

4.2.3 GPS Decoded Message Blocks

GPSNav	Number:	5891	
	"OnChange"	interval: block generated each time a new navigation data set is	١
		received from a GPS satellite	l

The \mathtt{GPSNav} block contains the decoded navigation data for one GPS satellite. These data are conveyed in subframes 1 to 3 of the satellite navigation message. Refer to GPS ICD for further details.

Parameter	Туре	Units	Do-Not-Use	Description
Sync1	c1			
Sync2	c1			
CRC	u2			Block Header, see 4.1.1
ID	u2			
Length	u2	1 byte		
TOW	u4	0.001 s	4294967295	SIS time stamp, see 4.1.3
WNc	u2	1 week	65535	·
PRN	u1			ID of the GPS satellite of which the ephemeris is given in this block (see 4.1.9)
Reserved	u1			Reserved for future use, to be ignored by decoding software
MN	u2	1 week	65535	Week number (10 bits from subframe 1, word 3)
CAorPonL2	u1			Code(s) on L2 channel (2 bits from subframe 1, word 3)
URA	u1			User Range accuracy index (4 bits from subframe 1 word 3)
health	u1			6-bit health from subframe 1, word 3 (6 bits from subframe 1, word 3)
L2DataFlag	u1			Data flag for L2 P-code (1 bit from subframe 1, word 4)
IODC	u2			Issue of data, clock (10 bits from subframe 1)
IODE2	u1			Issue of data, ephemeris (8 bits from subframe 2)
IODE3	u1			Issue of data, ephemeris (8 bits from subframe 3)
FitIntFlg	u1			Curve Fit Interval, (1 bit from subframe 2, word 10)
Reserved2	u1			unused, to be ignored by decoding software
T_gd	f4	1 s		Estimated group delay differential
t_oc	u4	1 s		clock data reference time
a_f2	f4	1 s / s ²		SV clock aging
a_f1	f4	1 s / s		SV clock drift
a_f0	f4	1 s		SV clock bias
C_rs	f4	1 m		Amplitude of the sine harmonic correction term to the orbit radius
DEL_N	f4	1 semi-circle / s		Mean motion difference from computed value
M_0	f8	1 semi-circle		Mean anomaly at reference time
C_uc	f4	1 rad		Amplitude of the cosine harmonic correction term to the argument of latitude
е	f8			Eccentricity
C_us	f4	1 rad		Amplitude of the sine harmonic correction term to the argument of latitude
SQRT_A	f8	1 m ^{1/2}		Square root of the semi-major axis
t_oe	u4	1 s		Reference time ephemeris



C_ic	f4	1 rad	Amplitude of the cosine harmonic correction term to the angle of inclination
OMEGA_0	f8	1 semi-circle	Longitude of ascending node of orbit plane at weekly epoch
C_is	f4	1 rad	Amplitude of the sine harmonic correction term to the angle of inclination
i_0	f8	1 semi-circle	Inclination angle at reference time
C_rc	f4	1 m	Amplitude of the cosine harmonic correction term to the orbit radius
omega	f8	1 semi-circle	Argument of perigee
OMEGADOT	f4	1 semi-circle / s	Rate of right ascension
IDOT	f4	1 semi-circle / s	Rate of inclination angle
WNt_oc	u2	1 week	WN associated with t_oc, modulo 1024
WNt_oe	u2	1 week	WN associated with t_oe, modulo 1024
Padding	u1[]		Padding bytes, see 4.1.5



GPSAlm	Number:	5892
	"OnChange"	interval: block generated each time a new almanac data set is re-
		ceived from a GPS satellite

The \mathtt{GPSAlm} block contains the decoded almanac data for one GPS satellite. These data are conveyed in subframes 4 and 5 of the satellite navigation message. Refer to GPS ICD for further details.

