



**TSCINBUNY**

## **ESP32 CAM McKnum Wheel ROBOT V1.0**

**V2.02.401.09**

## Introduction to the tutorial

This tutorial includes the file content shown in the figure below to help you learn more about the car kit and programming knowledge:

 1_Get_start	2023/5/6 18:29	文件夹
 2_Arduino_Code	2023/5/5 17:58	文件夹
 3_Reference	2023/5/6 19:15	文件夹

"1\_Get\_start": This folder stores the robot assembly guide and necessary software environment files, etc. In order to complete the assembly accurately and quickly, please be sure to review it in detail and assemble it according to the manual. At the same time, the premise of realizing the program function is to create the software environment correctly, **please check the PDF files under this folder first** .

"2\_Arduino\_Code": This folder is used to store Arduino code files, and each code file is uploaded and used independently;

"3\_References": This folder stores some reference materials;

After completing the assembly of the car and creating the programming environment, follow this tutorial to complete the programming of the smart car program and realize different functions step by step!

## content

<b>Introduction to the tutorial .....</b>	<b>1</b>
<b>1. ESP32 CAM .....</b>	<b>2</b>
1.1 Description .....	2
1.2 Upload code .....	2
1.3 View IP address .....	8
1.4 Check the camera screen .....	9
<b>2. wifi control .....</b>	<b>11</b>
2.1 Description .....	11
2.2 Upload code .....	11
2.3 Test function .....	14
2.4 Introduction to Control Interface .....	16

# 1. ESP32 CAM

## 1.1 Description

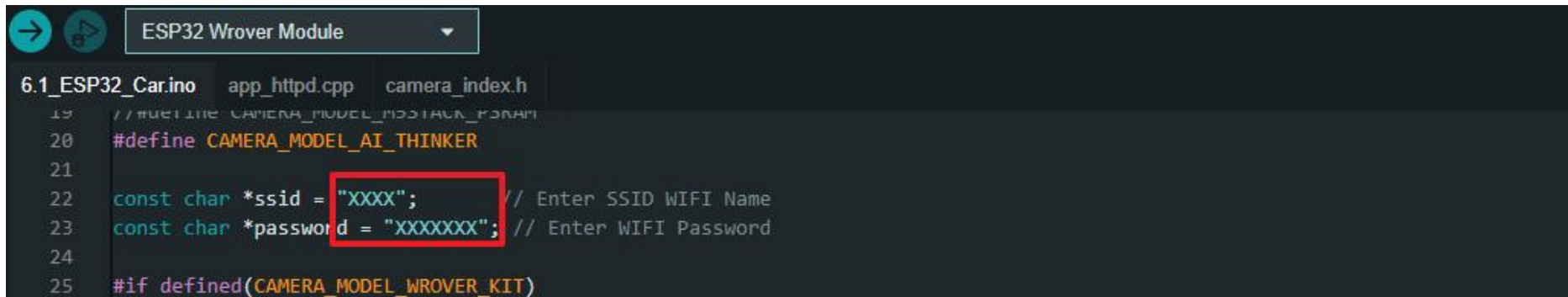
The content of this section mainly understands the use of ESP32 CAM, learns to upload codes and realizes that after ESP32 CAM is connected to WiFi, the shooting screen will be displayed on the browser in real time.

## 1.2 Upload code

Open the code file (path: 2\_Arduino\_Code\6.1\_ESP32\_Car\6.1\_ESP32\_Car.ino)

1_Auto_move	2023/5/6 9:19	文件夹	
2_servo_Angle	2023/5/5 17:55	文件夹	
3_Ultrasonic	2023/5/5 17:55	文件夹	
4_Obstacle_Avoidance	2023/5/6 9:19	文件夹	
5_Tracking	2023/5/6 9:19	文件夹	
6.1_ESP32_Car	2023/5/6 12:00	文件夹	
6.2_Arduino_UNO	2023/5/5 17:55	文件夹	
Tips.txt	2022/12/6 10:05	文本文档	1 KB

network credential account and password variables in the code to your own WiFi name and password !



