# MINISTERUL EDUCAȚIEI REPUBLICII MOLDOVA

# UNIVERSITATEA TEHNICĂ A MOLDOVEI

Facultatea "Calculatoare, Informatică și Microelectronică"

FILIERA ANGLOFONĂ

# **RAPORT**

**Operational Systems** 

# Creating an operational system and functions to it

### A efectuat:

st. gr. FAF-141 (l. engleză)

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A verificat:

lector. sup.

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**Task**: Create an operational system with a bootloader which loads a kernel with several functions bellow:

- 1. Calculator
- 2. Draw Moldova's flag
- 3. String inversor
- 4. Clr screen
- 5. ASCII printer
- 6. String verification for palindrom
- 7. String inversor
- 8. HELP
- 9. Exit

### Work flow:

### What is a Bootloader?

A bootloader is a special program that is executed each time a bootable device is initialized by the computer during its power on or reset that will load the kernel image into the memory. This application is very close to hardware and to the architecture of the CPU. All x86 PCs boot in Real Mode. In this mode you have only 16-bit instructions. Our bootloader runs in Real Mode and our bootloader is a 16-bit program.

### How this works?

When you switch on the PC the BIOS want to boot up an OS which must be found somewhere in hard disks, floppy disk, CDs, etc. The order in which BIOS searches an OS is user configurable. Next the BIOS reads the first 512 byte sector of the bootable disk. Usually a sector is 512 bytes in size. This is known as the Master Boot Record (MBR). BIOS simply loads the contents of the MBR into memory location "0x7c00" and jumps to that location to start executing whatever code is in the MBR. Our bootloader should be 512 bytes in size as well.

In computing, the kernel is a computer program that manages input/output requests from software, and translates them into data processing instructions for the central processing unit and other electronic components of a computer. The kernel is a fundamental part of a modern computer's operating system.

### The boot process is:

- Turn on your PC and BIOS executes
- The BIOS seeks the MBR in boot order which is user configurable.
- The BIOS loads a 512 byte boot sector into memory location "0x7c00" from the specified media and begins executing it.
- Those 512 bytes then go on to load the OS itself or a more complex bootloader.

### **BIOS Interrupts**

These interrupts help OS and application invoke the facilities of the BIOS. This is loaded before the bootloader and it is very helpful in communicating with the I/O. Since we don't have OS level interrupts this is the only option that would be helpful.

For example to print a character to the screen using BIOS interrupt calls.

```
mov ah, 0x0e ; function number = 0Eh : Display Character mov al, 'O' ; AL = code of character to display int 0x10 ; call INT 10h, BIOS video service
```

This is a simple boot loader written in AT&T syntax.

```
.code16
    .section .text
    .global main
main:
    Disk description table, to make it a valid floppy
    FAT12 file system format
    jmp _start
                     #NOP
    .byte 144
                        #OEMLabel
    .ascii "OsandaOS"
    .word 512
                     #BytesPerSector
                    #SectorsPerCluster
    .byte 1
                    #ReservedForBoot
    .word 1
                    #NumberOfFats
    .byte 2
                     #RootDirEntries (224 * 32 = 7168 = 14 sectors to read)
    .word 224
                      #LogicalSectors
    .word 2880
                     #MediumByte
    .byte 0xf0
                    #SectorsPerFat
    .word 9
    .word 18
                     #SectorsPerTrack
    .word 2
                    #Sides
                    #HiddenSectors
    .long 0
                    #LargeSectors
    .byte 0
                    #DriveNo
    .byte 0
                     #Signature (41 for Floppy)
    .byte 0x29
                         #VolumeID
    .long 0x12345678
    .ascii "My First OS"
                        #VolumeLabel
    .ascii "FAT12 "
                       #FileSystem
_start:
    movw $0, % ax
    movw %ax, %ss
    movw %ax, %ds
    movw %ax, %es
    movw $string, %si
loop:
    movb $0xe, %ah
    movb (%si), %al
```

```
cmpb $0, %al
    je done
    int $0x10
    addw $1, %si
    jmp loop

done:
    jmp done #infinite loop

string:
    .ascii "Welcome to my First OS :)"
    .byte 0
    .fill 0x1fe - (. - main) ,1,0 #Pad remainder of boot sector with 0s
    .word 0xaa55 #The standard PC boot signature
```

Assemble the file using binary as the format.

nasm -f bin -o myfirst.bin myfirst.nasm

If you use the file utility you will see that it's a legit 1.4MB floppy Disk and a 32-bit boot sector.

