SOM Visualization

March 30, 2022

1 SOM Visualization

1.1 Description

This notebook contains code for visualizing the contents of hierarchical data (*.h5) files produced by Sompy_experimentation.ipynb. The current things it displays are as follows:

- A set of linear-gradient heatmaps
- A set of log-gradient heatmaps
- An interactive interface for browsing through what items are in each cluster
- A "U-matrix" that highlights regions of high euclidean distance gradients, to identify how well-matching the cluster boundaries are

Workflow

- 1. Enter the particular codebook file you want to use in the codebook selection cell, change the KM_CLUSTERS value to whatever number of clusters you feel is appropriate, and then rerun the notebook.
- 2. Inspect the heatmaps in the heatmap view cells.
- 3. Search the cells for materials of interest in the cluster inspector cell.
- 4. Evaluate the accuracy of the fit of the clusters in the umatrix view cell.

Notes

- The trained SOM has many arrays, one for each parameter it was trained on. This is what is seen in the heatmap views each heatmap corresponds to one of these arrays.
- The cluster inspector has various features, which shall be listed here.
 - First, each cluster is given its own tab in the inspector. The order of the tabs by color matches the pattern in the colorbar to the side of the cluster map. You can confirm the color of a given cluster with the colored square next to the cluster's name inside of the tab's frame.
 - When a cluster is selected, you may view its statistical information and contained items in the tables in the tab's frame.
 - You can restrict the number of items shown in the tab by entering a **regular expression**(1, 2) that matches the items you wish to see.
 - Once the items have been filtered to your liking, you can hit the "render points" button in order to display all items visible in the table to the cluster map.

```
[1]: import numpy as np
import pandas as pd
import logging
```

```
import ipywidgets as widgets
     import matplotlib.pyplot as plt
     import tables
     import sompy
     from sompy.visualization.mapview import View2D
     from sompy.sompy import SOMFactory
     import skimage
     import matplotlib as mpl
     from tfprop_sompy.tfprop_vis import render_cluster_borders_to_axes,_
     →dataframe_to_coords, render_points_to_axes
     import sklearn.cluster as clust
[2]: # Codes from tfprop_sompy packages. Private code from Luna's group.
     from tfprop_sompy.jupyter_integration.cluster_inspector import_
     ⇒sort_materials_by_cluster, cluster_tabs,\
                                                                     ш
     →make_cluster_graph
     from tfprop_sompy.tfprop_vis import render_posmap_to_axes, kmeans_clust,_
     →render_points_to_axes,\
                                         show_posmap, ViewTFP, dataframe_to_coords,\
                                         clusteringmap_category, UMatrixTFP
[3]: # This makes all the loggers stay quiet unless it's important
     logging.getLogger().setLevel(logging.WARNING)
[4]: # Paste name of file generated by training in Sompy experimentation
     CODEBOOK_FILE = 'som_enamel_data.h5'
     # Number of clusters for k-means clustering
     KM_CLUSTERS = 6
[5]: # Creates necessary pd dataframes for visualization
     stored_cb_matrix = pd.read_hdf(CODEBOOK_FILE, 'sm_codebook_matrix')
     stored_mapsize = pd.read_hdf(CODEBOOK_FILE, 'sm_codebook_mapsize').values
     mats_df = pd.read_hdf(CODEBOOK_FILE, 'sm_data')
     # FIXME:
     # We do a hack using the "pytables" library in order to extract the information
     # For some reason pandas doesn't like to read object series out of h5 files
     stored columns = None
     stored matfamilies = None
     with tables.open_file(CODEBOOK_FILE, "r") as store:
         # We normally get byte strings from this
         # The mapping operation turns them all into unicode strings ready for
      \rightarrowpresentation
```

```
# Obtaining the column names
         stored_columns = list(map(lambda x: x.decode('utf-8'), store.root.
      →sm_codebook_columns.property_names.read()))
         # Obtaining the material identification
         stored_matfamilies = list(map(lambda x: x, store.root.

→sm_codebook_matfamilies.material_families.read()))
[6]: mats_df
[6]:
          modulus
                   hardness
                                                    age tooth_label mammal age_group
                              carb
                                     crys
                                              fluo
            76.07
                              0.08
                                    12.21
                                            962.65
                        4.17
                                                                          h
                                                                  6j
            75.07
                                    12.53
                                            962.60
     1
                        4.45
                              0.09
                                                      6
                                                                  6j
                                                                          h
                                                                                     p
     2
            74.10
                        3.91
                              0.10
                                    12.77
                                            962.61
                                                                  6j
                                                                          h
                                                                                     p
            68.91
                        3.94
                              0.11
                                    12.95
                                            962.51
                                                      6
                                                                  6j
                                                                          h
                                                                                     p
            63.81
                        3.11
                              0.12
                                    13.18
                                           962.68
                                                                  6j
                                                                          h
                                                                                     p
                                    13.06 960.71
     133
            64.80
                        3.47
                              0.10
                                                     10
                                                                  10
                                                                                   wad
                                                                          0
     134
            59.40
                        3.32
                             0.11
                                    13.35
                                           960.65
                                                     10
                                                                  10
                                                                                   wad
     135
            56.92
                        2.89
                              0.12
                                   13.53
                                            960.57
                                                     10
                                                                  10
                                                                                   wad
     136
            57.43
                        3.09
                              0.12
                                    13.66
                                            960.50
                                                     10
                                                                  10
                                                                                   wad
     137
            59.56
                        3.29
                             0.13
                                    13.83
                                            960.47
                                                     10
                                                                  10
                                                                          0
                                                                                   wad
         position
                   depth
                             kc
     0
                     1.00
                           1.02
                                 258.34
            outer
                                 277.70
     1
            outer
                     0.80
                           0.93
     2
           middle
                     0.60
                           1.02
                                 243.59
     3
           middle
                     0.40
                           1.00
                                 244.44
     4
                     0.20
                           0.92
                                 264.45
            inner
     133
            outer
                     0.77
                           1.02
                                 352.11
     134
           middle
                     0.59
                           1.04
                                 304.30
     135
           middle
                     0.39
                           1.07
                                 305.00
     136
            inner
                     0.21
                           1.14
                                 259.27
     137
            inner
                          1.20
                     0.02
                                 227.67
     [138 rows x 13 columns]
[7]: # Insert new column with material identification
     mats_df["Row"] = stored_matfamilies
[8]: # Function located in sompy.py
     # Creates a SOM object
     sm = SOMFactory.build(mats_df[stored_columns].values,
                      mapsize=(*stored_mapsize,),
                      normalization="var",
```

```
initialization="pca",
component_names=stored_columns)
```

```
[9]: # SOM object contains a codebook object
# Setting the matrix to the values of our current data.
sm.codebook.matrix = stored_cb_matrix.values
```

```
[10]: # Using scikit-learn K-means clustering method to predict cluster fit index for our SOM object.

cl_labels = kmeans_clust(sm, KM_CLUSTERS)
```

