Machine Learning Principles

Class8: Sept 28

Linear Classification II: Logistic Regression

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Today's Lecture

- 1. Modeling of Logistic Regression:
 - $P[C_k|x]$: sigmoid logistic function embedding "a linear regression function"
 - decision rule/ boundary
 - orientation and steepness of a sigmoid function

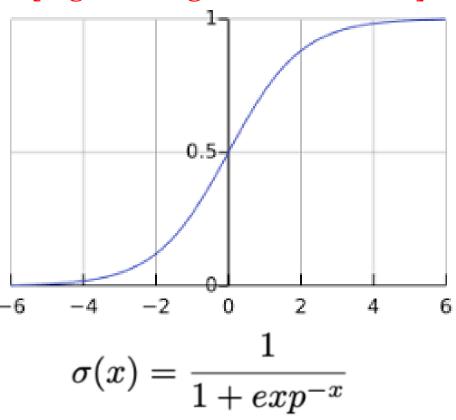
2. Training:

- defining objective Function (MLE) and its optimization
- overfitting and regularization

3. Multinomial (Multiclass) Logistic Regression

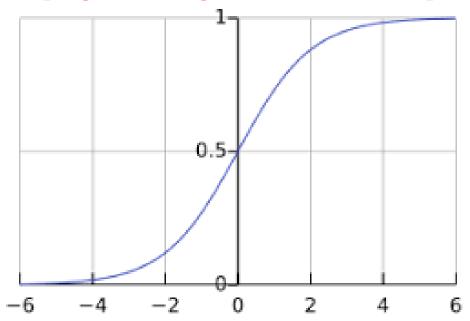
[1] Logistic Regression (sigmoid function)

[logistic sigmoid function]



[2] Logistic Regression (sigmoid function + linear function)

[logistic sigmoid function]



$$P[C_1|\vec{x}] = \frac{1}{1 + \exp(-\vec{w}^t \vec{x} - b)}$$
$$P[C_0|\vec{x}] = \frac{\exp(-\vec{w}^t \vec{x} - b)}{1 + \exp(-\vec{w}^t \vec{x} - b)}$$

$$\sigma(x) = \frac{1}{1 + exp^{-x}}$$

[decision rule]

$$w^{t}x + b \ge 0$$
 then $P[C_{1}|x] \ge P[C_{0}|x] \to x \in C_{1}$
 $w^{t}x + b < 0$ then $P[C_{1}|x] < P[C_{0}|x] \to x \in C_{0}$

[3] Logistic Regression (example)

ex] suppose we learned logistic regression on the 2-D data space like below. what are the decision rule/boundary/ region?

$$P[C_1|x] = \sigma(\begin{bmatrix} 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}) = \frac{1}{1 + \exp{-\begin{bmatrix} 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}}}$$

[4] Logistic Regression (example)

ex] suppose we learned logistic regression on the 2-D data space like below. what are the decision rule/boundary/ region?

$$P[C_1|x] = \sigma(\begin{bmatrix} 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}) = \frac{1}{1 + \exp{-\begin{bmatrix} 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}}}$$

- Decision Boundary (linear regression function/ hyperplane)
- The direction of the normal vector of the hyperplane
- The magnitude of the normal vector of the hyperplane

[5] Logistic Regression (normal vector's direction and magnitude)

Q: $w^t x + b = 0$ defines a decision boundary. do they define the same boundaries?

(1)
$$\sigma(\begin{bmatrix} 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}) = \frac{1}{1 + \exp{-\begin{bmatrix} 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}}}$$

(2)
$$\sigma(\begin{bmatrix} 2 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}) = \frac{1}{1 + \exp{-\begin{bmatrix} 2 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}}}$$

(3)
$$\sigma(\begin{bmatrix} 3 & 6 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}) = \frac{1}{1 + \exp{-\begin{bmatrix} 3 & 6 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}}}$$

$$||w||(w'^t x + b') = 0$$

where $||\begin{bmatrix} w' \\ b' \end{bmatrix}|| = 1$

There could be infinitely many solutions defining the same decision boundary for different ||w||, but they differ in the steepness of their logistic sigmoid functions. The larger ||w|| gives the steeper sigmoid.

[6] Logistic Regression (properties)

■ The direction & magnitude of the normal vector of the hyperplane determines orientation & steepness of the sigmoid functions.

