Inference of inter-particle forces from stochastic trajectories

Cristina Melnic

26.04.2021

System dynamics

Langevin equation

$$dx = \frac{1}{\gamma}F(x) dt + \sigma \xi(t)dt$$

- $p(x_0, t_0), p(x_i, t_i \mid x_{i-1}, t_{i-1}) ?$
- Fluctuation-dissipation theorem $D\beta\gamma=1$

$$dx = D\beta F(x) dt + \sigma \xi(t) dt$$
 (1)

Numerically generated trajectories

- Euler-Maruyama scheme
- Potentials

$$V_{HO}(x) = \frac{kx^2}{2} \tag{2}$$

$$V_{LJ}(x) = \epsilon \left[\left(\frac{r_{min}}{x} \right)^{12} - 2 \left(\frac{r_{min}}{x} \right)^{6} \right]$$
 (3)

$$V_{dw-HO}(x) = k_4 \frac{x^4}{4} + k_3 \frac{x^3}{3} + k_2 \frac{x^2}{2} + k_1 x + k_0$$
 (4)

Fitted displacement and position distributions

$$p(x) \propto \exp\left[-\beta V(x)\right]$$
 (5)

$$p(x, t \mid x_0, t_0) \propto \exp\left[-\beta V(x - x_0)\right] \tag{6}$$

Harmonic Oscillator

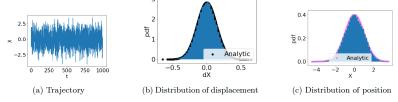


Figure 1.1: Stochastic trajectory of a particle in a harmonic oscillator potential

Position distribution

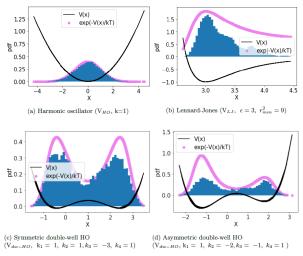


Figure 1.2: Distribution of positions from stochastic trajectories

Theoretical aspects I

• Re-written eq 6, $d\omega(t) = \xi(t)dt$

$$dx = D\beta F(x) dt + \sigma d\omega(t)$$

Average of eq. with the help of Itô lemma [2]

$$df[x(t)] = f'[x(t)]a[x(t), t]dt + f'[x(t)]b[x(t), t]d\omega(t) + \frac{1}{2}f''[x(t)](b[x(t), t])^{2}dt$$

Fokker-Planck equation [2]

$$\partial_t p(x,t \mid x_0,t_0) = \left(\partial_x a + \frac{1}{2}\partial_x^2 b\right) p(x,t \mid x_0,t_0) \qquad (7)$$

Theoretical aspects II

- Postulates at thd. equilibrium for conservative force fields
 - 1. Boltzmann probability distribution
 - 2. No net flux of particles (probability)
- Fluctuation dissipation theorem [2]

$$\nabla D = \mathbf{F}(\mathbf{r}) \left(\gamma^{-1} - D\beta \right) \tag{8}$$

Smoluchowski equation

00000

$$\partial_t p(x,t \mid x_0,t_0) = D\left(\partial_x^2 - \beta F(x)\right) p(x,t \mid x_0,t_0)$$
 (9)

• Linear Potential V(x) = cx [2]

$$p(x, t \mid x_0, t_0) = \frac{1}{\sqrt{4\pi D(t - t_0)}} \exp \left[-\frac{(x - x_0 + D\beta c(t - t_0))^2}{4D(t - t_0)} \right]$$
(10)

Bayesian Inference

[1]
$$p(\theta \mid X) = \frac{p(X \mid \theta) \pi(\theta)}{p(X)} = \frac{\mathcal{L}_n(\theta) \pi(\theta)}{c_n}$$

$$c_n = p(X_1, \dots, X_n) = \int \mathcal{L}_n(\theta) \pi(\theta) d\theta$$
(11)

- Parameters: $\theta = \{k_i\}, i = 1 \dots n \text{ from } F(\{k_i\}), X = dx_{i+1,i}$
- The likelihood: $\mathcal{L}_n(\theta) = \mathcal{N}\left(dx_{i+1,i} F_i, 2D\Delta t\right)$
- The prior: $\pi(\theta) = \frac{1}{n}$

Results I

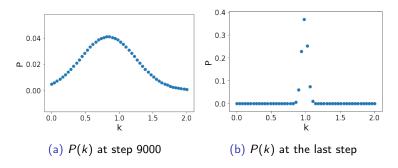


Figure 1: Evolution of P(k) for the HO case (Correct value k = 1)

Results II

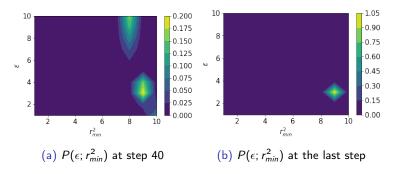
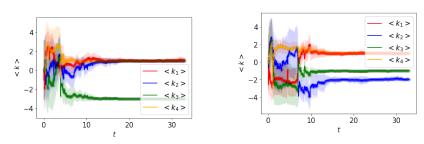


Figure 2: Evolution of $P(\epsilon; r_{min}^2)$ for the LJ case (Correct values $\epsilon = 3; r_{min}^2 = 9$)

(a)

 $k_1 = 1$, $k_2 = 1$, $k_3 = -3$, $k_4 = 1$

Results III



(b)

 $k_1 = 1, k_2 = -2, k_3 = -1, k_4 = 1$

Conclusions

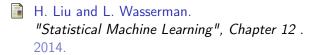
Advantages

- It works!
- No complicated Smoluchowski solution for p(dX|F) needed
- Not all the data necessary

Disadvantages

- Slow with more parameters
- Analytic form of the forces needed
- A good guess of parameter intervals

References



K. Schulten.
"Lecture Notes PHYS498", Chapters 2,4,5.