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## ABSTRACT

13 We study the representation of solutions of the three-dimensional quasi-  
14 geostrophic (QG) equations using Galerkin series with standard vertical  
15 modes, with particular attention to the incorporation of active surface buoy-  
16 ancy dynamics. We extend two existing Galerkin approaches (A and B) and  
17 develop a new Galerkin approximation (C). Approximation A, due to Flierl  
18 (1978), represents the streamfunction as a truncated Galerkin series and de-  
19 fines the potential vorticity (PV) that satisfies the inversion problem exactly.  
20 Approximation B, due to Tulloch and Smith (2009), represents the PV as a  
21 truncated Galerkin series and calculates the streamfunction that satisfies the  
22 inversion problem exactly. Approximation C, the true Galerkin approxima-  
23 tion for the QG equations, represents both streamfunction and PV as trun-  
24 cated Galerkin series, but does not satisfy the inversion equation exactly. The  
25 three approximations are fundamentally different unless the boundaries are  
26 isopycnal surfaces. We discuss the advantages and limitations of approxi-  
27 mations A, B, and C in terms of mathematical rigor and conservation laws,  
28 and illustrate their relative efficiency by solving linear stability problems with  
29 nonzero surface buoyancy. With moderate number of modes, B and C have  
30 have superior accuracy than A at high wavenumbers. Because B lacks conser-  
31 vation of energy, we recommend approximation C for constructing solutions  
32 to the surface-active QG equations using Galerkin series with standard verti-  
33 cal modes.

# 34 1. Introduction

35 Recent interest in upper-ocean dynamics and sub-mesoscale turbulence has focussed attention  
 36 on surface geostrophic dynamics and the role of surface buoyancy variations. A main issue is  
 37 the representation of active surface buoyancy by finite vertical truncations of the quasigeostrophic  
 38 (QG) equations. Standard multi-layer (e.g., Pedlosky 1987) and modal approximations (e.g.,  
 39 Flierl 1978) assume that there is no variation of buoyancy on the surfaces.

40 Only few attempts have being made to represent both surface active and interior dynamics in  
 41 the QG equations. The pioneering work by Tulloch and Smith (2009) developed a “two-mode  
 42 two-surface” model that represents the surface dynamics exactly and approximates the interior  
 43 dynamics using the barotropic and first baroclinic modes. The interaction of surface and interior  
 44 dynamics motivated the development a new set of vertical modes that simultaneously diagonalize  
 45 energy and a linear combination of enstrophy and surface buoyancy variance (Smith and Vanneste  
 46 2013). Other studies of the interaction of surface and interior dynamics avoid vertical modes and  
 47 use instead finite-difference schemes (Rouillet et al. 2012) or idealize the interior potential vorticity  
 48 as a delta-function sheet (Callies et al. 2015).

49 Here we explore the representation of surface and interior dynamics using the familiar vertical  
 50 modes of physical oceanography. These “standard modes”, denoted here by  $p_n(z)$ , are defined by  
 51 the Sturm-Liouville eigenproblem

$$\frac{d}{dz} \frac{f_0^2}{N^2} \frac{dp_n}{dz} = -\kappa_n^2 p_n, \quad (1)$$

52 with homogeneous Neumann boundary conditions at the bottom ( $z = z^-$ ) and top ( $z = z^+$ ) surfaces  
 53 of the domain:

$$\frac{dp_n}{dz}(z^\pm) = 0. \quad (2)$$

54 In (1)  $N(z)$  is the buoyancy frequency and  $f_0$  is the Coriolis parameter. The eigenvalue  $\kappa_n$  in  
 55 (1) is the deformation wavenumber of the  $n$ 'th mode. With normalization, the modes satisfy the  
 56 orthogonality condition

$$\frac{1}{h} \int_{z^-}^{z^+} p_n p_m dz = \delta_{mn}, \quad (3)$$

57 where  $h \stackrel{\text{def}}{=} z^+ - z^-$  is the depth. The barotropic mode is  $p_0 = 1$  and  $\kappa_0 = 0$ .

58 The modes defined by the eigenproblem (1) and (2) provide a fundamental basis for representing  
 59 solutions of both the primitive and quasigeostrophic equations as a linear combination of  $\{p_n\}$  (Gill  
 60 1982; Pedlosky 1987; Vallis 2006; Ferrari and Wunsch 2010; LaCasce 2012). In fact, the set  $\{p_n\}$   
 61 is mathematically complete and can be used to represent *any* field with finite square integral,

$$\int_{z^-}^{z^+} f^2 dz < \infty. \quad (4)$$

62 Even if the function  $f(z)$  has nonzero derivative at  $z^\pm$ , or internal discontinuities, its representation  
 63 as a linear combination of the basis functions  $\{p_n\}$  converges in  $L^2(z^-, z^+)$  i.e., the integral of the  
 64 squared error goes to zero as the number of basis functions increases (e.g., Hunter and Nachter-  
 65 gaele 2001, ch. 10). In quasigeostrophic dynamics both the streamfunction  $\psi$  and the potential  
 66 vorticity (PV)  $q$  satisfy the requirement (4) and thus both  $\psi$  and  $q$  can be effectively represented  
 67 by linearly combining  $\{p_n\}$ .

68 Despite the rigorous assurance of completeness in the previous paragraph, the utility of  $\{p_n\}$   
 69 for problems with nonuniform surface buoyancy has been questioned by several authors (e.g.,  
 70 Lapeyre 2009; Rouillet et al. 2012; Smith and Vanneste 2013). These authors argue that the ho-  
 71 mogeneous boundary conditions in (2) are incompatible with nonzero surface buoyancy and that  
 72 representation of the streamfunction  $\psi$  as a linear combination of  $\{p_n\}$  is useless if  $\psi_z$  is nonzero  
 73 on the surfaces.

74 The aim of this paper is to obtain a good Galerkin approximation to solutions of the QG equation  
75 with nonzero surface buoyancy using the familiar basis  $\{p_n\}$ . We show that that both the inversion  
76 problem *and* evolutionary dynamics can be handled using  $\{p_n\}$  to represent the streamfunction.  
77 As part of this program we revisit and extend two existing modal approximations (Flierl 1978;  
78 Tulloch and Smith 2009), and develop a new Galerkin approximation. We discuss the relative  
79 merit of the three approximations in terms of their mathematical rigor and conservation laws, and  
80 illustrate their efficiency and caveats by solving linear stability problems with nonzero surface  
81 buoyancy.

82 Using concrete examples, we show that the concerns expressed by earlier authors regarding the  
83 suitability of the standard modes  $\{p_n\}$  are over-stated: even with nonzero surface buoyancy, the  
84 Galerkin expansion of the streamfunction  $\psi$  in terms of  $\{p_n\}$  converges absolutely and uniformly  
85 with no Gibbs phenomena, and the same is true for the potential vorticity  $q$ . A modest number of  
86 terms provides a good approximation to  $\psi$  and  $q$  throughout the domain, including on the top and  
87 bottom boundaries. In other words, the surface streamfunction can be expanded in terms of  $\{p_n\}$   
88 and, with enough modes, this representation can then be used to accurately calculate the advection  
89 of nonzero surface buoyancy. In section 5 we illustrate this procedure by solving the classic Eady  
90 problem using the basis  $\{p_n\}$  for the streamfunction.

## 91 **2. The exact system**

92 In this section we summarize the basic properties of the QG system. For a detailed derivation  
93 see Pedlosky (1987).

94 *a. Formulation*

95 The streamfunction is denoted  $\psi(x, y, z, t)$  and we use the following notation.

$$u = -\psi_y, \quad v = \psi_x, \quad \vartheta = \left(\frac{f_0}{N}\right)^2 \psi_z. \quad (5)$$

96 The variable  $\vartheta$  is related to the buoyancy by  $b = N^2 \vartheta / f_0$ . The QG potential vorticity (QGPV)  
97 equation is

$$\partial_t q + J(\psi, q) + \beta v = 0, \quad (6)$$

98 where the potential vorticity is

$$q = (\Delta + L) \psi, \quad (7)$$

99 with

$$\Delta \stackrel{\text{def}}{=} \partial_x^2 + \partial_y^2, \quad \text{and} \quad L \stackrel{\text{def}}{=} \partial_z \left(\frac{f_0}{N}\right)^2 \partial_z. \quad (8)$$

100 Also in (6), the Jacobian is  $J(A, B) \stackrel{\text{def}}{=} \partial_x A \partial_y B - \partial_y A \partial_x B$ .

101 The boundary conditions at the top ( $z = z^+$ ) and bottom ( $z = z^-$ ) are that  $w = 0$ , or equivalently

$$@z = z^\pm : \quad \partial_t \vartheta^\pm + J(\psi^\pm, \vartheta^\pm) = 0. \quad (9)$$

102 Above we have used the superscripts  $+$  and  $-$  to denote evaluation at  $z^+$  and  $z^-$  e.g.,  $\psi^+ =$   
103  $\psi(x, y, z^+, t)$ .

104 *b. Quadratic conservation laws*

105 In the absence of sources and sinks, the exact QG system has four quadratic conservation laws:  
106 energy, potential enstrophy, and surface buoyancy variance at the two surfaces (e.g., Pedlosky  
107 1987; Vallis 2006). Throughout we assume horizontal periodic boundary conditions.

The well-known energy conservation law is

$$\frac{d}{dt} \underbrace{\int \frac{1}{2} |\nabla \psi|^2 + \frac{1}{2} \left( \frac{f_0}{N} \right)^2 (\partial_z \psi)^2 dV}_{\stackrel{\text{def}}{=} E} = 0. \quad (10)$$

The total energy is  $\rho_0 E$ , where  $\rho_0$  is a reference density.

If  $\beta = 0$  then there are many quadratic potential enstrophy invariants: the volume integral of  $q^2 A(z)$ , with  $A(z)$  an arbitrary function of the vertical coordinate, is conserved. The choice  $A(z) = \delta(z - z_*)$  reduces to conservation of the surface integral of  $q^2$  at any level  $z_*$ .