Performing K-means clustering to SOM trained data...

```
[11]: # This returns our function used to "filter"
      # our output in order to make differences more exaggerated
      def create_knee_function(cutoff: float, middle: float, maxm: float, minm:
       →float):
          def new_knee(x: float):
              # [-1,1] value determining closeness to "extremes"
              if x < middle:</pre>
                  diff = 0.5*(x-middle)/(middle-minm)
              else:
                  diff = 0.5*(x-middle)/(maxm-middle)
              # 0 if we're below our cutoff
              if np.abs(diff) < cutoff:</pre>
                  return middle
              # Linearly interpolate between our middle and the boundary
              else:
                  if diff < 0:</pre>
                       interp_diff = (diff + cutoff)/(0.5 - cutoff)
                      return middle + interp_diff*(middle - minm)
                      interp_diff = (diff - cutoff)/(0.5 - cutoff)
                      return middle + interp_diff*(maxm - middle)
          return new_knee
      class ViewTFP2(View2D):
          """Map viewer override that allows for specifying the normalization
       \hookrightarrow method"""
          def __init__(self, *args, knee_value=0, stdev_colorscale_coeff=1.0,_
       →**kwargs):
              super().__init__(*args, **kwargs)
              self.knee_value = knee_value
              self.stdev_colorscale_coeff = stdev_colorscale_coeff
          def _calculate_figure_params(self, som, which_dim, col_sz,
```

```
width=None, height=None):
""" Class method in MapView. calculate figure params() overrided """
codebook = som._normalizer.denormalize_by(som.data_raw,
                                           som.codebook.matrix)
indtoshow, sV, sH = None, width, height
if which_dim == 'all':
    dim = som._dim
    row_sz = np.ceil(float(dim) / col_sz)
    msz_row, msz_col = som.codebook.mapsize
    ratio_hitmap = msz_row / float(msz_col)
    ratio_fig = row_sz / float(col_sz)
    indtoshow = np.arange(0, dim).T
    sH, sV = (width, height) or (16, 16*ratio_fig*ratio_hitmap)
elif type(which_dim) == int:
    dim = 1
    msz_row, msz_col = som.codebook.mapsize
    ratio_hitmap = msz_row / float(msz_col)
    indtoshow = np.zeros(1)
    indtoshow[0] = int(which dim)
    sH, sV = (width, height) or (16, 16*ratio_hitmap)
elif type(which_dim) == list:
    max_dim = codebook.shape[1]
    dim = len(which_dim)
    row_sz = np.ceil(float(dim) / col_sz)
    msz_row, msz_col = som.codebook.mapsize
    ratio_hitmap = msz_row / float(msz_col)
    ratio_fig = row_sz / float(col_sz)
    indtoshow = np.asarray(which_dim).T
    sH, sV = (width, height) or (16, 16*ratio_fig*ratio_hitmap)
no_row_in_plot = dim / col_sz + 1 # 6 is arbitrarily selected
if no_row_in_plot <= 1:</pre>
    no_col_in_plot = dim
else:
    no_col_in_plot = col_sz
axis num = 0
width = sH
height = sV
return (width, height, indtoshow, no_row_in_plot, no_col_in_plot,
        axis_num)
```

```
def prepare(self, *args, **kwargs):
       self._close_fig()
       self._fig = plt.figure(figsize=(self.width, self.height))
       self._fig.suptitle(self.title)
       plt.rc('font', **{'size': self.text_size})
# NOTE: I'm using type rST syntax right now because I don't want to make
# excessive changes to make this use python's formal typing system.
# We may want to move to python's typing system later
    def show(self, som :sompy.sompy.SOM, cl labels :list, what='codebook', ...
⇔which_dim='all',
             cmap=None, col_sz=None, desnormalize=False, col_norm=None,_
→normalizer="linear", savepath="",
             isOutHtmap=True):
        """ Class method in View2D.show() overridden
        There's now an extra parameter, "col_norm", which is used to determine ⊔
 ⇒whether to normalize by
        the median or the mean
        :param som: The self-organizing map to visualize
        :type som: sompy.sompy.SOM
        :param cl labels: Cluster labels (?)
        :type cl_labels: list
        :param what: unused
        :type what: str
        :param which_dim: Which dimensions to display
        :type which_dim: "all" or int or list
        :param cmap: The color map to use for the plot
        :type cmap: matplotlib.colors.Colormap
        :param col_sz: Number of columns
        :type col_sz: integer
        :param desnormalize: Whether or not to denormalize the codebook
        :type desnormalize: Boolean
        :param col_norm: Determines what "middle value" to use for normalization
        :type col_norm: "median" or "mean"
        :param normalizer: Which normalizer to use
        :type normalizer: "linear" or "log"
        (self.width, self.height, indtoshow, no row in plot, no col in plot,
         axis num) = \
            self._calculate_figure_params(som, which_dim, col_sz,
                                          width=self.width, height=self.height)
        self.prepare()
        # Mathtext font to sans-serif
        mpl.rcParams['mathtext.fontset'] = 'custom'
        mpl.rcParams['mathtext.rm'] = 'sans\-serif'
```

```
mpl.rcParams['mathtext.cal'] = 'sans\-serif'
       cmap = cmap or plt.get_cmap('RdYlBu_r')
       if not desnormalize:
           codebook = som.codebook.matrix
       else:
           codebook = som._normalizer.denormalize_by(som.data_raw,
                                                      som.codebook.matrix)
       if which_dim == 'all':
           names = som._component_names[0]
       elif type(which_dim) == int:
           names = [som._component_names[0][which_dim]]
       elif type(which_dim) == list:
