

1 **Optimizing the Implementation PlanOrders of Watershed Best Management**
2 **Practices with Time-varying Effectiveness under Stepwise Investment**

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17 **Key Points:**

- 18 • Proposed a novel idea to optimize the implementation planorders of watershed best
19 management practices (BMPs) under stepwise investment
- 20 • Introduced the net present value to compare the net costs of BMP scenarios of BMP
21 scenarios and BMP's time-varying BMP effectiveness of BMP scenarios to assess
22 environmental effects
- 23 • The proposed BMP optimization approach was demonstrated in an agricultural watershed
24 case study for using four erosion control est management BMPs

27 **Abstract**

28 Optimizing the spatial configuration of diverse best management practices (BMPs) can provide
 29 valuable decision-making support for comprehensive watershed management. Most existing
 30 methods focus on selecting BMP types selection and location allocation allocating locations but
 31 neglect the BMPir implementation time or orders in a-management scenarios, which are often
 32 restricted by investment restricteds. This study proposes a new simulation-optimization
 33 framework for determining the implementation planorders of BMPs by using the net present value
 34 to calculate the economic costs of BMP scenarios, and the time-varying effectiveness of BMPs to
 35 evaluate the environmental effectiveness of multistage-BMP scenarios. The proposed framework
 36 was implemented based on a Spatially Explicit Integrated Modeling System and demonstrated in
 37 an agricultural watershed case study. The This case study optimized the implementation time of
 38 four erosion control BMPs in a specific spatial configuration scenario under a 5-year stepwise
 39 investment process. The results demonstrated that the proposed method could effectively provide
 40 more feasible BMP scenarios with a lower overall investment burden at the cost of with only a
 41 slight loss of environmental effectiveness. Gathering tTime-varying BMP effectiveness data
 42 should be gathered and incorporatedding them into watershed modeling and scenario optimization
 43 should be adopted extensively to better depict the environmental improvement effects of BMPs on
 44 improving the environment over time. The proposed framework was sufficiently flexible to be
 45 applied to other technical implementations and extensible to more actual application cases with
 46 sufficient BMP data. Overall, this study demonstrated the basic idea concept of extending the
 47 spatial optimization of BMPs to the a spatio-temporal level by considering stepwise investment-
 48 I, It, emphasizinged the value of integrating physical geographic processes and anthropogenic
 49 influences.

50

51 **Plain Language Summary**

52 Best management practices (BMPs) are a series of structural and nonstructural management
 53 practices implemented at different spatial scales in a watershed (e.g., sites, agricultural fields,
 54 roads, and streambanks) to reduce the negative environmental impacts of stormwater, soil erosion,
 55 nonpoint source pollution, etc. “When, and where, and to implement which types of BMPs should
 56 be implemented across the a watershed to control which certain environmental issues” are common
 57 but complex questions faced by considerations in comprehensive watershed management. Multi-
 58 objective BMP optimization based on watershed modeling can provide scientific and effective
 59 decision support for decision-making. Existing approaches primarily focus on optimizing the
 60 spatial dimension but neglect the temporal dimension of BMPs, including the optimization of their
 61 BMP implementation orders to pursue address the trade-offs between the high-environmental
 62 effectiveness and low-economic burden during the implementation period. This study proposed a
 63 novel spatio-temporal optimization framework considering two significant factors: stepwise
 64 investment and the time-varying effectiveness of BMPs. The framework was implemented and
 65 demonstrated in an agricultural watershed to find near-optimal optimize the BMP implementation
 66 plans for controlling soil erosion. The cComparative experiments demonstratedd that if a small
 67 portion of environmental effectiveness can could be sacrifice temporarily sacrificed,
 68 optimizations considering the stepwise investment can could provide more feasible
 69 implementation plans with less lower financial pressure, especially in the first year of
 70 implementation. This study emphasizes the value of integrating physical geographic processes

71 (i.e., the response of the watershed response to various spatio-temporal distributions of BMPs) and
 72 anthropogenic influences (i.e., stepwise investment) to design, implement, and apply more
 73 flexible, robust, and feasible geospatial analysis methods.

75 1 Introduction

76 The scientific and reasonable spatial configuration and optimization of diverse best
 77 management practices (BMPs) in ~~the a~~ watershed (~~the a~~ BMP scenario) ~~imply involvea~~ trade-offs
 78 between environmental effectiveness and economic benefits. Optimized BMP scenarios can
 79 provide valuable decision-making support for comprehensive watershed management, including
 80 ~~recommendations for~~ the types and locations of BMPs (Brarmort et al., 2004; Gitau et al., 2006;
 81 Veith et al., 2003). Additionally, a feasible watershed management plan often demonstrates “when
 82 to implement BMPs” considering available investments and other policy-related factors (Bekele
 83 & Nicklow, 2005; Liu et al., 2020). Therefore, how to better select BMP types and where and
 84 when to implement them are critical issues in optimizing watershed BMP scenarios.

85 The existing optimization methods for watershed BMP scenarios can be categorized into
 86 two types. The first is based on identifying priority management areas (PMAs) in the watershed
 87 (Shen et al., 2015; Wu et al., 2023). A PMA, also known as ~~the a~~ critical source area (Pionke et
 88 al., 2000; Srinivasan et al., 2005), refers to a small area that produces disproportionately high
 89 pollutants. More importantly, it dramatically impacts ~~direct or indirect receiving the~~ water bodies
 90 ~~that directly or indirectly receive those pollutants~~ (Wu et al., 2023). These areas are common
 91 priority areas for implementing BMPs to control eco-environmental problems, including non-point
 92 source pollution and soil erosion (Chen et al., 2016; White et al., 2009; Rana & Suryanarayana,
 93 2020). Therefore, after PMAs are identified and ~~ranked as priorities prioritized~~, the implementation
 94 orders of suitable BMPs in ~~the~~ PMAs can be designed accordingly (Jang et al., 2013; Shen et al.,
 95 2015). However, this approach is based only on the evaluation of current watershed conditions. It
 96 does not consider watershed responses to previously selected BMPs ~~in a step-by-stepwise manner~~
 97 during the implementation period. Consequently, such approaches cannot generate ~~an~~ optimized
 98 BMP implementation ~~orders plan~~ with multiple stages spanning several years.

99 The second type ~~of optimization method~~ is ~~an~~ intelligent optimization algorithm-based
 100 methods that ~~simplifies~~, formulates, and solves the complex optimization problem of
 101 selecting and locating BMPs by incorporating watershed modeling (Chen et al., 2016; Srivastava
 102 et al., 2002; Veith et al., 2003; Zhu et al., 2021). The optimization problem formulation comprises
 103 objectives, geographic decision variables, and constraining conditions (Arabi, Govindaraju, &
 104 Hantush, 2006; Zhu et al., 2021). Optimization objectives are often related to multiple and
 105 potentially conflicting objectives, including eco-environmental effectiveness and economic
 106 investment. A geographic decision variable generally represents the decision to plan, implement,
 107 and maintain BMPs in one spatial unit within the study area. A set of decisions determined for all
 108 spatial units constitutes a BMP scenario. ~~The c~~Onstraining conditions refer to ~~the~~ restrictive
 109 situations ~~for that enable~~ better representation and solving ~~of~~ the optimization problem, including
 110 spatial constraints (e.g., suitable spatial locations for implementing BMPs and spatial relationships
 111 among BMPs) and non-spatial constraints (e.g., limited budgets) (Zhu et al., 2021).

112 Most studies on optimization-based methods focus on determining and optimizing the
 113 spatial locations of BMPs from two perspectives. The first ~~perspective~~ is to adopt diverse types of

114 spatial units to define decision variables (Zhu, Qin, et al., 2019). ~~The spatial units adopted in~~
 115 literature, ~~the spatial units are can be~~ classified into five types with different levels in the watershed
 116 (Zhu, Qin, et al., 2019): subbasins (Liu et al., 2019), slope position units (Qin et al., 2018),
 117 hydrologically connected fields (Wu et al., 2018), farms and hydrologic response units (HRUs)
 118 (explicitly referring to HRUs in the SWAT [~~Soil and Water Assessment Tool]-model~~) (Gitau et
 119 al., 2004; Kalcic et al., 2015), and grid cells (Gaddis et al., 2014). The second perspective
 120 introduces diverse spatial constraints to ensure that the optimization results have meaningful
 121 geographic interpretations and practicability (Kreig et al., 2019; Wu et al., 2018; Zhu et al., 2021).
 122 Existing studies have considered three types of spatial constraints: spatial relationships between
 123 BMPs and locations, spatial relationships among adjacent BMPs, and spatial characteristic
 124 adjustment of spatial units (e.g., unit boundary; Zhu et al., 2021). These studies have significantly
 125 improved the reasonability, practicability, and efficiency of optimization methods for watershed
 126 BMP scenarios. However, they still follow the ideal assumption that one BMP scenario can be
 127 entirely implemented at one time. This signifies that they ignored one critical, realistic factor
 128 during ~~the~~ optimization: ~~the implementation ordersplan of BMPs over time~~ that are often restricted
 129 by stepwise investment (Hou et al., 2020).

130 To the best of our knowledge, few studies have been conducted to optimize ~~the~~ BMP
 131 implementation ~~ordersplan~~ (Bekele & Nicklow, 2005; Hou et al., 2020). One existing idea is to
 132 ~~take consider~~ all feasible orders of the selected BMPs during a decision-making period on the same
 133 type of spatial units (e.g., HRUs) as options for these corresponding decision variables.
 134 Consequently, the optimal order configured ~~on-at~~ each spatial unit usually comprises multiple
 135 BMPs, one per year in the decision period (Bekele & Nicklow, 2005). However, such optimization
 136 of an implementation ~~order plan~~ is more focused on every single spatial unit than on all ~~the~~ spatial
 137 units of one scenario. Another idea is ~~the-to~~ optimization ~~of~~ BMP scenarios under different
 138 investment periods as different optimization problems with independent environmental targets and
 139 economic constraints (Hou et al., 2020). These problems are solved in turn, that is, ~~the-an~~
 140 optimization problem under the first investment is ~~first~~ solved ~~first with using the results of~~
 141 ~~occupying~~ several spatial units, ~~followed by and then~~ the next optimization problem ~~is solved~~
 142 ~~using occupying~~ the remaining spatial units in the study area. The stepwise, optimized BMP
 143 scenarios are then combined (Hou et al., 2020). However, this idea only conducts BMP scenario
 144 optimization under diverse investment periods separately and then loosely combines the results
 145 instead of considering stepwise investment as an overall constraint in a single optimization
 146 problem. Therefore, existing methods cannot optimize ~~the~~ BMP implementation orders from a
 147 holistic perspective.