Charney (1971) noted that, in a doubly periodic domain, nonzero  $\beta$  destroys all these quadratic potential enstrophy conservation laws, including the conservation of potential enstrophy defined simply as the volume integral of  $q^2$ . Multiplying the QGPV equation (6) by  $q$ , and integrating by parts, we obtain

$$\frac{d}{dt} \int \frac{1}{2} q^2 dV + \beta \int [v \vartheta]_{z^-}^{z^+} dS = 0. \quad (11)$$

The potential enstrophy equation (11) is the finite-depth analog of equation (13) in Charney's paper. To make progress Charney assumed  $\vartheta = 0$  at the ground. But the  $\beta$ -term on the right of (11) can be eliminated by cross-multiplying the QGPV equation (6) evaluated at the surfaces  $z^\pm$  with the boundary conditions (9), and combining with (11). Thus, in a doubly periodic domain, nonzero  $\beta$  selects a uniquely conserved potential enstrophy from the infinitude of  $\beta = 0$  potential enstrophy conservation laws:

$$\frac{d}{dt} \underbrace{\int \frac{1}{2} q^2 dV - \int q^+ \vartheta^+ - q^- \vartheta^- dS}_{\stackrel{\text{def}}{=} Z} = 0. \quad (12)$$

With  $\beta \neq 0$  the surface contributions in (12) are required to form a conserved quadratic quantity involving  $q^2$ . Notice that  $Z$  is not sign-definite. To our knowledge, the conservation law in (12) is previously unremarked.

Finally, in addition to  $E$  and  $Z$ , the surface buoyancy variance is conserved on each surface

$$\frac{d}{dt} \int \frac{1}{2} (\vartheta^\pm)^2 dS = 0. \quad (13)$$

Thus, with  $\beta \neq 0$ , the QG model has four quadratic conservation laws:  $E$ ,  $Z$  and the buoyancy variance at the two surfaces.

### 3. Galerkin approximation using standard vertical modes

A straightforward approach is to represent the streamfunction by linearly combining the first  $N + 1$  vertical modes. The mean square error in this approximation is

$$\text{err}_\psi(a_0, a_1, \dots, a_N) \stackrel{\text{def}}{=} \frac{1}{h} \int_{z^-}^{z^+} \left( \psi - \sum_{n=0}^N a_n p_n \right)^2 dz. \quad (14)$$

We use a roman font, and context, to distinguish the truncation index  $N$  in (14) from the buoyancy frequency  $N(z)$ . The coefficients  $a_0$  through  $a_N$  are determined to minimize  $\text{err}_\psi$ , and thus one obtains the Galerkin approximation  $\psi_N^G$  to the exact streamfunction:

$$\psi_N^G(x, y, z, t) \stackrel{\text{def}}{=} \sum_{n=0}^N \check{\psi}_n(x, y, t) p_n(z), \quad (15)$$

where the coefficients in the sum above are

$$\check{\psi}_n(x, y, t) \stackrel{\text{def}}{=} \frac{1}{h} \int_{z^-}^{z^+} \psi p_n dz. \quad (16)$$

Throughout we use the superscript  $\check{\phantom{x}}$  to denote a Galerkin coefficient defined via projection of a field onto a vertical mode.

In complete analogy with the streamfunction, one can also develop an  $(N + 1)$ -mode Galerkin approximation to the PV:

$$q_N^G(x, y, z, t) \stackrel{\text{def}}{=} \sum_{n=0}^N \check{q}_n(x, y, t) p_n(z), \quad (17)$$

with coefficients

$$\check{q}_n \stackrel{\text{def}}{=} \frac{1}{h} \int_{z^-}^{z^+} q p_n dz. \quad (18)$$



141 The construction of the Galerkin approximation  $q_N^G$  above minimizes a mean square error  $\text{err}_q$   
 142 defined in analogy with (14).

143 Now recall that the exact  $\psi$  and  $q$  are related by the elliptic “inversion problem”:

$$(\triangle + L)\psi = q, \quad (19)$$

144 with boundary conditions at  $z^\pm$ :

$$\left(\frac{f_0}{N}\right)^2 \psi_z = \vartheta^\pm. \quad (20)$$

145 The Galerkin approximations in (15) through (18) are defined independently of the information  
 146 in (19) and (20). The relationship between the Galerkin coefficients  $\check{q}_n$  and  $\check{\psi}_n$  is obtained by  
 147 multiplying (19) by  $\frac{1}{h}p_n(z)$  and integrating over the depth. Noting the intermediate result

$$\frac{1}{h} \int_{z^-}^{z^+} p_n L \psi \, dz = \frac{1}{h} [p_n^+ \vartheta^+ - p_n^- \vartheta^-] - \kappa_n^2 \check{\psi}_n, \quad (21)$$

148 we obtain

$$\check{q}_n = \triangle_n \check{\psi}_n + \underbrace{\frac{1}{h} (p_n^+ \vartheta^+ - p_n^- \vartheta^-)}_{\text{surface terms}}, \quad (22)$$

149 where  $\triangle_n$  is the  $n$ 'th mode Helmholtz operator

$$\triangle_n \stackrel{\text{def}}{=} \triangle - \kappa_n^2. \quad (23)$$

150 The relation in (22) is the key to a good Galerkin approximation to surface-active quasigeostrophic  
 151 dynamics.

152 Term-by-term differentiation of the  $\psi_N^G$ -series in (15) does not give the  $q_N^G$  series in (17) unless  
 153  $\vartheta^\pm = 0$ . In other words, term-by-term differentiation does not produce the correct relation (22)  
 154 between  $\check{q}_n$  and  $\check{\psi}_n$ . Thus the Galerkin truncated PV and the Galerkin truncated streamfunction do  
 155 not satisfy the inversion boundary value problem exactly

$$(\triangle + L)\psi_N^G \neq q_N^G. \quad (24)$$

156 Despite (24), the truncated series  $\psi_N^G$  and  $q_N^G$  are the best least-squares approximations to  $\psi$  and  $q$ .

157 Notice that, in analogy with the Galerkin approximations for  $q$  and  $\psi$ ,

$$\check{\delta}_n^+ = \frac{1}{h} p_n^+ \quad \text{and} \quad \check{\delta}_n^- = \frac{1}{h} p_n^-, \quad (25)$$

158 where

$$\delta_N^{+G}(z) = \sum_{n=0}^N \check{\delta}_n^+ p_n \quad \text{and} \quad \delta_N^{-G}(z) = \sum_{n=0}^N \check{\delta}_n^- p_n, \quad (26)$$

159 are finite approximations to distributions  $\delta(z - z^\pm)$  at the surfaces. Of course, these surface  $\delta$ -  
 160 distributions do not satisfy the  $L^2$  convergence condition in (4) and thus the series in (26) only  
 161 converge in a distributional sense (e.g., Hunter and Nachtergaele 2001). For instance, if  $f$  satisfies  
 162 the  $L^2$  convergence condition in (4), then

$$\int_{z^-}^{z^+} f(z) \delta_N^{+G}(z) dz \rightarrow \int_{z^-}^{z^+} f(z) \delta(z - z^+) dz = f(z^+), \quad (27)$$

163 as  $N \rightarrow \infty$ . Thus, in that limit,

$$(\triangle + L) \psi_N^G \rightharpoonup q - \delta(z - z^+) \vartheta^+ + \delta(z - z^-) \vartheta^-, \quad (28)$$

164 where  $\rightharpoonup$  denotes distributional convergence. The right-hand-side of (28) is the Brethertonian  
 165 modified potential vorticity (Bretherton 1966) with the boundary conditions incorporated as PV  
 166 sheets. To illustrate (24) and (28) we present an elementary example that is relevant to our  
 167 discussion of the Eady problem in section 5.

168 *An elementary example: the Eady basic state*

169 As an example, consider the case with constant buoyancy frequency  $N$ . We use nondimensional  
 170 units so that the surfaces are at  $z^- = -1$  and  $z^+ = 0$ . The standard vertical modes are  $p_0 = 1$  and,  
 171 for  $n \geq 1$

$$p_n = \sqrt{2} \cos(n\pi z), \quad (29)$$

172 with  $\kappa_n = n\pi$ .

173 We consider the basic state of the Eady problem with streamfunction

$$\psi = -\underbrace{(1+z)}_U y, \quad (30)$$

174 and zero interior PV  $q = 0$  and  $\beta = 0$ . The surface buoyancies are  $\vartheta^\pm = -y$ .

175 The Galerkin expansion of the PV  $q = 0$  is exact:  $\check{q}_N = 0$  and therefore  $q_N^G = 0$ . The truncated

176 Galerkin expansion of  $\psi$  follows from either (16) or (22) and is

$$\psi_N^G = -\underbrace{\left[ \frac{1}{2}p_0 + 2\sqrt{2} \left( \frac{p_1}{\pi^2} + \frac{p_3}{(3\pi)^2} + \cdots + \frac{p_N}{(N\pi)^2} \right) \right]}_{U_N^G} y. \quad (31)$$

177 (We assume that  $N$  is odd, so that the last term in the truncated series is as above.) Despite the  
 178 nonzero derivative of  $\psi$  at the boundaries, the series in (31) is absolutely and uniformly convergent  
 179 on the closed interval  $-1 \leq z \leq 0$ . The  $N^{-2}$  behavior of the series (31) ensures uniform conver-  
 180 gence, e.g., using the M-test (Hunter and Nachtergaele 2001). There are no Gibbs oscillations and  
 181 a modest number of terms provides a good approximation to the base velocity  $U$  (Figure 1a). All  
 182 these desirable properties are lost if we differentiate (31) with respect to  $z$ .