           names = som._component_names[0][which_dim]
       while axis_num < len(indtoshow):</pre>
           axis_num += 1
           ax = plt.subplot(no_row_in_plot, no_col_in_plot, axis_num)
           ind = int(indtoshow[axis_num-1])
           if col_norm == 'median': # normalized by median
               middle_point = np.median(codebook[:, ind].flatten())
           else: # normalized by mean
               middle_point = np.mean(codebook[:, ind].flatten())
           cb_min = np.min(codebook[:, ind].flatten())
           cb_max = np.max(codebook[:, ind].flatten())
           min_color_scale = middle_point - self.stdev_colorscale_coeff \
               * np.std(codebook[:, ind].flatten())
           max_color_scale = middle_point + self.stdev_colorscale_coeff \
               * np.std(codebook[:, ind].flatten())
           min_color_scale = min_color_scale if min_color_scale >= \
               cb_min else cb_min
           max_color_scale = max_color_scale if max_color_scale <= \</pre>
               cb_max else cb_max
           # FIXME: Break this out into less hacked-in code
           # "Middle color" should be mean or median?
           # The min value should be at the bottom of the range
           # The max value should be at the top of the range
           # The "min_color_scale" value should be the absolute bottom of the
→original color range
           # The "max_color_scale" value should be the absolute top of the \square
→original color range
```

```
# .5 - .5 * min((middle_point - min_color_scale) / (middle_point -
\rightarrow cb min), 1)
            # .5 + .5 * min((middle_point - max_color_scale) / (middle_point -
\rightarrow cb \ max), 1)
            # I probably can reorder this to make more sense
            # FIXME: This code currently biases the colors in a not very usefulu
\rightarrow manner
            \#cmap\_bottom = .5 * (1 - min((middle\_point - min\_color\_scale) / 
\rightarrow (middle_point - cb_min), 1))
            #cmap_top = .5 * (1 + min((middle_point - max_color_scale) /_
\rightarrow (middle_point - cb_max), 1))
            #my cmap = ListedColormap(cmap(np.linspace(cmap bottom, cmap top, |
\rightarrow num=512)))
           my_cmap = cmap
           if normalizer == 'log':
                norm = mpl.colors.
→SymLogNorm(linthresh=(max_color_scale-min_color_scale)/100, vmin=0.
\rightarrow7*min_color_scale,
                                            vmax=max_color_scale,
                                            clip=True)
           else:
               norm = mpl.colors.Normalize(vmin=min_color_scale*0.5,
                                              vmax=max_color_scale,
                                              clip=True)
           mp = codebook[:, ind].reshape(som.codebook.mapsize[0],
                                            som.codebook.mapsize[1])
            # FIXME: Break this out into less hacked-in code
            # Insert the scaling function here
            # as-is this is likely very slow - an immediate improvement would
\hookrightarrow come
            # from using something such as "numba" here
            scaler = np.vectorize(create_knee_function(self.knee_value,__
→middle_point, np.max(codebook[:, ind].flatten()), np.min(codebook[:, ind].
→flatten())))
           pl = ax.pcolormesh(scaler(mp.T), norm=norm, cmap=my_cmap)
           ax.set xlim([0, som.codebook.mapsize[0]])
           ax.set_ylim([0, som.codebook.mapsize[1]])
           ax.set_aspect('equal')
           ax.set_title(names[axis_num - 1],fontsize=22)
            # Disable ticks and tick labels
           disable_ticks = ["labelbottom", "labelleft", "bottom", "left", "

¬"right", "top"]

           disable_ticks_dict = {a: False for a in disable_ticks}
            # This unpacks the dict into the keyword arguments,
```

```
# setting them all as false without needing to write each one out
                  ax.tick_params(**disable_ticks_dict)
                  plt.colorbar(pl, ticks=None, shrink=1, fraction=0.046, pad=0.00441)
       \rightarrow# format='%.1f',
                  # draw line segment to the border of cluster
                  msz = som.codebook.mapsize
                  for i in range(len(cl_labels)):
                      rect_x = [i // msz[1], i // msz[1],
                                i // msz[1] + 1, i // msz[1] + 1]
                      rect_y = [i % msz[1], i % msz[1] + 1,
                                i % msz[1] + 1, i % msz[1]]
                      if i % msz[1] + 1 < msz[1]: # top border</pre>
                          if cl_labels[i] != cl_labels[i+1]:
                              ax.plot([rect_x[1], rect_x[2]],
                                       [rect_y[1], rect_y[2]], 'k-', lw=4)
                      if i + msz[1] < len(cl_labels): # right border</pre>
                          if cl_labels[i] != cl_labels[i+msz[1]]:
                              ax.plot([rect_x[2], rect_x[3]],
                                       [rect_y[2], rect_y[3]], 'k-', lw=4)
              # plt.subplots_adjust(wspace=0.1, hspace=0.1)
              plt.tight_layout()
              plt.show()
              # save figure of heat map
              if isOutHtmap:
                  print("Saving figure of heat map for all thermofluid prop. to {}...
       →".format(savepath))
                  self._fig.savefig(savepath)
[12]: # Setting parameters for our heatmap
      heatmap_size = (50, 50)
      heatmap col sz = 1
      gauss_alpha = None
      cmap = plt.get_cmap('RdYlBu_r') # set color map using Matplolib function
```

