

# Chapter 8

## IIR Filters

# SECOND-ORDER FILTERS

- Two FEEDBACK TERMS

$$y[n] = a_1 \overset{\downarrow}{y}[n-1] + a_2 \overset{\downarrow}{y}[n-2] + b_0 x[n] + b_1 x[n-1] + b_2 x[n-2]$$

$$H(z) = \frac{b_0 + b_1 z^{-1} + b_2 z^{-2}}{1 - a_1 z^{-1} - a_2 z^{-2}}$$



# Example: SECOND-ORDER FILTERS

$$\frac{1 - 0.45z^{-1}}{1 - 0.9z^{-1} + 0.81z^{-2}}$$

$$y[n] = 0.9y[n-1] - 0.81y[n-2] + x[n] - 0.45x[n-1]$$

```
aa = [ 1, -0.9, 0.81 ];
bb = [ 1, -0.45 ];
hh = filter( bb, aa, xx );
HH = freqz( bb, aa, [-pi:pi/100:pi] );
```

# Implementation of second-order IIR filters (1)

- Difference equation

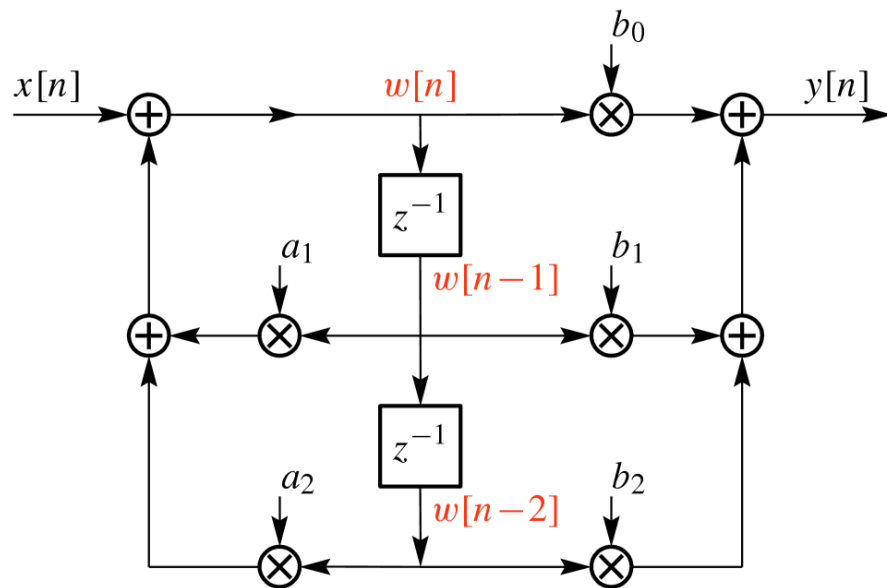
$$y[n] = a_1 y[n-1] + a_2 y[n-2] \\ + b_0 x[n] + b_1 x[n-1] + b_2 x[n-2]$$

- System function

$$H(z) = \frac{1}{1 - a_1 z^{-1} - a_2 z^{-2}} (b_0 + b_1 z^{-1} + b_2 z^{-2}) = \frac{1}{A(z)} B(z)$$

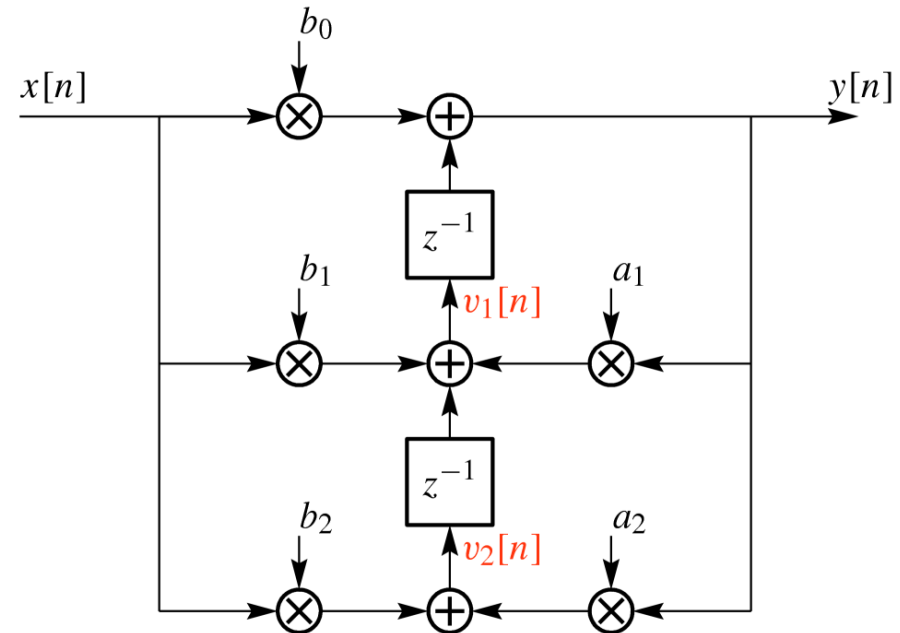
# Implementation of second-order IIR filters (2)

## Direct Form II Structure



McClellan, Schafer and Yoder, *Signal Processing First*, ISBN 0-13-065562-7.  
Pearson Prentice Hall, Inc. Upper Saddle River, NJ 07458. © 2003

## Transposed Direct Form II Structure



McClellan, Schafer and Yoder, *Signal Processing First*, ISBN 0-13-065562-7.  
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# POLES OF SECOND-ORDER FILTERS

- The Denominator is QUADRATIC.
  - 2 Poles: REAL  
or COMPLEX **CONJUGATES**

$$\frac{a_1 \pm \sqrt{a_1^2 + 4a_2}}{2}$$

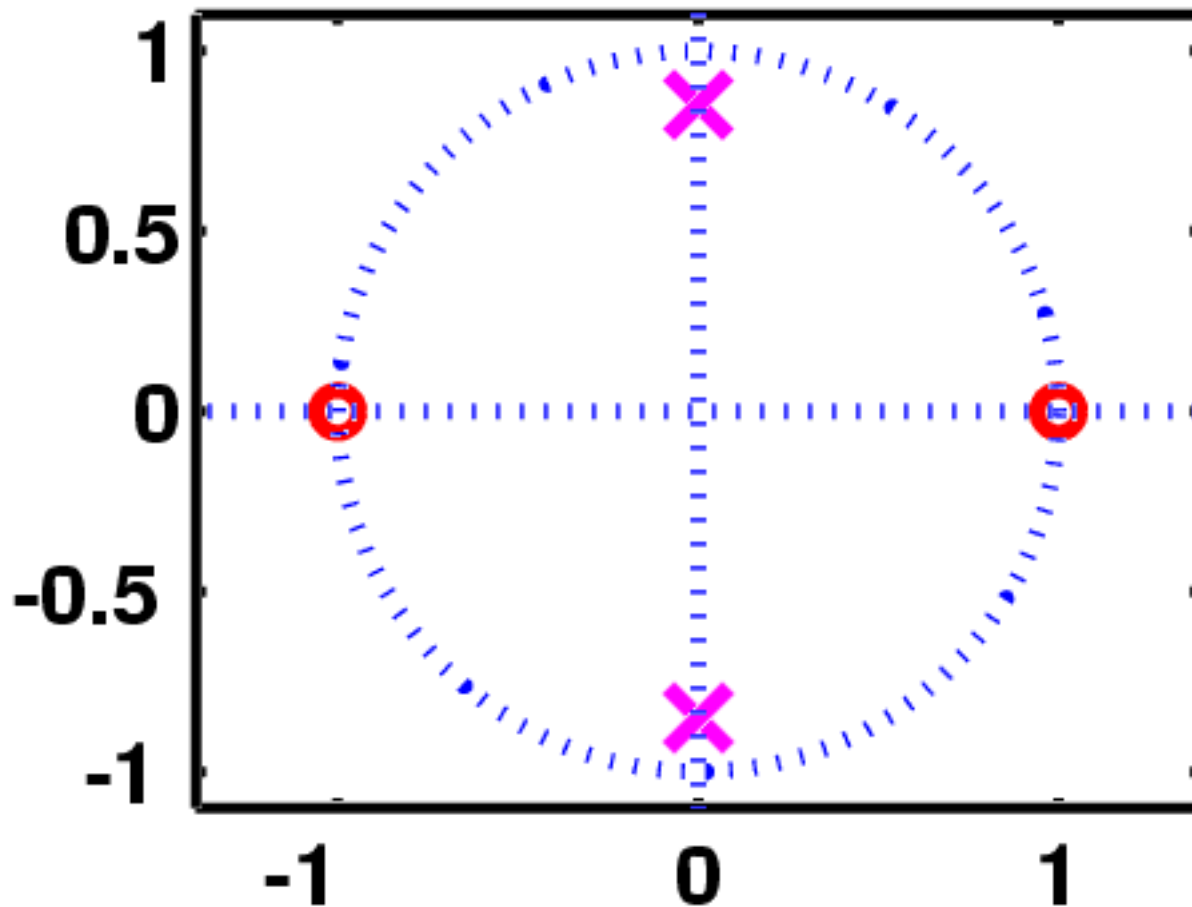
$$H(z) = \frac{b_0 + b_1 z^{-1} + b_2 z^{-2}}{1 - a_1 z^{-1} - a_2 z^{-2}} = \frac{b_0 z^2 + b_1 z + b_2}{z^2 - a_1 z - a_2}$$

