Multiclass Image Classification Project

Analisis Sederhana terhadap Data

Link dataset: https://www.kaggle.com/datasets/varpit94/disaster-images-dataset/code

Dataset yang digunakan terdiri atas 6 kategori utama, yaitu:

- 1. Damaged_Infrastructure (Earthquake, Infrastucture): gambar kerusakan infrastruktur / dampak gempa.
- 2. Fire_Disaster (Urban_Fire, Wild_Fire): gambar kebakaran di urban fire dan wild fire.
- 3. Human_Damage: gambar dampak bencana terhadap manusia
- 4. Land_Disaster (Drought, Land_Slide): gambar bencana tanah seperti drought dan land slide.
- 5. Non_Damage (Non_Damage_Buildings_Street, Non_Damage_Wildfire_Forest, human, sea): gambar tanpa kerusakan, seperti bangunan dan hutan utuh, manusia, dan perairan.
- 6. Water_Disaster: gambar bencana yang disebabkan oleh air.

Untuk project multiclass image classification ini, terdapat 4 class yang akan digunakan, yaitu Earthquake, Urban_Fire, Land_Slide, dan Water_Disaster. Dari analisis pada tahap data preparation, dapat diketahui bahwa terdapat class imbalance pada Earthquake (jumlah gambarnya jauh lebih sedikit dibandingkan class lainnya), sehingga diperlukan beberapa pendekatan agar proses training tetap optiimal.

Environment Setup

Import modules and libraries

```
import zipfile
import random
import os
import shutil
import numpy as np
import pandas as pd
import seaborn as sns
import matplotlib.pyplot as plt
from PIL import Image, ImageFile
from collections import defaultdict, Counter
from sklearn.model_selection import train_test_split
from sklearn.metrics import classification_report, confusion_matrix,
ConfusionMatrixDisplay
from sklearn.utils.class_weight import compute_class_weight
from sklearn.model_selection import train_test_split
```

```
import tensorflow as tf
from tensorflow import keras
from tensorflow.keras.layers import Conv2D, MaxPooling2D, Flatten,
Dense, Dropout, Input, BatchNormalization, GlobalAveragePooling2D,
LeakyReLU
from tensorflow.keras.callbacks import ModelCheckpoint, EarlyStopping,
ReduceLROnPlateau, CSVLogger
from tensorflow.keras.preprocessing import
image ,image_dataset_from_directory
from tensorflow.keras.preprocessing.image import ImageDataGenerator,
load_img, img_to_array
from tensorflow.keras.models import Model, load_model, Sequential
from tensorflow.keras.applications import MobileNetV2
from tensorflow.keras.optimizers import Adam
```

Set up seed = 42

```
SEED_VALUE = 42
np.random.seed(SEED_VALUE)
random.seed(SEED_VALUE)
tf.random.set_seed(SEED_VALUE)
```

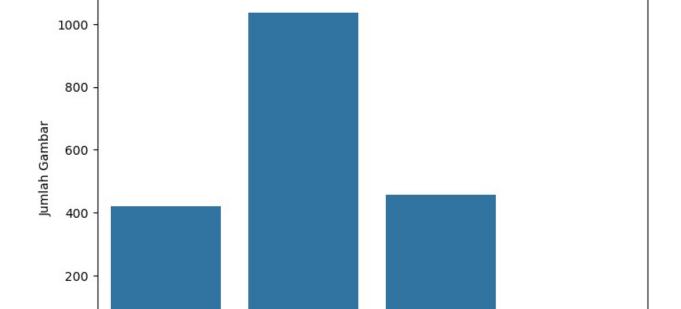
Data Preparation

```
with zipfile.ZipFile('CDD.zip', 'r') as zip_ref:
    zip_ref.extractall('data')

dataset_root = os.path.join('data', 'Comprehensive Disaster
Dataset(CDD)')
dataset_path = 'data'
source_map = {
    'Fire_Disaster/Urban_Fire': 'Urban Fire',
    'Water_Disaster': 'Water Disaster',
    'Land_Disaster/Land_Slide': 'Land Slide',
    'Damaged_Infrastructure/Earthquake': 'Earthquake'
}
```

EDA

1. Distribusi jumlah gambar per class



Water Disaster

Land Slide

Earthquake

0

Urban Fire

Distribusi Jumlah Gambar per Class

Dataset memiliki distribusi jumlah gambar yang tidak seimbang antar class. Terlihat bahwa Water Disaster (1035 gambar) mendominasi dataset, sementara Earthquake (36 gambar) sangat sedikit sehingga berpotensi menyebabkan **class imbalance** pada model.

2. Contoh gambar dari setiap class

```
plt.figure(figsize=(12, 8))
for i, (rel_path, class_name) in enumerate(source_map.items()):
    full_path = os.path.join(dataset_root, rel_path)
    sample_img = random.choice(os.listdir(full_path))
    img = Image.open(os.path.join(full_path, sample_img))
    plt.subplot(2, 2, i+1)
    plt.imshow(img)
    plt.title(class_name)
    plt.axis("off")
plt.suptitle("Contoh Gambar dari Setiap Class", fontsize=16)
plt.show()
```

Contoh Gambar dari Setiap Class

Urban Fire



Land Slide



Water Disaster



Earthquake



Berdasarkan contoh gambar dari masing-masing class di atas, dapat diketahui bahwa ciri khasnya adalah:

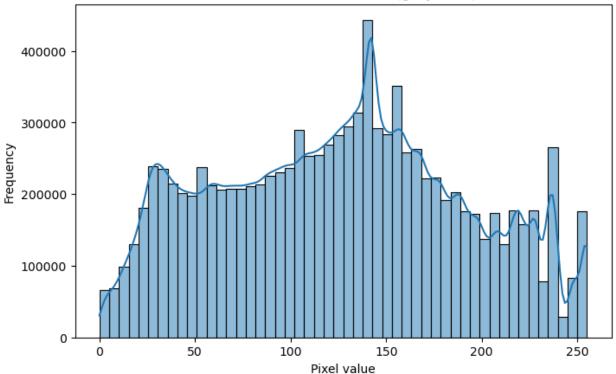
- Urban Fire: api di area perkotaan
- Water Disaster: banjir atau bencana air
- Land Slide: longsor di area pemukiman atau jalan
- Earthquake: reruntuhan akibat gempa bumi

Visualisasi ini membantu memastikan bahwa label data sudah sesuai dengan isi gambar.

3. Distribusi intensitas pixel (10 sample per class)

```
sample_paths = []
for rel_path, _ in source_map.items():
    full path = os.path.join(dataset root, rel path)
    sample paths.extend([os.path.join(full_path, f) for f in
os.listdir(full path)[:10]])
pixels = []
for sp in sample paths:
    img = Image.open(sp).convert("L")
    pixels.extend(np.array(img).flatten())
    img.close()
plt.figure(figsize=(8,5))
sns.histplot(pixels, bins=50, kde=True)
plt.title("Distribusi Intensitas Pixel (grayscale)")
plt.xlabel("Pixel value")
plt.ylabel("Frequency")
plt.show()
```

Distribusi Intensitas Pixel (grayscale)



Analisis ini dilakukan dengan mengambil 10 sampel gambar dari tiap class (total 40 gambar), lalu mengonversinya ke grayscale dan menghitung distribusi nilai piksel (0 = hitam, 255 = putih).

- Nilai piksel tersebar dari 0 hingga 255, menandakan adanya variasi pencahayaan yang luas.
- Terlihat puncak distribusi di sekitar 150, menandakan banyak gambar memiliki area terang.
- Frekuensi piksel gelap (< 50) juga cukup tinggi, menandakan keberadaan objek kontras seperti api, reruntuhan, atau bayangan.

Dapat disimpulkan bahwa dataset memiliki kontras tinggi antara area gelap dan terang, sehingga preprocessing seperti normalisasi pixel akan sangat dibutuhkan agar model lebih stabil saat training.

Splitting Data

```
for split in ['train', 'test']:
    split_dir = os.path.join(dataset_path, split)
    if os.path.exists(split_dir):
        shutil.rmtree(split_dir)

split_ratio = 0.8

for rel_path, label in source_map.items():
```

```
src folder = os.path.join(dataset root, rel path)
    all files = [f for f in os.listdir(src folder)]
    random.shuffle(all files)
    split idx = int(len(all files) * split_ratio)
    train files = all files[:split idx]
    test_files = all_files[split_idx:]
    for fname in train files:
        dst = os.path.join(dataset path, 'train', label)
        os.makedirs(dst, exist ok=True)
        shutil.copy(os.path.join(src folder, fname), os.path.join(dst,
fname))
    for fname in test files:
        dst = os.path.join(dataset path, 'test', label)
        os.makedirs(dst, exist ok=True)
        shutil.copy(os.path.join(src folder, fname), os.path.join(dst,
fname))
    print(f"{label} - train: {len(train files)}, test:
{len(test files)}")
Urban Fire - train: 335, test: 84
Water Disaster - train: 828, test: 207
Land Slide - train: 364, test: 92
Earthquake - train: 28, test: 8
def detect tf decode errors(directory):
    problematic files = []
    for root, _, files in os.walk(directory):
    for file in files:
            if file.lower().endswith(('.jpg', '.jpeg', '.png', '.bmp',
'.gif')):
                file path = os.path.join(root, file)
                try:
                    image data = tf.io.read file(file path)
                    = tf.image.decode image(image data, channels=3)
                except tf.errors.InvalidArgumentError:
                    print("TensorFlow decode error:", file path)
                    problematic files.append(file path)
    return problematic files
train dir = "data/train"
test dir = "data/test"
errors train = detect tf decode errors(train dir)
errors test = detect tf decode errors(test dir)
TensorFlow decode error: data/train\Land Slide\04 01 0007.png
TensorFlow decode error: data/train\Land Slide\04 01 0335.png
```

```
TensorFlow decode error: data/train\Urban Fire\01 01 0060.png
TensorFlow decode error: data/test\Land Slide\04 01 0373.png
files to remove = [
    "data/train/Land Slide/04 01 0007.png",
    "data/train/Land Slide/04 01 0335.png",
    "data/train/Urban Fire/01_01_0060.png",
    "data/test/Land Slide/04 01 0373.png"
1
for file path in files to remove:
    if os.path.exists(file path):
        os.remove(file path)
        print(f"file removed: {file path}")
    else:
        print(f"file not found: {file path}")
file removed: data/train/Land Slide/04 01 0007.png
file removed: data/train/Land Slide/04 01 0335.png
file removed: data/train/Urban Fire/01 01 0060.png
file removed: data/test/Land Slide/04 01 0373.png
image size = (224, 224)
batch size = 32
AUTOTUNE = tf.data.AUTOTUNE
train ds = tf.keras.preprocessing.image dataset from directory(
    os.path.join(dataset path, 'train'),
    validation split=0.2,
    subset="training",
    seed=SEED VALUE,
    label mode='categorical',
    image size=image size,
    batch size=batch size,
    shuffle=True
)
val ds = tf.keras.preprocessing.image dataset from directory(
    os.path.join(dataset path, 'train'),
    validation_split=0.2,
    subset="validation",
    seed=SEED VALUE,
    label mode='categorical',
    image size=image size,
    batch size=batch size,
    shuffle=True
)
test ds = tf.keras.preprocessing.image dataset from directory(
    os.path.join(dataset path, 'test'),
```

```
label_mode='categorical',
   image_size=image_size,
   batch_size=batch_size,
   shuffle=False
)

Found 1552 files belonging to 4 classes.
Using 1242 files for training.
Found 1552 files belonging to 4 classes.
Using 310 files for validation.
Found 390 files belonging to 4 classes.
label_names = train_ds.class_names
```

Normalization

```
normalization_layer = tf.keras.layers.Rescaling(1./255)
train_ds = train_ds.map(lambda x, y: (normalization_layer(x), y),
num_parallel_calls=AUTOTUNE)
val_ds = val_ds.map(lambda x, y: (normalization_layer(x), y),
num_parallel_calls=AUTOTUNE)
test_ds = test_ds.map(lambda x, y: (normalization_layer(x), y),
num_parallel_calls=AUTOTUNE)
```

Data normalization ini berfungsi untuk meningkatkan akurasi dengan mengubah pixel dari 0-255 (RGB) jadi nilai 0-1.