148 In summary, research on optimizing BMP scenarios often emphasizes BMP type-selection
 149 and location-allocation but neglects one crucial situation during ~~the~~ optimization, which is the
 150 implementation ~~ordersorder~~ of BMPs. The few studies assessing the optimization of ~~the BMP~~
 151 implementation ~~orders of BMPs~~ have failed to optimize the BMP implementation orders from a
 152 holistic perspective. Therefore, an effective optimization method for the implementation orders of
 153 BMPs ~~on-at~~ all spatial units of the study area under ~~a~~ stepwise investment ~~process in-for~~ one
 154 optimization problem is still lacking.

155 In this study, we proposed a new simulation-optimization framework for the
 156 implementation ~~ordersplan~~ of BMPs considering two important, realistic factors: stepwise
 157 investment and time-varying BMP effectiveness. This framework extended the existing spatial
 158 optimization framework of BMP scenarios (Arabi, Govindaraju, Hantush, et al., 2006; Maringanti

159 et al., 2011; Qin et al., 2018; Zhu et al., 2021) with regard to four aspects: geographic decision
 160 variables, BMP scenario cost model, BMP knowledge base, and watershed model. The framework
 161 was implemented and exemplified in an agricultural watershed in ~~Southeastern~~ China by
 162 considering the optimization problem of maximizing the soil erosion reduction rate and
 163 minimizing the net cost.

164 **2 Methods**

165 2.1 Basic idea

166 The critical issue in optimizing BMP implementation orders under a stepwise investment
 167 process is the reasonable quantification of the optimization objective, such as the most frequently
 168 used economic cost of BMP scenarios and the environmental effectiveness of BMP scenarios. This
 169 is because, according to most quantitative methods in existing research, if one complete BMP
 170 scenario is divided into several implementation stages, its economic net cost during the evaluation
 171 period (usually defined as the initial construction cost plus the maintenance cost minus the benefit)
 172 may either remain the same, increase, or decrease. However, the stepwise implementation of the
 173 BMP scenario will undoubtedly reduce the overall environmental effectiveness, as these methods
 174 assume that each BMP has a fixed effectiveness, which is often optimum-optimal during the life
 175 cycle of the BMP. Consequently, the comprehensive effectiveness of the BMP scenario is likely
 176 to be reduced and cannot reflect a situation in which stepwise investment is less stressful to
 177 decision-makers and managers. Thus, if the relative loss of environmental effectiveness is
 178 acceptable to them, considering the reduced budget burden, multi-stage implementation under a
 179 stepwise investment process will be more attractive than a one-time investment. Therefore, the
 180 basic idea is to reasonably quantify the economic net cost and environmental effectiveness of the
 181 a BMP scenario that is implemented in multiple stages, considering the actual economic activity
 182 and time-varying effectiveness of the BMPs.

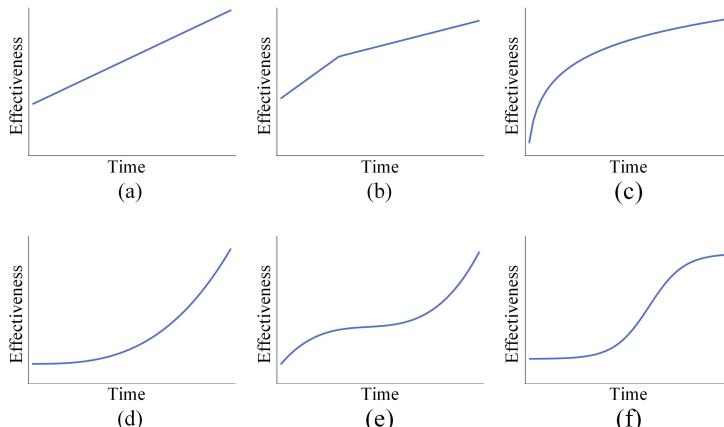
183 The net present value (NPV) is a dynamic economic benefit indicator commonly used in
 184 capital budgeting and investment planning to evaluate the profitability and feasibility of a multi-
 185 year project. Therefore, the NPV can be introduced-used to better represent the economic
 186 characteristics of a stepwise investment. The core idea of the NPV is that a dollar today is worth
 187 more than a dollar tomorrow (Khan & Jain, 1999; Žižlavský, 2014). The NPV calculates the
 188 difference between the discounted present value of cash inflows and outflows over time. To
 189 quantify net cost (outflow minus inflow), we revised the NPV calculation to the opposite form of
 190 its original formula in economics:

$$191 \quad NPV = \sum_{t=1}^q \frac{O_t - F_t}{(1+r)^t} \quad (1),$$

192 where O_t and F_t are cash outflows and cash inflows, respectively, during period t ; q is the number
 193 of periods; and r is the discount rate set by the investor or project manager (e.g., 10%).

194 For environmental efficiency, adopting the time-varying environmental efficiency of
 195 BMPs can overcome the ideal assumption that one BMP can achieve the desired optimal
 196 environmental effectiveness once implemented. Generally, the environmental efficiency of BMPs
 197 can be quantified from two perspectives. The first is to measuring-measure the direct effect of a
 198 BMP based on its governance-governing objective, such as the its reduction rate of a pollutant
 199 concentration in the surface flow out of the vegetation filter strip. The other is to measure-ing the
 200 effect of a BMP based on its related geographic variables, whose changes indirectly affect the

201 ~~governance-governing~~ objective. For example, measuring ~~the~~ improvements in soil properties
 202 resulting from ~~the returning return of~~ farmlands to forests can be utilized ~~in-to simulating simulate~~
 203 ~~the~~-increased infiltration and ~~then-the subsequently~~ reduced surface flow and soil erosion.
 204 However, all these ideal measurements based on field-controlled experiments (Wang et al., 2013;
 205 Zhu et al., 2020) are often time-consuming, laborious, and expensive, especially for time-varying
 206 data. Theoretical analyses based on the mechanisms of ~~a~~ BMP can be used ~~as anto~~ effectively
 207 supplement ~~to a few limited~~ measured data over time. It is now accepted that the environmental
 208 efficiency of ~~a~~ BMPs usually changes over time and gradually increases to ~~the an optimalum level~~
 209 in the ~~process of its taking effect in the~~ first stage of ~~its~~ life cycle ~~of the BMP~~ (Bracmort et al.,
 210 2004; Emerson & Traver, 2008; Emerson et al., 2010; Liu et al., 2017). Based on this, Liu et al.
 211 (2018) generalized a variety of possible time-varying curves for the average effectiveness of BMPs
 212 (Figure 1). Therefore, theoretical curves, combined with sampling data in individual years (if
 213 available), can be used to estimate changes in some key BMP parameters characterized in
 214 watershed models. In this manner, we can reasonably model the time-varying effectiveness of
 215 BMPs and evaluate the environmental effectiveness of BMP scenarios.



216
 217 Figure 1. Typical theoretical changes ~~efin~~ in ~~the effectiveness of a~~ best management practice
 218 (BMP) ~~effectiveness~~ over time for the first stage ~~after post-~~ implementation [adapted from Liu et
 219 al. (2018)]. (a)–(f) represent the linear, piecewise linear, logarithmic, exponential, polynomial,
 220 and logistic changes ~~efin~~ in ~~the~~ BMP effectiveness over time, respectively.

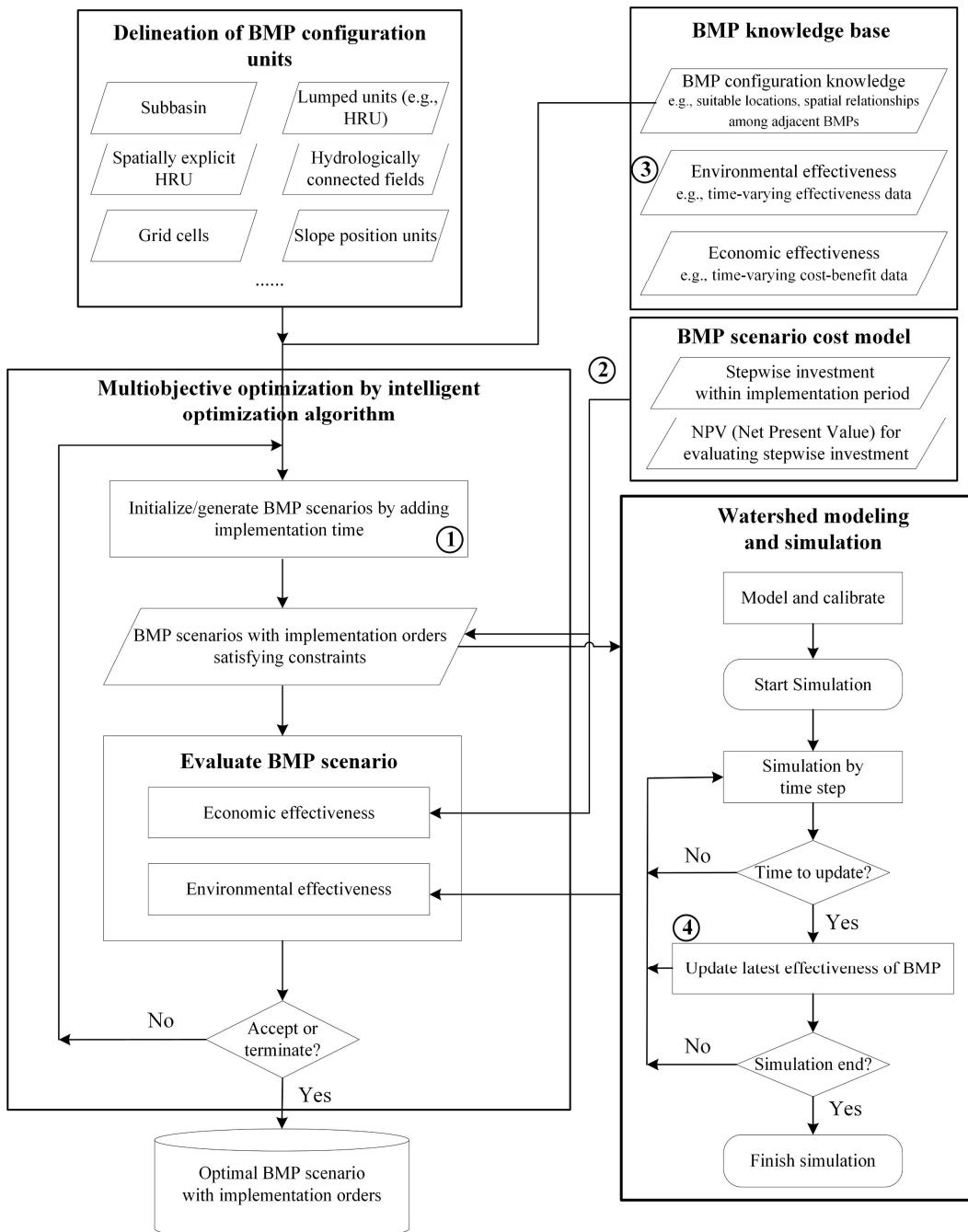
221 2.2 Overall design

222 To achieve the basic idea, we adopted a widely used simulation-optimization framework
 223 applied to agricultural and urban BMPs (Arabi, Govindaraju, Hantush, et al., 2006; Maringanti et
 224 al., 2011; Raei et al., 2019; Qin et al., 2018; Zhu et al., 2021) and improved it with respect to four
 225 aspects (Figure 2). The first was to extend the geographic decision variables to represent the
 226 implementation time of ~~a~~ BMP in initializing and generating BMP scenarios (label 1, Figure 2).
 227 The second improvement was ~~to incorporating incorporate~~ the NPV indicator into the BMP
 228 scenario cost model (label 2, Figure 2). Thus, the initialized and regenerated scenarios during the
 229 optimization process could be constrained by stepwise investment and screened before being
 230 evaluated. The third improvement ~~was to supported~~ the time-varying effectiveness of BMPs in the
 231 BMP knowledge base (label 3, Figure 2). The fourth was to improve the ~~applicability of the~~
 232 watershed model ~~for application~~ during the simulation (label 4, Figure 2). Subsections 2.3–2.6 of
 233 this study present detailed designs ~~ef-for~~ the four improvements with ~~the~~ specific ~~method~~

234 implementation ~~results~~ for a case study of a small agricultural watershed ~~case study~~ that aimed to
235 control soil erosion. Moreover, the multi-objective optimization algorithm ~~should be was~~
236 customized accordingly to handle the extended geographic decision variables during optimization
237 (Subsection 2.7). The optimized BMP scenarios based on this framework could provide decision-
238 makers with the a reference for option to include including implementation plans for BMPs with
239 multiple stages.

