

UNIVERSITY OF CANTABRIA



MASTER'S THESIS.

MASTERS DEGREE IN MATHEMATICS AND COMPUTING

Diameter of simplicial complexes y coma a computational approach

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Desvarío laborioso y empobrecedor el de componer vastos libros; el de explayar en quinientas páginas una idea cuya perfecta exposición oral cabe en pocos minutos. Mejor procedimiento es simular que esos libros ya existen y ofrecer un resumen, un comentario.

Borges, *Ficciones*

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C O M A

Diameter of simplicial complexes: a computational approach

Abstract

The computational complexity of the simplex method, widely used for linear programming, depends on the combinatorial diameter of the edge graph of a polyhedron with n facets and dimension d . Despite its popularity, little is known about the (combinatorial) diameter of polytopes, and even for simpler types of complexes. For the case of polytopes, it was conjectured by Hirsch (1957) that the diameter is smaller than $(n - d)$, but this was disproved by Francisco Santos (2010). In this thesis, we present two main results. First, a lower bound on the maximum diameter for two classes of simplicial complexes: pure simplicial complexes and pseudo-manifolds. Second, a topological improvement of Santos' counter example to the Hirsch Conjecture. This one is (slightly) smaller than the previously known smallest simplicial non-Hirsch sphere.

Keywords: Discrete Geometry, Computational Geometry, Simulated Annealing, Simplicial Complex, Combinatorial Diameter.

C O M A

Diámetro de complejos simpliciales: un enfoque computacional

Resumen

La complejidad computacional del método del símplex, ampliamente usado en programación lineal, depende del diámetro combinatorio del grafo de aristas de un poliedro con n facetas y dimensión d . Pese a su popularidad, sabemos muy poco sobre el diámetro (combinatorio) de los politopos, incluso para clases más simples de complejos. Para el caso de los politopos, Hirsch (1957) conjeturó que el diámetro era menor que $n - d$, pero su conjetura fue refutada por Francisco Santos (2010). En esta memoria, presentamos dos resultados fundamentales. Primero, una cota inferior para el diámetro de dos clases de complejos simpliciales: complejos simpliciales puros y pseudo-variedades. Segundo, una mejora topológica del contraejemplo de Santos a la conjetura de Hirsch. Ésta es más pequeña que la anterior esfera simplicial no Hirsch más pequeña que se conocía.

Palabras clave: Geometría discreta, Geometría computacional, Enfriamiento simulado, Complejo simplicial, Diámetro combinatorio.

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1 Introduction

The problem of finding the combinatorial diameter of simplicial complexes, particularly polytopal simplicial complexes, arises naturally from the analysis of the simplex method. In the simplex algorithm, we start from a vertex of a polytope and we move from one vertex to a neighbour until we reach the “best vertex” of an objective function. Therefore, a natural question to ask is how long can this path of vertices be in the worst case or, equivalently, what is the maximum possible diameter of a polytopal simplicial complex, as a function of its dimension and number of vertices.

For the case of polytopal simplicial complexes, it was conjectured by Hirsch (1957) that the diameter of a polytope with n facets and dimension d is at most $n - d$. This was disproven by Francisco Santos Leal (2010) [17], who found a non-Hirsch polytope with 86 facets and dimension 43. His construction, and the smaller ones subsequently constructed in [15], depend on certain lower dimensional polytopes called *prismatoids*. In particular, finding prismatoids satisfying certain property with a small number of vertices (or more significantly, with small difference “vertices minus dimension”) will yield smaller counterexamples to the Hirsch Conjecture. It is also important to note it could still be that the diameter of all polytopes is linear on $n - d$, even if no polynomial upper bound is known [12]. It would be desirable to prove or disprove this fact, and find the linear constant if applicable.

Partially as a means to shed light on the Hirsch question, but also as a natural mathematical question in itself, it is interesting to study how big can the diameter of other classes of simplicial complexes be, and learn from the examples that we may find in this greater generality. This approach was started by Adler and Dantzig in the early 70s and has been continued, for example, in [14, 2]. See [19] for a recent survey of results. This is also the approach taken in this work, in which we present two contributions:

- First, we show how to construct pure simplicial complexes of a given dimension $d - 1$ and number of vertices n which have diameters equal (modulo a constant depending on d) to the trivial upper bound of $O(n^{d-1})$. We first do this for some particular complexes that we call corridors (Theorem 4) and then show how to go from any pure simplicial complex to a pseudo-manifold of the same dimension without significantly changing neither the diameter nor the number of vertices (Theorem 8 and Corollary 1). These constructions improve the previously best ones which were of type $\Theta(n^{2d/3})$ for general complexes, and $\Theta(n^2)$ (no d in the exponent) for pseudo-manifolds. Our constructions are algebraic and are based on a sequence produced by certain polynomials over a (large enough) finite field. They are inspired in the well-known constructions of *linear-feedback shift registers* of maximal length. See the details in Section 3.
- We then introduce the concept of *topological prismatoids*, which generalize the (geometric) prismatoids from [17, 15], and we implement a metaheuristic to search for topological prismatoids with the non-Hirsch property and smaller than the ones

in [17, 15]. Our program has been able to find topological prisms of dimension 5 with 16 vertices and diameter 6. If one of these spheres turns out to be polytopal, then we would have constructed non-Hirsch polytopes of dimension 11 and with 22 facets, while the current smallest ones have dimension 20 and 40 facets [15]. Our algorithm combines the ideas of *simulated annealing* (SA), a common metaheuristic technique widely used in optimization, with the notion of *bistellar flips*, elementary transformations that change a simplicial complex in a local manner preserving its topology. Geometric bistellar flips are widely used in computational geometry and polyhedral combinatorics (see for example [18]). The topological version that we use is very similar to the one used in [3] in the context of triangulated manifold simplification, the main difference being that there only manifolds without boundary are used and here we need a version for manifolds with boundary. See the details in Section 4.

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Even if our example turned out to be nonpolytopal, it implies the existence of a sphere of dimension 10 and with 22 vertices whose diameter is greater than 11. This is an example of a non-Hirsch sphere (a $d - 1$ -sphere with n vertices and diameter greater than $n - d$). The existence on non-Hirsch spheres has been known for about 35 years now [14], but the smallest ones previously known are slightly bigger than ours: dimension 11 and 24 vertices in [14]. Both the sphere in [14] and the one we construct are *shellable*, a purely combinatorial property meaning basically that the sphere can be constructed one simplex at a time in such a way that all the intermediate complexes are balls. Shellability is a necessary condition for polytopality, but it is not sufficient. In fact, the sphere of [14] was proved to be non-polytopal in [2]. For the sphere we construct polytopality is unknown.

Let us mention that, although we speak of our sphere as a single example, in fact the program has given as output 5 prisms with the same parameters (dimension 5, 22 vertices, and width 6) and 100 5-dimensional prisms of width six and number of vertices still smaller than the previously known non-Hirsch prisms with a number of vertices ranging from 17 and 22. (But we have checked shellability only for one of them, since no polynomial time algorithm to check shellability is known).

As a final motivation for (the second part of) our work, we bring here a quote by Gil Kalai about the role of examples in mathematics [11, p. 769]:

It is not unusual that a single example or a very few shape an entire mathematical discipline. [...] And it seems that overall, *we are short of examples*. The methods for coming up with useful examples in mathematics (or counterexamples for commonly believed conjectures) are even less clear than the methods for proving mathematical statements.

2 Preliminaries

2.1 Definitions

Definition 1. A *simplicial complex* is a set $\mathcal{S} = \{s_1, \dots, s_n\}$ of sets, such that $\forall s \in \mathcal{S}, \forall f \subset s, f \in \mathcal{S}$. The complex is *pure of dimension $d - 1$* if every maximal element of \mathcal{S} has d vertices. *¿QUÉ ES UN VÉRTICE? ¿ELEMENTS?*

The elements of \mathcal{S} are called *faces*, and some faces have special names:

Facet If $|s| = d$.

Ridge If $|s| = d - 1$.

Edge If $|s| = 2$.

Vertex If $|s| = 1$.

Empty face If $s = \emptyset$.

Also note that the set of faces has a natural partial order, the inclusion. The *Hasse diagram* of the simplicial complex is the directed graph representing the inclusion relations between faces.

Example. The boundary of an octahedron in the three-dimensional space is a pure simplicial complex of dimension 2, that is, $d = 3$. It has eight facets, twelve ridges (that are also edges) and six vertices. It is also homeomorphic to the 2-dimensional sphere \mathbb{S}^2 .

