

---

# Coevo: a collaborative design platform with artificial agents

## Gerard Serra

GTM-Grup de recerca en Tecnologies Mèdia,  
La Salle-Universitat Ramon Llull  
Barcelona, Spain  
gerard.serra@salle.url.edu

## David Miralles

GTM-Grup de recerca en Tecnologies Mèdia,  
La Salle-Universitat Ramon Llull  
Barcelona, Spain  
david.miralles@salle.url.edu

## ABSTRACT

We present Coevo, an online platform that allows both humans and artificial agents to design shapes that solve different tasks. Our goal is to explore common shared design tools that can be used by humans and artificial agents in a context of creation. This approach can provide a better knowledge transfer and interaction with artificial agents since a common language of design is defined. In this paper, we outline the main components of this platform and discuss the definition of a human-centered language to enhance human-AI collaboration in co-creation scenarios.

## CCS CONCEPTS

• **Human-centered computing** → **Human computer interaction (HCI)**; • **Computing methodologies** → **Artificial intelligence**; *Bio-inspired approaches*;

## KEYWORDS

human computer collaboration, creativity, collaborative design, design computation, computational creativity, evolutionary computing

---

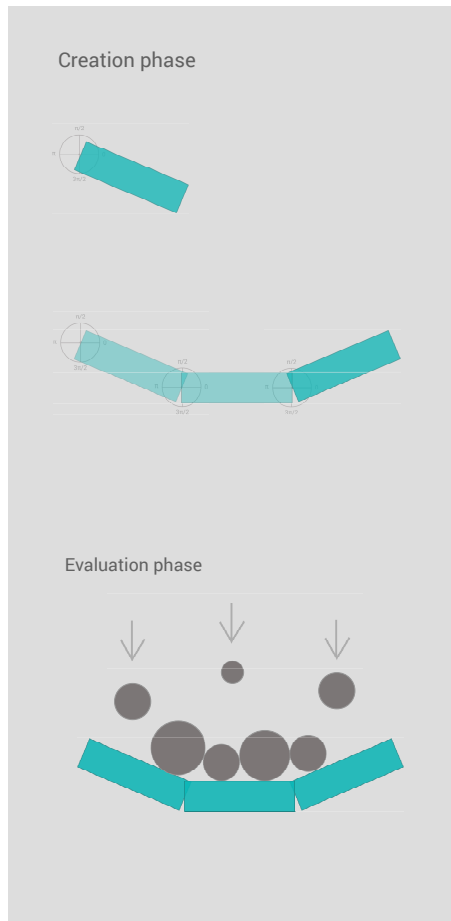
Permission to make digital or hard copies of all or part of this work for personal or classroom use is granted without fee provided that copies are not made or distributed for profit or commercial advantage and that copies bear this notice and the full citation on the first page. Copyrights for components of this work owned by others than ACM must be honored. Abstracting with credit is permitted. To copy otherwise, or republish, to post on servers or to redistribute to lists, requires prior specific permission and/or a fee. Request permissions from [permissions@acm.org](mailto:permissions@acm.org).

*CHI 2019, May 4–9, 2019, Glasgow, Scotland UK*

© 2019 Association for Computing Machinery.

ACM ISBN 978-1-4503-5970-2/19/05...\$15.00

<https://doi.org/10.1145/XXXXXX.XXXXXX>



**Figure 1: 2D shape emerges by combining multiple 2D pieces. This example illustrates the creation of a bowl in our environment**

## INTRODUCTION

Recent advances on Artificial Intelligence (AI) techniques have popularized their usage on a large number of applications. Specially on design and creative processes AI has emerged to support human design and creativity [1] [2] [3]. As stated on [4], the next step in this field is machine creativity in order to augment human capabilities on problem solving. Specially, in the design process, [5] proposed a computational and cognitive model assuming two parallel search spaces: the problem space and the solution space. Then an iterative process of search and evaluation within both spaces can allow to continually explore design possibilities.