## PROPERTY OF REAL POLYNOMIALS

*A polynomial of degree  $N$  has  $N$  roots. If all the coefficients of the polynomial are real, the roots either must be real, or must occur in complex conjugate pairs.*

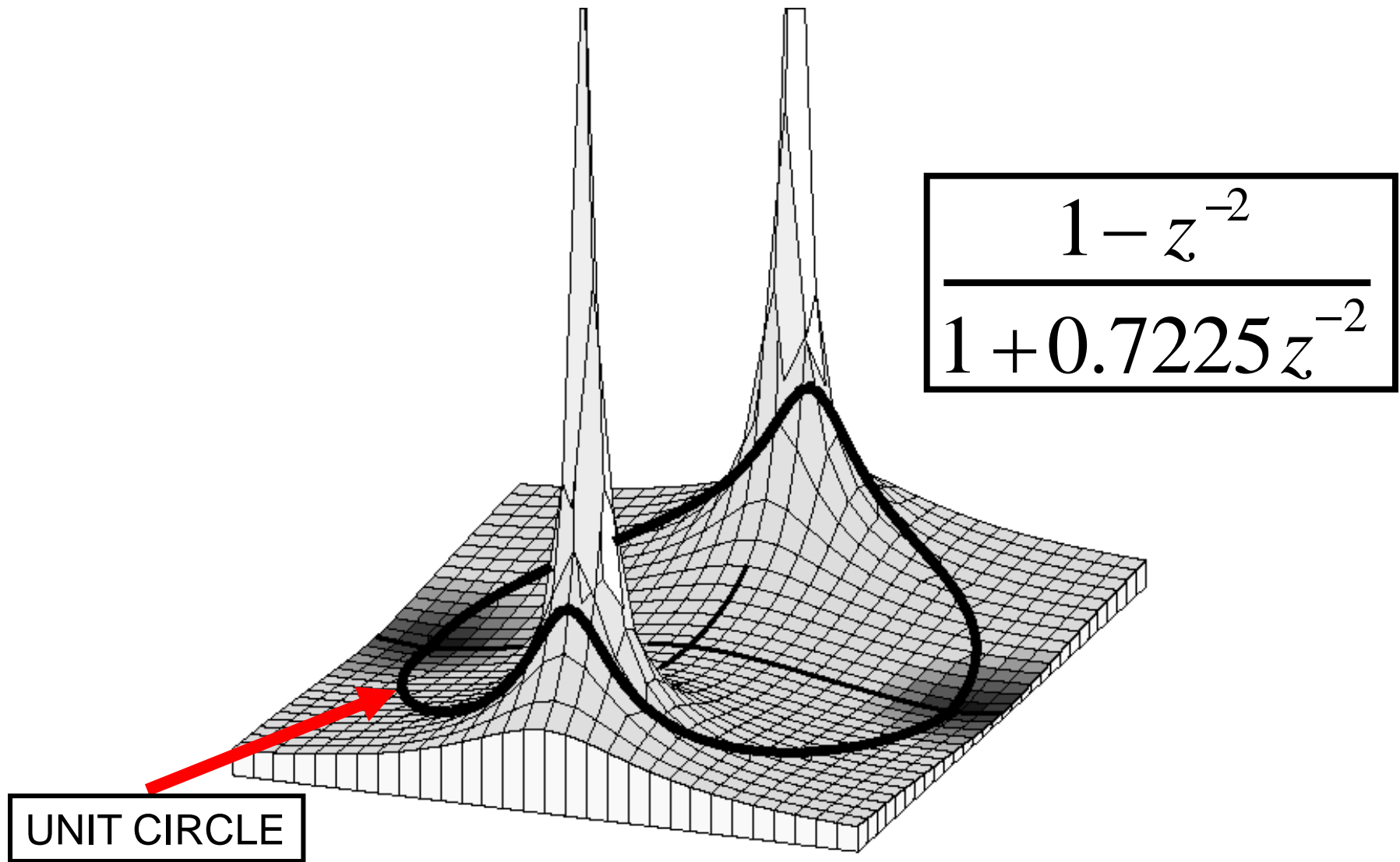


# Complex POLE-ZERO PLOT



$$\frac{1 - z^{-2}}{1 + 0.7225z^{-2}}$$

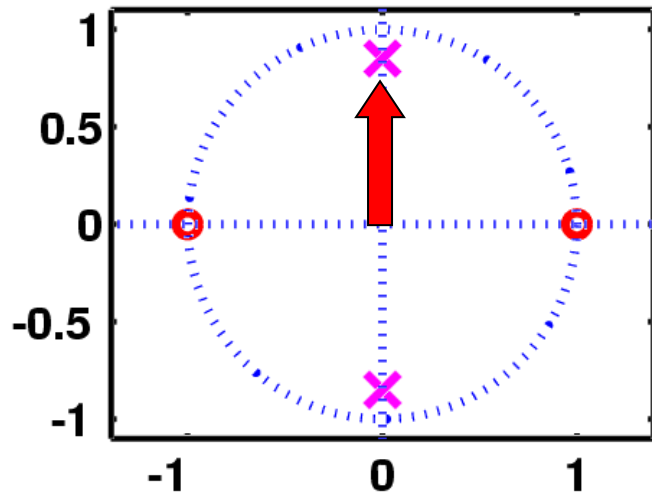
# 3-D VIEW



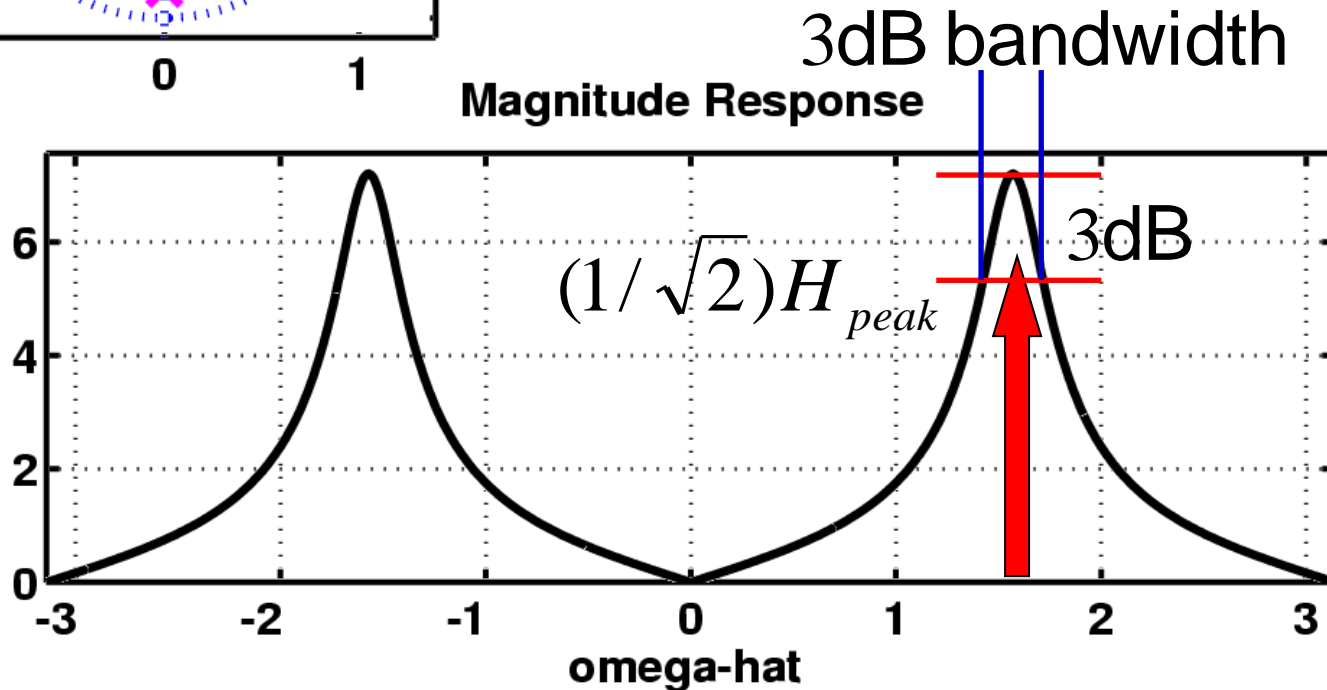
The poles are at  $z = 0.85e^{\pm j\pi/2}$  and the zeros at  $z = \pm 1$ .



