Testing for Harmonizability

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Abstract

Let R(s,t) be a covariance function having the representation

$$R(s,t) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \exp\left(i s x - i t y\right) d^2 G(x,y) \tag{1}$$

where G(x,y) is continuous to the right in both variables and is of bounded variation in the plane; then R(s,t) is harmonizable in that G(x,y) is also a covariance. Examples are given in which this result is used to determine the harmonizability of new processes and covariances that are formed by operations on old processes and covariances. Specifically, if X(t) is a real Gaussian harmonizable process, then $X^n(t)$ is harmonizable. If X(t) is harmonizable, G(x,y) has bounded support and g(t) is a Fourier-Stieltjes transform, then X(g(t)) and X(t+g(t)) are harmonizable. If

$$X(t) = \int_{-\infty}^{\infty} f(t, u) \ dZ(u)$$
 (2)

where f(t,u) = f(t-u) is a Fourier-Stieltjes transform and $G(u,v) = \mathbb{E}\{Z(u)Z^*(v)\}$ has finite total variation, then X(t) is harmonizable. A sufficient condition for Priestley's oscillatory processes to be harmonizable is also obtained. The Bochner-Eberlein characterization of Fourier-Stieltjes transforms is particularly convenient for determining harmonizability in these cases.

1 Introduction

Let $\{X(t,\omega), -\infty < t < \infty, \omega \in \Omega\}$ be a second-order continuous-parameter stochastic process defined on some probability space $(\Omega, \mathcal{F}, \mathbb{P})$. The process $X(t,\omega)$ is said to be harmonizable [loeve1955probability, p. 474] if it has the quadratic mean representation

$$X(t,\omega) = \int_{-\infty}^{\infty} \exp(itx) dZ(x,\omega)$$
 (3)

where $\{Z(x,\omega), -\infty < x < \infty\}$ is a process whose covariance is of bounded variation (BV) in the plane. Harmonizable processes are of engineering interest because decomposition relative to $\exp(itx)$ admits the usual frequency interpretation of linear filtering. If H(x) is the frequency response of a stable, linear time-invariant system, then the system output process $Y(t,\omega)$ is given by the quadratic mean integral

$$Y(t,\omega) = \int_{-\infty}^{\infty} \exp(itx) H(x) dZ(x,\omega)$$
(4)

A detailed account may be found in [blanc-lapierre1968random, Ch. 8]. For recent results on harmonizable processes in engineering, see [cambanis1970harmonizable, donati1971spectra, ogura1971spectra].

The covariance functions for X(t) and Y(t) are

$$R(s,t) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \exp\left(i s x - i t y\right) d^2 G(x,y)$$
 (5)

$$R_Y(s,t) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \exp(i s x - i t y) H(x) H^*(y) d^2 G(x,y)$$
 (6)

where $d^2G(x,y) = \mathbb{E} \{d\,Z(x)\,d\,Z^*(y)\}$. Any covariance with representation (5), with G(x,y) a covariance of bounded variation, is called harmonizable; harmonizable processes have harmonizable covariances. Conversely, processes with harmonizable covariances are themselves harmonizable [loeve1955probability, p. 476]. For brevity, we call those corresponding to G with finite total variation simply "harmonizable."

This paper addresses the determination of harmonizability for new processes or covariances constructed from old ones. The main results are as follows:

- If X(t) is a real Gaussian harmonizable process, then $X^n(t)$ is harmonizable.
- If X(t) is harmonizable with spectral decomposition of bounded support and g(t) is a Fourier-Stieltjes transform, then X(t+g(t)) and X(g(t)) are harmonizable.
- If R_1 and R_2 are harmonizable covariances, then for T of finite Lebesgue measure,

$$R_3(s,t) = \int_T R_1(s,u) R_2(u,t) du$$
 (7)

is harmonizable.