240

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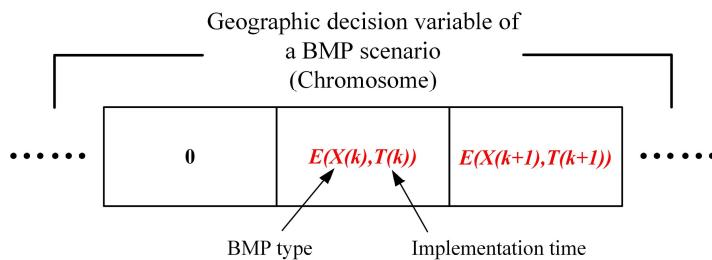
242

243 Figure 2. Proposed framework for optimizing the implementation planorders of best management
 244 practices (BMPs). Considering their stepwise investment and their time-varying effectiveness.
 245 Labels 1–4 represent improvements on the already-existing and widely utilized used
 246 spatial optimization framework of BMP scenarios.
 247

248 2.3 Extending geographic decision variables to represent BMP implementation time

249 Geographic decision variables are normally organized as a one-dimensional array to
 250 encode the spatial configuration information of BMPs, which is conveniently for-used as a
 251 examining chromosomes in genetic optimization algorithms. Each geographic decision variable
 252 uses an integer value to record the-a decision on the-a spatial unit without a BMP (i.e., equals 0)
 253 or the-a type of BMP (Qin et al., 2018). A reversible and easily extensible encoding approach was
 254 proposed and implemented to represent the BMP type and implementation time in-as one decision
 255 variable (Figure 3).

256



257

258 Figure 3. Schematic of the extended geographic decision variable of a best management practice
 259 (BMP) scenario. For the spatial unit k in a BMP scenario S , $X(k)$ and $T(k)$ denote the BMP type
 260 and implementation time, respectively. E is the reversible encoding method; for example, if $E =$
 261 $X(k) \times 10 + T(k)$, and if $X(k) = 4$, and $T(k) = 3$, the encoded value is 43. The multiplier 10 can be
 262 scaled up or down in multiples of 10, depending on the number of implementation periods. The
 263 decision variable equals 0 if the spatial unit is not configured with in-a-BMP.

264 Therefore, the extended geographic decision variables of a BMP scenario S can be
 265 expressed as follows:

$$266 \quad S(k) = \begin{cases} E(X(k), T(k)) = X(k) \times 10 + T(k), & \text{unit } k \text{ configure a BMP} \\ 0, & \text{otherwise} \end{cases} \quad (2),$$

267 where $k \in [1, n]$, $X(k) \in [1, p]$, $T(k) \in [1, q]$, n is the chromosome length (the number of spatial units
 268 in the study area), p is the number of BMP types, and q is the number of investment periods
 269 (typically in years) for implementing the BMPs.

270 With the extended geographic decision variables, the spatial distribution and
 271 implementation time of BMPs can be optimized separately optimized in the solution spaces of
 272 $(p+1)^n$ and q^n , respectively, and simultaneously optimized in an enlarged $(p*q+1)^n$ solution space.
 273 Stepwise investment can be used as a nonnon-spatial constraint to limit the solution space by
 274 setting the minimum and maximum allowable investment amount for each period.

275 2.4 Extending the BMP scenario cost model to calculate NPV

276 As stated in-the basic idea above, once the geographic decision variable supports the BMP
 277 implementation time, the classical cost calculation of the BMP scenario by-using simple cost
 278 accumulation is no longer applicable but is still retained for compatibility with the previous
 279 framework. We extended the BMP scenario cost model using Equation (1) to support the
 280 calculation of the NPV of the BMP scenario with implementation orders. The annual cost (e.g.,
 281 the abovementioned net cost explained earlier) is first summarized as a discrete numerical series
 282 $O = \{o_1, o_2, \dots, o_q\}$. The NPV can then be derived by discounting all costs to the beginning-first

283 year of the implementation period, ~~making allowing comparison of~~ the net costs of BMP scenarios
 284 with different implementation orders~~comparable~~.

285 2.5 Extending the BMP knowledge base to represent time-varying effectiveness

286 The spatial optimization framework utilized three main types of knowledge (Figure 2):
 287 spatial configuration, environmental effectiveness, and economic effectiveness (Zhu, Qin, et al.,
 288 2019). The latter two types of knowledge are time related. Environmental effectiveness can be
 289 expressed as changes in overall effectiveness corresponding to some specific environmental
 290 indices (e.g., total nitrogen reduction rate by vegetated filter strips) or changes in BMP modeling
 291 parameters, such as improvements in soil properties (e.g., increased soil conductivity by returning
 292 farmlandss to forests). Economic effectiveness includes cash outflow (e.g., initial implementation
 293 and maintenance costs) and inflow (e.g., direct and indirect income).

294 Generally, time-varying data can be represented in two forms: time-related formulase (Liu
 295 et al., 2018) and enumerated values. The former is suitable for ideal situations, such as when the
 296 mechanism of the ~~effect of~~ BMP ~~effect~~ is clearly understandable and the formula is derived from
 297 long-term environmental observation data. The latter method is relatively simple, flexible,
 298 adaptable, and easy to implement. The form of enumerated effectiveness values over time is
 299 appropriate when little observational data are available, and the BMP mechanism can be
 300 reasonably estimated using theoretical curves (Figure 1). Therefore, the form of enumerated values
 301 for ~~knowledge of~~ environmental and economic effectiveness was implemented in this study as an
 302 example to verify the proposed framework. All time-related effectiveness data were prepared as
 303 arrays with ~~a~~ user-defined time intervals and periodss.

304 2.6 Extending the watershed model to apply the time-varying environmental
 305 effectiveness of BMPs

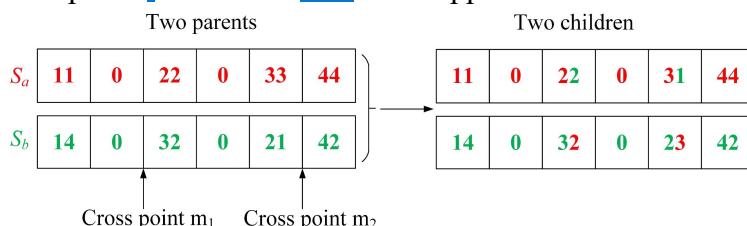
306 Unlike the updating of watershed parameters related to the fixed effectiveness of BMPs
 307 (e.g., soil hydraulic properties) at the beginning of a watershed simulation, which is performed in
 308 most existing watershed models, the environmental evaluation of BMP scenarios considering the
 309 implementation orders requires an iteration-iterative updating process during the simulation
 310 (Figure 2). When thean incremental simulation time is incremented, the model verifies whether it
 311 is time to update the followingsubsequent BMP effectiveness data: if the simulation time meets
 312 the preset update time, the model updates the relevant parameters and conducts subsequent
 313 simulations with the updated parameters until the next update time is reached or the entire
 314 simulation period ends (Figure 2).

315 To support the iterative updateupdating of time-varying environmental effectiveness data
 316 of the BMP, ~~a~~ source code-level improvement for the watershed models is neededrequired. The
 317 Spatially Explicit Integrated Modeling System (SEIMS), which has been developed over the past
 318 few years (Liu et al., 2014; Liu et al., 2016; Zhu, Liu, et al., 2019), was adoptedused as the
 319 watershed modeling framework to implement this improvement (Shen & Zhu, 2022). SEIMS has
 320 been successfully utilized in the spatial optimization of BMP scenarios with diverse types of spatial
 321 units and spatial configuration knowledge (Qin et al., 2018; Zhu et al., 2021; Zhu, Qin, et al.,
 322 2019).

323 2.7 Customizing a multi-objective optimization algorithm to handle the extended
 324 geographic decision variables

325 The non-dominated sorting genetic algorithm (NSGA-II) (Deb et al., 2002) is as one of the
 326 most efficient algorithms for multi-objective optimization problems, and it has been extensively
 327 employed in the spatial optimization of BMP scenarios (Babbar-Sebens et al., 2013; Kalcic et al.,
 328 2015; Maringanti et al., 2011; Qin et al., 2018; Wu et al., 2018). This study adopted the NSGA-II
 329 as an intelligent optimization algorithm, with customization of its crossover and mutation
 330 operators to support the regeneration process of BMP scenarios considering implementation time
 331 (Figure 2).

332 Because the extended geographic decision variables included information on both the BMP
 333 type and implementation time information, crossover and mutation operations that were
 334 accordingly designed accordingly could be conducted on them separately and simultaneously
 335 performed. For example, Figure 4 depicts a two-point crossover operation on implementation time
 336 only, that is, the second number in the genes of the two-parent individuals, S_a and S_b , between two
 337 randomly selected cross points m_1 and m_2 , we are swapped.



338 Figure 4. Example of the two-point crossover operation of two parents, S_a and S_b , on
 339 implementation time only. To facilitate the this demonstration, the first number of each gene
 340 denotes the best management practice (BMP) type, and the second number represents the
 341 implementation time.

343 The mutation operator iterates over each gene value of the new child individual child to
 344 and conduct mutation mutates (i.e., changes the original value to one of the applicable values)
 345 according to a small probability ρ . If a randomly generated number between 0 and 1 is less than ρ ,
 346 mutation occurs. The proposed framework allows users to determine whether the mutation object
 347 is the BMP type, implementation time, or both, according to the application.