# FREQ. RESPONSE from POLES & ZEROS



$$H(e^{j\hat{\omega}}) = \frac{1 - e^{-j2\hat{\omega}}}{1 + 0.7225e^{-j2\hat{\omega}}}$$



# TWO COMPLEX POLES

- Find the Impulse Response ?

- Can OSCILLATE vs.  $n$ .

- "RESONANCE"

$$(p_k)^n = (re^{j\theta})^n = r^n e^{jn\theta}$$

- Find the **FREQUENCY RESPONSE.**

- Depends on the Pole Location.

- Close to the Unit Circle?

- Correspond to a high peak.

- Make the **BANDPASS FILTER.**

$$\text{pole} = re^{j\theta}$$

$$r \rightarrow 1?$$

## 2nd ORDER z-transform PAIR (1)

$$h[n] = Ar^n \cos(\theta n + \varphi)u[n] = Ar^n \frac{1}{2} (e^{j(\theta n + \varphi)} + e^{-j(\theta n + \varphi)})u[n]$$

$$H(z) = A \frac{1}{2} \left( \frac{e^{j\varphi}}{1 - re^{j\theta} z^{-1}} + \frac{e^{-j\varphi}}{1 - re^{-j\theta} z^{-1}} \right)$$

$$H(z) = A \frac{1}{2} \left( \frac{e^{j\varphi} - re^{-j(\theta - \varphi)} z^{-1} + e^{-j\varphi} - re^{j(\theta - \varphi)} z^{-1}}{1 - 2r \cos \theta z^{-1} + r^2 z^{-2}} \right)$$

$$H(z) = A \frac{\cos \varphi - r \cos(\theta - \varphi) z^{-1}}{1 - 2r \cos \theta z^{-1} + r^2 z^{-2}}$$

## 2nd ORDER z-transform PAIR (2)

$$h[n] = Ar^n \cos(\theta n + \varphi)u[n]$$

$$H(z) = A \frac{\cos \varphi - r \cos(\theta - \varphi)z^{-1}}{1 - 2r \cos \theta z^{-1} + r^2 z^{-2}}$$

$$h[n] = r^n \cos(\theta n)u[n]$$

$$H(z) = \frac{1 - r \cos \theta z^{-1}}{1 - 2r \cos \theta z^{-1} + r^2 z^{-2}}$$

## 2nd ORDER EXAMPLE

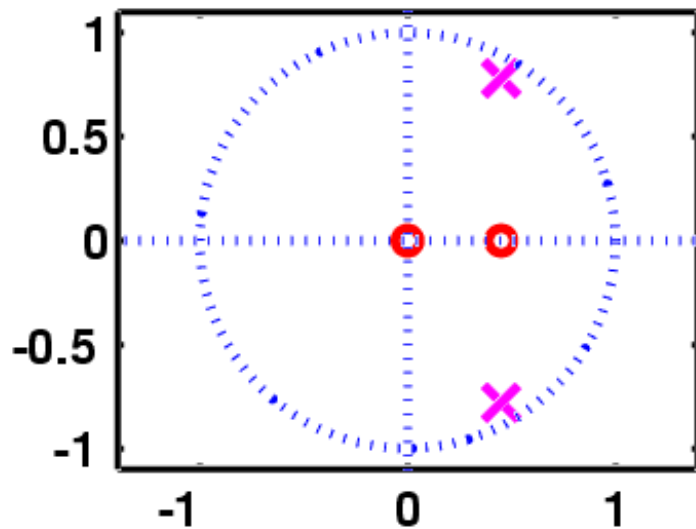
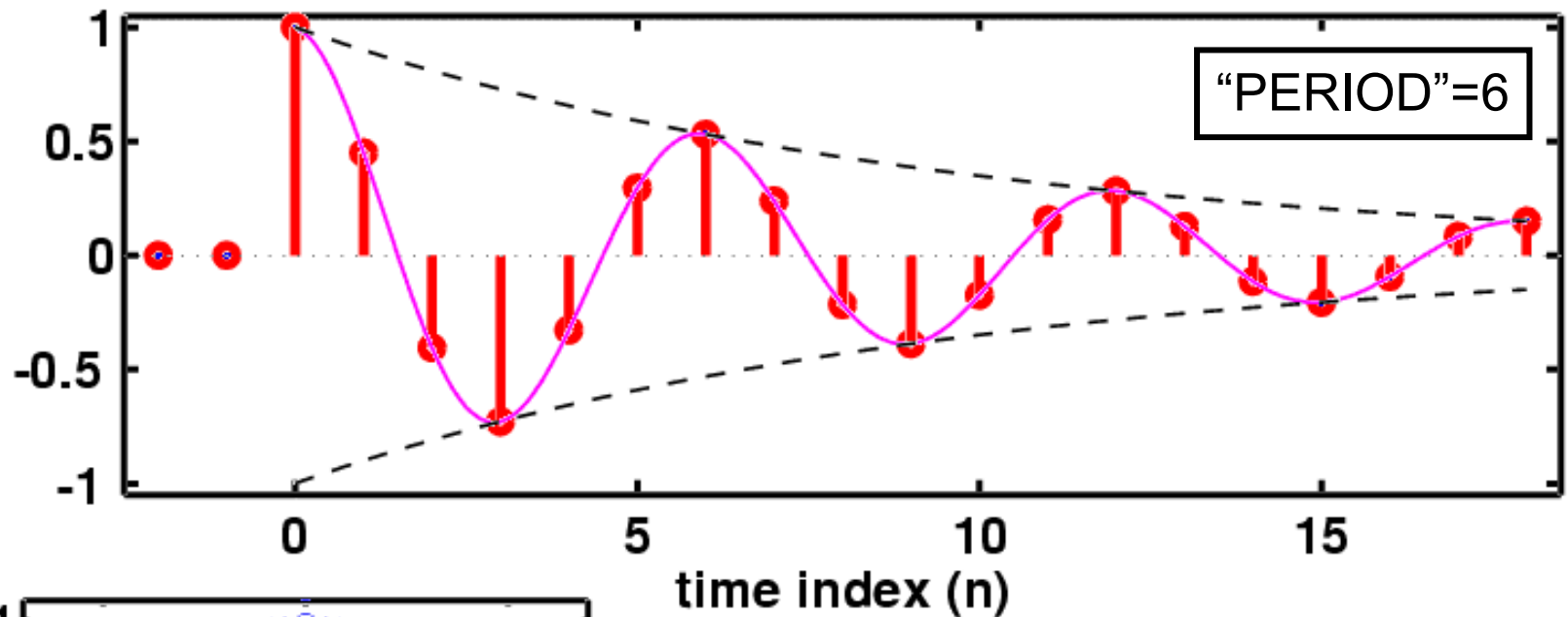
$$h[n] = (0.9)^n \cos\left(\frac{\pi}{3}n\right)u[n] = (0.9)^n \frac{1}{2} (e^{j\pi n/3} + e^{-j\pi n/3})u[n]$$

