
z-Transform

Prof. Tai-kyong Song
Dept. of Electronic Engineering
SOGANG UNIVERSITY

Z-Transform

❖ Definition

$$X(z) \equiv \sum_{n=-\infty}^{\infty} x(n)z^{-n} \qquad X(z) = Z\{x(n)\}$$

$$x(n) = \frac{1}{2\pi j} \oint_C X(z)z^{n-1}dz \qquad x(n) \leftrightarrow X(z)$$

- ❖ Z-transform is an infinite power-series that exists for values of z in a certain region, called Region of Convergence (ROC)
- ❖ Important tool for the analysis of DT signals and DT systems

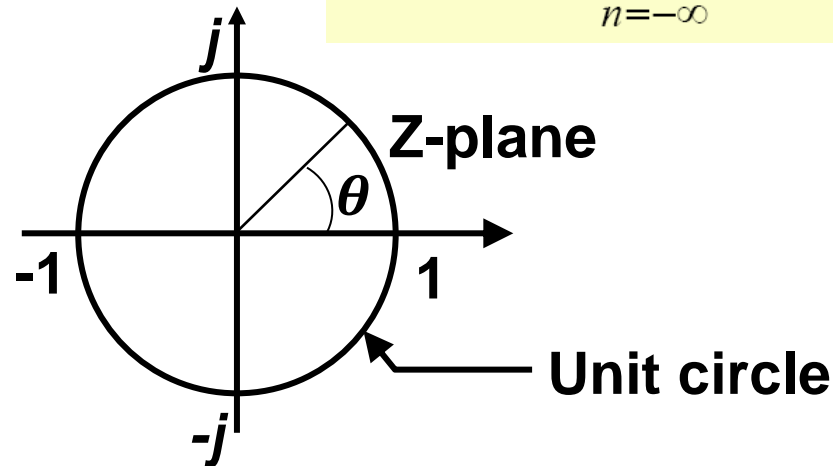
Z-Transform

❖ DTFT vs. Z-transform

$$X(z) \equiv \sum_{n=-\infty}^{\infty} x(n) z^{-n} \xrightarrow{z = r e^{j\omega}} X(z) = \sum_{n=-\infty}^{\infty} x(n) r^{-n} e^{-j\omega n}$$
$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n}$$

$$X(e^{j\theta}) = X(z)|_{z=e^{j\theta}}$$

or $X(\theta)$



❖ Existence (Convergence) of Z-transform

$$|X(z)| \leq \sum_{n=-\infty}^{\infty} |x(n) r^{-n} e^{-j\omega n}| = \sum_{n=-\infty}^{\infty} |x(n) r^{-n}| < \infty$$

Z-Transform

❖ Finding ROC

$$X(z) \equiv \sum_{n=-\infty}^{\infty} x(n) z^{-n}$$

- 1st sum (of **anti-causal part**) converges where $r < r_1$

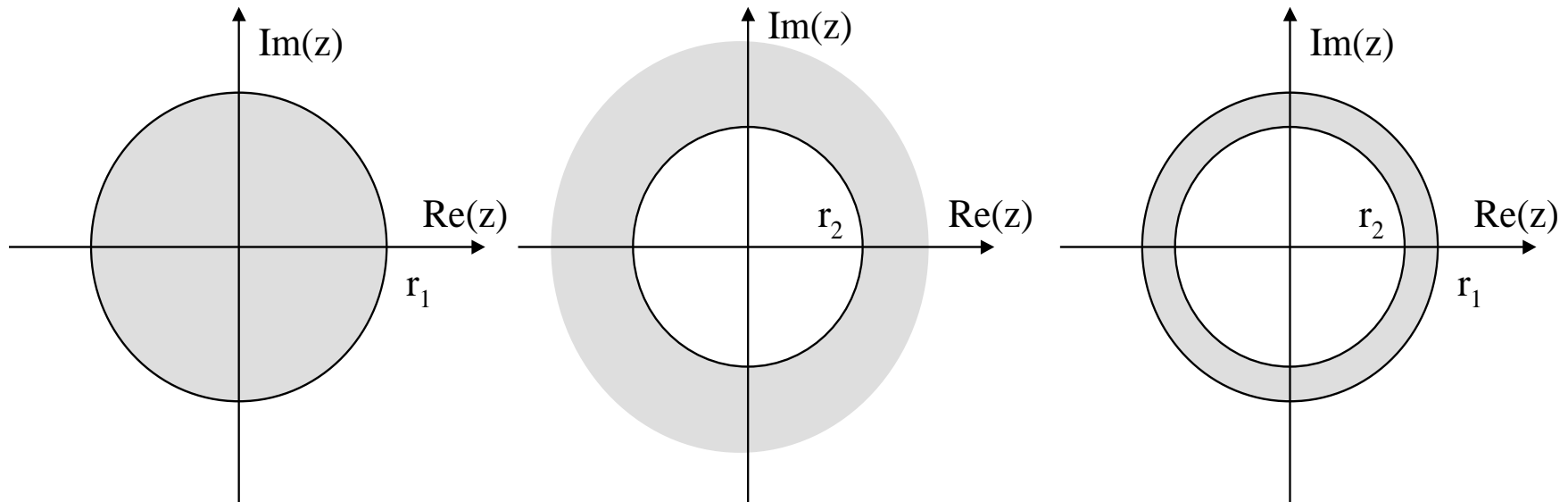
$$|X(z)| \leq \sum_{n=-\infty}^{-1} |x(n) r^{-n}| + \sum_{n=0}^{\infty} \left| \frac{x(n)}{r^n} \right| \leq \sum_{n=1}^{\infty} |x(-n) r^n| + \sum_{n=0}^{\infty} \left| \frac{x(n)}{r^n} \right|$$

- 2nd sum (of **causal part**) converges where $r > r_2$

Z-Transform

- ❖ ROC of is generally specified as the annular region in the z-plane

$$r_2 < r < r_1$$



Note : If $r_2 > r_1$, $X(z)$ does not exist.

Z-Transform

❖ Examples

$$X_1(z) = 1 + 2z^{-1} + 5z^{-2} + 7z^{-3} + z^{-5} \quad \text{ROC: } z \neq 0$$

$$X_2(z) = z^2 + 2z + 5 + 7z^{-1} + z^{-3} \quad \text{ROC: } z \neq 0 \quad z \neq \infty$$

$$X(z) = 1, \quad (\delta(n) \longleftrightarrow 1) \quad \text{ROC: entire } z\text{-plane}$$

$$X_3(z) = z^{-k} \quad (\longleftrightarrow \delta(n-k)) \quad \text{ROC: } z \neq 0$$

$$X_4(z) = z^k \quad (\longleftrightarrow \delta(n+k)) \quad \text{ROC: } z \neq \infty$$

$$k > 0$$

❖ ROC of a finite-duration signal: entire z -plane except possibly at $z = 0$ and/or ∞

Z-Transform

$$\text{Ex) } x(n) = a^n u(n)$$

$$X(z) = \sum_{n=0}^{\infty} a^n z^{-n} = \sum_{n=0}^{\infty} (a z^{-1})^n$$

$$\text{For } |a z^{-1}| < 1, \text{ that is, } |z| > |a|, \quad X(z) = \frac{1}{1 - a z^{-1}}$$

$$x(n) = a^n u(n) \longleftrightarrow X(z) = \frac{1}{1 - a z^{-1}} \quad \text{ROC : } |z| > |a|$$

$$\text{Ex) } x(n) = -a^n u(-n-1) \longleftrightarrow X(z) = \frac{1}{1 - a z^{-1}} \quad \text{ROC : } |z| < |a|$$

$$X(z) = - \sum_{n=-\infty}^{-1} a^n z^{-n} = - \sum_{n=1}^{\infty} a^{-n} z^n = - \frac{a^{-1} z}{1 - a^{-1} z} = \frac{1}{1 - a z^{-1}}$$