Augmentation

```
data_augmentation = tf.keras.Sequential([
    tf.keras.layers.RandomFlip("horizontal"),
    tf.keras.layers.RandomRotation(0.05),
    tf.keras.layers.RandomZoom(0.1),
    tf.keras.layers.RandomContrast(0.1)
])

train_ds = train_ds.map(lambda x, y: (data_augmentation(x,
training=True), y), num_parallel_calls=AUTOTUNE)
```

Data augmentation berfungsi untuk menghindari overfitting dengan menambah variasi data training secara acak.

Prefetch

```
train_ds = train_ds.prefetch(buffer_size=AUTOTUNE)
val_ds = val_ds.prefetch(buffer_size=AUTOTUNE)
test_ds = test_ds.prefetch(buffer_size=AUTOTUNE)
```

Prefetch untuk meningkatkan optimasi performance.

Modelling and Experimentation

```
early stop = EarlyStopping(monitor='val loss', patience=5,
restore best weights=True)
all labels = []
for images, labels in train_ds.unbatch():
    label val = labels.numpy()
    if label val.ndim > 0 and label val.size > 1:
        label scalar = np.argmax(label val)
    else:
        label_scalar = label val.item()
    all labels.append(label scalar)
all labels = np.array(all labels)
class weights = compute class weight(
    class weight='balanced',
    classes=np.unique(all labels),
    y=all labels
)
class weight dict = dict(enumerate(class weights))
print("class weights:", class weight dict)
class weights: {0: 14.785714285714286, 1: 1.0315614617940199, 2:
1.154275092936803, 3: 0.4769585253456221}
```

Dari distribusi data di atas, terlihat bahwa jumlah sampel pada kelas Earthquake jauh lebih sedikit dibandingkan kelas lain (hanya 36 gambar). Jika dilakukan training pada dataset yang imbalanced, model cenderung bias terhadap kelas mayoritas dan menyyebabkan performa prediksi pada kelas minoritas (seperti Earthquake) akan buruk.

Untuk mengurangi masalah tersebut, digunakan metode class weighting, yaitu memberikan bobot lebih besar pada kelas yang jumlah datanya sedikit, dan bobot lebih kecil pada kelas dengan jumlah data yang banyak.

```
label_names
['Earthquake', 'Land Slide', 'Urban Fire', 'Water Disaster']
```

LABEL:

0 - Earthquake; 1 - Land slide; 2 - Urban Fire; 3 - Water Disaster

Model 1 (from scratch)

```
Conv2D(32, (3, 3), activation='relu'),
MaxPooling2D(pool_size=(2, 2)),
BatchNormalization(),

Conv2D(64, (3, 3), activation='relu'),
MaxPooling2D(pool_size=(2, 2)),
BatchNormalization(),

Conv2D(128, (3, 3), activation='relu'),
MaxPooling2D(pool_size=(2, 2)),
BatchNormalization(),

Flatten(),
Dense(128, activation='relu'),
Dropout(0.5),
Dense(num_classes, activation='softmax')
])
return model
```

- Terdiri atas 4 hidden layers dengan aktivasi relu.
- Output layer menggunakan fungsi aktivasi softmax karena digunakan untuk klasifikasi multi-class.

```
model1 = design model1()
model1.compile(optimizer=Adam(learning rate=0.001),loss='categorical c
rossentropy',metrics=['accuracy'])
model1.summary()
Model: "sequential 1"
Layer (type)
                                       Output Shape
Param #
 conv2d (Conv2D)
                                        (None, 222, 222, 32)
896
                                       (None, 111, 111, 32)
 max pooling2d (MaxPooling2D)
0 |
 batch normalization
                                        (None, 111, 111, 32)
128 l
  (BatchNormalization)
```

```
conv2d 1 (Conv2D)
                                      (None, 109, 109, 64)
18,496
                                      (None, 54, 54, 64)
 max_pooling2d_1 (MaxPooling2D)
batch normalization 1
                                       (None, 54, 54, 64)
256
  (BatchNormalization)
 conv2d 2 (Conv2D)
                                      (None, 52, 52, 128)
73,856
 max pooling2d 2 (MaxPooling2D)
                                      (None, 26, 26, 128)
0 |
 batch normalization 2
                                       (None, 26, 26, 128)
  (BatchNormalization)
                                       (None, 86528)
 flatten (Flatten)
0
 dense (Dense)
                                       (None, 128)
11,075,712 |
dropout (Dropout)
                                       (None, 128)
0
dense_1 (Dense)
                                       (None, 4)
516
Total params: 11,170,372 (42.61 MB)
Trainable params: 11,169,924 (42.61 MB)
```

```
Non-trainable params: 448 (1.75 KB)
history model1 = model1.fit(train ds,
                        validation data=val ds,
                        epochs=50,
                        callbacks=[early stop],
                        class weight=class weight dict)
Epoch 1/50
39/39 —
                13.6744 - val accuracy: 0.2065 - val loss: 5.9115
Epoch 2/50
                 ----- 78s 2s/step - accuracy: 0.4790 - loss:
39/39 —
12.7139 - val_accuracy: 0.0484 - val loss: 10.7566
Epoch 3/50
                  —— 76s 2s/step - accuracy: 0.4607 - loss:
39/39 —
8.5047 - val accuracy: 0.2032 - val loss: 16.0583
Epoch 4/50
             71s 2s/step - accuracy: 0.5029 - loss:
39/39 —
7.4182 - val accuracy: 0.4613 - val loss: 4.6407
3.8800 - val accuracy: 0.5806 - val loss: 2.5381
Epoch 6/50
           ______ 70s 2s/step - accuracy: 0.4924 - loss:
39/39 ———
3.0708 - val accuracy: 0.4290 - val loss: 2.7457
Epoch 7/50
               39/39 —
3.8117 - val accuracy: 0.5355 - val loss: 6.3857
Epoch 8/50
                   —— 75s 2s/step - accuracy: 0.4989 - loss:
4.4235 - val accuracy: 0.3935 - val loss: 6.3608
Epoch 9/50
                   --- 75s 2s/step - accuracy: 0.4102 - loss:
39/39 -
2.3355 - val accuracy: 0.3065 - val loss: 5.7916
Epoch 10/50 74s 2s/step - accuracy: 0.4531 - loss:
2.0704 - val accuracy: 0.4516 - val loss: 7.8406
```

Model 2 (params < 10M)

```
def design_model2(input_shape=(224, 224, 3), num_classes=4):
    base_model = MobileNetV2(include_top=False, weights='imagenet',
input_shape=input_shape)
    base_model.trainable = True

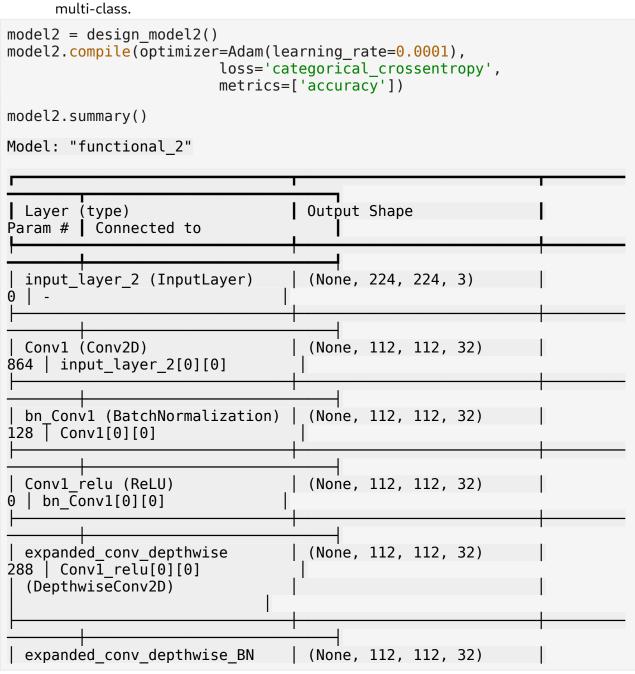
for layer in base_model.layers[:-50]:
    layer.trainable = False

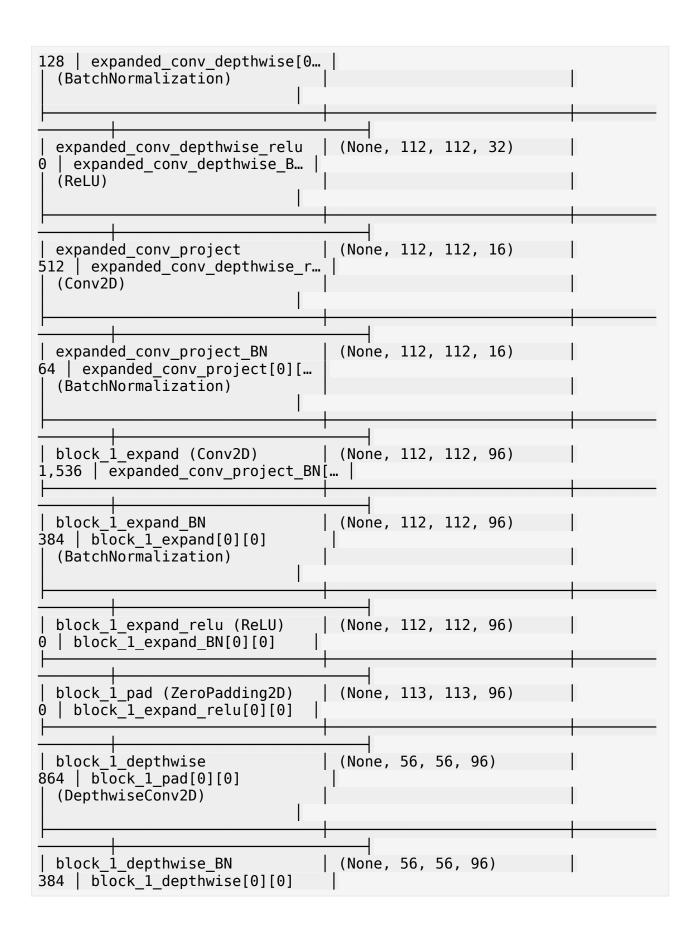
x = base_model.output
```

