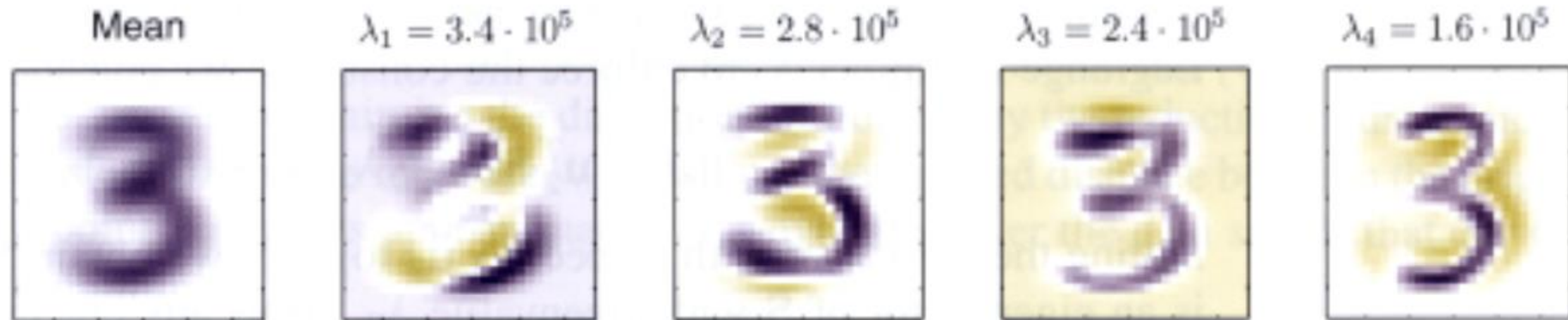


Figure 12.3 The mean vector \bar{x} along with the first four PCA eigenvectors u_1, \dots, u_4 for the off-line digits data set, together with the corresponding eigenvalues.

$$\widetilde{X}_n = \bar{x} + U_M U_M^t (x_n - \bar{x})$$

****Principal Component Analysis (eigenface in assignment#2)**



M: 2

1



M: 10

2



M: 100

3



M: 1000

4



M: 4000

5



6



7



8



9



10



[5] Principal Component Analysis (Data Visualization in 2D or 3D)

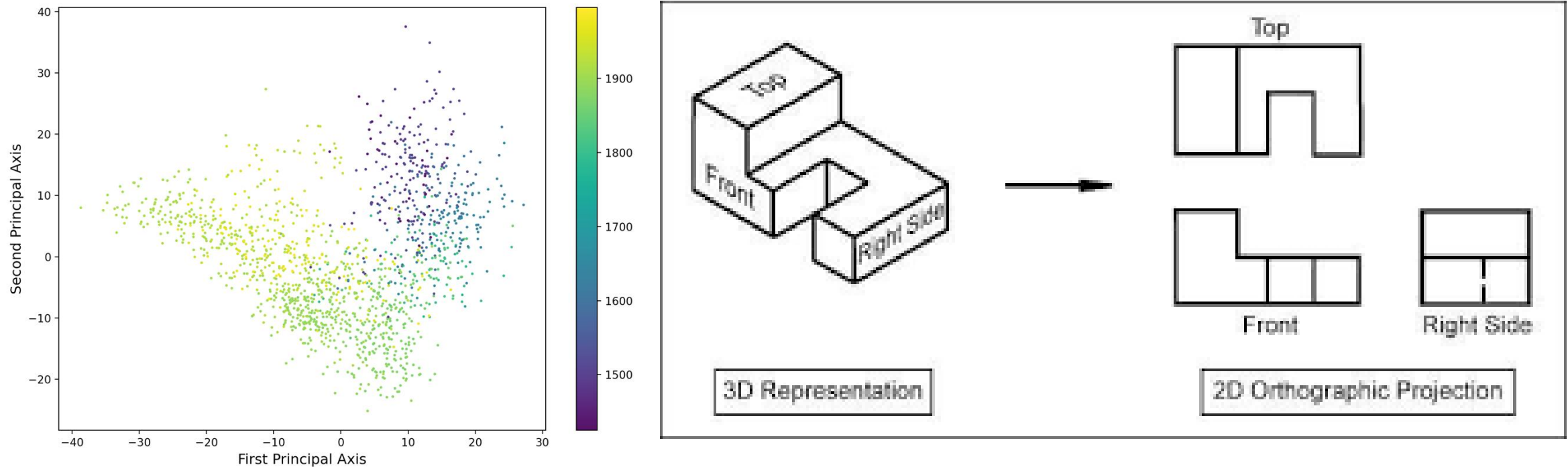
- “two ways to use PCA”
 - approximation
 - dimensionality reduction