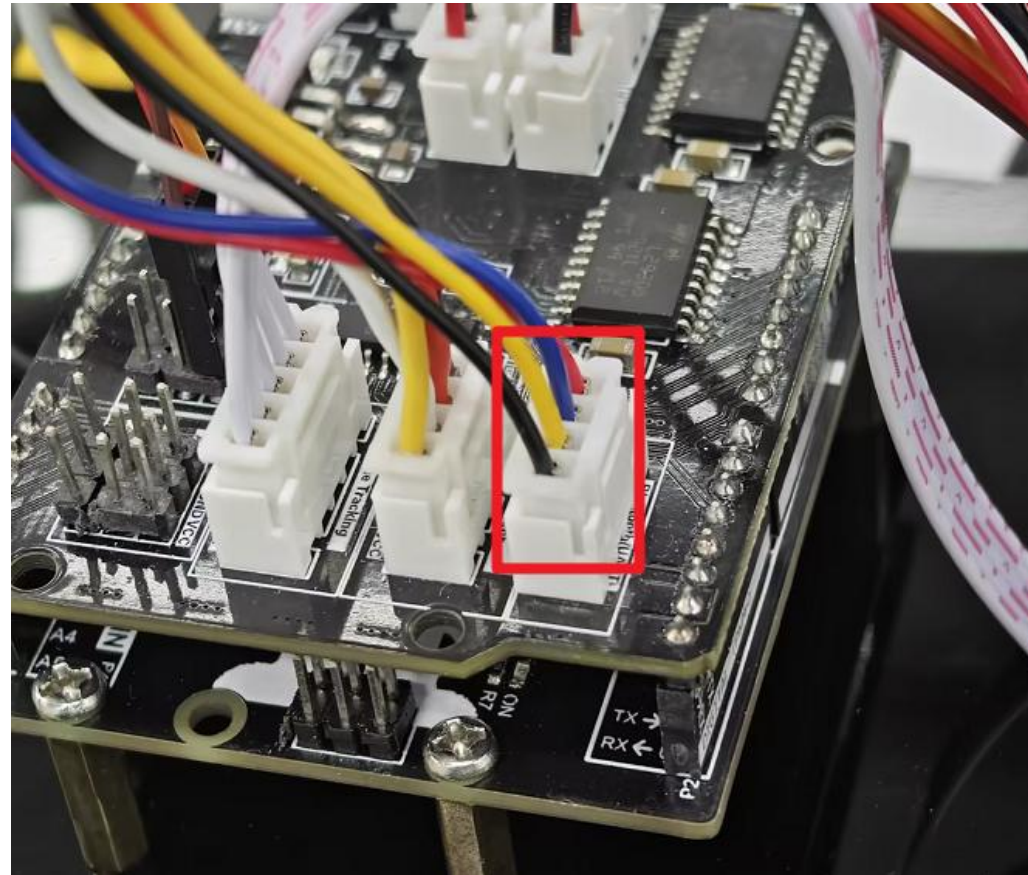
```
ESP32 Wrover Module
6.1_ESP32_Car.ino  app_httpd.cpp  camera_index.h
19 // #define CAMERA_MODEL_ESP8266_ESP01
20 #define CAMERA_MODEL_AI_THINKER
21
22 const char *ssid = "XXXX"; // Enter SSID WIFI Name
23 const char *password = "XXXXXXXX"; // Enter WIFI Password
24
25 #if defined(CAMERA_MODEL_WROVER_KIT)
```

ssid = " Your wifi name " ;

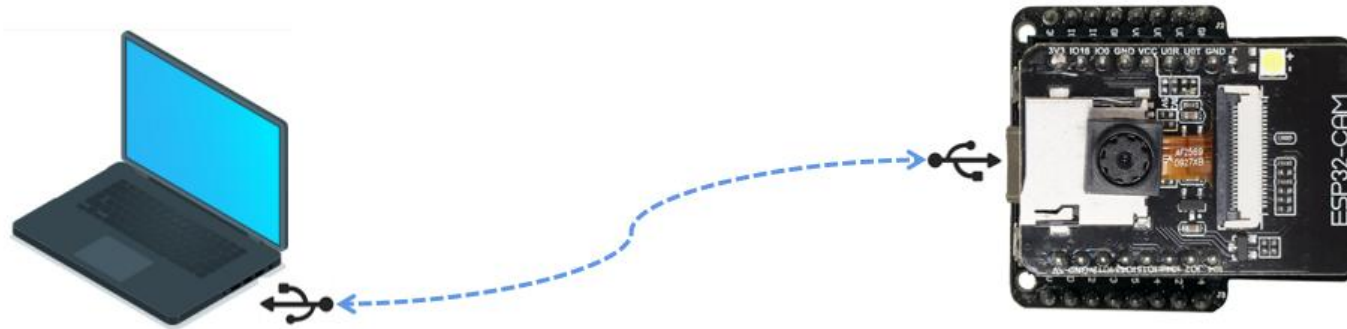
password = " WIFI Password "

At the same time, you should check that the WiFi you want to connect to is 2.4G instead of 5G frequency band, otherwise the function cannot be realized!

