# Hopping onto the Deep Learning bandwagon

Youssef Kashef Machine Intelligence I 08. December 2016



### Outline

- What is Deep Learning?
- Neural Networks make a comeback
- Popular Network Architectures
  - Auto-encoders
  - Restricted Boltzmann machines
  - Convolutional Neural Networks
- Benefits and Challenges
- Hands-on Deep Learning
- Deep Learning at MI

# What is Deep Learning?

The typical Machine Learning pipeline:

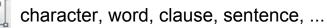


# What is Deep Learning?

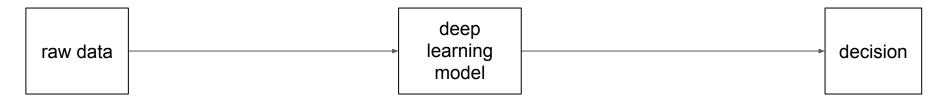
Learning a hierarchical representation of the data, directly from the data



pixel, motif, part, object, scene, ...

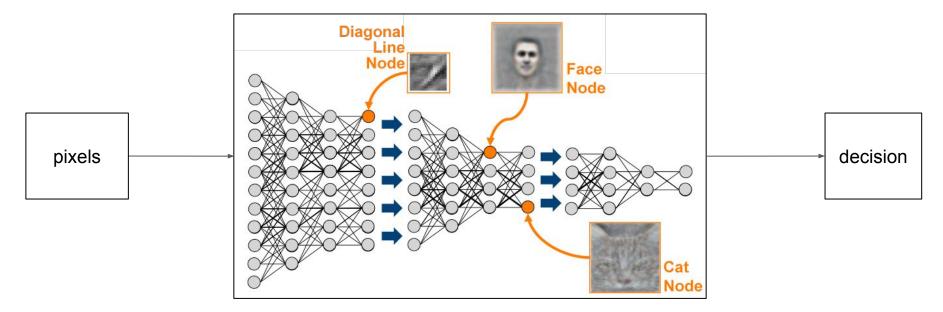


audio, band, phoneme, word, phrase, ...

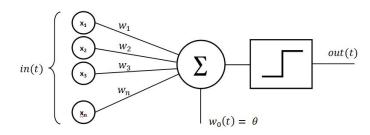


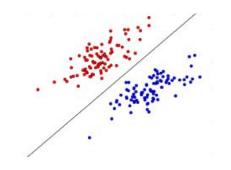
# What is Deep Learning?

Learning a hierarchical representation of the data, directly from the data

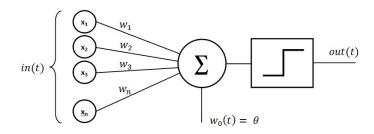


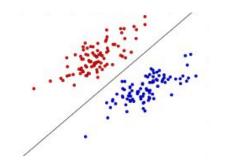
#### Good-old fashioned perceptron



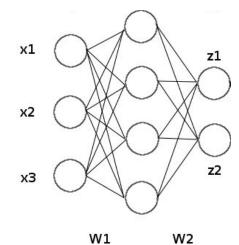


Good-old fashioned perceptron



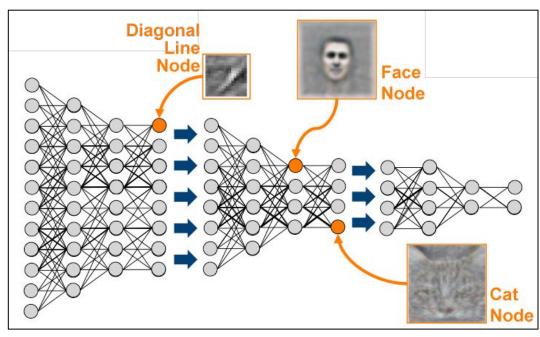


Good-old MLP



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MLP with many many layers  $\rightarrow$  Deep Neural Net

