The Muenster IceCube Display Software documentation

1 What you need

- Hardware:
 - 3× Teensy 3.2 connected to computer via USB, power supply and synchronized with each other
 - $-1 \times$ LED strip (at least) properly connected to one of the Teensys and power supply
 - Power supply (both the Teensys and the LED strips need 5 V)

• Software

- IceTray software V17-03-00
 (http://code.icecube.wisc.edu/svn/meta-projects/offline-software/
 releases/V17-03-00/)
- Teensyduino (https://www.pjrc.com/teensy/td_download.html) and an Arduino version compatible with it (https://www.arduino.cc/en/Main/Software)
- Teensy Loader (https://www.pjrc.com/teensy/loader.html)
- Python package pyusb (get it with pip AND pip3)
- All the stuff that is in folders muenster_icecube_display and teensy32_stuff
- A nice .i3 file

2 How to set this up

• Test whether pyusb works correctly by running Python interactively (should look something like the following):

```
$ python3
Python 3.4.0 ...
>>> import usb
>>> usb.version_info
(1, 0, 0, 'b2)
```

• Add the following rules from the teensy32_stuff folder so you can run all scripts as normal user:

```
$ sudo cp 90-icecube.rules /etc/udev/rules.d/
$ sudo groupadd leddisplay
$ usermod -a -G leddisplay [your username]
```

• Load the .hex file in the teensy32_stuff folder onto all three Teensys by means of the Teensy loader (explained on the Teensy webpage)

- Run the script display_info.py from the muenster_icecube_display folder to verify communication with the boards
 - \$ python3 display_info.py
- Now you have to load the display configuration (which strings are located where in the model) onto the Teensys. You do this by means of the update_eeprom.py script and the configuration file display_config_muenster.json. Should look something like this:

\$ sudo python3 update_eeprom.py display_config_muenster.json Found device

Please select one of the available device configurations to configure the device: (enter front, center or back here)

Selected configuration: Configuration uploaded. Please mark the device to be able to match it with its serial number or configuration. Please reboot the device for the new configuration to take effect.

• Verify wether writing new configuration worked by running display_info.py again; should get a slightly different output.

2.1 Testing and debugging

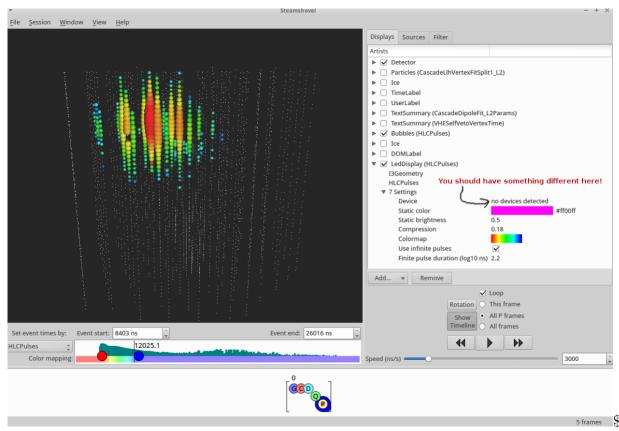
• The script test_draw.py in the muenster_icecube_display folder can be used for identifying your channels. The syntax is:

\$ python3 test_draw.py -m string -c 86 -d 1

The above command makes one string light up after the other (assuming 86 strings in total) for one second. Have a look at the script for more options like rgb mode and offset.

2.2 Controlling the display with steamshovel

- Open steamshovel:
 - \$ [directory of IceTray software]/build/ ./env-shell.sh
 - \$ steamshovel
- It is important at this point that the pyusb package is installed via pip, since steam-shovel runs on Python2 and not Python3
- Click the button "Add..." on the right and select LedDisplay()
- Select settings I3Geometry and e.g. HLCPulses (see figure 2.1)
- When you run your .i3 file, the onboard LEDs on the Teensys should flicker which means data is transmitted. The LED strips should light up in synch with the steamshovel event.
- HLCPulses if the cleanest service containing the pulses. They are triggered in time therefore only the event is shown. To produce this key (when it is not) and combine several files into only one, please use the script /preparefiles/processing.py.



[directory of IceTray software]/build/ ./env-shell.sh

Figure 2.1: A steamshovel screenshot with a possible configuration.

3 Errors you might see when running it

- After some loops, steamshovel breaks with an error as:
 - \$ Could not write frame to controller %s (USB errno 110 (maybe also 32)) There is a overlap between the teensy and the computer (probably because your computer is too slow). To solve this, we have to increased the max. time that pyusb allows for comunication between the teensy and the computer. Open the following files with root rights:
 - /usr/local/lib/python2.7/dist-packages/usb/legacy.py

Go to the lines 144 and 156, you should be over the member functions bulkWrite and bulkRead inside class DeviceHandle. By default the timeout of both functions is 100 ms. Increase it to 1000 or 10000. This should solve the issue.

- The led sometimes do blink/do something weird and you receive in the shell the following debug alert constantly:
 - \$ Rendering too fast, cannot send more than $25FPS^1$ Go to:
 - ${\tt \~IcetrayDirectory\'/src/steamshovel/python/artists/LedDisplay.py}$

You have to modify the parameter min_delta of the member function transmitDisplayBuffer

 $^{^{1}}$ The alert is only visible if Icetray was compiled with debug or higher verbosity level (by default it is)

inside the class <code>DisplayWorker</code> (line 501 in my version). Increase the render frequency by changing the default value of 1./25 to 1./15 or 1./10. This might not totally solve the problem but it should <code>improve</code>. If the problem it is not totally solve, you will still have the debug alert in the shell (still with 25FPS if you didn't change the logger.debug on line 514).

 \bullet If you see more errors or are able to solve the last one, please write me to: c_loza01@unimuenster.de