After that convert the binary file to floppy image.

dd status=noxfer conv=notrunc if= lmyfirst.bin of=fmyfirst.flp

You can also convert the binary file to an ISO using tools such as UltraISO, etc. You may burn and try in your PC instead of emulating.

Use Qemu to test our newly created bootloader

qemu-system-i386 -fda myfirst.flp

```
QEMU — + X

SeaBIOS (version 1.7.4-20150827_223240-lgw01-56)

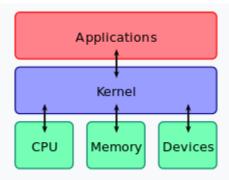
iPXE (http://ipxe.org) 00:03.0 C900 PCI2.10 PnP PMM+07FC10F0+07F210F0 C900

Booting from Hard Disk...
Boot failed: could not read the boot disk

Booting from Floppy...
This is my cool new OS!_
```

# Kernel

The **kernel** (also called **nucleus**) is a computer program that constitutes the central core of a computer's operating system. It has complete control over everything that occurs in the system. As such, it is the first program loaded on startup, and then manages the remainder of the startup, as well as input/output requests from software, translating them into data processing instructions for the central processing unit. It is also responsible for managing memory, and for managing and communicating with computing peripherals, like printers, speakers, etc. The kernel is a fundamental part of a modern computer's operating system.



A kernel connects the application software to the hardware of a computer.

The critical code of the kernel is usually loaded into a *protected area* of memory, which prevents it from being overwritten by other, less frequently used parts of the operating system or by applications. The kernel performs its tasks, such as executing processes and handling interrupts, in *kernel space*, whereas everything a user normally does, such as writing text in a text editor or running programs in a GUI (graphical user interface), is done in *user space*. This separation prevents user data and kernel data from interfering with each other and thereby diminishing performance or causing the system to become unstable (and possibly crashing).<sup>[1]</sup>

When a *process* makes requests of the kernel, the request is called a system call. Various kernel designs differ in how they manage system calls and resources. For example, a monolithic kernel executes all the operating system instructions in the same address space in order to improve the performance<sup>[]</sup> of the system. A microkernel runs most of the operating system's background processes in user space,<sup>[3]</sup> allowing a more modular design of the kernel which makes it easier to maintain.<sup>[4]</sup>

The kernel's interface is a low-level abstraction layer.

Bootloader is loaded, and I can go to kernel.