183 Thus, to illustrate (24) and (28), notice that if one attempts to calculate the Eady PV, namely  
 184  $q = 0$ , by direct differentiation of (31), one obtains

$$(\triangle + L) \psi_N^G = 2\sqrt{2} (p_1 + p_3 + \cdots p_N) y \quad (32)$$

$$= 2 \frac{\sin[(N+1)\pi z]}{\sin(\pi z)} y. \quad (33)$$

185 The series (32) does not converge in a pointwise sense and the partial sum is violently oscillatory  
 186 as  $N \rightarrow \infty$ . However, in a distributional sense (Hunter and Nachtergaele 2001, ch. 11), the exact  
 187 sum in (33) does converge to  $\delta$ -distributions on the boundaries; see figures 1(b) and 1(c). These  
 188 boundary  $\delta$ -distributions are the Brethertonian PV sheets (Bretherton 1966). To some extent,  
 189 which we investigate in section 5(a), the series (32) is rescued by this Brethertonian interpretation.

Of course the correct Galerkin approximation to the Eady PV  $q = 0$  is the splendidly convergent series  $0 = 0p_0 + 0p_1 + \dots$ , which is obtained if one uses either (18) or (22) to obtain  $\check{q}_n = 0$ . This seemingly trivial example illustrates potentially confusing issues which arise if one differentiates a Galerkin approximation: the standard modes provide good representations of  $\psi$  and  $q$ , even if  $\psi_z$  is nonzero on the boundaries. The problem is that differentiating the  $\psi$ -series to produce a  $q$ -series does not produce the Galerkin approximation to  $q$ .

#### 4. Three approximations

In (24) we noted that the Galerkin approximations to  $\psi$  and  $q$  do not exactly satisfy the inversion relation. To address this error there are at least three different approximations one can make. The three approximations are equivalent when  $\vartheta^\pm = 0$ . In the next three sub-sections, we provide a detail description of each approximation. After testing, we recommend approximation C as the most reliable approximation using standard vertical modes.

##### a. Approximation A

Approximation A uses the truncated series  $\psi_N^G$  in (15) as a least-squares Galerkin approximation to the streamfunction  $\psi$ . A does not use the Galerkin approximation for  $q$ . Instead, the approximate PV,  $q_N^A(x, y, z, t)$ , is *defined* so that the interior inversion relation is satisfied exactly:

$$q_N^A \stackrel{\text{def}}{=} (\triangle + L) \psi_N^G. \quad (34)$$

This is the approximation introduced by Flierl (1978) in a context without surface buoyancy, and it is now regarded as the standard in physical oceanography. Note that  $q_N^A$  in (34) is not the least-squares approximation to the exact  $q$ . Instead the series  $q_N^A$  is obtained using term-by-term differentiation of the series  $\psi_N^G$ . The example surrounding (32) shows that with nonzero surface buoyancy, the approximation  $q_N^A$  is strongly oscillatory in the interior of the domain and approaches

211 the Brethertonian PV on the right of (28) as  $N \rightarrow \infty$ . The rapid interior oscillation of  $q_N^A$  is a  
 212 spurious creation of term-by-term differentiation. Later, in section 5, these spurious oscillations  
 213 will produce significant errors in the solution of the Eady stability problem.

214 Following Flierl (1978), in approximation A the N-mode approximate PV is defined via (34)  
 215 and, using the modal representation for  $\psi_N^G$  in (15), this is equivalent to

$$q_N^A \stackrel{\text{def}}{=} \sum_{n=0}^N \Delta_n \check{\psi}_n(x, y, t) p_n(z), \quad (35)$$

216 where  $\Delta_n$  is the Helmholtz operator in (23). Following the appendix of Flierl (1978), one can  
 217 use Galerkin projection of the nonlinear evolution equation (6) onto the modes  $p_n$  to obtain  $N + 1$   
 218 evolution equations for the coefficients  $\check{\psi}_n$ :

$$\partial_t \Delta_n \check{\psi}_n + \sum_{m=0}^N \sum_{s=0}^N \Xi_{nms} J(\check{\psi}_m, \Delta_s \check{\psi}_s) + \beta \partial_x \check{\psi}_n = 0, \quad (36)$$

219 where

$$\Xi_{nms} \stackrel{\text{def}}{=} \frac{1}{h} \int_{z^-}^{z^+} p_n p_m p_s dz. \quad (37)$$

220 Note that  $\Xi_{nms}$  cannot be computed exactly except in cases with simple buoyancy frequency pro-  
 221 files. But it suffices to compute  $\Xi_{nms}$  to high accuracy, e.g. using Gaussian quadrature.

222 Flierl (1978) implicitly assumed that  $\vartheta^+ = \vartheta^- = 0$ , so that the surface terms in (22) vanish and  
 223 then there is no difference between  $q_N^A$  and  $q_N^G$ . But in general, with nonzero surface buoyancy,  
 224 we can append evolution equations for  $\vartheta^+$  and  $\vartheta^-$  to approximation A. That is, in addition to the  
 225  $N + 1$  modal equations in (36), we also have

$$\partial_t \vartheta^\pm + \sum_{n=0}^N p_n^\pm J(\check{\psi}_n, \vartheta^\pm) = 0. \quad (38)$$

226 Above we have evaluated the  $\psi$ -series (15) at  $z^\pm$  to approximate  $\psi^\pm$  in the surface boundary  
 227 conditions. This approach is not satisfactory because the resulting surface buoyancy equations  
 228 (38) are dynamically passive i.e.,  $\vartheta^+$  and  $\vartheta^-$  do not affect the interior evolution equations in (36).

Approximation A has the well-known energy conservation law

$$\frac{d}{dt} \sum_{n=0}^N \int \frac{1}{2} (\nabla \check{\psi}_n)^2 + \frac{1}{2} \kappa_n^2 \check{\psi}_n^2 dS = 0. \quad (39)$$

To obtain the energy analogous to  $E$  in (10), the modal sum above is multiplied by the depth  $h$ .

Approximation A also has the potential enstrophy conservation law,

$$\frac{d}{dt} \sum_{n=0}^N \int \frac{1}{2} (\Delta_n \check{\psi}_n)^2 dS = 0. \quad (40)$$

But the analog of the exact potential enstrophy (12) is not conserved by A (nor by B and C below).

Finally, with the surface equations in (38), approximation A also conserves surface buoyancy variance as in (13).

### *b. Approximation B*

Approximation B begins with the observation that the exact solution of the inversion problem in (19) and (20) can be decomposed as

$$\psi = \psi^I + \psi^S \quad (41)$$

where  $\psi^I(x, y, z, t)$  is the “interior streamfunction” and  $\psi^S(x, y, z, t)$  is the “surface streamfunction” (Lapeyre and Klein 2006; Tulloch and Smith 2009).

The surface streamfunction  $\psi^S(x, y, z, t)$  is defined as the solution of the boundary value problem

$$(\Delta + L) \psi^S = 0, \quad (42)$$

with inhomogeneous Neumann boundary conditions

$$\left( \frac{f_0}{N} \right)^2 \partial_z \psi^S(z^\pm) = \vartheta^\pm. \quad (43)$$

The interior streamfunction  $\psi^I(x, y, z, t)$  is defined as the solution of the boundary value problem

$$(\Delta + L) \psi^I = q, \quad (44)$$

243 with homogeneous Neumann boundary conditions

$$\left(\frac{f_0}{N}\right)^2 \partial_z \psi^I(z^\pm) = 0. \quad (45)$$

244 Approximation B assumes that one can solve the surface problem in (42) and (43) without  
 245 resorting to truncated series. For instance, with constant or exponential stratifications one can find  
 246 closed-form, exact expressions for  $\psi^S$  (Tulloch and Smith 2009; LaCasce 2012). Approximation  
 247 B requires that the two unknown Dirichlet boundary-condition functions  $\psi^{S\pm} = \psi^S(z^\pm)$  can be  
 248 obtained efficiently from specified Neumann boundary-condition functions  $\vartheta^+$  and  $\vartheta^-$ . The Eady  
 249 problem, discussed below in section 5, is a prime example in which one can obtain this Neumann-  
 250 to-Dirichlet map.

251 Once  $\psi^S$  is in hand, the approximate streamfunction is

$$\psi_N^B = \psi_N^I + \psi^S, \quad (46)$$

252 where the approximate interior streamfunction  $\psi_N^I$  is obtained by solving the interior inversion  
 253 problem (44) with the right hand side replaced by the N-mode Galerkin approximation  $q_N^G$  defined  
 254 in (17) and (18). The two-mode two-surface model of Tulloch & Smith (2009) is the case  $N = 1$ .  
 255 The exact solution of the approximate interior inversion problem is

$$\psi_N^I = \sum_{n=0}^N \check{\psi}_n^I(x, y, t) p_n(z), \quad (47)$$

256 where

$$\check{\psi}_n^I \stackrel{\text{def}}{=} \frac{1}{h} \int_{z^-}^{z^+} p_n \psi^I dz, \quad \text{and} \quad \triangle_n \check{\psi}_n^I = \check{q}_n. \quad (48)$$

257 To obtain the approximation B evolution equations we introduce the streamfunction (46) into  
 258 the QGPV equation (6) and project onto mode  $n$  to obtain

$$\begin{aligned} \partial_t \triangle_n \check{\psi}_n + \sum_{m=0}^N \sum_{s=0}^N \Xi_{nms} J(\check{\psi}_m^I, \triangle_s \check{\psi}_s^I) + \beta \partial_x (\check{\psi}_n^I + \check{\psi}_n^S) \\ + \sum_{s=0}^N \frac{1}{h} \int_{z^-}^{z^+} p_n p_s J(\psi^S, \triangle_s \check{\psi}_s^I) dz = 0, \end{aligned} \quad (49)$$

259 with  $\Xi_{nms}$  defined in (37). Approximation B assumes that the remaining integral on the second  
 260 line of (49) can be evaluated exactly. This is only possible for particular models of the  $N(z)$  (e.g.,  
 261 constant buoyancy-frequency profiles). In practice, however, it may suffice to compute the integral  
 262 on the second line (49) very accurately, e.g. using Gaussian quadrature.

