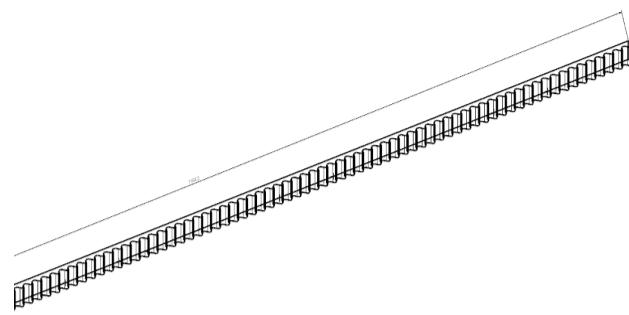


# D3 Specification

1

1 timing belt x3



timing belt

cutter  
ruler

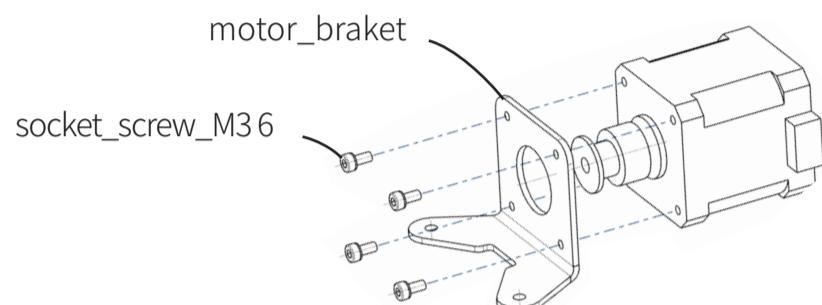
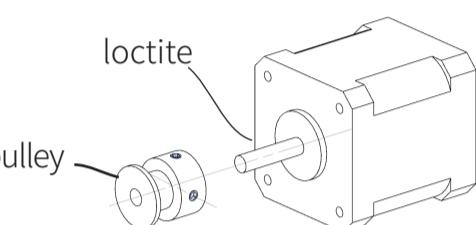
2

2 stepping motor x3

stepping\_motor  
motor\_braket  
pulley  
socket\_screw\_M3\_6

1.5 hex wrench  
2.5 hex wrench

loctite



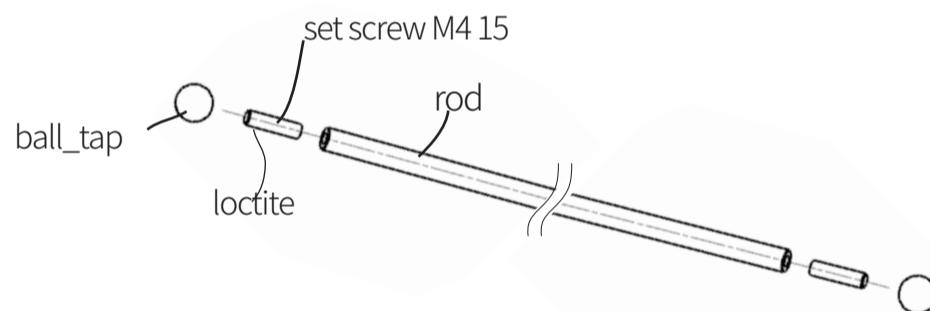
모터 축과 폴리의 체결 부분에 loctite를 적당량 바른 후 소켓 스크루를 체결한다.  
브라켓과 폴리가 체결된 모터를 체결한다.

3

3 rod x6

편심확인방 법 추가

ball\_tap  
rod  
set\_screw\_M4\_15  
loctite

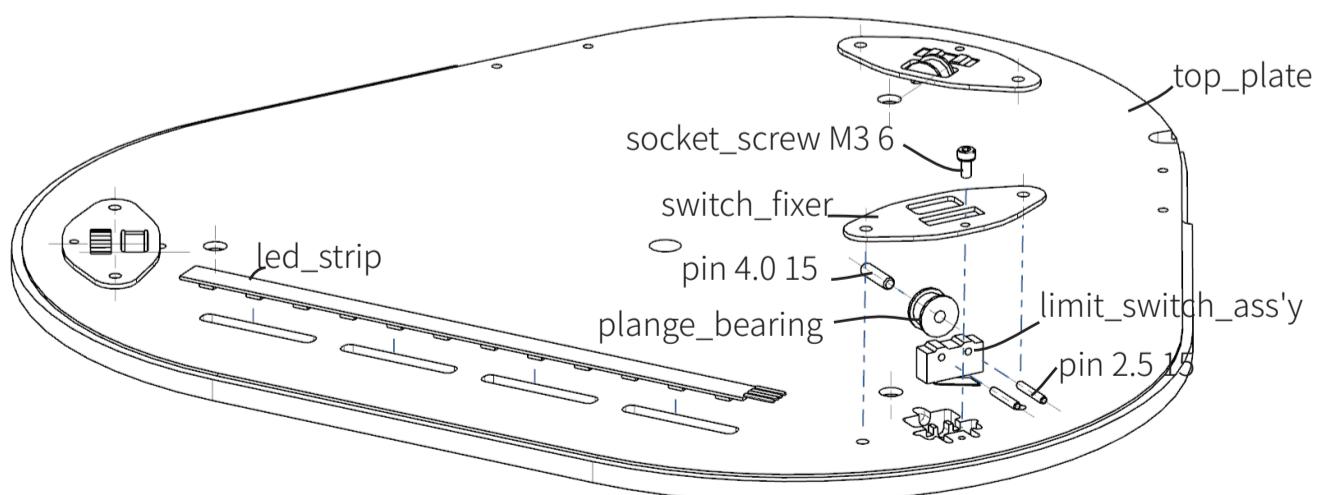


셋 스크루에 록타이트를 적당량 바른후 볼탭을 체결한다.  
로드의 양 끝 단에 체결한다.  
편심을 확인한다.