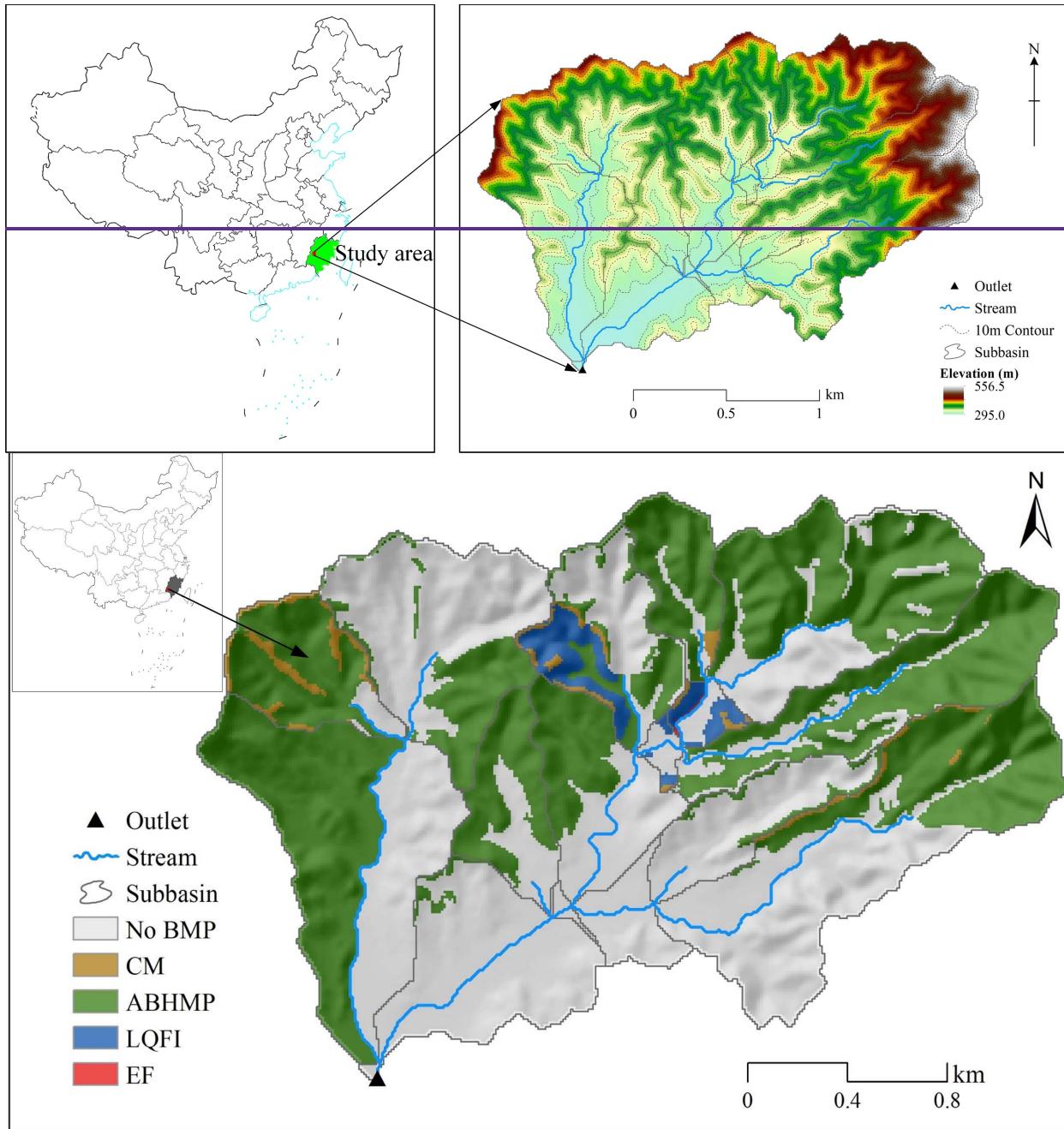
348 **3 Experimental designs**

349 To verify the rationality and validity of the proposed simulation-optimization framework
 350 for the BMP implementation orders, we implemented a new optimization tool. It is based on our
 351 former previous distributed watershed modeling and BMP optimization studies on slope position
 352 units, as introduced in the last section. The follow-up case study aimed at to optimizing find the
 353 near-optimal BMP implementation plans for controlling soil erosion under a 5-year stepwise
 354 investment process in a representative agricultural watershed in the red-soil region of
 355 Southeastern China.

356 **3.1 Study area and data**

357 The study area was the Youwuzhen watershed (approximately 5.39 km²) in the town of
 358 Hetian Town, Changting County, Fujian Province, China (Figure 5). This small watershed belongs
 359 to the Zhuxi River watershed, a first-level tributary of the Tingjiang River, and is located between

25° 40' 13" N, 116° 26' 35" E and 25° 41' 29" N, 116° 28' 40" E. The primary geomorphological characteristics are low mountains and hills. The elevation ranges from 295.0 to 556.5 m, with an average slope of 16.8°. The topographic trend inclines from northeast to southwest, and the riverbanks are relatively flat and wide. It The area has a mid-subtropical monsoon moist climate, with an annual average temperature of 18.3 °C and precipitation of 1697 mm (Chen et al., 2013). Precipitation is characterized by concentrated and intense thunderstorm events, and the total rainfall from March to August accounts for 75.4% of the rainfall of the entire year. The main land-use types are forests, paddy fields, and orchards, with proportional area-ratios of 59.8%, 20.6%, and 12.8%, respectively. Additionally, the study area is dominated by secondary or human-made planted forests with a low coverage owing to the destruction of vegetation destruction due to by soil erosion and economic development (Chen et al., 2013). The soil types in the study area are red soil (78.4%) and paddy soil (21.6%), which can be classified as *Ultisols* and *Inceptisols*—respectively, as per the US Soil Taxonomy, respectively—(Shi et al., 2010). The red soil is predominantly distributed in hilly regions, while the paddy soil is distributed primarily distributed in broad alluvial valleys with a similar spatial pattern as that of the land use of paddy rice agricultural land use. The study area is within one of the counties with the most severe soil erosion in Ssouthern China. The soil erosion type is severe water erosion, which is typical and representative of Changting County.



380 Figure 5. Spatial locationMap of the Youwuzhen watershed in Changting County, Fujian
 381 Province, China, and The sSpatial distribution of the fundamental spation scenario of best
 382 management practices (BMPs) based on slope position units derived from Zhu et al. (2019b).
 383 Four BMPs are included: closing measures (CM), arbor–bush–herb mixed plantation (ABHMP),
 384 low-quality forest improvement (LQFI), and economic fruit (EF).

385 The basic spatial data collected for the watershed modeling of the Youwuzhen watershed
 386 included a gridded digital elevation model, soil type map, and land-use type map, all of which
 387 were unified to a 10 m resolution (Qin et al., 2018). Soil properties of Each soil type properties
 388 wereproperty (e.g., organic matter and mechanical composition) waswere measured fromby field
 389 samplings (e.g., organic matter and mechanical composition; Chen et al., 2013) and derived from

the Soil–Plant–Air–Water (SPAW) model (e.g., field capacity and soil hydraulic conductivity; Saxton and Rawls, 2006). Land use or land cover-related parameters were referenced from the SWAT database (e.g., Manning's roughness coefficient; Arnold et al., 2012) and relevant literature (e.g., cover management factor for the universal soil loss equation [USLE]; Chen et al., 2019). Daily climate data from the nearest national weather station, including temperature, relative moisture, wind speed, and sunshine duration hours from 2011 to 2017, were derived from the National Meteorological Information Center of the China Meteorological Administration. Moreover, daily precipitation data from ~~one-a~~ local monitoring station were also collected. The ~~watershed outlet~~ periodic site monitoring streamflow and sediment discharge data ~~of the watershed outlet~~ from 2011 to 2017 were provided by the Soil and Water Conservation Bureau of Changting County. ~~Due to limited data quality, the~~ streamflow and sediment discharge data were screened by ~~a rule that required searching for~~ complete rainstorms records with more than three consecutive days for watershed modeling ~~due to limited data quality~~ (Qin et al., 2018).

3.2 BMP knowledge base

We selected four representative BMPs that have been widely implemented ~~in Changting County~~ for soil and water conservation ~~in Changting County~~: closing measures (CM), arbor–bush–herb mixed plantations (ABHMP), low-quality forest improvement (LQFI), and economic fruit (EF). Table 1 lists ~~the~~ brief descriptions ~~for these BMPs~~, which mainly include ~~their~~ ~~the~~ spatial configuration knowledge (Figure 2).

Table 1. Brief description of ~~the~~ four best management practices (BMPs) considered in this study
[adapted from (Qin et al., 2018)]

BMP	Brief description
Closing measures (CM)	Closing off the ridge areas and/or upslope positions from human disturbance (e.g., tree felling and forbidding grazing) to facilitate afforestation.
Arbor–bush–herb mixed plantation (ABHMP)	Planting trees (e.g., <i>Schima superba</i> and <i>Liquidambar formosana</i>), bushes (e.g., <i>Lespedeza bicolor</i>), and herbs (e.g., <i>Paspalum wettsteinii</i>) in level trenches on hillslopes.
Low-quality forest improvement (LQFI)	Improving infertile forests located in the upslopes and steep backslopes positions by applying compound fertilizer on fish-scale pits. Building new orchards on the middle-slopes and down-slopes positions or improving them under superior water and fertilizer conditions by constructing level terraces, drainage ditches, storage ditches, irrigation facilities and roads, planting economic fruit (e.g., chestnut, waxberry, and) and interplanting grasses and Fabaceae (<i>Leguminosae</i>) plants.
Economic fruit (EF)	

The environmental effectiveness of BMPs in controlling soil erosion can be reflected by ~~their~~ improvements ~~in-of~~ soil properties, including organic matter, bulk density, texture, and hydraulic conductivity. The Soil and Water Conservation Bureau of Changting County ~~selected examined~~ 50 sample plots in the study area in 2000, including the four BMP types mentioned above. Intensively eroded plots with similar basic conditions, including soil type, landform, and parent material, were selected as control plots. The physical and chemical properties of all the plots were measured in 2005. The change ratio of the soil properties ~~under each BMP compared~~ to the control plot ~~over five years under each BMP~~ was considered ~~as its~~ environmental effectiveness ~~over five years~~. By combining these measured data and determining the soil stable infiltration rate ~~by using the datamethods offrom~~ Lin (2005), this study assumed that key soil parameters ~~reasonably fluctuate reasonably in certain specific~~ years post-after BMP implementation. The time-varying changes in BMP effectiveness can be characterized predominantly ~~characterized~~ by one of the functions depicted in Figure 1, including linear functions, first fast and then slow functions,

424 and first slow and then fast functions, ~~and so on~~. Other derived properties and parameters utilized
425 in the SEIMS model ~~were prepared accordingly~~, including the total porosity and soil erodibility
426 factor, were prepared accordingly.