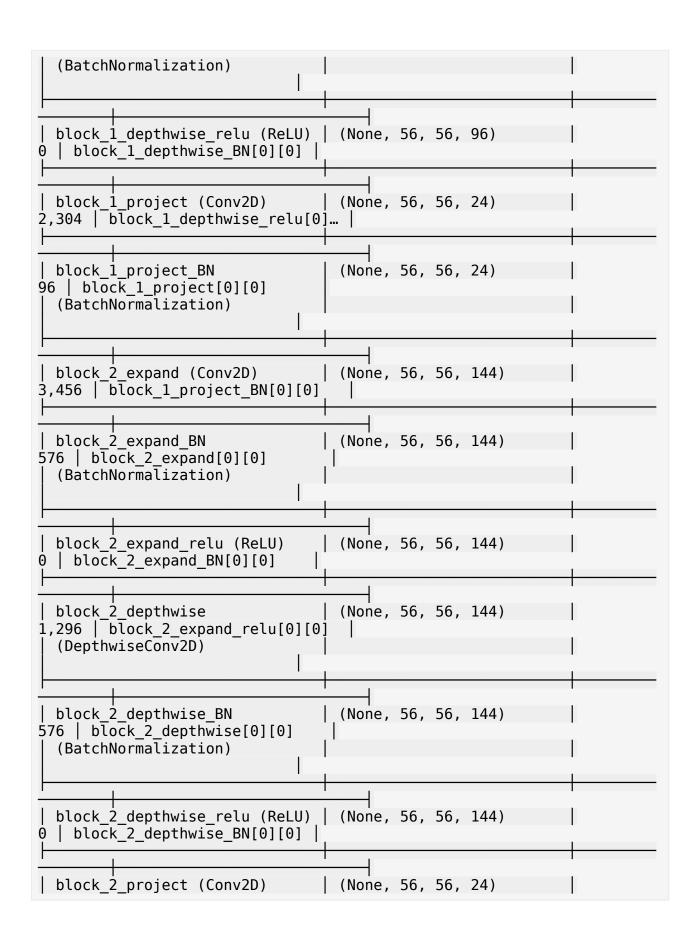
```
x = GlobalAveragePooling2D()(x)
x = Dropout(0.3)(x)
x = Dense(128, activation='relu')(x)
x = Dropout(0.3)(x)
predictions = Dense(num_classes, activation='softmax')(x)

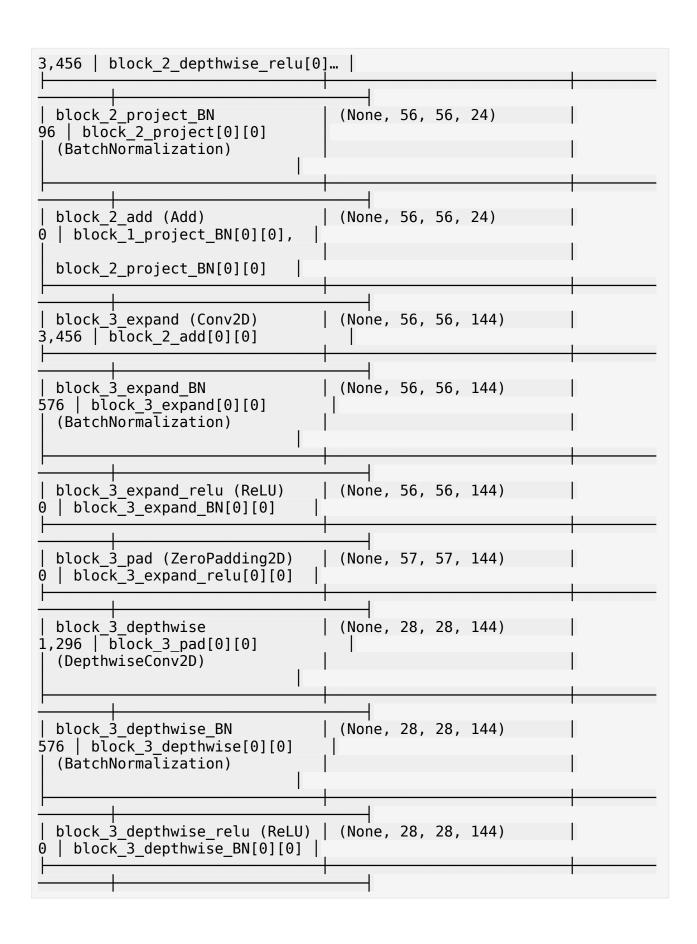
model = Model(inputs=base_model.input, outputs=predictions)
return model
```

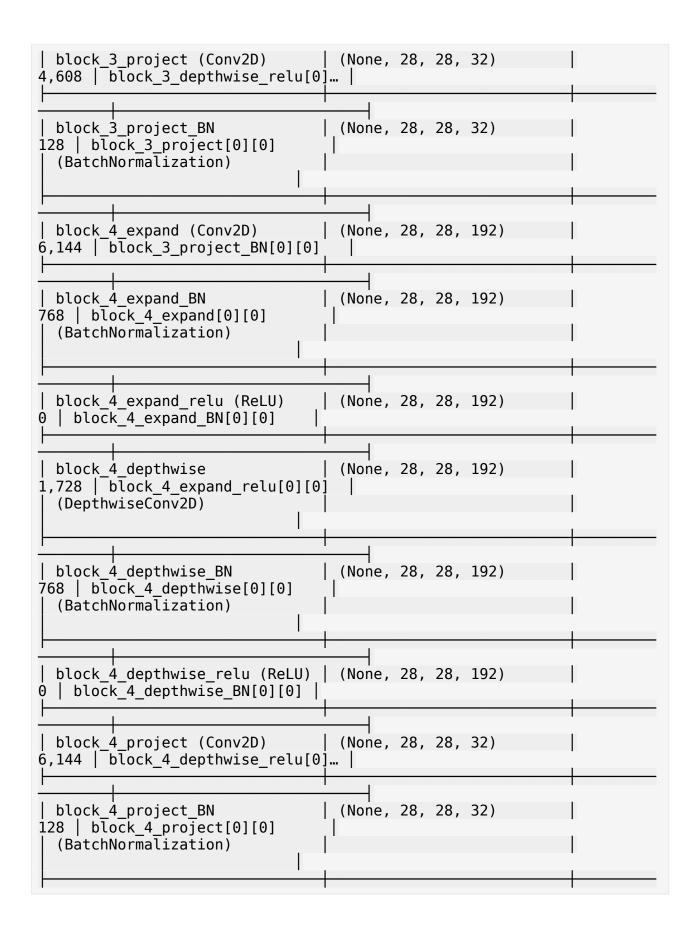
 Output layer menggunakan fungsi aktivasi softmax karena digunakan untuk klasifikasi multi-class.