263 The evolution equations for approximation B are completed with the addition of buoyancy-  
 264 advection at the surfaces

$$\partial_t \vartheta^\pm + J(\psi^{S^\pm}, \vartheta^\pm) + \sum_{n=0}^N p_n^\pm J(\check{\psi}_n^I, \vartheta^\pm) = 0. \quad (50)$$

265 With (49) and (50) we have  $N + 3$  evolution equations for the  $N + 3$  fields  $\check{\psi}_0^I, \check{\psi}_1^I, \dots, \check{\psi}_N^I$  and  $\vartheta^\pm$ .

266 Approximation B conserves surface buoyancy variance. But the conservation laws for energy  
 267 is problematic: because  $\psi^I$  is not orthogonal to  $\psi^S$  the energy (10) is not conserved in approxi-  
 268 mation B (K.S. Smith personal communication). These non-conservative effects are quantitatively  
 269 small, but are nonetheless irritating. The non-orthogonality of  $\psi^I$  and  $\psi^S$  was a motivation for  
 270 development of the surface-aware modes by Smith & Vanneste (2013).

271 With  $\beta = 0$ , approximation B conserves potential enstrophy

$$\frac{d}{dt} \sum_{n=0}^N \int \frac{1}{2} (\triangle_n \check{\psi}_n^I)^2 dS = 0. \quad (51)$$

272 But with  $\beta \neq 0$  the analog of the exact potential enstrophy (12) is not conserved.



### 273 *c. Approximation C*

274 Approximation C uses truncated Galerkin approximations  $\psi_N^G$  and  $q_N^G$  for *both*  $\psi$  and  $q$ . The  
 275 series  $q_N^G$  is *not* obtained by differentiation of  $\psi_N^G$  and therefore, as indicated in (24), the inversion  
 276 equation is not satisfied exactly by  $\psi_N^G$  and  $q_N^G$ . But instead, one will have true least-squares  
 277 approximations to both  $\psi$  and  $q$ . To our knowledge approximation C, correctly accounting for the  
 278 surface-buoyancy boundary terms, has not been previously investigated.

279 Because method C approximates *both* the streamfunction and the PV by Galerkin series, the  
 280 derivation of the modal equations is very straightforward compared with the calculations in ap-  
 281 pendix A of Flierl (1978): one simply substitutes the truncated Galerkin series for the streamfunc-  
 282 tion (15) and PV (17) into the QGPV equation (6), and then projects onto mode  $n$  to obtain

$$\partial_t \check{q}_n + \sum_{m=0}^N \sum_{s=0}^N \Xi_{nms} J(\check{\psi}_m, \check{q}_s) + \beta \partial_x \check{\psi}_n = 0, \quad (52)$$

283 where  $\Xi_{nms}$  is defined in (37), and we recall the relation between  $\check{\psi}_n$  and  $\check{q}_n$  from (22)

$$\check{q}_n = \triangle_n \check{\psi}_n + \frac{1}{h} (\mathbf{p}_n^+ \vartheta^+ - \mathbf{p}_n^- \vartheta^-). \quad (53)$$

284 In approximation C there are  $N + 3$  degrees of freedom: the  $N + 1$  modal amplitudes  $\check{\psi}_n$  and  
 285 the two surface buoyancy fields  $\vartheta^\pm$ . The approximation C evolution equations are completed by  
 286 advection of the surface buoyancy

$$\partial_t \vartheta^\pm + \sum_{n=0}^N \mathbf{p}_n^\pm J(\check{\psi}_n, \vartheta^\pm) = 0. \quad (54)$$

287 We emphasize that in approximation C the surface buoyancy fields  $\vartheta^\pm$  are not passive:  $\check{\psi}_n$ ,  $\check{q}_n$ ,  
 288 and  $\vartheta^\pm$  are related through (53).

289 Approximation C conserves surface buoyancy variance as in (13). Total energy is also conserved

$$\frac{d}{dt} \sum_{n=0}^N \int \frac{1}{2} |\nabla \check{\psi}_n|^2 + \frac{1}{2} \kappa_n^2 \check{\psi}_n^2 dS = 0. \quad (55)$$

290 With  $\beta = 0$ , approximation C has a potential enstrophy conservation law

$$\frac{d}{dt} \sum_{n=0}^N \int \frac{1}{2} \tilde{q}_n^2 dS = 0. \quad (56)$$

291 But with  $\beta \neq 0$ , as in B, approximation C does not conserve the analog of the exact potential  
292 enstrophy (12).

## 293 5. The Eady problem

294 We use classical linear stability problems with nonzero surface buoyancy to illustrate how so-  
295 lutions to specific problems can be constructed and to assess the relative merit and efficiency of  
296 approximations A, B, and C. The linear analysis does not provide the full picture of convergence of  
297 the approximate solutions. Nonetheless, in turbulence simulations forced by baroclinic instability,  
298 it is necessary (but not sufficient) to accurately capture the linear stability properties.

299 We use nondimensional variables so that the surfaces are at  $z^+ = 0$  and  $z^- = -1$ . The Eady  
300 exact base-state velocity is given by (30) with zero PV  $q = 0$  and  $\beta = 0$ .

### 301 *a. Approximation A*

302 While the surface fields  $\vartheta^\pm$  are dynamically passive in approximation A, the Eady problem can  
303 still be considered because the base-state PV defined via (35) converges to  $\delta$ -distributions on the  
304 boundaries (Section 3).

305 The base-state velocity in Approximation A is given by the series (31) and is a good approxima-  
306 tion to the exact base-state velocity (30). But, according to approximation A, there is a nonzero  
307 interior base-state PV gradient given by the series (33). As  $N \rightarrow \infty$  the PV gradient in (33) con-  
308 verges in a distributional sense to Brethertonian sheets at  $z = 0$  and  $-1$ . But for numerical imple-  
309 mentation of approximation A we stop short of  $N = \infty$ . While the PV gradient is much larger at  
310 the boundaries, there is always interior structure in the PV (Figure 1c). We show that this spurious

interior PV gradient has a strong and unpleasant effect on the approximate solution of the Eady stability problem.

To solve the Eady linear stability we linearize the interior equations (36) about the base-state velocity in (31) and the PV gradient in (33). We assume  $\check{q}_k = \hat{q}_k \exp[i(kx + ly - \omega^A t)]$ , etc, to obtain a  $(N + 1) \times (N + 1)$  eigenproblem

$$\sum_{m=0}^N \sum_{s=0}^N \Xi_{nms} \left[ \check{U}_m \hat{q}_s + \partial_y \check{Q}_s \hat{\psi}_m \right] = c^A \hat{q}_n, \quad (57)$$

where  $\check{Q}_s$  are the coefficients of the series (33) and  $c^A \stackrel{\text{def}}{=} \omega^A / k$ . The eigenproblem (57) can be recast in the matrix form  $A\mathbf{q} = c^A \mathbf{q}$ , where  $\tilde{\mathbf{q}} = [\hat{q}_0, \hat{q}_1, \dots, \hat{q}_{N-1}, \hat{q}_N]^T$  (Appendix B) and solved with standard methods.

Figure 2 shows the growth rate of the Eady instability according to approximation A, and compares this with the exact Eady growth rate. Approximation A does not do well, especially at large wavenumbers. The exact Eady growth rate has a high-wavenumber cut-off. At moderate values of  $N$ , such as 3, 5 and 7 approximation A produces unstable “bubbles” of instability at wavenumbers greater than the high-wavenumber cut-off. The growth rates in these bubbles are comparable to the true maximum growth rate. As  $N$  increases, the unstable bubbles are replaced by a long tail of unstable modes with a growth rate that slowly increases with  $\kappa$ . These spurious high-wavenumber instabilities are due to the rapidly oscillatory interior PV gradient which supports unphysical critical layers: see Figure 3.

#### *b. Approximation B, the exact solution*

In approximation B, the zero PV in the Eady problem implies  $\check{q}_n = \check{\psi}_n^I = 0$ . The  $N + 1$  modal equations (with  $\beta = 0$ ) are trivially satisfied; there is no interior contribution ( $\psi_N^I = 0$ ). Thus approximation B solves the Eady problem exactly.

Assuming  $\psi^S = \hat{\psi}^S(z) \exp[i(kx + ly - \omega^B t)]$ , we obtain the solution to the surface streamfunction inversion problem (42)-(43)

$$\hat{\psi}^S(z) = \frac{\cosh[\kappa(z+1)]}{\kappa \sinh \kappa} \vartheta^+ - \frac{\cosh(\kappa z)}{\kappa \sinh \kappa} \vartheta^-, \quad (58)$$

where the magnitude of the wavenumber vector is  $\kappa = \sqrt{k^2 + l^2}$ . We evaluate the surface streamfunction (58) at the boundaries to find the relationship between the streamfunction at the surfaces  $\hat{\psi}^{S\pm}$  and the boundary fields  $\vartheta^\pm$ :

$$\begin{bmatrix} \hat{\psi}^{S+} \\ \hat{\psi}^{S-} \end{bmatrix} = \frac{1}{\kappa} \begin{bmatrix} \coth \kappa & -\operatorname{csch} \kappa \\ \operatorname{csch} \kappa & -\coth \kappa \end{bmatrix} \begin{bmatrix} \hat{\vartheta}^+ \\ \hat{\vartheta}^- \end{bmatrix}, \quad (59)$$