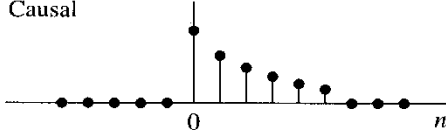
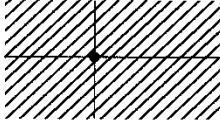
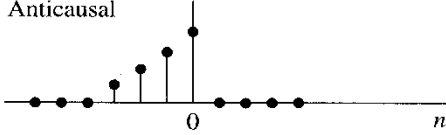
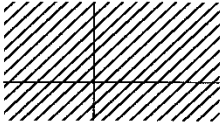
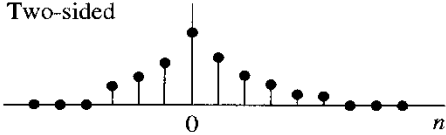
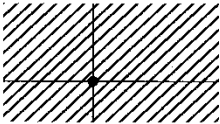
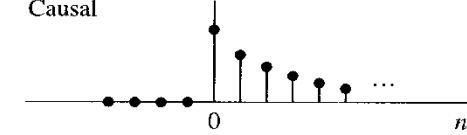
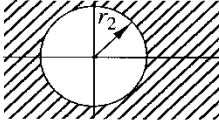
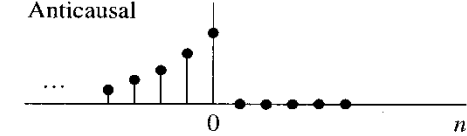
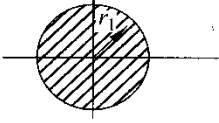
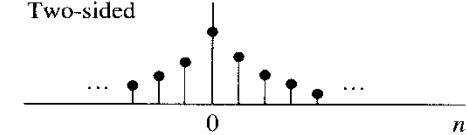
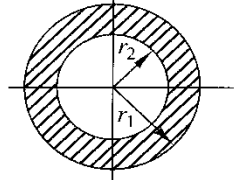
❖ It is obvious that a DT signal is uniquely determined by its z-transform and ROC.

Z-Transform

Characteristic families of Signals with their corresponding ROC

$$X(z) \equiv \sum_{n=-\infty}^{\infty} x(n)z^{-n}$$

TABLE 3.1 CHARACTERISTIC FAMILIES OF SIGNALS WITH THEIR CORRESPONDING ROC

Signal	ROC
Finite-Duration Signals	
<p>Causal</p> 	 <p>Entire z-plane except $z = 0$</p>
<p>Anticausal</p> 	 <p>Entire z-plane except $z = \infty$</p>
<p>Two-sided</p> 	 <p>Entire z-plane except $z = 0$ and $z = \infty$</p>
Infinite-Duration Signals	
<p>Causal</p> 	 <p>$z > r_2$</p>
<p>Anticausal</p> 	 <p>$z < r_1$</p>
<p>Two-sided</p> 	 <p>$r_2 < z < r_1$</p>

Z-Transform

❖ ROC of a signals

- Causal signal : $r > |r_1|$
- Anti-causal signal : $r < |r_2|$
- Finite-duration : Entire z-plane except possibly at $z=0$ and/or ∞

❖ Classifications

- Bilateral (two-sided) z-transform : $X(z) \equiv \sum_{n=-\infty}^{\infty} x(n)z^{-n}$
- Unilateral (one-sided) z-transform : $X^+(z) \equiv \sum_{n=0}^{\infty} x(n)z^{-n}$

Z-Transform: Properties

Property	Time Domain	z-Domain	ROC
Notation	$x(n)$ $x_1(n)$ $x_2(n)$	$X(z)$ $X_1(z)$ $X_2(z)$	ROC: $r_2 < z < r_1$ ROC ₁ ROC ₂
Linearity	$a_1x_1(n) + a_2x_2(n)$	$a_1X_1(z) + a_2X_2(z)$	At least the intersection of ROC ₁ and ROC ₂
Time shifting	$x(n - k)$	$z^{-k}X(z)$	That of $X(z)$, except $z = 0$ if $k > 0$ and $z = \infty$ if $k < 0$
Scaling in the z-domain	$a^n x(n)$	$X(a^{-1}z)$	$ a r_2 < z < a r_1$
Time reversal	$x(-n)$	$X(z^{-1})$	$\frac{1}{r_1} < z < \frac{1}{r_2}$
Conjugation	$x^*(n)$	$X^*(z^*)$	ROC
Real part	$\text{Re}\{x(n)\}$	$\frac{1}{2}[X(z) + X^*(z^*)]$	Includes ROC
Imaginary part	$\text{Im}\{x(n)\}$	$\frac{1}{2j}[X(z) - X^*(z^*)]$	Includes ROC
Differentiation in the z-domain	$nx(n)$	$-z \frac{dX(z)}{dz}$	$r_2 < z < r_1$
Convolution	$x_1(n) * x_2(n)$	$X_1(z)X_2(z)$	At least, the intersection of ROC ₁ and ROC ₂
Correlation	$r_{x_1x_2}(l) = x_1(l) * x_2(-l)$	$R_{x_1x_2}(z) = X_1(z)X_2(z^{-1})$	At least, the intersection of ROC of $X_1(z)$ and $X_2(z^{-1})$
Initial value theorem	If $x(n)$ causal	$x(0) = \lim_{z \rightarrow \infty} X(z)$	
Multiplication	$x_1(n)x_2(n)$	$\frac{1}{2\pi j} \oint_C X_1(v)X_2\left(\frac{z}{v}\right)v^{-1}dv$	At least $r_{1l}r_{2l} < z < r_{1u}r_{2u}$
Parseval's relation	$\sum_{n=-\infty}^{\infty} x_1(n)x_2^*(n)$	$\frac{1}{2\pi j} \oint_C X_1(v)X_2^*(1/v^*)v^{-1}dv$	

Z-Transform: Properties

Linearity $x(n) = a_1x_1(n) + a_2x_2(n) \xleftrightarrow{Z} X(z) = a_1X_1(z) + a_2X_2(z)$

Ex) $x(n) = \cos \omega_0 n \cdot u(n)$

$$x(n) = \frac{1}{2} e^{j\omega_0 n} u(n) + \frac{1}{2} e^{-j\omega_0 n} u(n)$$

$$X(z) = \frac{1}{2} Z\{e^{j\omega_0 n} u(n)\} + \frac{1}{2} Z\{e^{-j\omega_0 n} u(n)\}$$

$$e^{j\omega_0 n} u(n) \longleftrightarrow \frac{1}{1 - e^{j\omega_0} z^{-1}} \quad (|z| > 1)$$

$$e^{-j\omega_0 n} u(n) \longleftrightarrow \frac{1}{1 - e^{-j\omega_0} z^{-1}} \quad (|z| > 1)$$

$$\Rightarrow (\cos \omega_0 n) u(n) \xleftrightarrow{Z} \frac{1 - z^{-1} \cos \omega_0}{1 - 2z^{-1} \cos \omega_0 + z^{-2}} \quad \text{ROC: } |z| > 1$$

$$\Rightarrow (\sin \omega_0 n) u(n) \xleftrightarrow{Z} \frac{z^{-1} \sin \omega_0}{1 - 2z^{-1} \cos \omega_0 + z^{-2}}$$

Z-Transform: Properties

Time shifting: $x(n-k) \xLeftrightarrow{z} z^{-k}X(z)$

Scaling in the z-domain:

If $x(n) \longleftrightarrow X(z)$ ROC: $r_1 < |z| < r_2$

$a^n x(n) \xLeftrightarrow{z} X(a^{-1}z)$ ROC: $|a|r_1 < |z| < |a|r_2$

Note: Let's rewrite as $a = r_0 e^{j\omega_0}$ and $z = r e^{j\omega}$.

then, $z \rightarrow a^{-1}z = \frac{r}{r_0} e^{j(\omega - \omega_0)}$: Frequency shifting

$$\text{Ex)} \quad a^n (\cos w_0 n) u(n) \xLeftrightarrow{z} \frac{1 - az^{-1} \cos w_0}{1 - 2az^{-1} \cos w_0 + a^2 z^{-2}} \quad |z| > |a|$$

$$a^n (\sin w_0 n) u(n) \xLeftrightarrow{z} \frac{az^{-1} \sin w_0}{1 - 2az^{-1} \cos w_0 + a^2 z^{-2}} \quad |z| > |a|$$

