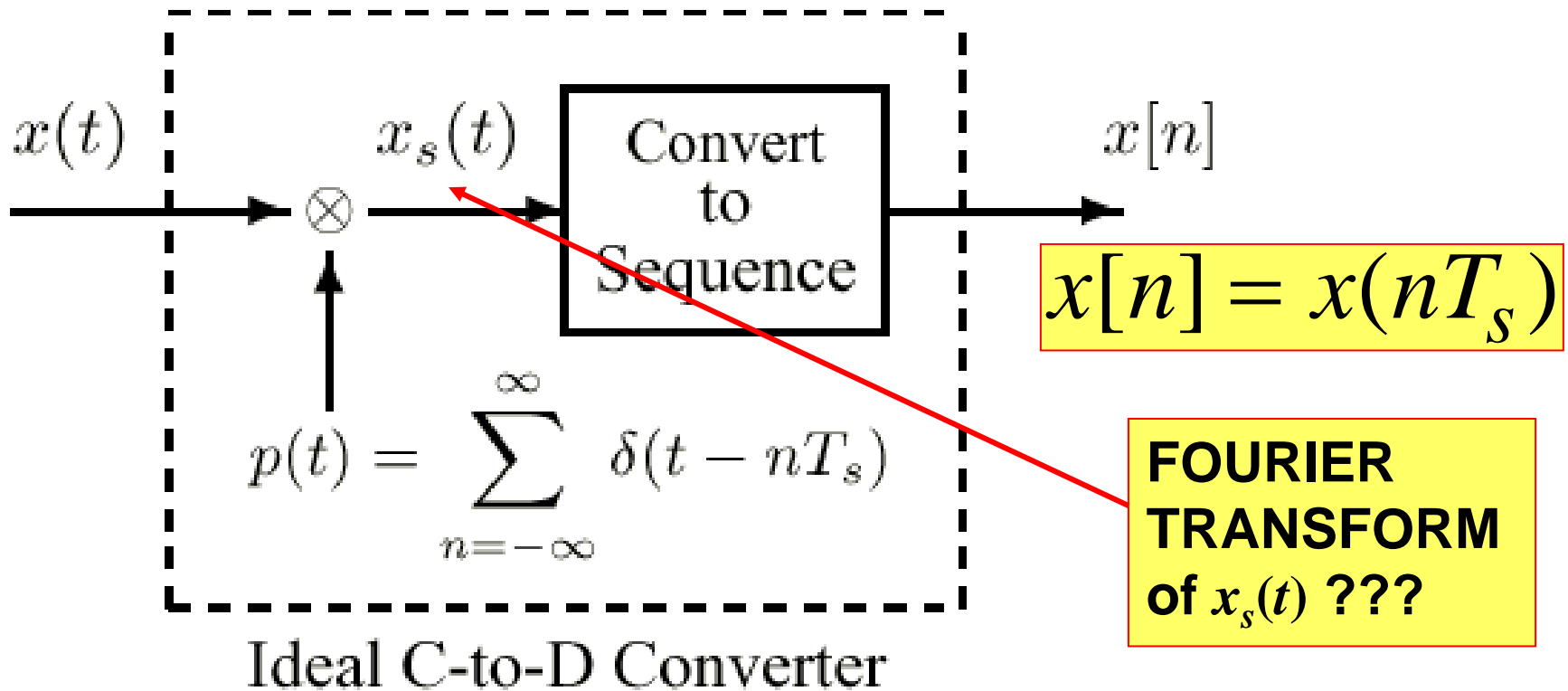


Chapter 12

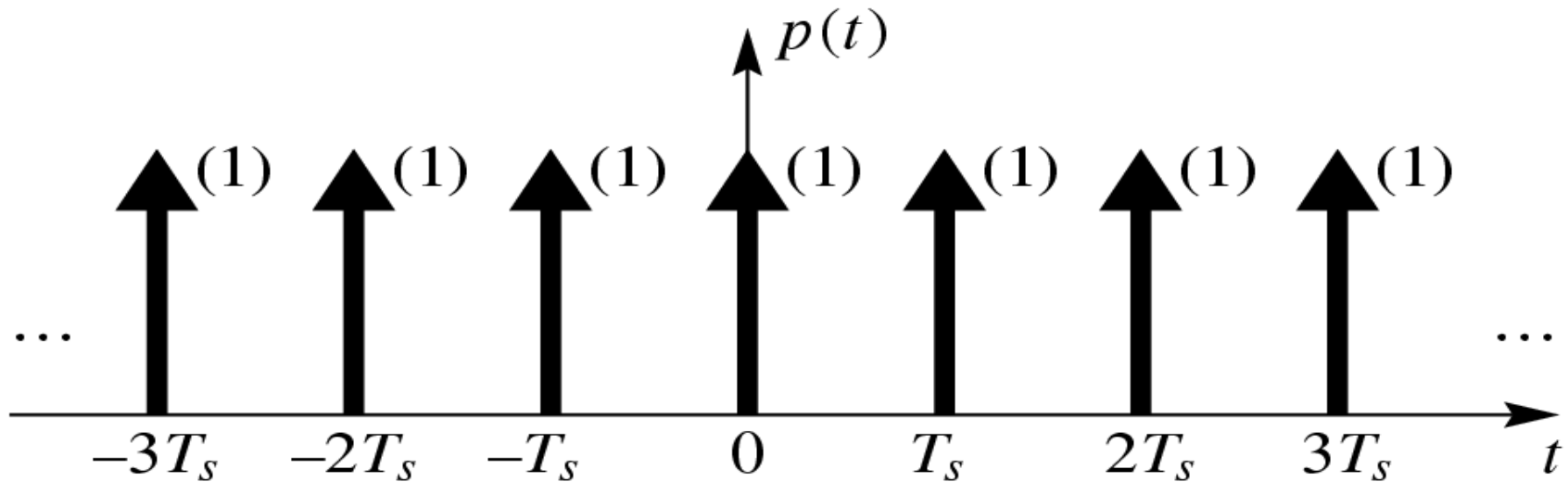
Filtering, Modulation, and Sampling

Ideal C-to-D Converter

- Mathematical Model for A-to-D



Periodic Impulse Train



$$p(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT_s) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_s t}$$

