



>>> IMAGE PROCESSING AND COMPUTATIONAL PHOTOGRAPHY

SESSION 6: CUT

Oriol Pujol

TODAY'S LECTURE

- Analyzing images as graphs
- Application: Retargeting (Seam carving)
- Semi-automatic segmentation: Grab-cuts

RETARGETING

Context-aware image resizing. Remove seams (horizontal or vertical) with the least information.



SEMI-AUTOMATIC SEGMENTATION

Given a region of interest or line segments in the desired regions provided by the user Obtain a complete context-aware segmentation/partition into the desired object and background.

Techniques:

- Intelligent scissors
- Grab-cuts







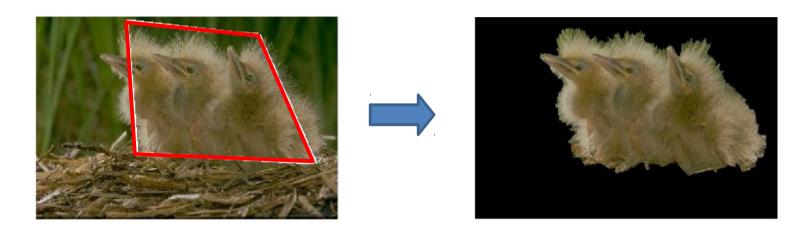


SUMMARY OF BIG IDEAS

- Treat image as a graph
 - Pixels are nodes
 - Between-pixel edge weights based on gradients
 - Sometimes per-pixel weights for affinity to foreground/background
- Good boundaries are a short path through the graph (Intelligent Scissors, Seam Carving)
- Good regions are produced by a low-cost cut (GrabCuts, Graph Cut Stitching)

SEMI-AUTOMATED SEGMENTATION

User provides imprecise and incomplete specification of region – your algorithm has to read his/her mind.



Key problems

- 1. What groups of pixels form cohesive regions?
- 2. What pixels are likely to be on the boundary of regions?
- 3. Which region is the user trying to select?

WHAT MAKES A GOOD REGION?

- Contains small range of color/texture
- Looks different than background
- Compact

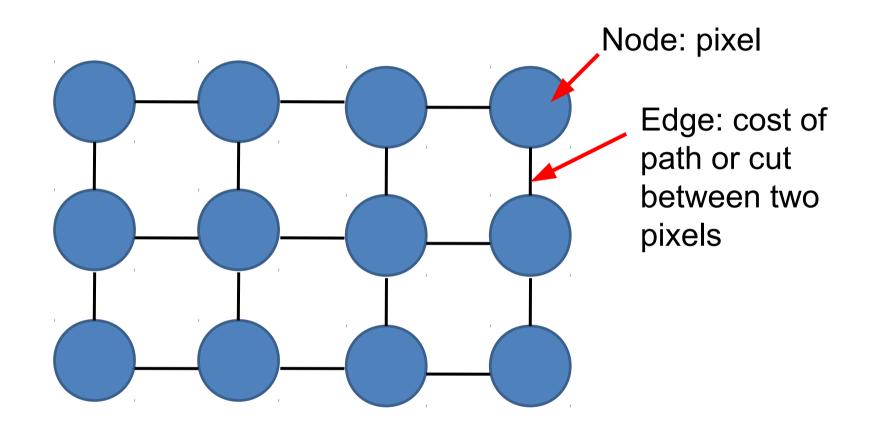


WHAT MAKES A GOOD REGION?