$$\widetilde{X}_n = \bar{x} + U_M U_M^t (x_n - \bar{x}) \quad \text{stop in projection!}$$

$\tilde{X}_n = U_M^t (x_n - \bar{x})$ the high dimensional data points (for example, 2048-d)
can be represented by 2d/3d data.

[6] Principal Component Analysis (Data Visualization Example)

[visualization (1) (the projection of high dimensional data to 3D or 2D)]



The last hidden layer embedding (2048D) of a Deep-CNN Style Classifier is projected to the top principal axes (the eigenvectors corresponding to the first and second largest eigenvalues). The samples are color-coded by year of made.

[7] Principal Component Analysis (Data Visualization Example)

- Visualization (2) (projection of high dimensional data to 3D or 2D)

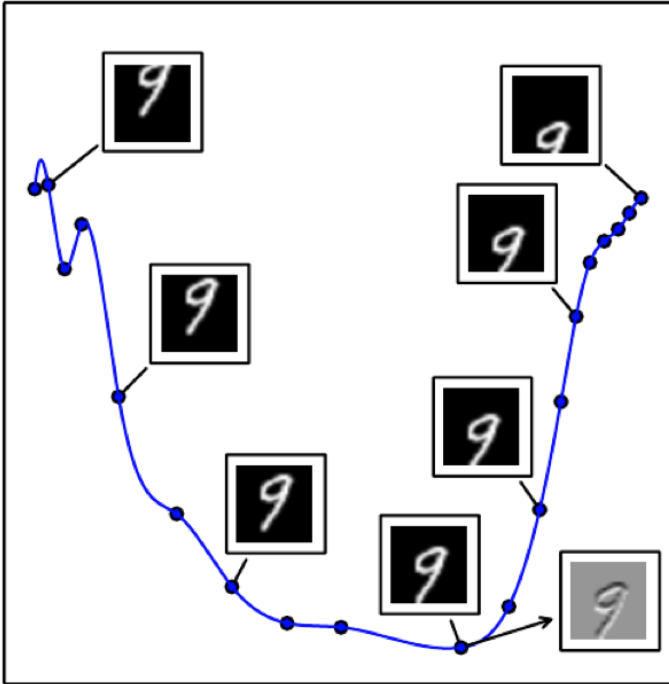


Figure 14. 6 from Deep Learning by Ian Goodfellow

One dimensional manifold that traces out a curved path for vertical shift of digit “9”. The manifold in the high dimensional space is projected into 2D.

- Singular Vector Decomposition of a Rectangular Matrix

[1] Singular Vector Decomposition of a **Rectangular** Matrix (A whose $n > m$)

$$A(n \times m) = \begin{bmatrix} | & & | \\ u_1 & u_2 & \dots u_n \\ | & & | \end{bmatrix} \cdot \begin{bmatrix} \sqrt{\lambda_1} & 0 & \dots & 0 \dots \\ 0 & \sqrt{\lambda_2} & \dots & 0 \dots 0 \\ \vdots & & & \\ 0 & \dots & \dots & \sqrt{\lambda_m} \\ \vdots & & & \\ 0 & \dots & \dots & 0 \\ 0 & \dots & \dots & 0 \end{bmatrix} \cdot \begin{bmatrix} v_1^t \\ v_2^t \\ \dots \\ v_m^t \end{bmatrix}$$

- u_i : eigenvectors of $AA^t = E\Lambda E^t$ ($n \times n$)
- v_i : eigenvectors of $A^t A = V\Lambda V^t$ ($m \times m$)
- λ_i : eigenvalues of both AA^t and $A^t A$

