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Explaining Sequential Model-Based Optimization

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- **Research gap:** the AF's choice in SMBO is not transparent → **why** are specific parameter values chosen in each iteration?
- **Idea:**
 - ① distribute the desirability/utility of a proposal among its parameters
 - ② further, split their desirability into mean and uncertainty effect
- **Solution:** Shapley value mainly because
 - ① in a few minutes...
- **Main contribution:** provide a tool, based on SV, ready to use for SMBO users to explain the proposals of the AF (ShapleyMBO)
- **Goal:** increase transparency of SMBO

- HPO as an independent research field has various HPI that could be adapted to our purposes

① Local Parameter Importance [1]: $contr_{LPI}(j) = \frac{Var_{a \in \Theta_j} \hat{g}(\theta[\theta_j=a])}{\sum_{l \in P} Var_{b \in \Theta_l} \hat{g}(\theta[\theta_l=b])}$

Problem: $contr_{LPI}(j) \in \mathbb{R}_0^+$ (≠EETO)

② Ablation Analysis [2]: $contr_{AA}(j) = \hat{g}(\theta^s) - \hat{g}(\theta^s[\theta_j^s = \theta_j^t])$

Problem: no consideration of interactions → an "avenue for further work is to make support for complex parameter interdependencies more flexible, for example [...] **to allow sets of parameters without conditional relationships to be modified in the same ablation round**" [2, p.456].



- Assume grand coalition P , contribution function v and game (P, v) . Further, assume that $\Pi(P)$ is the set of all permutations of P with $\pi \in \Pi(P)$, and $Pre_\pi(j)$ is the coalition consisting of the predecessors of player j .

$$\begin{aligned} contr_{SV}(j) = \phi_j(v) &= \frac{1}{p!} \sum_{\pi \in \Pi(P)} v(Pre_\pi(j) \cup \{j\}) - v(Pre_\pi(j)) \\ &= \sum_{S \subseteq P \setminus \{j\}} \frac{|S|! (p-1-|S|)!}{p!} [v(S \cup j) - v(S)] \end{aligned}$$

- + allows also negative contributions ($contr_{SV}(j) \in \mathbb{R}$)
- + incorporate interactions and interacting features are equally remunerated for the worth the coalition

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- the AF is nothing but a transformed surrogate model
- **Turning point:** CB criterion together with the Linearity axiom are the perfect solution¹:

$$\phi(cb) = \phi(m - \lambda \cdot se) = \phi(m) - \lambda \cdot \phi(se)$$

Up today we only had information on configuration level. Now, with the SV and the CB we can dig deeper and \Rightarrow

- ① assess the overall desirability of the chosen parameters
- ② understand **why** parameters are desirable, bringing to light previously hidden aspects of the EETO

¹assuming *min* problems CB becomes LCB

Algorithm 1 ShapleyMBO

Require: SMBO result object *mbo*, iteration of interest *t*, **sample size *K***

- 1: get explicand from *mbo*: $\tilde{\theta} = \theta_t^{new}$
- 2: **sample 1000 · *p* points *Z* from Θ** to approximate the space
- 3: **compute $\hat{\phi}(m) = (\hat{\phi}_1(m), \dots, \hat{\phi}_p(m))$:**
- 4: get SM from *mbo*: $\hat{f}_m = \hat{f}_t^{mean}$
- 5: explain $\tilde{\theta}$ with `iml::Shapley()` using *Z*, \hat{f}_m and *K*
- 6: **compute $\hat{\phi}(se) = (\hat{\phi}_1(se), \dots, \hat{\phi}_p(se))$:**
- 7: get SM from *mbo*: $\hat{f}_{se} = \hat{f}_t^{uncertainty}$
- 8: explain $\tilde{\theta}$ with `iml::Shapley()` using *Z*, \hat{f}_{se} and *K*
- 9: compute $\hat{\phi}(cb)$ with **linearity axiom**:
- 10: $\hat{\phi}(cb) = \hat{\phi}(m) - \lambda \hat{\phi}(se)$

- built on `{mlrMBO}` and `{iml}`
- supports: Single-objective, Single-point, Min-problems, `{mlrMBO}` built-in infill criteria (*), decomposition only for LCB (using `contribution = T`)
- plot results with `plotShapleyMBO` [▶ here](#)

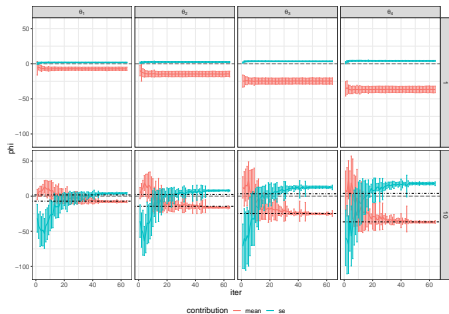
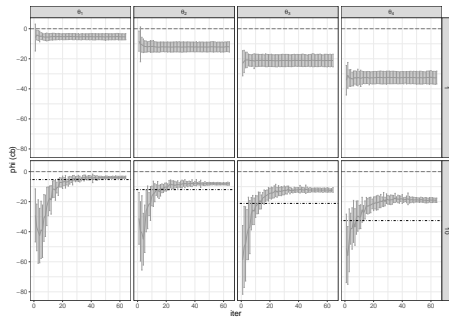
- can be found with `checkSampleSize` (later)
- recreate global AF search, sampling population for SV estimation, generates $\mathbb{E}[v(\Theta)]$ [▶ GS](#)
- same Shapley objects (except for prediction function), otherwise recreate wrong *cb* contributions (achieved with seeds setting)
- create custom prediction function in `{iml}`, that predicts uncertainty
- implemented by internal function `computePhiCb`