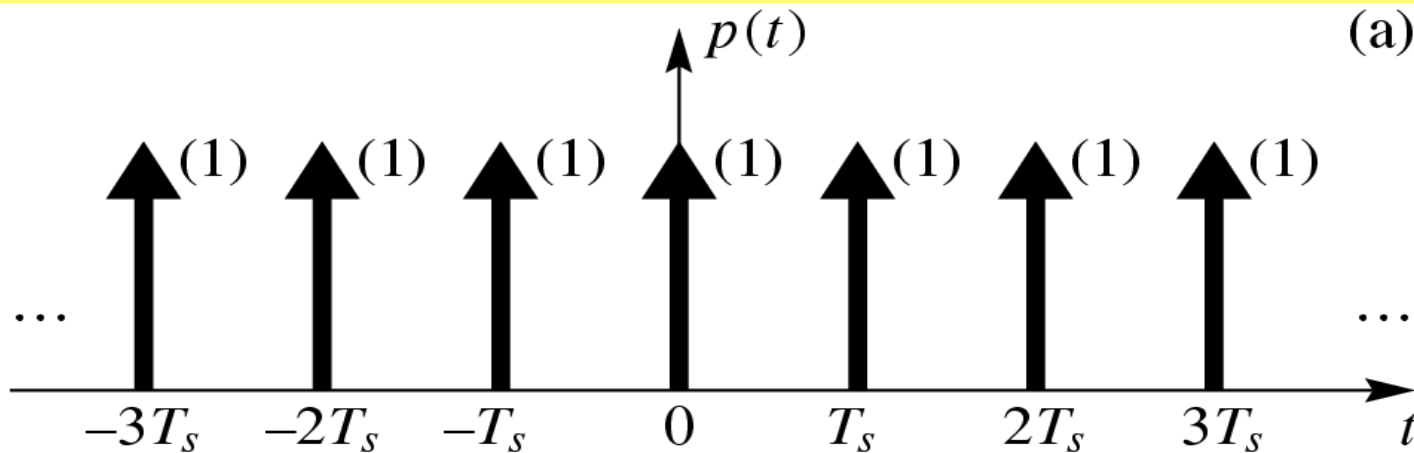
$$\omega_s = \frac{2\pi}{T_s}$$

$$a_k = \frac{1}{T_s} \int_{-T_s/2}^{T_s/2} \delta(t) e^{-jk\omega_s t} dt = \frac{1}{T_s}$$

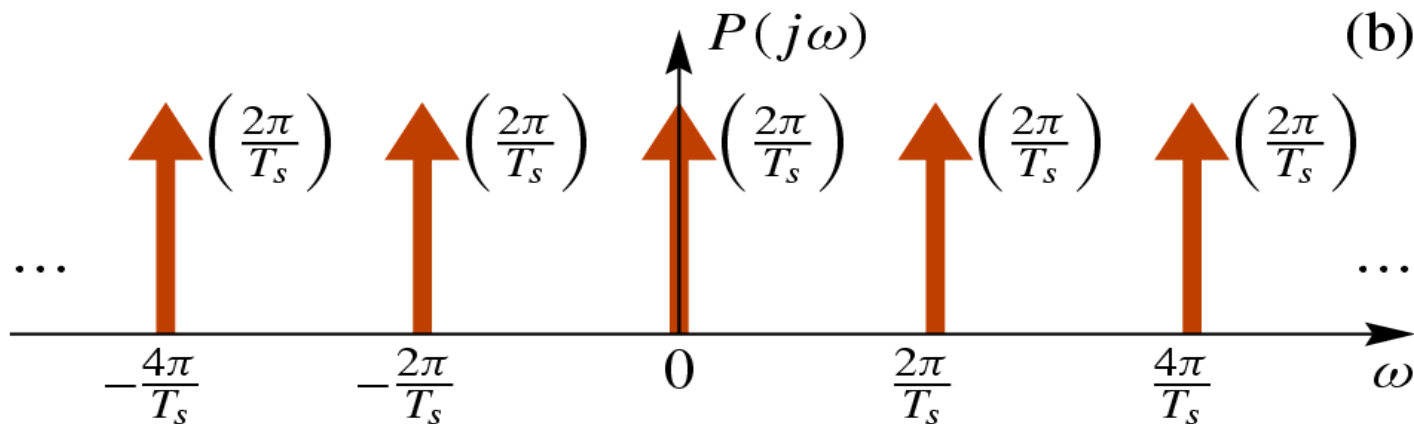
Fourier Series

FT of the Impulse Train

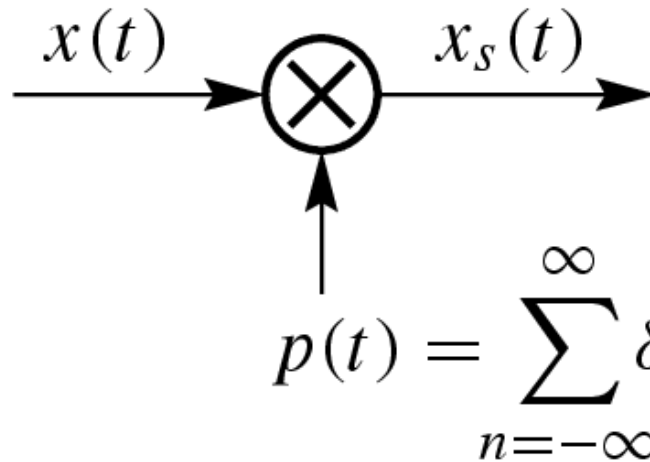
$$p(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT_s) \quad \leftrightarrow \quad P(j\omega) = \sum_{k=-\infty}^{\infty} \frac{2\pi}{T_s} \delta(\omega - k\omega_s)$$