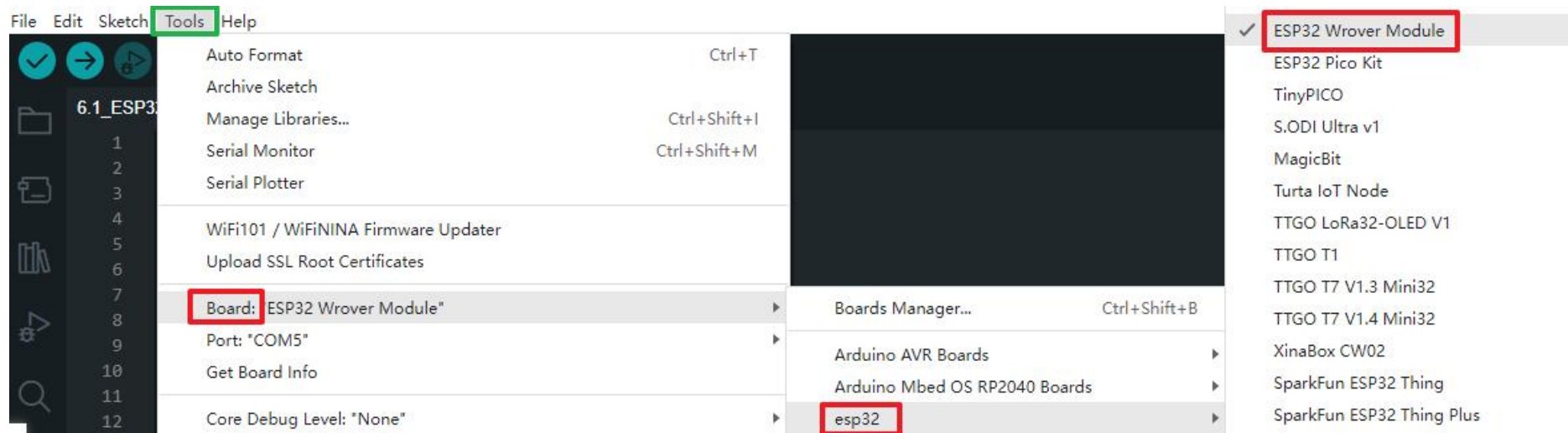
unplug the VCC/GND/RX/TX four connections and hold the BOOT button before uploading the program.



Connect the ESP32 CAM board to the computer with a USB cable



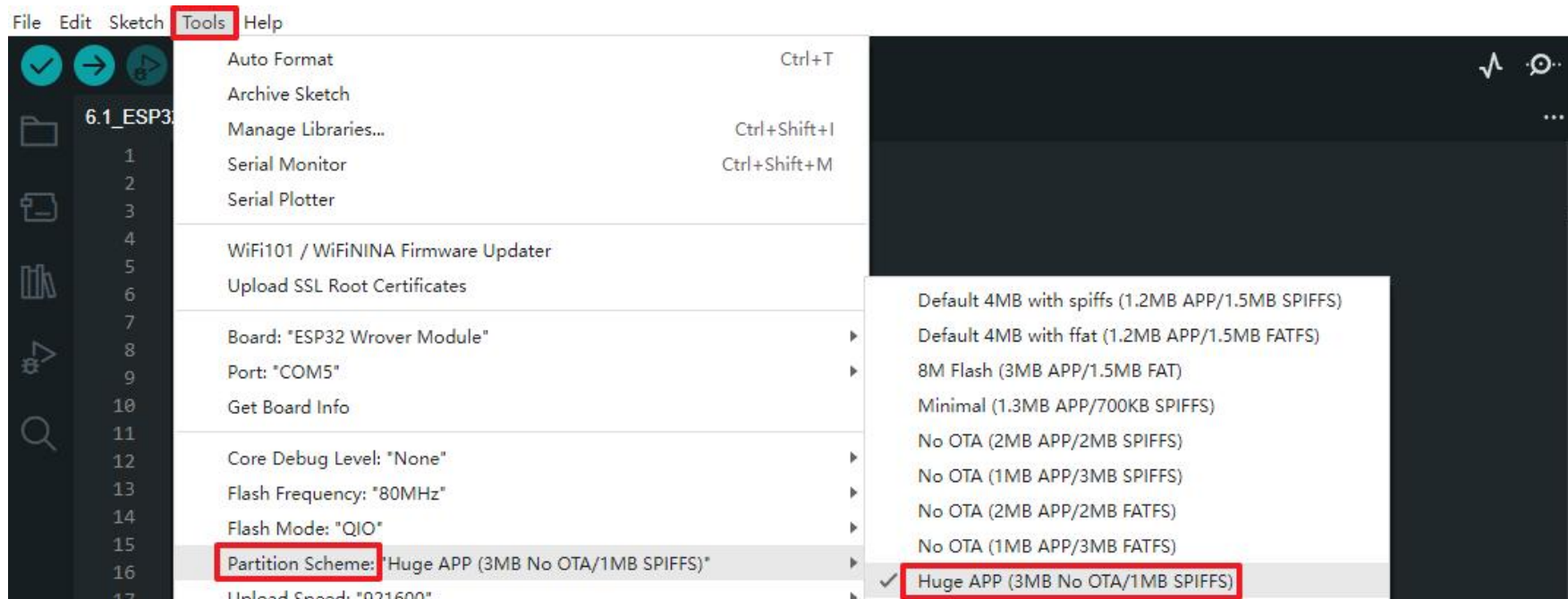
Select the board type as UNO and the serial port number as COM5