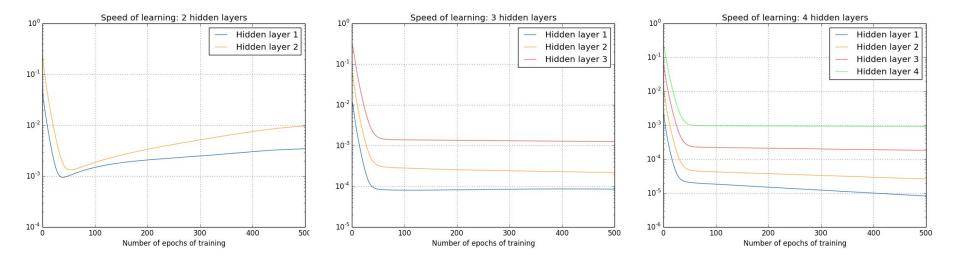


MLP with many many layers  $\rightarrow$  Deep Neural Net

# But when training it the usual way, not any better than 2-layer MLP

- Some weights get stuck
- Some weights are unstable
- gradients in one layer are very different from the next

#### The Vanishing Gradient Problem



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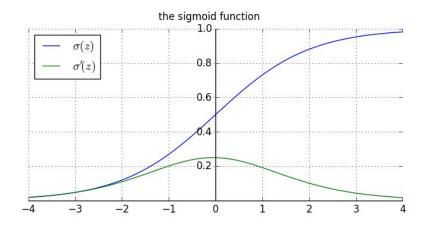
MLP with many many layers  $\rightarrow$  Deep Neural Net

- Vanishing/exploding of gradients
- Random initializations limiting
- Overfitting

MLP with many many layers  $\rightarrow$  Deep Neural Net

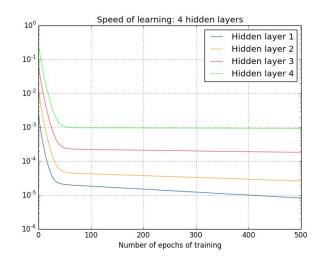
- Vanishing/exploding of gradients
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$$\underbrace{ \begin{array}{c} w_1 \\ \hline \end{array} \underbrace{ b_1 \\ \hline \end{array} \underbrace{ w_2 \\ b_2 \\ \hline \end{array} \underbrace{ b_3 \\ \hline \end{array} \underbrace{ b_3 \\ \hline \end{array} \underbrace{ w_4 \\ b_4 \\ \hline \end{array} \underbrace{ b_4 \\ \hline \end{array} \underbrace{ C \\ \hline \end{array} \underbrace{ \begin{array}{c} \partial C \\ \partial b_1 \\ \hline \end{array} \underbrace{ \sigma'(z_1) w_2 \sigma'(z_2) w_3 \sigma'(z_3) w_4 \sigma'(z_4) \frac{\partial C \\ \partial a_4 \\ \hline \end{array} } }_{ a_4 }$$



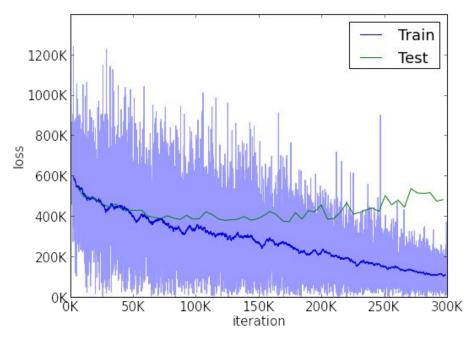
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MLP with many many layers  $\rightarrow$  Deep Neural Net

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MLP with many many layers  $\rightarrow$  Deep Neural Net

But:

- Vanishing/exploding of gradients
- Random initializations limiting
- Overfitting

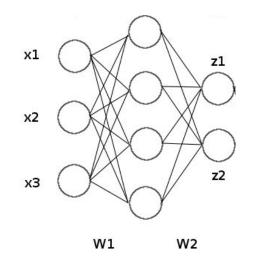


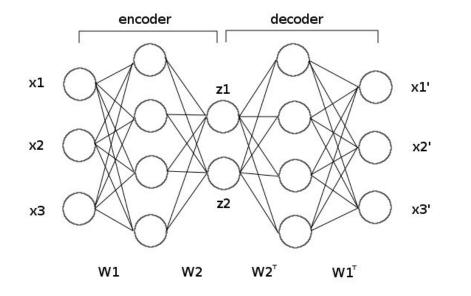
non-saturating activation function (e.g. ReLU)