Definition 2. Given a $(d - 1)$ -dimensional simplicial complex \mathcal{S} and a face $f \in \mathcal{S}$:

- The *star* of f is the set of faces of \mathcal{S} that are supersets of f .
- The *ustar* of f is the union of all faces in the star of f . That is to say, it is the set of vertices that appear in some face containing f .
- The *link* of f is the set of faces of $\mathcal{S} \setminus f$ that, joined with f , belong to the complex. That is, the vertices of the link, joined with f , form the ustar of f .

Note that the ustar of a face f is the set of vertices v such that $f \cup \{v\}$ is still in the complex. We will use this definition to “move up” in the Hasse diagram, and we can “move down” by removing vertices of the faces.

Definition 3. A *polytope* of dimension d is an bounded intersection of affine half-spaces in \mathbb{R}^d . A polytope is *simple* if every point of it is at most in d of the defining hyperplanes

at the same time. That is, a polytope can be defined by a set of n linear inequalities in d variables.

The intersection of one of the defining hyperplanes with the polytope (that is, the points satisfying one equation with equality) is called a *facet*. In a similar way, the set of points satisfying with equality two equations are a *ridge*.

The *dual graph* of the polytope is a graph with a vertex for each facet and an edge for each ridge, such that an edge connecting two vertices in the graph corresponds to a ridge in the intersection of two facets.

Definition 4. Given a d -dimensional simple polytope P defined by n equations, we can define its *dual simplicial complex* as the subsets of $\{1, \dots, n\}$ such that there is an $x \in \mathbb{R}^d$ satisfying exactly the corresponding equations with equality. That is, its vertices are the facets of the polytope, and its facets are the vertices of P .

Observe that the dual simplicial complex of a polytope P is the face complex of proper faces of the polytope dual to P . For example, the dual complex of a cube is the boundary complex of an octahedron.

Definition 5. The *dual graph* of a pure simplicial complex \mathcal{S} is a graph having the facets of \mathcal{S} as vertices where two facets are adjacent if their intersection is a ridge. The *dual diameter* of \mathcal{S} is the diameter of its dual graph. DEFINIR DIAMETRO

We define also $H_{\mathcal{C}}(n, d)$ as the maximum dual diameter a simplicial complex with n vertices and dimension $d - 1$ can have in a particular class \mathcal{C} of simplicial complexes.

Definition 6. A *prismatoid* is a polytope Q with two parallel facets Q^+ and Q^- , that we call the *bases*, containing all the vertices. We call a prismatoid *simplicial* if all faces except perhaps Q^+ and Q^- are simplices. Observe that the faces of a prismatoid of dimension d , excluding the two bases, form a simplicial complex of dimension $d - 1$ and homeomorphic to the product of \mathbb{S}^{d-2} with a segment. We call this complex the prismatoid complex of Q .

The width of a prismatoid is the distance in the dual graph from one base to the other, or, to be more in agreement with our definitions above, it is two plus the minimum distance between a facet adjacent to a base and a facet adjacent to the other base.) def

Theorem 1 (Strong d -step theorem for prismatoids[17]). *If Q is a d -prismatoid with width l and n vertices, there is another $n - d$ -prismatoid Q' with $2n - 2d$ vertices and width at least $l + n - 2d$.*

In particular, if $l > d$ then the polytope dual to Q' violates the Hirsch Conjecture.

Theorem 2 (Matschke-Santos-Weibel' improved counterexample [15]). *There is a prismatoid with 28 vertices, dimension 5 and width 6. That is, there is a non-hirsch polytope with dimension 23 and 46 vertices.*

Remark. The best example in [15] has actually 25 and not 28 vertices. But in our computations in section 4 we take the one with 28 vertices as the initial state for the SA, because it has much more symmetry and is thus easier to input. Part of our goal was in fact to see whether we could go from the 28 example to one smaller than 25, in order to compare our methods with the half-computational ones used in [15].

DEFINITION

One of our main results in this project is a simplification of the Matschke-Santos-Weibel example, but in a topological sense. We now define the main object we are working with:

Definition 7. A $((d - 1)$ -dimensional) *topological prismatoid* is a $(d - 1)$ -dimensional pure simplicial complex homeomorphic to $\mathbb{S}_{d-2} \times [0, 1]$ (that is, it is homeomorphic to a cylinder), and such that every face with all its vertices in the same boundary component is fully contained in the boundary. Put differently, the induced subcomplex on each boundary component coincides with the boundary component itself. (Observe that these boundary components are, by definition, $(d - 2)$ -spheres).

2.2 Previous best bounds on the diameter of simplicial complexes

For many important classes of simplicial complexes it is open whether $H_C(n, d)$ is polynomial or not. For example, no manifolds are known in which the diameter grows more than linearly, but no polynomial upper bound is known even in the much smaller class of simplicial spheres. Our first main result is precisely an improvement on the best known lower bound of two classes of simplicial complexes: pure simplicial complexes (defined in the previous section) and pseudomanifolds:

Definition 8. A *pseudo-manifold* is a pure simplicial complex in which every ridge belongs to exactly two facets.

For the class PSC of all pure (connected) simplicial complexes, it was known that:

Theorem 3 (Santos [19, Corollary 2.12]).

$$\Omega \left(\frac{n}{d} \right)^{\frac{2d}{3}} \leq H_{PSC}(n, d) \leq \frac{1}{d-1} \binom{n}{d-1} \simeq \frac{n^{d-1}}{d!}.$$

Here the upper bound is obtained by counting the number of ridges in the complex, and it is the same for pseudo manifolds.

For the case of pseudo-manifolds, the best known lower bound was quadratic. The following table sums the previously known best lower bounds.

	Upper bound	Lower bound
PSC	$O(n^{d-1})$	$\Omega(n^{2d/3})$ (Santos, 2013)
P. Mani-folds	$O(n^{d-1})$	$\Omega(n^2)$ (Todd, 1974)
Spheres	$2^{d-3}n$ (Larman 1970)	$1.08(n-d)$ (Walkup-Mani 1980)
Simplicial Polytopes	$2^{d-3}n$ (Larman 1970)	$1.05(n-d)$ (Matschke-Santos-Weibel 2015)

3 The maximum diameter of pure simplicial complexes and pseudo-manifolds

This section is based in my preprint [5]

3.1 pure simplicial complexes

Our bound for the pure simplicial complex case is as follows:

Theorem 4. *For every $d \in \mathbb{N}$ there are infinitely many $n \in \mathbb{N}$ such that:*

$$H_{PSC}(n, d) \geq \frac{n^{d-1}}{(d+2)^{d-1}} - 3.$$

Observe that this matches the upper bound in Theorem 3, modulo a factor in $\Theta(d^{3/2}e^{-d})$, since $d! \simeq e^{-d}d^d\sqrt{2\pi d}$.

Remark. *Our proof of Theorem 4 uses an arithmetic construction valid only when the number n of vertices is of the form $q(d+2)$ for a sufficiently large prime power q . But every interval $[m, 2m]$ contains an n of that form, because there is a power of 2 between $m/(d+2)$ and $m/2(d+2)$. Hence, the theorem is also valid “for every d and sufficiently large n ”, modulo an extra factor of 2^{d-1} in the denominator.*

$$\rightarrow m/(2(d+2))$$

Our construction uses the following well-known result that can be found, for example, in [13, Theorem 33.16]:

Theorem 5. *Let $p(x) = x^d + a_1x^{d-1} + \dots + a_d$ be a primitive polynomial of degree d over the field \mathbb{F}_q with q elements, for some $d \in \mathbb{N}$ and some prime power q . Consider the sequence $(u_n)_{n \in \mathbb{N}}$ defined by the linear recurrence*

$$u_{n+d} + a_1u_{n+d-1} + \dots + a_du_n = 0,$$

starting with any non-zero vector $(u_1, \dots, u_d) \in \mathbb{F}_q^d$. Then, $(u_n)_{n \in \mathbb{N}}$ has period $q^d - 1$. In particular, its intervals of length d cover all of $\mathbb{F}_q^d \setminus \{(0, \dots, 0)\}$. That is:

$$\{(u_i, \dots, u_{i+d-1}) : i \in \{1, \dots, q^d - 1\}\} = \mathbb{F}_q^d \setminus \{(0, \dots, 0)\}.$$

Remember that a primitive polynomial of degree d is the minimal polynomial of a primitive element in the degree d extension \mathbb{F}_{q^d} of \mathbb{F}_q . The number of monic primitive polynomials of degree d over \mathbb{F}_q equals $\phi(q^d - 1)/d$, since \mathbb{F}_{q^d} has $\phi(q^d - 1)$ primitive elements, and each primitive polynomial is the minimal polynomial of d of them. In our construction we will need the coefficients of $p(x)$ to be all different from zero. Primitive polynomials with this property do not exist for all q , but they exist when q is sufficiently large with respect to d , which is enough for our purposes:

Lemma 1. *For every fixed $d \in \mathbb{N}$ and every sufficiently large prime power q , there is a primitive polynomial of degree d over \mathbb{F}_q with all coefficients different from zero.*

Proof. This follows from the fact that the number of primitive monic polynomials of degree d is greater than the number of monic polynomials of degree d with at least one zero coefficient, for q large.