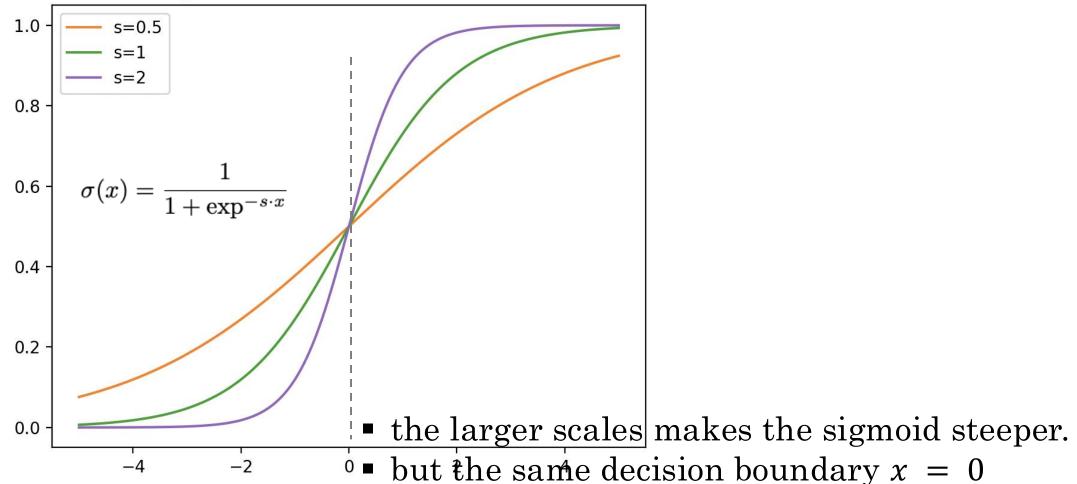
$$\checkmark \overrightarrow{w}x + b = 0$$

 $\checkmark \vec{w}$: normal vector (direction to be the class 1)

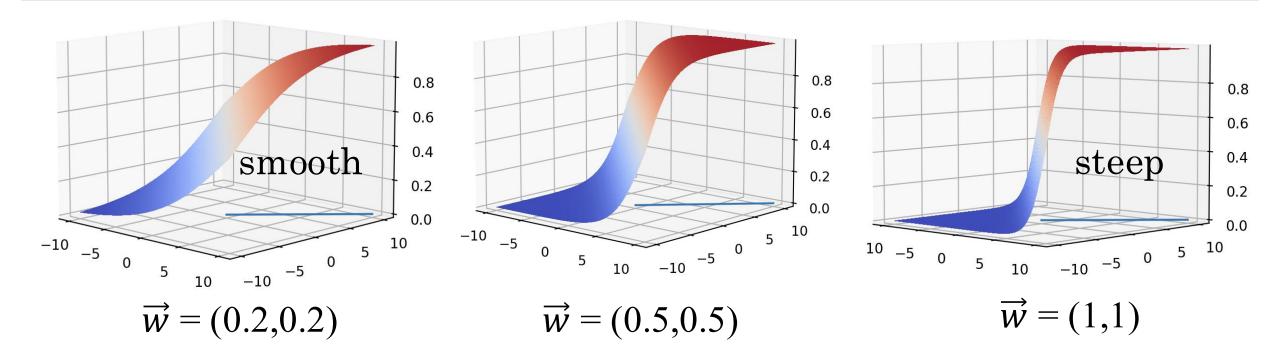
$$P[C_1|\vec{x}] = \frac{1}{1 + \exp(-\vec{w}^t \vec{x} - b)}$$
$$P[C_0|\vec{x}] = \frac{\exp(-\vec{w}^t \vec{x} - b)}{1 + \exp(-\vec{w}^t \vec{x} - b)}$$

**example 1D: sigmoid functions with different scales





**example 2D: same decision region but different sigmoid functions



• Their decision boundaries are the same as $X_1 + X_2 = 0$ but their steepness varies according to the magnitude of ||w|| Training Logistic Regression

how do we learn the parameters \overrightarrow{w} and b?