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- ① Application on Hyper-Ellipsoid: Test function with known analytical description
 - Does ShapleyMB0 deliver consistent results?
 - Does ShapleyMB0 react to different LCB settings?
- ② Application on MLP: real tuning example
 - show how users might benefit from ShapleyMB0

(*) LCB is minimized $\rightarrow \hat{cb} < \bar{cb}$. For a better intuition, when $\phi_j(cb) < 0$, we say that the contribution is **positive**. The analogous logic is applied to m and se contributions.



$$\mathcal{P}(cb) = (\hat{m} - \bar{m}) + \lambda(\bar{s}e - \hat{s}e)$$

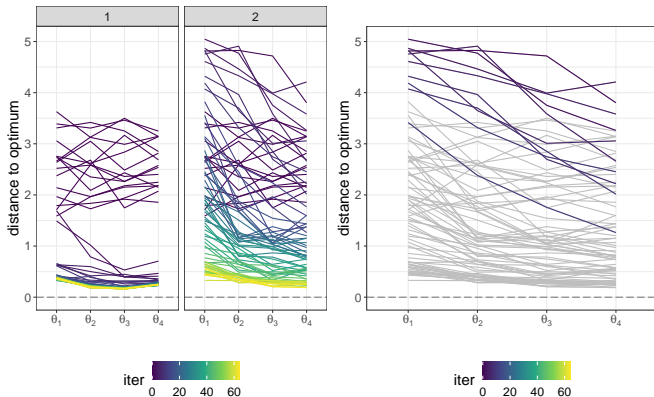


Figure: Design paths for both λ (left $\lambda = 1$, right $\lambda = 10$). For each parameter the average distance of the actual parameter value to its optimum $\theta_j^* = 0$ is displayed. Right Plot displays $\lambda = 10$ with only 10 iterations highlighted

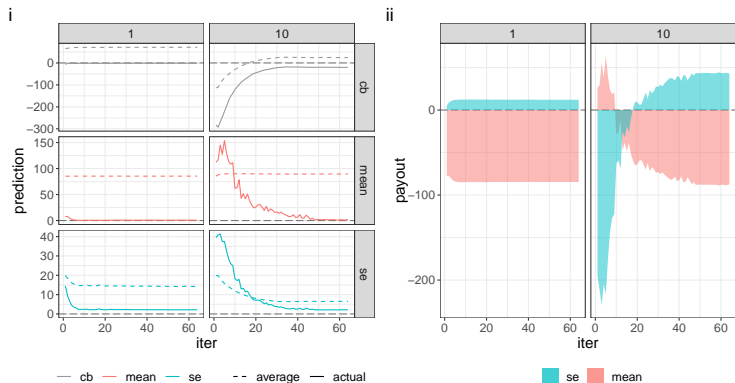


Figure: Payout paths for the Hyper-Ellipsoid optimization: (i) individually (se not scaled, (ii) m and se together, centered around their average prediction, se scaled

$$\mathcal{P}(cb) = (\hat{m} - \bar{m}) + \lambda(\bar{se} - \hat{se})$$

- **Idea:** find a sufficiently high sample size by greedy forward search
- contributions come with an efficiency error $\Delta_{eff}^K(v)$
- for $K \uparrow \Rightarrow \Delta_{eff}^K(v) \downarrow$
- **Approximations problematic** when ranking changes after redistributing $\Delta_{eff}^K(v)$
- **Solution:** error "position" is unclear, but ...
- it is sufficient to test $\Delta_{eff}^K(v)$ against the smallest contributions' distance between two parameters $\delta^K(v)$ (threshold) to check K
 - ① if ranking **does not change** using the smallest distance \rightarrow ranking **can not change** among multiple parameters either
- **Rule:** if $\Delta_{eff}^K(v) < \delta^K(v) \Rightarrow$ ranking can not change after correction $\Rightarrow K$ is sufficiently high