Indeed, the latter is $q^d - (q - 1)^d \leq dq^{d-1}$. The former equals $\phi(q^d - 1)/d$, which is greater than $(q^d - 1)^{1-\epsilon}/d$, for every $0 < \epsilon < 1$ and sufficiently large q . Letting $\epsilon = \frac{1}{d^2}$ we get:

$$\frac{\phi(q^d - 1)}{d} > \frac{(q^d - 1)^{1-\frac{1}{d^2}}}{d} > \frac{(q^d/2)^{1-\frac{1}{d^2}}}{d} = \frac{q^{(d^2-1)/d}}{2^{1-\frac{1}{d^2}}d} > \frac{q^{d-\frac{1}{d}}}{2d} > dq^{d-1}.$$

□

With this we can now show our first construction proving Theorem 4.

Theorem 6. *Suppose that $p(x) \in \mathbb{F}_q[x]$ is a primitive polynomial of degree $d - 1$ with no zero coefficients. Then, there is a pure simplicial complex C of dimension $d - 1$, with $n = (d + 2)q$ vertices and at least $\frac{n^{d-1}}{(d+2)^{d-1}} - 1$ facets whose dual graph is a cycle.*

Proof. Our set of vertices is $V = \mathbb{F}_q \times [d + 2]$. That is, we have as vertices the elements of \mathbb{F}_q but each comes in $d + 2$ different “colors”. In the sequence $(u_i)_{i \in \mathbb{N}}$ of Theorem 5 we color its terms cyclically. That is, call

$$v_i = (u_i, i \bmod (d + 2)).$$

Let C be the simplicial complex consisting of the intervals of length d in the sequence $(v_i)_{i \in \mathbb{N}}$. That is, we let:

$$F_i = \{v_i, \dots, v_{i+d-1}\}, \quad C = \{F_i : i \in \{1, \dots, q^d - 1\}\}.$$

*LCM($q^{d-1}, d+2$)
 O' NO SABES SI TIENE
 UN CICLO*

Observe that the sequence $\{F_i\}_{i \in \mathbb{N}}$ is periodic of period $\text{lcm}\{q^{d-1}-1, d+2\} \geq q^{d-1}-1 = \frac{n^{d-1}}{(d+2)^{d-1}} - 1$. Also, by construction, $G(C)$ contains a Hamiltonian cycle. We claim that, in fact, $G(C)$ equals that cycle.

For this, observe that ridges in C are of two types: some are of the form $\{v_i, \dots, v_{i+d-2}\}$ and some are of the form $\{v_i, \dots, v_j, v_{j+2}, \dots, v_{i+d-1}\}$. We will study the facets that these types of ridges may belong to.

For a ridge $R = \{v_i, \dots, v_{i+d-2}\}$ to be contained in a facet F we need the color of the vertex in $F \setminus R$ to be either $i-1$ or $i+d-1$ (modulo $d+2$).

Once we have the color c of the new vertex $v = (u, c) \in F \setminus R$, the recurrence relation (and the fact that p has non-zero coefficients) gives us only one choice for u . Thus, R is only contained in the two contiguous facets F_{i-1} and F_i .

SE USA EN EL OTRO CASO

The same argument applies to a ridge $\{v_i, \dots, v_j, v_{j+2}, \dots, v_{i+d-1}\}$. Now the color of the new vertex must be $j+1 \pmod{d+2}$ and the recurrence relation implies the vertex to be precisely v_{j+1} . □

and $a_i \neq 0$

Proof of Theorem 4. Delete a facet in the complex C of Theorem 6. □

A complex whose dual graph is a path, such as the one in this proof, is called a *corridor* in [19]. It is a general fact that the maximum diameter $H_{\text{PSC}}(n, d)$ is always attained at a corridor ([19, Corollary 2.7]). That is to say, $H_{\text{PSC}}(n, d)$ equals the maximum length of an induced path in the *Johnson graph* $J_{n,d}$: the dual graph of the complete complex of dimension $d-1$ with n vertices. Induced paths in graphs are sometimes called *snakes*. In this language Theorem 4 can be restated as:

Theorem 7. *There is a constant $c > 0$ such that for every fixed d and sufficiently large n the Johnson graph $J_{n,d}$ contains snakes passing through a fraction c^{-d} of its vertices.*

A stronger statement is known for the graph of a d -dimensional hypercube: it contains snakes passing through a positive, independent of d , fraction of the vertices [1].

3.2 Pseudo-manifolds

DEFINIR

Theorem 8. *For every strongly connected pure $(d-1)$ -dimensional simplicial complex with n vertices and diameter δ there is a $(d-1)$ -dimensional pseudo-manifold without boundary with $2n$ vertices and diameter at least $\delta+2$.*

Let C be the simplicial complex in the statement and V its vertex set. By [19, Corollary 2.7] there is no loss of generality in assuming that C is a *corridor*. That is, its dual graph is a path, so its facets come with a natural order F_0, \dots, F_δ .

We now construct a simplicial complex C' in the vertex set $V' = V \times \{1, 2\}$. For a vertex $v \in V$ we denote v^1 and v^2 the two copies of it in V' , and refer to the superscripts as “colors”. Let a_i and b_i be the unique vertices in $F_i \setminus F_{i+1}$ and $F_i \setminus F_{i-1}$, respectively. (For F_0 and F_δ we choose a_0 and b_δ arbitrarily, but different from b_0 and a_δ). We define C' as the complex containing, for each F_i , the 2^{d-1} colored versions of it in which a_i and b_i have the same color. The diameter of C' is at least the same as that of C . Let us see that C' is almost a pseudo-manifold:

- If a ridge R in C' is obtained from a colored version of F_i by removing a vertex v different from a_i or b_i , then the only other facet containing R is the copy of F_i in which the color of v is changed to the opposite one. This is so because the “uncolored” version of R is a ridge of only the facet F_i of C , by assumption.
- If a ridge R in C' is obtained from a colored version of F_i ($i < \delta$) by removing a_i then the only other facet containing R is obtained by adding to it the vertex b_{i+1} with the same color as a_{i+1} has in R .
- Similarly, if a ridge R in C' is obtained from a colored version of F_i ($i > 0$) by removing b_i then the only other facet containing R is obtained by adding to it the vertex a_{i-1} with the same color as b_{i-1} has in R .

That is, the only ridges of C' that do not satisfy the pseudo-manifold property are the 2^{d-1} colored versions of $R_1 := F_0 \setminus \{b_0\}$ and the 2^{d-1} colored versions of $R_2 := F_\delta \setminus \{a_\delta\}$, which form two $(d-2)$ -spheres, (each with the combinatorics of a cross-polytope, the generalization of the octahedron). Choose a vertex a in R_1 and a vertex $b \in R_2$, different from one another (which can be done since $R_1 \neq R_2$). Consider the complex C'' obtained from C' adding to it all the colored versions of $R_1 \setminus a$ joined to $\{a^1, a^2\}$ and all the colored versions of $R_2 \setminus b$ joined to $\{b^1, b^2\}$. The effect of this is glueing two $(d-1)$ -balls with boundary the two $(d-2)$ -spheres we wanted to get rid off, so that C'' is now a pseudo-manifold. (Observe that the new ridges introduced in C'' all contain either $\{a^1, a^2\}$ or $\{b^1, b^2\}$ so they were not already in C'). \square

DEF 1
cross
polytope

Remark. In some contexts it may be useful to apply Theorem 8 to closed corridors, that is, pure complexes whose dual graph is a cycle. The construction in the proof works exactly the same except now C' is already a pseudo-manifold, with no need to glue two additional balls to it as we did in the final step of the proof.

Putting together Theorems 4 and 8 we get the main result in this section:

Corollary 1. For every $d \in \mathbb{N}$ there are infinitely many $n \in \mathbb{N}$ such that:

$$H_{PM}(n, d) \geq \frac{n^{d-1}}{(d+2)^{d-1}} - 3,$$

where PM denotes the class of all pseudo-manifolds.

Our construction also works for a particularization of pseudo-manifolds, called *duoids*[20]. A duoid is a pseudomanifold with no induced crosspolytopes. For duoids, the previous lower bound was quadratic in n .

DEFINITION

4 Computational search for non-Hirsch topological prismatoids

The purpose of this second part is to find a non-Hirsch topological prismatoid by starting with the Matschke-Santos-Weibel prismatoid with 28 vertices and doing operations preserving its width while reducing its number of vertices.

We will use the metaheuristic method of simulated annealing modifying the initial example via topological bistellar flips.