[1] Training (Maximum Likelihood Estimator: MLE)

$$P(w|D) = \frac{p(w,D)}{P(D)} = \frac{p(D|w)p(w)}{p(D)}$$

w *= argmax P(D|w): Maximum Lliklihood Estimation (MLE)

[2] Training (MLE)

- suppose we have a data set $\{\overrightarrow{x_n}, t_n\}$ where $t_n \in \{0,1\}$ & $n = \{1,2,...,N\}$
- like 1,0, 0,...,1,0,1...
- $P(t_1, t_1, t_3, \dots t_N | \overrightarrow{w}, b, \overrightarrow{x_n})$
- $= \prod_{n=1}^{N} P(t_n | \overrightarrow{w}, b, \overrightarrow{x_n}) = P(t_n = 1 | \overrightarrow{w}, b, \overrightarrow{x_n})^{t_n} P(t_n = 0 | \overrightarrow{w}, b, \overrightarrow{x_n})^{1-t_n}$

Q: how we modeled $P(t_n = 1 | \vec{w}, b)$ in logistic regression?

[3] Training (cross entropy loss)

$$P(t_1, ..., t_N | w) = \prod_{n=1}^{N} \sigma(w^t x_n)^{t_n} (1 - \sigma(w^t x_n))^{1-t_n}$$

$$J(\vec{w}) = -\ln P(t_1, ..., t_N | w) = \sum_{n=1}^{N} -t_n \ln \sigma(w^t x_n) - (1 - t_n) \ln (1 - \sigma(w^t x_n))$$

$$w* = \underset{w}{\operatorname{arg \, min}} J(\vec{w})$$
[cross entropy loss]

** Entropy / Cross Entropy / KL Divergence (Kullback-Leibler)

$$H(X) = E[\log \frac{1}{P(X)}] = \sum_{x} p(x) \log \frac{1}{p(x)}$$
 [Entropy]:

the smallest number bits to encode R.V X

$$D(p||q) = \sum_{x} p(x) \log \frac{p(x)}{q(x)}$$

$$= \sum_{x} p(x) \log \frac{1}{q(x)} - \sum_{x} p(x) \log \frac{1}{p(x)}$$

• [KL divergence]:

how many bits more needed when using q(x) instead of the original density p(x)?

this measures the difference/distance between the two densities: p(x) and q(x) ** Entropy / Cross Entropy / KL Divergence (Kullback-Leibler)

KL divergence is always non-negative!

$$D(p||q) = \sum_{x} p(x) \log \frac{p(x)}{q(x)} \ge 0$$

$$-D(p||q) = \sum_{x} p(x) \log \frac{q(x)}{p(x)}$$
 [by Jensen's Inequality]
$$\leq \log \sum_{x} \frac{p(x)q(x)}{p(x)} = \log 1 = 0$$

** Entropy / Cross Entropy / KL Divergence (Kullback-Leibler)

$$H(p,q) = \sum_{x} p(x) \log \frac{1}{q(x)}$$

$$= \sum_{x} p(x) \log \frac{p(x)}{q(x)p(x)} = \sum_{x} p(x) \log \frac{p(x)}{q(x)} + \sum_{x} p(x) \log \frac{1}{p(x)}$$

$$= D(p||q) + H(X)$$

[Cross Entropy]

minimizing cross entropy directly minimizes KL divergence.

[4] Training (cross entropy)

$$P(t_1,...,t_N|w) = \prod_{n=1}^N \sigma(w^t x_n)^{t_n} (1 - \sigma(w^t x_n))^{1-t_n}$$

$$J(\vec{w}) = -\ln P(t_1,...,t_N|w) = \sum_{n=1}^N -t_n \ln \sigma(w^t x_n) - (1-t_n) \ln (1-\sigma(w^t x_n))$$

$$w* = \operatorname*{arg\,min}_w J(\vec{w})$$
[cross entropy loss]

• as taking the ground truth (1/0) as p(t) minimizing the cross entropy minimizes the distance between p(t) and $q(t) = \sigma(w^t x)$

[5] Training (computing Gradient)

$$\nabla_{w} J(\vec{w}) = \sum_{n=1}^{N} -t_{n} \frac{\sigma(w^{t} x_{n})(1 - \sigma(w^{t} x_{n}))}{\sigma(w^{t} x_{n})} x_{n} - (1 - t_{n}) \frac{-\sigma(w^{t} x_{n})(1 - \sigma(w^{t} x_{n}))}{1 - \sigma(w^{t} x_{n})} x_{n}$$

$$= \sum_{n=1}^{N} \{-t_{n} (1 - \sigma(w^{t} x_{n})) - (1 - t_{n})(-\sigma(w^{t} x_{n}))\} x_{n}$$