$$\omega_s = \frac{2\pi}{T_s}$$



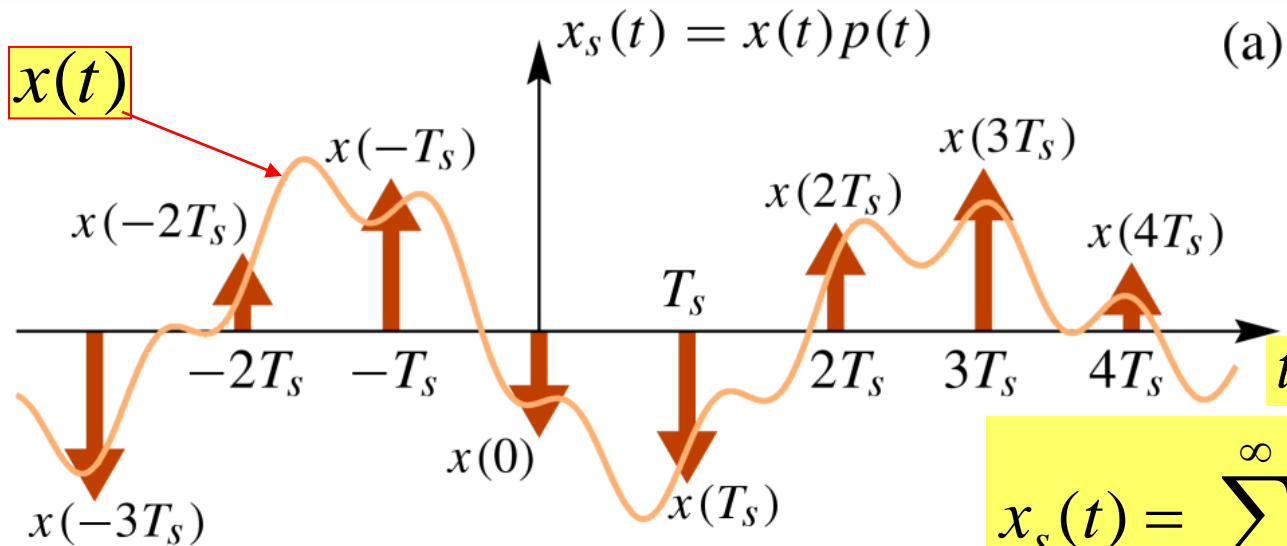
Impulse Train Sampling



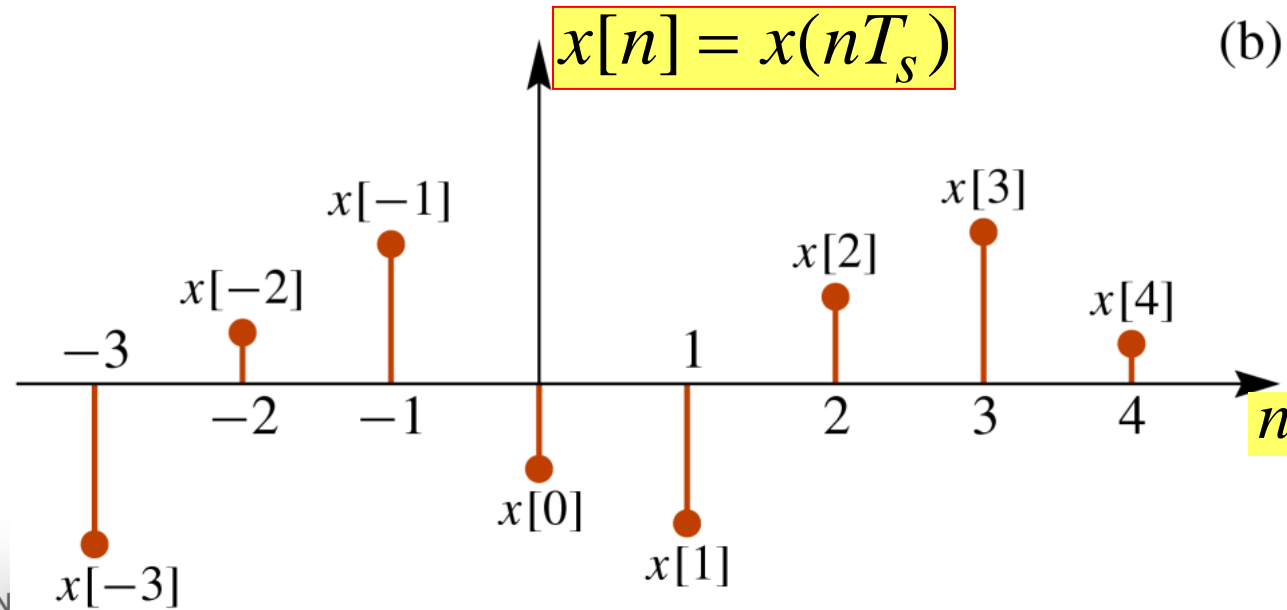
$$x_s(t) = x(t) \sum_{n=-\infty}^{\infty} \delta(t - nT_s) = \sum_{n=-\infty}^{\infty} \underline{x(t)\delta(t - nT_s)}$$

$$x_s(t) = \sum_{n=-\infty}^{\infty} \underline{x(nT_s)\delta(t - nT_s)}$$

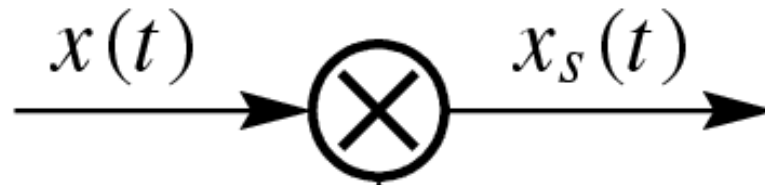
Illustration of Sampling



$$x_s(t) = \sum_{n=-\infty}^{\infty} x(nT_s)\delta(t - nT_s)$$



Sampling: Frequency Domain



$$p(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT_s)$$

$$p(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT_s) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_s t}$$

Frequency-Domain Analysis

$$x_s(t) = x(t) \sum_{n=-\infty}^{\infty} \delta(t - nT_s) = \sum_{n=-\infty}^{\infty} x(nT_s) \delta(t - nT_s)$$

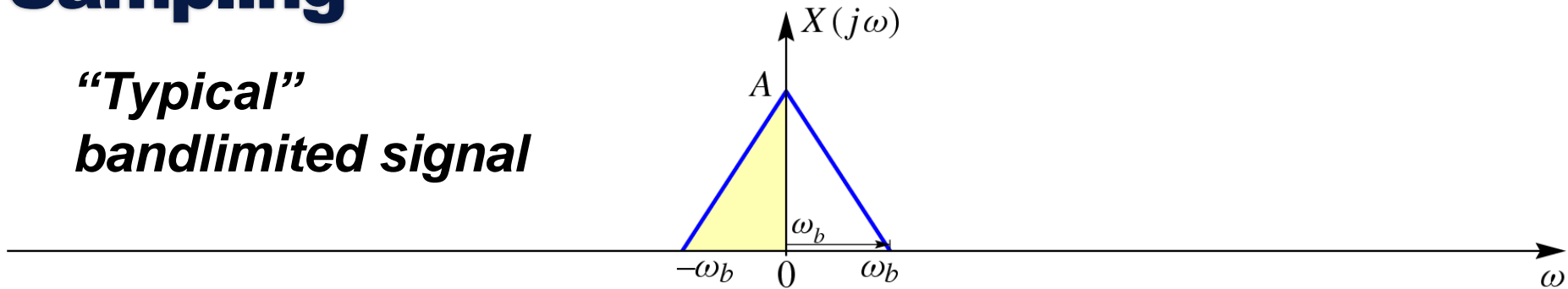
$$x_s(t) = x(t) \sum_{k=-\infty}^{\infty} \frac{1}{T_s} e^{jk\omega_s t} = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} \underline{x(t)e^{jk\omega_s t}}$$

$$X_s(j\omega) = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} \underline{X(j(\omega - k\omega_s))} \quad \omega_s = \frac{2\pi}{T_s}$$

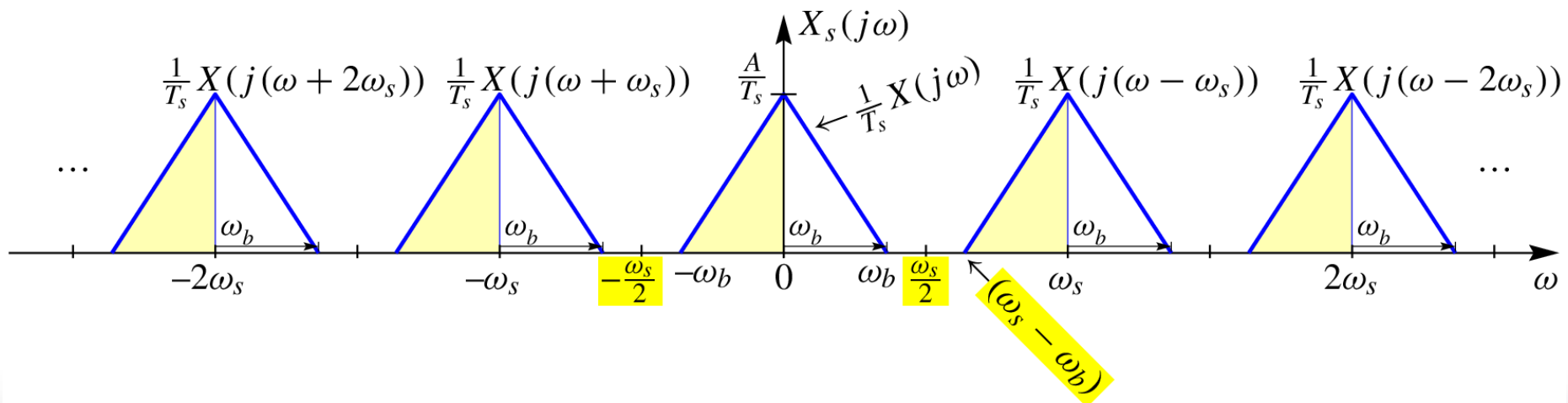
EXPECT FREQUENCY SHIFTING !!!