4.1 Bistellar flips

Bistellar flips are basic operation we perform in our complexes to transform them into hopefully simpler ones. The initial definition of a (topological) flip is as follows, first introduced in [16] and then used in [3] for sphere simplification:

Definition 9 (Bistellar flips in manifolds [3, 16]). In a pure simplicial complex \mathcal{C} homeomorphic to a manifold (without boundary), a *bistellar flip* is a transformation of \mathcal{C} defined by a pair (f, l) where $f \in \mathcal{C}$ and $l \notin \mathcal{C}$ is a minimal nonface of \mathcal{C} (every subset of l is a face but l is not), and $\text{link}(f) = \partial(l)$ ($\partial(l)$ here represents the topological boundary, which for a face l coincides with the simplicial complex of proper faces of l). The changes produced on the facets of \mathcal{C} are:

- Every face of \mathcal{C} containing f is removed.
- Every subset of $f \cup l$ containing l but not containing f is inserted as a new face.

Observe that the definition implies $f + l = d + 1$, since $f \cup l \setminus \{v\}$ is a facet in \mathcal{C} for every $v \in l$.

In a prismatoid, which is a manifold with boundary, we want to allow also boundary flips, so we are interested in flips of two types:

Interior flips These have exactly the definition above, except we need to require the new face l to be introduced to contain vertices of both bases of the prismatoid. Without this condition the flip introduces a face in the interior of our complex but with all vertices in the same boundary component, contradicting the requirement that the subcomplex induced by the vertices in each boundary component equals that boundary component.

Boundary flips The boundary of a prismatoid (or of any manifold with boundary) is itself a manifold without boundary. We want to allow for the flips in one of the

boundary components to be considered flips in the prismatoid, but this only makes sense if all facets to be removed by the flip contain one and the same vertex v in the other boundary component. If this happens we can modify the prismatoid by performing a cone over a flip in the boundary. Observe that in this case $|f| + |l| = d$ instead of $d + 1$, both f and l are contained in the same base. The vertex v in the other base is called the apex of the flip.

The following definition considers together these two types of flips:

Definition 10. A *bistellar flip* in a topological prismatoid \mathcal{C} is a triple (f, l, v) such that f is a face, l is a minimal nonface, and either:

- $|f| + |l| = d + 1$ and $v = \emptyset$, in which case l is required to have vertices from both bases and $\text{link}(f) = \partial(l)$.
- $|f| + |l| = d$ and v is a vertex, in which case f and l are required to be contained in the base opposite to v and $\text{link}(f) = \partial(l) * v$. Here $*$ denotes the operation of *join* of two simplicial complexes, but in the case where v is a single vertex $\text{link}(f) = \partial(l) * v$ is just a cone over $\partial(l)$.

In both cases, performing a flip makes the following changes:

- Every face containing f is removed.
- Every subset of the $f \cup l \cup v$ containing l but not f is added as a face.

As a side remark, if \mathcal{C} is a geometric simplicial complex and some additional geometric conditions on l are satisfied both cases of our flips are special cases of the usual *geometric bistellar flips* used in computational geometry and polyhedral combinatorics [18].

Only a boundary flip can modify the boundary. That means that only boundary flips can add or remove vertices, and only boundary flips can add new faces to the boundary.

One remark that is important for the implementation is that from the support of a flip (the set $f \cup l \cup v$ of vertices involved in the flip), we can determine if the flip is a boundary or an interior flip and recover the sets f , l and v :

- In a boundary flip, the support has a single vertex (v) in one of the components, and d in the other one, while in an interior flip it has at least two vertices in each: l has a vertex from each component by definition, and f has at least another from each base because the condition $\text{link}(f) = \partial(l)$, with $|f| + |l| = d + 1$, implies that f is an interior face.

- In both cases, the set $f \cup v$ equals the intersection of all facets of \mathcal{C} contained in $f \cup l \cup v$. This allows us to recover f , and hence l , once we know v by the previous point.

Then, given a possible support u with $d + 1$ vertices (d vertices if we want to allow flips that introduce a new vertex, that is flips in which l is a single vertex and f a single boundary ridge), we can check if it corresponds to a flip preserving the prismatoid definition:

1. First, u has to be the ustar of a ridge.
2. $\text{ustar}(f)$ must have $d + 1$ vertices (d vertices if we are adding a new one).
3. An interior flip can not add new faces to the boundary. That is, the bases must preserve their topology as spheres.
4. The corresponding l is not a face of \mathcal{C} .

Note that these conditions are necessary and sufficient for a flip to be valid in our context.

4.2 Simulated annealing

Simulated annealing is a very common metaheuristic for optimization problems, used when we have a search space and a “neighbourhood relation” between two feasible solutions. It has been used successfully in combinatorial topology to simplify simplicial complexes while preserving a condition (typically their homeomorphism type) [3]. It is also used in conjunction with other strategies to tackle the problem of sphere recognition [10].

The idea of simulated annealing is that we perform a random walk through the neighborhood graph of our feasibility space, but favouring moves that improve the objective function over moves that do not. There is a parameter, the *temperature*, regulating the probability assigned to each move as a function of how much it improves or worsens. At higher temperatures, the move selection is more random, and when the system cools down it converges to accepting only improving moves.

Then, areas of the graph with smaller values of the objective function will be more likely. As the temperature cools down, the random walk will focus on these areas, and make optimizations with more detail.

Simulated annealing requires some tweakings and adjustments for each particular problem:

- An appropriate objective function.
- A cooling schedule.
- A definition of the graph.

The first point requires a detailed analysis and is covered in the next subsection.

There is a lot of research on cooling schedules for each problem. It is known that SA converges to the global optimum for a particular cooling schedule [8], but it is too slow for any practical application. Since the best schedule depends on the problem, several adaptative schedules have been proposed too [9]. However, the most common approach is to define a geometric cooling schedule, of the form $T_t = t_0 * e^{st}$, where t_0 (initial temperature), s (cooling speed) and the number of iterations are chosen by hand. Since we are very fast at flipping the simplicial complex, we have chosen a slow schedule with a high number of iterations.

In our particular problem, the third point is already covered, every prismatoid is a state, and two prismatoids are neighbours if there is a flip connecting them. We just need to get random flips with uniform probability.

Note that uniform probability between the neighbours is very important, since SA works by defining custom probabilities for each flip. Modifying the “a priori” probability could make the search biased in unexpected ways.

4.3 The objective function

We initially had two independent goals with this project:

- Finding prismatoids of given dimension d and diameter $d + 1$.
- Finding prismatoids of dimension 5 starting with Matschke-Santos-Weibel’s example, and reduce the number of vertices.

The first case is called `Plan_Z` in the source files, and it uses the number of minimal paths from base to base as objective function, starting from a crosspolytope.

The second case is far more interesting. We add a restriction of preserving the width after each flip, but we need an objective function that helps us removing vertices. Note that to remove a vertex we require to have a flip of type $(1, d)$, that is, a vertex with $\text{card}(f) = 1$. Then, the objective function to minimize is the number of vertices, plus a smaller function to push the algorithm in the right direction. Some heuristics we have implemented for the latter are:

$1 \cdot 8 \cdot 7 = 1$
?

- A Number of facets.
- B Geometric mean of the sizes of the ustars.
- C Arithmetic mean of the sizes of the three vertices with the smallest ustars.
- D Number of faces.
- E Generalized mean for (relatively) large negative k ($k = -3$) of the sizes of the ustars.

The common idea in (most of) these functions is to make the algorithm to focus on the vertices that are easier to remove, that is, reducing the ustar of the vertex with the smallest ustar is a priority. Using just the minimum is not the best option since it will make the algorithm less sensible to reducing the ustars of other vertices that are not minimum.

We have obtained our best results with the last one. That is because the generalized mean with a negative parameter is heavily influenced by the smallest elements of the sample.

4.4 Data structures

Since we want to work with topological prisms, a type of simplicial complexes, we need a proper data structure with decent performance. It should have these operations:

- Construction from the list of facets.
- Check if a set of vertices is a face.
- Iterate through the maximal subfaces of a face.
- Iterate through the minimal superfaces of a face.
- Perform a flip.
- Compute the width of the prism.
- Get a valid random flip (with uniform probability).

A natural way of implementing this data structure would be to have the whole Hasse diagram as a graph. That is, every face is a “node” and has a list of which nodes are subsets and which are supersets. It is also required to have some form of indexing to get which subsets of V are actually facets.

This approach has the potential disadvantage of storing every face. Some other data structures are discussed in [4].

Since we need to check for membership to the complex (see 9), and our complexes are small, we will take this approach, with some tweaking to reduce its memory load while improving its performance.