$$= \sum_{n=1}^{N} (\sigma(w^{t} x_{n}) - t_{n}) x_{n}$$

**useful properties of logistic sigmoid function

symmetric & complement probability

$$\sigma(-x) = 1 - \sigma(x)$$
$$\sigma(x) = 1 - \sigma(-x)$$

$$\frac{d}{dx}\sigma(x) = \frac{\exp^{-x}}{(1 + \exp^{-x})^2}$$

$$= \frac{1}{(1 + \exp^{-x})} \cdot \frac{\exp^{-x}}{(1 + \exp^{-x})}$$

$$= \frac{1}{(1 + \exp^{-x})} \cdot \frac{1 + \exp^{-x} - 1}{(1 + \exp^{-x})}$$

$$= \sigma(x) \cdot (1 - \sigma(x))$$

[6] Training (computing Hessian)

$$\nabla_w^2 J(\vec{w}) = \sum_{n=1}^N \sigma(w^t x_n) \cdot (1 - \sigma(w^t x_n)) x_n^t x_n \succeq 0$$
non-negative definite

- two possible cases of $\nabla^2 J(w) = 0$
- no minimum solution $\overrightarrow{w*}$ when data is linearly separable.
- multiple minimum points: covariance matrix X^tX is singular, collinearity exist.

[7] Training (computing Hessian)

$$\nabla_w^2 J(\vec{w}) = \sum_{n=1}^N \sigma(w^t x_n) \cdot (1 - \sigma(w^t x_n)) x_n^t x_n \succeq 0$$
 non-negative definite

- unique solution: $\nabla^2 J(w) > 0$
- when data is not linearly separable and X^tX is full-rank matrix. then $\nabla^2 J(w) > 0 \rightarrow \nabla J(w*) = 0$ becomes a sufficient condition to be an optimal solution.

[8] Training (summary)

$\nabla^2 J(w) = 0$		$\nabla^2 J(w) > 0$
data is linearly separable	collinearity X^tX is singular	data is not linearly separable $\& X^t X$ is a full rank matrix
no minimum exist. $s.t \nabla J(w *) = 0$	multiple w is possible $s.t \nabla J(w *) = 0$	unique solution exist $s.t \nabla J(w *) = 0$
<i>w</i> goes to ∞	multiple, global minimum	unique, global minimum

[9] Training (no closed solution $\nabla J(\overrightarrow{w}) = 0$)

Let's try finding the optimal point $\overrightarrow{w} * \text{ by } \nabla J(\overrightarrow{w}) = 0!$

$$\nabla_w J(\vec{w}) = \sum_{n=1}^N -t_n \frac{\sigma(w^t x_n)(1 - \sigma(w^t x_n))}{\sigma(w^t x_n)} x_n - (1 - t_n) \frac{-\sigma(w^t x_n)(1 - \sigma(w^t x_n))}{1 - \sigma(w^t x_n)} x_n$$

$$= \sum_{n=1}^N \{-t_n (1 - \sigma(w^t x_n)) - (1 - t_n)(-\sigma(w^t x_n))\} x_n$$

$$= \sum_{n=1}^{N} (\sigma(w^t x_n) - t_n) x_n = 0$$

no closed solution for $\nabla_w J(w) = 0$

• Steepest Gradient Descent Algorithm (an iterative optimization method to minimize $J(\vec{w})$)

[1] Steepest Gradient Descent Algorithm

- it finds iteratively a local/global minimum of $J(\vec{w})$
- it computes the steepest descent direction at the current and take a step to that direction as amount of predefined and compute the next direction again

$$w_{i+1} = w_i - \eta \nabla J(w)$$
 (gradient gives the steepest & increasing direction)

[2] Steepest Gradient Descent Algorithm (direction by gradient)

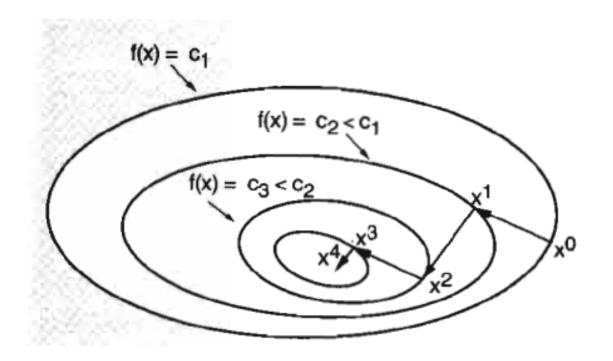


Figure 1.2.1. Iterative descent for minimizing a function f. Each vector in the generated sequence has a lower cost than its predecessor.