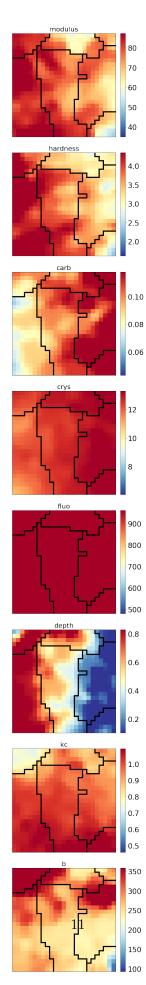
viewTFP = ViewTFP(*heatmap_size, '', stdev_colorscale_coeff=1., text_size=20)
viewTFP2 = ViewTFP2(*heatmap_size, '', stdev_colorscale_coeff=1., text_size=24)

#Initializing a map viewer imported from mapview.py

Output()

<ipython-input-11-e54ed6dc4a3c>:142: MatplotlibDeprecationWarning: Passing nonintegers as three-element position specification is deprecated since 3.3 and will be removed two minor releases later.

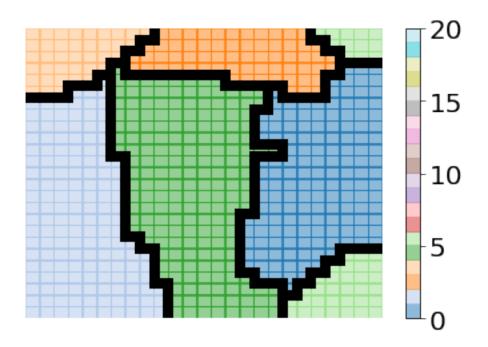
```
ax = plt.subplot(no_row_in_plot, no_col_in_plot, axis_num)
```