Frequency-Domain Representation of Sampling

*“Typical”
bandlimited signal*

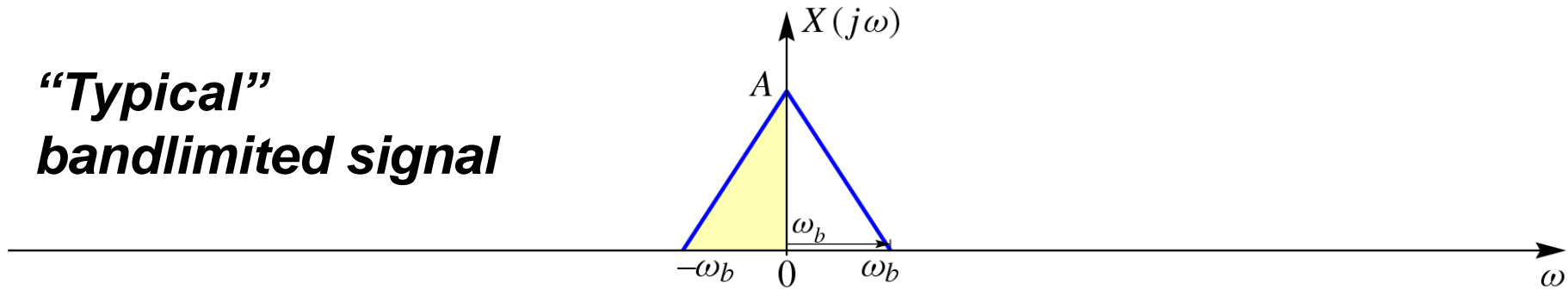


$$X_s(j\omega) = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} X(j(\omega - k\omega_s))$$

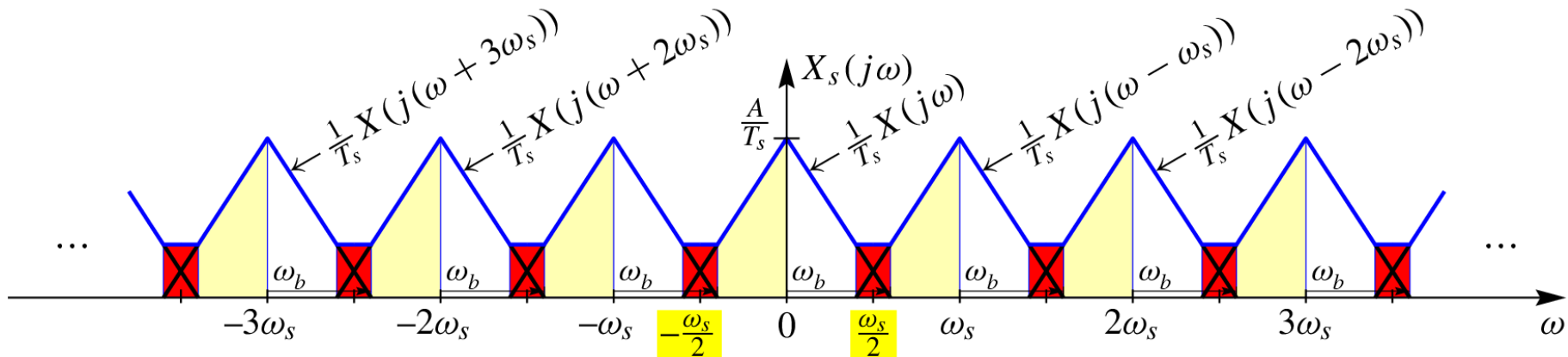


Aliasing Distortion

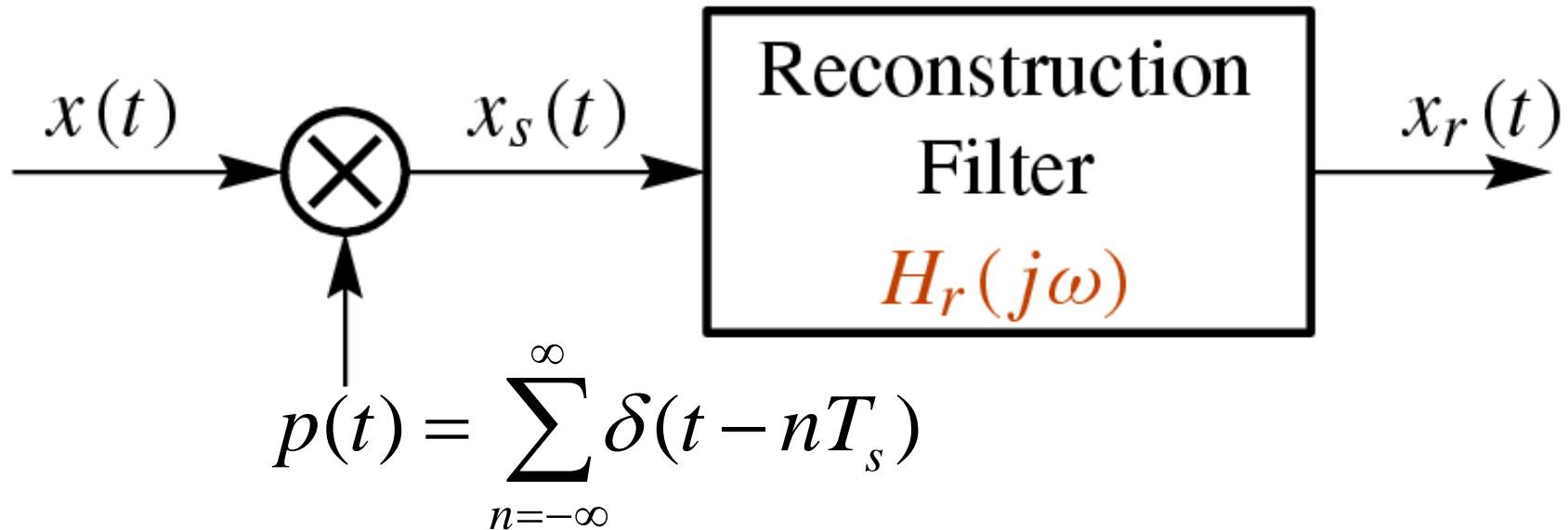
*“Typical”
bandlimited signal*



- If $\omega_s < 2\omega_b$, the copies of $X(j\omega)$ overlap, and we have **aliasing distortion**.