unsupervised pre-training (more in just a few)

data, LOTS of data, but not completely solved

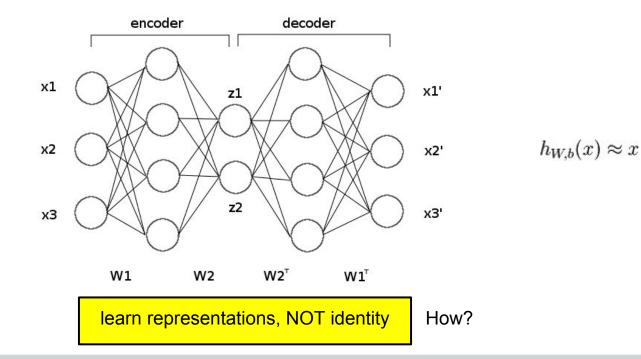
#### Good-old MLP





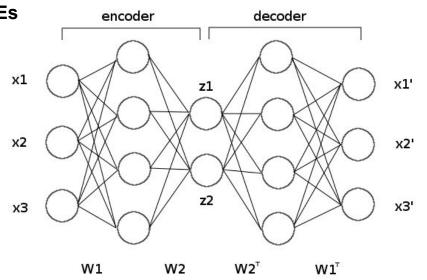
 $h_{W,b}(x) \approx x$ 

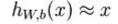
17



How to avoid learning the identity function?

- Undercomplete AEs
- Regularization
- Denoising





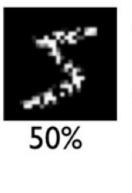
# $\textbf{Autoencoders} \rightarrow \textbf{Denoising Autoencoders}$

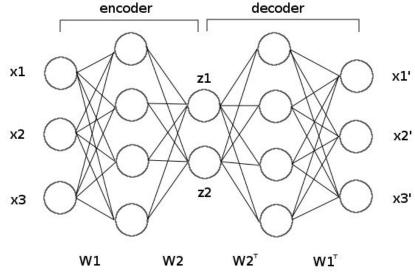
Reconstruct variables from corrupted input



30%



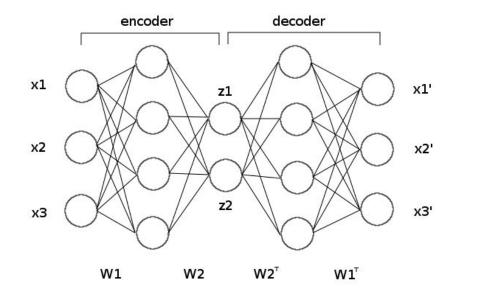








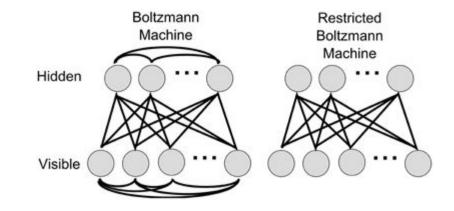
# $\begin{array}{l} \textbf{Autoencoders} \rightarrow \textbf{Stacked Denoising} \\ \textbf{Autoencoders} \end{array}$



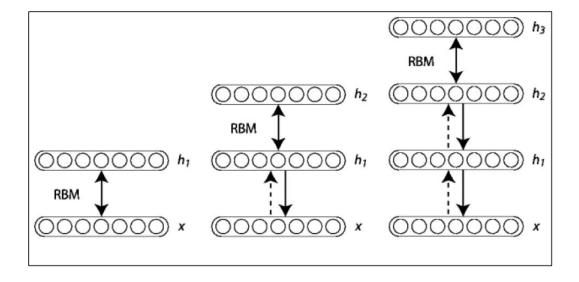
$$h_{W,b}(x) \approx x$$

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# Popular Architectures: Restricted Boltzmann Machines (RBM)