To address this topic, evolutionary computing [6] has been demonstrated as a powerful tool to explore solution space and generate valid proposals [7] [8] [9]. Many computational tools are been used to support human via generating or optimizing design solutions [10] [11] [12]. However, interaction with these systems is often based on providing some inputs and receiving output solutions generated by the system. This differs with human design process on which there is an inherent learning. A design process influences on perception and knowledge acquisition due to the exploration of possible designs and the relationships with their context [13]. Then, in a context of AI-human collaboration, this knowledge is lost if AI systems reasoning is not well-communicated and understood by humans.

Following this idea, other research lines seek a more interactive and intelligible collaboration in this context of creation [14] [15]. We highlight the work presented by [16] where a human designer collaborates with multiple artificial agents to co-design a game level. We consider that in order to support humans in a creative context, it is crucial to explore techniques that enable better knowledge transfer between humans and artificial agents during the whole process of designing rather than only receiving final outputs given by AI systems.

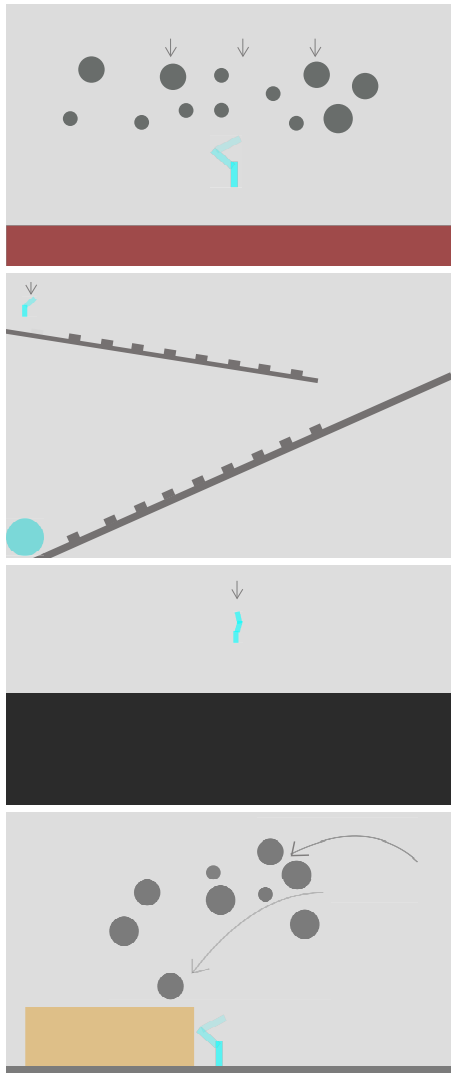
In this paper, as a first step, in order to explore this AI-human collaboration, we propose an environment where both artificial agents and humans can learn to design solutions for an specific problem.

## CONCEPT DESIGN

In Coevo, we have defined a shared environment for both artificial agents and humans. There, we propose a common set of creation tools establishing the same language of design and common evaluation criteria on design proposals. This approach can benefit knowledge transfer since all the actions taken during the process of creation can be interpreted.

### Interactive tools

As shown on Figure 1, design proposals are composed by a set of 2D bricks assembled together as a continuous chain that generates a 2D shape. Our interaction model is based on manipulating this



**Figure 2: Design challenges.** From top to bottom: Collect falling balls; Move to certain point; Cut through a dense medium (dark area); Protect orange area

common set of simple building blocks that, when combined together, a more complex structure can emerge. These structures are created by addition and subtraction of blocks and via rotating them in any direction defining the direction. This set of actions to be performed is the same for both artificial agents and humans. Moreover, all the actions taken during the process of creation are saved. This enables to access and visualize not only the final proposals but also all the design process until arriving to a certain final decision.

### Environments

In order to allow wider audiences to interact with our proposal we decided to create an online platform. There, users can generate their design proposals in our collection of environments. These environments are based on Javascript [17] libraries p5.js and matter.js [18] combined together to generate an interactive web interface with capabilities to run 2D rigid body physics. As show on Figure 2, a total of four design challenges have been defined: collect, move, cut and protect. For each challenge, an environment with initial design conditions is generated, involving positioning of the elements and design proposal and their physical behavior. In addition, an objective definition is set in order to measure design performance.