- If X(t) is a moving average as in (2) with f(t, u) = f(t u) a Fourier-Stieltjes transform and G(u, v) of bounded variation, then X(t) is harmonizable.
- If X(t) is as above, Z(u) has orthogonal increments with $dF(u) = \mathbb{E} |dZ(u)|^2$ and

$$f(t, u) = \exp(i u t) \int_{-\infty}^{\infty} \exp(i t x) dH_u(x)$$
(8)

with $H_u(x)$ of bounded variation for every u, the resulting processes include Priestley's oscillatory processes [priestley1965evolutionary], which are harmonizable under suitable conditions.

The method is to use the following result.

Theorem 1. If R(s,t) is simultaneously a covariance and a Fourier-Stieltjes (FS) transform with respect to some G(x,y) of bounded variation, then R(s,t) is harmonizable in that G is necessarily a covariance.

Proof. Sufficiency is immediate: one can find a process $Z(x,\omega)$ whose covariance is G and whose FS transform $X(t,\omega)$ as in (3) has covariance R(s,t). Conversely, suppose R is both a covariance and an FS transform with respect to some G that is BV. Define

$$G_a(x,y) = G(x,y) - G(a,y) - G(x,a) + G(a,a)$$
(9)

For any n and sequence $\{x_j \ge a, j = 1, ..., n\}$ and complex $\{c_j\}$,

$$\sum_{j,k=1}^{n} c_j c_k^* G_a(x_j, x_k) \ge 0$$

This follows by constructing $g_a(s) = \sum_{j=1}^n c_j [1 - \exp(-i s x_j)] \exp(-i s a)$ and applying the inversion theorem [loeve1955probability, p. 475]. Letting $a \to -\infty$, $G_a(x, y) \to G(x, y)$. Thus G(x, y) is non-negative definite.

Thus, any characterization of FS transforms, such as the Bochner-Eberlein theorem, also provides a characterization for harmonizable covariances [bochner1934fst, eberlein1955fst, rudin1962groups]. Cramér [cramer1939representation] and Dominguez [dominguez1940fst] provide alternative characterizations.

2 Mathematical Preliminaries

Assume G(x, y) is normalized, e.g.,

$$G(x,y) = \frac{1}{4} \left[G(x+0,y+0) + G(x+0,y-0) + G(x-0,y+0) + G(x-0,y-0) \right]$$
 (10)

and satisfies

$$\lim_{x \to -\infty} G(x, y) = \lim_{y \to -\infty} G(x, y) = 0.$$

We now state the key characterizations.

Theorem 2. [Bochner]A necessary and sufficient condition that f(t), $-\infty < t < \infty$, has the representation

$$f(t) = \int_{-\infty}^{\infty} \exp(ixt) dG(x)$$
(11)

for a complex measure G of bounded variation is that, for any n, any sequence $\{t_j\}_{j=1}^n$ and any complex $\{c_j\}_{j=1}^n$,

$$\left| \sum_{j=1}^{n} c_j f(t_j) \right| \le M \left[\sum_{j=1}^{n} \sum_{k=1}^{n} c_j c_k^* \exp\left(i x \left(t_j - t_k\right)\right) \right]^{1/2}$$
(12)

for some M > 0.

Theorem 3. [Bochner-Eberlein]A necessary and sufficient condition for a function R(s, t) to have representation (1) with

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} |d^2 G(x, y)| \le M \tag{13}$$

is that for any n, any sequence of pairs $\{(s_j,t_j)\}_{j=1}^n$ and any complex $\{c_j\}_{j=1}^n$,

$$\left| \sum_{j=1}^{n} c_{j} R(s_{j}, t_{j}) \right| \leq M \left[\sum_{j=1}^{n} \sum_{k=1}^{n} c_{j} c_{k}^{*} \exp\left(i \left(x s_{j} - y t_{j} - x s_{k} + y t_{k}\right)\right) \right]^{1/2}$$
(14)

for some M > 0.

3 Examples and Application

Example 4. Let X(t) be a zero-mean real Gaussian harmonizable process with covariance R(s,t). Then, for any $n \ge 1$, $X^n(t)$ is harmonizable.

Proof. An exercise with characteristic functions shows that

$$\mathbb{E}\left[X^{n}(s) X^{n}(t)\right] = \sum_{p,q,r \ge 0} c_{z}(p,q,r,n) R^{p}(s,s) R^{q}(s,t) R^{r}(t,s) R^{p}(t,t)$$
(15)

where the sum is over all $p, q, r \ge 0$ with n = 2p + q + r and $c_z(p, q, r, n)$ are combinatorial coefficients.