4

4 top\_plate

top\_plate  
plange\_bearing  
pin 2.5 15  
pin 4.0 15  
led\_strip  
switch\_fixer  
limit\_switch\_ass'y  
socket\_screw M3 6  
2.5 hex wrench  
polyimid\_tape

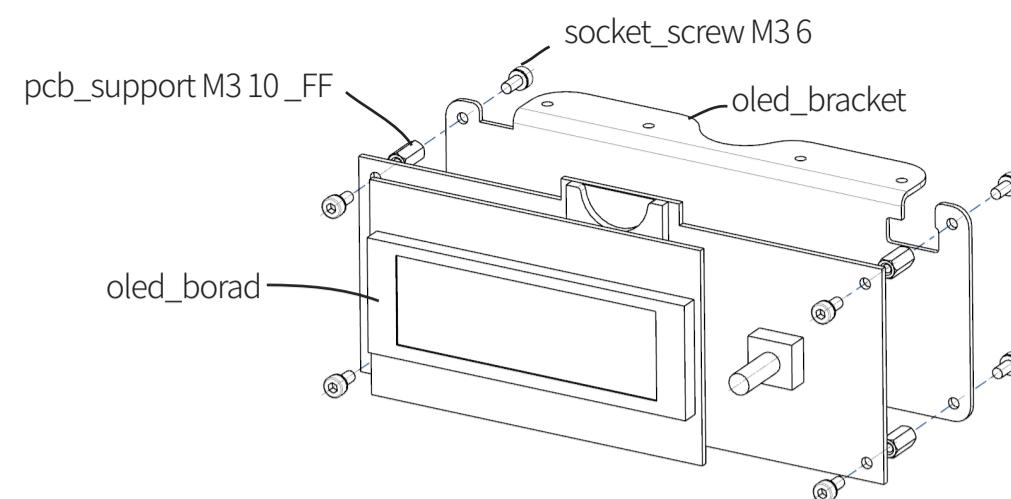


리미트 스위치에 2.5 핀을 끼운다  
플렌지 베어링 두개를 4핀에 끼운다.  
led는 250mm길이의 P.I tape으로 부착한다.

**5** board  
oled\_bracket

pcb\_support M3 10 \_FF  
socket\_screw M3 6

**5** oled

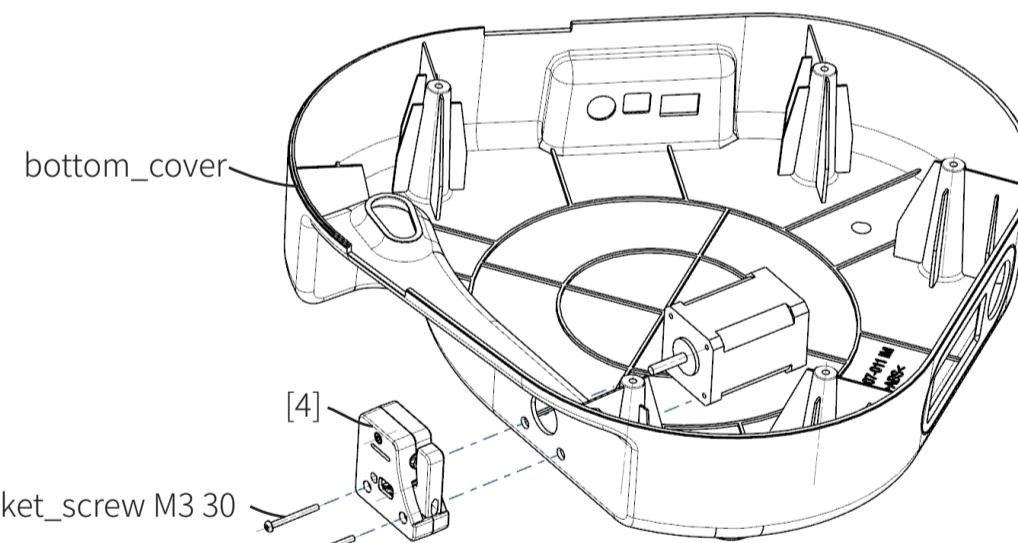
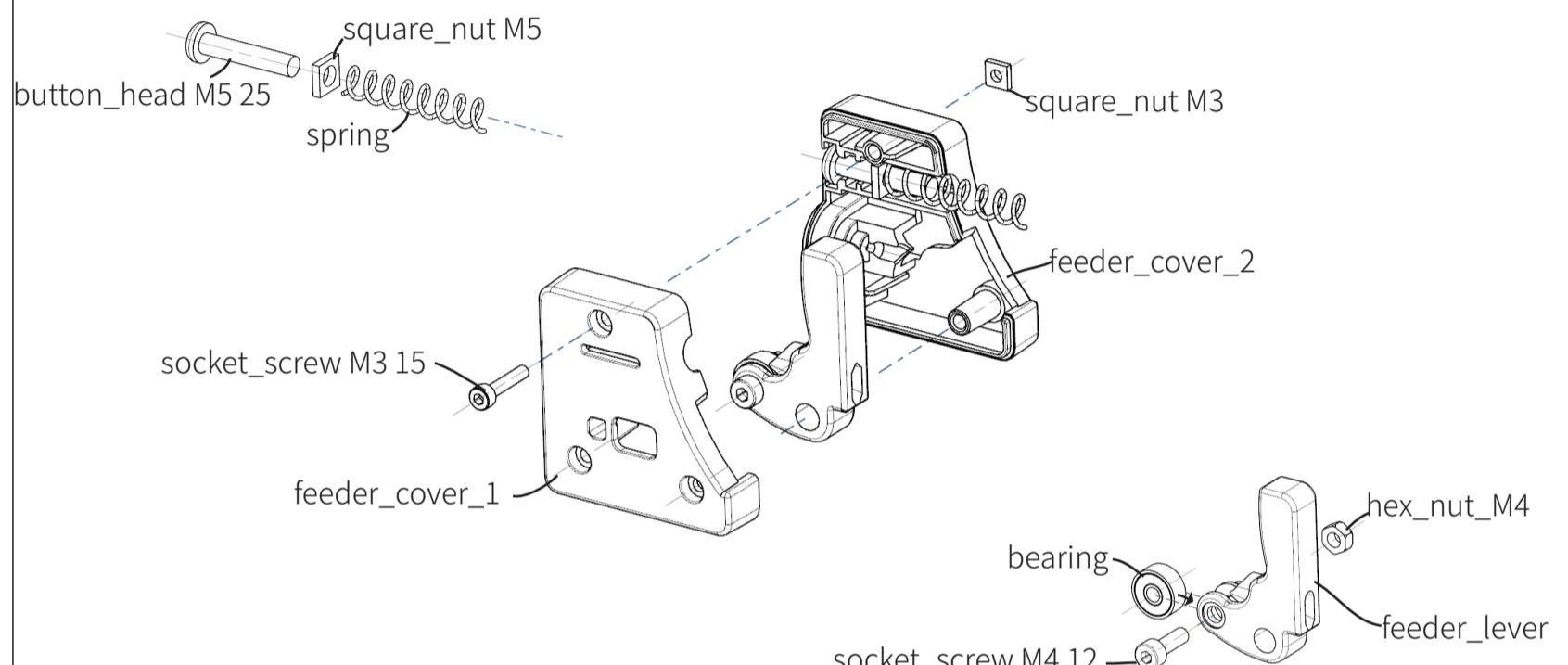


feeder\_cover\_1  
feeder\_cover\_2  
feeder\_lever  
bearing  
spring  
bottom\_cover  
button\_head M5 25  
socket\_screw M4 12  
hex\_nut\_M4  
socket\_screw M3 15  
socket\_screw M3 30  
square\_nut M5  
square\_nut M3  
socket\_screw M3 30

