

# Assignment 3

Carter Rhea

March 28, 2016

## Problem 1

One way to get an intuitive assessment of the accuracy and stability of a numerical method for solving ODE initial value problems in the form

$$\frac{dx}{dt} = f(t, x), x(a) = xa$$

is to apply it to a single time-step in each of two basic test cases:

(i) The integration  $\frac{dx}{dt} = f(t)$ , exact solution  $x(t + h) = x(t) + \int_t^{t+h} f(s)ds$ .

(ii) The exponential equation  $\frac{dx}{dt} = \lambda x$ , exact solution  $x(t + h) = x(t)e^{h\lambda}$ .

Apply this idea to a single step of the (classical) four-stage Runge-Kutta method:

**a)**

Verify that for the integration case (i), the result is the same as with Simpson's rule, so that the Runge-Kutta method is fourth-order accurate in this case.

## SOLUTION

Using the classical Runge-Kutta 4<sup>th</sup> order we have,

$$\int_t^{t+h} f(s)ds = \frac{1}{6}(K_1 + 2K_2 + 2K_3 + K_4)$$

Based on the differential equation we have  $f(t, x) = f(t)$  Hence plugging this into the RK we have

$$K_1 = hf(t)$$

$$K_2 = hf(t + 1/2h)$$

$$K_3 = hf(t + 1/2h)$$

$$K_4 = hf(t + h)$$

Thus

$$x(t + h) = x(t) + \frac{1}{6}\left(hf(t) + 4hf(t + \frac{1}{2}h) + hf(t + h)\right)$$

which is Simpson's rule. Therefore we have RK as a 4<sup>th</sup> order method for this basic case!

**b)**

Verify that for case (ii), the time-stepping formula is

$$x(t+h) \approx x(t)p(h\lambda)$$

where  $p(\xi)$  is a polynomial in  $\xi = h\lambda$ .

## SOLUTION

Based on the differential equation we have  $f(t, x) = \lambda x$ . Hence plugging this into the RK we have

$$K_1 = h\lambda x$$

$$K_2 = h\lambda \left( x + \frac{1}{2}(h\lambda x) \right) = h\lambda x + \frac{1}{2}h^2 \lambda^2 x$$

$$K_3 = h\lambda \left( x + \frac{1}{2} \left( h\lambda x + \frac{1}{2}h^2 \lambda^2 x \right) \right) = h\lambda x + \frac{1}{2}h^2 \lambda^2 x + \frac{1}{4}h^3 \lambda^3 x$$

$$K_4 = h\lambda \left( x + h\lambda x + \frac{1}{2}h^2 \lambda^2 x + \frac{1}{4}h^3 \lambda^3 x \right) = h\lambda x + h^2 \lambda^2 x + \frac{1}{2}h^3 \lambda^3 x + \frac{1}{4}h^4 \lambda^4 x$$

Hence,

$$\begin{aligned} x(t+h) &= x \frac{1}{6} \left( h\lambda x + 2h\lambda x + h^2 \lambda^2 x + 2h\lambda x + h^2 \lambda^2 x + \frac{1}{2}h^3 \lambda^3 x h\lambda x + h^2 \lambda^2 x + \frac{1}{2}h^3 \lambda^3 x + \frac{1}{4}h^4 \lambda^4 \right) \\ &= x + \frac{1}{6} \left( 6h\lambda x + 3h^2 \lambda^2 x + h^3 \lambda^3 x + \frac{1}{4}h^4 \lambda^4 x \right) \\ &= x + h\lambda x + \frac{1}{2}h^2 \lambda^2 x + \frac{1}{6}h^3 \lambda^3 x + \frac{1}{24}h^4 \lambda^4 x \\ &= x + x \left( h\lambda + \frac{1}{2}h^2 \lambda^2 + \frac{1}{6}h^3 \lambda^3 + \frac{1}{24}h^4 \lambda^4 \right) \\ &= x \left( 1 + h\lambda + \frac{1}{2}h^2 \lambda^2 + \frac{1}{6}h^3 \lambda^3 + \frac{1}{24}h^4 \lambda^4 \right) \end{aligned}$$

Thus we have what we were trying to demonstrate since if we allow  $h\lambda = \xi$  we then have a polynomial in  $\xi$ , as required.