Since both FS transforms [bochner1934fst, p.151] and covariances [loeve1955probability, p.468] are closed under products, $R^q(s,t) R^r(t,s) = R^{q+r}(s,t)$ is an FS transform and a covariance. The product $R^p(s,s) R^p(t,t)$ is also an FS transform, as for f(s) = R(s,s)

$$f^p(s) f^p(t)$$

is NND and an FS transform by Theorem 2. The sum in (15) is harmonizable since FS transforms and covariances are closed under positive sums.

Example 5. Suppose X(t) is harmonizable with spectral decomposition supported by a bounded set A and g(t) is the FS transform of some G(x) of finite variation. Then X(t+g(t)) and X(g(t)) are harmonizable.

Proof. Set Y(t) = X(t + g(t)), so

$$R_Y(s,t) = R_X(s+g(s),t+g(t)) = \langle \text{iint} \rangle_A \exp(i x (s+g(s)) - i y (t+g(t))) d^2 G(x,y).$$

Let M_A denote the variation over $A \times A$ of G(x, y). For any complex $\{c_j\}$ and parameter pairs,

$$Q = \left| \sum_{j=1}^{n} c_j R_Y(s_j, t_j) \right| \le M_A \left| \sum_{j=1}^{n} c_j \exp\left(i \, x' \, s_j + i \, x' \, g(s_j) - i \, y' \, t_j - i \, y' \, g(t_j)\right) \right|$$

where x', y' in closure of A. The mappings $t \mapsto \exp[i x' g(t)]$ and $t \mapsto \exp[-i y' g(t)]$ are FS transforms, so by repeated application of Bochner's condition this is bounded, and $R_Y(s, t)$ is an FS transform.

Example 6. Suppose R_1 and R_2 are harmonizable covariances, and for T of finite Lebesgue measure define $R_3(s,t)$ as in (7). Then R_3 is harmonizable.

Proof. By the Bochner-Eberlein condition, for any $\{c_i\}$,

$$Q = \left| \sum_{j=1}^{n} c_j \int_{T} R_1(s_j, u) R_2(u, t_j) du \right| \le M_1 \sup_{x, y} \left| \sum_{j=1}^{n} c_j \int_{T} R_2(u, t_j) \exp(i s_j x - i u y) du \right|.$$

With M_2 the variation bound for R_2 ,

$$Q \le M_1 M_2 m(T) \sup_{x,y} \left| \sum_{j=1}^{n} c_j \exp(i s_j x - i t_j y) \right|$$

where m(T) is Lebesgue measure. Thus R_3 is an FS transform.

Example 7. Suppose X(t) is a moving average as in (2) with f(t, u) = f(t - u) a Fourier-Stieltjes transform and G(u, v) of bounded variation. Then X(t) is harmonizable.

Proof. From (2) and the bounded variation of H(x) and G(u, v),

$$R(s,t) = \langle \mathsf{iiiint} \rangle \exp\left[i\,x\,(s-u) - i\,y\,(t-v)\right] \,d^2\,G(u,v) \,d\,H(x) \,d\,H^*(y).$$

This is an FS transform with variation bound $M_G M_H^2$, where M_G bounds G(u, v) and M_H bounds H(x).

Example 8. Suppose X(t) is as above, Z(u) has orthogonal increments with $dF(u) = \mathbb{E}[|dZ(u)|^2]$ and f(t,u) as in (8). Then X(t) is a Priestley oscillatory process, and is harmonizable provided

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} |d H_u(x)| |d H_u^*(y)| dF(u) < \infty.$$
 (16)

Proof. The covariance is

$$R(s,t) = \int_{-\infty}^{\infty} \exp[i u (s-t)] f(u,s) f^{*}(u,t) dF(u).$$

By repeated application of Bochner's and Fubini's theorems, provided (16) holds, R(s,t) is an FS transform and thus harmonizable.

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