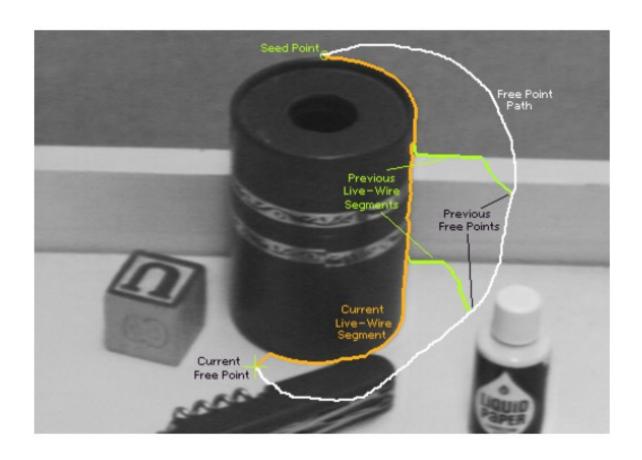
- High gradient along boundary
- Gradient in right direction
- Smooth



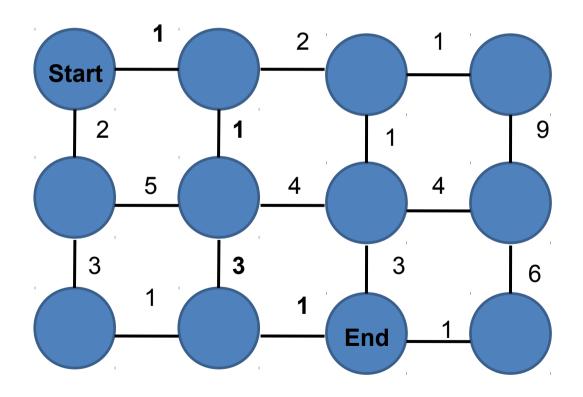
IMAGE AS A GRAPH



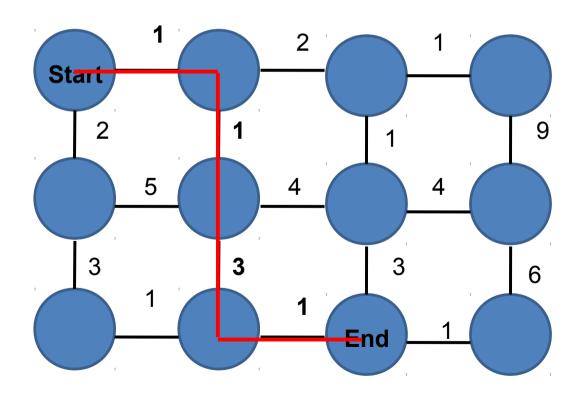
Mortenson and Barrett "Intelligent scissors for Image Composition" (SIGGRAPH 1995)



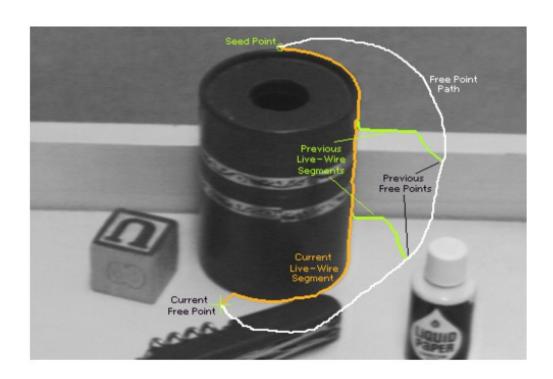
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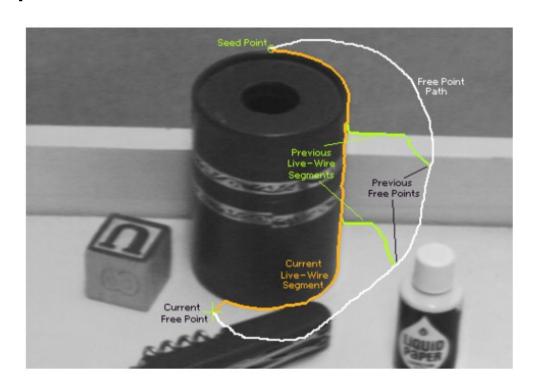


- Formulation: find good boundary between a free hand point and a seed point.
- Challenges
 - Minimize interaction time
 - Define what makes a good boundary
 - Efficiently find it



INTELLIGENT SCISSORS: METHOD

- 1. Define boundary cost between neighboring pixels
- 2. User specifies a starting point (seed)
- 3. Compute lowest cost from seed to each other pixel
- 4. Get path from seed to cursor, (we may choose a new seed), repeat.