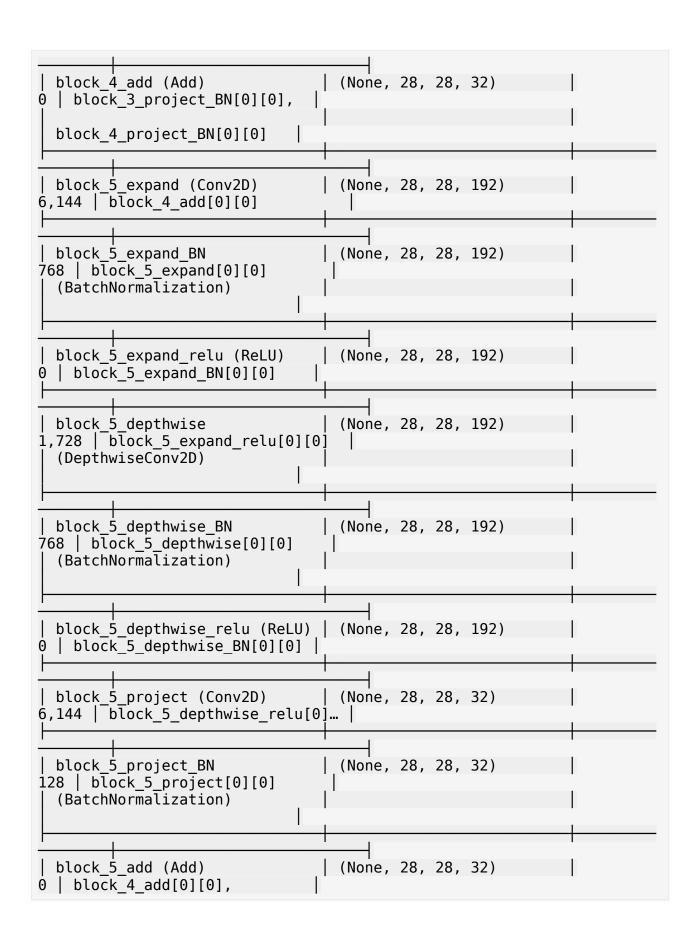


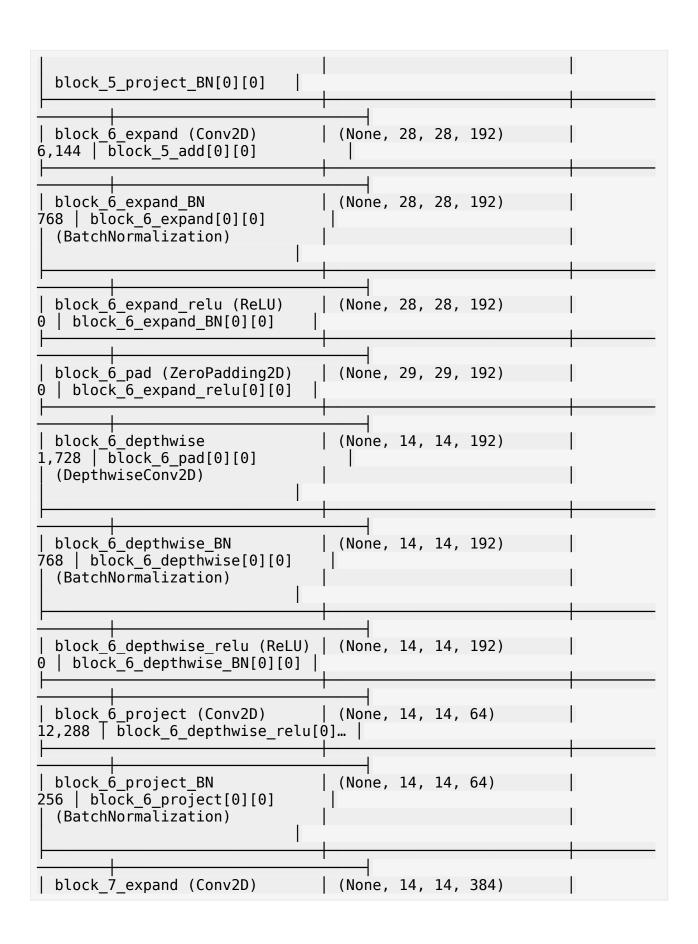


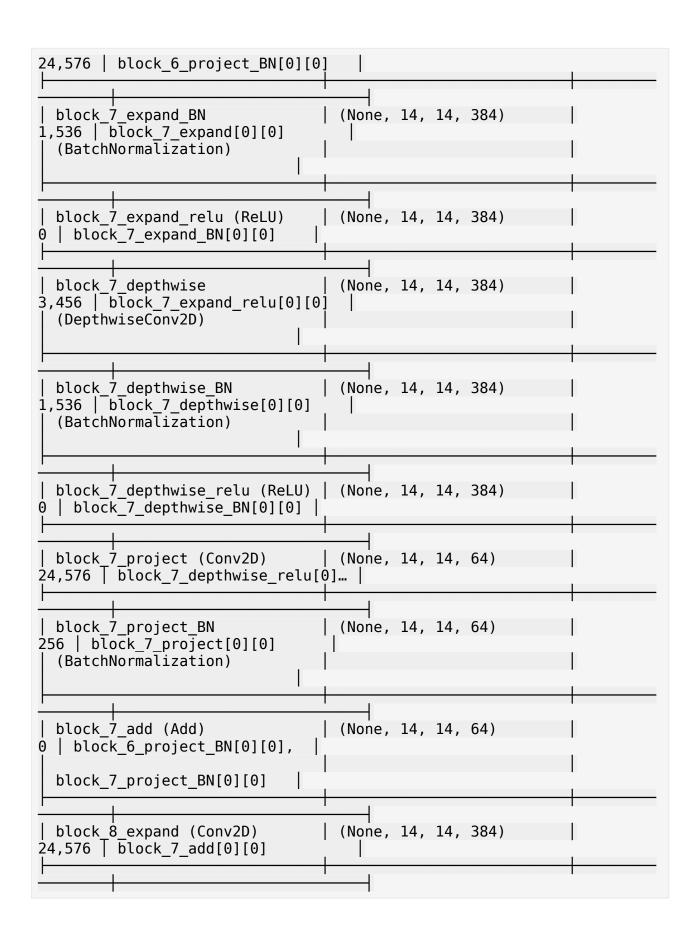


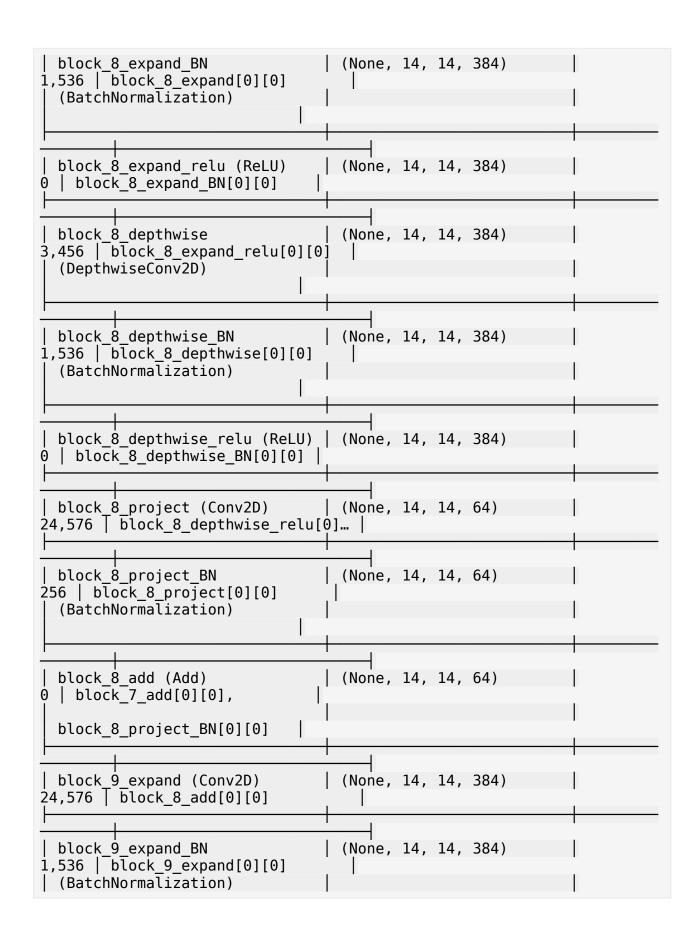


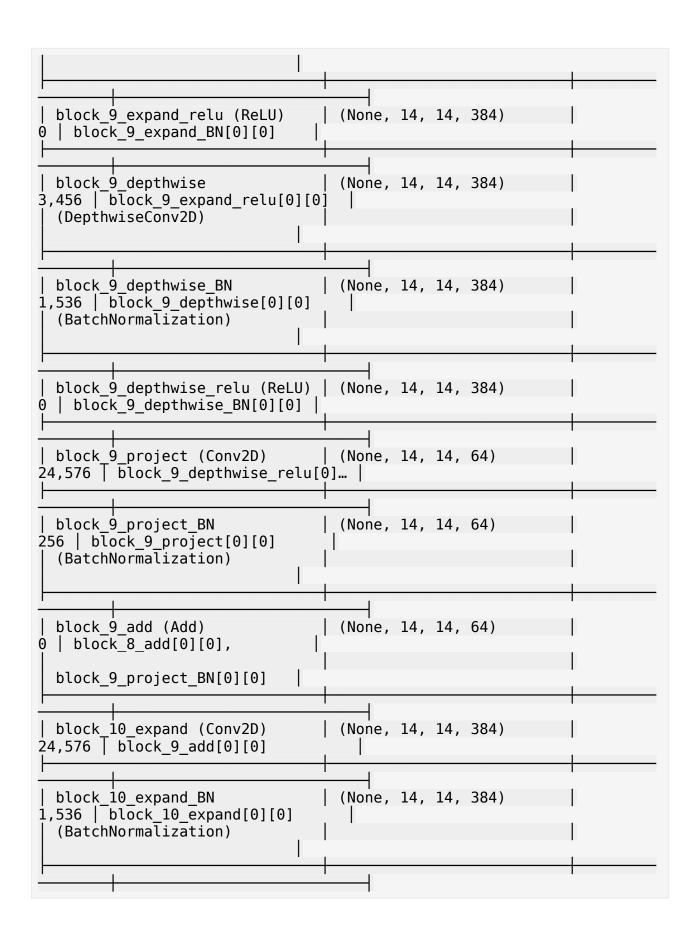


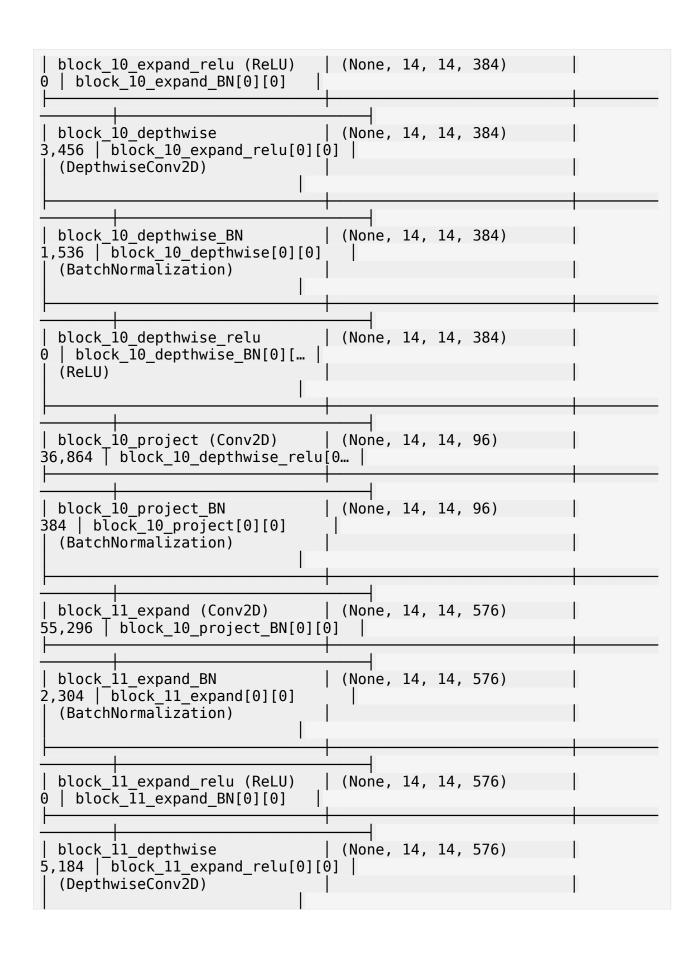


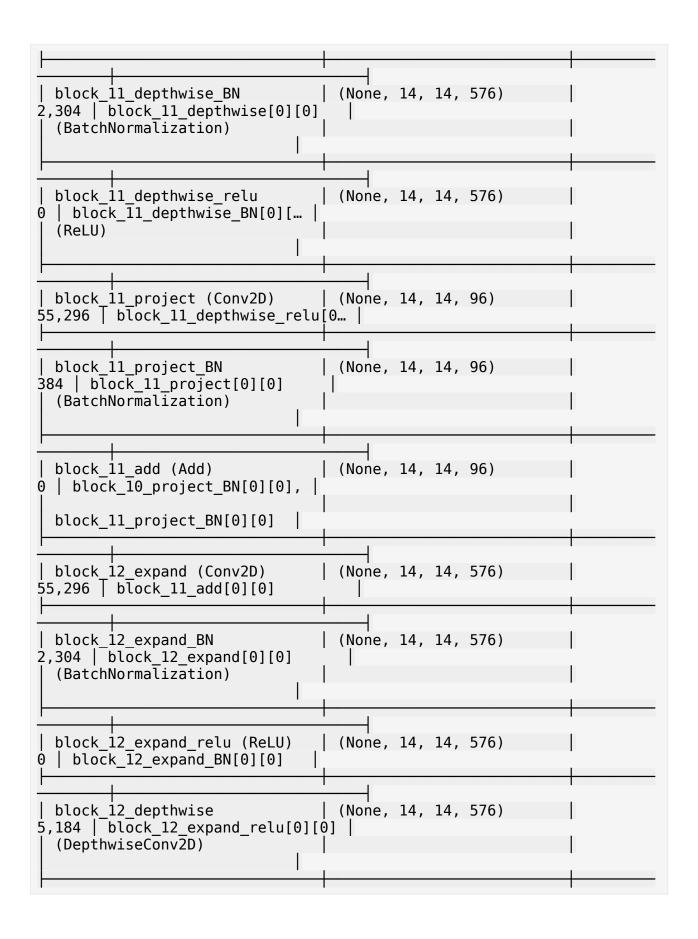


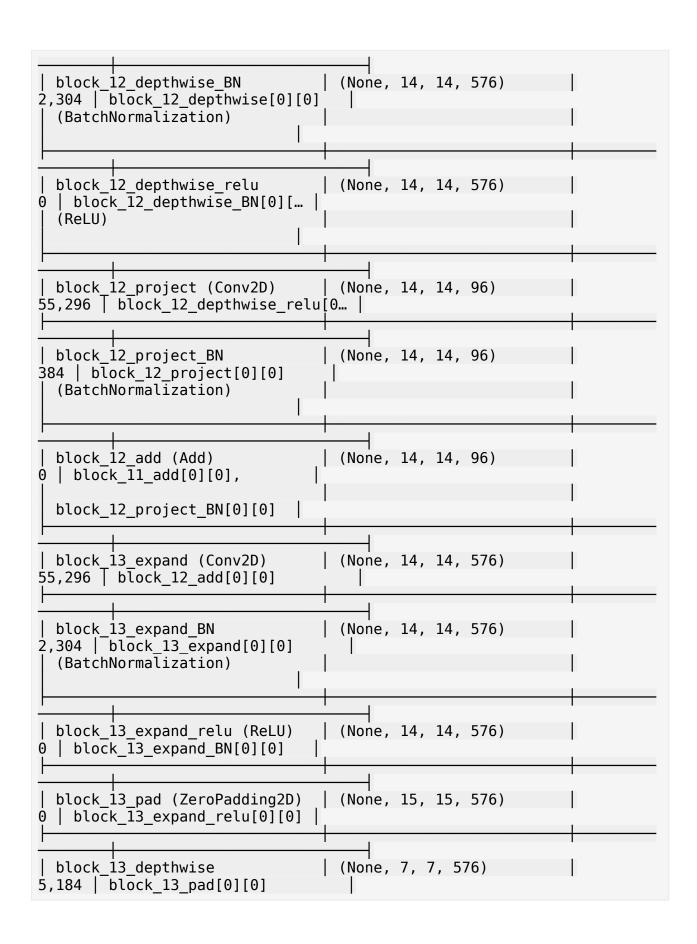


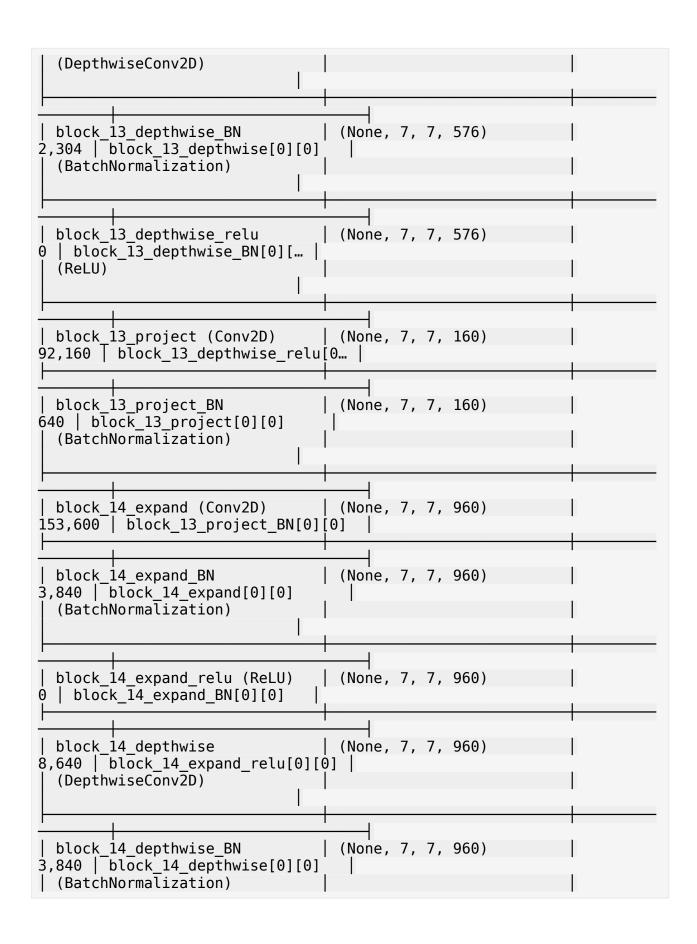


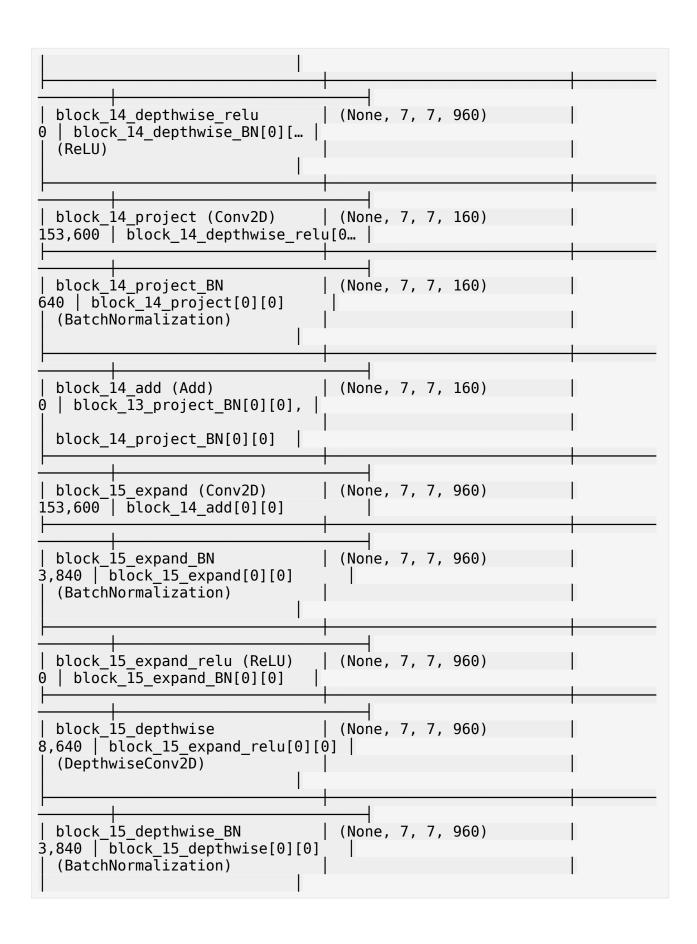


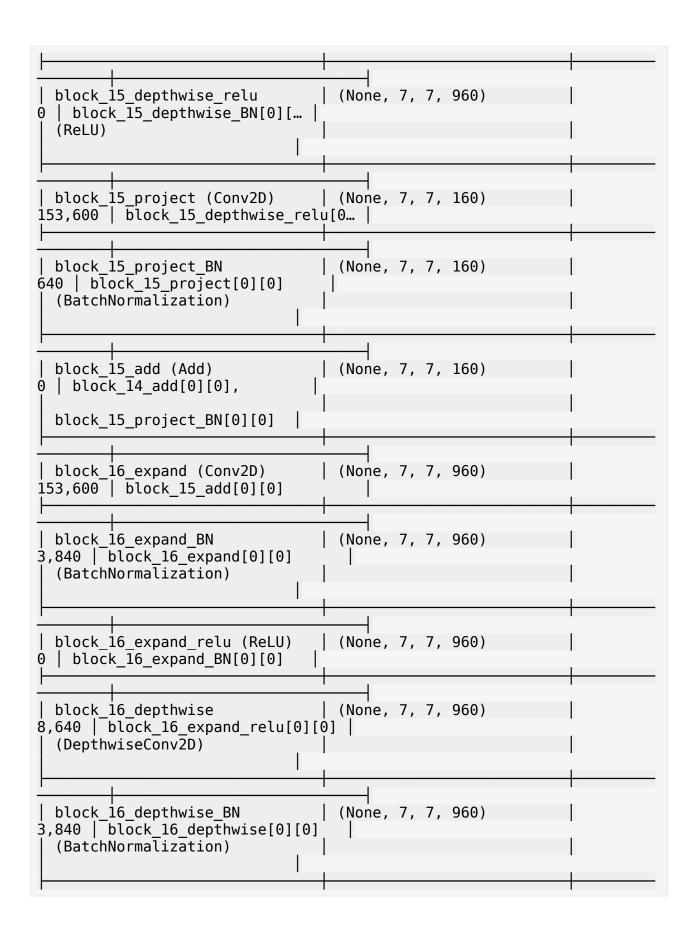


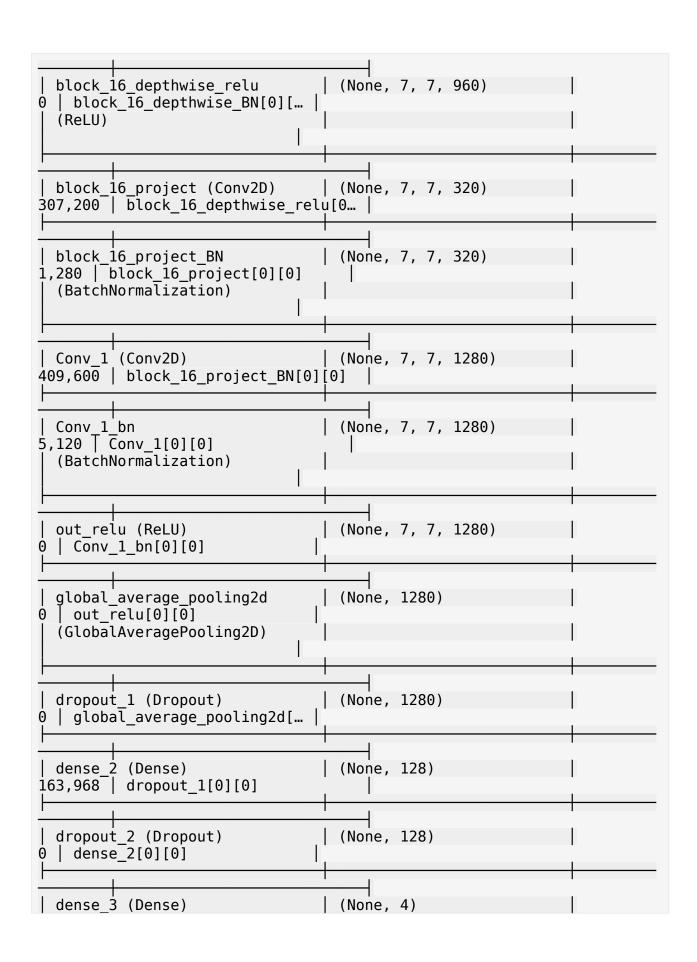












```
516 | dropout_2[0][0]

Total params: 2,422,468 (9.24 MB)

Trainable params: 2,019,588 (7.70 MB)

Non-trainable params: 402,880 (1.54 MB)
```

Model 2 memiliki parameter kurang dari 10M, yaitu sebanyak 2,422,468 parameters, dengan trainable parameters sebanyak 2,019,588 parameters.

```
history model2 = model2.fit(train ds,
                          validation_data=val_ds,
                          epochs=50,
                          callbacks=[early stop],
                          class weight=class weight dict)
Epoch 1/50
                  ———— 101s 2s/step - accuracy: 0.4319 - loss:
39/39 —