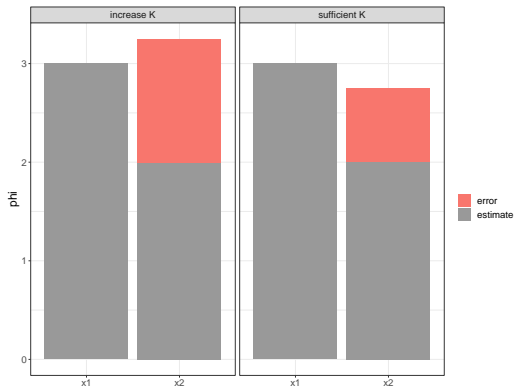
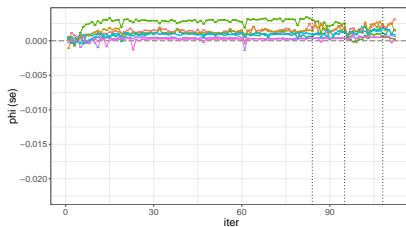
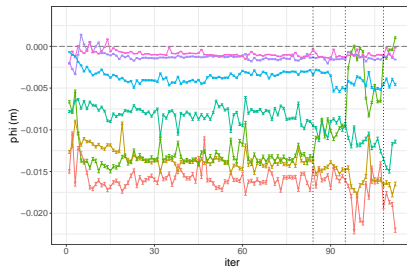
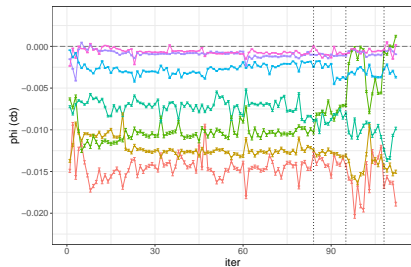
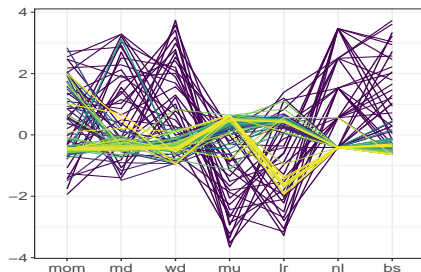


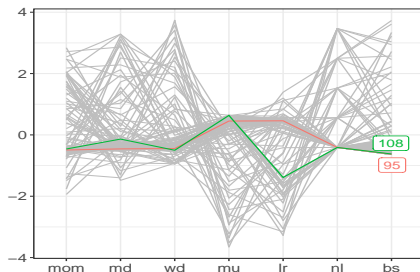
Figure: Example checkSampleSize



feature — batch_size — learning_rate — weight_decay — momentum
— num_layers — max_units — max_dropout



iter
0 30 60 90



iter	lr	\bar{lr}	error	\hat{m}	\hat{se}	$\hat{\phi}_{lr}^{rel}(cb)$	$\hat{\phi}_{lr}^{rel}(m)$	$\hat{\phi}_{lr}^{rel}(se)$
95	0.0079	0.007	0.2222	0.2226 (3.6)	0.0003 (8.0)	0.15	0.17	0.27
108	0.0041	0.007	0.2225	0.2229 (12.5)	0.0011 (66.1)	0.01	0.02	0.06

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Sampling strategy determines the average prediction and hence, indirectly, also the contributions (▶ ShapleyMBO)

Global sampling

- + recreates the global AF search
- + stable desirability paths
- mean contributions positively and se contributions negatively biased

⇒

- 1 awareness of GS effects → **globally** undesirable parameters
- 2 use additional materials for plausibility checks and interpretation of results
- 3 implement local sampling to further investigate results

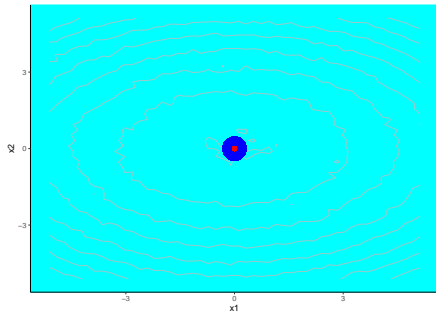


Figure: explicand (red), local (blue), global (cyan)

- Both analyses suggests that the SV is a valid method and ShapleyMBO is a diagnostic tool of great potential
- This thesis only set the first milestone and there are several improvements in which we should invest resources
 - ① more exhaustive validation phase
 - ② implement other sampling strategies
 - ③ implement the BS
 - ④ more research on mean contributions as HPI
 - ⑤ extend decomposition to other AF, e.g. the EI

$$EI(\theta) = (\psi^{min} - m(\theta))\Phi\left(\frac{\psi^{min} - m(\theta)}{se(\theta)}\right) + se(\theta)\phi\left(\frac{\psi^{min} - m(\theta)}{se(\theta)}\right)$$

We sincerely hope that with this project we contributed, although infinitesimally, to the improvement of the SMBO transparency.

Thank you for your attention.

Still some time left?

- used to display the results of ShapleyMBO
- supports various options:
 - ① single (bar-plot) and multiple iterations (line-plot, so called *desirability paths*)
 - ② uncertainty estimates using CI intervals $CI_{1-\alpha} = [\hat{\phi}_j \pm t_{(1-\frac{\alpha}{2}, K-1)} \frac{\hat{\sigma}_j}{\sqrt{K}}]$, with $\alpha = \{0.01, 0.05, 0.1\}$
 - ③ various plot combinations via decomp argument, each plot can also be used/saved/modified individually {patchwork}
 - ④ contribution = {T, F}

Back to [► ShapleyMBO](#)