Reconstruction of $x(t)$

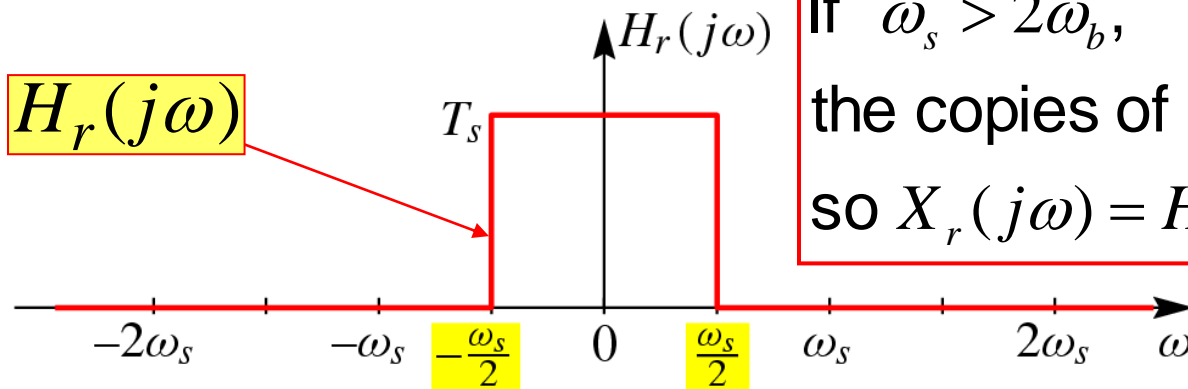
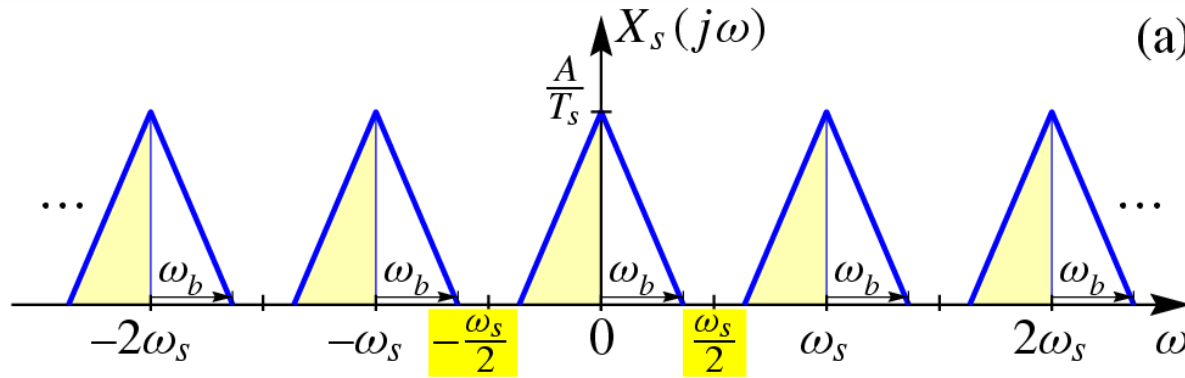


$$x_s(t) = \sum_{n=-\infty}^{\infty} x(nT_s) \delta(t - nT_s)$$

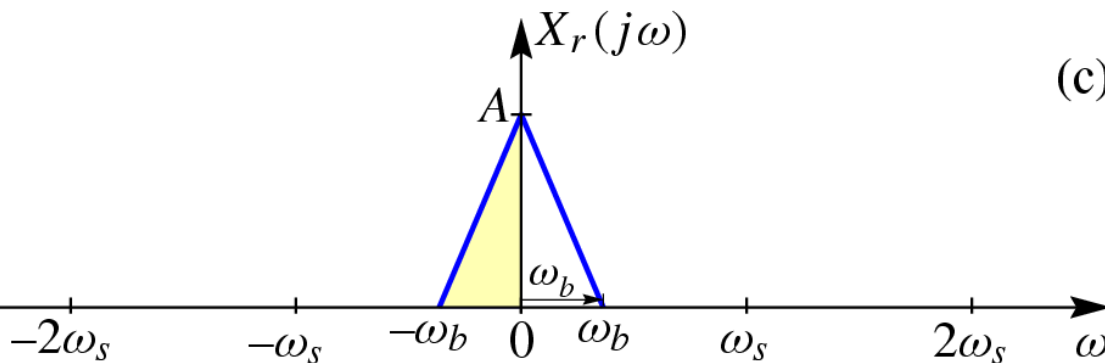
$$X_s(j\omega) = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} X(j(\omega - k\omega_s))$$

$$X_r(j\omega) = H_r(j\omega) X_s(j\omega)$$

Reconstruction in Frequency-Domain

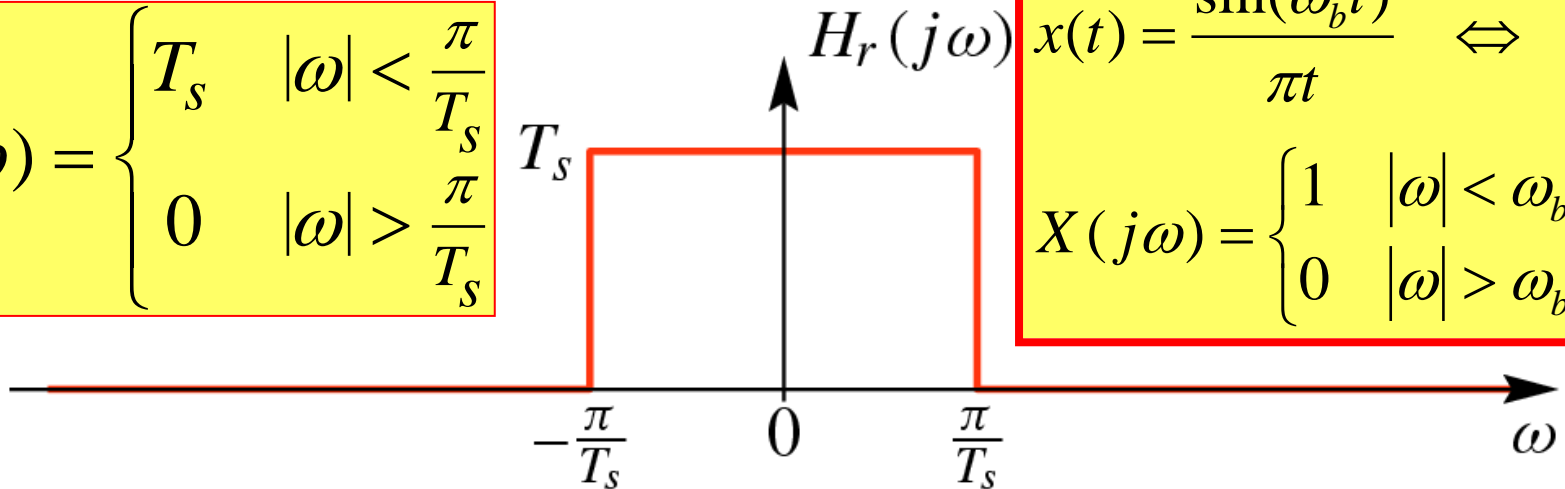


If $\omega_s > 2\omega_b$,
the copies of $X(j\omega)$ do not overlap,
so $X_r(j\omega) = H_r(j\omega)X_s(j\omega) = X(j\omega)$.