**c)**

By comparing  $p(h\lambda)$  to the factor  $e^{h\lambda}$  in the exact solution, show that the error in this single step is  $O(h^5)$ , so that the method is fourth-order accurate for this case too.

## SOLUTION

Note that our polynomial is the  $4^{th}$  order Taylor polynomial for  $e^{h\lambda}$ . Therefore the error in a single step is  $O(h^5)$ !

## Problem 2

The initial value problem  $\frac{dx}{dt} = x^{1/3}$ ,  $x(0) = 0$  has two solutions for  $t \geq 0$ :  $x_1(t) = 0$ , and  $x_2(t) = 2t$ . If the Runge-Kutta method is applied, what happens? Can you see what happens with other ones-step methods seen so far? What is the moral here?

Here we have  $f(x, t) = x^{1/3}$

## SOLUTION

$$K_1 = hx^{1/3}$$

$$K_2 = h\left(x + \frac{1}{2}hx^{1/3}\right)^{1/3}$$

$$K_3 = h\left(x + h\left(x + \frac{1}{2}hx^{1/3}\right)^{1/3}\right)^{1/3}$$

$$K_4 = h\left(x + h\left(x + h\left(x + \frac{1}{2}hx^{1/3}\right)^{1/3}\right)^{1/3}\right)^{1/3}$$

Thus starting with our initial condition  $x(0) = 0$  we get

$$K_1 = 0, K_2 = 0, K_3 = 0, K_4 = 0$$

Hence  $x(t+h) = 0$  for any time. It is readily seen how this would continue for further  $t$  values. But in case you dont believe this I will show using RK4 code from last semester (or project 2)...

In [1]:

```
from ODE_IVP_module import *
```

In [2]:

```
def f(t,x): return x**(1/3)
init = 0
a = 0
b = 10
n = 1000
y4 = Runge_Kutta(f,init,a,b,n)
print("The best estimate according to the Runge-Kutta method for the differential equation dx/dt = x^(1/3) is 0")
```

The best estimate according to the Runge-Kutta method for the differential equation  $dx/dt = x^{1/3}$  is 0

Hence we can see it runs into the solution of  $x_1(t) = 0$ . The same will happen for other one-step methods since they are so dependent on the initial condition (which should be no surprise). The moral of this is that the Initial Value Matters!

## Problem 3

Suppose that with a certain machine arithmetic model (such as IEEE 64-bit), the Runge-Kutta method applied to a certain ODE IVP on the interval  $[a, b]$  using fixed step size  $h = \frac{b-a}{n}$  has truncation error  $9nh^5$  and round-off error  $36n2^{-50}$ .

What is the optimal value of  $h$ , in the sense of minimizing total error, how many time steps are involved, and what is that minimal possible attainable error?

## SOLUTION

To find an optimal value of  $h$  we should simply add our truncation error and rounding error as our error function and then optimize it...

Note that  $n = \frac{b-a}{h}$

Hence,

$$E(h) = 9nh^5 + 36n2^{-50} = 9\left(\frac{b-a}{h}\right)h^5 + 36\left(\frac{b-a}{h}\right)2^{-50} = 9(b-a)h^4 + 36\left(\frac{b-a}{h}\right)2^{-50}$$

$$E'(h) = 63(b-a)h^3 - \frac{36(b-a)2^{-50}}{h^2} = 0$$

Hence we get,

$$h^5 = 2^{-50}$$

$$h = \sqrt[5]{2^{-50}} = \frac{1}{1024}$$

Hence our minimal amount of time steps is

$$n = \frac{b-a}{\frac{1}{1024}} = 1024(b-a)$$

And plugging these values into  $E(h)$  we get,

$$E(h) = 9(b-a)\left(\frac{1}{1024}\right)^4 + 36(1024(b-a))2^{-50} = \frac{45(b-a)}{1099511627776}$$