Saving figure of heat map for all thermofluid prop. to ...

```
[15]: my_out = widgets.Output() # Initializing widget
      cmap = plt.get_cmap('RdYlBu_r') # set color map 'viridis' 'RdYlBu_r'
      # No scaling
      viewTFP.knee_value = 0.0
      with my_out:
          print("Log scaling")
          viewTFP.show(sm, cl_labels, col_sz=heatmap_col_sz,
                               which_dim='all', desnormalize=True, col_norm='mean',
                               cmap=cmap, normalizer="log")
      my_out
     Output()
[16]: mats_df.index
[16]: Int64Index([ 0, 1,
                              2,
                                   3,
                                        4,
                                           5, 6, 7,
                                                            8,
                                                                 9,
                  128, 129, 130, 131, 132, 133, 134, 135, 136, 137],
                 dtype='int64', length=138)
[17]: # Creating 2-D list organized by clusters
      # 5 cluster = 5 lists within this list
      clusters_list = sort_materials_by_cluster(sm, mats_df, cl_labels)
      # This makes it so it will display the full lists
      pd.set_option('display.max_rows', 2000)
      pd.set_option('display.max_columns', 50)
      pd.set_option('display.width', 1000)
      # This should be the last statement of the cell, to make it display
      # That, or assign the return value to a variable, and have that variable be the
      \rightarrow final expression in a cell
      cluster_tabs(sm, mats_df, clusters_list, cl_labels)
```

Tab(children=(HBox(children=(VBox(children=(HBox(children=(Label(value='Cluster_ +#0'), HTML(value="<div style='...



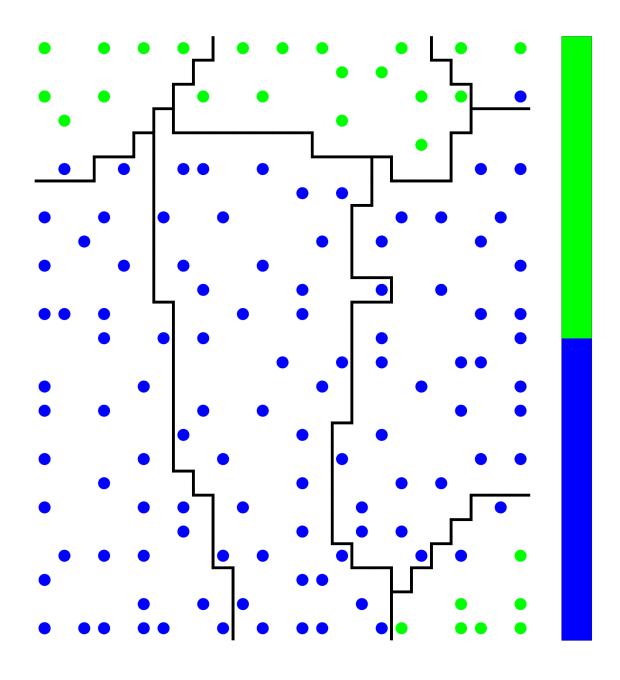
```
[18]: mats_df["Row"] = None
[19]: # cluster number -> color graph
      def make_cluster_graph(mysom: sompy.sompy.SOM, cl_labels: np.ndarray):
          Col1=6 #Total figure width
          pl1=2.7 #Drawing area width
          AR=14.63/18.47 #Height/width of figure.
          fig, ax = plt.subplots(figsize=[Col1,Col1*AR])
          #fig, ax = plt.subplots(1, 1)
          n_palette = 20
          cmap = plt.get_cmap("tab20")
          norm = mpl.colors.Normalize(vmin=0, vmax=n_palette, clip=True)
          msz = mysom.codebook.mapsize
          pl = ax.pcolormesh(cl_labels.reshape(msz[0], msz[1]).T % n_palette,
                        cmap=cmap, norm=norm, edgecolors='face',
                        lw=0.5, alpha=0.5)
          render_cluster_borders_to_axes(ax, cl_labels, msz)
          ax.axis('off')
          plt.tight_layout(rect=[0,0,1,1])
          fig.colorbar(pl, ax=ax)
          return fig, ax
```

