Nested HEX-Programs

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- 3 Nested HEX-Programs
- 4 Applications
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Motivation

Answer-Set Programming and HEX

- Declarative programming formalism
- Shortcomings: No reasoning about subresults
 - Modular programming [JOTW09, EGV97]
 - Meta-reasoning over multiple answer sets
 - XASP [XBG07]: Call LPs under stable model semantics from XSB-Prolog
 - HEX-programs: Calls of procedural external sources

Motivation

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 - HEX-programs: Calls of procedural external sources

Goal

- Fully declarative means for subprogram calls
- Relational input; Answer sets of subprograms = identifible objects

Example

- Suppose *P* computes shortest paths between two nodes in a graph
- Question: How to count the shortest paths (=answer sets of P)?

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Preliminaries

Definition (HEX-programs)

A HEX-program consists of rules of form

$$a_1 \vee \cdots \vee a_n \leftarrow b_1, \ldots, b_m, \text{ not } b_{m+1}, \ldots, \text{ not } b_n,$$

with classical literals a_i , and classical literals or an external atoms b_i .

Definition (External Atoms)

An external atom is of the form

&
$$p[q_1,\ldots,q_k](t_1,\ldots,t_l),$$

where

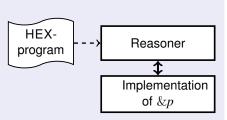
p . . . external predicate name or constants

 $q_i \dots$ predicate names

 t_j ... terms

Implementation: C++ function

Input: Extensions of q_i Output: Set of l-Tuples



Example

The &rdf External Atom

- Input: URL
- Output: Set of triples from RDF file

Usage

External knowledge base is a set of RDF files on the web:

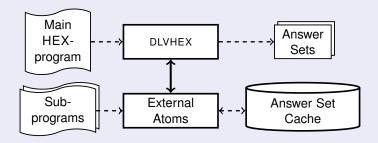
```
 \begin{array}{l} \mathit{addr}(\texttt{http://.../data1.rdf}). \\ \mathit{addr}(\texttt{http://.../data2.rdf}). \\ \mathit{bel}(X,Y) \leftarrow \mathit{addr}(U), \mathit{\&rdf}[U](X,Y,Z). \end{array}
```

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Architecture

Implementation

- On top of reasoner DLVHEX
- Main components:
 - External Atoms
 - 2 Answer Set Cache and Handles



Subprogram Calls

Startup: How to call a subprogram?

Possible subprogram sources:

- separate file
- string constant

External Atoms:

&callhexfile_n[f, p_1, \ldots, p_n](h) &callhex_n[c, p_1, \ldots, p_n](h)

Example: Separate file

$$p_1(x,y) \leftarrow p_2(a) \leftarrow p_2(b) \leftarrow$$

 $handle(H) \leftarrow &callhexfile_2[sub.hex, p_1, p_2](H)$

Answer Set: { handle(0)}

Example: Embedded subprogram

$$handle(H) \leftarrow \&callhex_0[a \leftarrow .b \leftarrow .c \leftarrow a.](H)$$

Answer Set: { handle(0)}

Subprogram Calls

Caching Mechanism

No unnecessary re-evaluation

Example

```
h_1(H) \leftarrow & callhexfile_0[sub.hex](H) 
 h_2(H) \leftarrow & callhexfile_0[sub.hex](H) 
 h_3(H) \leftarrow & callhex_0[a \leftarrow . b \leftarrow .](H)
```

Answer set: $\{h_1(0), h_2(0), h_3(1)\}\$ or $\{h_1(1), h_2(1), h_3(0)\}.$

Investigating Program Answers

What is "inside" a program's answer?

Program answer is a set of answer sets

External Atom: &answersets[ph](ah)

Example

```
ash(PH,AH) \leftarrow \&callhex_0[a \lor b \leftarrow .](PH), \&answersets[PH](AH)
```

Answer set: $\{ash(0,0), ash(0,1)\}$

Investigating Program Answers

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```
ash(PH,AH) \leftarrow \&callhex_0[a \lor b \leftarrow .](PH), \&answersets[PH](AH)
Answer set: \{ash(0,0), ash(0,1)\}
```

Motivating Example: Counting paths

Program paths.hex specifies a graph and computes all shortest paths between S and D (defined by s(S) and d(D)).

```
P_{cnt} = \{s(node_1). \qquad d(node_7).
as(AH) \leftarrow &callhexfile_2[paths.hex, s, d](PH), &answersets[PH](AH)
number(D) \leftarrow as(C), D = C + 1, not as(D)
exists\_path \leftarrow number(D)
number(0) \leftarrow not exists\_path\}
```

Internals of Answer Sets

What is the content of an answer set?

A set of literals over predicate symbols with certain arities

External Atom: &predicates[ph, ah](pred, arity)

Example

```
preds(P,A) \leftarrow &callhex_0[node(a). node(b). edge(a,b).](PH), \\ &&answersets[PH](AH), &predicates[PH,AH](P,A)
```

Answer Set: $\{preds(node, 1), preds(edge, 2)\}$

Extracting Literals

Which literals are in an answer sets?

Literals are of form $L_i = p(c_1, \ldots, c_k)$

Describe set of literals $\{L_{i_1}, \ldots, L_{i_n}\}$ as set of triples (i, a, c_{A+1})

- Unique literal index i
- Argument index $0 \le a \le (k-1)$ and s (sign)
- Argument values c_{a+1}

External Atom: & arguments $[ph, ah, pred](i, a, c_{a+1})$

Example: Reverse a directed graph

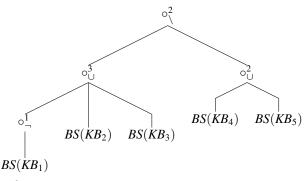
```
\begin{array}{lll} h(PH,AH) & \leftarrow & \& callhex_0[\texttt{node(a). node(b). node(c). edge(a,b).} \\ & & \texttt{edge(c,a).}](PH), \\ & & \& answersets[PH](AH) \\ edge(W,V) & \leftarrow & h(PH,AH), \& arguments[PH,AH,edge](I,0,V), \\ & & \& arguments[PH,AH,edge](I,1,W) \\ & & node(V) & \leftarrow & h(PH,AH), \& arguments[PH,AH,node](I,0,V) \\ \end{array}
```

Answer Set: $\{h(0,0), node(a), node(b), node(c), edge(b,a), edge(a,c)\}$

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Applications

■ MELD belief set merging system



- Aggregate Functions e.g. answer set counting
- Generalized Quantifiers
 e.g. cautious vs. brave reasoning; user-defined entailment relation
- Preferences over Answer Sets e.g. optimization tasks

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Summary

- Reasoning about sets of answer sets of (an)other program(s)
- Modularity by subprogram calls
- http://www.kr.tuwien.ac.at/research/dlvhex/meld.html

Nested HEX-Programs

- Set of External Atoms
- Answer Set Cache and Handles

Applications

- Belief Set Merging
- Generalization of aggregates
- Preferences (optimization tasks, etc)

References



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