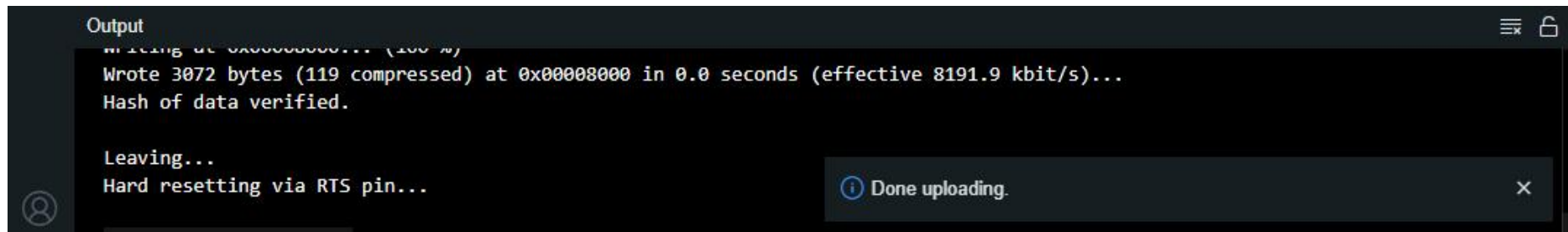
Note: The board type here is **ESP32 Wrover** and the serial port is **COM5**. Actually everyone displays the serial port differently, although COM 5 is selected here, it could be COM3 or COM4 on your computer.



After clicking the "Upload" button, the program starts to upload.

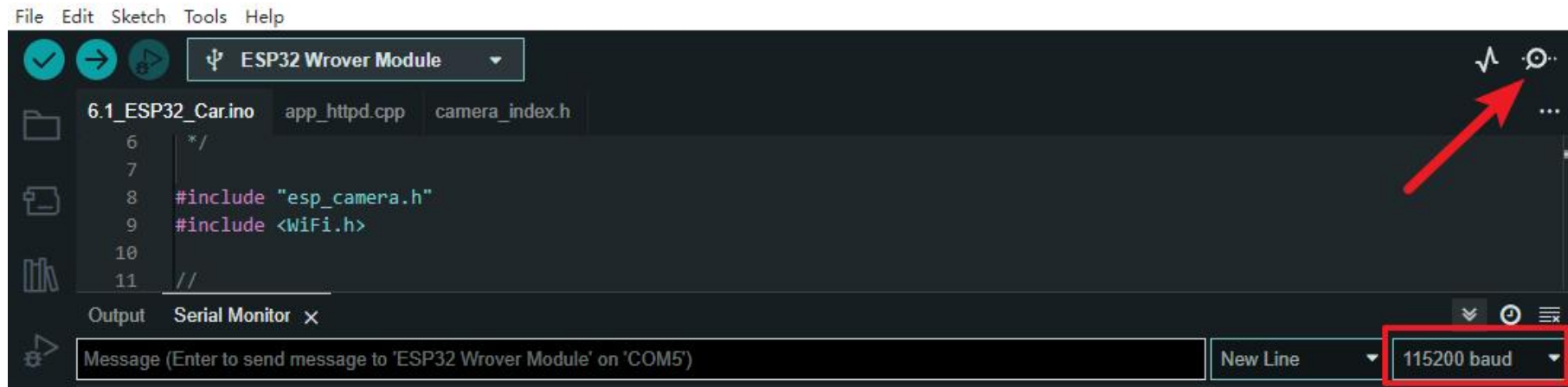


After the upload is successful, it prompts "Done uploading".