[Nonlinear Programming, Dimitri P. Bertsekas]

gradient direction is orthogonal to contours.

Training Logistic Regression using Gradient Steepest Descent

[1] Training (gradient/steepest decent algorithm)

$$w_{i+1} = w_i - \eta \nabla J(w)$$
 (gradient gives the steepest ascent direction)

$$\nabla_w J(\vec{w}) = \sum_{n=1}^N -t_n \frac{\sigma(w^t x_n)(1 - \sigma(w^t x_n))}{\sigma(w^t x_n)} x_n - (1 - t_n) \frac{-\sigma(w^t x_n)(1 - \sigma(w^t x_n))}{1 - \sigma(w^t x_n)} x_n$$

$$= \sum_{n=1}^N \{-t_n (1 - \sigma(w^t x_n)) - (1 - t_n)(-\sigma(w^t x_n))\} x_n$$

$$= \sum_{n=1}^{N} (\sigma(w^t x_n) - t_n) x_n$$

[5] Training (convergence?)

$\nabla^2 J(w) = 0$		$\nabla^2 J(w) > 0$
data is linearly separable	collinearity X^tX is singular	data is not linearly separable $\& X^t X$ is a full rank matrix
no minimum exist. $s.t \nabla J(w *) = 0$	multiple w is possible $s.t \nabla J(w *) = 0$	unique solution exist $s.t \nabla J(w *) = 0$
$ w $ goes to ∞	global minimum	global minimum
does gradient descent algorithm converge? (if tolerance set, improvement $<\epsilon$ & if we set the proper step size.)		

Overfitting

MLE is sensitive to data (# data points & data structure)

[1] Overfitting Scenario (limited data size)

Like regression model, logistic regression classifier overfits to train data when too many features relative to # training samples.

Q: even worse, when the training dataset is linearly separable, the overfitted model tends to have excessively high confidence in its predictions.

[2] Overfitting Scenario (steep logistic sigmoid)

the steep sigmoid function would be appropriate,

- if we have a well-designed feature map making data linearly separable.
- if we we have a sufficient number of data points.
- however, hard to achieve the condition in practice.

Regularization (MAP rule)

 $w *= argmax p(w|D) \propto p(D|w)p(w)$

[1] Regularization (ridge logistic regression)

$$p(w)$$
: $\overrightarrow{w} \sim N(0, \sigma^2 I)$

$$P(t_{1},...t_{N}|w)P(w) = \prod_{n=1}^{N} \sigma(w^{t}x_{n})^{t_{n}} (1 - \sigma(w^{t}x_{n}))^{1-t_{n}} \cdot \frac{1}{\sqrt{2\pi\sigma^{2M}}} \cdot \exp^{-\frac{1}{2}\sigma^{2}||W||^{2}}$$

$$-\ln P(t_{1},...t_{N}|w)P(w) = \sum_{n=1}^{N} -t_{n} \ln \sigma(w^{t}x_{n}) - (1 - t_{n}) \ln (1 - \sigma(w^{t}x_{n})) - \ln \frac{1}{\sqrt{2\pi\sigma^{2M}}} + \frac{1}{2\sigma^{2}}||W||^{2}$$

$$J(w) = \sum_{n=1}^{N} -t_{n} \ln \sigma(w^{t}x_{n}) - (1 - t_{n}) \ln (1 - \sigma(w^{t}x_{n})) + \frac{1}{2\sigma^{2}}||W||^{2}$$

$$J(w) = \sum_{n=1}^{N} -t_{n} \ln \sigma(w^{t}x_{n}) - (1 - t_{n}) \ln (1 - \sigma(w^{t}x_{n})) + \frac{1}{2\sigma^{2}}||W||^{2}$$
regularization parameters / set using cross validation.