The nondimensional linearized boundary conditions (50) are

$$\hat{\vartheta}^+ - \hat{\psi}^+ = c^B \hat{\vartheta}^+, \quad \text{and} \quad -\hat{\psi}^- = c^B \hat{\vartheta}^-, \quad (60)$$

where  $c^B = \omega^B/k$ . Using the boundary conditions (60) in (59) we obtain an eigenvalue problem

$$\underbrace{\frac{1}{\kappa} \begin{bmatrix} \kappa - \coth \kappa & \operatorname{csch} \kappa \\ -\operatorname{csch} \kappa & \coth \kappa \end{bmatrix}}_{\stackrel{\text{def}}{=} B} \begin{bmatrix} \hat{\vartheta}^+ \\ \hat{\vartheta}^- \end{bmatrix} = c^B \begin{bmatrix} \hat{\vartheta}^+ \\ \hat{\vartheta}^- \end{bmatrix}. \quad (61)$$

The eigenvalues of B are given by the celebrated dispersion relation for the Eady problem (Pedlosky 1987; Vallis 2006)

$$c^B = \frac{1}{2} \pm \frac{1}{\kappa} \left[ \left( \frac{\kappa}{2} - \tanh \frac{\kappa}{2} \right) \left( \frac{\kappa}{2} - \coth \frac{\kappa}{2} \right) \right]^{1/2}. \quad (62)$$

### c. Approximation C

Approximation C expands both the streamfunction and the PV in standard vertical modes. Thus in the Eady problem the PV is exactly zero, as it should be:  $q = \check{q}_n = 0$ . Thus approximation C does not have the spurious critical layers that bedevil A. Moreover, in approximation C, the  $N+1$

modal equations (with  $\beta = 0$ ) in (52) are trivially satisfied, and the inversion relationship (53) provides a simple connection between the streamfunction and the fields  $\vartheta^\pm$ . The base velocity for the Eady problem in approximation C is the series in (31) (the same as A). From the exact shear at the boundaries we obtain the exact base-state boundary variables

$$\Theta^\pm = -y. \quad (63)$$

We linearize the boundary equations (54) about the base-state (33) and (63), to obtain

$$\partial_t \vartheta^\pm + U_N^{\text{G}\pm} \partial_x \vartheta^\pm - \sum_{k=0}^N \partial_x \check{\psi}_k \mathbf{p}_k^\pm = 0. \quad (64)$$

Assuming  $\vartheta^\pm = \hat{\vartheta}^\pm \exp[i(kx + ly - \omega^C t)]$ , and using the inversion relationship (53), we obtain a  $2 \times 2$  eigenproblem

$$\mathbf{C} \begin{bmatrix} \hat{\vartheta}^+ \\ \hat{\vartheta}^- \end{bmatrix} = c^C \begin{bmatrix} \hat{\vartheta}^+ \\ \hat{\vartheta}^- \end{bmatrix}, \quad (65)$$

where matrix  $\mathbf{C}$  is defined in appendix C. It is straightforward to show that  $c^C$  converges to the exact eigenspeed, i.e.,  $c^C \rightarrow c^B$  as  $N \rightarrow \infty$  (Appendix C). Figure 2 shows that approximation C successfully captures the structure of the Eady growth rate even with modest values of  $N$ .

#### d. Remarks on convergence

The crudest truncation (i.e.  $N = 0$ ) is stable for both approximations A and C (Figure 2). With one baroclinic mode ( $N = 1$ ) the growth rates ( $\omega_i = k \times \text{Im}\{c\}$ ) are qualitatively consistent with the exact solution, and the results improve with  $N = 2$ . With a moderate number of baroclinic modes ( $N > 2$ ) approximations A and C converge rapidly to the exact growth rate at wavenumbers less than about 2.2 — see figure 2. But surprisingly the convergence of the growth rate at the most unstable mode ( $\kappa \approx 1.6$ ) is faster in approximation A ( $\sim N^{-4}$ ) than in approxima-

tion C ( $\sim N^{-2}$ ) — see figure 4. However, the convergence in approximation C is uniform: there are no spurious high-wavenumber instabilities.

Figure 4 also shows that the approximation A convergence of the growth rate to zero at  $\kappa = 8$  is slow ( $\sim N^{-1}$ ). While the growth rate does converge to zero at a fixed wavenumber, such as  $\kappa = 8$ , we conjecture that there are always faster growing modes at larger wavenumbers.

## 6. The Green problem

To further explore the relative merit and efficiency of approximations A, B, and C we study the instability properties of a system with nonzero  $\beta$ . For simplicity, we consider a problem with Eady’s base-state  $\psi = -(1+z)y$  on a  $\beta$ -plane. This is similar to the problem originally considered by Charney (1947) and Green (1960). The major difference is that Charney considered a vertically semi-infinite domain (Charney 1947; Pedlosky 1987) while we follow Green and consider a finite-depth domain with  $-1 < z < 0$ .

We obtain the exact system for this “Green problem” by linearizing the QG equations (6)-(9) about the base-state (30) with background PV  $\beta y$ , where  $\hat{\beta}$  is the nondimensional planetary PV gradient. Assuming  $\psi = \hat{\psi} \exp[i(kx + ly - \omega t)]$ , we obtain

$$(U - c) [\hat{\psi}_{zz} - \kappa^2 \hat{\psi}] + \hat{\beta} \hat{\psi} = 0, \quad -1 < z < 0, \quad (66)$$

and

$$(U - c) \hat{\psi}_z - \hat{\psi} = 0, \quad z = -1, 0. \quad (67)$$

As a reference solution, we solve the eigenproblem (66)-(67) using a centered second-order finite-difference scheme with 1000 vertical levels: see Figure 5.

The Green problem supports three classes of unstable modes, indicated in the lower right panel (N = 128) of Figure 5: (1) the “modified Eady modes”, which are instabilities that arise from the

382 interaction of Eady-like edge waves, only slightly modified by  $\beta$ ; (2) the “Green modes”, which  
 383 are very long slowly growing modes (Vallis 2006); (3) the high-wavenumber “Charney modes” are  
 384 critical layer instabilities that arise from the interaction of the surface edge wave with the interior  
 385 Rossby wave that is supported by nonzero  $\beta$ .

#### 386 *a. Implementation of approximation A*

387 The base-state for the Green problem is the same as in the Eady problem. In approximation A,  
 388 the  $\beta$ -term adds only a diagonal term to the Eady system (57) (see appendix C).

#### 389 *b. Implementation of approximation B*

390 The base-state is the same as in the Eady problem. The steady streamfunction and buoyancy  
 391 fields that satisfy (49) and (50) exactly are

$$\Sigma = -(1+z)y \quad \text{and} \quad \Theta^\pm = -y. \quad (68)$$

392 Assuming  $\check{q}_n = \hat{q}_n(z) \exp[i(kx + ly - \omega^B t)]$ , the  $N+1$  interior equations (49) linearized about (68)  
 393 are

$$\sum_{s=0}^N \xi_{ns} \hat{q}_s + \hat{\beta} (\hat{\psi}_n + \hat{\psi}_n^S) = c_c^B \hat{q}_n, \quad (69)$$

394 where

$$\xi_{ns} \stackrel{\text{def}}{=} \frac{1}{h} \int_{z^-}^{z^+} p_n p_s (z+1) dz. \quad (70)$$

395 The boundary conditions (50), linearized about (68), are

$$\hat{\vartheta}^+ - \sum_{s=0}^N p_s^+ \hat{\psi}_s - \hat{\psi}^S + = c_c^B \hat{\vartheta}^+, \quad (71)$$

396 and

$$- \sum_{s=0}^N p_s^- \hat{\psi}_s - \hat{\psi}^S - = c_c^B \hat{\vartheta}^-, \quad (72)$$

where  $\hat{\psi}^S$  is given by (58). We use the inversion relationship (48) and the Neumann-to-Dirichlet map (59) to recast this eigenproblem into standard form  $B\tilde{q} = c^B\tilde{q}$ , where  $\tilde{q} = [\hat{\vartheta}^+, \hat{q}_0, \hat{q}_1, \dots, \hat{q}_{N-1}, \hat{q}_N, \hat{\vartheta}^-]^T$  (see appendix C).

### c. Implementation of approximation C

Again the base-state is the same as in the Eady problem. But now there are  $N + 3$  equations: the two boundary equations of Eady's problem (64) plus  $N + 1$  interior equations

$$\sum_{m=0}^N \sum_{s=0}^N \Xi_{nms} \check{U}_m \hat{q}_s + \hat{\beta} \hat{\psi}_n = c^C \hat{q}_n, \quad (73)$$

We use the inversion relationship (53) in (73) to recast this eigenproblem in the form  $C\tilde{q} = c^C\tilde{q}$ , where  $\tilde{q}$  is defined as in approximation B (see appendix C).

### d. Remarks on convergence

The most crude truncation ( $N = 0$ ) is stable for approximations A and C. In contrast, the  $N = 0$  truncation in approximation B is qualitatively consistent with the modified Eady instabilities: see figure 5. With a moderate number of baroclinic modes ( $N = 2$  or  $3$ ), approximations A, B and C all resolve the modified Eady modes relatively well. At the most unstable modified Eady mode ( $\kappa \approx 1.9$ ), approximation B has typically the smallest error because it solves the surface problem exactly. As in the Eady problem, approximation A converges ( $\sim N^{-4}$ ) faster than approximations B and C ( $\sim N^{-2}$ ) at the most unstable mode, but B and C converge faster at high wavenumbers.

