# **Hopping onto the Deep Learning bandwagon**

Youssef Kashef Machine Intelligence I 08. December 2016



### **Outline**

- What is Deep Learning?
- Neural Networks make a comeback
- Popular Network Architectures
	- Auto-encoders
	- Restricted Boltzmann machines
	- Convolutional Neural Networks
- Benefits and Challenges
- Hands-on Deep Learning
- Deep Learning at NII

# **What is Deep Learning?**

The typical Machine Learning pipeline:



# **What is Deep Learning?**

Learning a hierarchical representation of the data, directly from the data



character, word, clause, sentence, ...

audio, band, phoneme, word, phrase, ...



## **What is Deep Learning?**

Learning a hierarchical representation of the data, directly from the data



#### Good-old fashioned perceptron





Good-old fashioned perceptron Good-old MLP







W<sub>2</sub>

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MLP with many many layers  $\rightarrow$  Deep Neural Net



MLP with many many layers  $\rightarrow$  Deep Neural Net

#### **But when training it the usual way, not any better than 2-layer MLP**

- Some weights get stuck
- Some weights are unstable
- gradients in one layer are very different from the next

#### The Vanishing Gradient Problem



[Nielsen15]

MLP with many many layers  $\rightarrow$  Deep Neural Net

- Vanishing/exploding of gradients
- Random initializations limiting
- Overfitting

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$$
\overbrace{\left(\begin{array}{c}\begin{array}{c}w_1\\ \partial G\end{array}\right)}^{w_1}=\sigma'(z_1)\,w_2\sigma'(z_2)\,w_3\sigma'(z_3)\,w_4\sigma'(z_4)\,\frac{\partial C}{\partial a_4}\end{array}}^{w_4}\overbrace{\left(\begin{array}{c}b_4\\ \partial G\end{array}\right)}^{w_2}C
$$



MLP with many many layers  $\rightarrow$  Deep Neural Net

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MLP with many many layers  $\rightarrow$  Deep Neural Net

But:

- Vanishing/exploding of gradients
- Random initializations limiting
- **Overfitting**



non-saturating activation function (e.g. ReLU)

unsupervised pre-training (more in just a few)

data, **LOTS** of data, but not completely solved

#### Good-old MLP





 $h_{W,b}(x) \approx x$ 

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How to avoid learning the identity function?

- **● Undercomplete AEs**
- **● Regularization**
- **● Denoising**





### **Autoencoders → Denoising Autoencoders**

Reconstruct variables from corrupted input



30%











### **Autoencoders → Stacked Denoising Autoencoders**



 $h_{W,b}(x) \approx x$ 

# **Popular Architectures: Restricted Boltzmann Machines (RBM)**



### **RBM → Deep Belief Nets**



# **Popular Architectures: Convolutional Neural Networks**

#### **2D Convolution Correlation**





Convolved Feature

# **Popular Architectures: Convolutional Neural Networks**

The convolutional stage:



# **Popular Architectures: Convolutional Neural Networks**

#### The convolutional stage:



### **Convolutional Neural Networks**



[LeCun et al.]

#### **Payoffs**

- **Implicit Feature Learning**
- Same data, same model, different tasks

### Visual Style Recognition Visual Style Recognition





#### **Payoffs**

#### **Challenges**

- **Implicit Feature Learning**
- Same data different tasks
- Computationally intensive
- Prone to overfitting
- adversarial images



#### **Challenges**

#### **Solutions**

?

- Computationally intensive
- Prone to overfitting
- adverserials images

#### **Payoffs**

- **Implicit Feature Learning**
- Same data, same model, different tasks

#### **Challenges**

#### **Solutions**

- Computationally intensive
- Prone to overfitting
- adverserials images

GPU accelerated computation

data augmentation, Convolution, Dropout

#### **Payoffs**

- **Implicit Feature Learning**
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#### **Challenges**

- Computationally intensive
- Prone to overfitting
- adverserials images

GPU accelerated computation

**Solutions**

data augmentation, Convolution, **Dropout**



(a) Standard Neural Net



(b) After applying dropout.

### **Hands-on Deep Learning**







Directed Acyclic Graph







base 1r: 0.01 momentum:  $0.9$ weight\_decay: 0.0005 max iter: 10000 snapshot\_prefix: "lenet\_snapshot"





# **Deep Learning at NI: Multi-Objective Deep Learning**



# **Deep Learning at NI: Multi-Objective Deep Learning**

Training specialized networks from random initializations.

Re-purposing networks is possible and successful.

How do we learn a general purpose representation?

Regularization in the objective space.