INTELLIGENT SCISSORS: METHOD

- 1. Define boundary cost between neighboring pixels (GOAL: Follow edges)
 - a) Lower if edge is present (e.g., with edge(im, 'canny'))
 - b) Lower if gradient is strong
 - c) Lower if gradient is in direction of boundary



GRADIENT, EDGES, AND PATH COST





Gradient Magnitude

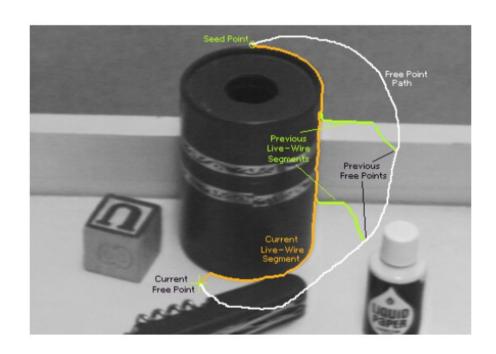


Edge Image



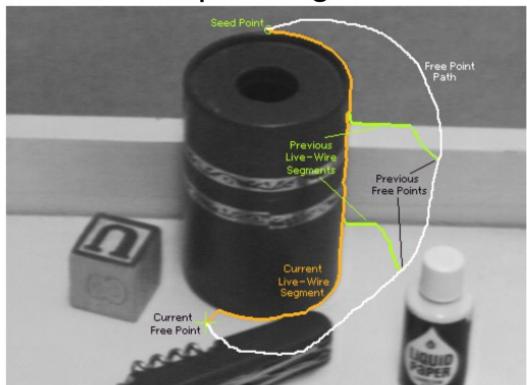
INTELLIGENT SCISSORS: METHOD

- Define boundary cost between neighboring pixels
- 2. User specifies a starting point (seed)
 - Snapping



INTELLIGENT SCISSORS: METHOD

- Define boundary cost between neighboring pixels
- 2. User specifies a starting point (seed)
- 3. Compute lowest cost from seed to each other pixel
 - Djikstra's shortest path algorithm



DJIKSTRA'S SHORTEST PATH ALGORITHM

Initialize, given seed s:

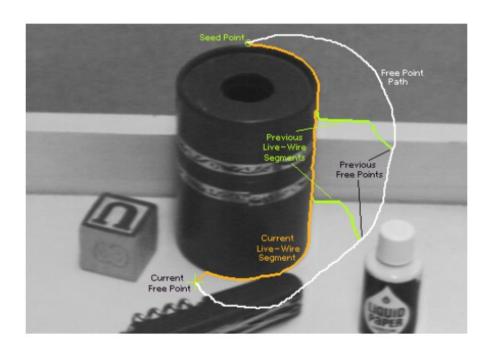
- Compute cost2(q, r) % cost for boundary from pixel q to neighboring pixel r
- cost(s) = 0 % total cost from seed to this point
- $A = \{s\}$ % set to be expanded
- **E** = { } % set of expanded pixels
- P(q) % pointer to pixel that leads to q

Loop while **A** is not empty

- 1. q = pixel in A with lowest cost
- 2. Add q to E
- 3. for each pixel r in neighborhood of q that is not in ${\bf E}$
 - a) cost_tmp = cost(q) + cost2(q,r)
 - b) if $(r \text{ is not in } \mathbf{A}) \text{ OR } (\text{cost_tmp} < \text{cost}(r))$
 - i. $cost(r) = cost_tmp$
 - ii. P(r) = q
 - iiiAdd r to A