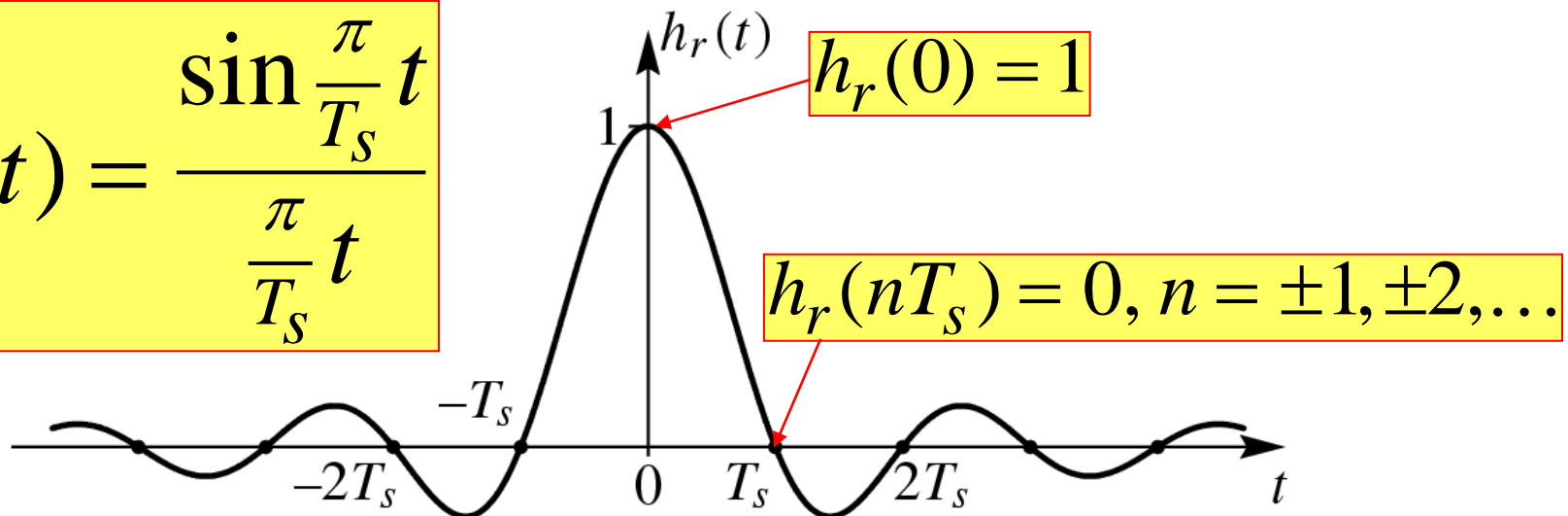
Ideal Reconstruction Filter

$$H_r(j\omega) = \begin{cases} T_s & |\omega| < \frac{\pi}{T_s} \\ 0 & |\omega| > \frac{\pi}{T_s} \end{cases}$$



$$x(t) = \frac{\sin(\omega_b t)}{\pi t} \Leftrightarrow X(j\omega) = \begin{cases} 1 & |\omega| < \omega_b \\ 0 & |\omega| > \omega_b \end{cases}$$

$$h_r(t) = \frac{\sin \frac{\pi}{T_s} t}{\frac{\pi}{T_s} t}$$



Signal Reconstruction

$$x_r(t) = h_r(t) * x_s(t) = h_r(t) * \sum_{n=-\infty}^{\infty} x(nT_s) \delta(t - nT_s)$$

$$x_r(t) = \sum_{n=-\infty}^{\infty} x(nT_s) h_r(t - nT_s)$$

$$x_r(t) = \sum_{n=-\infty}^{\infty} x(nT_s) \frac{\sin \frac{\pi}{T_s} (t - nT_s)}{\frac{\pi}{T_s} (t - nT_s)}$$

Ideal bandlimited interpolation formula

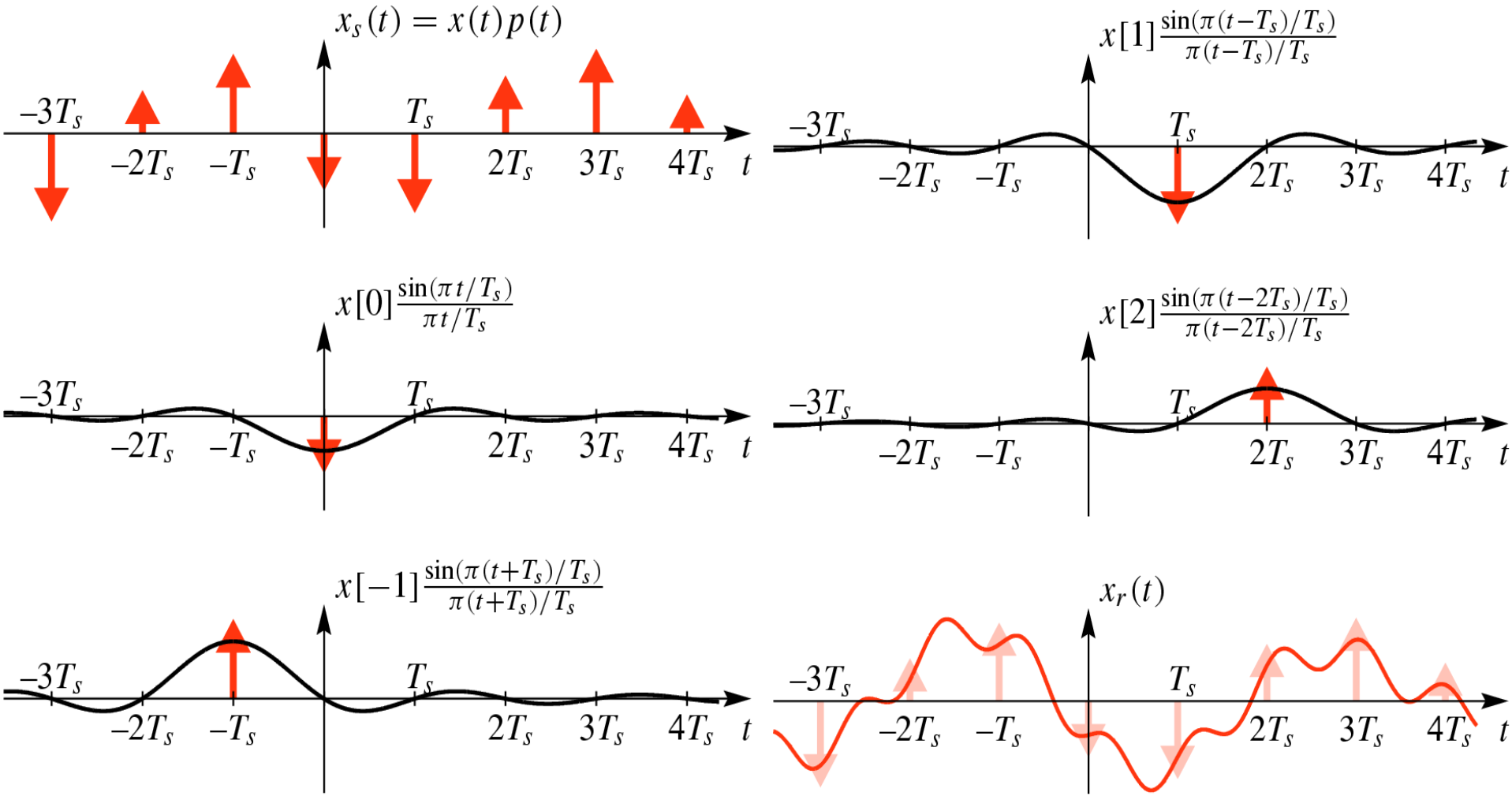
Shannon/Nyquist Sampling Theorem

- **“SINC” interpolation** is the ideal.
 - PERFECT RECONSTRUCTION of BANDLIMITED SIGNALS