Z-Transform: Properties

Time reversal: $x(-n) \xLeftrightarrow{z} X(z^{-1}) \quad \frac{1}{r_2} < |z| < \frac{1}{r_1}$

Differentiation in the z-domain: $nx(n) \xLeftrightarrow{z} -z \frac{dX(z)}{dz}$

Ex) $a^n u(n) \longleftrightarrow 1/(1 - az^{-1}) \quad \text{ROC: } |z| > |a|$

$$na^n u(n) \xLeftrightarrow{z} X(z) = -z \frac{dX_1(z)}{dz} = \frac{az^{-1}}{(1 - az^{-1})^2} \quad |z| > |a|$$

$$nu(n) \xLeftrightarrow{z} \frac{z^{-1}}{(1 - z^{-1})^2} \quad |z| > 1$$

Z-Transform: Properties

Convolution:

$$x(n) = x_1(n) * x_2(n) \xLeftrightarrow{z} X(z) = X_1(z) X_2(z)$$

Correlation:

$$r_{x_1 x_2}(l) = \sum_{n=-\infty}^{\infty} x_1(n) x_2(n-l) \xLeftrightarrow{z} R_{x_1 x_2}(z) = X_1(z) X_2(z^{-1})$$

Multiplication:

$$x(n) = x_1(n) x_2(n) \xLeftrightarrow{z} X(z) = \frac{1}{2\pi j} \oint_C X_1(v) X_2\left(\frac{z}{v}\right) v^{-1} dv$$

Parseval's relation:

$$\sum_{n=-\infty}^{\infty} x_1(n) x_2^*(n) = \frac{1}{2\pi j} \oint_C X_1(v) X_2^*\left(\frac{1}{v^*}\right) v^{-1} dv$$

$$x^*(n) \longleftrightarrow X^*(z^*)$$

Z-Transform: Properties

Initial value theorem for causal $x(n)$:

$$x(0) = \lim_{z \rightarrow \infty} X(z) \quad X(z) = x(0) + x(1)z^{-1} + x(2)z^{-2} + \dots$$

Final value theorem

$$\lim_{n \rightarrow \infty} x(n) = \lim_{z \rightarrow 1} (z-1)X^+(z)$$

$$Z[x(n)] = X(z) = \sum_{n=0}^{\infty} x(n)z^{-n} \quad Z[x(n+1)] = \sum_{n=0}^{\infty} x(n+1)z^{-n} = zX(z) - zx(0)$$

$$Z[x(n+1)] - Z[x(n)] = zX(z) - zx(0) - X(z)$$

$$(z-1)X(z) - zx(0) = [x(1) - x(0)]z^0 + [x(2) - x(1)]z^{-1} + [x(3) - x(2)]z^{-2} + \dots$$

$$\lim_{z \rightarrow 1} [(z-1)X(z)] - x(0) = x(\infty) - x(0)$$

Z-Transform: Common z-transform pairs

	Signal, $x(n)$	z -Transform, $X(z)$	ROC
1	$\delta(n)$	1	All z
2	$u(n)$	$\frac{1}{1 - z^{-1}}$	$ z > 1$
3	$a^n u(n)$	$\frac{1}{1 - az^{-1}}$	$ z > a $
4	$na^n u(n)$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z > a $
5	$-a^n u(-n - 1)$	$\frac{1}{1 - az^{-1}}$	$ z < a $
6	$-na^n u(-n - 1)$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z < a $
7	$(\cos \omega_0 n) u(n)$	$\frac{1 - z^{-1} \cos \omega_0}{1 - 2z^{-1} \cos \omega_0 + z^{-2}}$	$ z > 1$
8	$(\sin \omega_0 n) u(n)$	$\frac{z^{-1} \sin \omega_0}{1 - 2z^{-1} \cos \omega_0 + z^{-2}}$	$ z > 1$
9	$(a^n \cos \omega_0 n) u(n)$	$\frac{1 - az^{-1} \cos \omega_0}{1 - 2az^{-1} \cos \omega_0 + a^2 z^{-2}}$	$ z > a $
10	$(a^n \sin \omega_0 n) u(n)$	$\frac{az^{-1} \sin \omega_0}{1 - 2az^{-1} \cos \omega_0 + a^2 z^{-2}}$	$ z > a $

Rational z-Transforms

LTI system described by a constant coefficient difference equation has a rational transfer function of z^{-1}

$$\begin{aligned} G(z) &= \frac{B(z)}{A(z)} = \frac{b_0 + b_1 z^{-1} + \dots + b_{M-1} z^{-(M-1)} + b_M z^{-M}}{a_0 + a_1 z^{-1} + \dots + a_{N-1} z^{-(N-1)} + a_N z^{-N}} \\ G(z) &= \frac{z^{-M} z^M}{z^{-N} z^N} \cdot \frac{b_0 + b_1 z^{-1} + \dots + b_{M-1} z^{-(M-1)} + b_M z^{-M}}{a_0 + a_1 z^{-1} + \dots + a_{N-1} z^{-(N-1)} + a_N z^{-N}} \\ &= z^{N-M} \cdot \frac{b_0 z^M + b_1 z^{M-1} + \dots + b_{M-1} z + b_M}{a_0 z^N + a_1 z^{N-1} + \dots + a_{N-1} z + a_N} \end{aligned}$$

- Degree of $B(z) = M$
- Degree of $A(z) = N$

Rational z-Transforms

Poles and Zeros

$$G(z) = \frac{b_0 \prod_{i=1}^M (1 - z_i z^{-1})}{a_0 \prod_{k=1}^N (1 - p_k z^{-1})} = z^{(N-M)} \frac{b_0 \prod_{i=1}^M (z - z_i)}{a_0 \prod_{k=1}^N (z - p_k)}$$

zero
pole

- $G(z)$ has M finite zeros and N finite poles
- If $N > M$, there are $N - M$ additional zeros at $z = 0$
- If $M > N$, there are $M - N$ additional poles at $z = 0$

Including trivial poles and zeros at $z=0$ or ∞ , the number of poles and zeros are equal


Rational z-Transforms

Some related MATLAB functions

$$H(z) = \frac{B(z)}{A(z)} = \frac{b_0 + b_1 z^{-1} + \cdots + b_{m-1} z^{-(m-1)} + b_m z^{-m}}{a_0 + a_1 z^{-1} + \cdots + a_{n-1} z^{-(n-1)} + b_n z^{-n}}$$

- $[z, p, k] = \text{tf2zpk}(b, a)$

finds the zeros, poles, and gains of a discrete-time transfer function


$$H(z) = \frac{Z(z)}{P(z)} = k \frac{(z - z_1)(z - z_2) \cdots (z - z_m)}{(z - p_1)(z - p_2) \cdots (z - p_n)}$$

Rational z-Transforms

Some related MATLAB functions

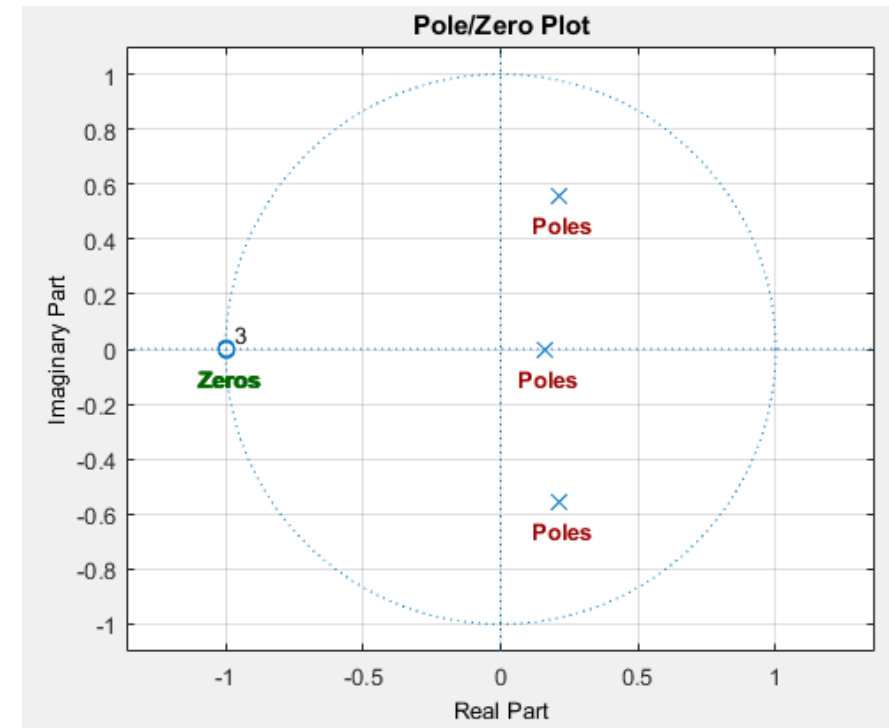
- $[z, p, k] = \text{tf2zpk}(b, a)$

$$H(z) = \frac{Z(z)}{P(z)} = k \frac{(z - z_1)(z - z_2) \cdots (z - z_m)}{(z - p_1)(z - p_2) \cdots (z - p_n)}$$