Now I can use my functions through Qemu Terminal:

```
QEMU
Booting from Floppy...
Boot failed: not a bootable disk
Booting from DVD/CD...
Boot failed: Could not read from CDROM (code 0003)
Booting from ROM...
iPXE (PCI 00:03.0) starting execution...ok
iPXE initialising devices...ok
iPXE 1.0.0+git-20131111.c3d1e78-2ubuntu1.1 -- Open Source Network Boot Firmware
  http://ipxe.org
Features: HTTP HTTPS iSCSI DNS TFTP AOE bzImage ELF MBOOT PXE PXEXT Menu
net0: 52:54:00:12:34:56 using 82540em on PCI00:03.0 (open)
[Link:up, TX:0 TXE:0 RX:0 RXE:0]
Configuring (net0 52:54:00:12:34:56)..... ok
net0: 10.0.2.15/255.255.255.0 gw 10.0.2.2
Nothing to boot: No such file or directory (http://ipxe.org/2d03e13b)
No more network devices
No bootable device.
```

```
QEMU - + X

SeaBIOS (version 1.7.4-20150827_223240-lgw01-56)

iPXE (http://ipxe.org) 00:03.0 C900 PCI2.10 PnP PMM+07FC10F0+07F210F0 C900

Booting from Hard Disk...
Boot failed: could not read the boot disk

Booting from Floppy...
(Loading Kernel) : Press a key
-
```

```
QEMU - + ×

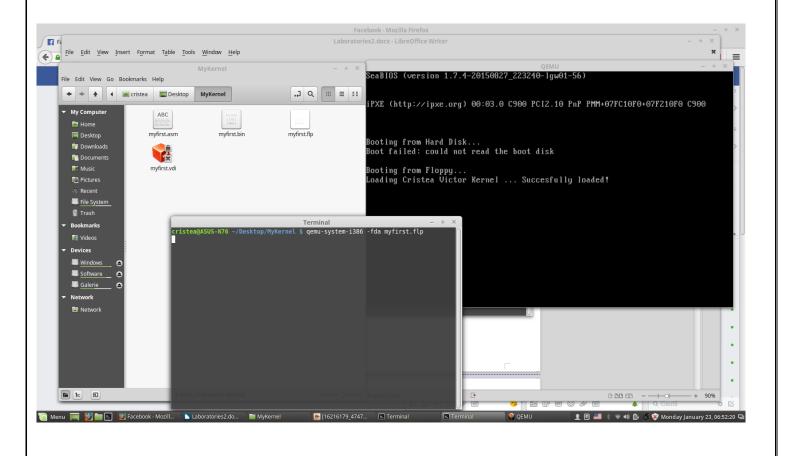
SeaBIOS (version 1.7.4-20150827_223240-lgw01-56)

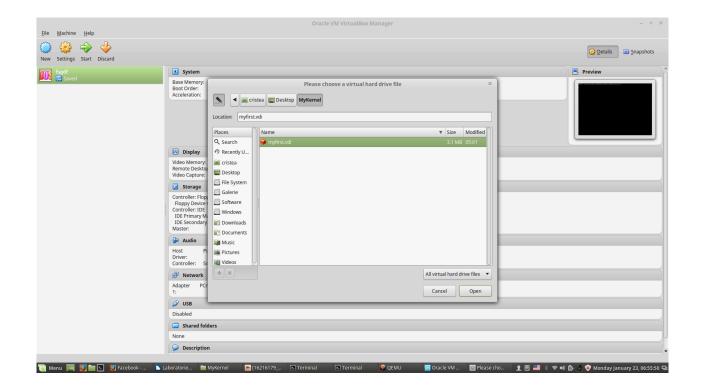
iPXE (http://ipxe.org) 00:03.0 C900 PCI2.10 PnP PMM+07FC10F0+07F210F0 C900

Booting from Hard Disk...
Boot failed: could not read the boot disk

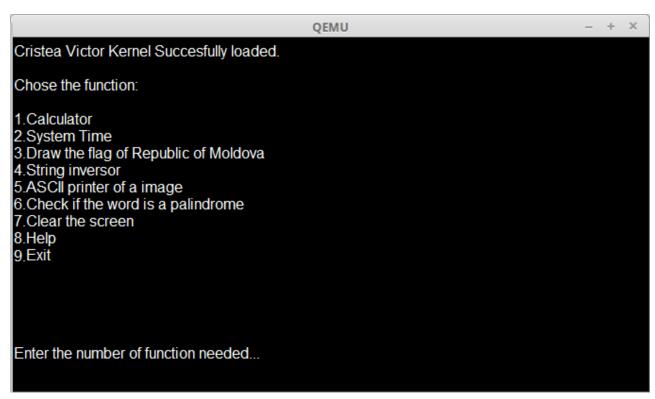
Booting from Floppy...
Loading Cristea Victor Kernel ... Succesfully loaded!
```

So here I have a Virtual disk image for launching through Virtualbox or Vmware and FLP for launching through QEMU.





# Were we have booted the system



```
Sequence of code for Main function which loads the screen above:
Main:
mov si, WaitInputMessage
call Writeline
xor ax, ax
int 16h; wait for keypress
; set destination segment
mov ax, 7E0h
mov es, ax
xor bx, bx
ReadFromFloppy:
 mov ah, 2; read sectors
 mov al, 3; number of sectors to read
 mov ch, 0; track number
 mov cl, 2; sector number (kernel is in the second sector)
 mov dh, 0; head number
 mov dl, 0; drive number
 int 13h; call BIOS
 jc ReadFromFloppy
                          ; Error, so try again
; check data integrity
mov al, byte [es:0h]
cmp al, 0B8h
je LoadKernel
; print error message and halt system
mov si, ErrorMessage
call Writeline
cli
h1
```