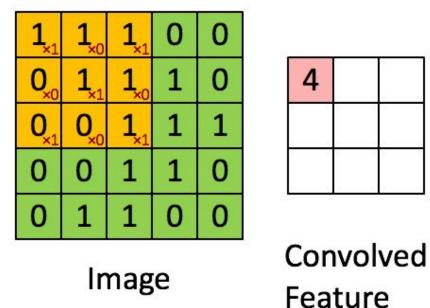


### **RBM** $\rightarrow$ **Deep Belief Nets**



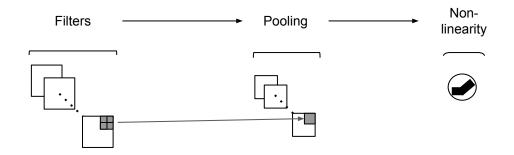
# Popular Architectures: Convolutional Neural Networks

#### 2D Convolution Correlation



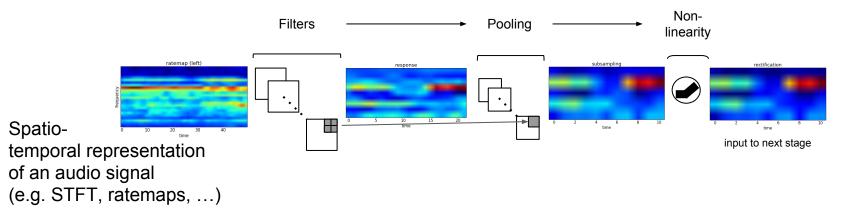
# Popular Architectures: Convolutional Neural Networks

The convolutional stage:

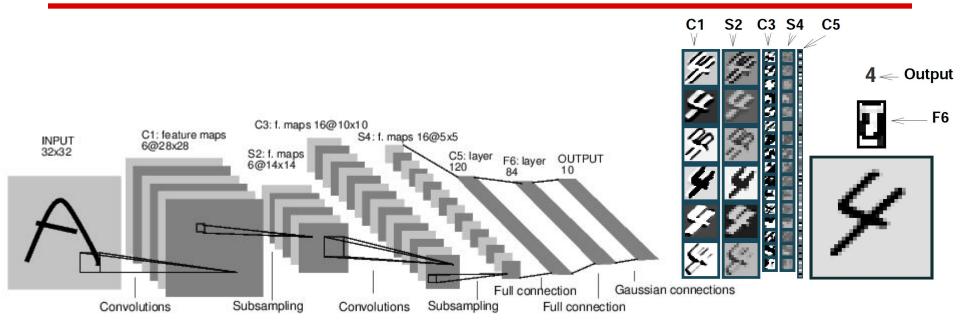


# Popular Architectures: Convolutional Neural Networks

#### The convolutional stage:



### **Convolutional Neural Networks**

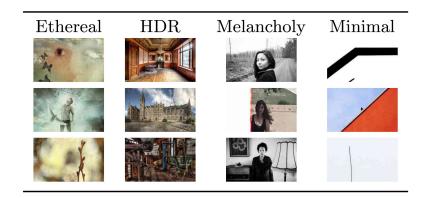


[LeCun et al.]

#### Payoffs

- Implicit Feature Learning
- Same data, same model, different tasks

#### Visual Style Recognition



#### [Karayev14]

#### Re-paint in style



[Gatys15]

#### Payoffs

#### Challenges

- Implicit Feature Learning
- Same data different tasks
- Computationally intensive
- Prone to overfitting
- adversarial images



#### Challenges

#### Solutions

?

- Computationally intensive
- Prone to overfitting
- adverserials images

#### Payoffs

- Implicit Feature Learning
- Same data, same model, different tasks

#### Challenges

#### **Solutions**

- Computationally intensive
- Prone to overfitting
- adverserials images

GPU accelerated computation

data augmentation, Convolution, Dropout

#### Payoffs

- Implicit Feature Learning
- Same data, same model, different tasks

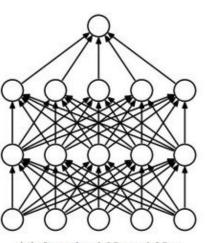
#### Challenges

#### Solutions

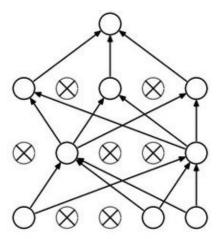
- Computationally intensive
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GPU accelerated computation