Taking a face as a set, iteration through maximal subsets is the same as iterating through the set, and remove a vertex each time. The hard part is to iterate through minimal supersets. Here is where the idea of the *ustar* is useful. If a face f has ustar u , every superfacet of f is of the form $f \cup \{v\}$ where $v \in u \setminus f$. Therefore, having the ustar of every face stored, it is very easy to iterate through supersets too. Thus, we implement the simplicial complex as a dictionary of pairs (face,ustar), indexed by the face.

A flip is implemented simply by removing the old faces and inserting the new inserted faces

There is no need to store the dual graph, because it is implicit in the complex. The neighbours of a face can be computed from the ustar of the corresponding ridge, even if the ridge is a boundary ridge. However, we do store, for each facet, the distance to the first base, and the number of paths achieving that distance. The reason is that we don't want to iterate through all the facets when performing a flip, we just want to update the values that have changed.

Therefore, when we perform the flip, the new facets are inserted into a queue, and the distances are updated by cascading through the prismatoid.

Finally, it is very important to have an unbiased generation of random flips. We imitate to some extent the technique used in polymake [7]. In polymake, there is a set of pairs (f, l) , called “options” satisfying some conditions for flipability, in particular conditions 1 and 2 of subsection 4.1. The flips are categorized by dimension of f . Since every flip has the ustar of a ridge as support, we planned to simplify this by using ridges instead of the pairs (f, l) . However, several ridges may have the same ustar (making them correspond to the same potential flip). This makes this idea biased and some flips more likely than others.

To avoid this bias, we store in `options` the support instead of the ridge that has that support as its ustar.

This is very convenient, as it also makes it very easy to spot vertex-adding flips (which are represented by having a support of d vertices). And it is also very easy to update, because in the “fl-model”, after every flip, some potential flips may change their f and l while having the same support. And, since there is a bijection between a particular set of ustar of ridges and the set of flips (we have defined this bijection with the construction of (f, l, v)), it is easy to choose a random flip we just need to choose a random ustar and filter non-valid ones. So our approach is more stable, requires less changes to the data structure and it is a bit cleaner.

4.5 Implementation details

Along the course of the project we have developed several versions of the simulated annealing algorithm.

1. One written in pure C used bitmask techniques with a pool of faces, for fast addressing and modification. This limited the maximum number of facets, making it impossible to use it for high dimension. We did not implement boundary flips, and we used it to try to find non-Hirsch prisms starting with a nonHirsch one (in fact a cross-polytope, the dual of a hypercube).
2. A second one written in C++98, using the open-source project polymake [7] as a library. After severe problems with polymake's implementation of the graph data structure, we decided to implement our own simplicial complex structure from scratch.
3. Finally, we developed a version in C++11, using bitmask techniques from the first version and the versatility of C++ templates. This version can make boundary flips with great speed and has a correct implementation of everything needed for a simulated annealing strategy. As it is common for SA, it may require some tweaking to get good solutions.

I will focus on the last one, which can be found at my github [6]. Basically, it has three source files:

annealing.cpp The main file, implements the simulated annealing strategy.

prismatoid.hpp Is the header file for the prismatoid class, and includes some useful macros and functions for working with bitmasks.

prismatoid.cpp Implements the simplicial complex. It is conveniently partitioned as follows:

1. Constructors and functions to read and write prismatoids.
2. Functions dealing with choosing and executing flips.
3. Functions dealing with the dual graph, objective function and feasibility of the prismatoid.
4. Error handling.

The class `prismatoid` has some interesting attributes:

- `map<mask, mask> SC` represent the set of faces of the simplicial complex as a c++ map. It first argument is the bitmask representing the face, and the second one is the union of all the faces in its star. Using this information, we can iterate through its subsets and supersets, easily traversing the complex in logarithmic time.
- `map<mask, il> dists` has, for every facet, its distance to the first base, and the number of shortest paths from the base to that facet.
- `map<mask, int> options` is the set of ustars of ridges. There is a bijection between the set of possible flips and options, as explained previously. The second argument is for reference counting, it represents how many ridges have this ustar. It speeds up the execution of a flip.

The most relevant source files can be found also as an appendix. There are some smaller scripts for polymake, verification and file manipulation, written in perl, c++ and python that are not included here.

4.6 Experimental results

Using our approach, we have found 105 non-Hirsch topological prisms improving the best (geometrical) non-Hirsch prismatoid previously known [15], which had 25 vertices. 5 of them have 16 vertices, (the minimum we have been able to get). Here is one of those. Vertices 0, 1, 2, 3, 4, 5, 6, 7 are in one base and vertices a, b, c, d, e, f, g, h in the other one. The list of facets is arranged by “layers”, meaning by this the number of vertices in one and the other base:

(1,2,3,4,g)	(6,1,3,g,h)	(0,7,1,g,f)	(0,7,g,h,a)	(2,3,h,a,f)	(2,a,b,c,f)
(2,5,3,4,g)	(0,5,4,b,c)	(0,2,5,g,f)	(0,2,g,h,a)	(0,2,h,b,f)	(4,h,c,e,f)
(0,7,3,4,b)	(0,3,4,b,c)	(6,1,3,g,f)	(6,3,g,h,a)	(0,5,h,b,f)	(5,b,c,e,f)
(7,6,3,4,b)	(0,7,1,g,d)	(2,5,3,g,f)	(2,3,g,h,a)	(7,3,h,c,f)	(7,g,c,d,f)
(6,1,3,4,b)	(0,1,3,g,d)	(0,1,4,g,f)	(0,7,h,a,c)	(3,4,h,c,f)	(7,h,c,d,f)
(0,5,3,4,d)	(0,2,3,g,d)	(0,5,4,g,f)	(0,2,h,a,c)	(0,7,a,c,f)	(7,g,a,c,f)
(0,1,2,3,g)	(0,7,1,h,d)	(1,3,4,g,f)	(0,2,h,b,c)	(0,2,a,c,f)	(2,h,a,b,c)
(0,1,2,4,g)	(0,2,5,h,d)	(5,3,4,g,f)	(0,5,h,b,c)	(0,2,b,c,f)	(2,h,a,b,f)
(0,2,5,4,g)	(0,1,3,h,d)	(7,6,1,h,f)	(0,7,g,h,d)	(0,3,b,c,f)	(5,h,b,c,e)
(0,2,5,3,d)	(2,5,3,h,d)	(0,2,5,h,f)	(6,1,g,h,d)	(5,4,b,c,f)	(5,h,b,e,f)
(0,7,1,4,b)	(0,5,4,h,d)	(7,6,3,h,f)	(0,2,g,h,d)	(3,4,b,c,f)	(6,g,h,a,f)
(0,7,1,3,e)	(0,3,4,h,d)	(2,5,3,h,f)	(1,3,g,h,d)	(7,1,g,d,f)	(7,g,h,a,c)
(7,6,1,4,b)	(5,3,4,h,d)	(5,3,4,h,f)	(2,3,g,h,d)	(6,1,g,d,f)	(6,g,h,d,f)
(7,6,1,3,e)	(0,7,1,h,e)	(0,7,1,b,f)	(0,7,h,c,e)	(7,1,h,d,f)	(7,g,h,c,d)
	(7,6,1,h,e)	(7,6,1,b,f)	(0,5,h,c,e)	(6,1,h,d,f)	
	(7,6,3,h,e)	(0,7,3,b,f)	(7,3,h,c,e)	(5,4,h,e,f)	
	(0,1,3,h,e)	(7,6,3,b,f)	(3,4,h,c,e)	(5,4,c,e,f)	
	(6,1,3,h,e)	(6,1,3,b,f)	(0,7,g,a,f)		
	(0,5,4,h,e)	(0,1,4,b,f)	(0,2,g,a,f)		
	(0,3,4,h,e)	(0,5,4,b,f)	(6,3,g,a,f)		
	(0,7,3,c,e)	(1,3,4,b,f)	(2,3,g,a,f)		
	(0,5,4,c,e)	(0,7,3,c,f)	(6,3,h,a,f)		
	(0,3,4,c,e)				

Checking whether this prismatoid is polytopal or not seems out of reach computationally, at least within the scope of this master's thesis. (We mention ideas on how to try to do it in the conclusions section). But we have done two partial checks.

- We have checked that the two subcomplexes in the bases of the prismatoid are indeed 3-dimensional polytopal spheres, as they should if the whole thing is polytopal.
- We have checked that the complex obtained by filling-in a triangulation of each of the bases is a shellable 4-sphere.

Shellability of a complex is a necessary condition for polytopality, and has interesting topological implications.

Definition 11. A pure simplicial complex of dimension $d - 1$ is *shellable* if there is an ordering of the facets such that the intersection of each facet with the complex consisting of the previous ones is pure $(d - 2)$ -dimensional (that is, a union of ridges).