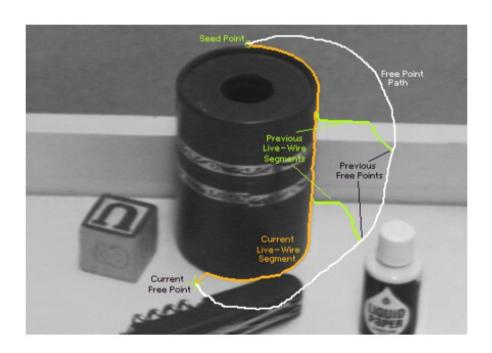
INTELLIGENT SCISSORS: METHOD

- Define boundary cost between neighboring pixels
- 2. User specifies a starting point (seed)
- 3. Compute lowest cost from seed to each other pixel
- 4. Get new seed, get path between seeds, repeat



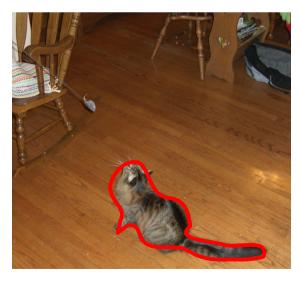
INTELLIGENT SCISSORS: IMPROVING INTERACTION

- 1. Snap when placing first seed
- 2. Automatically adjust to boundary as user drags
- 3. Freeze stable boundary points to make new seeds



Where will intelligent scissors work well, or have problems?