data augmentation, Convolution,
 Dropout



(a) Standard Neural Net

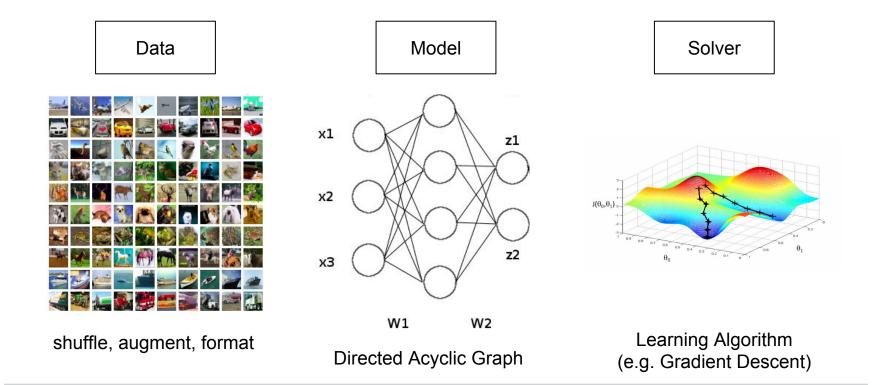


(b) After applying dropout.

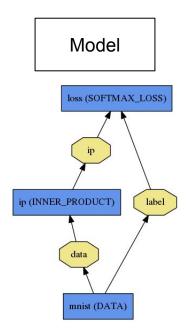
# Hands-on Deep Learning



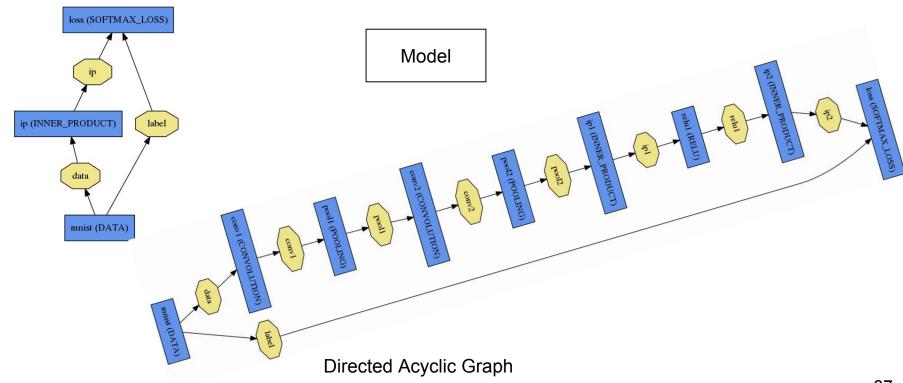
# Hands-on Deep Learning using Caffe

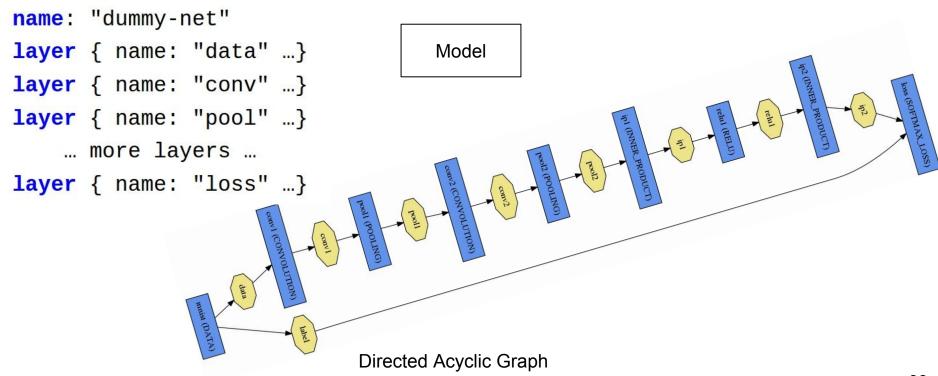


# Hands-on Deep Learning using Caffe



Directed Acyclic Graph





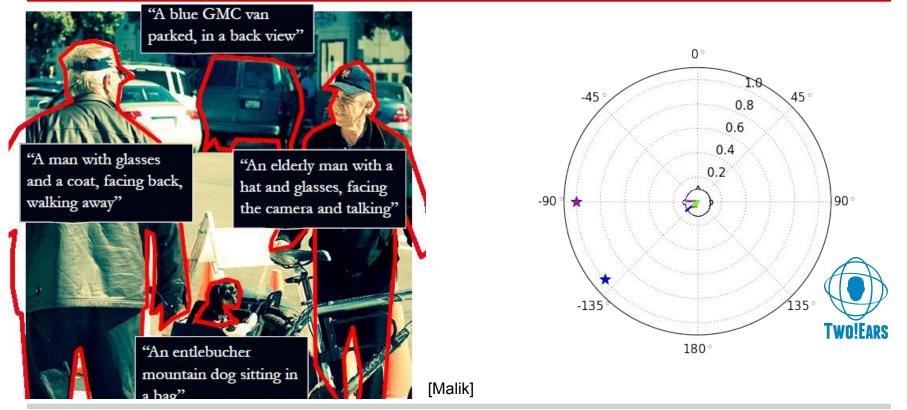


base\_lr: 0.01
momentum: 0.9
weight\_decay: 0.0005
max\_iter: 10000
snapshot\_prefix: "lenet\_snapshot"



I0901 13:35:20.426187 20072 solver.cpp:232] Iteration 65000, loss = 61.5498
I0901 13:35:20.426218 20072 solver.cpp:251] Iteration 65000, Testing net (#0) # train set
I0901 13:35:22.780092 20072 solver.cpp:289] Test loss: <b>60.8301</b>
I0901 13:35:22.780138 20072 solver.cpp:302] Test net output #0: cross_entropy_loss = 60.8301 (* 1 = 60.8301 loss)
I0901 13:35:22.780146 20072 solver.cpp:302] Test net output #1: 12_error = 2.02321