Approximations A, B, and C all converge very slowly to the high-wavenumber Charney modes (Figures 5 and 6). These modes are interior critical-layer instabilities (Pedlosky 1987) and the critical layer is confined to a small region about the steering level (i.e., the depth at which the phase speed matches the base velocity — see figure 7). With finite base-state shear, the critical layer is always in the interior. Thus, the problem is not that standard vertical modes are inefficient



418 because they do not satisfy inhomogeneous boundary conditions; a low resolution finite-difference  
 419 solution also presents such “bubbles” in high-wavenumber growth rates (not shown). Resolution  
 420 of the interior critical layer, not the surface boundary condition, is a problem for all methods  
 421 at high wavenumbers. The “surface-aware” modes of Smith and Vanneste (2013) have similar  
 422 performance to approximations B and C, but also have the same limitation — a large number of  
 423 vertical modes is required to resolve interior critical layers (K. S. Smith, personal communication).  
 424 For example, with  $N < 25$ , at  $\kappa = 8$ , approximations are qualitatively inconsistent with the  
 425 high-resolution finite-difference solution. For larger values of  $N$ , the growth rate convergence for  
 426 approximations B and C scales  $\sim N^{-3}$ . The growth rate for approximation A converges painfully  
 427 slowly ( $\sim N^{-1}$ ). As in the Eady problem, at large wavenumbers, the growth rate for approxi-  
 428 mation A is qualitatively different from that of the finite-difference solution because of spurious  
 429 instabilities associated with the rapidly oscillatory base-state PV gradient in (33).

## 430 **7. Summary and conclusions**

431 The Galerkin approximations A, B, and C are equivalent if there are no buoyancy variations  
 432 at the surfaces. Thus all three approximations are well-suited for applications with zero surface  
 433 buoyancy (Flierl 1978; Fu and Flierl 1980; Hua and Haidvogel 1986). But with nonzero surface  
 434 buoyancy the three approximations are fundamentally different. In particular, approximation A,  
 435 originally introduced by Flierl (1978) in a context without surface buoyancy, obtains the approxi-  
 436 mate PV by differentiating the Galerkin series for the streamfunction, and consequently its approx-  
 437 imate PV has violent oscillations in the interior. Approximation B represents the PV as a Galerkin  
 438 series in standard modes and calculates the streamfunction that satisfies the exact inversion prob-  
 439 lem associated with the approximate PV (Tulloch and Smith 2009). The inversion relationship  
 440 is split into surface and interior problems. Because the surface streamfunction projects onto the

interior solution the energy is not diagonalized and consequently approximation B has small errors in energy conservation (K.S. Smith personal communication). The surface-aware modes of Smith & Vanneste (2013) correct this problem. Approximation C uses Galerkin series for both streamfunction and PV but does not satisfy the inversion problem exactly. Nevertheless, the Galerkin series for  $\psi$  and  $q$  converge absolutely and uniformly, and approximation C provides a good finite truncation of the QG equations that represents surface buoyancy dynamics and also conserves energy.

With nonzero interior PV gradients the convergence of all approximations is slow for the high-wavenumber Charney-type modes. The critical layer associated with these modes spans a very small fraction of the total depth (Figure 7). To accurately resolve these near-singularities at the steering level there is no better solution than having high vertical resolution in the interior.

For problems with nonuniform surface buoyancy and nonzero interior PV gradient, we recommend approximation C for obtaining solutions to the three-dimensional QG equations using standard vertical modes.

The codes that produced the numerical results of this paper, plotting scripts, and supplementary figures are openly available at [github.com/crocha700/qg.vertical.modes](https://github.com/crocha700/qg.vertical.modes).

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## APPENDIX A

### Convergence of Galerkin series in standard modes

464 Jackson (1914) gives conditions for the uniform convergence of series expansions in eigenfunc-  
 465 tions of the Sturm-Liouville eigenproblem

$$\frac{d^2 P_n}{dZ^2} + [\rho_n^2 - \Lambda(Z)] P_n = 0, \quad (A1)$$

466 defined on the interval  $Z \in [0, \pi]$  with boundary conditions

$$P'_n(0) - \gamma_0 P_n(0) = 0, \text{ and } P'_n(\pi) - \gamma_\pi P_n(\pi) = 0 \quad (A2)$$

467 where  $\gamma_0$  and  $\gamma_\pi$  are real constants of arbitrary sign and  $\rho_n^2$  is the eigenvalue. The equations  
 468 defining the standard modes (1)-(2) can be brought to this form using the following Liouville  
 469 transformation

$$Z(z) = \frac{1}{\bar{Z}} \int_{z^-}^z S(\xi)^{-1/2} d\xi, \text{ with } \bar{Z} \stackrel{\text{def}}{=} \frac{1}{\pi} \int_{z^-}^{z^+} S(\xi)^{-1/2} d\xi, \quad (A3)$$

470 and

$$P_n(Z) = S(z)^{1/4} p_n(z), \text{ where } S(z) \stackrel{\text{def}}{=} \frac{f_0^2}{N^2(z)}. \quad (A4)$$

471 The eigenvalues are related by  $\rho_n = \bar{Z} \kappa_n$  and

$$\Lambda(Z) = \bar{Z}^2 \left[ \frac{1}{4} \frac{d^2 S}{dz^2} - \frac{1}{16S} \left( \frac{dS}{dz} \right)^2 \right]. \quad (A5)$$

472 The boundary condition for the standard modes (2) implies that the transformed modes satisfy  
 473 (A2) with

$$\gamma_0 = \frac{4S(z^-)^{1/2}}{\bar{Z} dS(z^-)/dz}, \text{ and } \gamma_\pi = -\frac{4S(z^+)^{1/2}}{\bar{Z} dS(z^+)/dz}. \quad (A6)$$

474 If  $dS/dz = 0$  at a boundary then the appropriate condition at that boundary is  $P_n = 0$ .

475 A special case of Theorem I from Jackson (1914) states that the expansion of a function  $f(Z)$   
 476 as a series in eigenfunctions  $P_n$  converges absolutely and uniformly provided that both  $df/dZ$  and  
 477  $d\Lambda/dZ$  are continuous and bounded, regardless of whether or not  $f$  satisfies the same boundary  
 478 conditions as  $P_n$ . (The remainder of the theorem concerns the rate of convergence under stronger

conditions on  $\psi$  and  $\Lambda$ .) The streamfunction, potential vorticity, and buoyancy profiles are typically assumed to be smooth in studies of QG dynamics, which implies that both  $f$  and  $\Lambda$  will satisfy the above conditions. Uniform convergence over  $Z \in [0, \pi]$  implies uniform convergence over  $z \in [z^-, z^+]$ .

## APPENDIX B

### Derivation of conservation laws for approximation C

To obtain the conservation of energy in approximation C we multiply the modal equations (52) by  $-\check{\psi}_n$ , integrate over the horizontal surface, and sum on  $n$ , to obtain

$$\begin{aligned} \frac{d}{dt} \sum_{n=0}^N \int [(\nabla \check{\psi}_n)^2 + \kappa_n^2 \check{\psi}_n^2] dS \\ - \sum_{n=0}^N \frac{1}{h} \int \check{\psi}_n \partial_t (\mathfrak{p}_n^+ \vartheta^+ - \mathfrak{p}_n^- \vartheta^-) dS \\ + \sum_{n=0}^N \sum_{m=0}^N \sum_{s=0}^N \Xi_{nms} \int \check{\psi}_n \mathcal{J}(\check{\psi}_m, \triangle_s \check{\psi}_s) dS = 0, \end{aligned} \quad (\text{B1})$$

The triple sum term vanishes by the same symmetry arguments used above in approximation A. The term on the second line of (B1) is also zero: multiply the boundary conditions (54) by  $\mathfrak{p}_n^\pm \check{\psi}_n$  and integrate over the horizontal surface. Thus we obtain the energy conservation law in (55).

The analog of the exact potential enstrophy (12),

$$Z_n \stackrel{\text{def}}{=} \sum_{n=0}^N \int \frac{\check{q}_n^2}{2} + \check{q}_n \triangle_n \check{\psi}_n dS, \quad (\text{B2})$$

is only conserved with  $N = 0$ .

## APPENDIX C

### Details of the stability problems

494 *a. The interaction tensor*

495 Because the standard vertical modes with constant stratification are simple sinusoids (29), the  
 496 interaction coefficients (37) can be computed analytically. First we recall that  $\Xi_{ijk}$  is fully sym-  
 497 metric. Permuting the indices so that  $i \geq j \geq k$  we obtain

$$\Xi_{ijk} = \begin{cases} 1 : & i = j, k = 0; \\ \frac{\sqrt{2}}{2} : & i = j + k; \\ 0 : & \text{otherwise.} \end{cases} \quad (\text{C1})$$

498 The second line in (C1) corrects a factor of  $\frac{1}{2}$  missed by Hua and Haidvogel (1986).

499 *b. Approximation A*

500 Using the symmetry in  $\Xi_{nms}$ , and the inversion relation (35), we rewrite row  $n + 1$  of the linear  
 501 Green system

$$\sum_{s=0}^N \sum_{m=0}^N \Xi_{nms} (\check{U}_m + \partial_y \check{Q}_m \alpha_s) \hat{q}_s + \hat{\beta} \alpha_n \hat{q}_n = c^A \hat{q}_n, \quad (\text{C2})$$

502 where the inverse of the  $n$ 'th mode Helmholtz operator in Fourier space is

$$\alpha_n \stackrel{\text{def}}{=} -(\kappa^2 + (n\pi)^2)^{-1}. \quad (\text{C3})$$

503 The Eady problem is the special case  $\hat{\beta} = 0$ . We use a standard eigenvalue-eigenvector algorithm  
 504 to obtain the approximate eigenspeed  $c^A$ .

