參考資料

* [多車軌道路徑規劃演算法設計](https://iter01.com/615138.html)  
  參考引入隨機數
* [多 A G V 路径规划方法研究](http://www.jsjkx.com/CN/article/openArticlePDF.jsp?id=16594)
* [A system control strategy of a conflict-free multi-AGV routing based on improved A∗ algorithm](https://ieeexplore.ieee.org/document/8211447)  
  參考轉向權重
* [Just-in-Time Routing and Scheduling for Multiple Automated Guided Vehicles](https://ieeexplore.ieee.org/document/8914493)  
  參考架構
* [AGV Path Planning based on Improved A-star Algorithm](https://ieeexplore.ieee.org/abstract/document/8983841)  
  參考加入不同的heuristic function
* [Improved A-star Algorithm with Least Turn for Robotic Rescue Operations](https://link.springer.com/chapter/10.1007/978-981-10-6430-2_48)  
  轉彎加入cost(現用方法，not optimal)
* [Path planning of automated guided vehicles based on improved A-Star algorithm](https://ieeexplore.ieee.org/document/7279630)  
  建立time-path模型
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* [Localization and navigation using QR code for mobile robot in indoor environment](https://www.researchgate.net/publication/304414914_Localization_and_navigation_using_QR_code_for_mobile_robot_in_indoor_environment)
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  參考利用在每個節點建立一個Queue的方式來避免AGV衝突
* [Collision-Free Route Planning for Multiple AGVs in an Automated Warehouse Based on Collision Classification](https://ieeexplore.ieee.org/document/8325291)  
  參考各論文提出的碰撞類型，完整的自動化倉儲架構
* [Research on the Collision-Free Path Planning of Multi-AGVs System Based on Improved A\* Algorithm](https://www.scirp.org/journal/paperinformation.aspx?paperid=72034)  
  參考加入考慮到traffic jam的heuristic function