[20]: # This function prints labels on cluster map

```
def clusteringmap_category(sm,n_clusters,dataset,colorcategory,labels,_
⇒savepath):
    11 11 11
    Description:
    This function is used to output maps that prints colors on dots based
    on their properties
    categories = dataset[colorcategory] #if colorcategory is one col of the
 \rightarrow dataset
    cmap = plt.get_cmap("Greys") #cmap for background
    n palette = 100000 # number of different colors in this color palette
    color list = [cmap((i % n palette)/n palette) for i in range(n clusters)]
    msz = sm.codebook.mapsize
    proj = sm.project_data(sm.data_raw)
    coord = sm.bmu_ind_to_xy(proj)
    fig, ax = plt.subplots(1, 1, figsize=(30,30))
    cl_labels = clust.KMeans(n_clusters=n_clusters,random_state=555).
 →fit_predict(sm.codebook.matrix)
    # fill each rectangular unit area with cluster color
    # and draw line segment to the border of cluster
    norm = mpl.colors.Normalize(vmin=0, vmax=n_palette, clip=True)
    ax.pcolormesh(cl_labels.reshape(msz[0], msz[1]).T % n_palette,
                cmap=cmap, norm=norm, edgecolors='face',
                lw=0.5, alpha=0.5)
    ax.scatter(coord[:, 0]+0.5, coord[:, 1]+0.5, c='k', marker='o')
    ax.axis('off')
    categoryname = list(dataset.groupby(colorcategory).count().index)
    categories_int = categories.apply(categoryname.index)
    N = len(categoryname)
    cmap_labels = plt.cm.brg
    # extract all colors from the .jet map
    cmaplist = [cmap_labels(i) for i in range(cmap_labels.N)]
    # create the new map
    cmap_labels = cmap_labels.from_list('Custom cmap', cmaplist, cmap_labels.N)
    # define the bins and normalize
    bounds = np.linspace(0,N,N+1)
    norm_labels = mpl.colors.BoundaryNorm(bounds, cmap_labels.N)
    scat = ax.scatter(coord[:, 0]+0.5, coord[:, 1]+0.5, 
 ⇒c=categories_int,s=1000,cmap=cmap_labels,norm=norm_labels)
    cbar = plt.colorbar(scat, spacing='proportional', ticks=bounds)
```

```
cbar.ax.get_yaxis().set_ticks([])
   for j, lab in enumerate(categoryname):
       cbar.ax.text(1, (2 * j + 1) / (2*(len(categoryname))), lab, ha='left', u

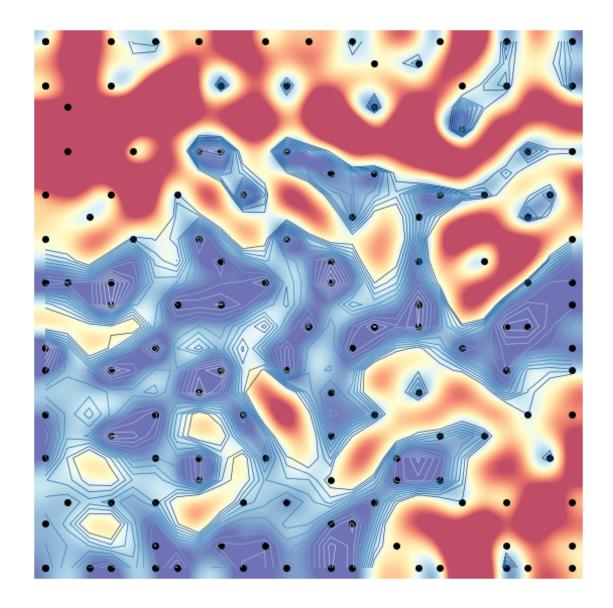
¬va='center', fontsize=0)
   cbar.ax.get yaxis().labelpad = 15
   # cbar.ax.set_ylabel('# of contacts', rotation=270)
   ax.axis('off')
   for label, x, y in zip(labels, coord[:, 0], coord[:, 1]):
       x += 0.2
       y += 0.2
       # "+ 0.1" means shift of label location to upperright direction
       # randomize the location of the label
       # not to be overwrapped with each other
       x += 0.1 * np.random.randn()
       y += 0.3 * np.random.randn()
       # wrap of label for chemical compound
       \#label = str wrap(label)
       ax.text(x+0.4, y+0.4, label, horizontalalignment='left', u
→verticalalignment='bottom',rotation=30, fontsize=12, weight='semibold')
   # cl_labels = som.cluster(n_clusters)
   cl labels = clust.KMeans(n clusters = n clusters, random state = 555).
→fit_predict(sm.codebook.matrix)
   for i in range(len(cl_labels)):
       rect_x = [i // msz[1], i // msz[1],
              i // msz[1] + 1, i // msz[1] + 1]
       rect_y = [i % msz[1], i % msz[1] + 1,
               i % msz[1] + 1, i % msz[1]]
       if i % msz[1] + 1 < msz[1]: # top border</pre>
           if cl_labels[i] != cl_labels[i+1]:
               ax.plot([rect_x[1], rect_x[2]],
                       [rect_y[1], rect_y[2]], 'k-', lw=8)
       if i + msz[1] < len(cl_labels): # right border</pre>
           if cl_labels[i] != cl_labels[i+msz[1]]:
               ax.plot([rect_x[2], rect_x[3]],
                       [rect_y[2], rect_y[3]], 'k-', lw=8)
   plt.savefig(savepath)
   return cl_labels, ax, fig
```



```
[22]: # Initializing size
umat_size = (50, 50)

# Utilizes SOMPY's UMatrixView, which uses matplotlib
umat = UMatrixTFP(*umat_size, 'U-matrix')

# Plots the UMatrix map
# Must set "ifOutUmat" to True in order to output a image file
umat.show(sm, mats_df, mats_df, 'umatrix.png',cmap=cmap, isOutUmat=True)
```