427 The annual data on the environmental effectiveness and cost–benefit knowledge of the four
428 BMPs are depicted in Table 2. For example, in the first, second, third, fourth, and fifth year after
429 implementing CM, ~~the~~ organic matter (OM) ~~would increase~~ in ratios of by 1.50, 1.62, 1.69, 1.74,
430 and 1.77, respectively, within five years. The relative changes in the ~~e~~conservation practice factor
431 USLE_P conservation practice factor of the USLE in Table 2 were adopted from ~~one-a~~ calibrated
432 SWAT model for this area (Chen et al., 2013), which maintained the same value within over five
433 years.

434 Table 2. Environmental effectiveness and cost–benefit knowledge of the four best management practices (BMPs) [within](#) [in the](#) five
 435 years [post](#) [after](#) [their](#) implementation

BMP	Year	Environmental effectiveness ^a					Cost–benefit (CNY 10,000/km ²)			
		OM	BD	PORO	SOL_K	USLE_K	USLE_P	Initial	Maintain	Benefits
CM	1	1.50	0.98	1.02	2.21	0.78	0.90	15.50	1.50	0.00
	2	1.62	0.97	1.03	4.00	0.99	0.90	0.00	1.50	0.00
	3	1.69	0.95	1.05	3.35	0.70	0.90	0.00	1.50	2.00
	4	1.74	0.94	1.06	3.60	0.60	0.90	0.00	1.50	2.00
	5	1.77	0.92	1.08	5.24	0.26	0.90	0.00	1.50	2.00
ABHMP	1	1.30	0.99	1.01	1.39	0.71	0.50	87.50	1.50	0.00
	2	1.36	0.98	1.02	1.38	0.89	0.50	0.00	1.50	0.00
	3	1.40	0.97	1.03	1.26	0.76	0.50	0.00	1.50	6.90
	4	1.42	0.96	1.04	1.15	0.75	0.50	0.00	1.50	6.90
	5	1.42	0.95	1.05	1.07	0.80	0.50	0.00	1.50	6.90
LQFI	1	2.80	0.98	1.02	1.54	0.88	0.50	45.50	1.50	0.00
	2	3.22	0.96	1.04	2.00	0.80	0.50	0.00	1.50	0.00
	3	3.47	0.94	1.07	2.76	0.60	0.50	0.00	1.50	3.90
	4	3.66	0.92	1.09	2.53	0.69	0.50	0.00	1.50	3.90
	5	3.80	0.90	1.11	2.38	0.73	0.50	0.00	1.50	3.90
EF	1	1.20	0.99	1.01	0.90	1.10	0.75	420.00	20.00	0.00
	2	1.23	0.98	1.02	1.16	1.06	0.75	0.00	20.00	0.00
	3	1.25	0.96	1.04	0.95	0.70	0.75	0.00	20.00	0.00
	4	1.26	0.95	1.05	1.60	0.65	0.75	0.00	20.00	0.00
	5	1.30	0.94	1.06	1.81	0.76	0.75	0.00	20.00	60.30

436 Note. ^a Environmental effectiveness of BMPs [includes](#) [as indicated by](#) soil property parameters [organic matter (OM), bulk density
 437 (BD), total porosity (PORO), and soil hydraulic conductivity (SOL_K)] and universal soil loss equation (USLE) factors [soil
 438 erodibility (USLE_K) and conservation practice factor (USLE_P)]. [The v](#)[Values](#) in each column represent relative changes
 439 (multiplying) and, thus, have no units.

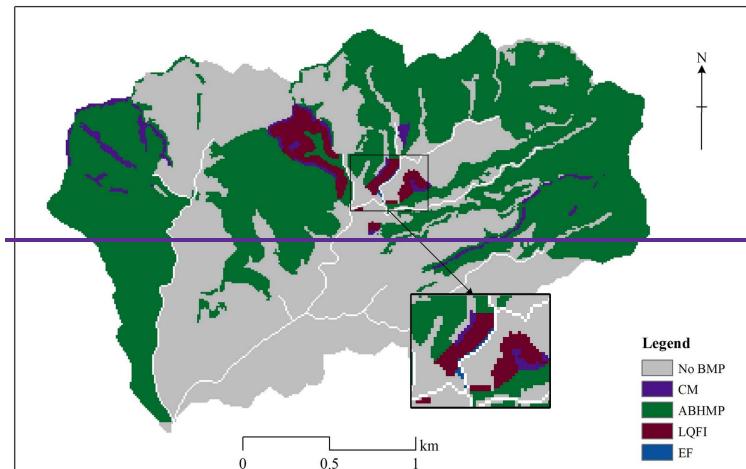
440 CM, closing measures; ABHMP, arbor–bush–herb mixed plantation; LQFI, low-quality forest improvement; EF, economic fruit.

442 The economic data ~~of for~~ these BMPs were estimated by Wang (2008) according to the
 443 price standard adopted 15 years ago. Although this is no longer applicable to the current price
 444 standards, it is still suitable for evaluating the relative net cost among the BMP scenarios. Owing
 445 to the long estimation cycle of the economic benefits of soil and water conservation projects, the
 446 direct economic benefits of the four BMPs (e.g., fruit production growth and forest stock volume)
 447 ~~are were~~ generally calculated from the third (e.g., CM, ABHMP, and LQFI) or fifth year (e.g., EF)
 448 ~~post after~~ implementation.

449 3.3 Calibrated watershed model and selected BMP scenario from [a former study](#)

450 To simulate daily soil erosion in the Youwuzhen watershed, we adopted the SEIMS-based
 451 watershed model that considers gridded cells as the basic simulation unit constructed and
 452 calibrated by Zhu, Qin, et al. (2019). The details of the selected watershed process and ~~the~~
 453 calibration and validation [processes](#) of ~~the~~ watershed outlet streamflow and sediment discharge
 454 can be found in Zhu, Qin, et al. (2019).

455 To ~~perform optimize~~ the [optimization on the](#) temporal dimension and evaluate the impact
 456 of stepwise investment and [the](#) time-varying effectiveness of BMPs ~~on in on~~ the BMP
 457 implementation plans, we selected an optimized BMP scenario (Figure 65) from Zhu, Qin, et al.
 458 (2019) as the fundamental spatial scenario. The selected BMP scenario considered~~s~~ a simple
 459 system of three types of slope positions (ridge, backslope, and valley) as the BMP configuration
 460 units, which have been proven to be effective in ~~the our~~ previous studies [undertaken by us](#) (Qin et
 461 al., 2018; Zhu, Qin, et al., 2019). In this scenario, ABHMP occupied the most prominent area, with
 462 large clumps distributed over the west, central, and northeast ridge, backslope, and valley. LQFI
 463 was concentrated on the backslope in the middle region. CM was scattered on the west, central,
 464 and east ridges and backslope. EF occupied the smallest area in the central valley.



465
 466 **Figure 6. Spatial distribution of the selected BMP scenario based on slope position units**
 467 **from Zhu, Qin, et al. (2019). Partially enlarged details of the configured economic fruit (EF)**
 468 **practice along the river have ~~are also~~ been depicted (white lines).**

471 3.4 Multi-objective BMP scenarios optimization

472 The multi-objective of this case study was to maximize the soil erosion reduction rate and
 473 minimize the net cost of a BMP scenario. The optimization problem can be formulated as follows:

474 $\min\{-f(S), g(S)\}$ (4),

475 where $f(S)$ and $g(S)$ denote the reduction rate of soil erosion and net cost of BMP scenario S ,
 476 respectively. $f(S)$ is calculated by the average soil erosion reduction rate after implementing
 477 scenario S with an implementation orders, as follows:

478
$$f(S) = \sum_{t=1}^q f(S, t) / q = \sum_{t=1}^q \frac{V(0) - V(S, t)}{V(0)} \times 100\% / q \quad (5),$$

479 where t is the implementation period, q is the total number of time periods, $f(S, t)$ represents the
 480 reduction rate of soil erosion within period t , and $V(0)$ and $V(S, t)$ are the total amounts of sediment
 481 yields from hillslopes that are routed into the channel (kg) under the baseline scenario and S
 482 scenario, respectively, in period t .

483 $g(S)$ can be calculated by the net cost of implementing scenario S with implementation
 484 order scheme T using the NPV defined in Equation (1). The cash outflow O_t and inflow F_t of S at
 485 time t were calculated using Equations (6) and (7), respectively:

486
$$O_t = \sum_{k=1}^n O(S, k, t) = \sum_{k=1}^n \begin{cases} A(X(k), t) * \{C(X(k)) + M(X(k), t)\}, & \text{if } t \geq T(k) \\ 0, & \text{if } t < T(k) \end{cases} \quad (6),$$

487
$$F_t = \sum_{k=1}^n F(S, k, t) = \sum_{k=1}^n \begin{cases} A(X(k), t) * B(X(k), t), & \text{if } t > T(k) \\ 0, & \text{if } t \leq T(k) \end{cases} \quad (7),$$

488 where $A(X(k), t)$ is the configured BMP area on the k th spatial unit in time t ; $C(X(k))$, $M(X(k), t)$,
 489 and $B(X(k), t)$ are the initial construction cost, annual maintenance cost, and annual benefit per unit
 490 area, respectively (Table 2).

491 The parameter settings for the NSGA-II algorithm included an evolutionary generation of
 492 100, a population number of 100, a crossover rate of 0.8 for the two-point crossover operator, a
 493 mutation rate of 0.1, and a selection probability of 0.8. The reference point for calculating the
 494 hypervolume index was set to (300, 0), which denotes the worst-case scenario: a net cost of 300
 495 (CNY 10,000) and a soil erosion reduction rate of zero. To improve the ecomputing computational
 496 efficiency of numerous executions of the SEIMS model, as required by the optimization algorithm,
 497 the Tianhe-2 supercomputer (Liao et al., 2014), one of the fastest supercomputers in the world,
 498 was utilized to take full advantage of the parallelizability of the SEIMS (Zhu, Liu, et al., 2019),
 499 that is, occupying a maximum of 10 nodes and simultaneously executing four SEIMS models per
 500 nodesimultaneously.