[2] Singular Vector Decomposition of a Rectangular Matrix (A^t)

$$A^t(m \times n) = \begin{bmatrix} | & & \\ v_1 & v_2 & \dots v_m \\ | & & \end{bmatrix} \cdot \begin{bmatrix} \sqrt{\lambda_1} & 0 & \dots & 0 & \dots & 0 & 0 \\ 0 & \sqrt{\lambda_2} & \dots & 0 & \dots & 0 & 0 \\ \vdots & & & & & & \\ 0 & \dots & \dots & \sqrt{\lambda_m} & \dots & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} u_1^t \\ u_2^t \\ \dots \\ u_n^t \end{bmatrix}$$

- u_i : eigenvectors of AA^t
- v_i : eigenvectors of A^tA
- λ_i : eigenvalues of both AA^t and A^tA

[3] Singular Vector Decomposition of a Rectangular Matrix (AA^t and A^tA)

when A is a $(n \times m, n > m)$ matrix, both AA^t and A^tA are symmetric.

$$AA^t = \begin{bmatrix} | & & \\ u_1 & & \\ | & & \\ u_2 & & \\ | & & \\ \vdots & & \\ | & & \\ u_n & & \\ | & & \end{bmatrix} \cdot \begin{bmatrix} \lambda_1 & 0 & \dots & 0 & \dots & 0 & 0 \\ 0 & \lambda_2 & \dots & 0 & \dots & 0 & 0 \\ \vdots & 0 & \dots & \lambda_m & \dots & 0 & 0 \\ 0 & \dots & 0 & \dots & \dots & 0 & 0 \\ 0 & \dots & 0 & \dots & \dots & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} u_1^t \\ u_2^t \\ \vdots \\ u_n^t \end{bmatrix}$$

$[n \times n]$

filling up $(n-m)$ zeros!

$$A^tA = \begin{bmatrix} | & & \\ v_1 & & \\ | & & \\ v_2 & & \\ | & & \\ \vdots & & \\ | & & \\ v_m & & \\ | & & \end{bmatrix} \cdot \begin{bmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & & & \\ 0 & \dots & \dots & \lambda_m \end{bmatrix} \cdot \begin{bmatrix} v_1^t \\ v_2^t \\ \vdots \\ v_m^t \end{bmatrix}$$

$[m \times m]$

[4] Singular Vector Decomposition of a Rectangular Matrix (proof)

Proof]

$$A^t A = V \Lambda V^t$$

$$A^t A V = V \Lambda$$

$$A A^t \textcircled{A V} = \textcircled{A V} \Lambda$$

- $[A v \text{ is eigenvector of } A A^t]$

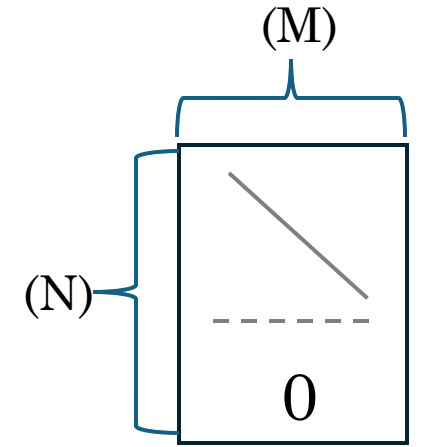
$$V^t A^t A V = \Lambda$$

$$(A V)^t (A V) = \Lambda \quad \text{▪ } [\text{length of } \|A v\|^2 = \lambda]$$

- $[U \text{ is orthonormal and eigenvector matrix}]$

- $[\Lambda' (n \times m)]$

$$A V = U \textcircled{\Lambda'^{1/2}}$$
$$A = U \Lambda'^{1/2} V^t$$



- Pseudo-Inverse (using SVD)

Generalization of the notion of inverse matrix.