Saving figure of U-matrix to umatrix.png...

```
[0.35112846, 0.43128235, 0.53232877, 0.44205611, 0.50435585,
0.54254445, 0.40738645, 0.46144375, 0.42344022, 0.39044725,
0.54622528, 0.51302932, 0.33044715, 0.32762093, 0.53358436,
0.65025542, 0.48458573, 0.62345564, 0.88666111, 1.17592573,
1.24925753, 0.89212393, 0.77647788, 0.8039997, 0.85402051],
[0.3144104 , 0.46542526, 0.54734353, 0.42273056, 0.5127573 ,
0.46867345, 0.27014282, 0.40734972, 0.40860071, 0.27380071,
0.48078994, 0.49612545, 0.23328278, 0.21517174, 0.39022745,
0.61785969, 0.57928191, 0.59750005, 0.89521823, 1.0751143,
1.36826434, 0.97337562, 0.52495928, 0.56975826, 0.58548501],
[0.42103399, 0.44170049, 0.42178242, 0.3930278, 0.44869413,
0.38216421, 0.28380008, 0.33310041, 0.40417658, 0.31881213,
0.36782949, 0.53914873, 0.40723485, 0.3070725, 0.33424362,
0.4709035 , 0.71978336, 0.92480643, 0.89130613, 0.58383546,
0.97046287, 1.09768224, 0.57913521, 0.50811403, 0.46637679],
[0.36161399, 0.33211299, 0.34325641, 0.43362299, 0.4497005,
0.39260003, 0.33226398, 0.3004502, 0.4193215, 0.39598886,
0.27309396, 0.40818351, 0.42592049, 0.42312905, 0.45765446,
0.49295075, 0.63662404, 0.7775049, 0.80240155, 0.68616396,
0.87972354, 1.35491381, 1.04082858, 0.5287578, 0.45434754],
[0.29001177, 0.35191807, 0.48434799, 0.51749408, 0.39884318,
0.38701766, 0.44767039, 0.4301042, 0.35937226, 0.39021082,
0.41116216, 0.3648572, 0.29342899, 0.41116959, 0.4905932,
0.45945137, 0.46087232, 0.47554091, 0.6561767, 0.646757
0.77336479, 1.20161022, 1.21447061, 0.74934136, 0.60469078],
[0.38948196, 0.37326074, 0.57032443, 0.58111518, 0.30351688,
0.2937863, 0.53340908, 0.51658355, 0.25239866, 0.28406101,
0.46164487, 0.39411355, 0.29994901, 0.36127088, 0.34684854,
0.30295122, 0.45889889, 0.65356507, 0.52018393, 0.30543866,
0.56881384, 0.78798479, 0.70693803, 0.71071531, 0.61154597
[0.39360456, 0.32232602, 0.40306668, 0.55794169, 0.46760136,
0.44840467, 0.52137419, 0.45492598, 0.32283879, 0.25208092,
0.4012182 , 0.38032115 , 0.29119629 , 0.33634336 , 0.325379
0.40222224, 0.58777587, 0.61354404, 0.40728496, 0.27676377,
0.59786217, 0.67553081, 0.41250294, 0.60924323, 0.78989265],
[0.30668097, 0.32950867, 0.37506253, 0.44460183, 0.51618776,
0.5188758 , 0.39063947 , 0.32598491 , 0.45940654 , 0.45904241 ,
0.49566706, 0.43807672, 0.31565223, 0.33034915, 0.37659231,
0.58472052, 0.53931949, 0.31901018, 0.45853831, 0.53730221,
0.81616639, 0.80610079, 0.61287401, 0.74875102, 0.83342686],
[0.3111605, 0.31401657, 0.38073996, 0.41848707, 0.42979331,
0.37892445, 0.40016618, 0.57150811, 0.67874326, 0.49550233,
0.39697953, 0.49918266, 0.39363768, 0.2932814, 0.43514119,
0.51608843, 0.50046277, 0.44812924, 0.52957151, 0.5527543,
0.80726874, 0.77492694, 0.64260552, 0.70074044, 0.58770625
[0.36559008, 0.38196811, 0.41892894, 0.3821469, 0.44825928,
0.48105853, 0.60434173, 0.76474495, 0.543899 , 0.29357153,
```

```
0.30637252, 0.38489502, 0.43757491, 0.42960524, 0.41168225,
0.30573803, 0.51960444, 0.72528708, 0.49132206, 0.32451518,
0.58907955, 0.55836027, 0.43170014, 0.60119675, 0.60435638],
[0.35629731, 0.35632924, 0.41257275, 0.42148373, 0.44952023,
0.52328714, 0.55355533, 0.50368971, 0.42004192, 0.41032148,
0.39473079, 0.30729485, 0.36398749, 0.37374119, 0.36305019,
0.43045754, 0.68135981, 0.63862581, 0.38670101, 0.39686967,
0.71068049, 0.80005024, 0.61289669, 0.65774095, 0.62358603],
[0.27149045, 0.26567012, 0.33366916, 0.4608993, 0.50594703,
0.44821494, 0.37391688, 0.3490283, 0.36523112, 0.41185916,
0.40996146, 0.40513783, 0.36786664, 0.21691024, 0.28453821.
0.5358725 , 0.58584902, 0.42967088, 0.33422319, 0.50240299,
1.08126919, 1.02344615, 0.6874896, 0.57710801, 0.59595313],
[0.30102867, 0.30180272, 0.28854821, 0.38444102, 0.57538715,