When human or artificial agent propose a design, the system will place it on the environment and evaluate it regarding each objective definition. Then it returns a score from 0 to 1 to quantify the overall performance within that experiment based on each specific goal definition.

Similar to other research projects and benchmarks [19] [20] [21], by evaluating within the same conditions an agent behaviour we can directly compare their performance with humans one. Since our platform provides a quantitative score based on design performance, an incremental learning process can be defined. Designers will be encouraged to obtain output solutions with their higher score associated. Same goes for our algorithm that by receiving the scores of the generated proposals it will seek to maximize its final score.

Apart from that, given a certain challenge there is the possibility that many different solutions are valid. A richer solution space will emerge when several valid proposals appear, so we want to maximize it.

Moreover, since the creation tools are common, at any point of the process we can visualize the experiments and understand how a proposal is constructed. This can allow editing in any step and enable capabilities to retake the experiments.

### Artificial agent definition

We want to explore how multiple proposals can emerge given a specific design challenge. For that reason, our algorithm starts designing from scratch rather than using labeled data with possible solutions to train our system. Following this approach, we propose to use a general common algorithm



**Figure 3: Gallery of AI generated designs. In a design problem such as "Create an object that moves on a inclined plane" we can observe multiple solutions that differ of the common solution in that context: the wheel**

for all the experiments. We decided to create a population-based optimization algorithm that learns using the scores obtained when system evaluates each design proposal.

In contrast to many design optimization techniques, we propose an interactive process allowing users to visualize all the steps in the optimization. Moreover, since the design tools are the same, we potentially allow users to contribute at any point of the optimization, fine-tuning any piece that composes the 2D shape and continue the learning process without relaunching the experiment. This also helps to increase system transparency which becomes more explainable to humans during the whole process (the opposite of a black box algorithm). We can measure intelligibility of an artificial system with possible interactions and potential contributions that an user can do in any step of its learning process.

Finally, as described in [4], population-based algorithms can explore wider solution spaces and potentially propose novel designs. These unexpected proposals can inspire creators with new approaches to solve a defined problem and augment their capabilities on designing by expanding their vision on a possible solution space [7]. As an example, in Figure 3 we expose valid solutions generated by our algorithm when given the task to create an object that moves through an inclined plane.

## DISCUSSION AND FUTURE WORK

In this paper, we discussed how a common environment and tools can support user understanding of artificial agents decisions and enable collaborations within a full process of design.

In particular, we presented a proof-of-concept scenario where both artificial agents and humans create 2D shapes to perform a certain task in multiple physically simulated environment. Building complex structures with minimal elements (2D pieces) and the usage of simple actions (rotate/add/remove) allows a wide range of creation possibilities. Moreover, common creation tools allow better knowledge transfer, compare proposals and explore on new designs. Population-based optimization algorithms also help on maximizing the exploration of the solution space. This exploration provides not only variants of similar designs but also sometimes radically novel proposals. This new knowledge can help to augment human design capabilities and offers a broader view of the problem and the solution space.

Finally, we consider that our proposal opens a new space to explore future scenarios of co-designing with artificial agents encouraging wider audiences to interact and design with AI .

## ACKNOWLEDGMENTS

This work has been partially funded with the support of the European Social Fund and the Secretaria d'Universitats i Recerca del Departament d'Economia i Coneixement of the Catalan Government for the pre-doctoral the pre-doctoral FI grant No. 2018FI\_01052.