### **Semantic Segmentation**

![](_page_42_Picture_1.jpeg)

Foreground-Background subtraction (Binary)

![](_page_42_Picture_3.jpeg)

![](_page_42_Figure_4.jpeg)

**Stuff** and **Things** (M-way)

![](_page_42_Picture_6.jpeg)

![](_page_42_Picture_7.jpeg)

scene parsing (M-way)

2 large *M* large *M* and the set close of *M* and *M* large *M* 

no. of classes *M*

### **End-to-end learning: Fully Conv. Networks for Semantic Segmentation (CVPR 2015)**

![](_page_43_Picture_1.jpeg)

Figure 2. Transforming fully connected layers into convolution layers enables a classification net to output a heatmap. Adding layers and a spatial loss (as in Figure 1) produces an efficient machine for end-to-end dense learning.

[Long et al.]

NIPS 1992

![](_page_43_Figure_5.jpeg)

### **Training Fully Conv. Networks for Semantic Segmentation**

![](_page_44_Figure_1.jpeg)

### **Finetuning vs. random initialization**

loss := multinomial logistic softmax loss (without normalization)

![](_page_45_Figure_2.jpeg)

### **Finetuning vs. random initialization**

#### **Train** loss without normalization **Test** loss without normalization

![](_page_46_Figure_3.jpeg)

# **Fixing Feature Layers**

 $\bigodot$ 

![](_page_47_Figure_1.jpeg)

 $\mathbf{r}$ 

 $7x7$ 

 $\mathbf{r}$ 

### **Fixing Feature Layers**

Preventing earlier weights from updating during optimization<br>
FRACEL-Context-59 on Train set 350K 300K 250K input feat. conv1 1 Train loss 200K parameters increasing no. of parameters $\omega$ conv1 2 conv2 1 150K conv2 2 100K conv3 1 conv3 2 50K conv3 3  $\overline{\sigma}$  $0K_{K}$ conv4 1 **50K**  $\overline{100K}$ ρ. iterations conv4 2  $- -$ FCN-32s on PASCAL-Context-59 on Test set 380K conv4 3 increasing conv5 1 360K conv5\_2 н. 340K conv5\_3 320K fc6 శ్ Test loss fc7  $\mathbf{a}$ 300K 280K Ξ 260K 240K  $220K$ 50K 100K

iterations

![](_page_48_Figure_2.jpeg)

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 $\mathbf{A}$ 

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 $7x7$ 

### **Fixing Feature Layers**

Preventing earlier weights from updating during optimization<br>
FRACEL-Context-59 on Train set 350K 300K 250K input feat. conv1 1 Train loss 200K parameters increasing no. of parameters  $\omega$ conv1 2 conv2 1 150K conv2 2 100K conv3 1 conv3 2 50K conv3 3  $\overline{\sigma}$  $0K_{K}$ conv4 1  $50K$  $\overline{100K}$ ρ. iterations conv4 2  $- -$ FCN-32s on PASCAL-Context-59 on Test set 380K conv4 3 increasing conv5 1 360K conv5\_2 н. 340K conv5\_3 conv3 1 320K fc6 శ్ Test loss fc7  $\mathbf{a}$ 300K  $conv4<sub>2</sub>$ 280K Ξ conv5 1 260K 240K  $220K$ 50K 100K iterations

![](_page_49_Figure_2.jpeg)

iterations

 $\mathbf{A}$ 

 $\mathbf{w}$ 

 $7x7$ 

### **Joint sound identification and localisation**

![](_page_50_Figure_1.jpeg)

![](_page_50_Picture_2.jpeg)

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### **www.kahoot.it**

![](_page_51_Picture_1.jpeg)

### **Further Reading**

#### **Books**

Goodfellow, I., Bengio Y. and Courville A. (2016). [Deep Learning](http://www.deeplearningbook.org/). Book in preparation for MIT Press.

Nielsen, M.A (2015). [Neural Networks and Deep Learning.](http://neuralnetworksanddeeplearning.com/index.html) Determination Press.

**Review papers**

J. Schmidhuber. (2015). [Deep Learning in Neural Networks: An Overview.](http://people.idsia.ch/~juergen/deep-learning-overview.html) Neural Networks.

#### **Tutorials and code examples**

[Deep Learning Tutorials.](http://deeplearning.net/tutorial/) Theano.

**A bit of everything**

<http://deeplearning.net/>

![](_page_52_Picture_10.jpeg)

### **References**

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Mottaghi, R., Chen, X., Liu, X., Cho, N.-G., Lee, S.-W., Fidler, S., Yuille, A. (2014). The role of context for object detection and semantic segmentation in the wild. *Cvpr*, 891–898. doi:10.1109/CVPR.2014.119

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Christian Szegedy, Wojciech Zaremba, Ilya Sutskever, Joan Bruna, Dumitru Erhan, Ian Goodfellow, Rob Fergus. (2014). Intriguing properties of neural networks

Van Essen, D. C., & Gallant, J. L. (1994). Neural mechanisms of form and motion processing in the primate visual system. Neuron, 13(1), 1–10.