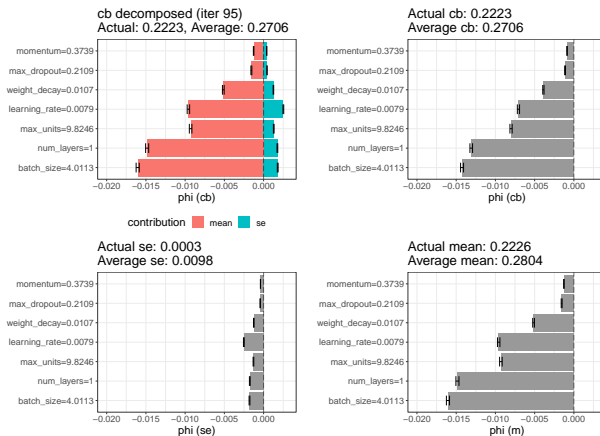


Figure: This figure shows how the complete output of `plotShapleyMB0` for single iteration looks. Here, we show the results of `ShapleyMB0` in the MLP application in iteration 95.



introduced by Sundararajan and Najmi [4]

$$v(S) = \hat{f}(\tilde{\theta}_S; \theta'_{P \setminus S}) \Rightarrow v(\emptyset) = \hat{f}(\theta')$$

- + complementary results interpretation
 - + no independence assumption
 - AF choice explained relative to one configuration only
 - baseline choice can be complicated, but
- ⇒ special case of SMBO for HPO
- ① default baseline provided by libraries
 - ② adaptive baseline using incumbent configuration



- Idea: We could use the mean contributions as a HPI metric
- Problem: results strongly on the quality of the surrogate models
- The aim of the project was to explain the choices of AF, hence using the actual SM is the best way to do that. But, using the SM to generalize importance scored is dangerous
- Use mean contributions as HPI with care!

	<i>bs</i>	<i>md</i>	<i>mu</i>	<i>nl</i>	<i>lr</i>	<i>mom</i>	<i>wd</i>
$\hat{\phi}(m)_{sm_{95}}$	-0.016	-0.002	-0.009	-0.015	-0.010	-0.001	-0.005
$\hat{\phi}(m)_{sm_{113}}$	-0.015	-0.002	-0.012	-0.016	-0.007	-0.001	-0.005

Table: Comparison of the mean contributions of the best-predicted proposal (iteration 95) in the MLP tuning example using the actual surrogate model (iteration 95) and the final surrogate model.

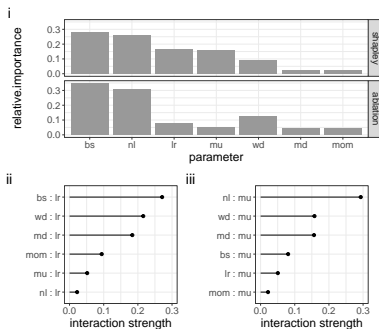


Figure: Relative m contribution of the parameters for configuration proposed in iteration 95 (plot i). To understand the difference in the results the interaction strength of learning rate (plot ii) and max units (plot iii) with other parameters is computed using Friedman's H-Statistic (interaction between two features).

	<i>bs</i>	<i>nl</i>	<i>lr</i>	<i>mu</i>	<i>wd</i>	<i>md</i>	<i>mom</i>
relative SV	0.278	0.257	0.166	0.161	0.089	0.027	0.022
relative AA	0.348	0.307	0.076	0.050	0.128	0.044	0.047

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- [1] A. Biedenkapp, J. Marben, M. Lindauer, and F. Hutter. Cave: Configuration assessment, visualization and evaluation. In *International Conference on Learning and Intelligent Optimization*, pages 115–130. Springer, 2018.
- [2] C. Fawcett and H. H. Hoos. Analysing differences between algorithm configurations through ablation. *Journal of Heuristics*, 22(4):431–458, 2016.
- [3] V. Picheny, T. Wagner, and D. Ginsbourger. A benchmark of kriging-based infill criteria for noisy optimization. *Structural and Multidisciplinary Optimization*, 48(3):607–626, 2013.
- [4] M. Sundararajan and A. Najmi. The many shapley values for model explanation. In H. D. III and A. Singh, editors, *Proceedings of the 37th International Conference on Machine Learning*, volume 119 of *Proceedings of Machine Learning Research*, pages 9269–9278, Virtual, 13–18 Jul 2020. PMLR.

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Algorithm 2 SMBO basic procedure I

- 1: create an initial design $\mathcal{D} = \{(\theta^{(i)}, \Psi^{(i)})\}_{i=1}^{n_{init}}$
- 2: **while** termination criterion is not fulfilled **do**
- 3: **fit** a surrogate model \hat{f} on design \mathcal{D}
- 4: **propose** $\theta^{new} = \arg\min_{\theta \in \Theta} u(\theta|\mathcal{D})$
- 5: **evaluate** Ψ on θ^{new} and **update** $\mathcal{D} \leftarrow \mathcal{D} \cup (\theta^{new}, \Psi(\theta^{new}))$
- 6: **end while**

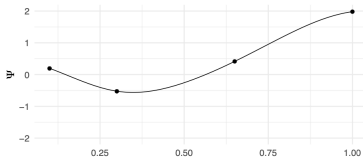
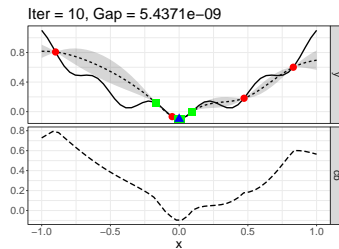
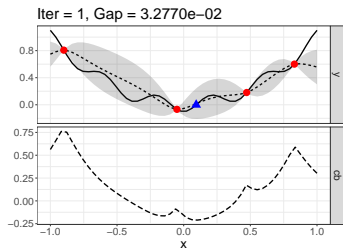