## REFERENCES

- [1] David Ha and Douglas Eck. A neural representation of sketch drawings. *arXiv preprint arXiv:1704.03477*, 2017.
- [2] Adam Roberts, Jesse Engel, Colin Raffel, Curtis Hawthorne, and Douglas Eck. A hierarchical latent vector model for learning long-term structure in music. *arXiv preprint arXiv:1803.05428*, 2018.
- [3] Cristóbal Valenzuela, Alejandro Matamala, and Anastasis Germanidis. Runway: Adding artificial intelligence capabilities to design and creative platforms.
- [4] Risto Miikkulainen. Creative ai through evolutionary computation. *arXiv preprint arXiv:1901.03775*, 2019.
- [5] Mary Maher and Hsien-Hui Tang. Co-evolution as a computational and cognitive model of design. *Research in Engineering Design*, 14(1):47–64, 2003.
- [6] Agoston E Eiben, James E Smith, et al. *Introduction to evolutionary computing*, volume 53. Springer, 2003.
- [7] Joel Lehman, Jeff Clune, Dusan Misevic, Christoph Adami, Julie Beaulieu, Peter J Bentley, Samuel Bernard, Guillaume Belson, David M Bryson, Nick Cheney, et al. The surprising creativity of digital evolution: A collection of anecdotes from the evolutionary computation and artificial life research communities. *arXiv preprint arXiv:1803.03453*, 2018.
- [8] Hod Lipson and Jordan B Pollack. Automatic design and manufacture of robotic lifeforms. *Nature*, 406(6799):974, 2000.
- [9] Antoine Cully, Jeff Clune, Danesh Tarapore, and Jean-Baptiste Mouret. Robots that can adapt like animals. *Nature*, 521(7553):503, 2015.
- [10] Peter Bentley. *Evolutionary design by computers*. Morgan Kaufmann, 1999.
- [11] Rubaiat Habib Kazi, Tovi Grossman, Hyunmin Cheong, Ali Hashemi, and George W Fitzmaurice. Dreamsketch: Early stage 3d design explorations with sketching and generative design. In *UIST*, pages 401–414, 2017.
- [12] MOTHERSILL Philippa and BOVE V Michael. An ontology of computational tools for design activities.
- [13] John S Gero. Creativity, emergence and evolution in design. *Knowledge-Based Systems*, 9(7):435–448, 1996.
- [14] Jerry Alan Fails and Dan R Olsen Jr. Interactive machine learning. In *Proceedings of the 8th international conference on Intelligent user interfaces*, pages 39–45. ACM, 2003.
- [15] Changhoon Oh, Jungwoo Song, Jinhan Choi, Seonghyeon Kim, Sungwoo Lee, and Bongwon Suh. I lead, you help but only with enough details: Understanding user experience of co-creation with artificial intelligence. In *Proceedings of the 2018 CHI Conference on Human Factors in Computing Systems*, page 649. ACM, 2018.
- [16] Matthew Guzdial, Nicholas Liao, Jonathan Chen, Shao-Yu Chen, Shukan Shah, Vishwa Shah, Joshua Reno, Gillian Smith, and Mark Riedl. Friend, collaborator, student, manager: How design of an ai-driven game level editor affects creators. *arXiv preprint arXiv:1901.06417*, 2019.
- [17] David Flanagan. *JavaScript: the definitive guide*. " O'Reilly Media, Inc.", 2006.
- [18] Lauren McCarthy. p5.js.(2017). Retrieved September, 18:2017, 2017.
- [19] Marc G Bellemare, Yavar Naddaf, Joel Veness, and Michael Bowling. The arcade learning environment: An evaluation platform for general agents. *Journal of Artificial Intelligence Research*, 47:253–279, 2013.
- [20] Volodymyr Mnih, Koray Kavukcuoglu, David Silver, Andrei A Rusu, Joel Veness, Marc G Bellemare, Alex Graves, Martin Riedmiller, Andreas K Fidjeland, Georg Ostrovski, et al. Human-level control through deep reinforcement learning. *Nature*, 518(7540):529, 2015.
- [21] Greg Brockman, Vicki Cheung, Ludwig Pettersson, Jonas Schneider, John Schulman, Jie Tang, and Wojciech Zaremba. Openai gym. *arXiv preprint arXiv:1606.01540*, 2016.