501 3.5 Comparative experiments

502 Based on the selected spatial distribution of BMPs from the former study, we designed four
 503 comparative experiments to evaluate the effects of stepwise investment and the time-varying
 504 effectiveness of BMPs on the optimized implementation plans:

- 505 ● Stepwise investment and fixed BMP effectiveness (STEP + FIXED)
- 506 ● One-time investment and fixed BMP effectiveness (ONE + FIXED)

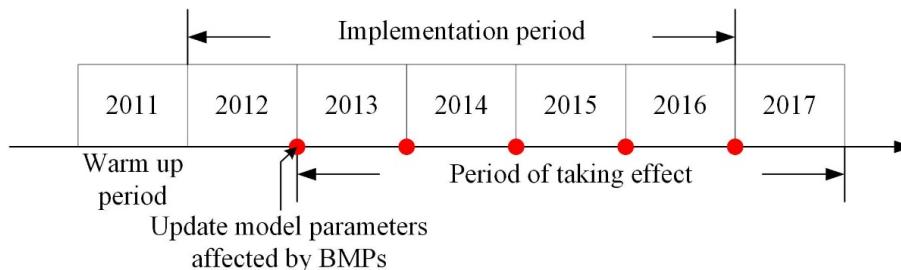
- 507 ● Stepwise investment and time-varying BMP effectiveness (STEP + VARY)
 508 ● One-time investment and time-varying BMP effectiveness (ONE + VARY)

509 Experiments with a fixed BMP effectiveness used the stable environmental effectiveness
 510 data of the BMPs in this case study, that is, data in the fifth year post-after implementation (Table
 511 2). For the one-time investment, we assumed that all funds would be available at the beginning of
 512 a specific year in the implementation period and that all BMPs would be implemented within the
 513 same year. Therefore, each experiment with one-time investment had only five solutions.
 514 Simultaneously, experiments with a stepwise investment needed to be optimized, resulting in near-
 515 optimal Pareto solutions (also termed as-Pareto fronts).

516 The experimental design followed three assumptions for implementing efa target BMP
 517 scenario:

- 518 ● Once a spatial unit was configured with a BMP in a certain year, the BMP type would
 519 not change throughout thein subsequent evaluation periods.
- 520 ● TheAn unlimited number of BMPs that could be implemented within a year was
 521 unlimited, ranging from zero to the total number of spatial units n, could be
 522 implemented within a year.
- 523 ● Each BMP type could be implemented onaton any spatial unit within onea year and
 524 would start to take effect in the subsequent year.

525 The simulation period for each SEIMS-based model was from 2011 to 2017 (Figure 76).
 526 The environmental effectiveness and cost–benefit data of the four BMPs listed in Table 2 were
 527 used as model inputs with a one-year update interval. The implementation period
 528 for the BMP scenario was from 2012 to 2016. At the end of each year, the model parameters
 529 affected by the BMPs (i.e., soil properties offfor the spatial units withof the BMPs; Table 2) would
 530 be updated (red dots in Figure 76), including the newly and previously implemented
 531 ones parametersBMPs. Therefore, the effect period of BMPs taking effect in this study lasted from
 532 2013 to 2017.



533
 534 Figure 76. Schematic diagram of the watershed model simulation periods for evaluating a best
 535 management practice (BMP) scenario.

537 The selected BMP scenario required 207.35 (CNY 10,000) for the initial construction and
 538 subsequent maintenance costs before making a profit (in the first two years) (Zhu, Qin, et al.,
 539 2019). To conduct experiments with stepwise investment, gradually decreased investments were
 540 designed to gradually decrease within the 5-year implementation period, specifically, from 90, to
 541 70, to 30, to 20, and finally to 20 (CNY 10,000). The maximum available investment was set to
 542 increase by 10% to more quickly generate eligible possible scenarios more quickly. The discount

543 rate was set to 0.1. All cash flows during the implementation period were discounted to values in
 544 the first year of the implementation period (2012).

545 3.6 Evaluation methods

546 We compared and discussed the four comparative experiments from two perspectives.
 547 From the numerical perspective, we evaluated all solutions under two objectives. From ~~the_a~~
 548 qualitative perspective, we analyzed the characteristics of the selected solutions considering the
 549 BMP implementation orders.

550 In this case study, two aspects were considered in the numerical evaluation of BMP
 551 scenarios under the two objectives. One ~~is-was an~~ intuitive comparison conducted by plotting
 552 Pareto fronts from stepwise investment experiments and BMP scenarios from one-time investment
 553 experiments as scattered plots. The other ~~is-usingused~~ a quantitative index, such as the commonly
 554 used hypervolume index, to measure the overall quality of the Pareto fronts, ~~such as, the commonly~~
 555 used hypervolume index (Zitzler et al., 2003). In this study, the larger the hypervolume ~~iwas~~, the
 556 better the Pareto front. Additionally, changes in the hypervolume index with evolutionary
 557 generations could provide a qualitative reference for optimization optimizing the efficiency. In an
 558 ideal optimization process, the hypervolume initially ~~rises~~ rapidly increases, then gradually slows
 559 down, and finally stabilizes. The faster the hypervolume becomes stable, the higher the
 560 optimization efficiency (Zhu, Qin, et al., 2019).

561 To qualitatively evaluate the BMP implementation ~~ordersorder~~ characteristics under the
 562 impacts of stepwise investment and time-varying BMP effectiveness, typical scenarios were
 563 selected and compared based on their temporal distributions. Three selection criteria were
 564 designed: high NPV with a high soil erosion reduction rate (HH), low NPV with a low soil erosion
 565 reduction rate (LL), and moderate NPV with a moderate soil erosion reduction rate (MM).

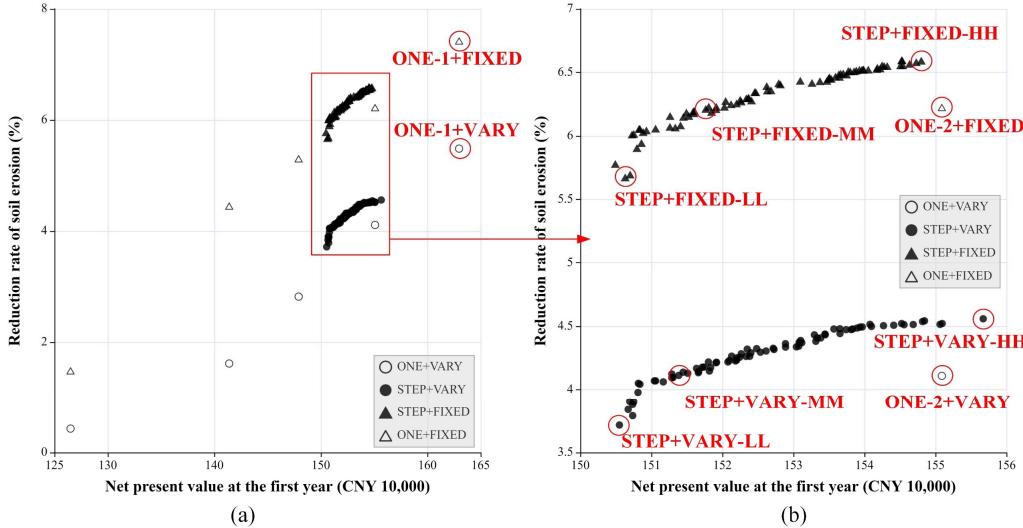
566

567 **4 Experimental results and discussion**

568 4.1 Numerical evaluation of BMP scenarios under two objectives

569 The BMP scenarios derived from the four experiments ~~are-were~~ plotted as scatter points
 570 with the NPV and soil erosion reduction rate as axes (Figure 8a~~7a~~). Two comparisons between
 571 stepwise and one-time investments (STEP + FIXED vs. ONE + FIXED and STEP + VARY vs.
 572 ONE + VARY) demonstrated the same distribution patterns. The NPV and reduction rate of soil
 573 erosion of the one-time investment solutions (ONE + VARY and ONE + FIXED) ~~descended~~
 574 synchronously declined from the top right (ONE-1) to the bottom left (ONE-5, which denotes
 575 investment in the fifth year). The ONE + FIXED scenario ~~that invested in with~~ the first year
 576 investment (the existing method, labeled as ONE-1 + FIXED in Figure 8a~~7a~~) required the greatest
 577 NPV (163, the unit is in CNY 10,000) to achieve the most significant soil erosion reduction rate
 578 (7.42%). The Pareto fronts under stepwise investment were densely distributed near the ONE-2
 579 solutions and ~~took had~~ dominant positions. Figure 8b~~7b~~ depicts an enlarged area of 150–156 NPV
 580 with a reduction rate of soil erosion at 3.5–7.0% to highlight this pattern. The best soil erosion
 581 reduction rates under stepwise investment were approximately 0.8–0.9% lower than those under
 582 the ONE-1 scenarios, with savings of about approximately 7.7 NPV and soil erosion reduction rates
 583 that were about approximately 0.4% higher than those of the ONE-2 scenarios requiring similar
 584 NPVs. In general, the proposed optimization method of the BMP implementation orders

585 considering stepwise investment could effectively provide more choices with ~~a lower~~
 586 investment burden ~~at the cost of with only~~ a slight loss ~~of in~~ environmental effectiveness.
 587



588
 589 Figure 8.7. Comparison of best management practice (BMP) scenarios derived from the four
 590 comparative experiments: (a) overall comparison; (b) zoomed-in area at approximately 150–156
 591 NPV (CNY 10,000) with a soil erosion reduction rate of 3.5–7.0%. STEP: stepwise investment;
 592 ONE- n : one-time investment in the n^{th} year; FIXED: fixed effectiveness of BMP; VARY: time-
 593 varying effectiveness of BMP; LL: low NPV and low soil erosion reduction rate; MM: moderate-
 594 moderate; HH: high-high.

595
 596 Six representative scenarios were selected from the two STEP Pareto fronts to ~~make~~ more
 597 specifically ~~comparisons with~~ the two ONE-2 scenarios, as depicted in Figure 8b-7b (e.g., STEP
 598 + VARY-HH, STEP + VARY-MM, STEP + VARY-LL, and ONE-2 + VARY). One scenario with
 599 the same soil erosion reduction rate as the ONE-2 scenario was selected as the MM scenario.
 600 Conversely, ~~the~~ LL scenario was ~~set as the one scenario~~ with the lowest NPV and reduction rate,
 601 and ~~the~~ HH scenario ~~as had~~ the highest NPV and reduction rate. Table 3 ~~en~~lists the NPV in the
 602 first year and the detailed investments (including initial and maintenance investments, i.e., the cash
 603 outflow of the NPV) in different years for the selected scenarios.

604 In addition to the similar pattern of the two Pareto fronts under stepwise investment (STEP
 605 + VARY and STEP + FIXED), the ~~generational~~ changes in the hypervolume index ~~with~~
 606 ~~generations~~ for the two optimization experiments also demonstrated similar changing trends
 607 (Figure 98). Although the STEP + VARY hypervolume seemed to first attain stability in the 65th
 608 generation, while STEP + FIXED demonstrated a slowly increasing trend, we believed that they
 609 both had similar evolution characteristics without significant differences in optimization efficiency
 610 under the current experimental settings of the NSGA-II algorithm. The only difference between
 611 the two experiments, ~~which that~~ considered the time-varying effectiveness of ~~a~~ BMP, was the
 612 cause of the overall high hypervolume index of STEP + FIXED, as depicted in Figure 98. This
 613 result could be expected because the experiments with ~~a~~ fixed BMP effectiveness used data from
 614 the fifth year (Table 2), which ~~was had~~ the ~~optimum optimal~~ effectiveness ~~values~~ during the

615 evaluation period of this study. The hypervolume index proved that optimization under stepwise
616 investment could enlarge the solution space and derive better BMP scenarios.