3 hex wrench  
2.5 hex wrench

**6** feeder+bottom\_cover

tube삽입



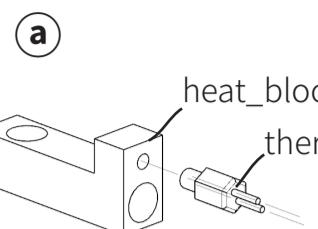
head\_top\_plate  
magnet  
heat\_sink  
disc\_spring  
tefron\_guide  
nozzle  
nozzle\_cap  
heat\_block  
heat\_cartridge\_ass'y  
thermistor\_ass'y  
fan\_ass'y  
cable\_sleeve  
head\_cover  
tube\_clamp  
cable\_tie  
cable\_sleeve  
P.I film

socket\_screw M3 4  
socket\_screw M3 10  
socket\_screw M3 15  
socket\_screw M3 25

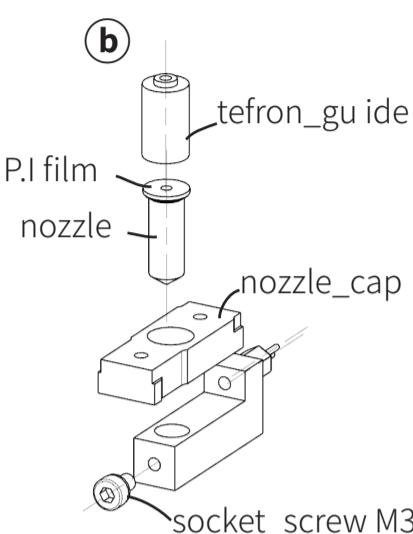
2.5 hex wrench

## 7

## head

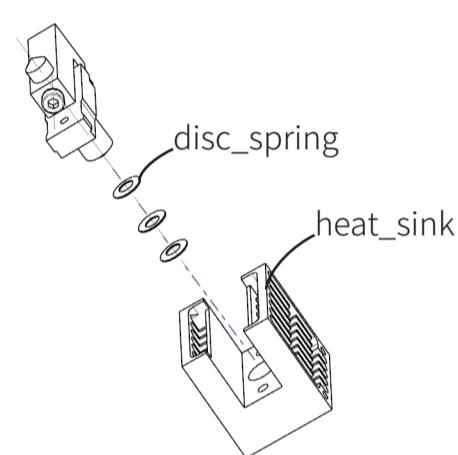


!떠미스터 조립시 케이블 주의

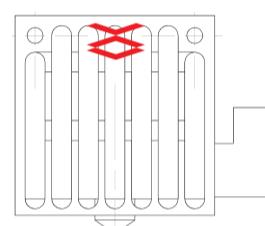


!테프론방향

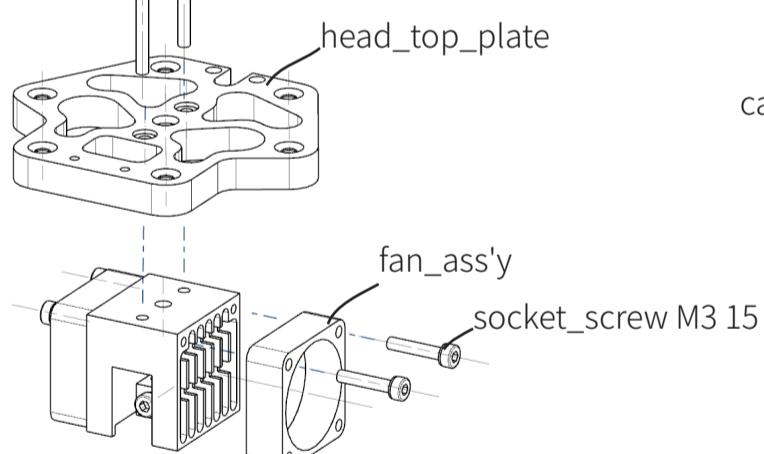
## (c)



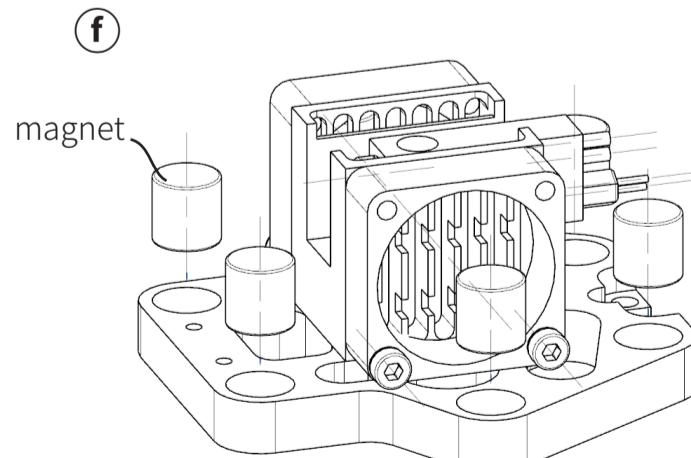
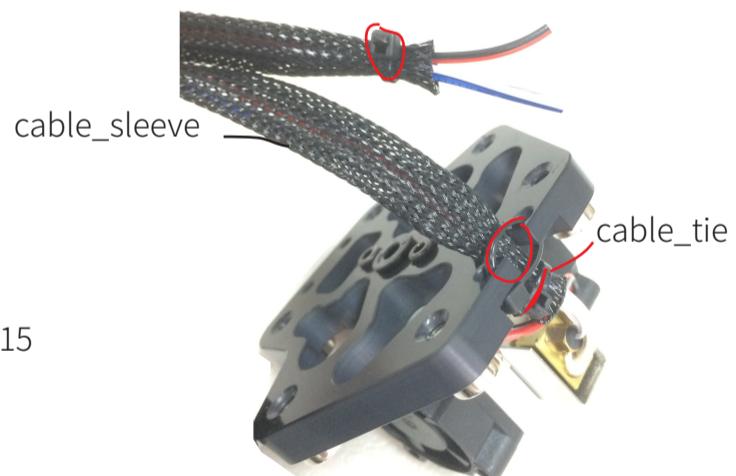
노즐조립 디스크스프링방향