`zplane(z, p)`

`grid`

`Title('Pole/Zero Plot')`



Rational z-Transforms

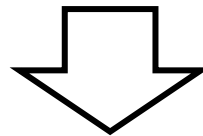
Some related MATLAB functions

$$H(z) = \frac{1 - 0.5z^{-1}}{1 + 1.8z^{-1} + 0.6z^{-2} - 0.2z^{-3}}$$

```
n = [1 -0.5];  
d = [1 1.8 0.6 -0.2];  
[z, p, k] = tf2zpk(n, d);  
[num, den] = zp2tf(z, p, k);
```

```
z = 0.5  
p = -1.0000  
    -1.0000  
    0.2000  
k = 1
```

```
num = [0 0 1 -0.5]  
den = [1 1.8 0.6 -0.2]
```



$$H(z) = k \frac{(z - z_1)(z - z_2) \cdots (z - z_n)}{(z - p_1)(z - p_2) \cdots (z - p_m)}$$

Rational z-Transforms

$$x(n) = a^n u(n), \quad a > 0$$

$$X(z) = \sum_{n=0}^{M-1} a^n z^{-n} = \sum_{n=0}^{M-1} (az^{-1})^n = \frac{1 - (az^{-1})^M}{1 - az^{-1}} = \frac{z^M - a^M}{z^{M-1}(z - a)}$$

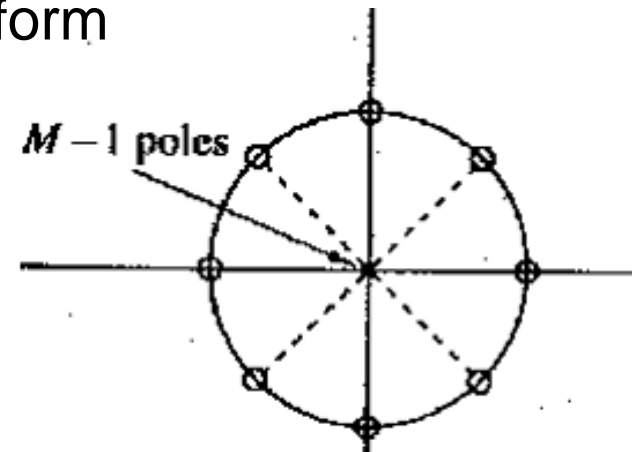
$$z^M - a^M = 0 \Rightarrow z_k^M = a^M e^{j2\pi k} \Rightarrow z_k = a e^{j2\pi k/M}, \quad k = 0, 1, 2, \dots, M-1$$

$$X(z) = \frac{(z - z_0)(z - z_1)(z - z_2) \cdots (z - z_{M-1})}{z^{M-1} \underline{(z - a)}} \quad (z - a) : \text{Common factor}$$

$$= \frac{(z - z_1)(z - z_2) \cdots (z - z_{M-1})}{z^{M-1}} : \text{Irreducible form}$$

Zeros: $z_k = a e^{j2\pi k/M}, \quad k = 1, 2, \dots, M-1$

Poles: M-1 poles at zero



Rational z-Transforms

- Determining $X(z)$ from a pole-zero plot.

$$X(z) = G \frac{(z - z_1)(z - z_2)}{(z - p_1)(z - p_2)} = G \frac{z(z - r \cos \omega_0)}{(z - re^{j\omega_0})(z - re^{-j\omega_0})} \quad \text{ROC: } |z| > r$$

$$\Leftrightarrow X(z) = G \frac{1 - rz^{-1} \cos \omega_0}{1 - 2rz^{-1} \cos \omega_0 + r^2 z^{-2}} \quad \text{ROC: } |z| > r$$

From the z-transform pair table,

$$x(n) = G(r^n \cos \omega_0 n)u(n)$$

Note) In general, if a polynomial has real coeffs, its roots are either real or occurs in complex-conjugate pairs.

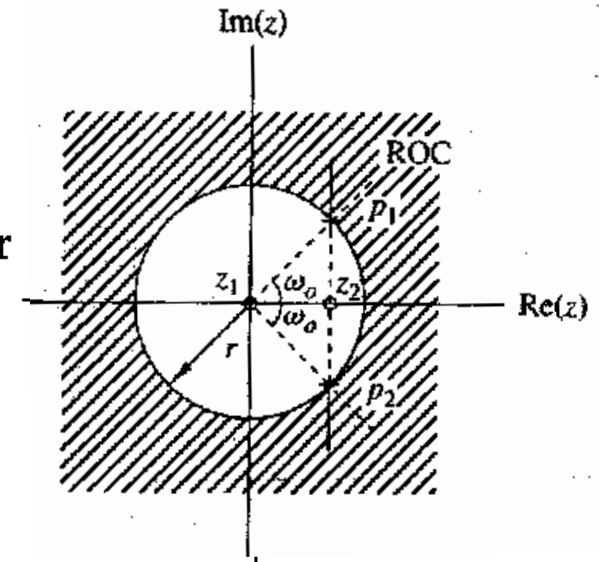


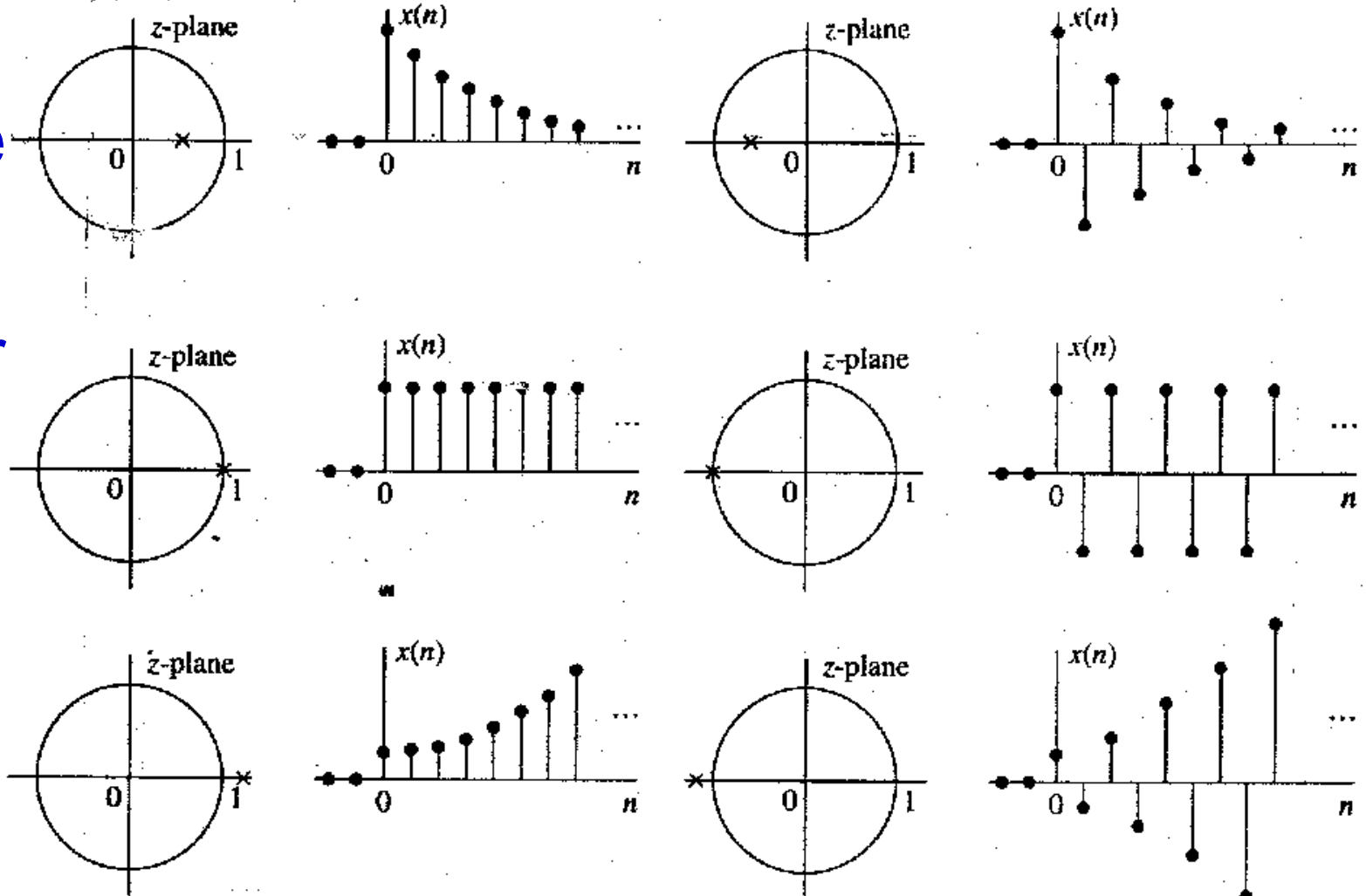
Figure 3.9 Pole-zero pattern for Example 3.3.3.