### 1.3 View IP address

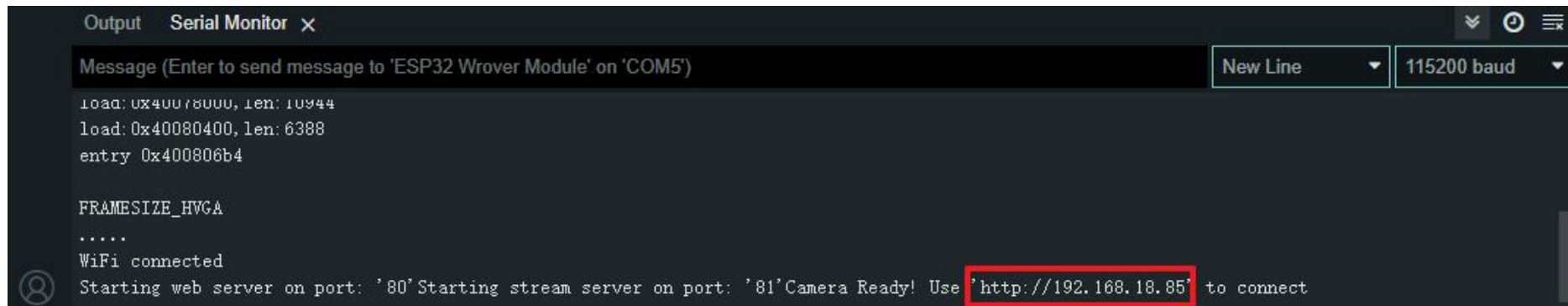
Open the serial monitor and set the baud rate to 115200 in the lower right corner



Program reload by pressing reset key on ESP32 CAM



When the program reloads and successfully connects to WiFi, the IP address will be displayed: `http://xxx.xxx.xxx.xxx`, please write it down



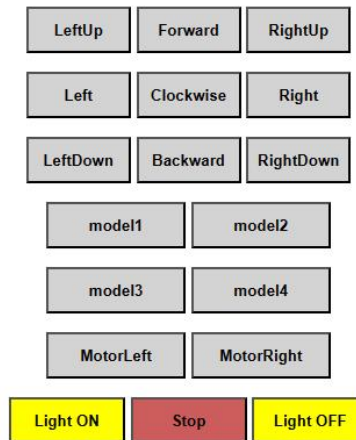
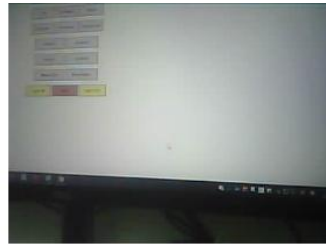
The screenshot shows the Arduino IDE Serial Monitor window. The title bar says "Output Serial Monitor x". The message input field at the top says "Message (Enter to send message to 'ESP32 Wrover Module' on 'COM5')". The output area shows the following text: `load: 0x400078000, len: 10944`, `load: 0x40080400, len: 6388`, `entry 0x400806b4`, `FRAME_SIZE_HVGA`, `.....`, `WiFi connected`, and `Starting web server on port: '80' Starting stream server on port: '81' Camera Ready! Use 'http://192.168.18.85' to connect`. The IP address `192.168.18.85` is highlighted with a red box.

## 1.4 Check the camera screen

with a device **connected to the WiFi** of the same LAN, enter the IP address into the address bar and run Jump.



You'll see the camera feed, but you won't be able to control the car's movement yet, which will be covered later.



When you can't see the screen:

1. Please check whether the WiFi name and password have been modified correctly;
2. Whether the network is 2.4G, and the signal is good;
3. Reset ESP32 CAM to ensure stable power supply;

## 2. wifi control

### 2.1 Description

This section mainly understands the use of TSCINBUNY control board and how to realize the WiFi control function.