$$H(z) = \frac{0.5}{1 - 0.9e^{j\pi/3}z^{-1}} + \frac{0.5}{1 - 0.9e^{-j\pi/3}z^{-1}}$$

$$H(z) = \frac{1 - 0.9\cos\left(\frac{\pi}{3}\right)z^{-1}}{(1 - 0.9e^{j\pi/3}z^{-1})(1 - 0.9e^{-j\pi/3}z^{-1})}$$

$$H(z) = \frac{1 - 0.45z^{-1}}{1 - 0.9z^{-1} + 0.81z^{-2}}$$

# $h[n]$ Decays & Oscillates.

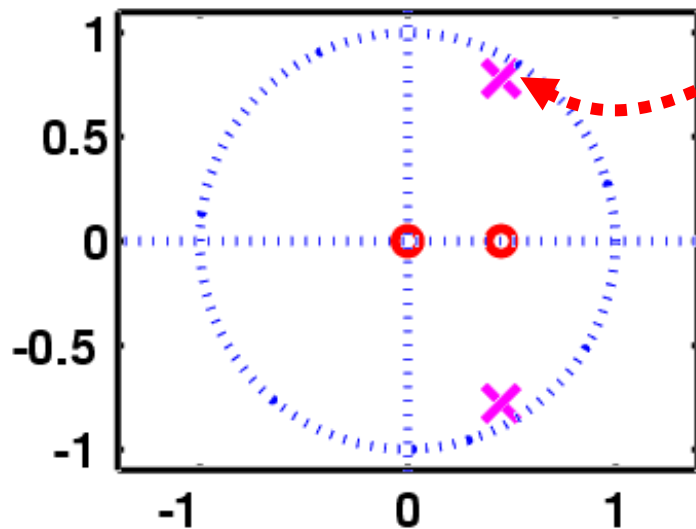
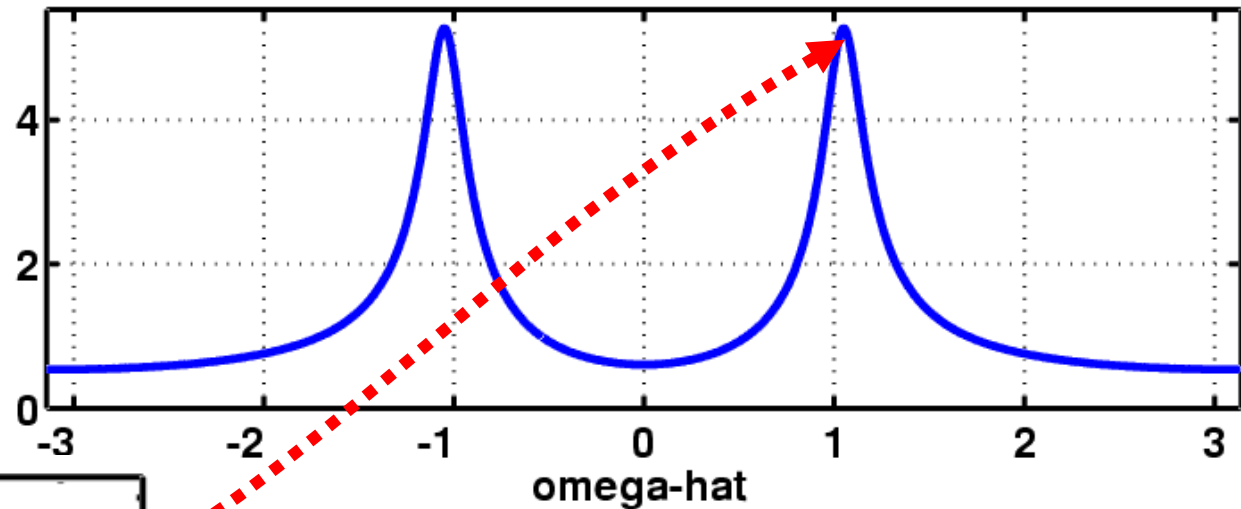


$$h[n] = (0.9)^n \cos\left(\frac{\pi}{3} n\right) u[n]$$

$$\frac{1 - 0.45z^{-1}}{1 - 0.9z^{-1} + 0.81z^{-2}}$$

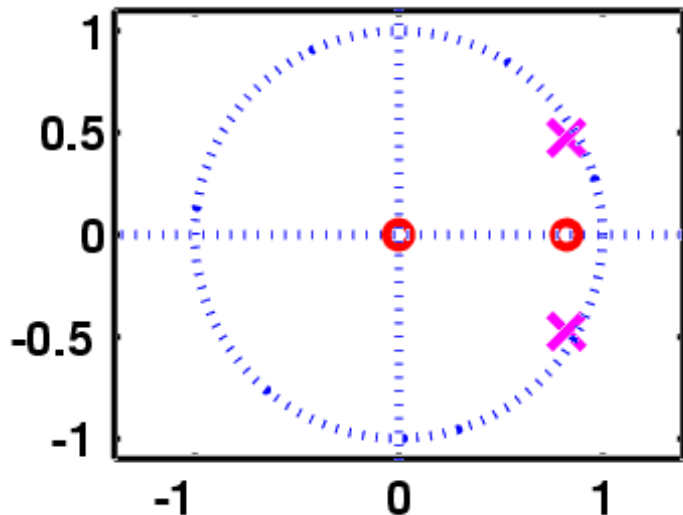
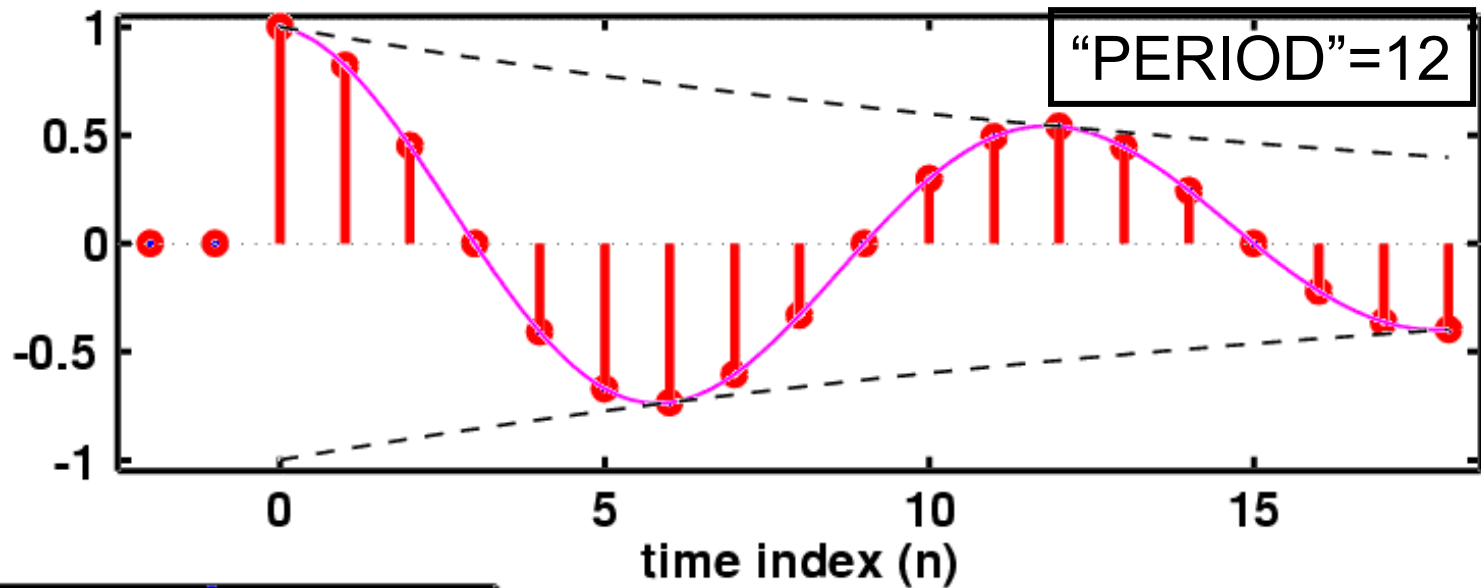
# FREQ. RESPONSE from POLES & ZEROS