1.3842 - val_accuracy: 0.7355 - val_loss: 0.6650
Epoch 2/50
                ______ 56s 1s/step - accuracy: 0.6588 - loss:
39/39 —
0.7380 - val accuracy: 0.7645 - val loss: 0.5461
Epoch 3/50
                ______ 56s 1s/step - accuracy: 0.7628 - loss:
39/39 ——
0.5676 - val_accuracy: 0.7806 - val_loss: 0.5580
Epoch 4/50
                 ------ 57s 1s/step - accuracy: 0.7866 - loss:
39/39 ——
0.5068 - val accuracy: 0.8097 - val loss: 0.5090
Epoch 5/50
                    —— 56s 1s/step - accuracy: 0.8196 - loss:
39/39 —
0.4267 - val accuracy: 0.8097 - val loss: 0.5443
Epoch 6/50
                     55s 1s/step - accuracy: 0.8166 - loss:
0.3878 - val accuracy: 0.7871 - val loss: 0.6200
Epoch 7/50
                     --- 56s 1s/step - accuracy: 0.8677 - loss:
39/39 —
0.3076 - val_accuracy: 0.7968 - val_loss: 0.6183
Epoch 8/50
                  _____ 55s 1s/step - accuracy: 0.8911 - loss:
39/39 -
0.3105 - val accuracy: 0.7871 - val loss: 0.6096
Epoch 9/50
0.2541 - val accuracy: 0.7742 - val loss: 0.7455
```

Berdasarkan hasil evaluation, dapat diketahui bahwa model 2 adalah model yang lebih optimal dibandingkan model 1.

