

Robot

- id
 - state
 - lastActivity
 - mtx
 - active
 - position
 - currentTask
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- + Robot()
 - + assignTask()
 - + getState()
 - + getLastActivity()
 - + getId()
 - + isActive()
 - + guidePatient()
 - + notifyAppointment()
 - + emergencyAssistance()
 - + displayInfo()
 - updateState()