Figure: surrogate model fit, credits: Fortgeschrittene Computerintensive Methoden - lecture slides, Bischl B. and Moosbauer J. (2019)



Suppose u is minimized and predicted with a RF model, source and target are respectively $\theta^s = (0.5, 0.5, 0.5)^T$ and $\theta^t = (0, 0, 0)^T$.

$$u = \theta_1 + \theta_2 \cdot \theta_3 + \epsilon$$

$$\theta_1, \theta_2, \theta_3 \stackrel{i.i.d}{\sim} \mathcal{U}(0, 1), \epsilon \sim \mathcal{N}(0, 0.05^2),$$

We expect similar contributions for θ_2 and θ_3 , and yet

parameter	aa round 1	relative aa	relative sv
θ_1	0.483	0.66	0.66
θ_2	0.262	0.31	0.21
θ_3	0.258	0.03	0.17

\Rightarrow unfair contribution of θ_3 , which has a very similar, unconditional effect in the first round

- $contr_{SV} \in \mathbb{R}$, better to explain EETO
- $contr_{SV}$ considers all possible interactions

parameter	aa round 1	relative aa	relative sv
θ_1	0.483	0.66	0.66
θ_2	0.262	0.31	0.21
θ_3	0.258	0.03	0.17

⇒ fair contribution of θ_3 !

- the SV is a better method for the purposes of our project, **in addition...**

get back to [▶ SV theory](#)



Dummy player: If $v(S \cup \{j\}) - v(S) = v(j)$ for player j and all $S \subseteq P \setminus \{j\}$, then $\phi_j(v) = v(j)$.

Efficiency: $\sum_{j=1}^p \phi_j(v) = v(P) - v(\emptyset)$

Linearity: Given two games (P, v_1) and (P, v_2) , for $a, b \in \mathbb{R}$ it holds

$$\phi_j(av_1 + bv_2) = a\phi_j(v_1) + b\phi_j(v_2)$$

Symmetry: If $v(S \cup \{j\}) = v(S \cup \{l\})$ for players j, l and every $S \subseteq P \setminus \{j, l\}$, then $\phi_j(v) = \phi_l(v)$

Algorithm 3 Estimation of the CES

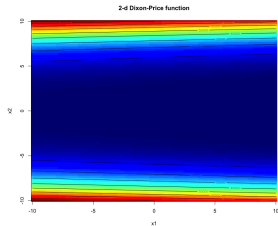
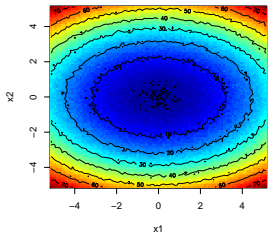
Require: explicand $\tilde{\theta}$, feature index j , model \hat{f} and sample size K

- 1: **for** $k = 1 \rightarrow K$ **do**
 - 2: sample (at random and with replacement) an instance $\mathbf{z} \in \Theta$
 - 3: sample (at random and with replacement) an order $\pi \in \Pi(P)$
 - 4: order $\tilde{\theta}$ and \mathbf{z} according to π
 - 5: $\tilde{\theta}_{\pi} = (\tilde{\theta}_{(1)}, \dots, \tilde{\theta}_{(p)})$
 - 6: $\mathbf{z}_{\pi} = (z_{(1)}, \dots, z_{(p)})$
 - 7: construct two new instances
 - 8: $\tilde{\theta}_{+j} = (\tilde{\theta}_{(1)}, \dots, \tilde{\theta}_{(j-1)}, \tilde{\theta}_{(j)}, z_{(j+1)}, \dots, z_{(p)})$
 - 9: $\tilde{\theta}_{-j} = (\tilde{\theta}_{(1)}, \dots, \tilde{\theta}_{(j-1)}, z_{(j)}, z_{(j+1)}, \dots, z_{(p)})$
 - 10: $\hat{\phi}_j^k(v) = \hat{f}(\tilde{\theta}_{+j}) - \hat{f}(\tilde{\theta}_{-j})$
 - 11: **end for**
 - 12: $\hat{\phi}_j(v) = \frac{1}{K} \sum_{k=1}^K \hat{\phi}_j^k(v)$
-

In both analyses, where possible we use default SMBO setting

hyperparameter	value
<i>min</i> objective function	TRUE
noisy objective	TRUE
initial design	size $4p$ sampled with maximin LHS
surrogate model	GP regression
kernel function	$\frac{3}{2}$ -Matérn
acquisition function	LCB
<i>min</i> acquisition function(*)	TRUE
infill optimizer	focussearch ($n_r = 3, n_i = 5, n_p = 1000$)
termination condition	max. evaluations $20p[3, p.614]$

- scalable dimensions: $4p$ is not too low and not too high
- intuitive functional form: clear *mean* contribution
- same parameter's domain: clear *se* contributions
- convex, clear optimum region and smooth: algorithmic paths somehow predictable (smooth convergence), useful for expectations on *cb* contributions