0.64715012, 0.48993256, 0.35929344, 0.42323519, 0.39168428,
0.2939959 , 0.33691337, 0.44353873, 0.33653431, 0.4137359 ,
0.5166364 , 0.38095851, 0.3897126 , 0.39471092, 0.76627735,
1.06814475, 0.63661645, 0.59310712, 0.50859278, 0.45861184],
[0.51408005, 0.44980308, 0.39821304, 0.35924363, 0.44536479,
0.60687348, 0.61450862, 0.41660546, 0.55899193, 0.57610425,
0.34628765, 0.27034468, 0.4152742, 0.49158388, 0.60820229,
0.6181928 , 0.51276732, 0.42341182, 0.3705924 , 0.74606086,
0.72600668, 0.40196073, 0.54322677, 0.52620426, 0.52906139
[0.5919386, 0.55475899, 0.58371201, 0.47973882, 0.32184656,
0.33325459, 0.54301969, 0.56386608, 0.53925484, 0.58569274,
0.47286019, 0.31019346, 0.37514596, 0.45468826, 0.50367107,
0.55816521, 0.5273753, 0.46378174, 0.50742139, 0.84496765,
0.96319601, 0.67980821, 0.63836736, 0.50536857, 0.65041136
[0.48695489, 0.56160917, 0.7220856, 0.57956509, 0.29953137,
0.26800178, 0.4643526, 0.60888607, 0.41853824, 0.49415902,
0.50273996, 0.27395185, 0.2661928, 0.33751887, 0.36358368,
0.38771503, 0.3998607, 0.36862521, 0.59897817, 1.0521555,
1.1160787, 0.87264943, 0.62161248, 0.45358501, 0.54530169],
[0.52377734, 0.73469599, 0.7815243, 0.52683382, 0.35338345,
0.33170554, 0.42880672, 0.62183553, 0.58054986, 0.51263219,
0.44016199, 0.38283823, 0.37888464, 0.51546713, 0.61635343,
0.65545299, 0.48957328, 0.34410604, 0.72153255, 0.97002121,
0.59240469, 0.61701029, 0.70995311, 0.6402336, 0.48967669],
[1.09182016, 1.04678585, 0.80099574, 0.49007731, 0.46489779,
0.45213129, 0.38345426, 0.54114534, 0.67277273, 0.47510931,
0.32643292, 0.46916066, 0.67905552, 0.62825163, 0.5821275,
0.86019277, 0.67732979, 0.42690332, 0.75645837, 0.73428277,
0.34333293, 0.39033664, 0.57576866, 0.78510284, 0.88335113
[0.95779482, 0.87155045, 0.87062577, 0.60870174, 0.62224649,
0.58882301, 0.43483189, 0.60718439, 0.53850283, 0.39046765,
0.36373332, 0.40089119, 0.65733457, 0.72069426, 0.49031037,
0.75549837, 0.75362751, 0.43879845, 0.53554723, 0.787674
```

```
0.6430256, 0.47539896, 0.46869056, 0.57555092, 0.76235243],
              [0.40797112, 0.52723749, 0.70912386, 0.58704336, 0.67446352,
               0.70686952, 0.58575068, 0.59060301, 0.40300656, 0.33263074,
               0.32490723, 0.26295175, 0.36287882, 0.69051949, 0.79754076,
               0.77636557, 0.59137777, 0.52877177, 0.44811296, 0.57869103,
               0.79796128, 0.58695316, 0.43915276, 0.45807081, 0.410507],
              [0.56578374, 0.66833743, 0.84250198, 0.80070013, 0.68306256,
               0.56887005, 0.52585501, 0.48670191, 0.47145327, 0.45754967,
               0.33050593, 0.26041086, 0.29941596, 0.43759724, 0.75427234,
               0.74651725, 0.40894753, 0.49934407, 0.53194 , 0.39562645,
               0.6244876 , 0.7746353 , 0.63006698 , 0.54207626 , 0.57587271],
              [0.68798216, 0.64717158, 0.78557438, 0.83483918, 0.67965616,
               0.44835996, 0.56729208, 0.59251007, 0.53469443, 0.46508798,
               0.35295295, 0.32705262, 0.3151689, 0.33127889, 0.4459132,
               0.6326786, 0.50590128, 0.42653821, 0.56183568, 0.47607809,
               0.62665737, 0.78220303, 0.59476855, 0.50042913, 0.55797781
              [0.59398556, 0.57794926, 0.68670189, 0.65964845, 0.75370361,
               0.80869301, 0.76018435, 0.65481557, 0.64793631, 0.45641862,
               0.35550611, 0.38118811, 0.32000201, 0.33031016, 0.3546421,
               0.49880329, 0.61870559, 0.64856327, 0.66572734, 0.47028743,
               0.71722405, 0.70616126, 0.40110409, 0.4295862, 0.39542477]]))
[23]: # Calculate quantization error value
      sm.calculate_quantization_error()
[23]: 0.09080619458930875
[24]: # Calculate topographic error value
      sm.calculate_topographic_error()
[24]: 0.014492753623188406
 []:
```