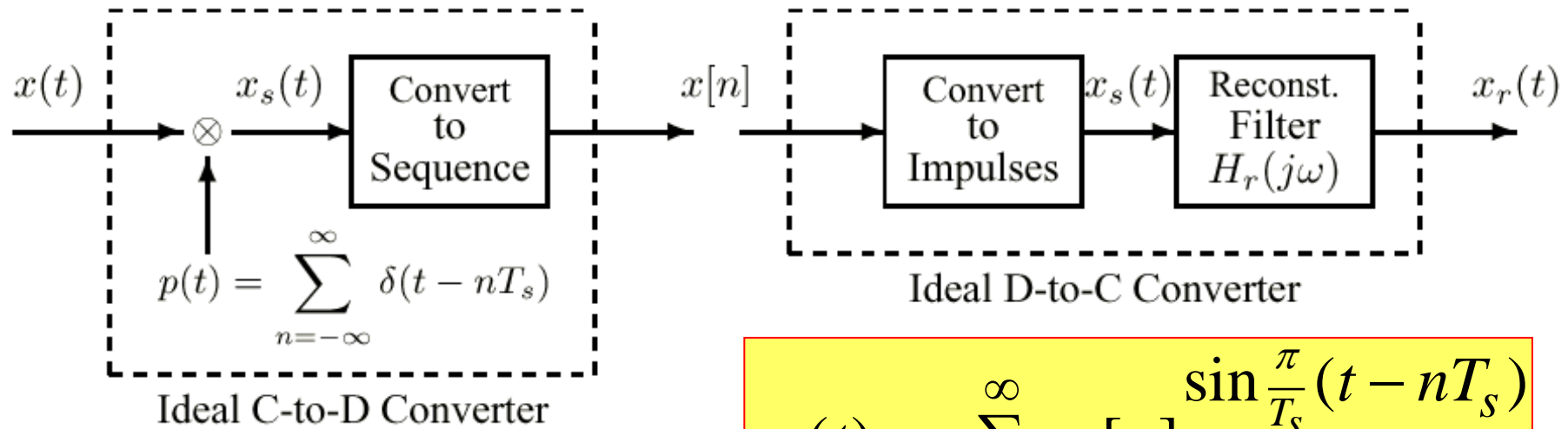
A signal $x(t)$ with bandlimited Fourier transform such that $X(j\omega) = 0$ for $|\omega| \geq \omega_b$ can be reconstructed exactly from samples taken with sampling rate $\omega_s = 2\pi/T_s \geq 2\omega_b$ using the following bandlimited interpolation formula:

$$x_r(t) = \sum_{n=-\infty}^{\infty} x(nT_s) \frac{\sin \left[\frac{\pi}{T_s} (t - nT_s) \right]}{\frac{\pi}{T_s} (t - nT_s)}.$$

Reconstruction in Time-Domain



Ideal C-to-D and D-to-C



$$x[n] = x(nT_s)$$

Ideal Sampler

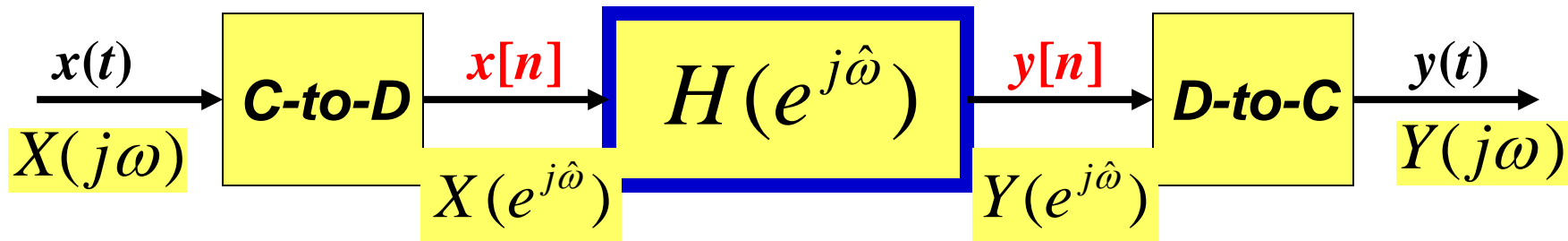
$$x_r(t) = \sum_{n=-\infty}^{\infty} x[n] \frac{\sin \frac{\pi}{T_s} (t - nT_s)}{\frac{\pi}{T_s} (t - nT_s)}$$

Ideal bandlimited interpolator

$$X_s(j\omega) = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} X(j(\omega - k\omega_s))$$

$$X_r(j\omega) = H_r(j\omega) X_s(j\omega)$$

DT Filtering of CT Signals



- If no aliasing occurs in sampling $x(t)$,

$$X(j\omega) = 0 \text{ for } |\omega| > \omega_s / 2$$

- Then, it follows that

$$Y(j\omega) = H_{\text{eff}}(e^{j\omega})X(j\omega)$$

- Overall effective frequency response

$$H_{\text{eff}}(e^{j\omega}) = H(e^{j\omega T_s})$$

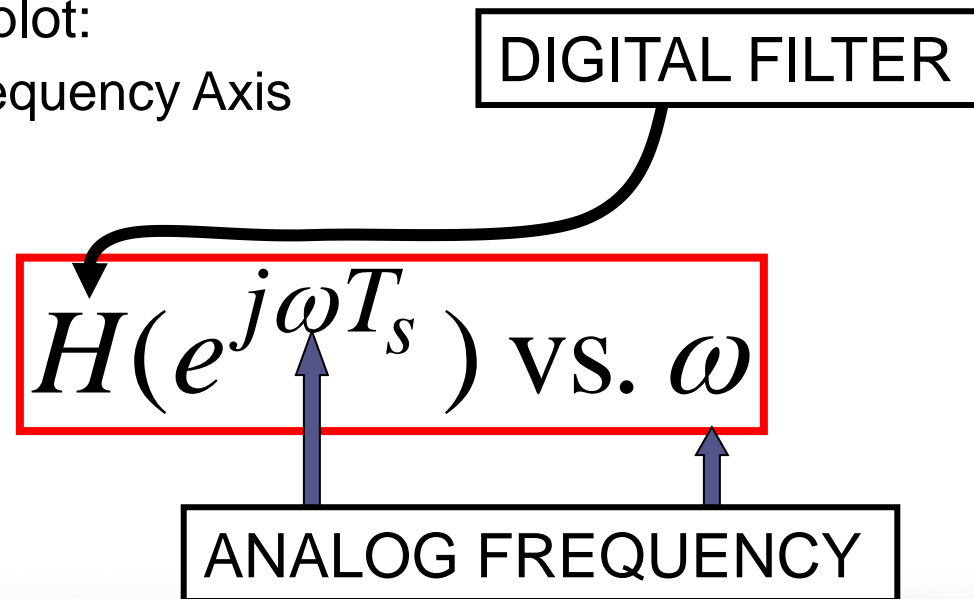
$$\hat{\omega} = \omega T_s = \frac{2\pi f}{f_s}$$