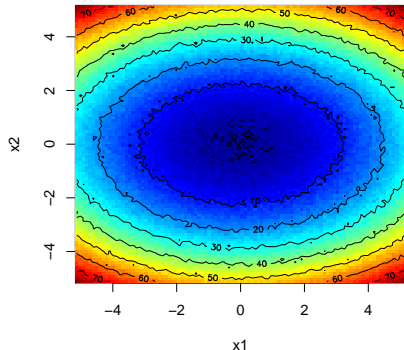


get back to [Hyper-Ellipsoid](#)

$$f(\boldsymbol{\theta}) = \sum_{j=1}^4 j \cdot \theta_j^2, \theta_j \in [-5.12, 5.12] \text{ for}$$

$$\boldsymbol{\theta}^* = (0, 0, 0, 0)^T \text{ and } f(\boldsymbol{\theta}^*) = 0.$$

- $\epsilon \stackrel{i.i.d}{\sim} \mathcal{N}(0, \sigma^2)$ observation noise added, where $\sigma = 0.05 \cdot \hat{\sigma}_{HE}$ [3, p.613]
- $\lambda \in \{1, 10\}$
- 30 runs for each λ
- $K = 1000$



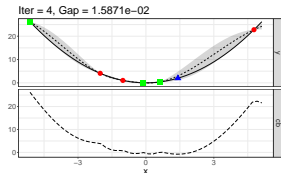
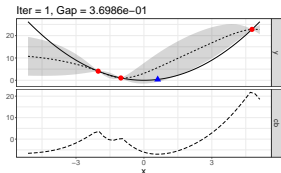
- Although (i) contributions depends on proposed values and (ii) each dimensions might be explored and exploited differently, we tried to formulate general expectations
- For $\lambda = \{1, 10\}$: similar $\phi(m)$, $\phi(se)$ stronger for $= 10$

$$f(\theta) = 1\theta_1^2 + 2\theta_2^2 + 3\theta_3^2 + 4\theta_4^2$$

$$\theta^* = (0, 0, 0, 0)^T$$

$$\theta_j \in [-5.12, 5.12]$$

- $\phi(m)$: distance to θ^* , higher parameters more important
- $\phi(se)$: equally important, conditional on dimension exploration
- $\phi(cb)$: convex f , smooth convergence \rightarrow initially $\phi(se)$, then $\phi(m)$



Purpose: compare "similar" points to understand the effect of λ

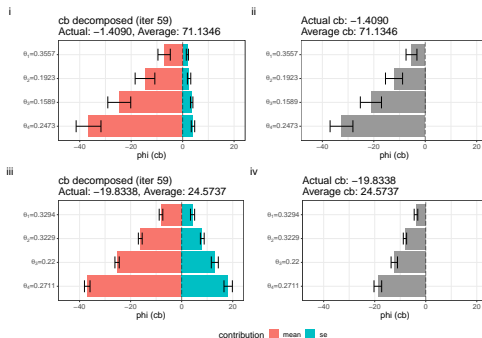
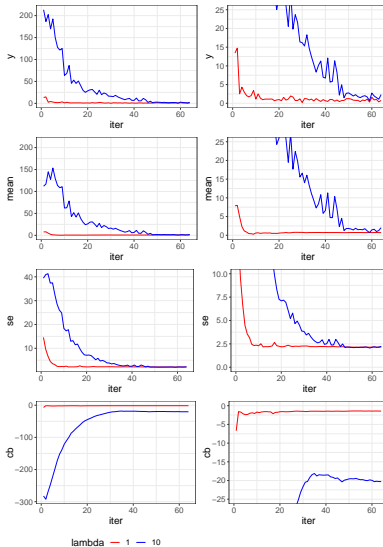


Figure: results in iteration 59 for $\lambda = 1$ on top, for $\lambda = 10$ at the bottom.

	y	\bar{cb}	\bar{cb}	$\mathcal{P}(cb)$	\hat{m}	\bar{m}	$\mathcal{P}(m)$	\hat{se}	\bar{se}	$\mathcal{P}(se)$
$\lambda = 1$	0.34	-1.41	71.13	-72.54	0.73	85.38	-84.64	2.14	14.25	12.11
$\lambda = 10$	0.66	-19.83	24.57	-44.40	0.72	89.47	-88.75	2.06	6.49	44.3





		θ_1	θ_2	θ_3	θ_4
$\lambda = 1$	$\hat{\phi}(cb)$	-5.35 (2.12)	-12.14 (3.33)	-21.12 (4.11)	-32.56 (4.44)
	$\hat{\phi}(m)$	-7.20 (2.4)	-14.64 (3.83)	-24.63 (4.46)	-36.58 (4.83)
	$\hat{\phi}(se)$	1.85 (0.42)	2.50 (0.66)	3.51 (0.47)	4.02 (0.67)
$\lambda = 10$	$\hat{\phi}(cb)$	-3.82 (0.7)	-8.14 (0.65)	-12.32 (1.26)	-18.77 (1.5)
	$\hat{\phi}(m)$	-8.09 (0.71)	-16.22 (0.75)	-25.31 (0.84)	-36.99 (1.09)
	$\hat{\phi}(se)$	4.27 (0.81)	8.08 (0.74)	12.99 (1.37)	18.22 (1.64)