## (d)



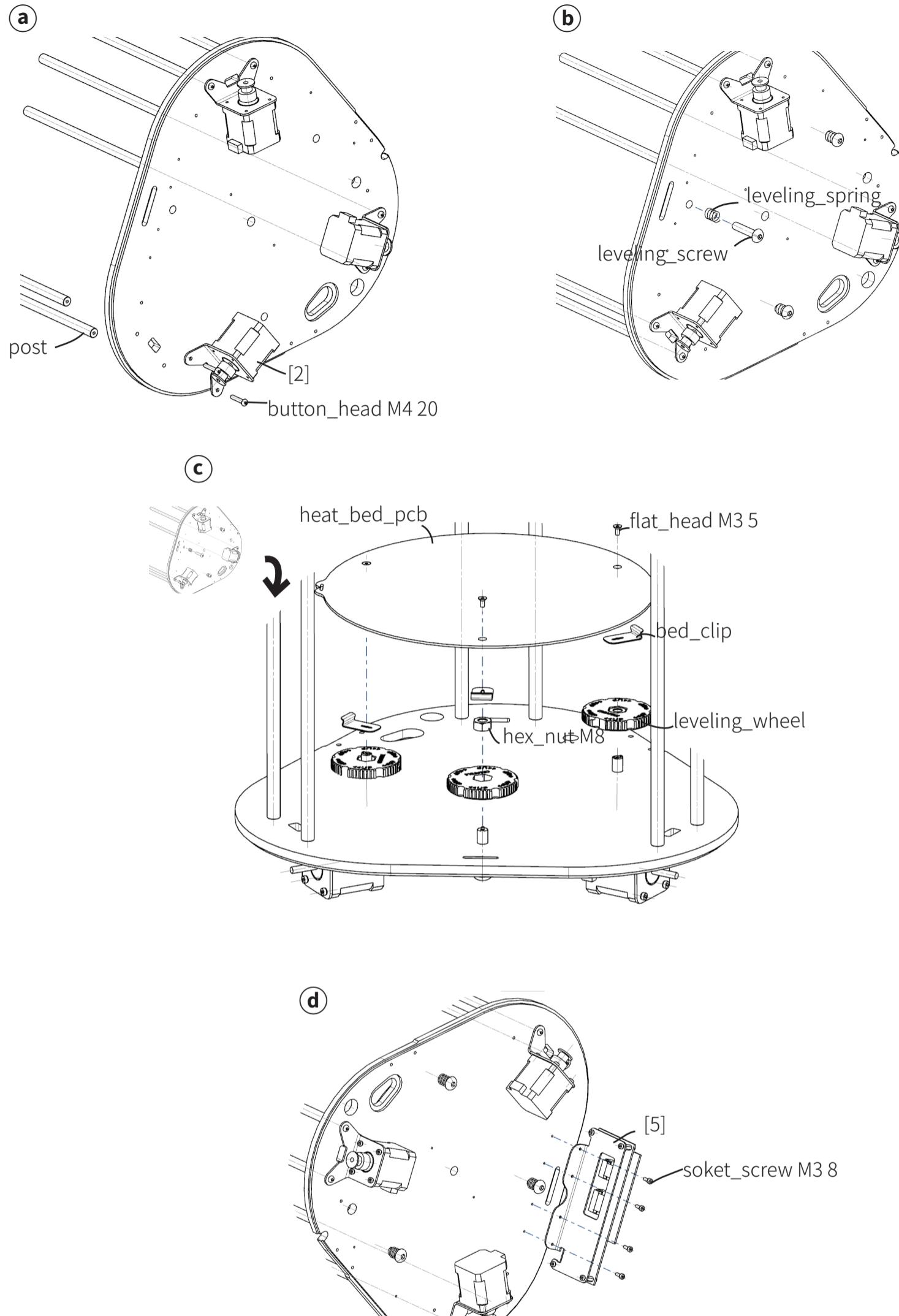
## (e)



(g)(h)매탈 스티커 부착 및 커버 체결.

떠미스터를 고정시키고 히틀록을 돌려 체결한다. (단선의 위험으로 떠미스터 조립의 주의가 필요함)  
노즐의 넓은 부위에 PI필름을 붙인다.  
히싱크에 티스크 스프링을 놓을때는 방향을 참고하여 삽입한다.  
슬리브를 끼울때 떠미스터의 단선에 유의하며 작업한다.

## 8 bottom\_plate



⑥ 과정은 옆으로 누인 채로 수행하며 레벨링스크류를 끼우고 M8 너트와 레벨링 휠을 체결한다.

다시 세워서 베드의 체결을 수행한다.