Rational z-Transforms

Pole
Location
and time
domain
behavior

$$x(n) = a^n u(n) \xleftrightarrow{z} X(z) = 1/(1 - az^{-1}) \quad \text{ROC: } |z| > |a|$$

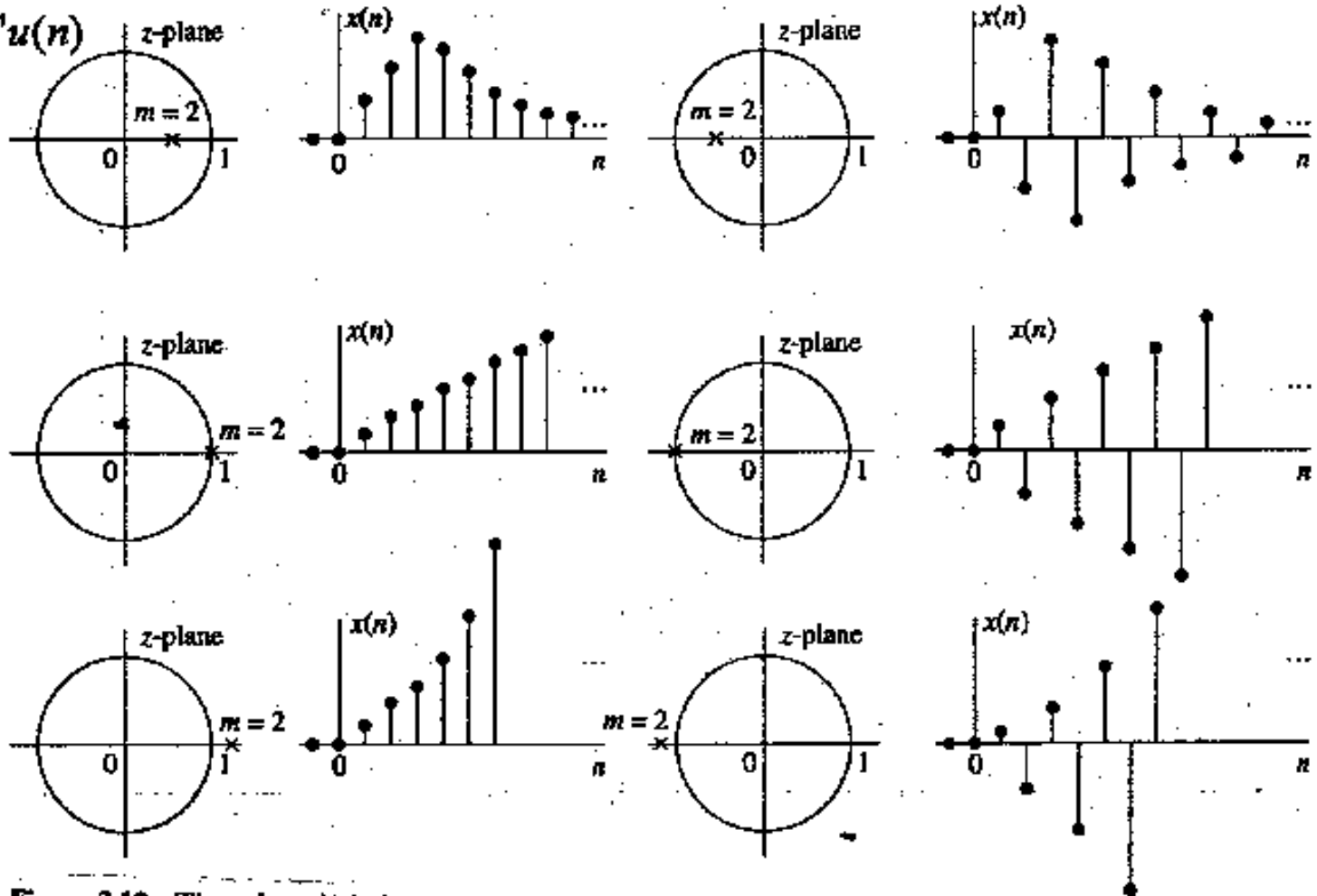
which has one zero at $z = 0$ and one pole at $z = a$.



Rational z-Transforms

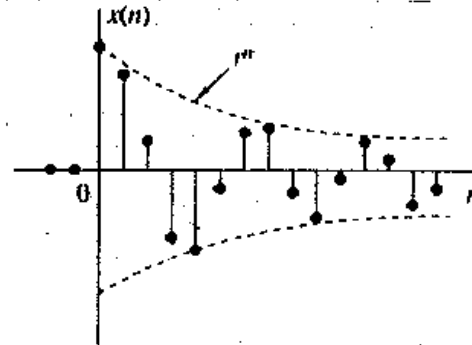
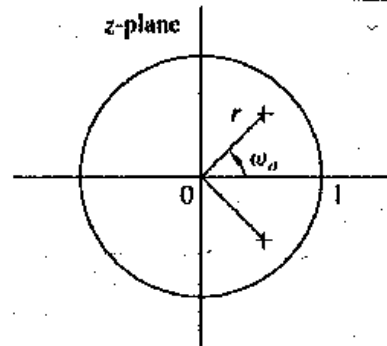
A real causal signal with a double pole has the form