# **Appendix for Calculator**

```
Cristea Victor Kernel Succesfully loaded.

1. Calculator
Enter the first value: 15
Choose the operation: + , - , * , /
/
Enter the second value: 5
Result: 3

To return press "r" ...
```

```
.date
             operation1: .word 0
             operand1: .word 0
             operand2: .word 0
             operation2: .word 0
             operand3: .word 0
             priority: .word 0
             msg1: .asciiz
                             "\nEnter the first valuer: "
             msg3: .asciiz "Choose the operation:+,-,^*,/: "
             msg4: .asciiz "Enter the second value: "
             msg7: .asciiz "Result: "
             .text
             .globl main
       main:
                   #get 1st operation
                   li $v0, 4
                                         #system call for print str
                   la $a0,msg1
                                         #addr of string to print
                   syscall
                   li $v0, 5
                                          #read 1st operand
                   syscall
                   sw $v0, operand1
```

```
#get 1st operand
li $v0, 4
la $a0, msg2
syscall
li $v0, 5
                      #read 1st operation
syscall
sw $v0, operation1
#get 2nd operand
li $v0, 4
la $a0, msg3
syscall
li $v0, 5
syscall
sw $v0, operand2
#get 2nd operation
li $v0, 4
la $a0, msg4
syscall
li $v0, 5
syscall
sw $v0, operation2
#get 3rd operand
li $v0, 4
la $a0, msg5
syscall
li $v0, 5
syscall
sw $v0, operand3
#get operation priority
li $v0, 4
la $a0, msg6
syscall
li $v0, 5
syscall
sw $v0, priority
#put operations and operands into $t0-$t5
lw $t0, operation1
lw $t1, operand1
lw $t2, operand2
lw $t3, operation2
lw $t4, operand3
lw $t5, priority
```

#determine which priority to use

```
#default operation priority
           beq $t5, 0, default
            #1st operation priority
           beq $t5, 1, first
            #2nd operation priority
           beq $t5, 2, second
           li
                 $v0, 10
                                    # system call code for exit = 10
            syscall
default:
           beq $t0, 3, first
           beq $t0, 4, first
           beq $t3, 3, second
           beq $t3, 4, second
first:
            #perform operation1 on operand1 and operand2
            #set priority to 1 for default operations
           li $t5, 1
           move $a0, $t1
           move $a1, $t2
           beq $t0, 1, addit1
           beq $t0, 2, subtr1
           beg $t0, 3, multi1
           beq $t0, 4, divis1
first2:
            #perform operation2 on result and operand3
            #place operand in $a1
           move $a1, $t4
           beq $t3, 1, addit2
           beq $t3, 2, subtr2
           beq $t3, 3, multi2
           beq $t3, 4, divis2
            j Exit
second:
                  #perform operation2 on operan2 and operand3
            #set priority to 2 for default operations
            li $t5, 2
           move $a0, $t2
           move $a1, $t4
           beg $t3, 1, addit2
           beq $t3, 2, subtr2
           beq $t3, 3, multi2
           beq $t3, 4, divis2
second2:
            #perform operation 1 on operand1 and result
           move $a1, $a0 #puis result into $a1
```

```
move $a3, $a0  #saves result in case it's lost on 2nd
pass
           move $a0, $t1
           beg $t0, 1, addit1
           beg $t0, 2, subtr1
           beq $t0, 3, multi1
           beg $t0, 4, divis1
           move $a0, $a3 #retains result
            j Exit
addit1:
            #place the operands in $a0 and $a1
            #reset operation
            li $t0, 0
            jal addition
addit2:
            #place the operands in $a0 and $a1
            #reset operation
            li $t3, 0
            jal addition
subtr1:
                  #place the operands in $a0 and $a1
            #reset operation
            li $t0, 0
            jal subtraction
subtr2:
                  #place the operands in $a0 and $a1
            #reset operation
            li $t3, 0
            jal subtraction
multi1:
                  #place the operands in $a0 and $a1
            #reset operation
            li $t0, 0
            jal multiplication
multi2:
            #place the operands in $a0 and $a1
            #reset operation
            li $t3, 0
            jal multiplication
divis1:
                  #place the operands in $a0 and $a1
            #reset operation
```