Checking shellability is believed to be NP-complete, and general purpose methods (including the one implemented in polymake) failed to do it for this example. But a semiautomatized method based on first ordering the facets by layers and distance to the

initial base, and then iteratively swapping facets that violated the shelling definition with later ones, succeeded. We believe this to be because our initial ordering was sufficiently close to a shelling. It is however interesting to note that no shelling order is compatible with the layers, because the union of the first three layers is not a ball, while every initial segment in a shelling of a sphere is a ball.

5 Conclusions

We have obtained simplified prisms preserving a property (non d-step), using a common technique. 5 of them achieve the minimum, 16 vertices. We are interested in finding if these topological prisms correspond to a polytope. If one of these prisms is polytopal, according to Theorem 1, there is a non-Hirsch polytope in dimension 11 with 22 vertices.

Thus, an interesting idea for the future is to check if our prisms are polytopal. There is some research on the topic, and a necessary condition for polytopability is shellability. It is possible (but not trivial) to check the shellability of our prisms using their “layer” structure as a guide.

Another possibility to get a polytopal prism is to repeat our procedure with *geometric flips*. That is, instead of only using topological information, we could keep track of the coordinates of each vertex and allow only flips that are realizable geometrically. Originally we did not consider this because of its computational complexity. But since topological flips are achieved in 150ms and (in the topological case) it is easy to improve the starting prism, with the information we have now (a reasonable objective function and cooling schedule) it looks like a promising idea.

We could also repeat our simulated annealing strategy, starting from our smallest prisms, and trying to improve heuristics for polytopability while preserving the number of vertices.

If polytopal, these smaller examples of non d-step prisms could shed some light on the subject of the combinatorial diameter of polytopes. Studying them could help us understand the properties of combinatorial diameter, maybe even giving us information about the polynomial Hirsch conjecture.

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A Source code.

Here is the source code for reference. An updated version can be found at my github [6].

A.1 annealing.cpp

```
1  #include "prismatoid.hpp"
2  #include <fstream>
3  #include <functional>
4  #include <iomanip>
5  #include <cmath>
6
7  double schedule(int k) {
8      // "a ojo"-selected annealing schedule
9      double t0=1000.0;
10     return t0*pow(0.99997, k);
11     /*
12     return 1e-10;
13
14     double t0=500.0;
15     return t0/log(k+2);
16     /**/
17 }
18
19 int main() {
20     unsigned seed=chrono::system_clock::now().time_since_epoch().count();
21     rng generator(seed);
22     uniform_real_distribution<double> dist(0.0,1.0);
23     auto dice=bind(dist,generator);
24     double totaltime=0.0; int totalflips=0;
25
26     flip fl; double record=28;
27
28     for(int experiment=1; experiment<=10; experiment++) {
29         int maxk=500000;
30         double cost, oldCost, avgCost=0.0, bestCost=1e30, numPrisms=0.0;
31
32         #ifndef PLAN_Z
33             ifstream file("./28prismatoid"); prismatoid p(file); file.close();
34         #else
35             //prismatoid p(9);
36             ifstream file("./outputs1/sol83"); prismatoid p(file); file.close();
37         #endif
38
39         for(int k=0; k<maxk; k++) {
40             oldCost=p.cost();
```

```

41     double t=schedule(k);
42
43     numPrisms++; avgCost+=oldCost; bestCost=min(bestCost,oldCost);
44     if(((k-1)%1000)==0) {
45
46         cout<<"Experiment " <<experiment
47             <<" (" <<setw(4)<<100*double(k-1)/maxk<<"%): "
48             <<setw(5)<<" temp= " <<t<<" : "
49             << oldCost <<" " <<avgCost/numPrisms<<" " <<bestCost
50             <<" flip time: " <<totaltime/totalflips/1000.0<<"us." <<endl;
51         cout<<" vertices: " <<countBits(p.base1|p.base2)
52             <<" diameter: " <<p.distBase2.first<<endl;
53         totaltime=0.0; totalflips=0;
54         numPrisms=0.0; bestCost=1e30; avgCost=0.0;
55     }
56
57     auto start=chrono::steady_clock::now();
58     while(true) {
59         fl=p.execFlip(generator);
60         cost=p.cost();
61
62         swap(fl.f, fl.l);
63
64         if(!p.feasible()) {
65             p.execFlip(fl);
66             assert(p.cost()==oldCost);
67         }
68         else break;
69     }
70     auto end=chrono::steady_clock::now();
71
72     totaltime+=chrono::duration<double,nano>(end-start).count();
73     totalflips++;
74
75     double delta=cost-oldCost;
76
77     if(delta>0.0 && dice()>exp(-delta/t)) {
78         p.execFlip(fl);
79         assert(oldCost==p.cost());
80     }
81
82     t=schedule(k);
83 }
84
85 ofstream index("./outputs/index", ofstream::app);
86 index<<"Experiment " <<experiment
87     <<" (" << oldCost
88     <<" ) Vertices: " <<countBits(p.base1|p.base2)
89     <<" Diameter: " <<p.distBase2.first<<endl;

```

```

90     index.close();
91
92     ofstream sol("./outputs/sol"+to_string(experiment));
93     p.write(sol);
94     sol.close();
95 }
96
97 return 0;
98 }

```

A.2 prismaoid.hpp

```

1  #ifndef PRISMATOID
2  #define PRISMATOID          // Decaf ninja style. Bit ninjustu but with class.
3                              // My humble interpretation of what SimplicialComplex.hpp
4  #include <map>               // should be.
5  #include <vector>            //
6  #include <algorithm>         // Author: Francisco "Paco" Criado
7  #include <iostream>          //
8  #include <fstream>           // I think my coding style is evolving into something
9  #include <iomanip>            // more readable after this.
10 #include <queue>              // Brief reminder: A simplex has dim vertices.
11 #include <ctime>
12 #include <chrono>
13 #include <random>
14 #include <cstdlib>
15 #include <set>
16 #include <string>
17 #include <bitset>
18 #include <cassert>
19 #include <cmath>
20
21 #define N 14
22 #define LAYER2 ((1<N)-1)
23 #define LAYER1 (((1<N)-1)<<N)
24
25 //PLAN_A is minimizing the facets
26 //PLAN_B is minimizing the geometric mean of card(ustar(v))
27 // (Actually it just uses the product)
28 //PLAN_C is minimizing the ustar of the smallest vertex
29 //PLAN_D minimizes the number of faces
30 //PLAN_E is generalized mean (k=3)
31 //PLAN_Z should be starting with crosspolytope
32
33 //define DEBUG
34 #define PLAN_E
35

```



```

36 using namespace std;
37
38 typedef unsigned int mask;
39 typedef pair<int, long long unsigned> il;
40 typedef vector<int> vi;
41 typedef default_random_engine rng;
42
43 class flip { public:          // f:  face to remove
44     mask f,l,v;              // l:  maximal face to add
45 };                            // v:  apex of the cone (frontier flip)
46 class prismatoid { public:
47     ///////////////////////////////////////////////////
48     // Public stuff (that should be private)
49     ///////////////////////////////////////////////////
50
51     mask base1, base2;        // The actual vertices in each base.
52     int dim;                  // A facet has dim vertices
53     int numFacets;            // Number of facets.
54     bool changeBases=true;    // Can we add/remove vertices?
55
56     map<mask,mask> SC;         // Face and ustar of face
57     map<mask, il> dists;       // Pair <distance, width> of each facet
58     il distBase2;             // (distance,width) for base2
59     set<mask> adyBase2;        // The set of the ridges adjacent to base2
60
61     map<mask,int> options;     // Set of ustars of ridges. That's it.
62                                // Frontier flips have dim vertices.
63                                // The int represents reference counting.
64
65     ///////////////////////////////////////////////////
66     // Public methods
67     ///////////////////////////////////////////////////
68
69     // S1:  Constructors and IO
70     prismatoid(int _dim);      // Crosspolytope
71     prismatoid(istream& input); // Reads prismatoid from file
72     void write(ostream& output); // Writes prismatoid to file
73
74     // S2:  Flippin' magic
75     flip execFlip(rng& gen);   // These two update everything.
76     void execFlip(flip fl);    // The first choses flip at random.
77
78     // S3:  Costs and graph stuff
79     double cost();              // Cost of this prismatoid (various options).
80     bool feasible();            // Do we want this prismatoid?
81     pair<vi,vi> statsForSantos(); // f-vector and layers
82
83     // S4:  Dont panic
84     bool everythingIsOK();      // Is everything OK?