Magnitude Response



$$\frac{1 - 0.45z^{-1}}{1 - 0.9z^{-1} + 0.81z^{-2}}$$

# $h[n]$ Decays & Oscillates.



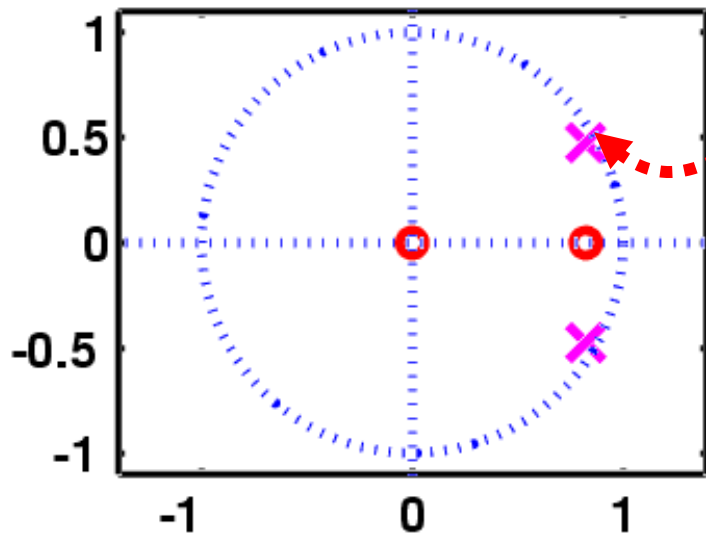
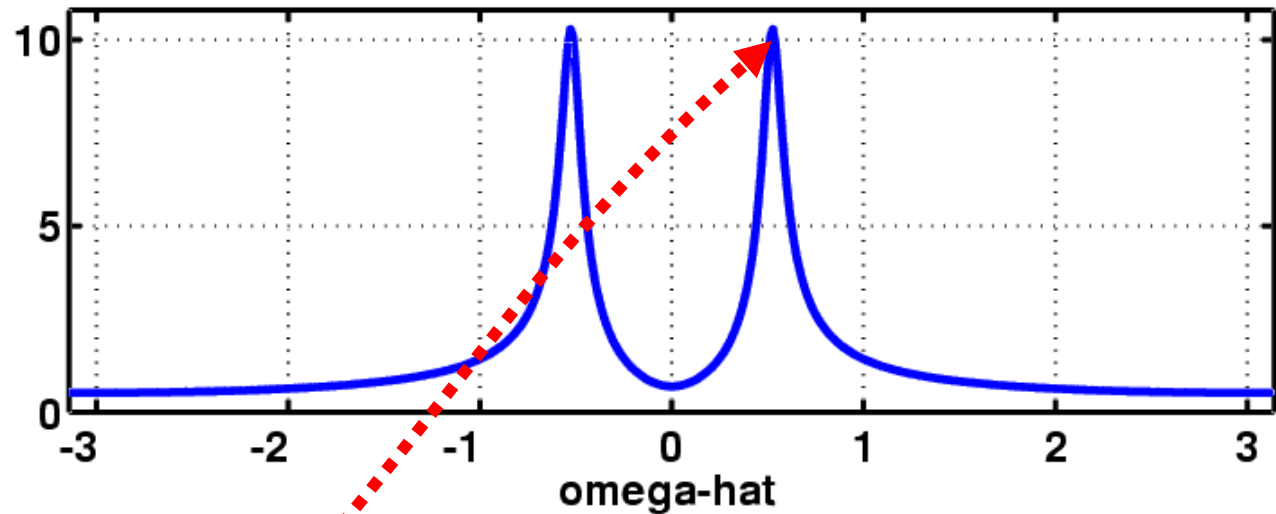
$$h[n] = (0.95)^n \cos\left(\frac{\pi}{6} n\right) u[n]$$

$$\frac{1 - 0.8227z^{-1}}{1 - 1.6454z^{-1} + 0.9025z^{-2}}$$



# FREQ. RESPONSE from POLES & ZEROS

Magnitude Response



$$\frac{1 - 0.8227z^{-1}}{1 - 1.6454z^{-1} + 0.9025z^{-2}}$$

# CALCULATE the RESPONSE.

$$x[n] = e^{j\hat{\omega}_0 n} u[n]$$

$$X(z) = \frac{1}{1 - e^{j\hat{\omega}_0} z^{-1}}$$

$$H(z)$$

$$Y(z) = H(z)X(z) = \left( \frac{b_0}{1 - a_1 z^{-1}} \right) \left( \frac{1}{1 - e^{j\hat{\omega}_0} z^{-1}} \right)$$

Use the z-Transform Method  
and the PARTIAL FRACTION EXPANSION.

# GENERAL INVERSE $z$ -TRANSFORM

## PROCEDURE FOR INVERSE $z$ -TRANSFORMATION ( $M < N$ )

1. Factor the denominator polynomial of  $H(z)$  and express the pole factors in the form  $(1 - p_k z^{-1})$  for  $k = 1, 2, \dots, N$ .
2. Make a partial fraction expansion of  $H(z)$  into a sum of terms of the form

$$H(z) = \sum_{k=1}^N \frac{A_k}{1 - p_k z^{-1}} \quad \text{where} \quad A_k = H(z)(1 - p_k z^{-1}) \Big|_{z=p_k}$$

3. Write down the answer as

$$h[n] = \sum_{k=1}^N A_k (p_k)^n u[n]$$



# SPLIT $Y(z)$ . (1)

Partial Fraction Expansion

$$Y(z) = \left( \frac{b_0}{1 - a_1 z^{-1}} \right) \left( \frac{1}{1 - e^{j\hat{\omega}_0} z^{-1}} \right) = \frac{A}{1 - a_1 z^{-1}} + \frac{B}{1 - e^{j\hat{\omega}_0} z^{-1}}$$

$$Y(z)(1 - a_1 z^{-1}) \Big|_{z=a_1} = A + \frac{B(1 - a_1 z^{-1})}{1 - e^{j\hat{\omega}_0} z^{-1}} \Big|_{z=a_1} = A$$

$$A = Y(z)(1 - a_1 z^{-1}) \Big|_{z=a_1} = \frac{b_0}{1 - e^{j\hat{\omega}_0} z^{-1}} \Big|_{z=a_1} = \frac{b_0}{1 - e^{j\hat{\omega}_0} a_1^{-1}}$$

$$B = Y(z)(1 - e^{j\hat{\omega}_0} z^{-1}) \Big|_{z=e^{j\hat{\omega}_0}} = \frac{b_0}{1 - a_1 z^{-1}} \Big|_{z=e^{j\hat{\omega}_0}} = \frac{b_0}{1 - a_1 e^{-j\hat{\omega}_0}}$$



# SPLIT $Y(z)$ . (2)

$$Y(z) = H(z)X(z) = \left( \frac{b_0}{1 - a_1 z^{-1}} \right) \left( \frac{1}{1 - e^{j\hat{\omega}_0} z^{-1}} \right)$$

$$Y(z) = \frac{A}{1 - a_1 z^{-1}} + \frac{B}{1 - e^{j\hat{\omega}_0} z^{-1}}$$

$$= \frac{(A + B) + (-a_1 B - e^{j\hat{\omega}_0} A) z^{-1}}{(1 - a_1 z^{-1})(1 - e^{j\hat{\omega}_0} z^{-1})}$$

$$\Rightarrow (A + B) = b_0 \text{ and } (-a_1 B - e^{j\hat{\omega}_0} A) = 0$$

# INVERT $Y(z)$ to $y[n]$ .

- Use the z-Transform Table.