		Description
		Block Header, see 4.1.1
byte		
001 s 429	94967295	SIS time stamp, see 4.1.3
week 65	535	313 time stamp, see 4.7.3
		ID of the GPS satellite of which the almanac is given in this block (see 4.1.9)
		Reserved for future use, to be ignored by decoding software
		Eccentricity
S		almanac reference time of week
semi-circle		Inclination angle at reference time, relative to $i_0 = 0.3$ semi-circles
semi-circle / s		Rate of right ascension
m ^{1/2}		Square root of the semi-major axis
semi-circle		Longitude of ascending node of orbit plane at weekly epoch
semi-circle		Argument of perigee
semi-circle		Mean anomaly at reference time
s/s		SV clock drift
S		SV clock bias
week		Almanac reference week, to which t_oa is referenced
		Anti-spoofing and satellite configuration (4 bits from subframe 4, page 25)
		health on 8 bits from the almanac page
		health summary on 6 bits (from subframe 4, page 25 and subframe 5 page 25)
		Padding bytes, see 4.1.5
	emi-circle emi-circle / s n ^{1/2} emi-circle emi-circle emi-circle / s	emi-circle emi-circle emi-circle emi-circle emi-circle emi-circle emi-circle ewi-circle ewi-circle ewi-circle



GPSIon	Number:	5893
	"OnChange"	interval: block generated each time subframe 4, page 18, is re-
		ceived from a GPS satellite

The GPSIon block contains the decoded ionosphere data (the Klobuchar coefficients). These data are conveyed in subframes 4, page 18 of the satellite navigation message. Refer to GPS ICD for further details.

Parameter	Туре	Units	Do-Not-Use	Description
Sync1	c1			
Sync2	c1			
CRC	u2			Block Header, see 4.1.1
ID	u2			
Length	u2	1 byte		
TOW	u4	0.001 s	4294967295	SIS time stamp, see 4.1.3
WNc	u2	1 week	65535	ors time stamp, see 4.1.5
PRN	u1			ID of the GPS satellite from which the coefficients have been received (see 4.1.9)
Reserved	u1			Reserved for future use, to be ignored by decoding software
alpha_0	f4	1 s		vertical delay coefficient 0
alpha_1	f4	1 s / semi-circle		vertical delay coefficient 1
alpha_2	f4	1 s / semi-circle ²		vertical delay coefficient 2
alpha_3	f4	1 s / semi-circle ³		vertical delay coefficient 3
beta_0	f4	1 s		model period coefficient 0
beta_1	f4	1 s / semi-circle		model period coefficient 1
beta_2	f4	1 s / semi-circle ²		model period coefficient 2
beta_3	f4	1 s / semi-circle ³		model period coefficient 3
Padding	u1[]			Padding bytes, see 4.1.5



GPSUtc	Number:	5894
	"OnChange"	interval: block generated each time subframe 4, page 18, is re-
		ceived from a GPS satellite

The \mathtt{GPSUtc} block contains the decoded UTC data. These data are conveyed in subframes 4, page 18 of the satellite navigation message. Refer to GPS ICD for further details.

Parameter	Туре	Units	Do-Not-Use	Description
Sync1	c1			
Sync2	c1			
CRC	u2			Block Header, see 4.1.1
ID	u2			
Length	u2	1 byte		
TOW	u4	0.001 s	4294967295	SIS time stamp, see 4.1.3
WNc	u2	1 week	65535	Jos time stamp, see 4.1.5
PRN	u1			ID of the GPS satellite from which these UTC parameters have been received (see 4.1.9)
Reserved	u1			Reserved for future use, to be ignored by decoding software
A_1	f4	1 s / s		first order term of polynomial
A_0	f8	1 s		constant term of polynomial
t_ot	u4	1 s		reference time for UTC data
WN_t	u1	1 week		UTC reference week number, to which t_ot is referenced
DEL_t_LS	i1	1 s		Delta time due to leap seconds whenever the effectivity time is not in the past
WN_LSF	u1	1 week		Effectivity time of leap second (week)
DN	u1	1 day		Effectivity time of leap second (day, from 1 to 7)
DEL_t_LSF	i1	1 s		Delta time due to leap seconds whenever the effectivity time is in the past