$$x(n) = na^n u(n)$$



Rational z-Transforms

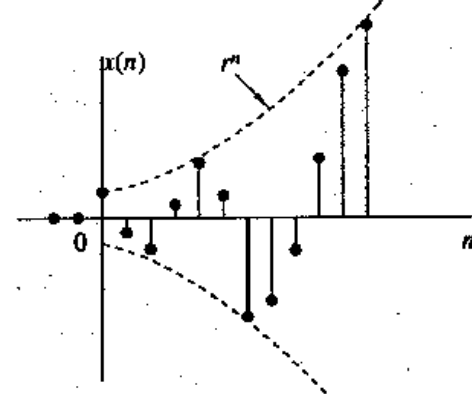
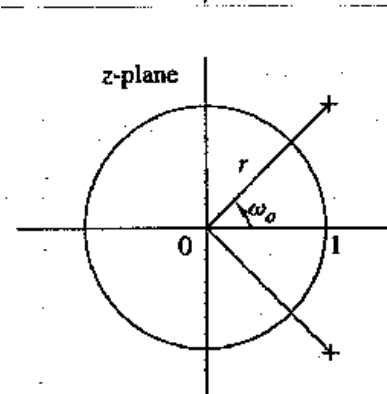
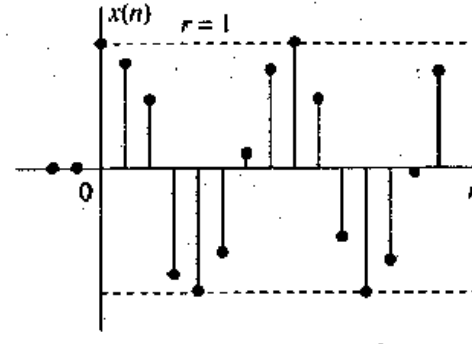
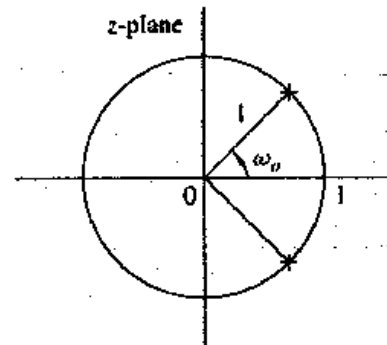
- A real causal signal with a pair of complex-conjugate poles:



$$x(n) = a^n \sin \omega_0 n \cdot u(n) \text{ or}$$

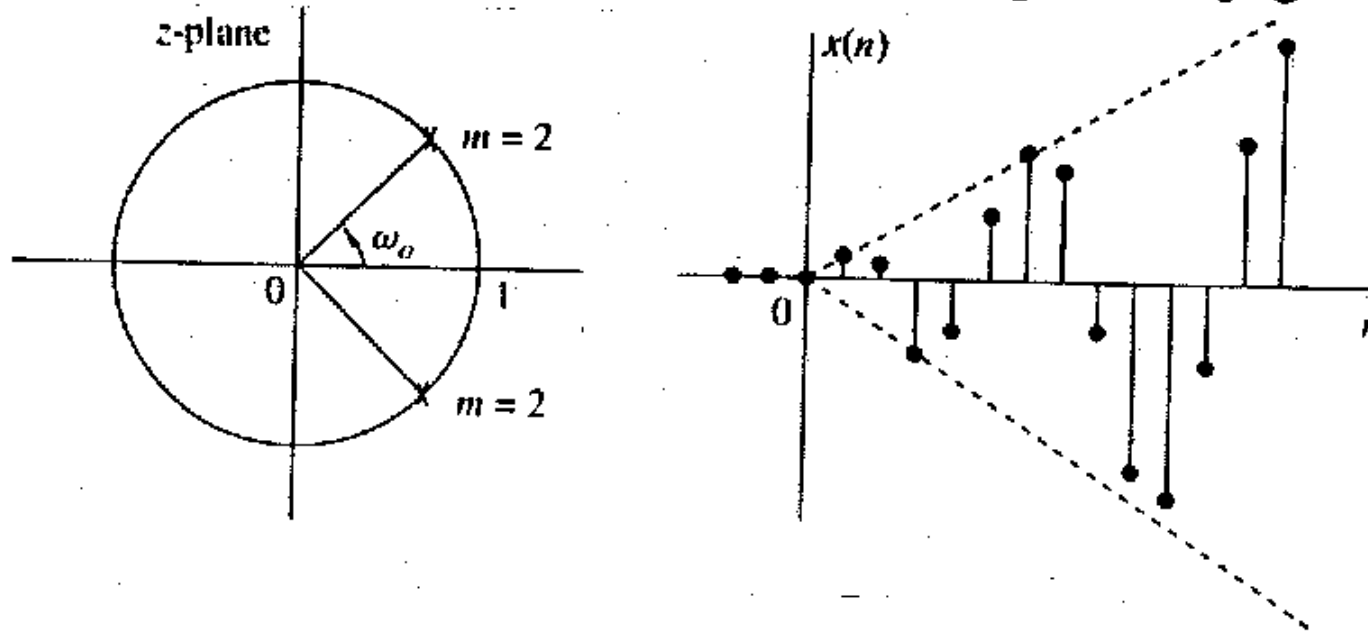
$$x(n) = a^n \cos \omega_0 n \cdot u(n)$$

Note) Location of zeros
only affects the signal
phase in this case.



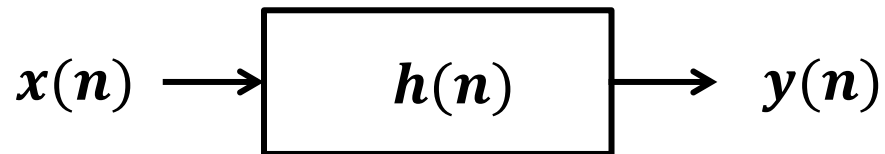
Rational z-Transforms

A real causal signal with a double pair of complex-conjugate poles:



Rational z-Transforms

The system function of a LTI system



$$y(n) = h(n) * x(n) \xleftrightarrow{z} Y(z) = H(z)X(z)$$

$$y(n) = -\sum_{k=1}^N a_k y(n-k) + \sum_{k=0}^M b_k x(n-k)$$

$$\xleftrightarrow{z} Y(z) = -\sum_{k=1}^N a_k z^{-k} Y(z) + \sum_{k=0}^M b_k z^{-k} X(z)$$

$$Y(z) \left(1 + \sum_{k=1}^N a_k z^{-k} \right) = X(z) \left(\sum_{k=0}^M b_k z^{-k} \right) \quad \Rightarrow$$

Rational transfer function

$$H(z) = \frac{\sum_{k=0}^M b_k z^{-k}}{1 + \sum_{k=1}^N a_k z^{-k}}$$

Rational z-Transforms

The system function of a LTI system

- All zero system (FIR, Non-recursive)

$$H(z) = \sum_{k=0}^M b_k z^{-k} = \frac{1}{z^M} \sum_{k=0}^M b_k z^{M-k}$$

- All pole system (IIR, recursive)

$$H(z) = \frac{b_0}{1 + \sum_{k=1}^N a_k \cdot z^{-k}} = \frac{b_0}{\sum_{k=0}^N a_k \cdot z^{-k}} \quad a_0 \equiv 1$$

- Pole-zero system (IIR, recursive)

Rational z-Transforms

Determining the impulse response from difference equation

$$\text{Ex) } y(n) = \frac{1}{2}y(n-1) + 2x(n)$$

$$\rightarrow Y(z) = \frac{1}{2}z^{-1}Y(z) + 2X(z)$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{2}{1 - (1/2)z^{-1}}$$

From the table,

$$\rightarrow h(n) = 2\left(\frac{1}{2}\right)^n u(n)$$

No information on the initial condition and transient response

Inverse z-Transform

❖ Formula

$$x(n) = \frac{1}{2\pi j} \oint_C X(z) z^{n-1} dz \quad X(z) = \sum_{k=-\infty}^{\infty} x(k) z^{-k}$$

$$\begin{aligned} \frac{1}{2\pi j} \oint_C X(z) z^{n-1} dz &= \frac{1}{2\pi j} \oint_C \sum x(k) z^{-k+n-1} dz = \sum \frac{x(k)}{2\pi j} \oint_C z^{-k+n-1} dz \\ &= \sum \left[\begin{array}{c} \text{Residues of } X(z) z^{n-1} \\ \text{at the poles inside } C \end{array} \right] = \begin{cases} x(n), & k=n \\ 0, & \text{otherwise} \end{cases} \end{aligned}$$

❖ Methods

- Direct evaluation by contour integration
- Series expansion method
- Partial-fraction expansion

