

# Chris Rockwell

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EDUCATION	<b>University of Michigan</b> <i>Ph.D. in Computer Science and Engineering</i> • Advisors: David F. Fouhey, Justin Johnson  <i>Master of Science, Computer Science and Engineering</i> • GPA: 4.00/4.00 • Advisors: David F. Fouhey, Jia Deng  <i>Bachelor of Science, Economics, Magna Cum Laude</i> <i>Minors in Computer Science and Mathematics</i> • GPA: 3.95/4.00	Ann Arbor, MI Sep. 2020 - Present  Sep. 2018 - May 2020  Sep. 2011 - May 2015
INTERESTS	Computer Vision, Machine Learning	

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PUBLICATIONS	The 8-Point Algorithm as an Inductive Bias for Relative Pose Prediction by ViTs <b>Chris Rockwell</b> , Justin Johnson and David F. Fouhey 3DV 2022.  PlaneFormers: From Sparse View Planes to 3D Reconstruction Samir Agarwala, Linyi Jin, <b>Chris Rockwell</b> and David F. Fouhey ECCV 2022.  FWD: Real-time Novel View Synthesis with Forward Warping and Depth Ang Cao, <b>Chris Rockwell</b> and Justin Johnson CVPR 2022.  Understanding 3D Object Articulation in Internet Videos Shengyi Qian, Linyi Jin, <b>Chris Rockwell</b> , Siyi Chen and David F. Fouhey CVPR 2022.  PixelSynth: Generating a 3D-Consistent Experience from a Single Image <b>Chris Rockwell</b> , David F. Fouhey and Justin Johnson ICCV 2021.  Full-Body Awareness from Partial Observations <b>Chris Rockwell</b> and David F. Fouhey ECCV 2020.
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RESEARCH EXPERIENCE	<b>Meta Reality Labs, Computational Photography Research</b> <i>Research Scientist Intern</i>   Team Manager: Johannes Kopf  <b>Michigan Vision Lab</b> <i>Graduate Research Assistant</i>   Advisor: Justin Johnson  Novel View Synthesis • <i>FWD</i> : Engineer real-time, high-quality novel view synthesis from sparse views • <i>PixelSynth</i> : Create an immersive experience from a single image	Seattle, WA May 2022 - Present  Ann Arbor, MI May 2020 - Present
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**Fouhey AI Lab***Graduate Research Assistant* | Advisor: David F. FouheyAnn Arbor, MI  
May 2019 - PresentRelative Pose Estimation – *Relative Pose Prediction by ViTs*

- Propose modification to ViT block to improve relative pose estimation

3D Reconstruction – *PlaneFormers*

- Jointly estimate pose and reconstruct via planes; use Transformer to refine correspondences

3D Object Articulation – *Understanding 3D Object Articulation*

- Collect rich dataset of people articulating objects and learn axes of object articulation.

3D Human Pose Estimation – *Full-Body Awareness*

- Introduce self-training method to substantially improve pose estimation on internet video
- Annotate four internet video datasets for eval; present out-of-image keypoint evaluation

**Princeton Vision and Learning Lab***Graduate Research Assistant* | Advisor: Jia DengPrinceton, NJ  
May 2018 - May 2019

2D Human Pose Estimation

- Add bottleneck-to-attention module to improve *Stacked Hourglass* accuracy 0.7%

Meta-Learning

- Improve fine-tune model to within 0.1 *avg. rank* of meta-learning baseline on *Meta-Dataset*

**Strategic Reasoning Group***Undergraduate Research Assistant* | Advisor: Michael P. Wellman

Ann Arbor, MI

May 2013 - Jul. 2013

Agent-based simulation of High-Frequency Trading and Latency Arbitrage

- Model trading agents with varying speeds to measure effects of latency arbitrage

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**TEACHING  
&  
ACTIVITIES**

Reviewer: CVPR, ICCV, ECCV, NeurIPS, 3DV, TPAMI

AI4ALL Project Instructor: lead vision project for nine underrepresented high-schoolers

AI4ALL Curriculum Advisory Board Member: contributed to national curriculum

AI4ALL Application Reviewer: assessed student applications for AI4ALL acceptance

Technical Mentor: mentored four undergrads with David Fouhey, including one remote in the African Undergraduate Research Adventure (AURA); mentored two BNP interns

Academic Mentor: mentored five undergraduate CSE students; grad orientation panelist

Graduate Student Advisory Committee: represented CSE students to improve experience

Grader: EECS 598 Deep Learning

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**SALIENT  
COURSES****University of Michigan, MS:**

Ecological Approach to Perception: explored embodied amodal perception of novel objects

Advanced AI: replicated *Image Generation from Scene Graphs*, evaluated using VQAMachine Learning: replicated and improved accuracy of *Stacked Hourglass Networks*Self-Driving Cars: fine-tuned *Squeeze and Excitation ResNet* for road-side classificationAdvanced Data Mining: performed link prediction using *SDNE* on sparse, temporal graphs

Deep Learning for Computer Vision (no class project)

**University of Michigan, BS:**

AI, Linear Algebra, Econometrics, Adv. Calculus, Numerical Methods, Algorithms &amp; DS

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HONORS & AWARDS	<b>University of Michigan</b>	Ann Arbor, MI
	Research Experience for Undergraduates Award	2013
	James B. Angell Scholar	2013-2016
	William J. Branstrom Freshman Prize	2012
	University Honors	2011-2015
	Phi Kappa Phi Honors Society	2015

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PROFESSIONAL EXPERIENCE	<b>TuringSense, INC.</b>	Santa Clara, CA
	<i>Technical Consultant (Computer Vision)</i>	Feb. 2021 - Apr. 2021
	<ul style="list-style-type: none"> <li>• Suggested and implemented improvements to TuringSense home yoga product</li> </ul>	
	<b>Citadel, LLC.</b>	New York, NY
	<i>Trader, Global Fixed Income (Core Team)</i>	Apr. 2017 - Oct. 2017
	<ul style="list-style-type: none"> <li>• Generated trade ideas and managed risk to assist Portfolio Manager and Fund Manager</li> <li>• Designed and implemented tools to improve team's trading portfolios</li> </ul>	
	<b>BNP Paribas</b>	New York, NY
	<i>Interest Rates and FX Structuring Analyst (Intern in summer 2014)</i>	Jul. 2015 - Mar. 2017
	<ul style="list-style-type: none"> <li>• Priced, modeled and executed exotic and bespoke products</li> <li>• Created and analyzed systematic hedging strategies and trade ideas</li> </ul>	