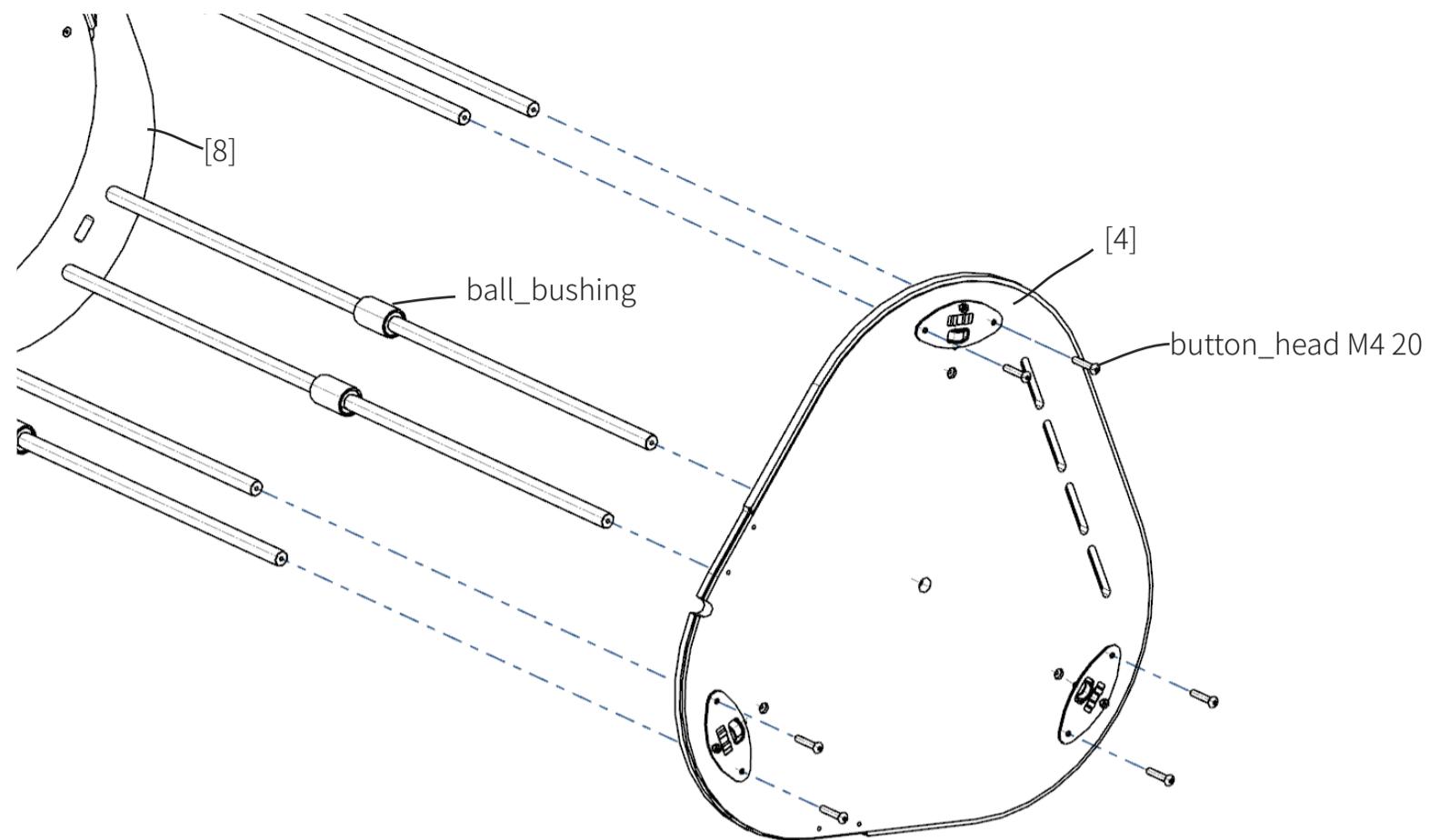
[11]번 과정을 위해 옆으로 누인채로 [6]번을 조립한다.

**9****9**

[4]+[8]

[4]  
[8]  
button\_head M4 20  
ball\_bushing

3 hex wrench

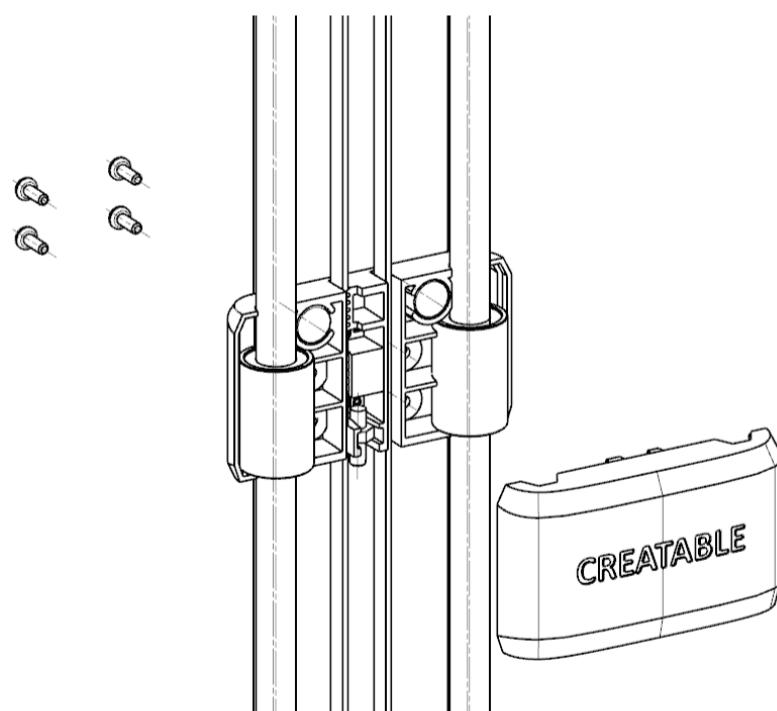


양쪽 플레이트를 결합과 동시에 각각의 포스트에 부싱을 삽입한다.

**10****10**

lift\_block

[9]  
lift\_blk\_front  
lift\_blk\_back  
belt\_fixer  
timing\_belt  
magnet Φ10X10  
ball\_bushing  
BH\_tapping\_screw 3 16  
screwdriver



백커버- 자석- 픽서 순으로 조립한다.