Table: Contributions in iteration 59 for both λ

	with <i>id</i>	θ_1	θ_2	θ_3	θ_4
$\lambda = 1$	yes	0.95	0.99	1.01	0.98
[1 – 58]	no	0.24	0.15	0.08	0.07
$\lambda = 10$	yes	1.29	1.26	1.15	1.07
[1 – 58]	no	1.40	1.31	1.11	0.97

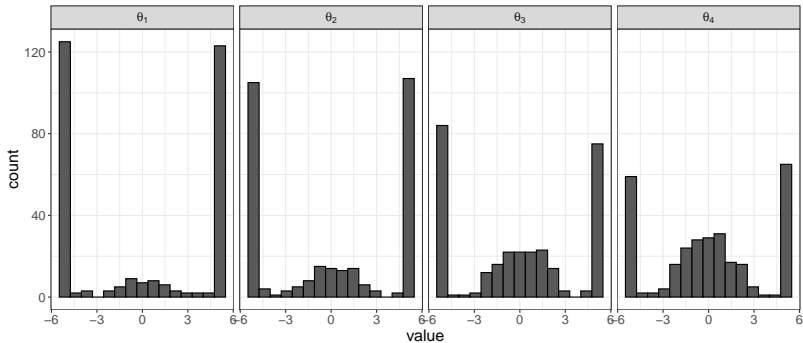
Table: Exploration of each dimension up to iteration 58 (iteration 1 to 58 are included). Column *with id* indicates if the initial design was included or not. The exploration is measured as the standard deviation of the average distance of the configurations from its optimal value $\theta_j^* = 0$.



		θ_1	θ_2	θ_3	θ_4
$\lambda = 1$	$\hat{\phi}(cb)$	-5.29 (2.22)	-11.97 (3.57)	-21.6 (4.41)	-32.59 (4.41)
[1 – 64]	$\hat{\phi}(m)$	-7.10 (2.53)	-14.44 (4.09)	-24.66 (4.54)	-36.57 (4.81)
	$\hat{\phi}(se)$	1.81 (0.48)	2.47 (0.68)	3.50 (0.52)	3.98 (0.70)
$\lambda = 10$	$\hat{\phi}(cb)$	-33.04 (16.06)	-30.35 (14.83)	-37.68 (16.62)	-38.88(14.21)
[1 – 10]	$\hat{\phi}(m)$	8.43 (9.06)	10.97 (15.62)	9.05 (27.14)	2.42 (34.65)
	$\hat{\phi}(se)$	-41.47 (21.48)	-41.33 (26.12)	46.73 (37.29)	41.3 (39.38)
$\lambda = 10$	$\hat{\phi}(cb)$	-3.81(0.77)	-8.12(0.8)	-12.31(1.31)	-19.01(1.54)
[55 – 64]	$\hat{\phi}(m)$	-7.79 (1.16)	-16.12 (1.01)	-25.09 (1.47)	-39.96 (1.27)
	$\hat{\phi}(se)$	3.98 (1.06)	8.00 (0.89)	12.78 (1.64)	17.94 (1.76)

Table: Contributions averaged over multiple iterations in the process. Range in brackets below λ indicates the iterations included.

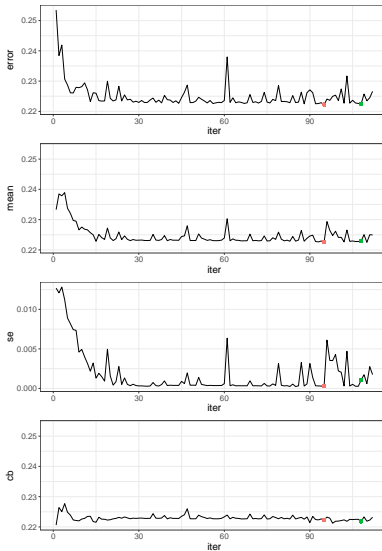
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- real application example: tuning of a multilayer perceptron for a speech recognition classification task using SMBO with LCB and $\lambda = 1$ (*min* validation error)

HP	Notation	Type	Lower	Upper	Trafo
batch size	<i>bs</i>	numeric	$\log_2 16$	$\log_2 512$	2^x
max dropout	<i>md</i>	numeric	0	1	
max units	<i>mu</i>	numeric	$\log_2 64$	$\log_2 1024$	2^x
number of layers	<i>nl</i>	integer	1	5	
learning rate	<i>lr</i>	numeric	0	0.01	
momentum	<i>mom</i>	numeric	0.1	1	
weight decay	<i>wd</i>	numeric	0	0.1	

- SV estimation with $K = 20000$ found with `checkSampleSize` among $\{100, 1000, 5000, 10000, 15000, 20000\}$



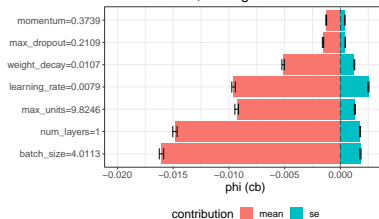


	<i>bs</i>	<i>nl</i>	<i>mu</i>	<i>lr</i>	<i>wd</i>	<i>md</i>	<i>mom</i>
$\hat{\phi}(cb)$	-0.014	-0.013	-0.008	-0.007	-0.004	-0.001	-0.001
$\hat{\phi}(m)$	-0.016	-0.015	-0.009	-0.010	-0.005	-0.002	-0.001
$\hat{\phi}(se)$	0.002	0.002	0.001	0.003	0.001	0.000	0.000

Table: Contributions of the parameters in iteration 95 for the MLP optimization problem. Payout \mathcal{P} for cb , m and se are respectively -0.048 , -0.058 , 0.09 .