Oleh karena itu, dilakukan hyperparameter tuning untuk mengetahui best learning rate pada model ini.

```
def design tuning model2(input shape=(224, 224, 3), num classes=4):
    base model = MobileNetV2(include top=False, weights='imagenet',
input shape=input shape)
    base model.trainable = True
    for layer in base model.layers[:-50]:
        layer.trainable = False
    x = base model.output
    x = GlobalAveragePooling2D()(x)
    x = Dropout(0.3)(x)
    x = Dense(128, activation='relu')(x)
    x = Dropout(0.3)(x)
    predictions = Dense(num classes, activation='softmax')(x)
    model = Model(inputs=base model.input, outputs=predictions)
    return model
highest accuracy= 0
best learningrate = None
for lr in [0.001, 0.0001, 0.00001]:
    print(f"Learning rate = {lr}")
    tuning_model2 = design_tuning_model2()
    tuning model2.compile(
        optimizer=keras.optimizers.Adam(learning rate = lr),
        loss='categorical_crossentropy',
        metrics=['accuracy'])
    history tuning model2 = tuning model2.fit(train ds,
                                              validation data =
val ds,
                                              epochs = 50,
                                              callbacks=[early stop],
class weight=class weight dict)
    val accuracy = max(history tuning model2.history['val accuracy'])
    if val_accuracy > highest_accuracy:
        highest accuracy = val accuracy
        best learningrate = lr
        best model = tuning model2
print(f"Learning rate with the highest accuracy is:
{best learningrate}")
Learning rate = 0.001
Epoch 1/50
```

```
39/39 ————— 99s 2s/step - accuracy: 0.6042 - loss:
1.0110 - val accuracy: 0.7258 - val loss: 1.1253
Epoch 2/50
             ______ 56s 1s/step - accuracy: 0.7799 - loss:
39/39 ———
0.5544 - val accuracy: 0.6677 - val loss: 1.3379
Epoch 3/50 _____ 55s 1s/step - accuracy: 0.8469 - loss:
0.4668 - val accuracy: 0.5097 - val_loss: 2.5695
0.6623 - val accuracy: 0.4065 - val loss: 3.8080
0.4592 - val accuracy: 0.5516 - val loss: 3.1095
Epoch 6/50 ______ 56s 1s/step - accuracy: 0.8496 - loss:
0.3810 - val accuracy: 0.4484 - val loss: 5.1572
Learning rate = 0.0001
1.3370 - val accuracy: 0.7323 - val loss: 0.7277
0.7077 - val accuracy: 0.7484 - val loss: 0.6960
0.5997 - val accuracy: 0.7516 - val_loss: 0.7766
Epoch 4/50
            ______ 56s ls/step - accuracy: 0.7921 - loss:
39/39 ———
0.4929 - val_accuracy: 0.7613 - val_loss: 0.8251
Epoch 5/50
            ______ 56s 1s/step - accuracy: 0.8198 - loss:
39/39 ——
0.4144 - val_accuracy: 0.7742 - val_loss: 0.7438
Epoch 6/50

56s 1s/step - accuracy: 0.8307 - loss:
0.3967 - val accuracy: 0.7742 - val loss: 0.6996
0.3785 - val accuracy: 0.7968 - val loss: 0.6358
0.2888 - val accuracy: 0.7871 - val loss: 0.6454
Epoch 9/50 ______ 56s 1s/step - accuracy: 0.8752 - loss:
0.2667 - val accuracy: 0.7839 - val loss: 0.7424
Epoch 10/50
39/39 ______ 56s ls/step - accuracy: 0.9003 - loss:
0.2312 - val accuracy: 0.8065 - val loss: 0.5996
Epoch 11/50
```

```
______ 55s 1s/step - accuracy: 0.9041 - loss:
0.2265 - val accuracy: 0.7968 - val loss: 0.7261
Epoch 12/50
               ———— 56s 1s/step - accuracy: 0.9229 - loss:
39/39 ---
0.1901 - val accuracy: 0.7935 - val loss: 0.6586
Epoch 13/50 ______ 57s 1s/step - accuracy: 0.9373 - loss:
0.1777 - val accuracy: 0.8129 - val loss: 0.6230
Epoch 14/50 57s 1s/step - accuracy: 0.9470 - loss:
0.1416 - val accuracy: 0.7774 - val loss: 0.7706
Epoch 15/50 ______ 56s 1s/step - accuracy: 0.9437 - loss:
0.1796 - val accuracy: 0.7806 - val loss: 0.8516
Learning rate = 1e-05
1.6689 - val_accuracy: 0.1645 - val_loss: 1.6534
Epoch 2/50

55s 1s/step - accuracy: 0.2547 - loss:
1.6122 - val accuracy: 0.2968 - val loss: 1.4447
1.2940 - val accuracy: 0.4258 - val loss: 1.2893
1.2088 - val accuracy: 0.5290 - val_loss: 1.1773
Epoch 5/50
             ______ 56s 1s/step - accuracy: 0.3885 - loss:
39/39 ———
1.1988 - val_accuracy: 0.5613 - val_loss: 1.0898
Epoch 6/50
              ______ 56s 1s/step - accuracy: 0.4621 - loss:
39/39 ----
1.0809 - val_accuracy: 0.6032 - val_loss: 1.0075
Epoch 7/50

56s 1s/step - accuracy: 0.4718 - loss:
1.0705 - val accuracy: 0.6484 - val loss: 0.9360
1.0121 - val accuracy: 0.6774 - val loss: 0.8877
0.8696 - val accuracy: 0.7065 - val loss: 0.8386
Epoch 10/50 ______ 56s 1s/step - accuracy: 0.5476 - loss:
0.8698 - val accuracy: 0.7194 - val loss: 0.7963
Epoch 11/50
39/39 ______ 55s 1s/step - accuracy: 0.6170 - loss:
0.7850 - val accuracy: 0.7484 - val loss: 0.7567
Epoch 12/50
```

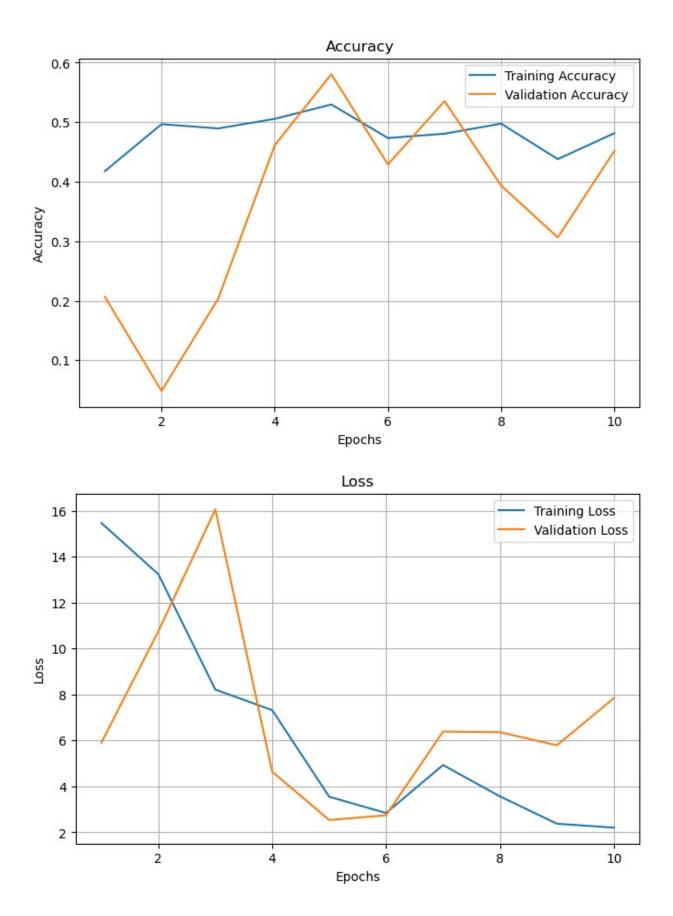
```
0.8119 - val accuracy: 0.7452 - val loss: 0.7301
Epoch 13/50
                ———— 56s 1s/step - accuracy: 0.5878 - loss:
39/39 —
0.7990 - val accuracy: 0.7581 - val loss: 0.7016
Epoch 14/50 ______ 56s 1s/step - accuracy: 0.6245 - loss:
0.7513 - val accuracy: 0.7645 - val loss: 0.6786
0.7583 - val accuracy: 0.7742 - val loss: 0.6607
0.7342 - val accuracy: 0.7806 - val loss: 0.6363
Epoch 17/50
              ______ 55s 1s/step - accuracy: 0.6878 - loss:
39/39 ———
0.6600 - val_accuracy: 0.7774 - val_loss: 0.6188
Epoch 18/50
                _____ 53s 1s/step - accuracy: 0.7022 - loss:
0.6880 - val accuracy: 0.7774 - val loss: 0.6090
Epoch 19/50
               37s 917ms/step - accuracy: 0.7266 - loss:
39/39 —
0.6227 - val accuracy: 0.7774 - val loss: 0.5970
Epoch 20/50 _____ 36s 894ms/step - accuracy: 0.7316 - loss:
0.6160 - val accuracy: 0.7806 - val loss: 0.5814
Epoch 21/50 39/39 37s 911ms/step - accuracy: 0.7387 - loss:
0.6012 - val accuracy: 0.7839 - val loss: 0.5703
0.5608 - val accuracy: 0.7871 - val loss: 0.5693
Epoch 23/50
              ______ 35s 876ms/step - accuracy: 0.7458 - loss:
39/39 ———
0.5933 - val accuracy: 0.7839 - val loss: 0.5650
Epoch 24/50
               41s 1s/step - accuracy: 0.7709 - loss:
0.5677 - val accuracy: 0.7903 - val loss: 0.5515
Epoch 25/50
30/30 — 36s 861ms/step - accuracy: 0.7718 - loss:
0.4890 - val accuracy: 0.7968 - val loss: 0.5335
Epoch 26/50
30/30 ————— 35s 846ms/step - accuracy: 0.7459 - loss:
0.5611 - val accuracy: 0.8065 - val loss: 0.5220
Epoch 27/50 40s 980ms/step - accuracy: 0.7962 - loss:
0.4936 - val accuracy: 0.8065 - val loss: 0.5211
Epoch 28/50
39/39 —
           36s 875ms/step - accuracy: 0.7701 - loss:
```

```
0.4907 - val accuracy: 0.8032 - val loss: 0.5156
Epoch 29/50
               _____ 37s 918ms/step - accuracy: 0.7716 - loss:
39/39 ———
0.5143 - val accuracy: 0.8032 - val loss: 0.5137
Epoch 30/50
                 37s 921ms/step - accuracy: 0.7745 - loss:
0.4818 - val accuracy: 0.8065 - val loss: 0.5122
Epoch 31/50
                  _____ 37s 917ms/step - accuracy: 0.7755 - loss:
39/39 ——
0.4757 - val accuracy: 0.8097 - val loss: 0.5005
Epoch 32/50 37s 921ms/step - accuracy: 0.8128 - loss:
0.4234 - val accuracy: 0.8097 - val loss: 0.4883
Epoch 33/50 41s 915ms/step - accuracy: 0.8163 - loss:
0.4140 - val accuracy: 0.8161 - val loss: 0.4844
Epoch 34/50
39/39 ————— 37s 920ms/step - accuracy: 0.8038 - loss:
0.4305 - val accuracy: 0.8194 - val_loss: 0.4821
Epoch 35/50
39/39 ______ 37s 915ms/step - accuracy: 0.8187 - loss:
0.4351 - val accuracy: 0.8161 - val loss: 0.4802
Epoch 36/50
                  _____ 37s 909ms/step - accuracy: 0.8311 - loss:
0.3659 - val accuracy: 0.8161 - val loss: 0.4752
Epoch 37/50
                 41s 904ms/step - accuracy: 0.8249 - loss:
39/39 —
0.4330 - val accuracy: 0.8129 - val loss: 0.4770
Epoch 38/50 ______ 37s 907ms/step - accuracy: 0.8352 - loss:
0.3823 - val accuracy: 0.8129 - val loss: 0.4760
Epoch 39/50 ______ 37s 913ms/step - accuracy: 0.8065 - loss:
0.4121 - val accuracy: 0.8194 - val loss: 0.4691
Epoch 40/50 39/39 38s 919ms/step - accuracy: 0.8181 - loss:
0.4090 - val accuracy: 0.8194 - val loss: 0.4614
Epoch 41/50
39/39 —————— 38s 930ms/step - accuracy: 0.8098 - loss:
0.4078 - val accuracy: 0.8226 - val loss: 0.4665
Epoch 42/50
                  _____ 38s 922ms/step - accuracy: 0.8324 - loss:
39/39 ———
0.3604 - val_accuracy: 0.8258 - val_loss: 0.4665
Epoch 43/50
                 _____ 36s 886ms/step - accuracy: 0.8327 - loss:
0.4014 - val_accuracy: 0.8226 - val_loss: 0.4675
Epoch 44/50
30/30 — 36s 892ms/step - accuracy: 0.8319 - loss:
0.3758 - val accuracy: 0.8226 - val loss: 0.4679
```