505 *c. Approximation B*

506 The Green eigenvalue problem in (69) through (72) can be recast in the standard form  $B \mathbf{q} = c^B \mathbf{q}$ ,  
 507 where  $\tilde{\mathbf{q}} = [\hat{\vartheta}^+, \hat{q}_0, \hat{q}_1, \dots, \hat{q}_{N-1}, \hat{q}_N, \hat{\vartheta}^-]^T$ . The first and last rows of the system stem from the

508 boundary conditions (71)-(72)

$$\left(1 - \frac{\coth \kappa}{\kappa}\right) \hat{\vartheta}^+ - \sum_{s=0}^N \mathbf{p}_s^+ \alpha_s \hat{q}_s - \frac{\operatorname{csch} \kappa}{\kappa} \hat{\vartheta}^- = c^B \hat{\vartheta}^+, \quad (\text{C4})$$

509 and

$$\frac{\operatorname{csch} \kappa}{\kappa} \hat{\vartheta}^+ - \sum_{s=0}^N \mathbf{p}_s^- \alpha_s \hat{q}_s + \frac{\coth \kappa}{\kappa} \hat{\vartheta}^- = c^B \hat{\vartheta}^-. \quad (\text{C5})$$

510 The  $(n+1)$ 'th row originates from the  $n$ 'th interior equation (69)

$$-\hat{\beta} \mathbf{p}_n^+ \alpha_n \vartheta^+ + \sum_{s=0}^N \gamma_{ns} \hat{q}_s + (\beta \alpha_n + 1) + \hat{\beta} \mathbf{p}_n^- \alpha_n \vartheta^- = c^B \hat{q}_n, \quad (\text{C6})$$

511 where the symmetric matrix  $\gamma_{ms}$  is

$$\gamma_{ij} \stackrel{\text{def}}{=} \int_{-1}^0 \mathbf{p}_i \mathbf{p}_j z \, dz = \begin{cases} -\frac{1}{2} : & i = j; \\ \frac{2\sqrt{2}}{(j\pi)^2} : & i = 0, j \text{ is odd}; \\ \frac{4(i^2 + j^2)}{[(i^2 - j^2)\pi]^2} : & i + j \text{ is odd}. \end{cases} \quad (\text{C7})$$

512 *d. Approximation C*

513 THE EADY PROBLEM

514 The  $2 \times 2$  eigenproblem is

$$\underbrace{\begin{bmatrix} U_N^{G^+} + \Sigma_N & -\Omega_N \\ \Omega_N & U_N^{G^-} - \Sigma_N \end{bmatrix}}_{\stackrel{\text{def}}{=} C} \begin{bmatrix} \hat{\vartheta}^+ \\ \hat{\vartheta}^- \end{bmatrix} = c^C \begin{bmatrix} \hat{\vartheta}^+ \\ \hat{\vartheta}^- \end{bmatrix}, \quad (\text{C8})$$

515 where

$$\Sigma_N \stackrel{\text{def}}{=} \alpha_0 + 2 \sum_{n=1}^N \alpha_n, \quad \text{and} \quad \Omega_N \stackrel{\text{def}}{=} \alpha_0 + 2 \sum_{n=1}^N (-1)^n \alpha_n. \quad (\text{C9})$$

516 The sums (C9) become exact in the limit  $N \rightarrow \infty$

$$\Sigma_\infty = -\frac{\coth \kappa}{\kappa}, \quad \text{and} \quad \Omega_\infty = -\frac{\operatorname{csch} \kappa}{\kappa}. \quad (\text{C10})$$

517 The base velocity also converges to the exact result. Using standard results for the summation of  
 518 inverse squares, we obtain

$$U_{\infty}^{G+} = 1, \quad \text{and} \quad U_{\infty}^{G-} = 0. \quad (\text{C11})$$

519 Thus

$$C \rightarrow B \quad \text{as} \quad N \rightarrow \infty, \quad (\text{C12})$$

520 and the eigenvalues of the Eady problem using approximation C become exact i.e.,  $c^C \rightarrow c^B$  as  
 521  $N \rightarrow \infty$ .

## 522 THE GREEN PROBLEM

523 The  $(N+3) \times (N+3)$  eigenproblem is

$$C \tilde{q} = c^C \tilde{q}, \quad (\text{C13})$$

524 where  $\tilde{q}$  is defined as above in approximation B. The first and last rows of (C13) stem from the  
 525 boundary conditions (64)

$$\left( U_N^{G+} + \Sigma_N \right) \hat{v}^+ - \sum_{n=0}^N \alpha_n p_n^+ \hat{q}_n - \Omega_N \hat{v}^- = c^C \hat{v}^+, \quad (\text{C14})$$

526 and

$$\Omega_N \hat{v}^+ - \sum_{n=0}^N \alpha_n p_n^- \hat{q}_n + \left( U_N^{G-} - \Sigma_N \right) \hat{v}^- = c^C \hat{v}^-. \quad (\text{C15})$$

527 Row  $n+1$  originates from the  $n$ 'th modal equation (73):

$$\begin{aligned} \hat{\beta} \alpha_n p_n^+ \hat{v}^+ + \sum_{s=0}^N \sum_{m=0}^N \Xi_{mns} \check{U}_m \hat{q}_s + \hat{\beta} \alpha_n \hat{q}_n \\ - \hat{\beta} \alpha_n p_n^- \hat{v}^- = c^C \hat{q}_n. \end{aligned} \quad (\text{C16})$$

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## LIST OF FIGURES

<b>Fig. 1.</b>	Nondimensional base-state for the Eady problem using various truncation for the series (31). In the middle panel $N$ is the number of baroclinic modes. (a) Zonal velocity: although the truncation has zero slope at the boundaries there are no Gibbs oscillations. (b) Meridional PV gradient associated with the truncated series (33). (c) as in (b) but with an expanded abscissa. As $N$ increases, the PV gradient distributionally converges to two Brethertonian delta functions at the boundaries.	35
<b>Fig. 2.</b>	Growth rate for the Eady problem as a function of the zonal wavenumber ( $l = 0$ ) using approximations A, B (exact), C with various number of baroclinic modes ( $N$ ).	36
<b>Fig. 3.</b>	Structure of $\kappa = 8$ unstable mode for the Eady problem obtained using approximation A and $N = 64$ . Streamfunction is the black curves and PV is the colors. The streamfunction slightly tilts westward as $z$ increases. One can see the unphysical critical layer associated with the fast-oscillating base-state PV. The critical level, $z_c$ , is the depth where the unstable wave speed matches the velocity of the base-state. Only the top quarter of the domain is shown.	37
<b>Fig. 4.</b>	Absolute error as a function of number of baroclinic modes ( $N$ ) for the growth rates of the Eady problem. The solid lines show the error at the exact fastest growing mode ( $\kappa \approx 1.6$ ). The dashed line is the approximation A error at $\kappa = 8$ .	38
<b>Fig. 5.</b>	Growth rate for the Green problem with $\hat{\beta} = 1$ as a function of the zonal wavenumber ( $l = 0$ ) using approximations A, B, C with various number of baroclinic modes ( $N$ ). The black line is a finite-differences solution with 1000 vertical levels.	39
<b>Fig. 6.</b>	Absolute error as a function of number of baroclinic modes ( $N$ ) for the growth rates of the Green problem. The solid line represent the error at the exact fastest growing mode ( $\kappa \approx 1.9$ ). The dashed line is the error at $\kappa = 8$ .	40
<b>Fig. 7.</b>	Wave structure of the $\kappa = 8$ unstable mode for the Green problem with $\hat{\beta} = 1$ solved using a second-order finite-difference scheme with 1000 vertical levels. Streamfunction (black contours) and potential vorticity (colors). The streamfunction slightly tilts westward as $z$ increases. The potential vorticity is confined to a small region, the critical layer. The critical level, $z_c$ , is the depth where the unstable wave speed matches the velocity of the base-state. Only the bottom quarter of the domain is shown.	41