# Deep Learning at NI: Multi-Objective Deep Learning



# Deep Learning at NI: Multi-Objective Deep Learning

Training specialized networks from random initializations.

Re-purposing networks is possible and successful.

How do we learn a general purpose representation?

Regularization in the objective space.

### **Semantic Segmentation**

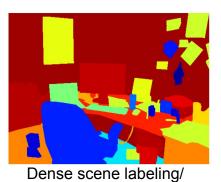


Foreground-Background subtraction (Binary)



Stuff and Things (M-way)

[Mottaghi]



scene parsing (M-way)

large M

#### no. of classes M

# End-to-end learning: Fully Conv. Networks for Semantic Segmentation (CVPR 2015)

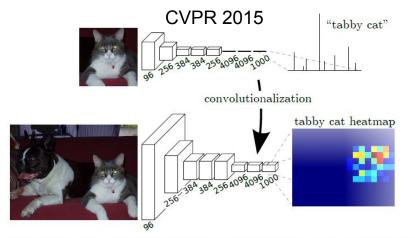
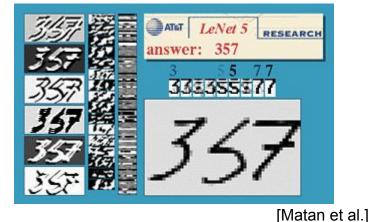


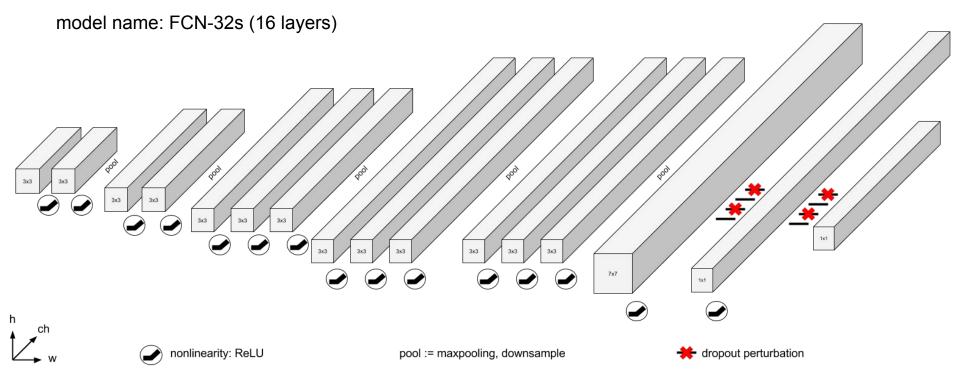
Figure 2. Transforming fully connected layers into convolution layers enables a classification net to output a heatmap. Adding layers and a spatial loss (as in Figure 1) produces an efficient machine for end-to-end dense learning.