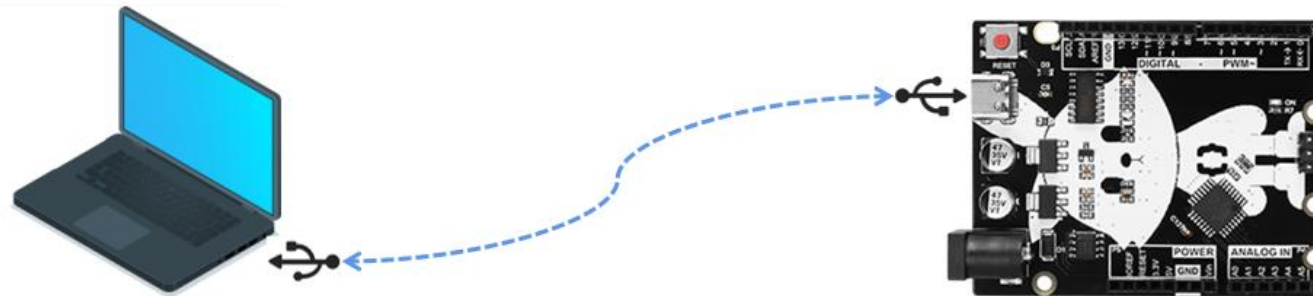
### 2.2 Upload code

Open the code file (path: 2\_Arduino\_Code\6.2\_Arduino\_UNO\6.2\_Arduino\_UNO.ino)

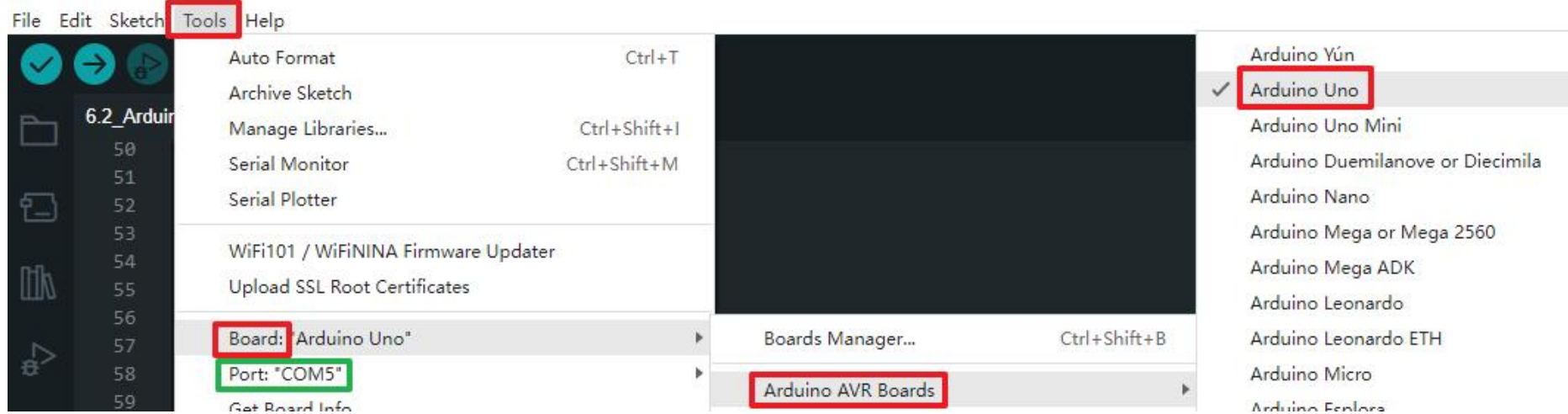
1_Auto_move	2023/5/6 9:19	文件夹
2_servo_Angle	2023/5/5 17:55	文件夹
3_Ultrasonic	2023/5/5 17:55	文件夹
4_Obstacle_Avoidance	2023/5/6 9:19	文件夹
5_Tracking	2023/5/6 9:19	文件夹
6.1_ESP32_Car	2023/5/6 12:00	文件夹
6.2_Arduino_UNO	2023/5/5 17:55	文件夹

unplug the four wires VCC/GND/RX/TX before uploading the program .

Connect the Arduino board to the computer with a USB cable .