$$Y(z) = \frac{\left( \frac{b_0 a_1}{a_1 - e^{j\hat{\omega}_0}} \right)}{1 - a_1 z^{-1}} + \frac{\left( \frac{b_0}{1 - a_1 e^{-j\hat{\omega}_0}} \right)}{1 - e^{j\hat{\omega}_0} z^{-1}}$$

$$y[n] = \left( \frac{b_0 a_1}{a_1 - e^{j\hat{\omega}_0}} \right) (a_1)^n u[n] + \left( \frac{b_0}{1 - a_1 e^{-j\hat{\omega}_0}} \right) e^{j\hat{\omega}_0 n} u[n]$$

# TWO PARTS of $y[n]$

- **TRANSIENT Component**

- Acts like  $(a_1)^n$ .
- Dies out ?
  - If  $|a_1| < 1$

$$\left( \frac{b_0 a_1}{a_1 - e^{j\hat{\omega}_0}} \right) a_1^n u[n]$$

- **STEADY-STATE Component**

- Depends on the input.
- e.g., Sinusoidal

$$\left( \frac{b_0}{1 - a_1 e^{-j\hat{\omega}_0}} \right) e^{j\hat{\omega}_0 n} u[n]$$

# STEADY-STATE COMPONENT

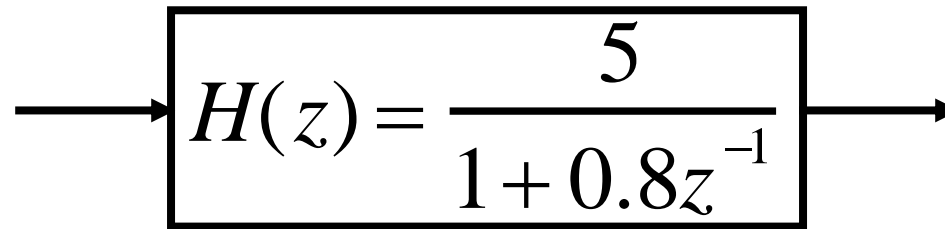
- When the Transient component dies out...
- Limit as “ $n$ ” approaches infinity.
- Use the Frequency Response to get the Magnitude & the Phase for a sinusoid.

$$y[n] \rightarrow y_{ss}[n] = \left( \frac{b_0}{1 - a_1 e^{-j\hat{\omega}_0}} \right) e^{j\hat{\omega}_0 n}$$
$$= H(e^{j\hat{\omega}_0}) e^{j\hat{\omega}_0 n}$$



# THREE INPUTS

- Given:



- Find the output,  $y[n]$ .

- When

$$x[n] = \cos(0.2\pi n)$$

$$x[n] = u[n]$$

$$x[n] = \cos(0.2\pi n)u[n]$$

# SINUSOID RESPONSE

- Given:

$$H(z) = \frac{5}{1 + 0.8z^{-1}}$$

- The input:

$$x[n] = \cos(0.2\pi n)$$

- Then  $y[n]$

$$y[n] = M \cos(0.2\pi n + \psi)$$

$$H(e^{j0.2\pi}) = \frac{5}{1 + 0.8e^{-j0.2\pi}} = 2.92e^{j0.28}$$

# Step Response (1)

- Given:

$$H(z) = \frac{5}{1 + 0.8z^{-1}}$$

- The input:

$$x[n] = u[n]$$

$$X(z) = \frac{1}{1 - z^{-1}}$$

- Then  $y[n]$

## Step Response (2)

$$Y(z) = H(z)X(z) = \left( \frac{5}{1 + .8z^{-1}} \right) \left( \frac{1}{1 - z^{-1}} \right)$$

$$Y(z) = \frac{\frac{20}{9}}{1 + .8z^{-1}} + \frac{\frac{25}{9}}{1 - z^{-1}}$$

$$y[n] = \frac{20}{9}(-.8)^n u[n] + \frac{25}{9} u[n]$$

Transient

Steady-State

$$y[n] \rightarrow \frac{25}{9} \quad \text{as} \quad n \rightarrow \infty$$



# SINUSOID Starting at $n=0$ (1)

- Given:

$$H(z) = \frac{5}{1 + 0.8z^{-1}}$$

- The input:

$$\begin{aligned} x[n] &= \cos(0.2\pi n)u[n] \\ &= \Re\{e^{j0.2\pi n}u[n]\} \end{aligned}$$

- Then  $y[n]$

$$y[n] = \Re\{5(-0.8)^n u[n] * e^{j0.2\pi n} u[n]\}$$

# SINUSOID Starting at $n=0$ (2)

$$y[n] = \Re\{5(-0.8)^n u[n] * e^{j0.2\pi n} u[n]\}$$

$$Y(z) = H(z)X(z) = \frac{5}{1+0.8z^{-1}} \frac{1}{1-e^{j0.2\pi} z^{-1}}$$

$$Y(z) = \frac{\frac{5}{1+1.25e^{j0.2\pi}}}{1+0.8z^{-1}} + \frac{\frac{5}{1+0.8e^{-j0.2\pi}}}{1-e^{j0.2\pi} z^{-1}}$$

$$= \frac{2.19 - j0.8}{1+0.8z^{-1}} + \frac{2.81 + j0.8}{1-e^{j0.2\pi} z^{-1}}$$

$$H(e^{j0.2\pi})$$

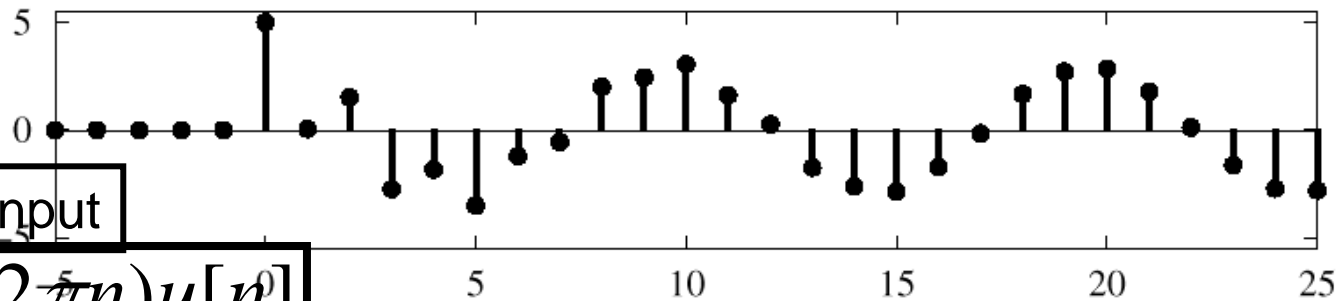
$$y[n] = \Re\{(2.19 - j0.8)(-0.8)^n u[n] + 2.92e^{j0.28} e^{j0.2\pi n} u[n]\}$$

$$y[n] = 2.19(-0.8)^n u[n] + 2.92 \cos(0.2\pi n + 0.28)u[n]$$



# SINUSOID Starting at $n=0$ (3)

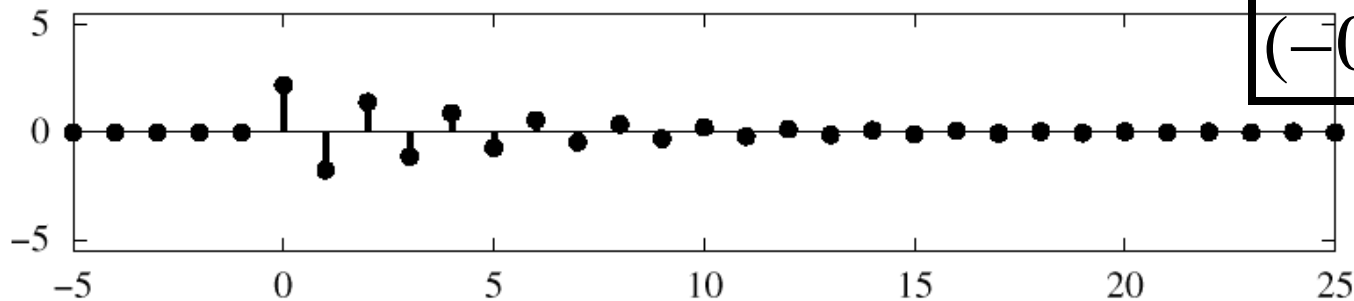
Real Part of Output  $y[n]$  for IIR Filters  $b = [5]$ ,  $a = [1, 0.8]$