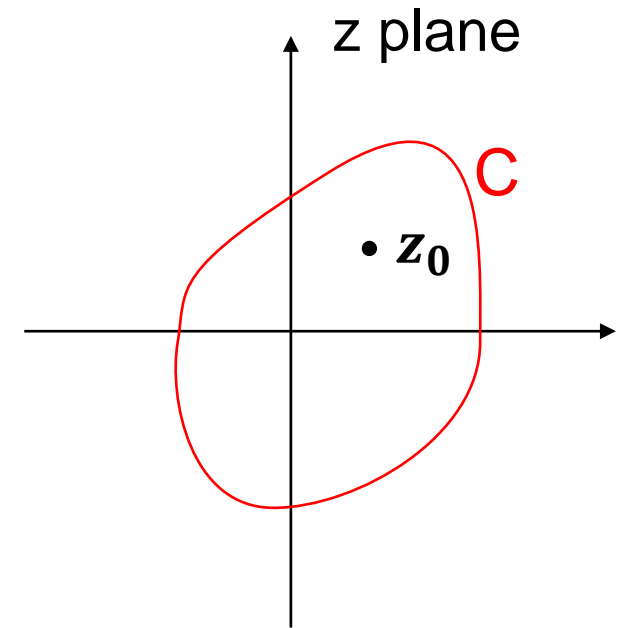
Inverse z-Transform

❖ Contour Integration

Cauchy residue theorem)

Let $f(z)$ be a function of the complex variable z and C be a closed path in the z -plane. If the $(k+1)$ -order derivative of $f(z)$ exists on and inside the contour C and **if $f(z)$ has no poles at z_0** , then

$$\frac{1}{2\pi j} \oint_C \frac{f(z)}{(z - z_0)^k} dz = \begin{cases} \frac{1}{(k-1)!} \left. \frac{d^{k-1} f(z)}{dz^{k-1}} \right|_{z=z_0} & \text{if } z_0 \text{ is inside } C \\ 0, & \text{if } z_0 \text{ is outside } C \end{cases}$$



Inverse z-Transform

In general, if $X(z)z^{n-1}$ is a rational function of z , it may be expressed as

$$X(z)z^{n-1} = \frac{f(z)}{(z - z_0)^m} \quad \boxed{x(n) = \frac{1}{2\pi j} \oint_C X(z)z^{n-1} dz}$$

where $X(z)z^{n-1}$ has m poles at $z = z_0$ and
 $f(z)$ has no poles at $z = z_0$

Note) **The residues of** $X(z)z^{n-1}$ at $z = z_0$ is given by

$$\text{Res} \left[X(z)z^{n-1} \text{ at } z = z_0 \right] = \frac{1}{(m-1)!} \left. \frac{d^{m-1} f(z)}{dz^{m-1}} \right|_{z = z_0}$$

Note) **First-order pole:** $m = 1$ at $z = z_0$

$$\text{Res} \left[X(z)z^{n-1} \text{ at } z = z_0 \right] = f(z_0)$$

Inverse z-Transform

Example) $X(z) = 1/(1 - az^{-1}) \quad |z| > |a|$

$$x(n) = \frac{1}{2\pi j} \oint_C \frac{z^{n-1}}{1 - az^{-1}} dz = \frac{1}{2\pi j} \oint_C \frac{\overset{f(z)}{\cancel{z^n}}}{\underset{z_0}{\cancel{z - a}}} dz$$

where C is a circle of a radius $|z| > |a|$

For $n \geq 0 \rightarrow$ one pole at $z = a \rightarrow x(n) = a^n, \quad n \geq 0$

Inverse z-Transform

❖ Power series expansion method

- Expand $X(z)$ into a power series of the form

$$X(z) = \sum_{n=-\infty}^{\infty} c_n z^{-n} \text{ in the given ROC}$$

$$\rightarrow x(n) = c_n$$

- When $X(z)$ is rational, the expansion can be done by long division
➔ closed-form solution is not possible

Inverse z-Transform

❖ Power series expansion method

- The function **impz** can be used to find the inverse of a rational z-transform $G(z)$
- **impz** computes the coefficients of the power series expansion of $G(z)$
- The number of coefficients can either be user specified or determined automatically

$[h, t] = \text{impz}(\text{num}, \text{den})$ or $\text{impz}(\text{num}, \text{den}, N)$ or $\text{impz}(\text{num}, \text{den}, N, F_s)$

Inverse z-Transform

❖ Power series expansion method

$$\frac{1}{1 - 1.5z^{-1} + 0.5z^{-2}}$$

(a) *ROC: $|z| > 1 \rightarrow$ Causal signal*

\rightarrow Find a power series expansion in negative powers of z by long division

$$1 - 1.5z^{-1} + 0.5z^{-2} \overline{) 1 + \frac{3}{2}z^{-1} + \frac{7}{4}z^{-2} + \dots}$$

n=[1]

d=[1 -1.5 0.5]

[h, t] = impz(n, d, 7)

h = { 1.0 1.5 1.75 1.875 1.9375 1.9688 1.9844 }

Inverse z-Transform

❖ Power series expansion method

- (b) *ROC: $|z| < 1 \rightarrow$ Noncausal signal*
 \rightarrow Find a power series expansion in positive powers of z by long division

$$\frac{1}{2}z^{-2} - \frac{3}{2}z^{-1} + 1 \left| \begin{array}{r} 2z^2 + 6z^3 + 14z^4 + \dots \\ 1 - 3z + 2z^2 \\ \hline 3z - 2z^2 \\ \vdots \end{array} \right.$$

Inverse z-Transform

❖ Partial-fraction expansion method

- A rational $G(z)$ can be expressed as

$$G(z) = \frac{P(z)}{D(z)} = \frac{\sum_{i=0}^M p_i z^{-i}}{\sum_{i=0}^N d_i z^{-i}}$$

- If $M \geq N$ then $G(z)$ can be re-expressed as

$$G(z) = \sum_{l=0}^{M-N} c_l z^{-l} + \frac{P_1(z)}{D(z)} \rightarrow \text{Proper function}$$

where degree of $P_1(z) < N$

Inverse z-Transform

❖ Partial-fraction expansion method: **Example**

$$\begin{aligned} G(Z) &= \frac{2 + 0.8z^{-1} + 0.5z^{-2} + 0.3z^{-3}}{1 + 0.8z^{-1} + 0.2z^{-2}} \\ &= -3.5 + 1.5z^{-1} + \frac{5.5 + 2.1z^{-1}}{1 + 0.8z^{-1} + 0.2z^{-2}} \\ &= -3.5 + 1.5z^{-1} + \frac{r_1}{1 - p_1z^{-1}} + \frac{r_2}{1 - p_2z^{-1}} \end{aligned}$$

Long division

Partial fraction expansion

$$\Rightarrow \underline{g(n) = -3.5\delta(n) + 1.5\delta(n-1) + (r_1p_1^n + r_2p_2^n)u(n)}$$

Note) For a real rational function, complex poles must occur in conjugate pairs. And, *If* $p_1 = p_2^*$, *then* $r_1 = r_2^*$

Inverse z-Transform

❖ Partial-fraction expansion method

- Simple poles: Generally, the rational z-transform of interest $X(z)$ is a proper fraction with “**simple poles**”

$$X(Z) = \frac{N(z)}{D(z)} = \frac{N(z)}{(1 - p_1 z^{-1})(1 - p_2 z^{-1}) \cdots (1 - p_N z^{-1})}$$

$p_1 \neq p_2 \neq \cdots \neq p_N$: *Simple Poles*

➔
$$X(z) = \sum_{i=1}^N \left(\frac{\overset{\text{residues}}{r_i}}{1 - p_i z^{-1}} \right)$$

Inverse z-Transform

❖ Partial-fraction expansion method

- The constants r_l (residues) are given by

$$r_l = (1 - p_l z^{-1}) X(z) \Big|_{z=p_l}$$

$$(1 - p_l z^{-1}) X(z) = (1 - p_l z^{-1}) \sum_{i=1}^N \left(\frac{r_i}{1 - p_i z^{-1}} \right) = r_l + \cancel{(1 - p_l z^{-1})} \sum_{i \neq l} \left(\frac{r_i}{1 - p_i z^{-1}} \right)$$