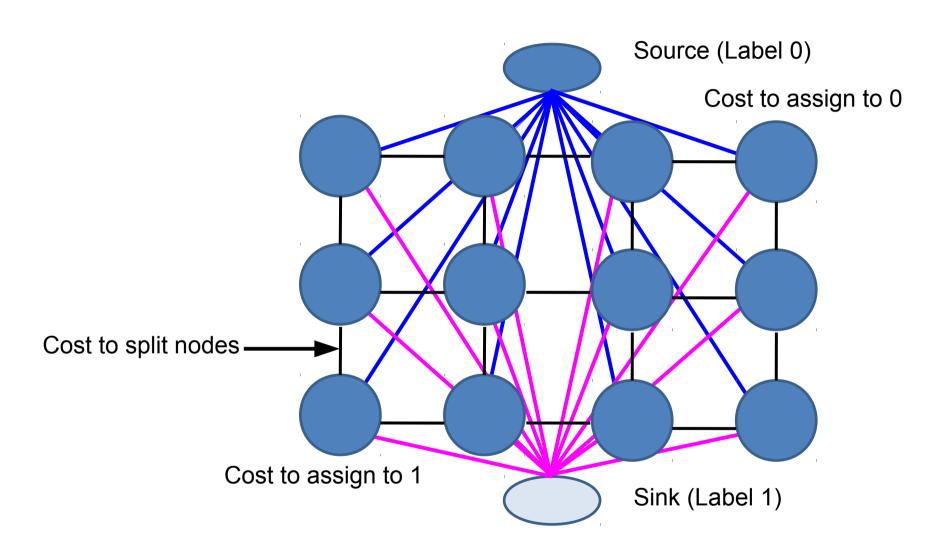


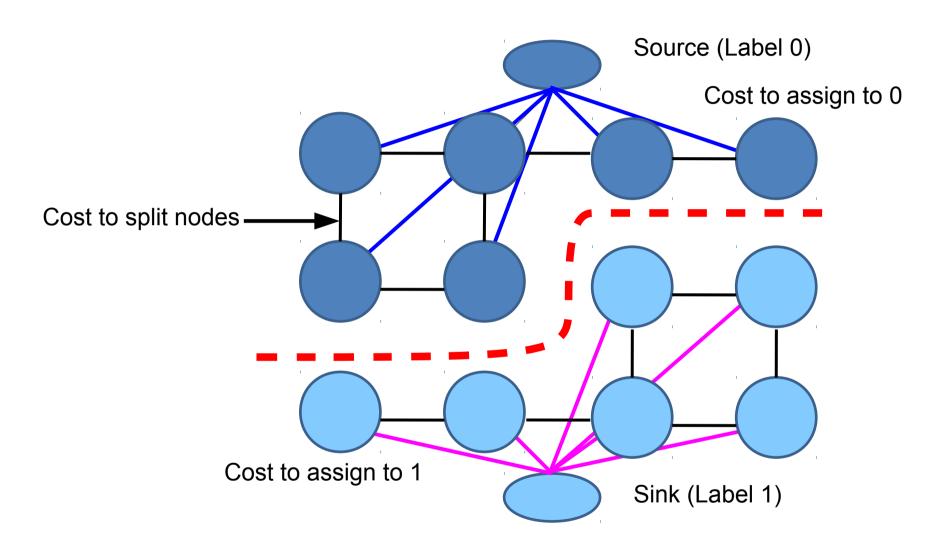


GRAB CUTS and GRAPH CUTS

Magic Wand **Intelligent Scissors** GrabCut User's input Result Regions Regions & Boundary Boundary

Do you remember Ford-Fulkerson MIN-CUT/MAX-FLOW algorithm? It is time to apply it.





Nowadays vision of graph based segmentation relies on the minimization of a potential or energy function.

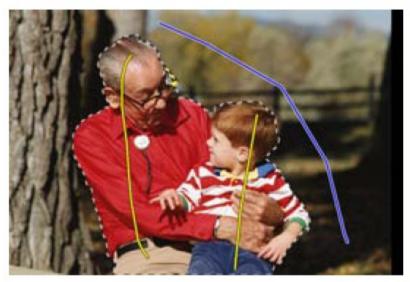
Formally, we are looking for the labels assignation that minimizes the potential function

$$l: \mathbf{R}^{M \times N} \to \{+1, -1\}^{M \times N}$$
$$L = \arg\min_{l} \sum_{p} \left(\psi(l(p), p) + \sum_{q \in \mathcal{N}(p)} \eta(p, q, l(p), l(q)) \right)$$

It is usually composed of two terms:

Unary potential: Defines the cost/probability/likelihood/confidence of a pixel belonging to one of the class labels.

Edge potential: Transition cost. Defines the cost of two adjacent pixels for changing the class label or staying with the same label. It encodes a smoothness constraint.













UNARY POTENTIAL

Given a certain user input for the target region (foreground) and the rest (background).

GOAL: Model both regions on a feature space.

HOW?

Feature space: Color space (e.g. sRGB, CIELab, ...)

Simple model: Gaussian model

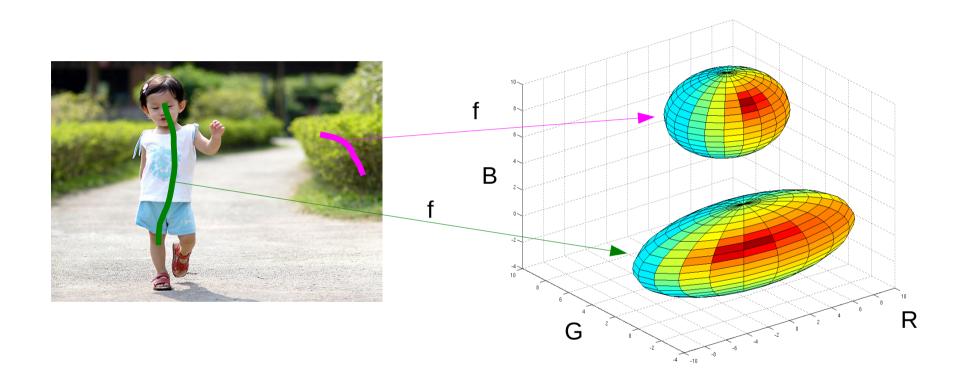
$$\phi(x,\mu,\Sigma) = \frac{1}{(2\pi)^{d/2} |\Sigma|^{1/2}} e^{-1/2(x-\mu)^T \Sigma^{-1}(x-\mu)}$$

Unknowns: We have to estimate the mean and covariance matrix.

Simplifying the covariance matrix:

$$\Sigma = \sigma^2 I$$

UNARY POTENTIAL: COLOR MODEL



What are your opinions with respect to this modeling?