Cosine input

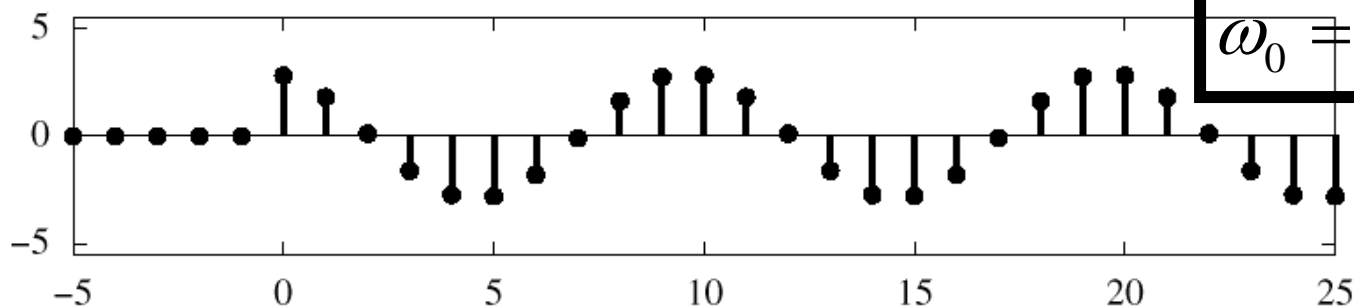
$$\cos(0.2\pi n)u[n]$$

Transient Real Part of Output  $y[n]$  for IIR Filters



$$(-0.8)^n$$

Steady-State Real Part of Output  $y[n]$  for IIR Filters



$$\omega_0 = 0.2\pi$$

Time Index ( $n$ )



# Stability (1)

- When Does the TRANSIENT DIE OUT ?

## STEADY-STATE RESPONSE AND STABILITY

A stable system is one that does not “blow up.” This intuitive statement can be formalized by saying that the output of a stable system can always be bounded ( $|y[n]| < M_y$ ) whenever the input is bounded ( $|x[n]| < M_x$ ).<sup>3</sup>

$$y[n] = a_1 y[n-1] + b_0 x[n]$$

$$H(z) = \frac{b_0}{1 - a_1 z^{-1}}$$

$$h[n] = b_0 a_1^n u[n]$$

need  $|a_1| < 1$

- If  $|a| \geq 1$ , the impulse response will not die out.
  - May produce unbounded outputs even if the input is bounded.





# Stability (2)

- Nec. & suff. condition: 
$$\sum_{n=-\infty}^{\infty} |h[n]| < \infty$$

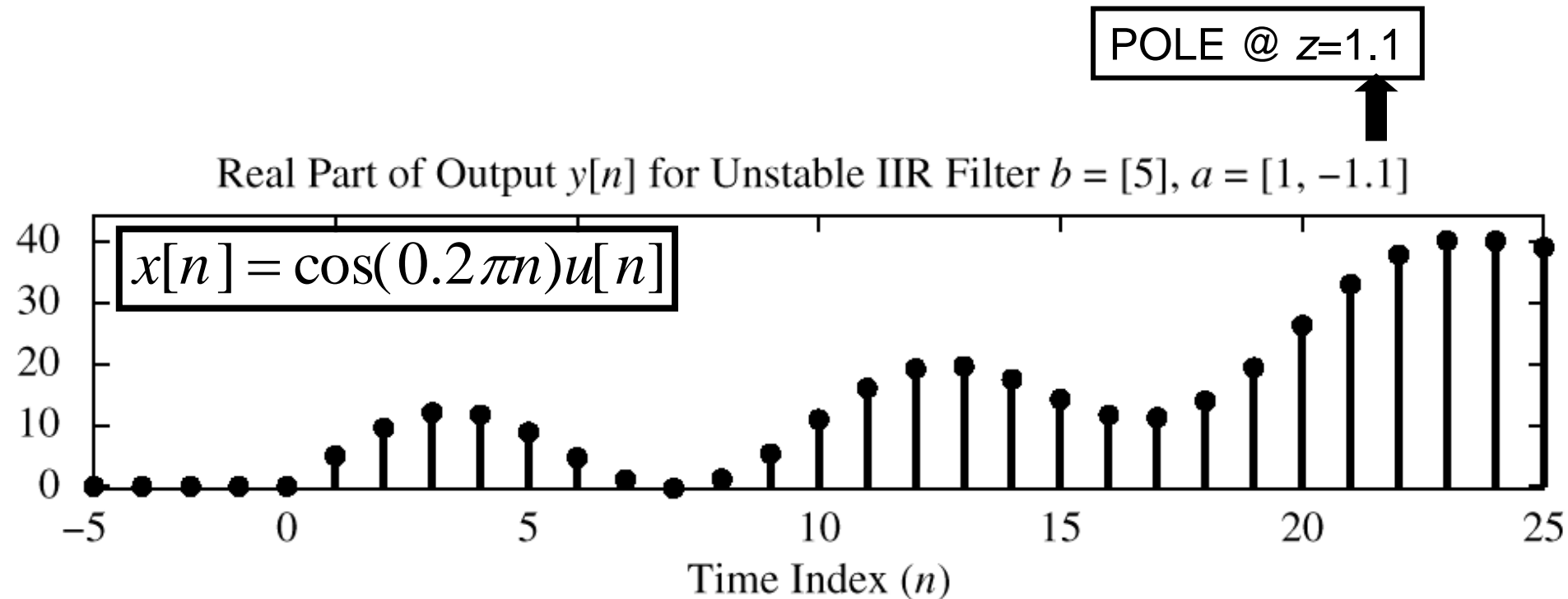
$$h[n] = b(a)^n u[n] \Leftrightarrow H(z) = \frac{b}{1 - az^{-1}}$$

$$\sum_{n=0}^{\infty} |b||a|^n < \infty \text{ if } |a| < 1 \Rightarrow \text{Poles must be inside the unit circle.}$$



# STABILITY CONDITION

- ALL POLES LIE INSIDE the UNIT CIRCLE.
- UNSTABLE EXAMPLE:



**Figure 8.15** Illustration of an unstable IIR system. Pole is at  $z = 1.1$ .

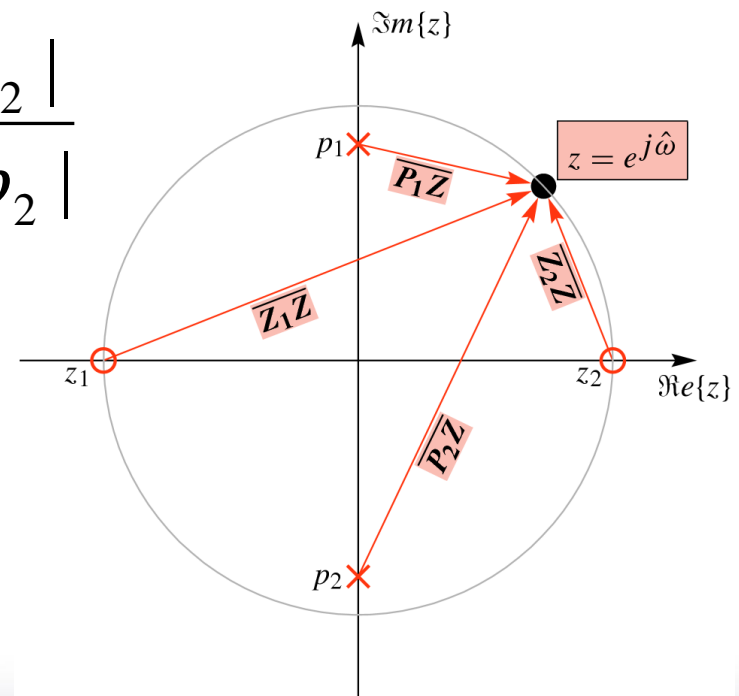
# Magnitude of the frequency response

- System function

$$H(z) = G \frac{(z - z_1)(z - z_2)}{(z - p_1)(z - p_2)}$$

- Magnitude of the frequency response

$$\begin{aligned} |H(e^{j\hat{\omega}})| &= G \frac{|e^{j\hat{\omega}} - z_1| |e^{j\hat{\omega}} - z_2|}{|e^{j\hat{\omega}} - p_1| |e^{j\hat{\omega}} - p_2|} \\ &= G \frac{\overline{Z_1 Z} \cdot \overline{Z_2 Z}}{\overline{P_1 Z} \cdot \overline{P_2 Z}} \end{aligned}$$