EFFECTIVE Frequency Response

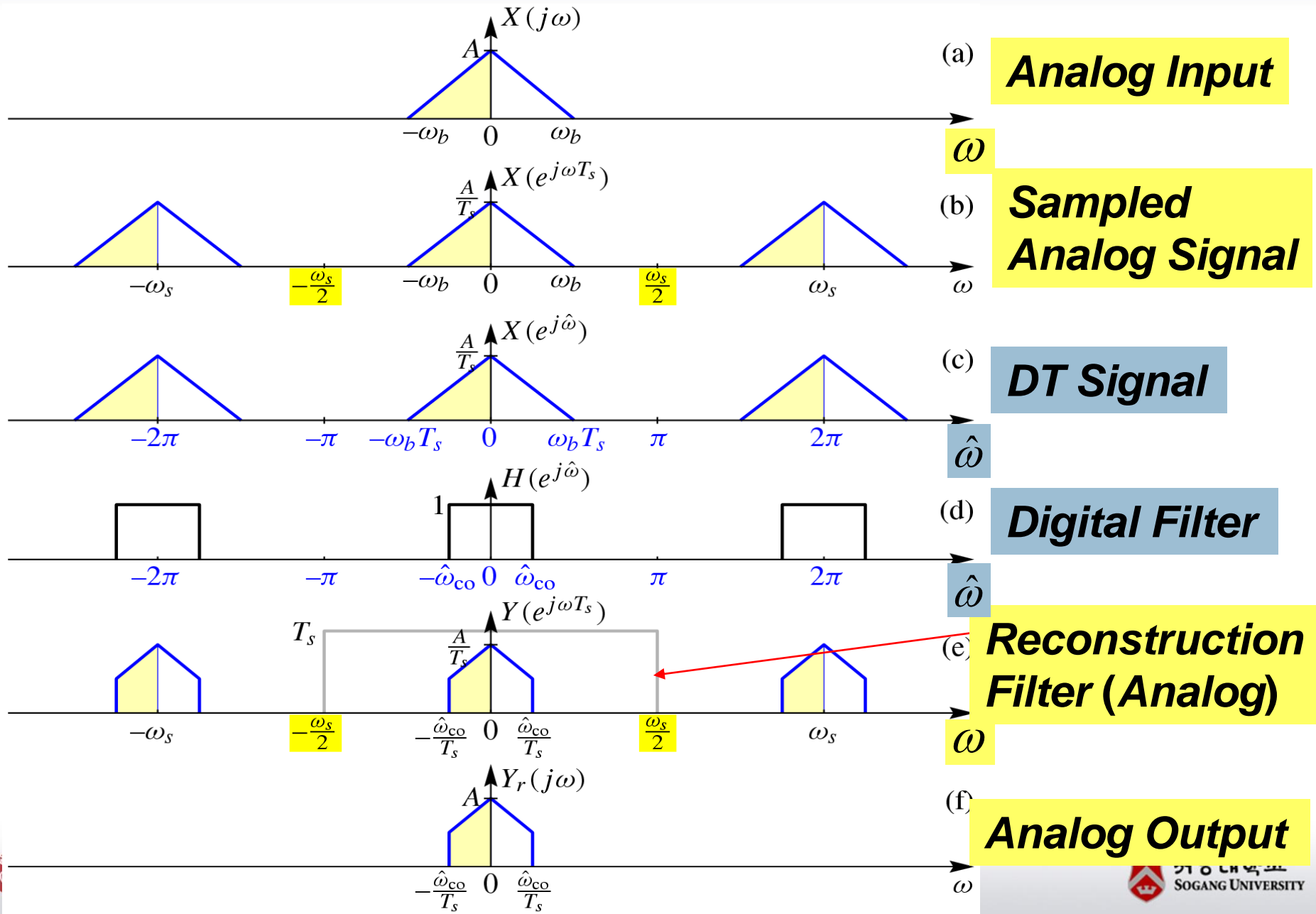
- Assume NO Aliasing, then
 - ANALOG FREQ. <--> DIGITAL FREQ.

$$\hat{\omega} = \omega T_s = \frac{\omega}{f_s}$$

- So, we can plot:
 - Scaled Frequency Axis



DT Filtering of a CT Signal



H_{eff} for 11-pt Running Averager

- Frequency Response for a Discrete-Time System

$$H(e^{j\hat{\omega}}) = \frac{\sin(11\hat{\omega} / 2)}{\sin(\hat{\omega} / 2)}$$

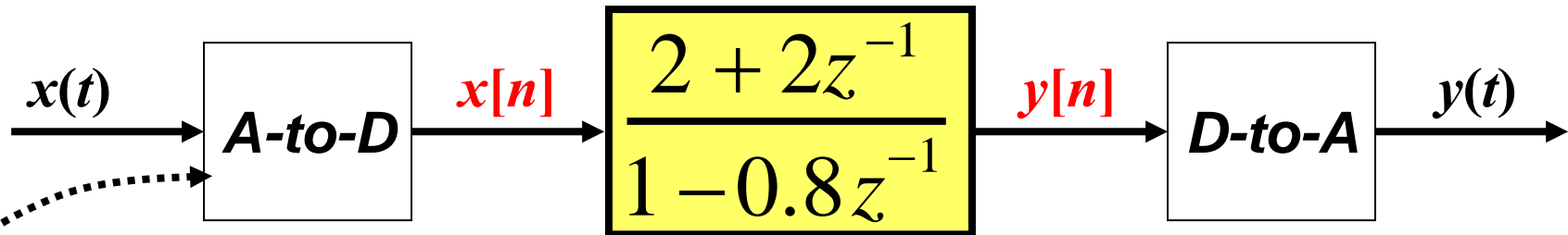
$$\hat{\omega} = \omega T_s = \frac{\omega}{f_s} = \frac{\omega}{1000}$$

- Overall Effective Frequency Response

$$H_{\text{eff}}(j\omega) = H(j\omega T_s) = \frac{\sin(11\omega / 2000)}{\sin(\omega / 2000)}$$

Example

- Given:



- Find the output, $y(t)$.

- When

$$x(t) = \cos(2000 \pi t)$$

$$f_s = 5000 \text{ Hz}$$

- Because

$$\omega T_s = 2000 \pi / 5000 = 0.4 \pi$$

$$x[n] = \cos(0.4 \pi n)$$

NO Aliasing

SINUSOIDAL RESPONSE

- $x[n] = \text{SINUSOID} \Rightarrow y[n] = \text{SINUSOID}$
- Get MAGNITUDE & PHASE from $H(z)$.

If $x[n] = e^{j\hat{\omega}n}$,
 then $y[n] = H(e^{j\hat{\omega}})e^{j\hat{\omega}n}$,
 where $H(e^{j\hat{\omega}}) = H(z)\big|_{z=e^{j\hat{\omega}}}$.

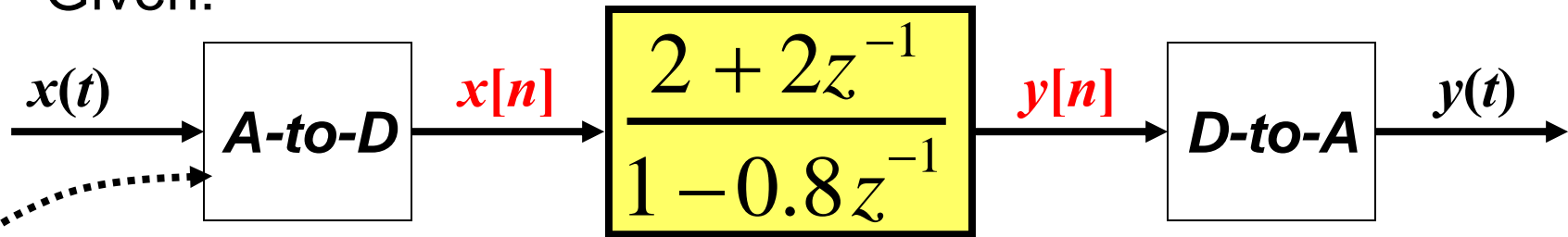
- Then $y[n] = M \cos(0.4\pi n + \psi)$

$$H(e^{j0.4\pi}) = \frac{2 + 2e^{-j0.4\pi}}{1 - 0.8e^{-j0.4\pi}} = 3.02e^{-j0.452\pi}$$



Answer for the Example

- Given:



- When

$$x(t) = \cos(2000 \pi t)$$

$$f_s = 5000 \text{ Hz}$$

- The output

$$y(t) = 3.02 \cos(2000 \pi t - 0.452 \pi)$$

Thank you