UNARY POTENTIAL

Given a certain user input for the target region (foreground) and the rest (background).

GOAL: Model both regions on a feature space.

HOW?

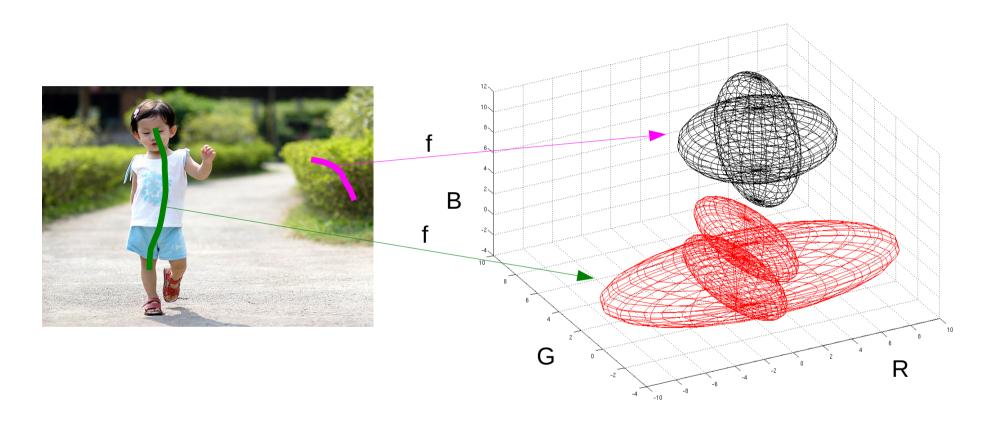
Feature space: Color space (e.g. sRGB, CIELab, ...)

A better model: Gaussian mixture model

$$\mathcal{M}(x) = \sum_{i} \alpha_{i} \phi(x, \mu_{i}, \Sigma_{i})$$

Unknowns: We have to jointly estimate the mean and covariance matrix for each of the composing Gaussian functions and the mixing weighing vector. One can address this problem using **Expectation Maximization (EM)** algorithm.

UNARY POTENTIAL: COLOR MODEL



What are your opinions with respect to this modeling?

EDGE POTENTIAL: SMOOTHNESS

No user input needed

GOAL: Model a smoothness constraint.

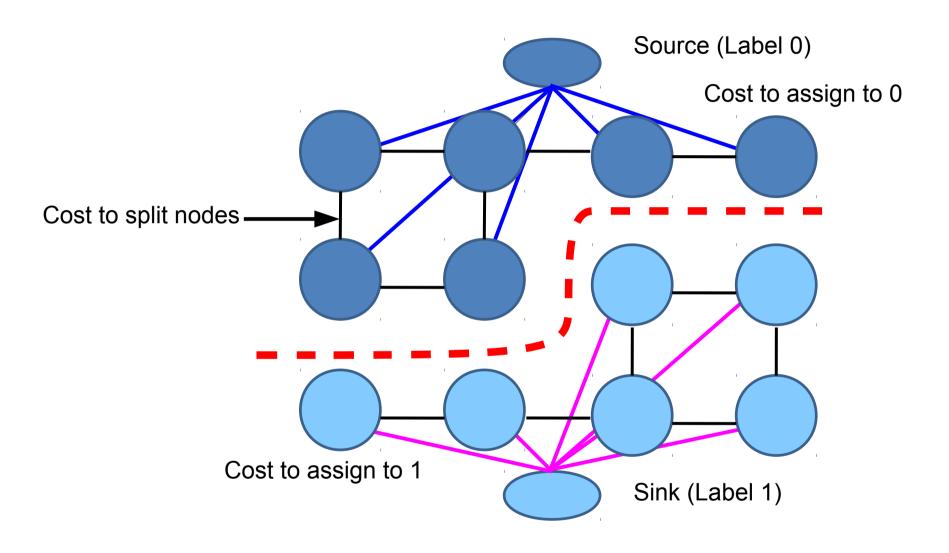
HOW?