```

```

85
86 private:
87 ///////////////////////////////////////////////////////////////////
88 // Private stuff
89 ///////////////////////////////////////////////////////////////////
90
91 void cascadeFacets();           // Completes the construction from the facets
92
93 void initOptions();            // Inits the options list
94 void initGraph();              // Inits graph and dists
95 void updateDists(queue<mask>& q); // Updates dists by cascading
96
97 flip findFlip(rng& gen);       // Finds a flip or crashes tryin'
98 bool checkFlip(mask u, flip& fl); // Checks the validity of u as option,
99 };                             // returns the flip fl (by reference)
100
101 ///////////////////////////////////////////////////////////////////
102 // S0: Ancient bit-jutsu techniques
103 ///////////////////////////////////////////////////////////////////
104 inline uint countBits(mask i) {
105     i = i - ((i >> 1) & 0x55555555); i = (i & 0x33333333) + ((i >> 2) & 0x33333333);
106     return (((i + (i >> 4)) & 0x0F0F0F0F) * 0x01010101) >> 24;
107 }
108
109 // for (mask x=firstElement(f); x!=0; x=nextElement(f,x))
110 inline mask firstElement(mask f) {return f&-f;}
111 inline void nextElement(mask f, mask& x) {x= ((x|~f)+x)&f;}
112
113 // mask x=0; do stuff while(x=nextSubset(f,x), x!=0)
114 inline void nextSubset(mask f, mask& x) {x= ((x|~f)+1)&f;}
115
116 inline void printMask(mask f) {
117     for(int i=0; i<2*N; i++) if(((1<<i)&f)!=0) cout<<i<<" "; cout<<endl;
118 }
119 inline mask readMask() {
120     string str; getline(cin, str); mask res=0;
121     for(int i=0; i<str.size(); i++) res=2*res+((str[i]=='1')?1:0);
122     return res;
123 }
124
125 inline bool in(mask a, mask b) {return !(a&(~b));}
126
127 #endif

```

A.3 prismaticoid.cpp

```

1 #include "prismaticoid.hpp"

```

```

2
3 ///////////////////////////////////////////////////////////////////
4 // S1: Constructors and IO
5 ///////////////////////////////////////////////////////////////////
6
7 // Assumes that in SC we have only facets of dim dim. Builds everything else.
8 void prismatoid::cascadeFacets() {
9     queue<mask> q; base1=base2=0; numFacets=0;
10
11     for(auto& it: SC) q.push(it.first),
12                     base1|= LAYER1 & it.first,
13                     base2|= LAYER2 & it.first,
14                     numFacets++;
15
16     while(!q.empty()) {
17         mask f=q.front(); q.pop();
18         for(mask x=firstElement(f); x!=0; nextElement(f,x)) {
19             SC[f^x]|=f; q.push(f^x);
20         }
21
22         initOptions(); initGraph();
23         #ifdef DEBUG
24             assert(everythingIsOK());
25         #endif
26
27         cout<<"built"<<endl;
28     }
29
30     // Crosspolytope constructor
31     prismatoid::prismatoid(int _dim) {
32         dim=_dim; SC=map<uint,uint>(); mask f; base2=(1<<dim)-1; base1=base2<<N;
33
34         for(uint i=1; i<base2; i++) f=(i|((i<<N)^base1)), SC[f]=f;
35         cascadeFacets();
36     }
37
38     // Constructor reading from file. The format is:
39     // -first line: dim, number of facets
40     // -next lines: each line is a new facet.
41     // The vertices 0..N-1 are in base2 and N..2N-1 in base1 (N=10).
42     prismatoid::prismatoid(istream& input) {
43         SC=map<mask,mask>();
44
45         input>>dim>>numFacets;
46
47         for(int i=0; i<numFacets; i++) { //readFacet?
48             mask f=0, aux; for(int j=0; j<dim; j++) input>>aux, f|=(1<<aux);
49             SC[f]=f;
50         }

```

```

51     cascadeFacets();
52 }
53
54 // Write prismatoid to file in the same format.
55 void prismatoid::write(ostream& output) {
56     output<<dim<<" "<<numFacets<<endl;
57     for(auto& it: SC) if(countBits(it.first)==dim) {
58         for(int i=0; i<2*N; ++i) if((it.first&(1<<i))!=0) output<<i<<" ";
59
60         output<<endl;
61     }
62 }
63
64 ///////////////////////////////////////////////////
65 // S2: Flippin' magic.
66 ///////////////////////////////////////////////////
67
68 // Inits the option set.
69 void prismatoid::initOptions() {
70     options=map<mask,int>();
71     for(auto &it:SC) if(countBits(it.first)==dim-1) options[it.second]++;
72 }
73
74 // Finds a move or crashes tryin'.
75 flip prismatoid::findFlip(rng& gen) {
76     flip fl;
77
78     uniform_int_distribution<int> dis(0, options.size()-1);
79     auto origin = options.begin(); advance(origin, dis(gen));
80
81     for(auto it= origin; it!= options.end(); ++it)
82         if(checkFlip(it->first, fl)) return fl;
83     for(auto it=options.begin(); it!=origin; ++it)
84         if(checkFlip(it->first, fl)) return fl;
85
86     assert(false); return fl;
87 }
88
89 #ifdef DEBUG
90     int numflips=0;
91 #endif
92 // Makes the flip (f,l,v).
93 void prismatoid::execFlip(flip fl) {
94     queue<mask> q; const mask f=fl.f, l=fl.l, v=fl.v, u=f|l|v;
95     // Note that the star (within the support) for a new face is:
96     // -If it has exactly one 0 in f, the support without that zero
97     // -If it has more than one 0 in f, u
98
99     #ifdef DEBUG

```

```

100     assert(everythingIsOK());
101 #endif
102 mask x=0; do {
103
104     // The forbidden facet
105     if(x==(f|l)) continue;
106
107     // The supersets of f are disappearing faces.
108     if(in(f,x)) {
109         if(countBits(x)==dim) dists.erase(x),--numFacets;
110         if(countBits(x)==dim-1) {
111             if(in(x,base2)) adyBase2.erase(x);
112             if(--options[SC[x]]==0) options.erase(SC[x]);
113         }
114         SC.erase(x);
115     }
116
117     // The supersets of l are appearing faces.
118     else if(in(l,x)) {
119         SC[x]= (countBits(f&~x)==1)? ((f&x)|l|v): u;
120         if(countBits(x)==dim) q.push(x),++numFacets;
121         if(countBits(x)==dim-1) {
122             if(in(x,base2)) adyBase2.insert(x);
123             ++options[SC[x]];
124         } }
125
126     // Stuff that remain the same.
127     else {
128         if(countBits(x)==dim-1) if(--options[SC[x]]==0) options.erase(SC[x]);
129         SC[x]&=~u; SC[x] |= ((countBits(f&~x)==1)? ((f&x)|l|v): u);
130         if(countBits(x)==dim-1) ++options[SC[x]];
131     }
132
133 } while(nextSubset(u,x), x!=u);
134
135 base1=SC[0]&LAYER1; base2=SC[0]&LAYER2; updateDists(q);
136
137 #ifdef DEBUG
138     if(!everythingIsOK()) {
139         cout<<"Panic Attack at flip "<<numflips<<endl;
140         printMask(f);
141         printMask(l);
142         printMask(v);
143         assert(false);
144     }
145     numflips++;
146 #endif
147 }
148

```

```

149 // Makes a random move. Returns its (f,l,v).
150 flip prismatoid::execFlip(rng& gen) {
151     flip fl=findFlip(gen); execFlip(fl); return fl;
152 }
153
154 // Allow a flip with support u if:
155 // - It is the ustar of a ridge (assumed by pertence to options)
156 // - There's room to add a new vertex (when required).
157 // - It does not add faces to the frontier (unless it is a frontier flip)
158 // - It does not change the set of vertices (under changeBases==false)
159 // - The ustar of f has exactly dim+1 vertices
160 // - The corresponding l is not in the complex.
161 // Returns the flip by reference.
162 bool prismatoid::checkFlip(mask u, flip& fl) {
163     mask f,l,v;
164
165     if(countBits(u)==dim) { // Add a vertex to the support when required.
166         mask newv, LAYER;
167
168         if (countBits(u&LAYER2)==1) newv= firstElement(LAYER1 &~base1);
169         else if(countBits(u&LAYER1)==1) newv= firstElement(LAYER2 &~base2);
170         else cerr<<"Error 841: Not enough cheese in buffer."<<endl;
171
172         if(newv==0) return false; u|=newv;
173     }
174
175     f=u;
176     for(mask x=firstElement(u); x!=0; nextElement(u,x))
177         if(SC.find(u^x)!=SC.end()) f&=u^x;
178     l=u^f;
179
180     if (countBits(u&base1)==1) v=(u&base1), f^=v;
181     else if (countBits(u&base2)==1) v=(u&base2), f^=v;
182     else v=0;
183
184     // Interior flips should not add new frontier faces.
185     if(v==0 && (in(l,base1) || in(l,base2))) return false;
186
187     // Am I adding/removing a vertex?
188     //if(!changeBases && (countBits(l)==1 || countBits(f)==1)) return false;
189
190     // Correct size of the support
191     if(v==0 && countBits(SC[f])!=dim+1) return false;
192     if(v!=0 && countBits(SC[f])!=dim) return false;
193
194     // l must not be in SC.
195     if(SC.find(l)!=SC.end()) return false;
196
197     fl.f=f; fl.l=l; fl.v=v; return true;