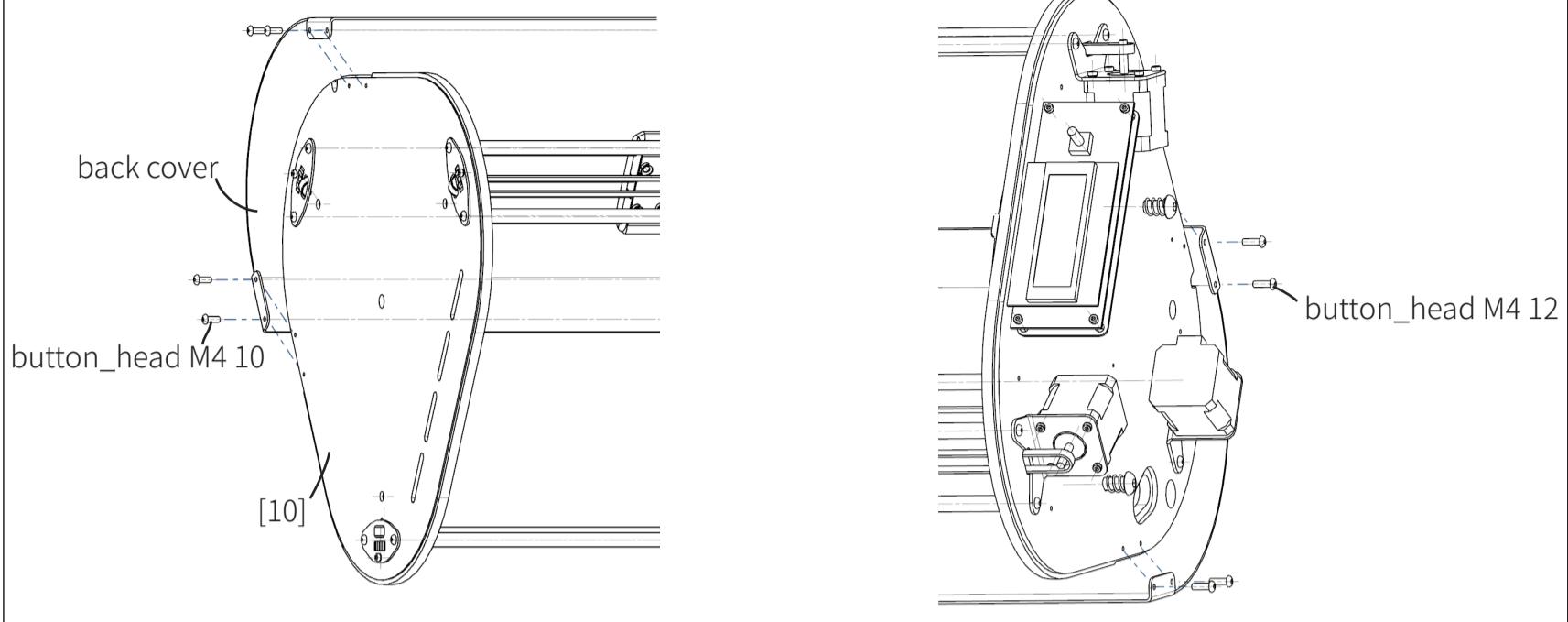
11

11

[10]+back\_cover

[10]  
back cover  
button\_head M4 10  
button\_head M4 12

3 hex wrench



아래와 위의 볼트길이가 다르므로 구분하여 체결한다.