Feature space: Color space (e.g. sRGB, CIELab, ...) **Model:** Enforce smoothness. Penalize differences of features on contiguous pixels.

$$\eta(p, q, l(p), l(q)) = e^{\omega \|f(p) - f(c)\|^2}$$

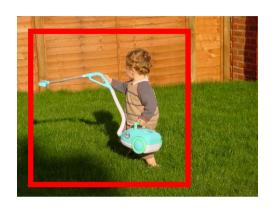
GRAPH CUTS SEGMENTATION ALGORITHM

- 1. Define graph
 - usually 4-connected or 8-connected
- 2. Set weights to foreground/background
 - Color histogram or mixture of Gaussians for background and foreground
- 3. Set weights for edges between pixels
- 4. Apply min-cut/max-flow algorithm
- 5. Return to 2, using current labels to compute foreground, background models



Which edges does min-cut cuts from the unary potential? And from the edge potential?

What is easy or hard about these cases for graphcut-based segmentation?





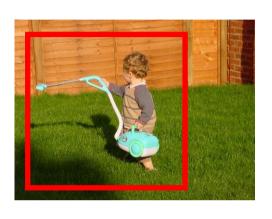








Easier examples













More difficult Examples

Camouflage & Low Contrast





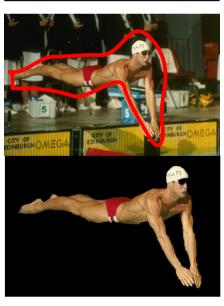
Fine structure





Harder Case





Limitations of Graph Cuts

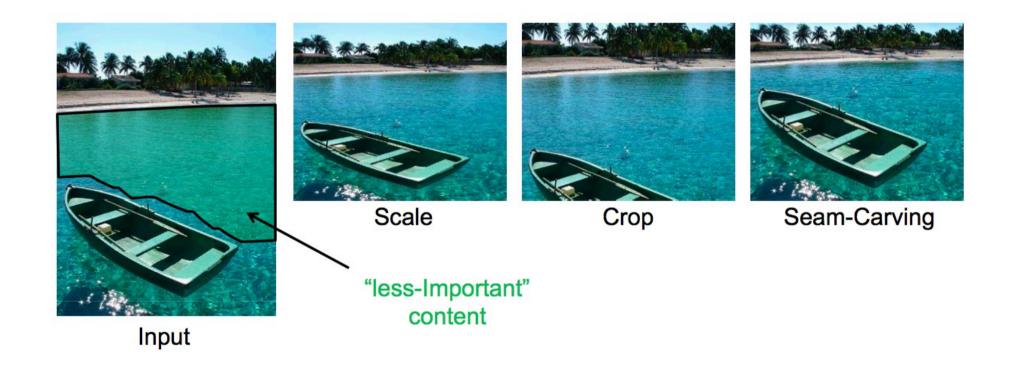
- Requires associative graphs
 - Connected nodes should prefer to have the same label

Is optimal only for binary problems

Problem statement:

- Input Image I nxm, and new size n'xm'
- Output Image I' of size n'xm' which will be "good representative" of the original image I
- To date, no clear definition, or measure, as to what a good representative is in this context!