0 when $z = p_l$

- Each term of the sum in partial-fraction expansion has an ROC by $|z| > |p_l|$ and, thus

$$x(n) = (r_1 p_1^n + r_2 p_2^n + \cdots + r_N p_N^n) u(n)$$

Inverse z-Transform

❖ Partial-fraction expansion method

▪ Example

$$H(z) = \frac{z(z+2)}{(z-0.2)(z+0.6)} = \frac{1+2z^{-1}}{(1-0.2z^{-1})(1+0.6z^{-1})}$$

$$H(z) = \frac{r_1}{1-0.2z^{-1}} + \frac{r_2}{1+0.6z^{-1}}$$

$$r_1 = (1-0.2z^{-1})H(z)|_{z=0.2} = \frac{1+2z^{-1}}{1+0.6z^{-1}}|_{z=0.2} = 2.75$$

$$r_2 = (1+0.6z^{-1})H(z)|_{z=-0.6} = \frac{1+2z^{-1}}{1-0.2z^{-1}}|_{z=-0.6} = -1.75$$

$$\Rightarrow h[n] = 2.75(0.2)^n u(n) - 1.75(-0.6)^n u(n)$$

Inverse z-Transform

❖ Partial-fraction expansion method

■ Multiple poles

$$G(Z) = \frac{N(z)}{(1 - p_1 z^{-1})(1 - p_2 z^{-1}) \underline{(1 - \nu z^{-1})^L} \cdots (1 - p_N z^{-1})}$$

- Let the pole at $z = \nu$ be of multiplicity L and the remaining $N - L$ poles be simple and at $z = p_l, 1 \leq l \leq N - L$

Inverse z-Transform

❖ Partial-fraction expansion method

- Then the partial-fraction expansion of $G(z)$ is of the form

$$G(z) = \sum_{l=0}^{M-N} \eta_l z^{-l} + \sum_{i=1}^{N-L} \frac{r_i}{1 - p_i z^{-1}} + \sum_{i=1}^L \frac{\gamma_i}{(1 - \nu z^{-1})^i}$$

$$\gamma_i = \frac{1}{(L-i)!(-\nu)^{L-i}} \frac{d^{L-i}}{d(z^{-1})^{L-i}} \left[(1 - \nu z^{-1})^L G(z) \right]_{z=\nu},$$

$1 \leq i \leq L$

- The residues for simple poles are calculated as before

Inverse z-Transform

❖ Partial-fraction expansion method

- Using MATLAB: $[r,p,k]=\text{residuez}(\text{num},\text{den})$

develops the partial-fraction expansion of a rational z-transform with numerator and denominator coefficients given by vectors **num** and **den**

- Vector **r** contains the residues
- Vector **p** contains the poles
- Vector **k** contains the constants η_ℓ

$[\text{num},\text{den}]=\text{residuez}(r,p,k)$ converts a z-transform expressed in a partial-fraction expansion form to its rational form

Inverse z-Transform

$$G(z) = \frac{2 + 0.8z^{-1} + 0.5z^{-2} + 0.3z^{-3}}{1 + 0.8z^{-1} + 0.2z^{-2}}$$

$$G(z) = -3.5 + 1.5z^{-1} + \frac{5.5 + 2.1z^{-1}}{1 + 0.8z^{-1} + 0.2z^{-2}}$$

```
n = [2 0.8 0.5 0.3];  
d = [1 0.8 0.2];  
[r, p, k] = residuez(n, d);
```



$$\begin{array}{lll} r = 2.75 + 0.25i & p : -0.4 + 0.2i & k : -3.5 \\ & 2.75 - 0.25i & -0.4 - 0.2i & 1.5 \end{array}$$

$$G(z) = -3.5 + 1.5z^{-1} + \frac{r_0}{1 - p_0z^{-1}} + \frac{r_0^*}{1 - p_0^*z^{-1}}$$

$$g(n) = -3.5\delta(n) + 1.5\delta(n-1) + \underbrace{[r_0(p_0)^n + r_0^*(p_0^*)^n]u(n)}$$

$$r_0 = |r_0|e^{j\alpha_0} \text{ and } p_0 = |p_0|e^{j\beta_0} \quad \Downarrow$$

$$2|r_0| \cdot |p_0|^n \cdot \cos(\beta_0 n + \alpha_0)$$

Rational z-Transforms

$$H(z) = \frac{1}{1 - 0.9z^{-1} - 0.81z^{-2} + 0.729z^{-3}} = \frac{1}{(1 - 0.9z^{-1})^2(1 + 0.9z^{-1})}, \quad |z| > 0.9$$

n = 1;

d = [1 -0.9 -0.81 0.729];

[r, p, k]= residuez(n, d);

r: 0.25

0.5

0.25

p: 0.9

0.9

-0.9

K: []

$$H(z) = \frac{0.25}{1 - 0.9z^{-1}} + \frac{0.5}{(1 - 0.9z^{-1})^2} + \frac{0.25}{1 + 0.9z^{-1}}$$

$$H(z) = \frac{0.25}{1 - 0.9z^{-1}} + \frac{0.5}{0.9} z \frac{(0.9z^{-1})}{(1 - 0.9z^{-1})^2} + \frac{0.25}{1 + 0.9z^{-1}}$$

$$x(n) = 0.25(0.9)^n u(n) + \frac{5}{9}(n+1)(0.9)^{n+1} u(n+1) + 0.25(-0.9)^n u(n)$$

Time shifting

$x(n-k)$

$z^{-k}X(z)$

$$na^n u(n) \xleftrightarrow{z} X(z) = -z \frac{dX_1(z)}{dz} = \frac{az^{-1}}{(1 - az^{-1})^2} \quad |z| > |a|$$

Decomposition of rational z-transforms

❖ Rational z-transform

$$X(z) = \frac{\sum_{k=0}^M b_k z^{-k}}{1 + \sum_{k=1}^N a_k z^{-k}} = b_0 \frac{\prod_{k=1}^M (1 - z_k z^{-1})}{\prod_{k=1}^N (1 - p_k z^{-1})}$$

- $M \geq N$: Improper ➡ $X(z) = \sum_{k=0}^{M-N} c_k z^{-k} + X_{pr}(z)$

- Decomposition with real coefficients
complex conjugate poles are combined as

$$\begin{aligned} \frac{A}{1 - pz^{-1}} + \frac{A^*}{1 - p^* z^{-1}} &= \frac{A - Ap^* z^{-1} + A^* - A^* p z^{-1}}{1 - pz^{-1} - p^* z^{-1} + pp^* z^{-2}} \\ &= \frac{b_0 + b_1 z^{-1}}{1 + a_1 z^{-1} + a_2 z^{-2}} \end{aligned}$$

$b_0 = 2\operatorname{Re}(A),$	$a_1 = -2\operatorname{Re}(p)$
$b_1 = -2\operatorname{Re}(Ap^*),$	$a_2 = p ^2$

Decomposition of rational z-transforms

❖ General result

$$X(z) = \sum_{k=0}^{M-N} c_k z^{-k} + \sum_{k=1}^{K_1} \frac{b_k}{1 + a_k z^{-1}} + \sum_{k=1}^{K_2} \frac{b_{0k} + b_{1k} z^{-1}}{1 + a_{1k} z^{-1} + a_{2k} z^{-2}}$$

where $K_1 + 2K_2 = N$

- If $M=N$, $c_0 = \text{const}$
- If $M < N$, no FIR terms

Note: Higher order terms should exist when there are multiple poles.

Decomposition of rational z-transforms

❖ Decomposition into products of simple terms

$$\frac{(1 - z_k z^{-1})(1 - z_k^* z^{-1})}{(1 - p_k z^{-1})(1 - p_k^* z^{-1})} = \frac{1 + b_{1k} z^{-1} + b_{2k} z^{-2}}{1 + a_{1k} z^{-1} + a_{2k} z^{-2}}$$

$$b_{1k} = -2 \operatorname{Re}(z_k), \quad a_{1k} = -2 \operatorname{Re}(p_k)$$

where

$$b_{2k} = |z_k|^2, \quad a_{2k} = |p_k|^2$$

$$\Rightarrow X(z) = b_0 \prod_{k=1}^{K_1} \frac{1 + b_k z^{-1}}{1 + a_k z^{-1}} \prod_{k=1}^{K_2} \frac{1 + b_{1k} z^{-1} + b_{2k} z^{-2}}{1 + a_{1k} z^{-1} + a_{2k} z^{-2}}$$

$$\text{where } N = K_1 + 2K_2$$