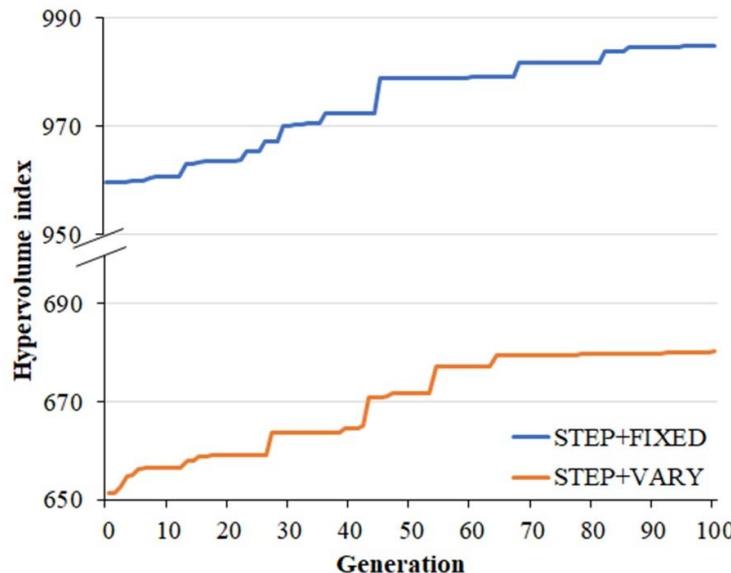
617

618 Table 3. Net present value (NPV) in the first year and detailed investments (including initial and maintenance investments, i.e., the cash
 619 outflow part of the NPV) in different years of selected scenarios (STEP: stepwise investment; ONE- n : one-time investment in the n^{th}
 620 year; FIXED: fixed effectiveness of best management practice [BMP]; VARY: time-varying effectiveness of BMP; LL: low NPV and
 621 low reduction rate of soil erosion; MM: moderate-moderate; HH: high-high)

	ONE-2 + FIXED	STEP + FIXED			ONE-2 + VARY	STEP + VARY		
		LL	MM	HH		LL	MM	HH
NPV (CNY 10,000)	155.09	150.63	151.77	154.80	155.09	150.55	151.39	155.67
Soil erosion reduction rate (%)	6.22	5.67	6.20	6.59	4.11	3.72	4.11	4.56
1 st investment (CNY 10,000)	0.00	55.31	72.80	85.53	0.00	57.94	76.28	88.40
2 nd investment	203.75	67.36	57.35	67.57	203.75	62.77	44.56	69.82
3 rd investment	3.60	31.87	25.53	29.68	3.60	31.86	32.31	33.07
4 th investment	3.60	27.42	28.23	14.56	3.60	28.81	29.32	10.83
5 th investment	3.60	30.63	29.39	17.23	3.60	31.16	30.64	12.80

622

623



624
625 Figure 98. Generational changes in the hypervolume index with generations for two
626 optimization experiments under with stepwise investment (STEP + VARY denotes the
627 optimization using time-varying effectiveness of best management practices [BMPs] and STEP +
628 FIXED using fixed effectiveness).

629

630 4.2 Impact of stepwise investment on BMP implementation plans

631 In our case study, the NPVs of the STEP scenarios did not seem to be significantly reduced
632 lower compared to that of than the ONE-2 scenario (e.g., 151.39 in STEP + VARY-MM compared
633 to 155.09 in ONE-2 + VARY). However, from the perspective of the a project's start-up fund (i.e.,
634 money invested in the first year), the STEP scenarios had apparent advantages. For example, the
635 start-up fund of scenario ONE-1 + VARY was 203.75 (CNY 10,000), while that those of scenarios
636 STEP + VARY-HH and STEP + VARY-LL were only 88.40 and 57.94 (CNY 10,000), with
637 reductions of 56.61% and 71.56%, respectively.

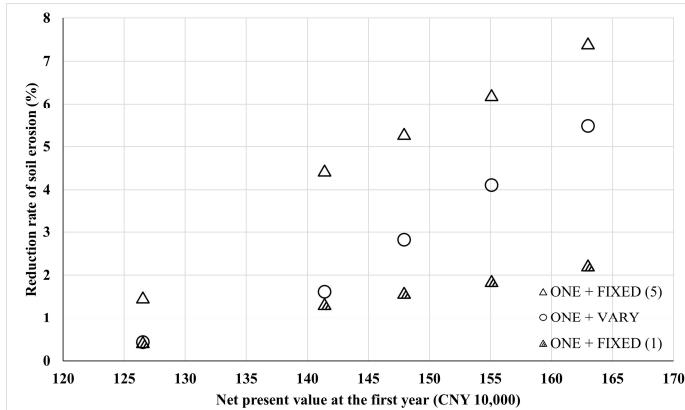
638 From Table 3, we learn shows that the start-up fund has a is positively correlation correlated
639 with the overall environmental effectiveness. The cumulative investments over time decreased
640 from the HH to the MM, and to the then to the LL scenarios. This phenomenon is precisely in
641 accordance consistent with the processes of environmental effectiveness and investment trade-offs.
642 The more and the earlier BMPs are implemented, the higher their environmental effectiveness.
643 The less fewer and the later BMPs are implemented, the lower the NPV will be. Furthermore, from
644 Figure 8b7b, we can observe obvious inflection points at an NPV of approximately 151; that is,
645 as the NPV of the Pareto fronts decreases, the soil erosion reduction rate gradually decreases and
646 declines rapidly declines after the inflection point. This phenomenon may be caused by low
647 investment in the first year (e.g., the 1st investment is less lower than the 2nd investment in the two
648 LL scenarios; Table 3), and as most BMPs are implemented in and after the second year.

649 Therefore, by considering stepwise investments for to optimizing optimize BMP
650 implementation plans, the significantly reduced burden on of start-up funds would undoubtedly
651 improve the flexibility in funding during the entire implementation period. In the meantime, the

652 investments should be made extensively in the first few years (e.g., two or three years in this case
 653 study) to achieve higher environmental effectiveness.

654 4.3 Impact of time-varying effectiveness on BMP implementation plans

655 Two comparisons of the time-varying and fixed effectiveness of BMPs (i.e., STEP +
 656 FIXED vs. STEP + VARY and ONE + FIXED vs. ONE + VARY) demonstrated that under the
 657 same NPV, the reduction rates of soil erosion in the VARY scenarios decreased by approximately
 658 1.6–2.8% in the VARY scenarios (Figure 8a7a). The apparent results are attributed to the
 659 representation of BMP effectiveness data. Inaccurate representation may over- or under-estimate
 660 the overall effectiveness of BMP scenarios, especially in long-term evaluations. Figure 10–9
 661 depicts a comparison between BMP scenarios under one-time investments using a fixed
 662 effectiveness in the first (ONE+FIXED (1)) and the fifth year (ONE+FIXED (5)) and time-varying
 663 effectiveness (Table 2). Figure 10–9 indicates that using reasonable time-varying effectiveness can
 664 appropriately reduce the bias in evaluating the overall effectiveness of the BMP scenario since the
 665 “true” effectiveness of BMPs over time is difficult to measure—precisely measure. Therefore, to
 666 minimize this bias or error as much as possible, researchers are suggested to should periodically
 667 and thoroughly monitor BMP effectiveness data—periodically and thoroughly. Furthermore,
 668 modelers are meanwhile suggested to should reasonably quantify time-varying BMP data and
 669 utilize it in watershed models.



670
 671 Figure 109. Comparison of best management practice (BMP) scenarios under one-time
 672 investments using diverse BMP environmental effectiveness data. ONE + VARY represents the
 673 a BMP scenarios under with a one-time investment using time-varying effectiveness. ONE +
 674 FIXED (1) and ONE + FIXED (5) represent the BMP scenarios under with one-time investments
 675 using a fixed effectiveness in the first and fifth years, respectively.

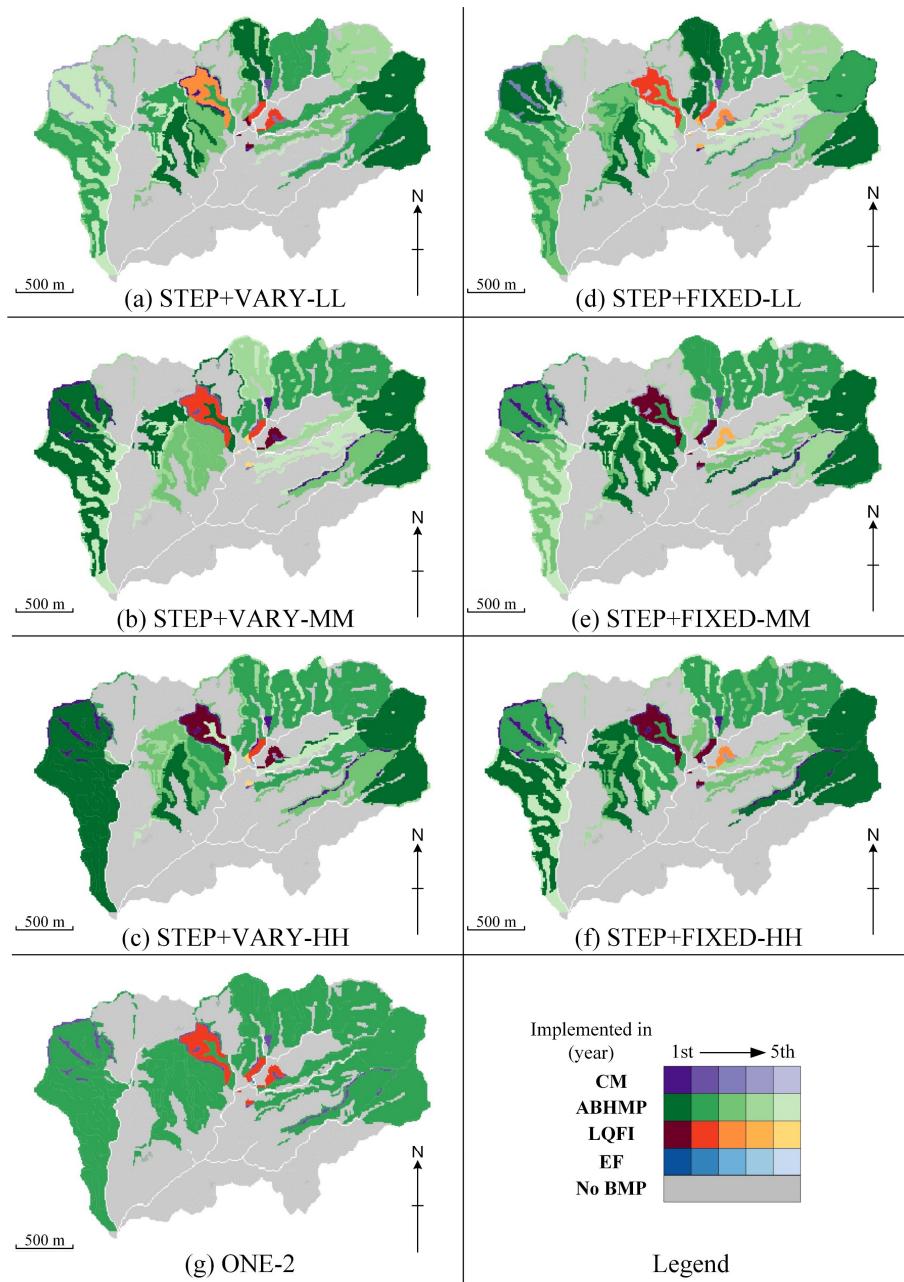
676

677 4.4 Qualitative analysis of the spatio-temporal distribution of selected BMP scenarios