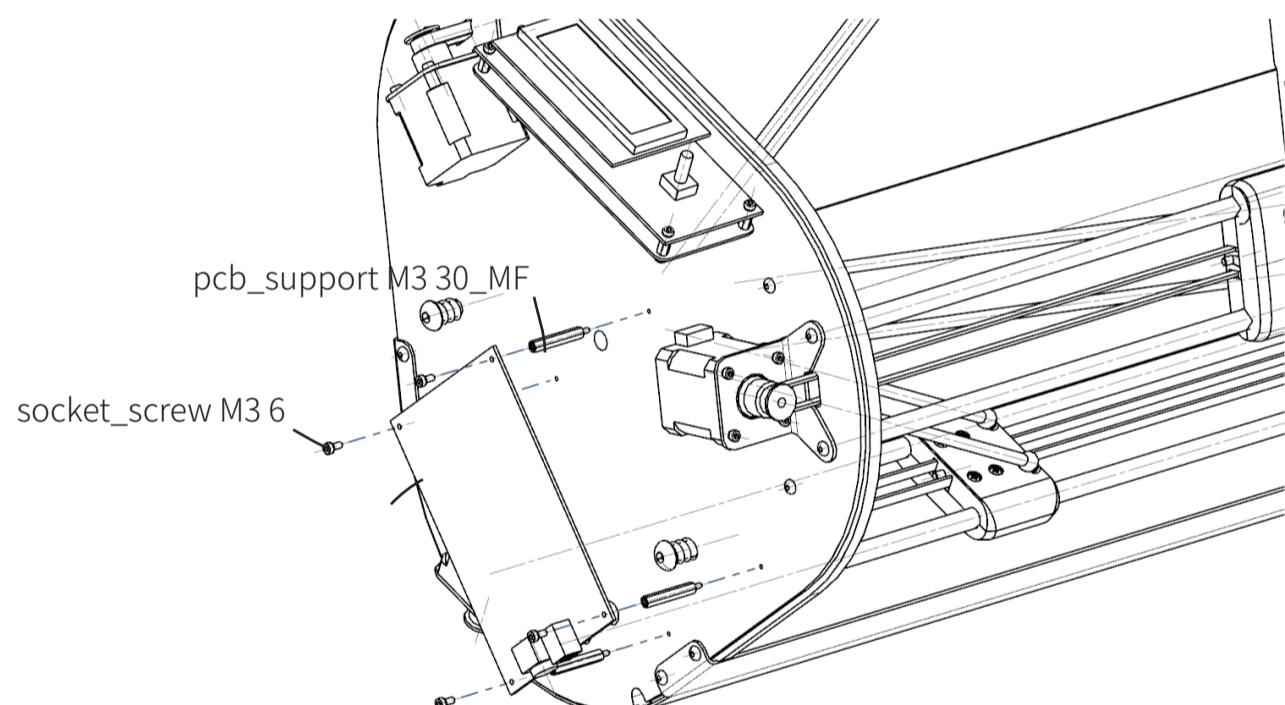
12

12

[11]+main\_board

[11]  
main\_board  
pcb\_support M3 30\_MF  
socket\_screw M3 6

2.5 hex wrench



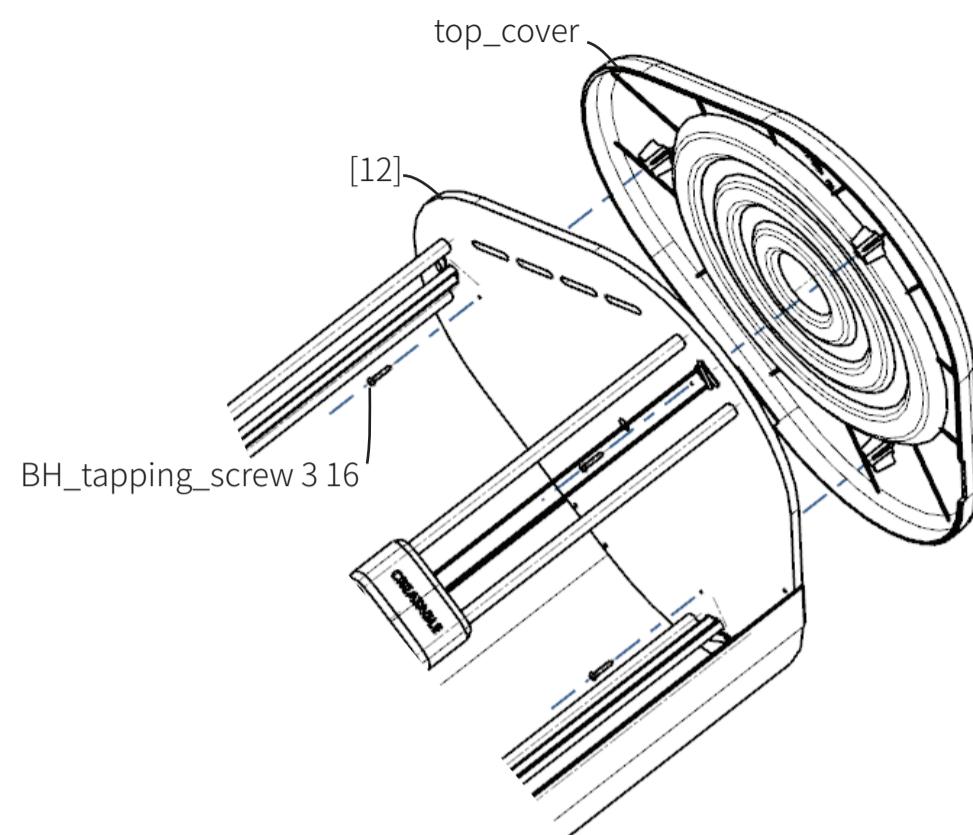
케이블 정리

**13****13**

[12]+top\_cover

[12]  
top\_cover  
BH\_tapping\_screw 3 16

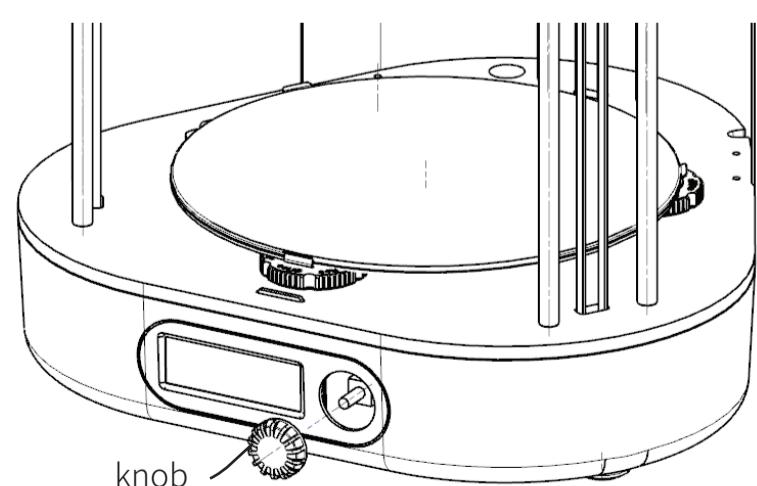
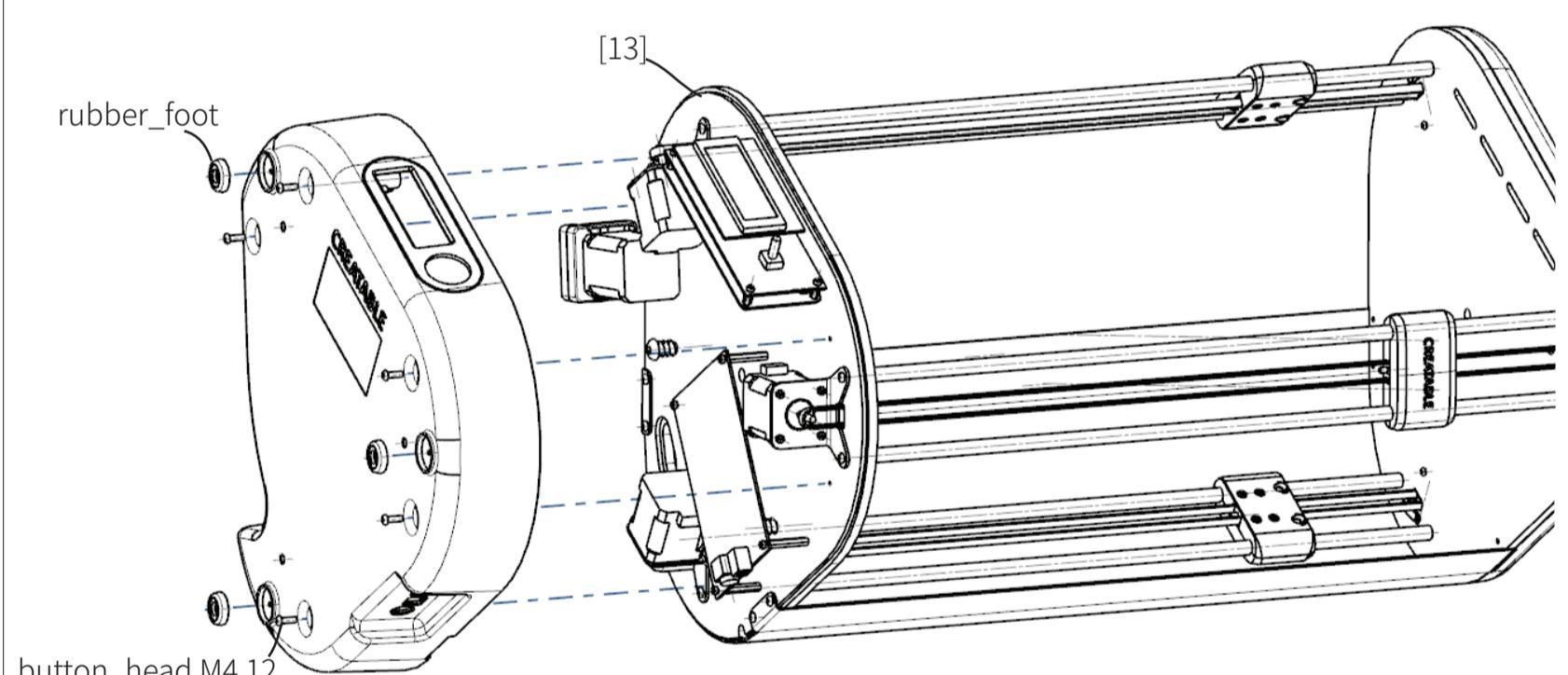
Phillips head screwdriver