Evaluation

Berdasarkan hasil plot accuracy dan loss

```
def plot history(history, model name):
    acc = history.history['accuracy']
    val_acc = history.history.get('val_accuracy')
    loss = history.history['loss']
    val loss = history.history.get('val loss')
    epochs = range(1, len(acc) + 1)
    plt.figure(figsize=(8, 5))
    plt.plot(epochs, acc, label='Training Accuracy')
    if val acc:
        plt.plot(epochs, val acc, label='Validation Accuracy')
    plt.title(f'Accuracy')
    plt.xlabel('Epochs')
    plt.vlabel('Accuracy')
    plt.legend()
    plt.grid(True)
    plt.show()
    plt.figure(figsize=(8, 5))
    plt.plot(epochs, loss, label='Training Loss')
    if val loss:
        plt.plot(epochs, val loss, label='Validation Loss')
    plt.title(f'Loss')
    plt.xlabel('Epochs')
    plt.ylabel('Loss')
    plt.legend()
    plt.grid(True)
    plt.show()
plot_history(history_model1, model1)
```

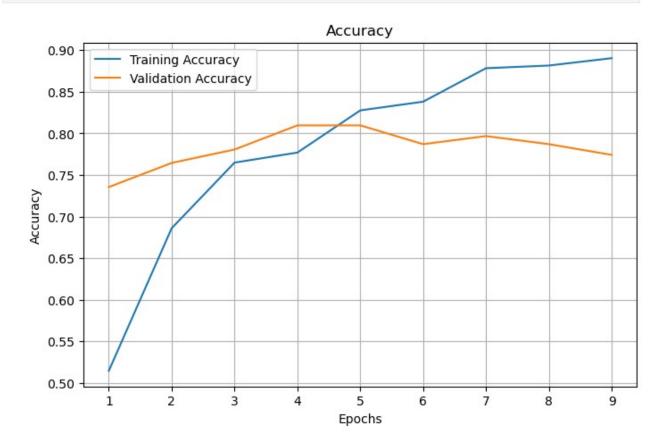


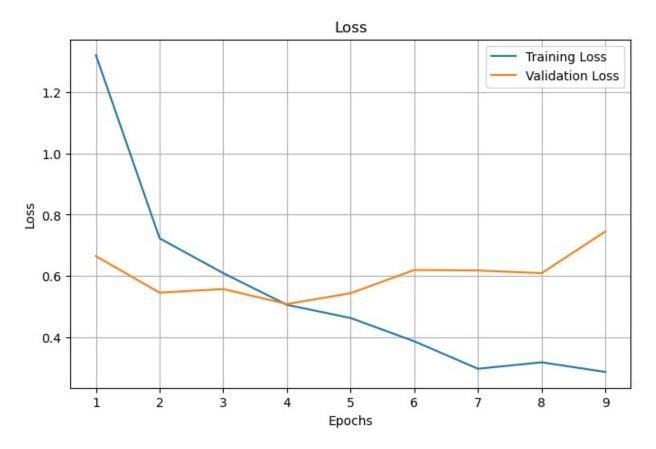
Berdasarkan grafik hasil training model 1, dapat dilihat bahwa:

- Training accuracy meningkat secara bertahap dari awal hingga mencapai sekitar 53% pada epoch ke-5, kemudian fluktuatif di kisaran 45–50% hingga akhir.
- Validation accuracy sempat mengalami peningkatan signifikan pada epoch ke-3 hingga ke-5, namun setelah itu cenderung menurun cukup drastis hingga sekitar 30% di epoch ke-9, lalu sedikit meningkat kembali pada epoch ke-10 (sekitar 45%).
- Training loss menurun konsisten dari awal hingga menjadi sekeitar 2.2 pada akhir epoch.
- Validation loss sangat fluktuatif: naik tajam di awal hingga ~16 (epoch ke-3), kemudian turun drastis hingga sekitar 2.5 pada epoch ke-5–6, tetapi kembali meningkat hingga 8 pada akhir epoch.

Secara keseluruhan, grafik ini menunjukkan bahwa model masih dalam proses belajar yang cukup baik, namun performanya masih tergolong moderate karena belum menunjukkan generalisasi yang sangat kuat.

plot_history(history_model2, model2)





Berdasarkan grafik hasil training model 2 (parameter < 10M), dapat dilihat bahwa:

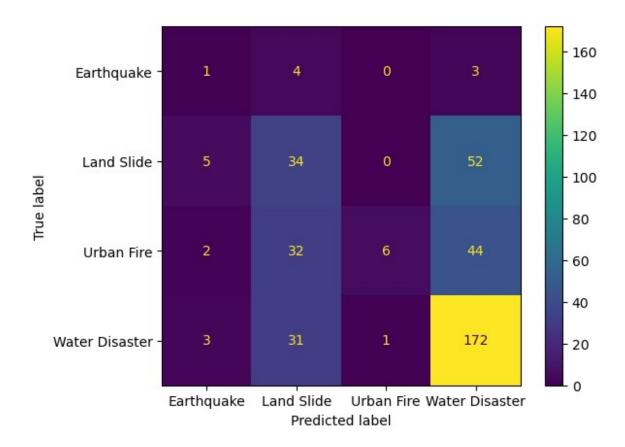
- Training accuracy meningkat secara stabil dan konsisten, dari sekitar 51% pada epoch pertama hingga 89% pada epoch ke-9.
- Validation accuracy mengalami peningkatan hingga epoch ke-5, kemudian cenderung stagnan bahkan sedikit menurun setelah epoch ke-6. Hal ini mengindikasikan bahwa meskipun model semakin baik pada data training, kemampuannya untuk menggeneralisasi ke data validasi mulai menurun.
- Training loss mengalami penurunan yang signifikan dan stabil, yang menandakan bahwa model terus memperbaiki prediksinya terhadap data yang sudah dikenal.
- Validation loss mengalami penurunan yang cenderung stagnan, bahkan sedikit meningkat setelah epoch ke-6, kemungkinan besar overfitting.

Melalui kedua grafik tersebut, dapat diketahui bahwa model ke-2 yang memanfaatkan arsitektur MobileNetV2 ini menunjukkan hasil yang lebih efisien dibandingkan model 1. Hal tesebut dikarenakan hasil accuracy training dan validation yang lebih tinggi dan stabil.

Berdasarkan hasil classification report dan correlation matrix

```
def evaluate(model, test_ds, label_names):
    y_true = []
    y_pred = []
```

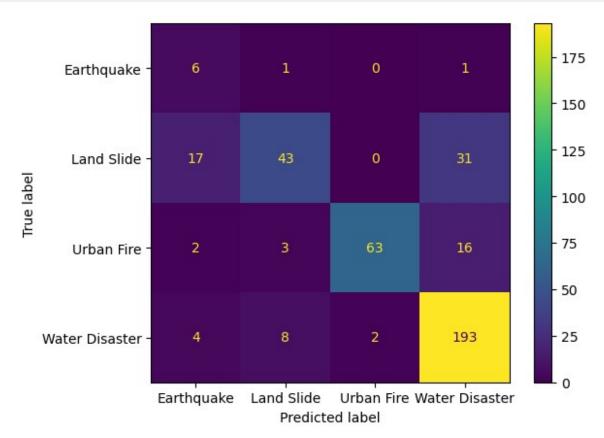
```
for x, y in test ds:
        pred = model.predict(x)
        y_pred.extend(np.argmax(pred, axis=1))
        y true.extend(np.argmax(y.numpy(), axis=1))
    print(classification_report(y_true, y_pred,
target names=label names)
    cm = confusion matrix(y true, y pred)
    ConfusionMatrixDisplay(cm, display labels=label names).plot()
evaluate(model1, test_ds, label_names)
1/1 -
                       1s 999ms/step
1/1 -
                        0s 370ms/step
1/1 -
                         0s 358ms/step
                         0s 370ms/step
1/1 -
1/1 -
                         0s 393ms/step
                        0s 395ms/step
1/1 -
1/1 -
                        - 0s 392ms/step
1/1 -
                        0s 422ms/step
1/1 -
                        - 0s 429ms/step
1/1 -
                        0s 372ms/step
1/1 -
                        - 0s 376ms/step
1/1 -
                        0s 373ms/step
1/1 -
                        0s 434ms/step
                precision recall f1-score
                                                 support
                                                       8
    Earthquake
                     0.09
                                0.12
                                          0.11
    Land Slide
                     0.34
                                0.37
                                          0.35
                                                       91
    Urban Fire
                     0.86
                                0.07
                                          0.13
                                                       84
Water Disaster
                     0.63
                                0.83
                                          0.72
                                                      207
                                          0.55
                                                      390
      accuracy
                                                      390
     macro avg
                     0.48
                                0.35
                                          0.33
 weighted avg
                     0.60
                                0.55
                                          0.50
                                                      390
```