[Long et al.]

NIPS 1992

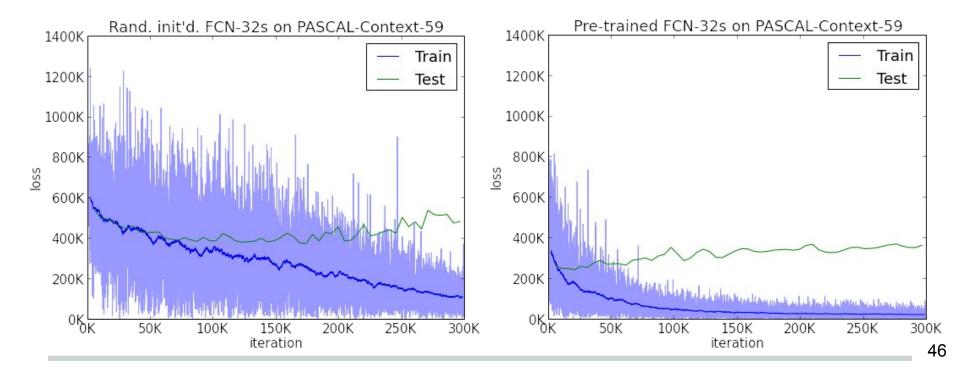


# Training Fully Conv. Networks for Semantic Segmentation



### Finetuning vs. random initialization

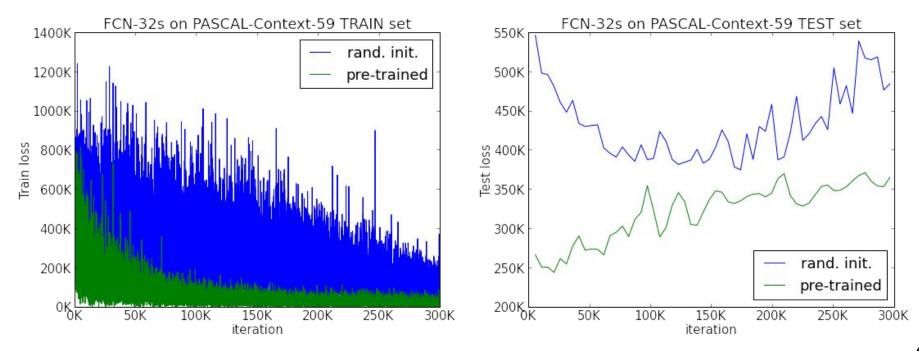
loss := multinomial logistic softmax loss (without normalization)



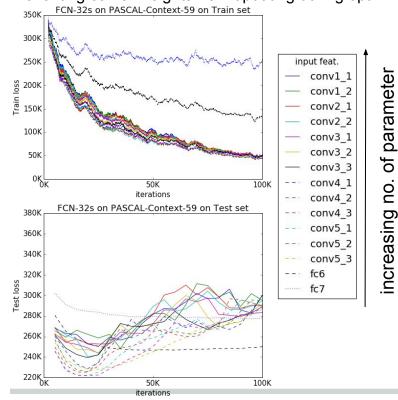
### Finetuning vs. random initialization

#### Train loss without normalization

#### Test loss without normalization



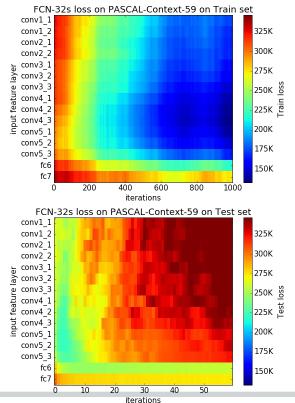




# **Fixing Feature Layers**

Preventing earlier weights from updating during optimization FCN-32s on PASCAL-Context-59 on Train set 350K 300K 250K input feat. š convl 1 Train loss 200K parameters æ conv1 2 conv2 1 150K nput conv2 2 100K conv3 1 conv3 2 50K ď conv3 3 ok⊏ ok conv4 1 50K 100K <u>o</u> iterations conv4 2 FCN-32s on PASCAL-Context-59 on Test set 380K conv4 3 increasing conv5 1 360K conv5 2 340K conv5 3 320K fc6 ay Test loss fc7 Φ 300K 280K a 260K 240K 220KL 50K 100K

