

Cristian Baruch Gonzalez 孔克荀

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Technical Strengths

Computer Languages	C++, PSpice, MatLab/Scilab, Verilog, Java, LabVIEW, HTML, R, CUDA
Environment	Visual Studio, Matlab, LabVIEW, Android SDK, PSpice, Xilinx ISE, R
Spoken Languages	English (Native), Japanese (Inter), Mandarin (Elem), Spanish (Fluent)
Office Productivity	L ^A T _E X, Adobe Photoshop, Adobe Illustrator

Education

California State University, San Bernardino
B.S. in Computer Engineering
Minor in Japanese

December 2014

Experience

Computer Science and Engineering Club Quadrotor Project	September 2013 — Present
<i>Team Lead</i>	<i>San Bernardino, CA</i>

- Quadrotor is assembled with a Raspberry Pi as the micro controller.
- PID evaluated using Matlab, face detection evaluation using Matlab.
- Currently implementing PID controller with Python, Face detection with OpenCV.

Multimedia Processing Lab	December 2009 - October 2010
<i>Research Intern</i>	<i>Dankook University, Yongin City, South Korea</i>

- Researched into Computer Vision involving Tensor Voting to recognize facial expression.
- Website for the lab and current projects: http://mip.dankook.ac.kr/index.php?mid=welcome_page

NASA Dryden Flight Research Center	June 2013 — August 2013
<i>Student Intern</i>	<i>Edwards, CA</i>

- Tested a quadrotor by doing Hardware in the loop using APM, Mission Planner and X-Plane 10.
- Used a PID controller to help stabilize a quadrotor during flight and determine faults in quadrotor.
- Currently part of the Automatic Collision Avoidance Technology (ACAT) project at NASA Armstrong.

Autonomous Navigation with a Quadrotor Aircraft	September 2011 — February 2012
<i>Exchange Student</i>	<i>National Taiwan University, Taipei, Taiwan</i>

- Developed shape detection, object depth calculations and dynamic navigation planning.
- Developed an autonomous UAV for path finding and tracking in 3D space for it to go through rings.

Garner Holt Production	April 2011 — August 2011, September 2013 — June 2014
<i>Student Intern</i>	<i>San Bernardino, CA</i>

- Developed robotics control system with a team of students.
- Developed human tracking software based on human recognition.
- Project known as Project Yeti and still under research and development.