Basic Idea: remove unimportant pixels from the image

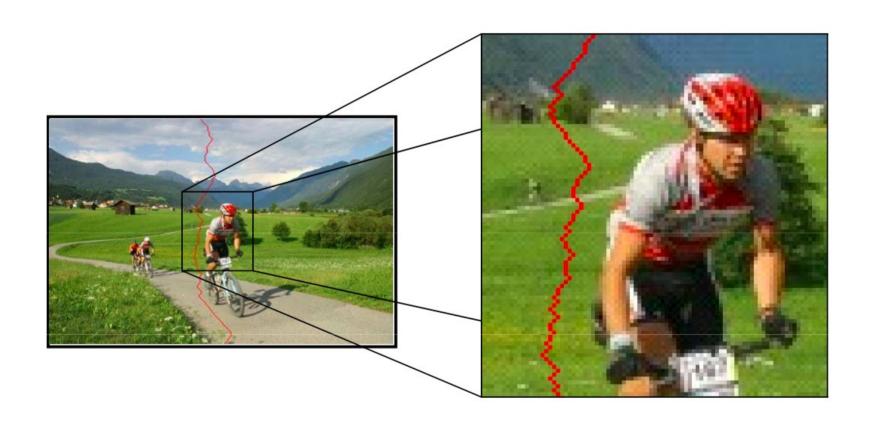
– Unimportant = pixels with less "energy"

$$E(I) = \left| \frac{\partial I}{\partial x} \right| + \left| \frac{\partial I}{\partial y} \right|$$

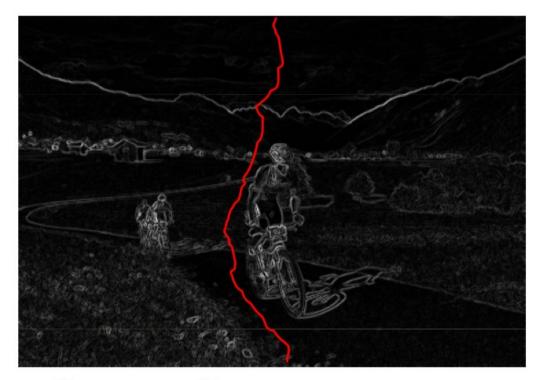
Intuition for gradient-based energy:

- Preserve strong contours
- Human vision more sensitive to edges so try remove content from smoother areas
- Simple, enough for producing some nice results

Seam: A set of contiguous pixels from top to down or left to right with one single pixel per column or row, respectively



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$$E(\mathbf{I}) = |\frac{\partial}{\partial x}\mathbf{I}| + |\frac{\partial}{\partial y}\mathbf{I}| \implies s^* = \arg\min_{S} E(s)$$

Finding the optimal seam with dynamic programing:

$$M(i,j) = E(i,j) + min(M(i-1,j-1), M(i-1,j), M(i-1,j+1))$$

Step 1: Fill the matrix

| 5 | 8 | 12 | 3 |
|---|---|----|---|
| 9 | 2 | 3 | 9 |
| 7 | 3 | 4 | 2 |
| 4 | 5 | 7 | 8 |

| 5 | 8 | 12 | 3 |
|---|-------|----|---|
| 9 | 2 + 5 | 3 | 9 |
| 7 | 3 | 4 | 2 |
| 4 | 5 | 7 | 8 |

Step 2: Backtracking (or storing while creating)

| 5 | 8 | 12 | 3 |
|----|----|----|----|
| 9 | 7 | 6 | 12 |
| 14 | 9 | 10 | 8 |
| 14 | 14 | 15 | 16 |
| | | | |

| 5 | 8 | 12 | 3 |
|----|----|----|----|
| 9 | 7 | 6 | 12 |
| 14 | 9 | 10 | 8 |
| 14 | 14 | 15 | 16 |

| 5 | 8 | 12 | 3 |
|----|----|----|----|
| 9 | 7 | 6 | 12 |
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| 5 | 8 | 12 | 3 |
|----|----|----|----|
| 9 | 7 | 6 | 12 |
| 14 | 9 | 10 | 8 |
| 14 | 14 | 15 | 16 |

SEAM CARVING: REMOVING OBJECTS





SEAM CARVING AND THE MISSING SHOE









SEAM CARVING AND IMAGE SYNTHESIS











SUMMARY OF BIG IDEAS

- Treat image as a graph
 - Pixels are nodes
 - Between-pixel edge weights based on gradients
 - Sometimes per-pixel weights for affinity to foreground/background
- Good boundaries are a short path through the graph (Intelligent Scissors, Seam Carving)
- Good regions are produced by a low-cost cut (GrabCuts, Seam Carving)