Select **Uno** for the board type and **COM5** for the serial port



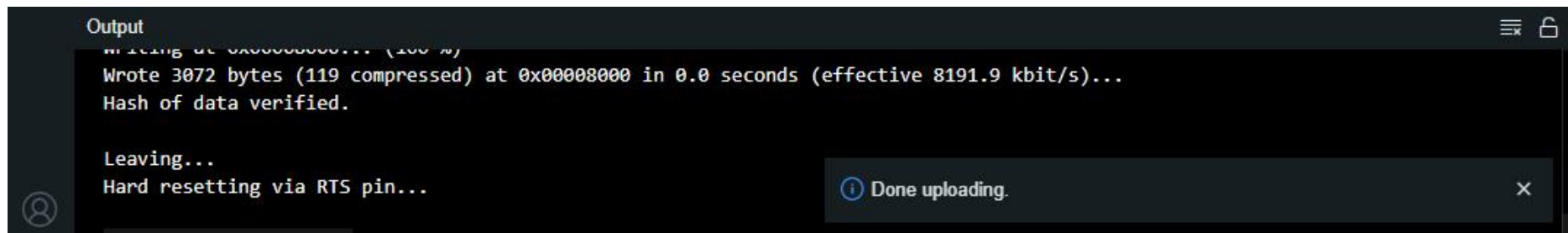
Note: In fact , everyone 's serial port display will be different, although COM 5 is selected here , it may be COM3 or

COM4 on your computer.

After clicking the "Upload" button, the program starts to upload.



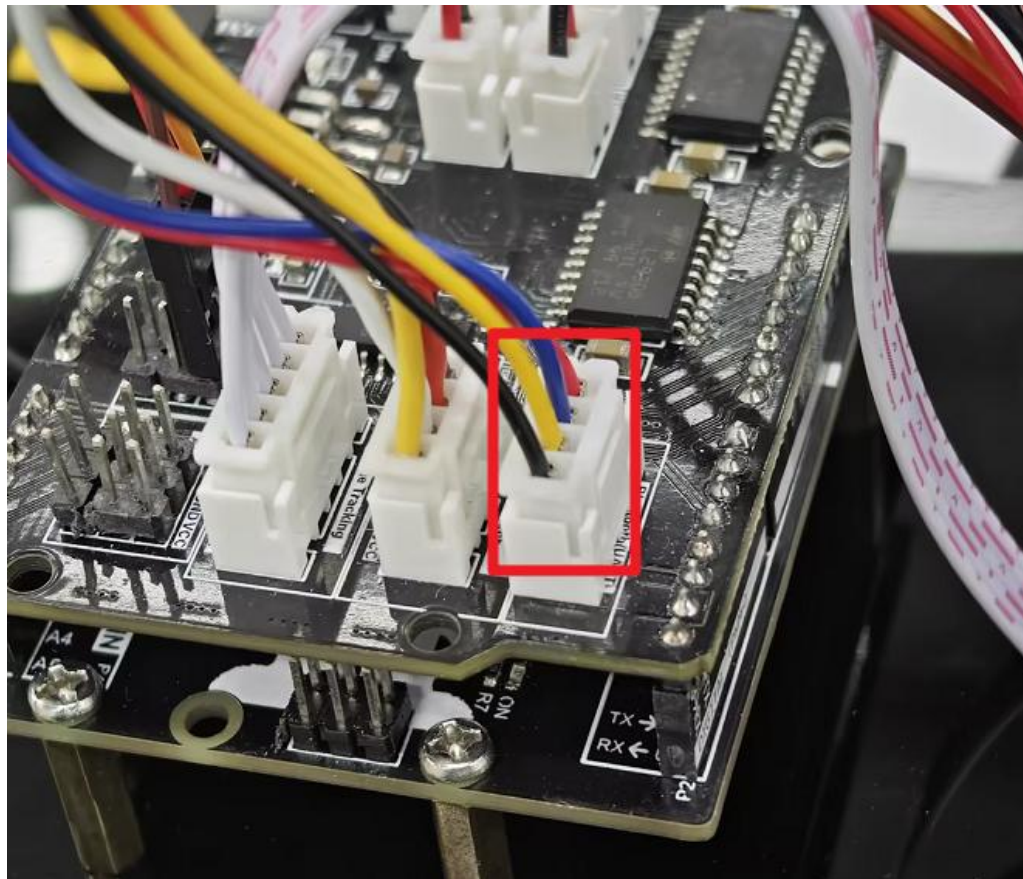
After the upload is successful, it prompts "Done uploading".





## 2.3 Test function

Re-plug the four VCC/GND/RX/TX cables



Install the 18650 battery (sufficient power), turn on the power switch, and press the ESP32 CAM reset button.