Berdasarkan hasil correlation matrix model 1, dapat diketahui bahwa model 1 paling baik mengenali Water Disaster dengan prediksi benar terbanyak, sementara kelas Earthquake dan Urban Fire sulit dikenali karena banyak salah klasifikasi. Selain itu, terdapat kekeliruan yang cukup besar antara kelas Land Slide dan Water Disaster.

evaluate(model2) 1/1	3s 1s 2s	3s/step 580ms/st 571ms/st 540ms/st 579ms/st 557ms/st 557ms/st 578ms/st 548ms/st 533ms/st 552ms/st 2s/step	ep ep ep ep ep ep ep ep	aun no nt	
	precision	recali	f1-score	support	
Earthquake Land Slide Urban Fire	0.21 0.78 0.97	0.75 0.47 0.75	0.32 0.59 0.85	8 91 84	

Water Disaster	0.80	0.93	0.86	207	
accuracy macro avg weighted avg	0.69 0.82	0.73 0.78	0.78 0.66 0.78	390 390 390	



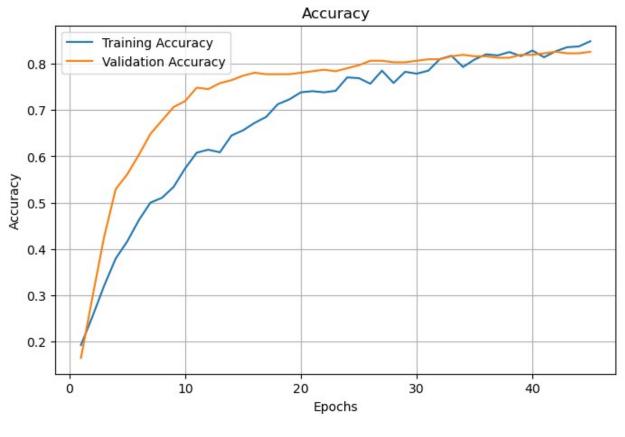
Jika dilihat berdasarkan classification report dan correlation matrix kedua model tersebut, dapat disimpulkan bahwa secara keseluruhan, model ke-2 adalah model yang lebih optimal dibandingkan model ke-1 untuk dataset ini. Model 2 lebih unggul dalam semua metric dan kemampuannya dalam mengklasifikasikan class minoritas seperti Earthquake dengan f1-score yang meningkat signifikan dibanding model pertama.

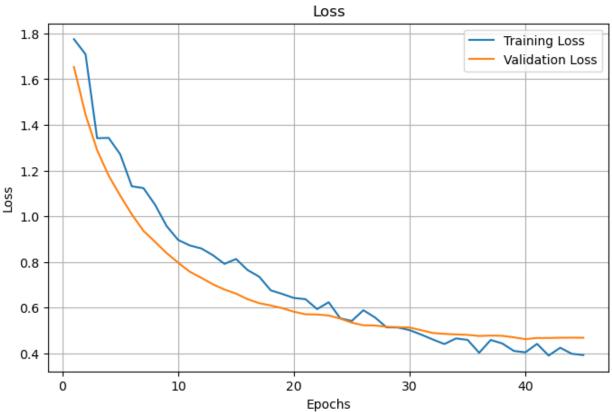
Best Model

BEST MODEL = MODEL 2

Evaluasi untuk best model yang telah di hyperparameter tuning

plot_history(history_tuning_model2, best_model)



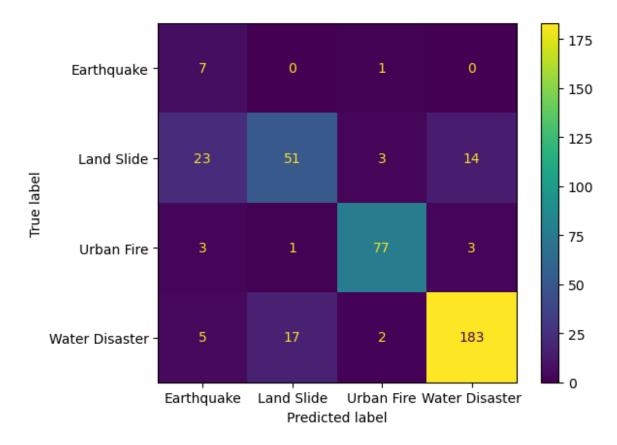


Berdasarkan grafik hasil training dari best model (model 2 dengan learning rate 0.00001), dapat dilihat bahwa:

- Training accuracy meningkat secara konsisten dari 20% hingga mencapai angka yang cukup tinggi sekitar 85% di akhir epoch.
- Validation accuracy naik cukup tajam pada awal training, kemudian cenderung stabil di kisaran 80%, yang berarti model mmapu menjaga performanya pada data validasi.
- Training loss menurun signifikan dari awal dan terus berkurang hingga berada di bawah 0.4, menunjukkan bahwa model terus memperbaiki prediksinya terhadap data training.
- Validation loss juga menunjukkan pola penurunan yang konsisten dan stabil hingga akhir epoch.

Grafik ini memperlihatkan bahwa model belajar secara efektif dan mampu melakukan generalisasi dengan baik terhadap data validasi. Performa stabil tanpa gejala overfitting serius, sehingga model ini lebih efisien dan lebih baik dibanding model 1.

evaluate(best_m	odel, test_d	s, label_	names)		
1/1	1s	3s/step 544ms/st 559ms/st 548ms/st 538ms/st 547ms/st 556ms/st 534ms/st 571ms/st 527ms/st 533ms/st 586ms/st 3s/step	ep ep ep ep ep ep ep		
1, 1	precision	•	f1-score	support	
Earthquake Land Slide Urban Fire Water Disaster	0.18 0.74 0.93 0.92	0.88 0.56 0.92 0.88	0.30 0.64 0.92 0.90	8 91 84 207	
accuracy macro avg weighted avg	0.69 0.86	0.81 0.82	0.82 0.69 0.83	390 390 390	



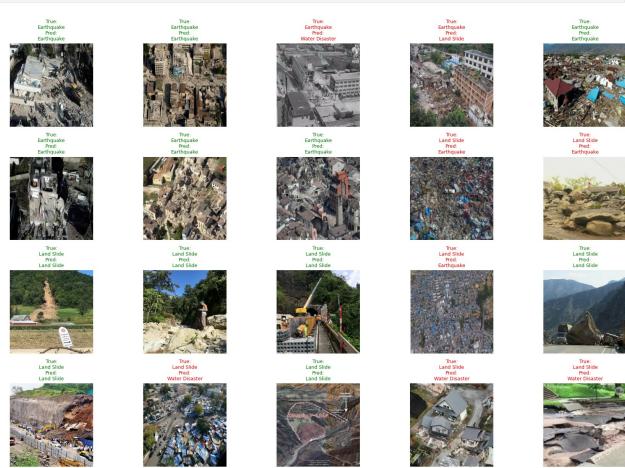
Best model (hasil hypertuning model 2) menunjukkan performa model yang sudah sangat baik dengan akurasi keseluruhan sebesar 82%. Model mampu mengenali kelas Urban Fire dan Water Disaster dengan sangat baik (f1-score di atas 0.9), sementara kelas Land Slide juga cukup solid dengan F1-score 0.64. Bahkan untuk kelas Earthquake, meski datanya lebih sedikit, recall mencapai 0.88 yang berarti model cukup handal dalam mendeteksi kejadian tersebut. Secara keseluruhan, hasil ini membuktikan bahwa hypertuning berhasil meningkatkan kualitas model.

Documentation

```
def predictions_of_the_best_model(model, dataset, num_images,
label_names):
    for images, labels in dataset.take(1):
        preds = model.predict(images)
        pred_labels = tf.argmax(preds, axis=1).numpy()
        true_labels = tf.argmax(labels, axis=1).numpy()

        num_to_show = min(num_images, images.shape[0])

    plt.figure(figsize=(18, num_to_show // 5 * 3))
    for i in range(num_to_show):
        ax = plt.subplot((num_to_show + 4) // 5, 5, i + 1)
        img = (images[i].numpy() * 255).astype("uint8")
        plt.imshow(img)
```



Distribusi data yang digunakan:

• Urban Fire: 419

• Water Disaster: 1035

• Land Slide: 456

• Earthquake: 36 -> unbalanced sehingga menggunakan class_weight dengan perbandingan:

Earthquake: 14.785714285714286, Urban Fire: 1.0315614617940199, Land Slide: 1.154275092936803, Water Disaster: 0.4769585253456221

Dimensi setiap gambar di resize menjadi 224 x 224

```
model1.evaluate(val ds)
model1.evaluate(test ds)
                     ---- 3s 246ms/step - accuracy: 0.5533 - loss:
10/10 -
2.6707
13/13 -
                      --- 3s 233ms/step - accuracy: 0.4056 - loss:
3.2489
[2.556565046310425, 0.5461538434028625]
best model.evaluate(val ds)
best model.evaluate(test ds)
                   _____ 5s 485ms/step - accuracy: 0.8106 - loss:
10/10 -
0.4907
13/13 -
                       --- 6s 452ms/step - accuracy: 0.7407 - loss:
0.7133
[0.5448195338249207, 0.8153846263885498]
```

Model 2 yang menggunakan arsitektur MobileNetV2 (dengan learning rate 0.0001) terbukti lebih unggul dibandingkan model 1. Hal tersebut dikarenakanmodel 2 memanfaatkan arsitektur MobileNetV2 yang memang dirancang untuk efisiensi komputasi, sehingga sangat cocok digunakan dalam proyek klasifikasi gambar seperti ini yang membutuhkan performa tinggi namun tetap ringan dari sisi resource. Dengan memanfaatkan transfer learning dari MobileNetV2, proses training menjadi lebih cepat dan hasilnya juga lebih akurat.

Selain itu, dari hasil training, model 2 menunjukkan akurasi validasi yang lebih tinggi dan lebih stabil dibandingkan model 1, yang menunjukkan bahwa model tidak hanya belajar dengan baik dari data training, tetapi juga mampu melakukan generalisasi dengan lebih baik terhadap data yang belum pernah dilihat sebelumnya. Sedangkan model 1 merupakan arsitektur CNN yang dibangun from scratch, dengan struktur yang relatif sederhana, sehingga model ini kurang mampu menangkap pola fitur yang kompleks dan cenderung menghasilkan model yang bias terhadap data training (contohnya biased pada Water_Disaster).