678 Figure 11–10 presents the spatio-temporal distributions of the six selected representative
 679 scenarios from two STEP Pareto fronts and two ONE-2 scenarios. All scenarios have the same
 680 BMP spatial distribution but different implementation times. With the same NPV and
 681 implementation time, the two ONE-2 scenarios achieved a 6.22% soil erosion reduction rate based
 682 on thea fixed effectiveness of BMPs (155.09 NPV, 6.22%) and a soil reduction rate of 4.11%
 683 based on a time-varying effectiveness (Table 3). Figures 11a10a–c demonstrated three
 684 representative scenarios based on thea time-varying effectiveness of BMPs, including STEP +

685 VARY-LL (150.55 NPV, 3.72%), STEP + VARY-MM (151.39 NPV, 4.11%), and STEP +
 686 VARY-HH (155.67 NPV, 4.56%). Figures 44d10d–f demonstrated ~~another~~^{the} three other scenarios
 687 based on ~~the~~^a fixed effectiveness of BMPs, including STEP + FIXED-LL (150.63 NPV, 5.67%),
 688 STEP + FIXED-MM (151.77 NPV, 6.20%), and STEP + FIXED-HH (154.80 NPV, 6.59%).

689



690
 691 Figure 44d10d. Spatio-temporal distributions of the representative best management practice
 692 (BMP) scenarios: (a)–(c) represent scenarios of a low net present value (NPV) with a low soil
 693 erosion reduction rate (LL), a moderate NPV with a moderate reduction rate (MM), and a high
 694 NPV with a high reduction rate (HH) ~~ef~~ⁱⁿ optimization experiments under^{with} stepwise
 695 investment and a fixed BMP effectiveness (STEP + FIXED), respectively; (d)–(f) represent the
 696 corresponding scenarios under a time-varying BMP effectiveness (STEP + VARY); (g)

697 represents the scenarios of both fixed and time-varying BMP effectiveness under a one-time
 698 investment in the second year (ONE-2).
 699

700 **Spatio-temporal**The s**Spatiotemporal** distributions of the optimized BMP scenarios under
 701 stepwise investment exemplified supported the tacit knowledge that the environmental and
 702 economic effectiveness of the BMPs affect the decision-making of BMP-implementation order
 703 decisionss under the specific investment plans. For example, BMPs that require high initial and
 704 maintenance costs but have late returns (e.g., EF) are more likely to be implemented in the mid-
 705 to-late stage when investment burden alleviation is a priority (Figures 44a-10a and 44d10d). BMPs
 706 whichthat have high environmental effectiveness and can take effect quickly (e.g., ABHMP) tend
 707 to be implemented in large areas in the first stage, when focusing more which focuses more on eco-
 708 environmental governance (Figures 44e-10c and 44f10f). Additionally, BMPs whichthat have a
 709 moderate performance in overall effectiveness performance and take effect efficiently quickly
 710 (e.g., CM and EF) have more flexibility to be implemented according to diverse investment plans.
 711 The proposed framework can provide diverse BMP implementation plans as candidates a reference
 712 for decision-makers decision-makers to further screen and reach a consensus, meeting all the
 713 stakeholders' interests.

714

715 4.5 Applicability of the proposed optimization framework

716 Although the proposed simulation-optimization framework was implemented and
 717 demonstrated through an agricultural watershed management problem, it is designed to be a
 718 universal framework that is not related toindependent of BMP types, watershed models,
 719 optimization algorithms, and applied watershed scales. Similar optimization methods and tools
 720 (e.g., the System for Urban Stormwater Treatment and Analysis Integration, SUSTAIN; Lee et al.,
 721 2012) can be improved accordingly, to the proposed idea from referencing the following key
 722 points: (1) incorporating BMP implementation time into the construction of BMP scenarios;that
 723 is, for example, updating BMP selection and placement strategies in the BMP Optimization
 724 program of SUSTAIN; (2) considering dynamic economic indicators (e.g., the NPV is used in this
 725 study) to evaluate the long-term investments;that is, for example, improving the BMP Cost
 726 Estimation of in SUSTAIN; (3) quantifying time-varying BMP effectiveness data throughin
 727 diverse ways, such as by integrating sampled data with theoretical analysis; and (4) modifying
 728 watershed models to support updating time-varying BMP effectiveness data during the simulation
 729 period;that is, for example, the BMP Simulation of in SUSTAIN.

730 The ability to support diverse types of BMPs and watershed scales depends on the specific
 731 implementation of the proposed framework, especially the watershed model. The watershed model
 732 can represent the time-varying effectiveness of the a BMP, which may be quantified by the effect
 733 of the BMP on its governance governing objective or BMP-related geographic variables. The four
 734 BMPs selected in this case study are representative and successful agricultural BMPs in the study
 735 area. Some of them can be regarded as a combination of engineering and non-engineering BMPs,
 736 such as the economic fruit (EF) BMP. The EF BMP requires not only the construction of level
 737 terraces, drainage ditches, storage ditches, and irrigation facilities; but also the plantation of
 738 economic fruit, grasses, and Fabaceae plants (Table 1). Engineering BMPs (also known as
 739 structural BMPs) may have a significantly different time-varying effectiveness from non-
 740 engineering (or non-structural) BMPs. For example, they may take effect immediately after

741 implementation and achieve periodic high effectiveness values over time under maintenance
 742 operations. Therefore, it will be meaningful to consider structural and non-
 743 structuralnonstructural BMPs in practical application cases.

744 It is worth mentioning that the primary concern issues in the spatio-temporal
 745 optimization of BMPs in a large watershed isare the construction of thea watershed model and
 746 the determining determination ofthe appropriate BMP spatial configuration units. The
 747 computational performance of large watershed models may be an important technical issue that
 748 can be essentially resolved by utilizing high-performance computing clusters.
 749

750 5 Conclusions and future work

751 This study proposed a new simulation-optimization framework for the implementation
 752 ordersplan of BMPs by considering two important, realistic factors: the stepwise investment and
 753 time-varying effectiveness of BMPs. The framework was designed based on a widely used spatial
 754 optimization framework that was applied to agricultural and urban BMPs. The proposed
 755 framework extended geographic decision variables to represent the BMP implementation time and
 756 introduced the concept of NPV into thea BMP scenario cost model. It also customized the BMP
 757 knowledge base and watershed model to evaluate the environmental effectiveness of BMP
 758 scenarios using the time-varying effectiveness of BMPs. The exemplified framework
 759 implementation and experimental results demonstrated that optimizations considering stepwise
 760 investment could effectively provide more feasible choices with a lowerless investment burden at
 761 the cost ofwith only a slight loss ofin environmental effectiveness, especially in terms of the
 762 significantly reducedreducing the load pressures on start-up funds compared to those versus of
 763 one-time investments. By accounting for time-varying effectiveness and stepwise investment, the
 764 optimized multi-stage BMP scenarios may better reflect the reality of BMP performancess and costs
 765 over time, providing diverse choices for watershed management-decision-making in watershed
 766 management.

767 The flexibility and extensibility of the proposed framework could make it easy to be
 768 appliedapply to other technical implementations of similar simulation-optimization frameworks.
 769 The essential components in this framework could be implemented by similar functional
 770 techniques to as those implemented in the case study, including multi-objective optimization
 771 algorithms and watershed models. Application-specific data and settings could also be extended
 772 in this framework, including spatial units for BMP configuration, BMP types and knowledge bases
 773 for specific watershed problems, and diverse stepwise investment representations (e.g., range
 774 constraints, even distribution), could also be extended in this framework. Before implementing
 775 undertaking a practical application case, the sources of biases or errors in the proposed framework
 776 must be known and addressedhandled to minimize errors and improve credibility. It is critical to
 777 note that the data and modeling method should be highly accurate in itstheir representation forof
 778 the characteristics of the study area and its environmental problems. From this perspective, biases
 779 or errors ofin this proposed framework may be reduced or avoided by: (1) reasonably describing
 780 the time-varying effectiveness of BMPs based on observational data and modeling their all-sided
 781 effects in watershed models from multiple perspectives; (2) selecting suitable BMPs and
 782 determining their corresponding spatial configuration units and configuration strategies; and (3)
 783 reducing the randomness and calculation errors of multi-objective optimization algorithms by
 784 incorporating expert knowledge in defining the optimization problem.

As this framework is intended to be a universal simulation-optimization framework unrelated that is independent of BMP types, watershed models, optimization algorithms, and applied watershed scales, there are several issues worth studying in the future, including extensive applications and sensitivity analysis. The wide applications may include: (1) improving other existing simulation-optimization frameworks focused on urban BMPs; (2) explicitly considering structural and non-structural BMPs in case studies; and (3) solving BMP optimization problems in large watersheds, and so on. The A sensitivity analysis of the proposed framework and specific implementation could be conducted on three sets of parameters to provide feasible suggestions for practical applications. The first is related to the evaluation of watershed responses to BMP scenarios, including the proper appropriate evaluation period length. Correspondingly, the second parameter set concerns the economic calculation of BMP scenarios, including the discount rate for NPV calculation. The last parameter set is involves the optimization algorithm settings, including crossover and mutation operators, maximum generation number, and population size.

Overall, this study proposed and demonstrated the novel idea of extending the spatial optimization of BMPs to the a spatio-temporal level by considering the stepwise investment, which is a realistic constraint that must be taken into account during decision-making. This study also emphasized the value of integrating physical geographic processes (i.e., watershed responses to various spatio-temporal distributions of BMPs) and anthropogenic influences (i.e., stepwise investment) in the design, implementation, and application of more flexible, robust, and feasible geospatial analysis methods.

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 814 experiments in this study.

816 Open Research

817 The improved SEIMS programs and the prepared data are freely available at Shen & Zhu
 818 (2022)<https://doi.org/10.5281/zenodo.7048969>. The Youwuzhen watershed spatio-temporal
 819 datasets are located in the /SEIMS/data/youwuzhen/data_prepare folder. These include
 820 precipitation and meteorological data, lookup tables, spatial data, and BMP data. Both sets of fixed
 821 BMP and time-varying BMP effectiveness used in the case study are included in the BMP data
 822 (the scenario subfolder).

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