<del>li \$10, 0</del>

```
jal division
divis2:
           #place the operands in $a0 and $a1
            #reset operation
            li $t3, 0
            jal division
addition:
            #take the operands perform addition
            add $a0, $a0, $a1
           beq $t5, 1, Jumpfirst
           beg $t5, 2, Jumpsecond
subtraction:
                 #take the operands perform subtraction
            sub $a0, $a0, $a1
           beq $t5, 1, Jumpfirst
           beq $t5, 2, Jumpsecond
multiplication: #take the operands perform multiplication
           mult $a0, $a1
           mflo $a0
           beq $t5, 1, Jumpfirst
           beg $t5, 2, Jumpsecond
division: #take the operands perform division
           div $a0, $a0, $a1
           beq $t5, 1, Jumpfirst
           beq $t5, 2, Jumpsecond
Jumpfirst:
            j first2
Jumpsecond:
            j second2
Exit:
                  ##prints result
           move $v1, $a0
            li $v0, 4
            la $a0, msg7
            syscall
            li $v0, 1
            move $a0, $v1
            syscall
            #jumps back to main
```

j main

### **Appendix for System Time**



```
.MODEL SMALL
.STACK 100H
.DATA
 PROMPT DB 'Current System Time is : $'
  TIME DB '00:00:00$' ; time format hr:min:sec
.CODE
  MAIN PROC
   MOV AX, @DATA
                            ; initialize DS
   MOV DS, AX
   LEA BX, TIME
                          ; BX=offset address of string TIME
    CALL GET_TIME
                  ; call the procedure GET_TIME
    LEA DX, PROMPT
                            ; DX=offset address of string PROMPT
    MOV AH, 09H
                             ; print the string PROMPT
    INT 21H
    LEA DX, TIME
                             ; DX=offset address of string TIME
    MOV AH, 09H
                             ; print the string TIME
    INT 21H
    MOV AH, 4CH
                             ; return control to DOS
    INT 21H
```

```
MAIN ENDP
```

END MAIN

```
;----- GET TIME -----
  GET TIME PROC
   ; this procedure will get the current system time
   ; input : BX=offset address of the string TIME
   ; output : BX=current time
                            ; PUSH AX onto the STACK
   PUSH AX
   PUSH CX
                             ; PUSH CX onto the STACK
   MOV AH, 2CH
                           ; get the current system time
   INT 21H
   MOV AL, CH
                           ; set AL=CH , CH=hours
   CALL CONVERT
                           ; call the procedure CONVERT
   MOV [BX], AX
                           ; set [BX]=hr , [BX] is pointing to hr
                            ; in the string TIME
   MOV AL, CL
                            ; set AL=CL , CL=minutes
                          ; call the procedure CONVERT
   CALL CONVERT
   MOV [BX+3], AX
                            ; set [BX+3]=min , [BX] is pointing to
min
                            ; in the string TIME
                           ; set AL=DH , DH=seconds
   MOV AL, DH
   CALL CONVERT
                            ; call the procedure CONVERT
   MOV [BX+6], AX
                            ; set [BX+6]=min , [BX] is pointing to
sec
                            ; in the string TIME
   POP CX
                            ; POP a value from STACK into CX
                            ; POP a value from STACK into AX
   POP AX
   RET
                            ; return control to the calling procedure
  GET TIME ENDP
                            ; end of procedure GET_TIME
  ;----;
  CONVERT PROC
   ; this procedure will convert the given binary code into ASCII code
   ; input : AL=binary code
   ; output : AX=ASCII code
   PUSH DX
                           ; PUSH DX onto the STACK
   MOV AH, 0
                            ; set AH=0
   MOV DL, 10
                            ; set DL=10
   DIV DL
                           ; set AX=AX/DL
   OR AX, 3030H
                            ; convert the binary code in AX into ASCII
   POP DX
                            ; POP a value from STACK into DX
   RET
                           ; return control to the calling procedure
  CONVERT ENDP
                            ; end of procedure CONVERT
```