[2] Regularization (gradient)

• $\nabla J(\overrightarrow{W})$

$$\nabla_{w} J(\vec{w}) = \sum_{n=1}^{N} -t_{n} \frac{\sigma(w^{t} x_{n})(1 - \sigma(w^{t} x_{n}))}{\sigma(w^{t} x_{n})} x_{n} - (1 - t_{n}) \frac{-\sigma(w^{t} x_{n})(1 - \sigma(w^{t} x_{n}))}{1 - \sigma(w^{t} x_{n})} x_{n} + 2\lambda \vec{w}$$

$$= \sum_{n=1}^{N} \{-t_{n} (1 - \sigma(w^{t} x_{n})) - (1 - t_{n})(-\sigma(w^{t} x_{n}))\} x_{n} + 2\lambda \vec{w}$$

$$= \sum_{n=1}^{N} (\sigma(w^{t} x_{n}) - t_{n}) x_{n} + 2\lambda \vec{w}$$

gradient descent

$$w_{i+1} = w_i - \eta \nabla J(w)$$

• Multinomial Logistic Regression (Learning K posterior $P[C_k|x]$)

[1] Multinomial Logistic Regression (posterior using linear functions)

$$P[C_0|x] = \frac{P[x|C_0]P[C_0]}{P[x|C_0]P[C_0] + P[x|C_1]P[C_1] + P[x|C_2]P[C_2]}$$

$$\exp[\ln P[x|C_0]P[C_0]]$$

$$\exp[\ln P[x|C_0]P[C_0]]$$

$$\exp[\ln P[x|C_0]P[C_0]]$$

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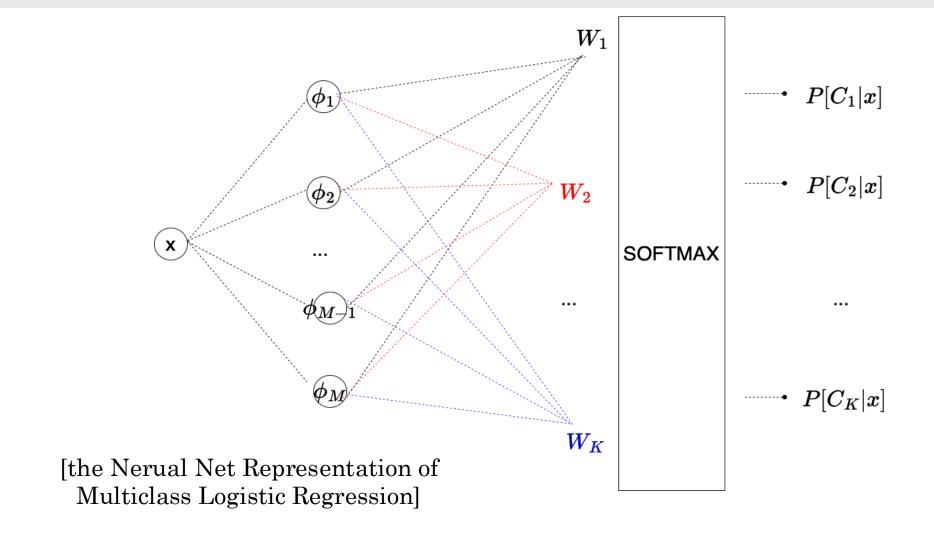
when Gaussain assumed, these log elements are quadratic. But each exponent becomes a linear function: $w^t x + b$; the second order terms are cancelled out when covariances are equal.

[2] Multinomial Logistic Regression (softmax function)

$$P[C_k|x] = \frac{\exp w_k^t \phi(x)}{\sum_{k=1}^K \exp w_k^t \phi(x)}$$

■ using normalized exponential (softmax) and *K* linear functions, the *K* posteriors are represented.

[3] Multinomial Logistic Regression (softmax function)



[4] Multinomial Logistic Regression (softmax example)

ex] compute $P[C_k|x]$ using softmax

- x = 1 (one observation example, this can be any real number)
- $\phi(x): \{1, x, x^2\}$

$$W = \begin{bmatrix} 1 & 2 & 3 & 4 & 5 \\ 1 & 2 & 3 & 4 & 5 \\ 1 & 2 & 3 & 4 & 5 \end{bmatrix}$$

[5] Multinomial Logistic Regression

Multiclass logistic regression learns *K* discriminant linear functions the functions are translated into posterior by softmax (deep neural net classifier has the same structure in the last layer) Q: how can we learn the discriminant linear functions?

[6] Multinomial Logistic Regression (training)

$$P[C_k|x] = \frac{\exp w_k^t \phi(x)}{\sum_{k=1}^K \exp w_k^t \phi(x)}$$

- then how to learn the parameters \vec{w} ?
- MLE! we plug in the posteriors in *k*-categorical density and estimate the parameter using MLE as we did in binary logistic regression.