[0] When do we need Pseudo-Inverse?

$$\text{ex] } \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 5 \end{bmatrix}$$



$$\begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 5 \end{bmatrix}$$



$$\begin{bmatrix} 5 & 10 \\ 10 & 20 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 11 \\ 22 \end{bmatrix}$$

- no solution example
- projection to the column space
- finding an **approximated** solution
- now we could find approximated solution
- rank:1 but two columns so redundant, ∞ sols
- no invertible (but we could find one of the ∞ solutions)

[1] Singular Vector Decomposition of a Rectangular Matrix (Pseudo-Inverse)

$$D = \underbrace{\begin{bmatrix} | & & \\ u_1 & u_2 & \dots u_n \\ | & & \end{bmatrix}}_U \cdot \begin{bmatrix} \sqrt{\lambda_1} & 0 & \dots & 0 \\ 0 & \sqrt{\lambda_2} & \dots & 0 \\ \vdots & & & \\ 0 & & \sqrt{\lambda_{m-1}} & 0 \\ 0 & \dots & \dots & 0 \\ 0 & \dots & \dots & 0 \\ 0 & \dots & \dots & 0 \end{bmatrix} \cdot \underbrace{\begin{bmatrix} v_1^t \\ v_2^t \\ \dots \\ v_m^t \end{bmatrix}}_{V^t}$$

$$D^\dagger = \underbrace{\begin{bmatrix} | & & \\ v_1 & v_2 & \dots v_m \\ | & & \end{bmatrix}}_V \cdot \begin{bmatrix} \frac{1}{\sqrt{\lambda_1}} & 0 & \dots & 0 & \dots & 0 \\ 0 & \frac{1}{\sqrt{\lambda_2}} & \dots & 0 & \dots & 0 \\ \vdots & & & & & \\ 0 & & \frac{1}{\sqrt{\lambda_{m-1}}} & 0 & \dots & 0 \\ 0 & \dots & \dots & 0 & \dots & 0 \end{bmatrix} \cdot \underbrace{\begin{bmatrix} u_1^t \\ u_2^t \\ \dots \\ u_n^t \end{bmatrix}}_{U^t}$$

pseudo-inverse

[2] Singular Vector Decomposition of a Rectangular Matrix (Pseudo-Inverse)

ex) compute the pseudo-inverse of the matrix below. [rectangular matrix]

$$\Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 2 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

[3] Singular Vector Decomposition of a Rectangular Matrix (Pseudo-Inverse)

ex) compute the pseudo-inverse of the matrix below. [square matrix]

$$\Sigma = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 1 & -1 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \cdot \begin{bmatrix} 3 & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 1 & -1 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$$

$$\Sigma = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 1 & -1 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 1 & -1 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \quad \text{for square and full rank matrix,} \\ [\Sigma^\dagger = \Sigma^{-1}]$$

[4] Singular Vector Decomposition of a Rectangular Matrix (Linear System: $Dx = b$)

no solution of a linear system ($Dx = b$) exist
if the vector b is on the column space of D .

ex] in linear regression, we aim to solve $[a, b, c]$

	X_1	X_2	X_3
#1	1.4	2.7	3.2
#2	2.2	3.5	3.3
#3	3.1	5.2	1.2
#4	1.7	1.0	0.2
#5	4.6	1.1	0.9
#6	2.2	4.3	2.7
#7	1.2	2.3	7.6
#8	0.3	0.2	3.2
#9	2.5	0.5	0.9
#10	1.8	1.9	1.1
...			

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} =$$

	Y
#1	1
#2	1.3
#3	0.8
#4	0.3
#5	1
#6	4
#7	3.6
#8	2.9
#9	2.5
#10	0
...	

- the vector for Y is likely be outside of the three-dimensional column space in \mathbb{R}^M ($M: \#data$)

[5] Singular Vector Decomposition of a Rectangular Matrix (Linear System: $Dx = b$)

$$Dx = b \quad \blacksquare \text{ no solution}$$

$$D^t D x = D^t b \quad \begin{array}{l} \blacksquare \text{ projection to column space (approximated)} \\ \blacksquare \text{ exist solution (one / infinite many solution)} \end{array}$$

$$\begin{array}{l} (D^t D)^\dagger (D^t D) x = (D^t D)^\dagger D^t b \\ x = (D^t D)^\dagger D^t b \end{array} \quad \blacksquare \begin{array}{l} \text{by using pseudo-inverse,} \\ \text{find a solution in the subspace} \end{array}$$

We will study solving linear system using pseudo-inverse again in Linear Regression (Sept. 15)