Open the browser with a device connected to the WiFi of the same LAN, enter [the IP address](#) (see the previous section for how to obtain it) and run the jump.



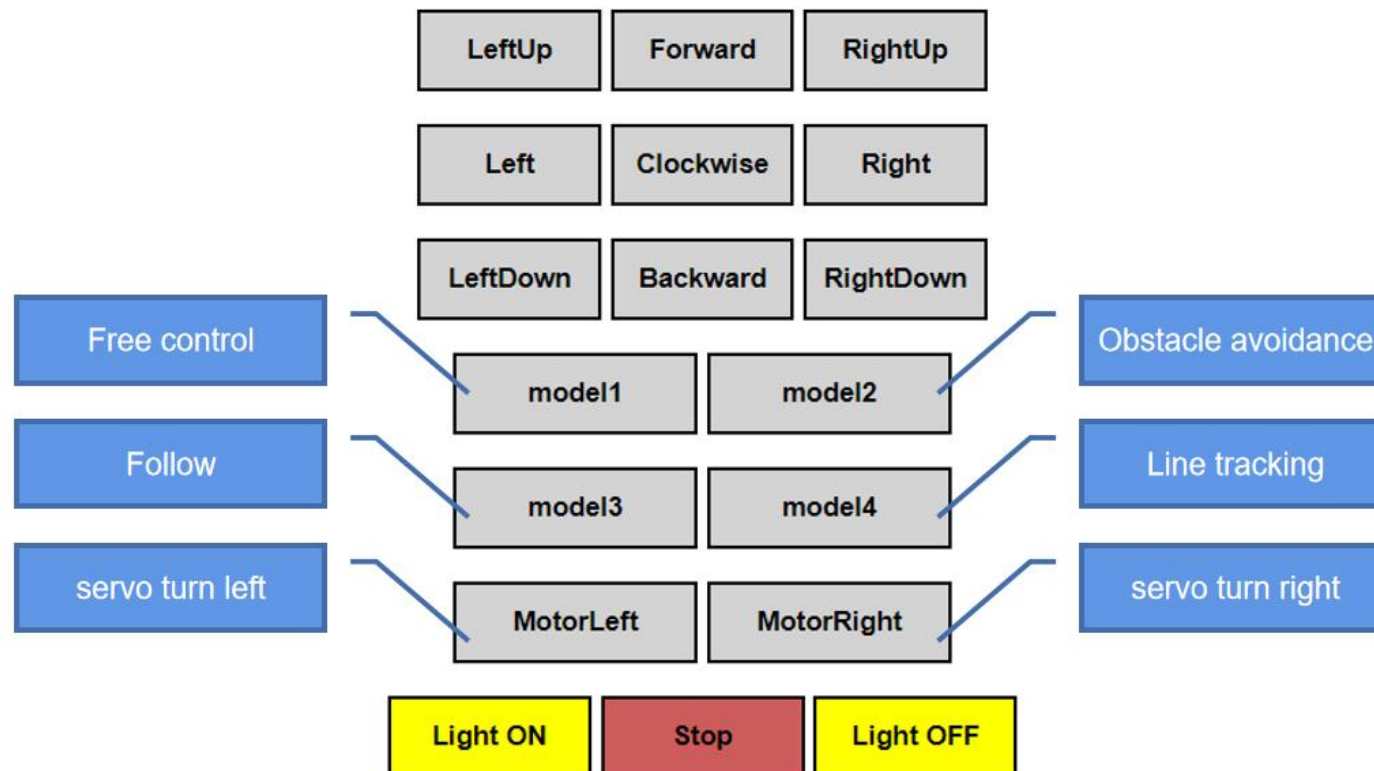
If the WiFi connection is successful, you should see the camera screen and the control button screen.

**If the picture is delayed:**

1. Check whether the network is smooth and stable without interference;
2. Whether the battery power is sufficient;

## 2.4 Introduction to Control Interface

The 9 buttons on the top correspond to the upper left, forward, upper right, leftward, clockwise rotation, rightward, leftward, backward and rightward movement of the car.



In addition to remote control of the car in the browser, you can also use the APP we provide to remote control. The premise is that the WiFi hotspot signal should be good and stable. Please refer to the folder "4\_APP" for details.

See the Reference Documentation for more details !

 1_Get_start	2023/5/6 18:29	文件夹
 2_Arduino_Code	2023/5/5 17:58	文件夹
 3_Reference	2023/5/8 17:08	文件夹