# **Appendix for Drawing**

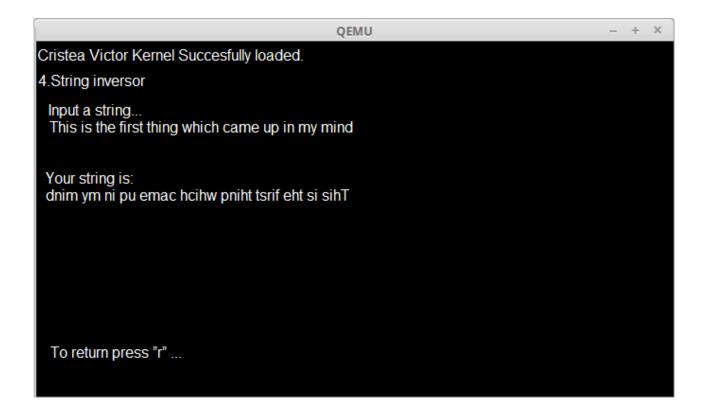


```
DrawImage:
   cmp word [ID], "BM"
   je DrawBMP
   ret
DrawBMP:
   cmp word [Depth], 24
   je DrawBMP24
   cmp word [Depth], 32
   je DrawBMP32
   ret
DrawBMP24:
   pushad
   mov [.X], eax
   mov [.Y], ebx
   mov [.x], eax
   mov [.y], ebx
   xor edx, edx
   mov [.align], edx
   mov ebx, 4
   mov eax, [Width]
   div ebx
   cmp edx, 0
   je .skip
mov dword [.align], 1
```

```
xor edx, edx
   mov eax, [Width]
   inc eax
   div ebx
   cmp edx, 0
   je .skip
   mov dword [.align], 2
   xor edx, edx
   mov eax, [Width]
   add eax, 2
   div ebx
   cmp edx, 0
   je .skip
   mov dword [.align], 3
.skip:
   mov esi, BMP
   add esi, [Offset]
   mov [.pointer], esi
   mov ebx, [Height]
   add [.y], ebx
.drawLine:
   mov esi, [.pointer]
   mov al, [esi]
   mov [.color], al
   mov al, [esi + 1]
   mov [.color + 1], al
   mov al, [esi + 2]
   mov [.color + 2], al
   add dword [.pointer], 3
   mov esi, .params
   call DrawPixel
   inc dword [.x]
   mov ebx, [Width]
   add ebx, [.X]
   cmp [.x], ebx
   jne .drawLine
   mov ebx, [.X]
   mov [.x], ebx
   dec dword [.y]
   mov ebx, [.pointer]
   add ebx, [.align]
   mov [.pointer], ebx
   mov ebx, [.Y]
   cmp [.y], ebx
   je .done
   jmp short .drawLine
.done:
```

```
popad
   ret
.X dd 0
.Y dd 0
.align dd 0
.pointer dd 0
.params:
   .color dd 0
    .x dd 0
    .y dd 0
DrawBMP32:
   pushad
   mov [.X], eax
   mov [.Y], ebx
   mov [.x], eax
   mov [.y], ebx
   mov esi, BMP
   add esi, [Offset]
   mov [.pointer], esi
   mov ebx, [Height]
   add [.y], ebx
.drawLine:
   mov esi, [.pointer]
   mov eax, [esi]
   mov [.color], eax
   add dword [.pointer], 4
   mov esi, .params
   call DrawPixel
   inc dword [.x]
   mov ebx, [Width]
   add ebx, [.X]
   cmp[.x], ebx
   jne .drawLine
   mov ebx, [.X]
   mov [.x], ebx
   dec dword [.y]
   mov ebx, [.Y]
   cmp [.y], ebx
    je .done
   jmp short .drawLine
.done:
   mov dword [.y], 0
   popad
   ret
.X dd 0
.Y dd 0
.pointer dd 0
.params:
    .color dd 0
    .x dd 0
```