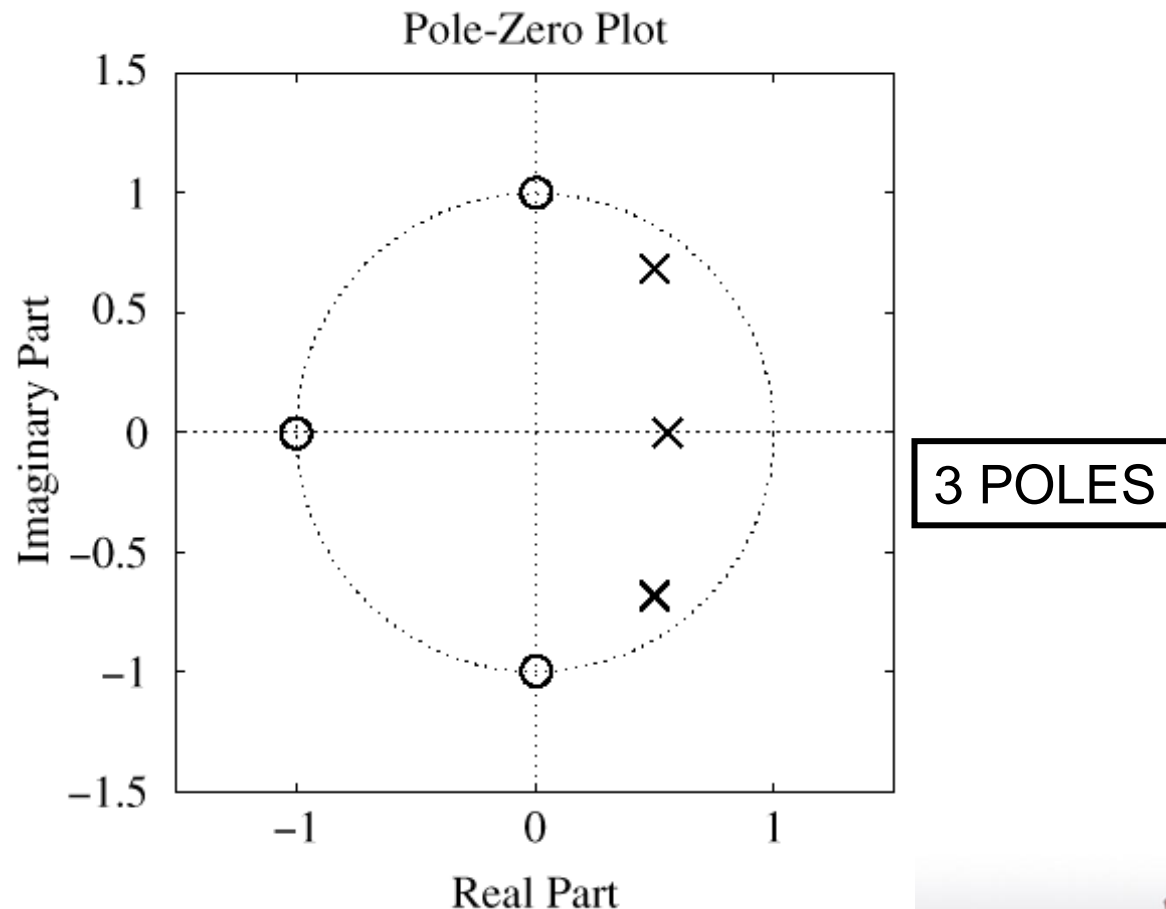
# IIR Elliptic LPF ( $N=3$ ) (1)

- Higher-order IIR filters
  - Realize frequency responses with flatter passbands and stopbands and sharper transition regions.
- Matlab functions to design filters with prescribed frequency-selective characteristics
  - butter, cheby1, cheby2, and ellip
- Lowpass elliptic filter
  - Coefficients were obtained using the Matlab function ellip.



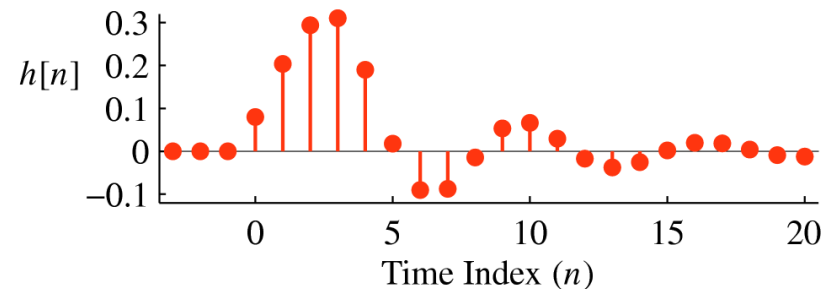
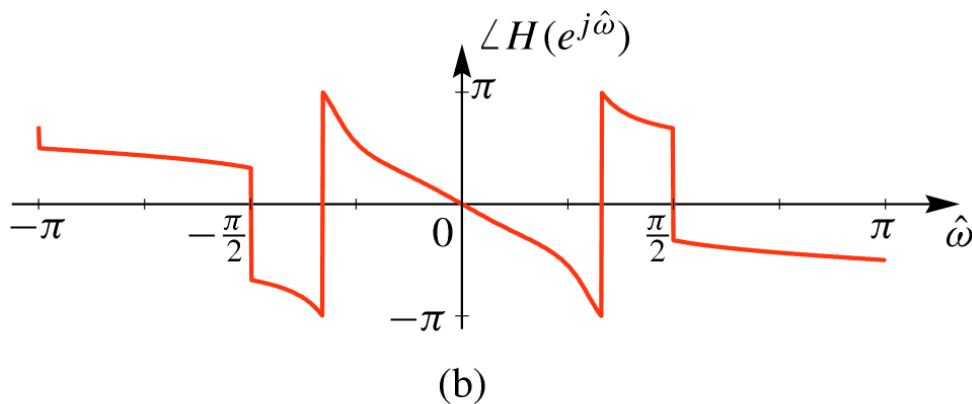
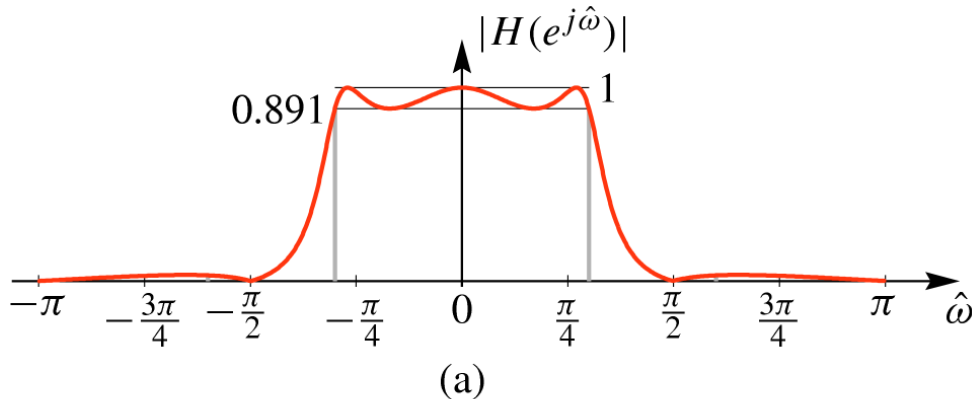
# IIR Elliptic LPF ( $N=3$ ) (2)

- `ellip(3,1,30,0.3)`  
(order, ripple(dB), att.(dB), bandwidth)



# IIR Elliptic LPF ( $N=3$ ) (3)

- Passband:  $|\hat{\omega}| \leq 2\pi(0.15)$



McClellan, Schafer and Yoder, *Signal Processing First*, ISBN 0-13-065562-7.  
Pearson Prentice Hall, Inc. Upper Saddle River, NJ 07458. © 2003

# Thank you

- Homework
  - P-8.5, 12(a,b), 16, 17, 19, 20, 22
- Reading assignment
  - ~ Section 9.5