```

```

198 }
199
200 ///////////////////////////////////////////////////
201 // S3: Costs and graph stuff
202 ///////////////////////////////////////////////////
203
204 // Inits graph and dists
205 void prismatoid::initGraph() {
206     adyBase2=set<mask>(); queue<mask> q;
207
208     for(auto &it:SC) {
209         if(countBits(it.first)==dim-1) {
210             if ((LAYER1 & it.first)==0) adyBase2.insert(it.first);
211             else if((LAYER2 & it.first)==0) q.push(it.second);
212         } }
213     dists=map<mask,il>(); updateDists(q);
214 }
215
216
217 // Stuff for the computation of the diameter and width.
218 inline void relaxPair(il& me, il& other) {
219     if(other.first+1<me.first)         me.first = other.first+1,
220                                     me.second= other.second;
221     else if(other.first+1==me.first) me.second+=other.second;
222 }
223 void prismatoid::updateDists(queue<mask>& q) {
224
225     while(!q.empty()) {
226         mask f=q.front(), f2; q.pop();
227
228         if(countBits(base1&f)==dim-1) {
229             if(dists[f]==il(1,1)) continue;
230             dists[f]=il(1,1);
231
232             for(mask x= firstElement(f); x!=0; nextElement(f,x))
233                 if(SC.find(f^x)!=SC.end())
234                     if(countBits(f2=SC[f^x]^x)==dim) q.push(f2);
235         }
236         else {
237             // if(dists[f]==ii(0,0)) dists[f]=ii(201,0); // needed?
238             il aux(200,0);
239             for(mask x= firstElement(f); x!=0; nextElement(f,x))
240                 if(SC.find(f^x)!=SC.end())
241                     if(countBits(f2=SC[f^x]^x)==dim && dists.find(f2)!=dists.end())
242                         relaxPair(aux, dists[f2]);
243
244             if(aux!=dists[f]) {
245                 dists[f]=aux;
246                 for(mask x=firstElement(f); x!=0; nextElement(f,x))

```

```

247         if(SC.find(f^x)!=SC.end())
248             if(countBits(f2=SC[f^x]^x)==dim) q.push(f2);
249     } } }
250
251     il aux(200,0);
252     for(auto &it: adyBase2) relaxPair(aux, dists[SC[it]]);
253     assert(aux.first!=1); distBase2=aux;
254 }
255
256 // Number of vertices, distance and width
257 double prismatoid::cost() {
258     #ifdef PLAN_A
259     return double(numFacets);
260     #endif
261     #ifdef PLAN_B
262     mask vertices=base1|base2;
263     double avg=0.0;
264     for(mask x=firstElement(vertices); x!=0; nextElement(vertices,x))
265         avg+=log(countBits(SC[x]));
266     avg/=double(countBits(vertices));
267
268     return exp(avg);
269     #endif
270     #ifdef PLAN_C
271     mask vertices=base1|base2;
272     vector<double> ustars;
273
274     for(mask x=firstElement(vertices); x!=0; nextElement(vertices,x))
275         ustars.push_back((double)countBits(SC[x]));
276     sort(ustars.begin(),ustars.end());
277     return ustars[0]+ustars[1]+ustars[2]+ustars[3];
278     #endif
279     #ifdef PLAN_D
280     return SC.size();
281     #endif
282     #ifdef PLAN_E
283     mask vertices=base1|base2;
284     double avg=0.0, k=-3.0;
285     for(mask x=firstElement(vertices); x!=0; nextElement(vertices,x))
286         avg+=pow(countBits(SC[x])-dim,k)/double(countBits(vertices));
287
288     return countBits(vertices)*600 + (pow(avg,1/k)+dim);
289     #endif
290     #ifdef PLAN_Z
291     return (distBase2.first>dim)?-1e10:distBase2.second;
292     #endif
293 }
294 bool prismatoid::feasible() {
295     #ifndef PLAN_Z

```



```

296     return distBase2.first>dim;
297 #else
298     return true;
299 #endif
300 }
301
302 // f-vector and layers.
303 pair<vi, vi> prismatoid::statsForSantos() {
304     vi fvector(dim+1), layers(dim+2);
305     for(auto &it: SC) fvector[countBits(it.first)]++;
306     for(auto &it: dists) layers[it.second.second]++;
307
308     return make_pair(fvector, layers);
309 }
310
311 ///////////////////////////////////////////////////////////////////
312 // S4: Don't panic. Please don't panic.
313 ///////////////////////////////////////////////////////////////////
314
315 // Can I panic now?
316 #ifdef DEBUG
317 bool prismatoid::everythingIsOK() {
318
319     // 1: is SC a simplicial complex?
320     /**
321     for(auto& it: SC)
322         for(mask x=firstElement(it.first); x!=0; nextElement(it.first,x))
323             if(SC.find(it.first&~x)==SC.end()||!in(it.second,SC[it.first&~x])) {
324                 cout<<"I find your lack of queso annoying"<<endl;
325                 cout<<"face and ustar"<<endl;
326                 printMask(it.first);
327                 printMask(it.second);
328                 cout<<"son and ustar"<<endl;
329                 printMask(it.first&~x);
330                 printMask(SC[it.first&~x]);
331                 return false;
332             }
333     /**/
334
335     // 1.5: Pure simplicial complex
336     /**
337     for(auto &it: SC)
338         if(it.first==it.second && countBits(it.first)!=dim) {
339             cout<<"sssh, no tears. Only "<<numflips<<" dreams now"<<endl;
340             return false;
341         }
342     /**/
343
344     // 2: Every ridge must be internal xor in a base.

```

```

345  /**
346  for(auto& it: SC)
347      if(countBits(it.first)==dim-1)
348          if((countBits(it.second)==dim+1) ==
349              (in(it.first,base1) || in(it.first,base2))) {
350              cout<<"Non-specified excuse at "<<numflips<<"! *flips table*"<<endl;
351              printMask(it.first);
352              printMask(it.second);
353              return false;
354          }
355  /**/
356
357  // 3:  adybase2 is in fact adybase2
358  // 4:  options is options
359  /**
360  map<mask, int> otherOptions; set<mask> otherAdyBase2;
361  for(auto& it: SC)
362      if(countBits(it.first)==dim-1) {
363          otherOptions[it.second]++;
364          if(in(it.first, base2)) otherAdyBase2.insert(it.first);
365      }
366  if(options!=otherOptions) {
367      cout<<"Number of cows backflipping: "<<numflips<<endl;
368      return false;
369  }
370  if(adyBase2!=otherAdyBase2) {
371      cout<<numflips<<" people thinking in piranhas right now"<<endl;
372      return false;
373  }
374  for(auto& it: adyBase2){
375      assert(SC.find(it)!=SC.end());
376      if(dists.find(SC[it])==dists.end()) {
377          cout<<numflips<<" likes in Facebook"<<endl;
378          printMask(it);
379          printMask(SC[it]);
380          assert(SC.find(SC[it])!=SC.end());
381      }
382  }
383  /**/
384
385  // 5:  dists
386  /**
387  for(auto& it:SC)
388      if(countBits(it.first)==dim) {
389          mask f=it.first, f2; il aux(200,0);
390
391          if(dists.find(f)==dists.end()) {
392              cout<<numflips<<" weird errors yet to be invented"<<endl;
393              return false;

```

```

394     }
395
396     if(countBits(f&base1)==dim-1) {
397         if(dists[f]==il(1,1)) continue;
398         else {
399             cout<<numflips<<" bottles standing at the wall"<<endl;
400             return false;
401         }
402     }
403
404     for(mask x= firstElement(f); x!=0; nextElement(f,x))
405         if(SC.find(f^x)!=SC.end())
406             if(countBits(f2=SC[f^x]^x)==dim && dists.find(f2)!=dists.end())
407                 relaxPair(aux, dists[f2]);
408
409     if(aux!=dists[f]) {
410         cout<<"Please reset the Universe "<<numflips<<" times."<<endl;
411         return false;
412     }
413 }
414 il aux(200,0);
415 for(auto &it: adyBase2) relaxPair(aux, dists[SC[it]]);
416 if (aux!=distBase2) {
417     cout<<numflips<<" heroes saving the day"<<endl;
418     return false;
419 }
420
421 /**/
422 return true;
423 }
424 #endif

```