# **Appendix for string inversor**



```
DATA SEGMENT
        STR1 DB "ENTER YOUR STRING HERE ->$"
        STR2 DB "YOUR STRING IS ->$"
        STR3 DB "REVERSE STRING IS ->$"
        INSTR1 DB 20 DUP("$")
        RSTR DB 20 DUP("$")
        NEWLINE DB 10,13,"$"
        N DB ?
        S DB ?
DATA ENDS
CODE SEGMENT
        ASSUME DS:DATA,CS:CODE
START:
        MOV AX, DATA
        MOV DS, AX
        LEA SI, INSTR1
;GET STRING
        MOV AH, 09H
        LEA DX, STR1
        INT 21H
        MOV AH, OAH
```

```
MOV DX,SI
        INT 21H
        MOV AH,09H
        LEA DX, NEWLINE
        INT 21H
; PRINT THE STRING
        MOV AH,09H
        LEA DX, STR2
        INT 21H
        MOV AH,09H
        LEA DX, INSTR1+2
        INT 21H
        MOV AH,09H
        LEA DX, NEWLINE
        INT 21H
; PRINT THE REVERSE OF THE STRING
        MOV AH,09H
        LEA DX, STR3
        INT 21H
        MOV CL, INSTR1+1
        ADD CL, 1
        ADD SI,2
     L1:
        INC SI
        CMP BYTE PTR[SI], "$"
        JNE L1
        DEC SI
        LEA DI, RSTR
     L2:MOV AL, BYTE PTR[SI]
        MOV BYTE PTR[DI], AL
        DEC SI
        INC DI
        LOOP L2
        MOV AH,09H
        LEA DX, NEWLINE
        INT 21H
        MOV AH,09H
        LEA DX, RSTR
        INT 21H
        MOV AH,09H
        LEA DX, NEWLINE
```

тмт 21ц

MOV AH, 4CH INT 21H CODE ENDS END START

# **Appendix for Palindrome**

```
Cristea Victor Kernel Successfully loaded.

6 Check if the word is a palindrome

Input the string: ...

I am not a palindrome

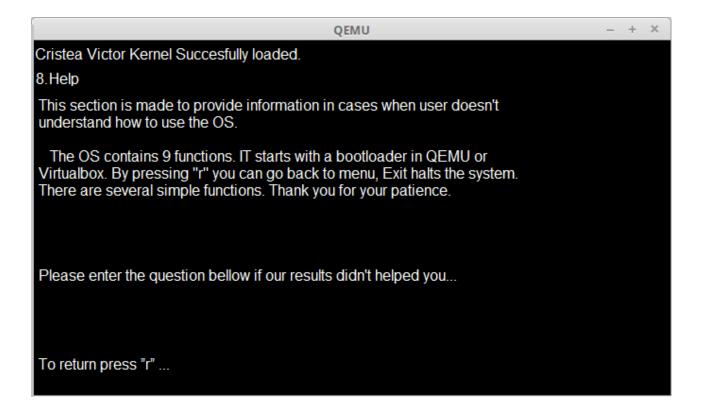
Inputed string is not a palindrom ,

To return press "r" ...
```

```
; this sample checks if string is a palindrome or not.
; palindrome is a text that can be read backwards
; and give the same meaning as if it was read forward.
; for example: "abba" is polindrome.
; note: this program is case sensitive, "abba" is not "abba".
name "pali"
org 100h
jmp start
m1:
s db 'able was ere ere saw elba'
s size = $ - m1
 db 0Dh,0Ah,'$'
start:
; first let's print it:
mov ah, 9
mov dx, offset s
int 21h
lea di, s
mov si, di
```

```
add si, s_size
dec si ; point to last char!
mov cx, s_size
cmp cx, 1
je is_palindrome ; single char is always palindrome!
shr cx, 1 ; divide by 2!
next char:
   mov al, [di]
   mov bl, [si]
   cmp al, bl
   jne not_palindrome
   inc di
   dec si
loop next_char
is palindrome:
  ; the string is "palindrome!"
  mov ah, 9
  mov dx, offset msg1
  int 21h
jmp stop
not palindrome:
  ; the string is "not palindrome!"
  mov ah, 9
  mov dx, offset msg2
  int 21h
stop:
; wait for any key press:
mov ah, 0
int 16h
ret
msg1 db " this is palindrome!$"
msg2 db " this is not a palindrome!$"
```

### **Function HELP**



**Conclusion**: In this laboratory works I have understood how to create an operating system, elaborating a menu for control through command Help. Writing code in assembly, then compiling with nasm, then converting and finally start on a virtual machine QEMU.It was difficult to start with but after couple of hours of reading it was real to obtain a result.

### **REFFERENCES**

https://osandamalith.com/2015/10/26/writing-a-bootloader/http://mikeos.sourceforge.net/write-your-own-os.html