[7] Multinomial Logistic Regression (cross entropy based on MLE)

likelihood

$$P[T|W,x] = \prod_{n=1}^{N} \prod_{k=1}^{K} P[C_k|W,x_n]^{t_{nk}}$$

negative-log (cross entropy)

$$J(W) = -\ln P[T|W, x] = -\sum_{n=1}^{N} \sum_{k=1}^{K} t_{nk} \ln P[C_k|W, x_n]$$

[8] Multinomial Logistic Regression (softmax gradient)

• $\nabla P[C_j|x] \ r.t \ w_i \ (i=j)$

$$P[C_{j}|x] = \frac{\exp w_{j}^{t}\phi(x)}{\sum_{k=1}^{K} \exp w_{k}^{t}\phi(x)}$$

$$\nabla_{W_{j}}P[C_{j}|x] = \{\frac{(\sum_{k=1}^{K} \exp w_{k}^{t}\phi(x))(\exp w_{j}^{t}\phi(x)) - (\exp w_{j}^{t}\phi(x))^{2}}{(\sum_{k=1}^{K} \exp w_{k}^{t}\phi(x))^{2}}\}\phi(x)$$

$$\nabla_{W_{j}}P[C_{j}|x] = \{\frac{\exp w_{j}^{t}\phi(x)}{\sum_{k=1}^{K} \exp w_{k}^{t}\phi(x)} \cdot (1 - \frac{\exp w_{j}^{t}\phi(x)}{\sum_{k=1}^{K} \exp w_{k}^{t}\phi(x)})\}\phi(x)$$

• $\nabla P[C_i|x] \ r.t \ w_i \ (i \neq j)$

$$P[C_{j}|x] = \frac{\exp w_{j}^{t}\phi(x)}{\sum_{k=1}^{K} \exp w_{k}^{t}\phi(x)}$$

$$\nabla_{W_{i}}P[C_{j}|x] = \{\frac{-(\exp w_{j}^{t}\phi(x))(\exp w_{i}^{t}\phi(x))}{(\sum_{k=1}^{K} \exp w_{k}^{t}\phi(x))^{2}}\}\phi(x)$$

$$\nabla_{W_{i}}P[C_{j}|x] = \{\frac{\exp w_{j}^{t}\phi(x)}{\sum_{k=1}^{K} \exp w_{k}^{t}\phi(x)} \cdot (-\frac{\exp w_{i}^{t}\phi(x)}{\sum_{k=1}^{K} \exp w_{k}^{t}\phi(x)})\}\phi(x)$$

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[9] Multinomial Logistic Regression (softmax gradient for gradient descent)

$$\nabla_{W_j} P[C_j | x] = P[C_j | x] \cdot (1 - P[C_j | x]) \phi(x) \qquad (i = j)$$

$$\nabla_{W_i} P[C_j | x] = P[C_j | x] \cdot (-P[C_i | x]) \phi(x) \qquad (i \neq j)$$

Q: can we compute $P[C_j|x]$? yes, during training, we can compute $P[C_j|x]$ using the current parameter W!

[10] Multinomial Logistic Regression (cross entropy gradient)

$$\begin{split} \nabla_{W_j} J(W_1, W_2, ...W_K) &= -\sum_{n=1}^N \sum_{k=1}^K t_{nk} \nabla_{W_j} \ln P[C_k | \phi(x)] \\ &= \sum_{n=1}^N t_{n1} P[C_j | \phi(x)] + ... + t_{nj} (P[C_j | \phi(x)] - 1) + ... + t_{nK} P[C_j | \phi(x)] \\ &= \sum_{n=1}^N \{ P[C_j | \phi(x)] (t_{n_1} + t_{n_2} + ...t_{nK}) - t_{n_j} \} \phi(x) \\ &= \sum_{n=1}^N \{ P[C_j | \phi(x)] - t_{n_j} \} \phi(x) \end{split}$$

[11] Multinomial Logistic Regression (gradient descent)

$$w_{i+1} = w_i - \eta
abla J(w)$$
 $abla J(W) = egin{bmatrix}
abla_{W_1} J(W) \\

abla_{W_2} J(W) \\

abla_{W_2} J(W) \\

abla_{W_K} J(W) \\

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