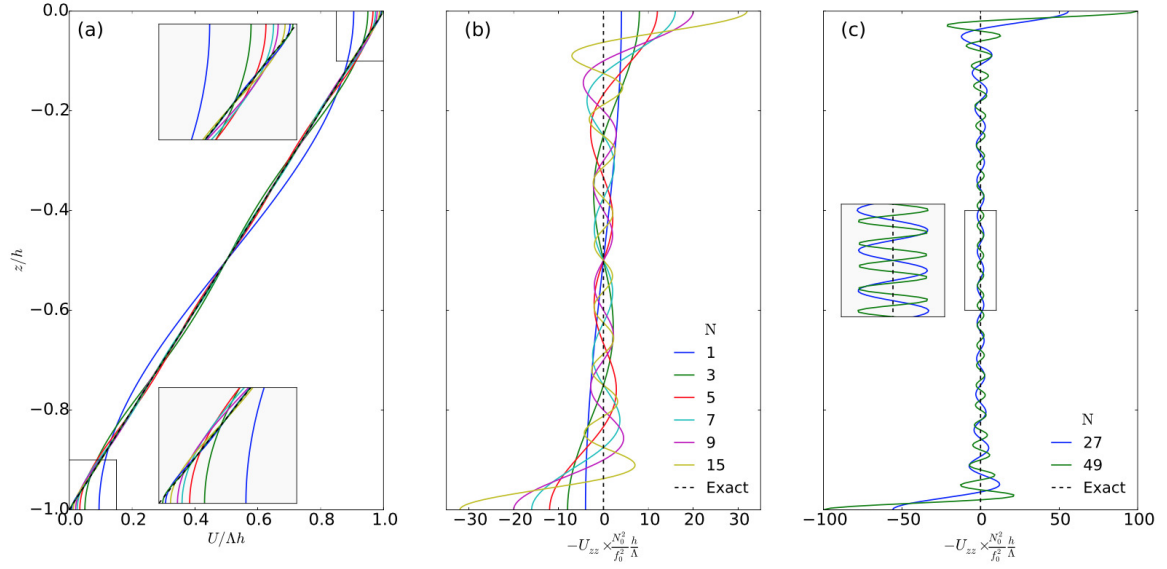


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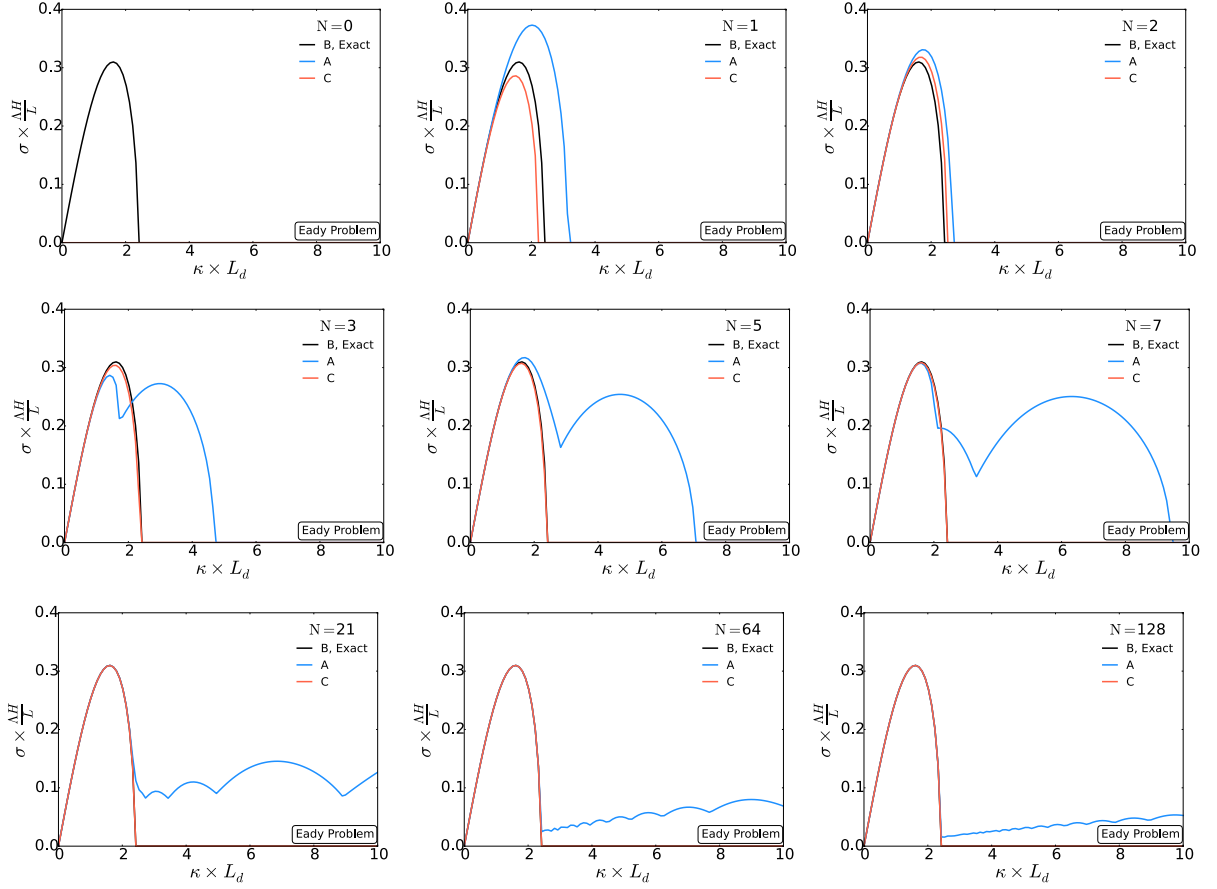


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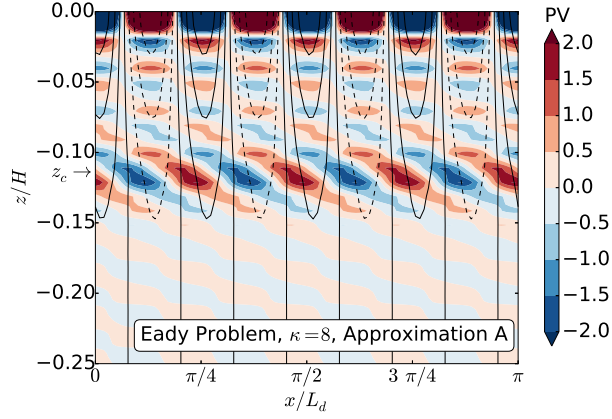


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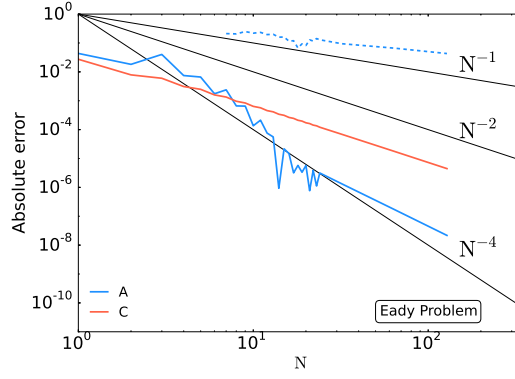


FIG. 4. Absolute error as a function of number of baroclinic modes ( $N$ ) for the growth rates of the Eady problem. The solid lines show the error at the exact fastest growing mode ( $\kappa \approx 1.6$ ). The dashed line is the approximation A error at  $\kappa = 8$ .

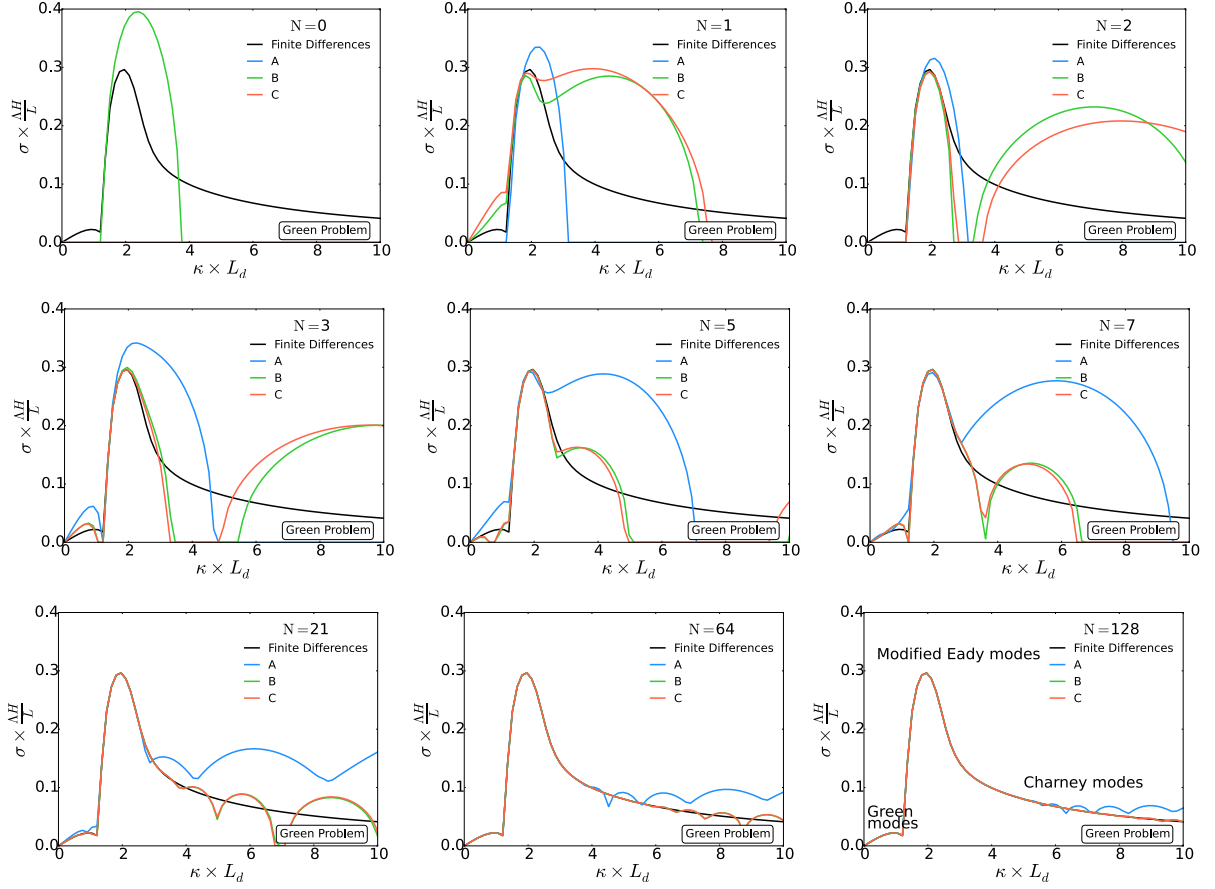


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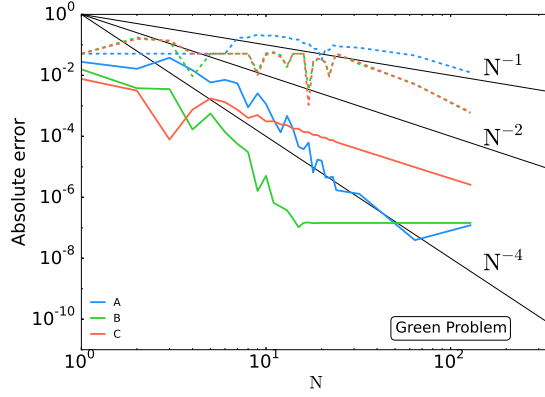
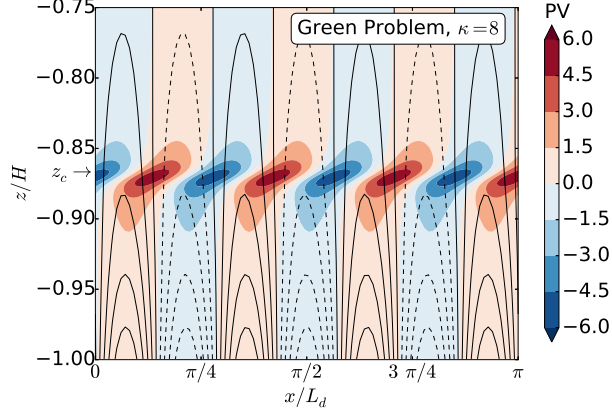


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 620 order finite-difference scheme with 1000 vertical levels. Streamfunction (black contours) and potential vorticity  
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 623 of the base-state. Only the bottom quarter of the domain is shown.