iterations



49

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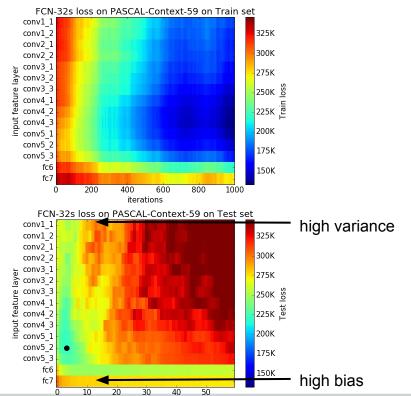
7x7

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Preventing earlier weights from updating during optimization FCN-32s on PASCAL-Context-59 on Train set 350K 300K 250K input feat. š convl 1 Train loss 200K parameters conv1 2 150K conv2 1 nput conv2 2 100K conv3 1 conv3 2 50K ď conv3 3 OK conv4 1 50K 100K <u>o</u> iterations conv4 2 - -FCN-32s on PASCAL-Context-59 on Test set 380K conv4 3 increasing conv5 1 360K conv5 2 340K conv5\_3 320K fc6 ay Test loss fc7 Φ 300K 280K a 260K 240K 220KL 100K 50K

iterations



iterations

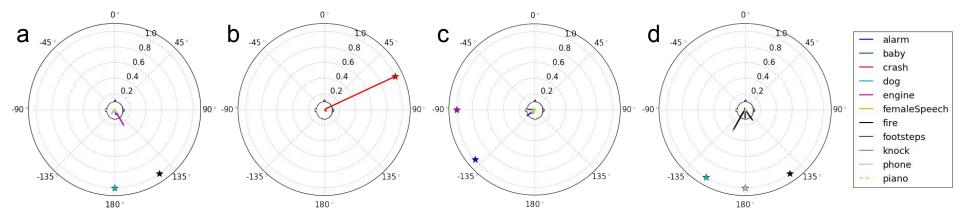
50

\_**\*** 

7x7

\*

### Joint sound identification and localisation





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### www.kahoot.it



# **Further Reading**

#### Books

Goodfellow, I., Bengio Y. and Courville A. (2016). Deep Learning. Book in preparation for MIT Press.

Nielsen, M.A (2015). Neural Networks and Deep Learning. Determination Press.

**Review papers** 

J. Schmidhuber. (2015). Deep Learning in Neural Networks: An Overview. Neural Networks.

#### Tutorials and code examples

Deep Learning Tutorials. Theano.

A bit of everything

http://deeplearning.net/



### References

Couprie, C., Farabet, C., Najman, L., & LeCun, Y. (2013). Indoor Semantic Segmentation using depth information. Iclr, 1–8. Retrieved from http://arxiv.org/pdf/1301.3572.pdf

Felzenszwalb, P. F., Girshick, R. B., McAllester, D., & Ramanan, D. (2010). Object detection with discriminatively trained part-based models. IEEE Transactions on Pattern Analysis and Machine Intelligence, 32(9), 1627–45.

Gatys, L. a, Ecker, A. S., & Bethge, M. (2015). A Neural Algorithm of Artistic Style. arXiv, 3–7. Retrieved from http://arxiv.org/abs/1508.06576

Karayev, S., Trentacoste, M., Han, H., Agarwala, A., Darrell, T., Hertzmann, A., & Winnemoeller, H. (2013). Recognizing Image Style, 1–20. Retrieved from http://arxiv.org/abs/1311.3715

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Christian Szegedy, Wojciech Zaremba, Ilya Sutskever, Joan Bruna, Dumitru Erhan, Ian Goodfellow, Rob Fergus. (2014). Intriguing properties of neural networks

Van Essen, D. C., & Gallant, J. L. (1994). Neural mechanisms of form and motion processing in the primate visual system. Neuron, 13(1), 1–10.