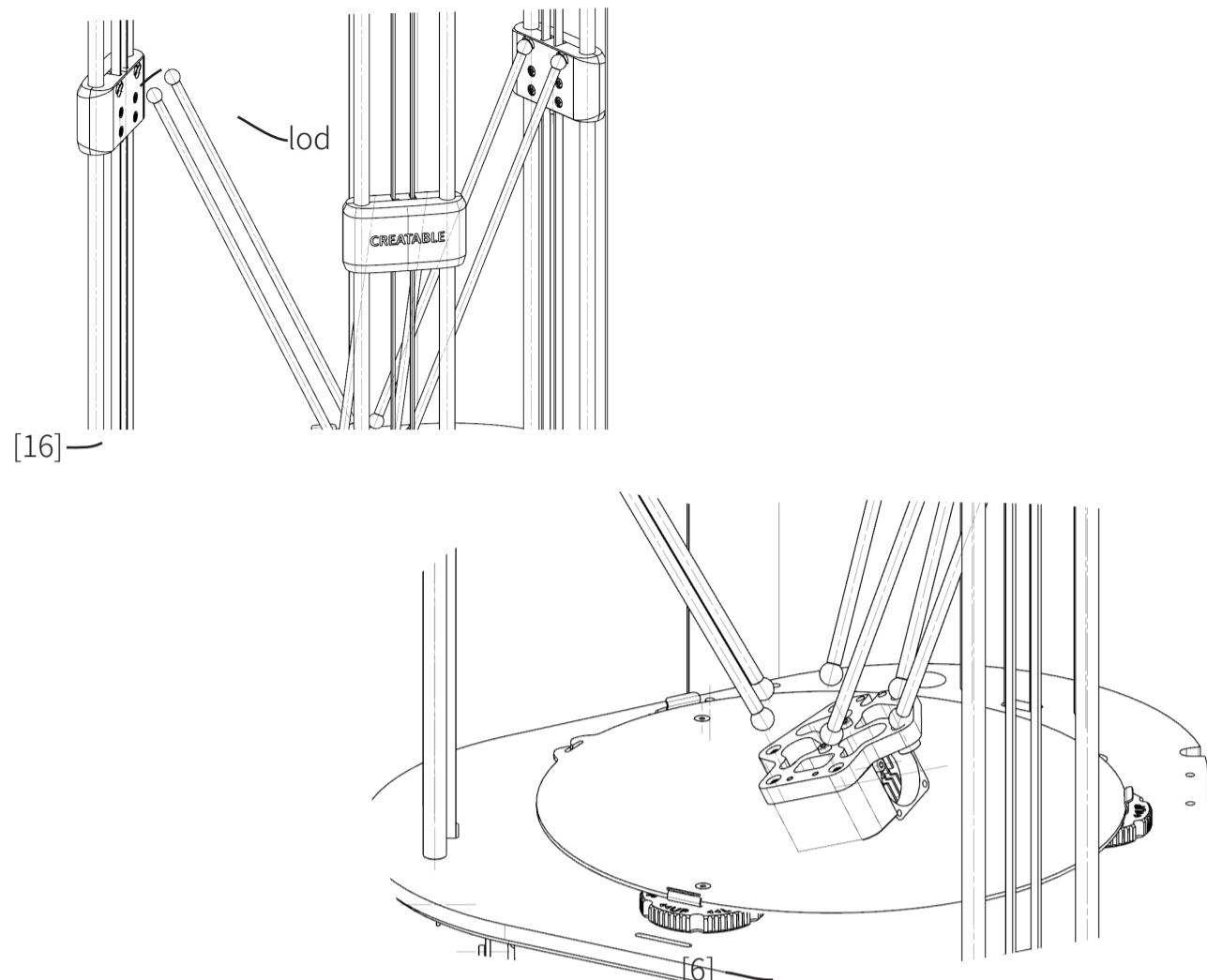
**14****14**

[13]+[4]

[4]  
[13]  
rubber\_foot  
knob  
button\_head M4 12

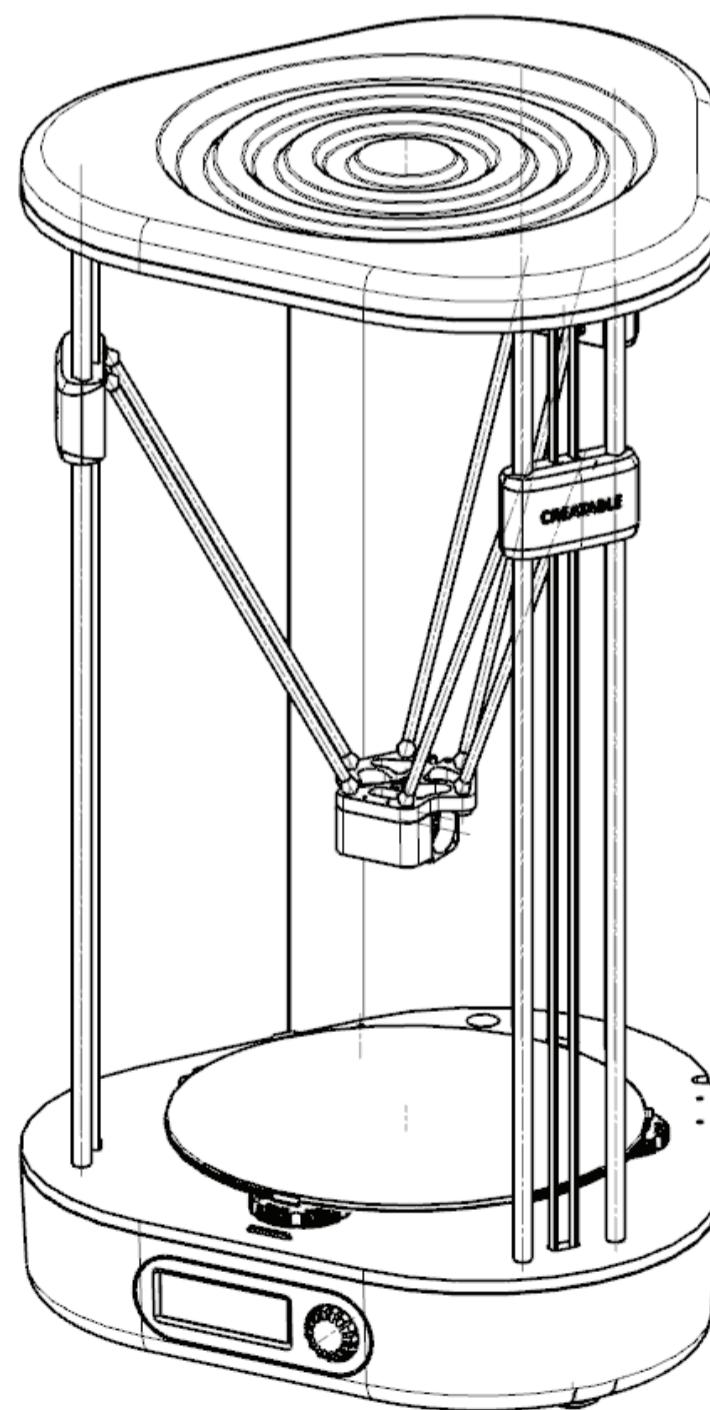
2.5 hex wrench



[16]  
lod  
[7]

튜브 클램프에 픽서를 끼운 다음에 튜브를 넣는다.`

com



**9**

**9**

7+8

7  
8

3 hex wrench

button\_head M4 20  
ball\_bushing