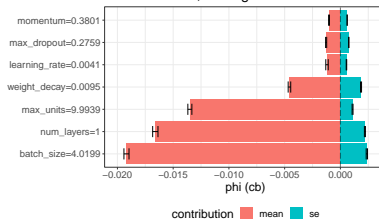
cb decomposed (iter 95)

Actual: 0.2223, Average: 0.2706



cb decomposed (iter 108)

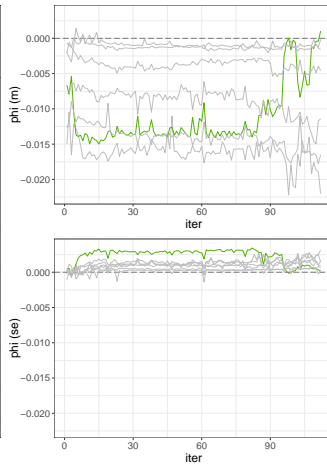
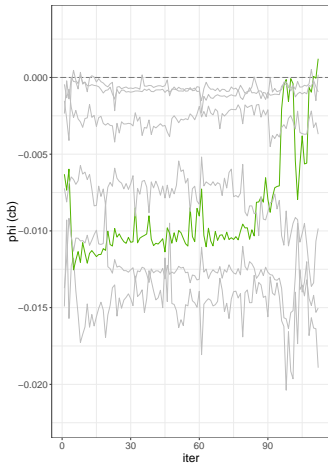
Actual: 0.2219, Average: 0.2698



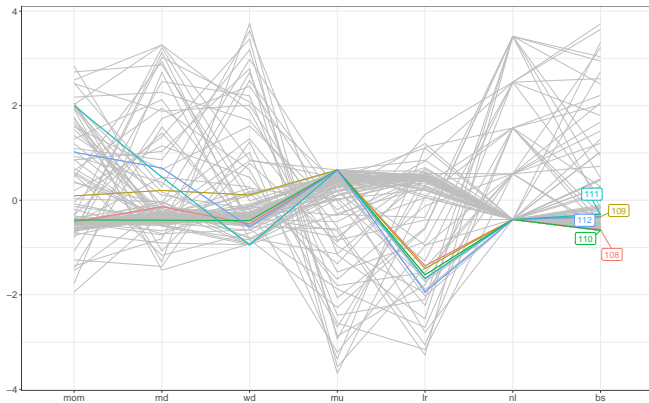
Algorithm 4 checkSampleSize

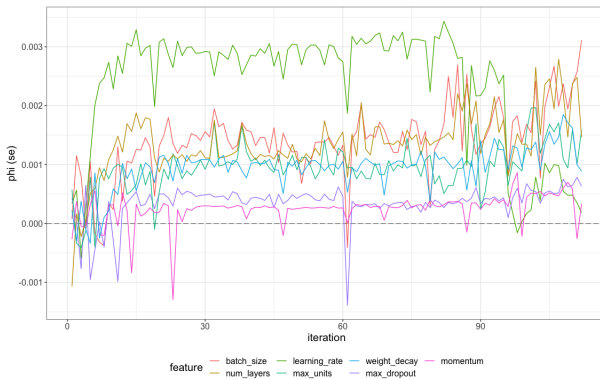
Require: ShapleyMB0 results for $\tilde{\theta}_t$ with size K , models \hat{f}^v with $v = \{cb, m, se\}$

```
1: for  $w$  in  $v$  do
2:   compute payout  $\mathcal{P}(w)$ , error  $\Delta_{eff}^K(w)$  and threshold  $\delta^K(w)$ 
3:   if  $\Delta_{eff}^K(w) < \delta^K(w)$  then
4:      $K_w = T$ 
5:   end if
6:   if  $\Delta_{eff}^K(w) \geq \delta^K(w)$  then
7:      $K_w = F$ 
8:   end if
9: end for
10: if  $(K_{cb}, K_m, K_{se}) = (T, T, T)$  then
11:    $K$  is high enough
12: else if  $(K_{cb}, K_m, K_{se}) \neq (T, T, T)$  then
13:    $K$  should be increased
```



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- umbrella package for many IML tools → homogenous results
- “in House” package
- Big potential for future work: IML tools provided show that `{iml}` package can be adapted to the interpretation of BO processes
→ Apply `PredictorAf` object to other IML tools



- before measuring the SV the `{iml}` package requires a `Predictor` object, which basically contains the data and the ML model
- we created a new object called `PredictorAf`, which inherits from the `Predictor` class and can be used in combination with `Shapley`
- How?
 - ① `data` → sampling population
 - ② `pred.fun` → `acf.fun`
 - ③ some infill criteria (e.g. EI) need design points → new field called `design` (correspond to data in `Predictor`)
 - ④ some additional fields
- adjustments from our Cosulting Project