

Unitary Time Changes of Stationary Processes Yield Oscillatory Processes

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Abstract

A unitary time-change operator U_θ is constructed for absolutely continuous, strictly increasing time reparametrizations θ , acting on functions that are locally square-integrable (meaning over compact sets). Applying U_θ to the Cramér spectral representation of a stationary process $X(t)$ produces the transformed process $Z(t) = U_\theta X(t) = \sqrt{\dot{\theta}(t)} X(\theta(t)) = \sqrt{\dot{\theta}(t)} \int_{\mathbb{R}} e^{i\lambda\theta(t)} d\Phi(\lambda)$, which is an oscillatory process in the sense of Priestley with oscillatory function $\varphi_t(\lambda) = \sqrt{\dot{\theta}(t)} e^{i\lambda\theta(t)}$, evolutionary spectrum $dF_t(\lambda) = \dot{\theta}(t) dF(\lambda)$, and covariance kernel $K_Z(t, s) = \sqrt{\dot{\theta}(t)\dot{\theta}(s)} K_X(\theta(t), \theta(s))$ where K_X is the stationary covariance of $X(t) = \int_{\mathbb{R}} e^{i\lambda t} d\Phi(\lambda)$, and the expected zero-counting function $\mathbb{E}[N_{[a,b]}]$ of the oscillatory process paths equals $\sqrt{-\ddot{K}(0)} (\theta(a) - \theta(b))$. The sample paths of any non-degenerate second-order stationary process are locally square integrable, making the unitary time-change operator U_θ applicable to typical realizations. A zero-localization measure $d\mu(t) = \delta(Z(t)) |\dot{Z}(t)| dt$ induces a Hilbert space $L^2(\mu)$ on the zero set of each oscillatory process realization $Z(t)$, and the multiplication operator $(L f)(t) = t f(t)$ has simple pure point spectrum equal to the zero crossing set of Z .

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1 Gaussian Processes

1.1 Definition

Definition 1. (*Gaussian process*) Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a probability space and T a non-empty index set. A family $\{X_t: t \in T\}$ of real-valued random variables on $(\Omega, \mathcal{F}, \mathbb{P})$ is called a Gaussian process if for every finite subset $\{t_1, \dots, t_n\} \subset T$ the random vector $(X_{t_1}, \dots, X_{t_n})$ is multivariate normal (possibly degenerate). Equivalently, every finite linear combination $\sum_{i=1}^n a_i X_{t_i}$ is either almost surely constant or Gaussian. The mean function is $m(t) := \mathbb{E}[X_t]$ and the covariance kernel is

$$K(s, t) = \text{Cov}(X_s, X_t) \quad (1)$$

For any finite $(t_i)_{i=1}^n \subset T$, the matrix $K_{ij} = K(t_i, t_j)$ is symmetric positive semidefinite, and a Gaussian process is completely determined in law by m and K

1.2 Stationary processes

Definition 2. [*Cramér spectral representation*][1] A zero-mean stationary process X with spectral measure F admits the sample path representation

$$X(t) = \int_{\mathbb{R}} e^{i\lambda t} d\Phi(\lambda) \quad (2)$$

which has covariance

$$R_X(t-s) = \int_{\mathbb{R}} e^{i\lambda(t-s)} dF(\lambda) \quad (3)$$

1.2.1 Sample path realizations

Definition 3. [*Locally square-integrable functions*] Define

$$L_{\text{loc}}^2(\mathbb{R}) := \left\{ f: \mathbb{R} \rightarrow \mathbb{C} : \int_K |f(t)|^2 dt < \infty \text{ for every compact } K \subseteq \mathbb{R} \right\} \quad (4)$$

Remark 4. Every bounded measurable set in \mathbb{R} is compact or contained in a compact set; hence $L_{\text{loc}}^2(\mathbb{R})$ contains functions that are square-integrable on every bounded interval, including functions with polynomial growth at infinity

Theorem 5. [*Sample paths in $L_{\text{loc}}^2(\mathbb{R})$*] Let $\{X(t)\}_{t \in \mathbb{R}}$ be a second-order stationary process with

$$\sigma^2 := \mathbb{E}[X(t)^2] < \infty \quad (5)$$

Then almost every sample path lies in $L_{\text{loc}}^2(\mathbb{R})$

Proof. Fix an arbitrary bounded interval $[a, b] \subset \mathbb{R}$ with $a < b$. Define

$$Y_{[a, b]} := \int_a^b X(t)^2 dt \quad (6)$$

By Tonelli's theorem, since $X(t)^2 \geq 0$,

$$\mathbb{E}[Y_{[a, b]}] = \mathbb{E}\left[\int_a^b X(t)^2 dt\right] = \int_a^b \mathbb{E}[X(t)^2] dt \quad (7)$$

By stationarity, $\mathbb{E}[X(t)^2] = \sigma^2$ for all t , hence

$$\mathbb{E}[Y_{[a, b]}] = \sigma^2(b - a) < \infty \quad (8)$$

Markov's inequality yields, for $M > 0$,

$$\mathbb{P}(Y_{[a, b]} > M) \leq \frac{\mathbb{E}[Y_{[a, b]}]}{M} = \frac{\sigma^2(b - a)}{M} \quad (9)$$

and letting $M \rightarrow \infty$ gives $\mathbb{P}(Y_{[a, b]} < \infty) = 1$. Now let $K \subset \mathbb{R}$ be compact, so $K \subseteq [-N, N]$ for some $N > 0$. Then

$$\int_K X(t)^2 dt \leq \int_{-N}^N X(t)^2 dt < \infty \quad \text{a.s.} \quad (10)$$

hence almost every path satisfies $\int_K |X(t, \omega)|^2 dt < \infty$ for every compact K , i.e. $X(\cdot, \omega) \in L^2_{\text{loc}}(\mathbb{R})$ \square

1.3 (Non-Stationary) Oscillatory Processes

Definition 6. [Oscillatory process][3] Let F be a finite nonnegative Borel measure on \mathbb{R} . Let

$$A_t \in L^2(F) \quad \forall t \in \mathbb{R} \quad (11)$$

be the gain function and

$$\varphi_t(\lambda) = A_t(\lambda) e^{i\lambda t} \quad (12)$$

the corresponding oscillatory function. An oscillatory process is a stochastic process represented as

$$Z(t) = \int_{\mathbb{R}} \varphi_t(\lambda) d\Phi(\lambda) = \int_{\mathbb{R}} A_t(\lambda) e^{i\lambda t} d\Phi(\lambda) \quad (13)$$

where Φ is a complex orthogonal random measure with spectral measure F satisfying

$$d\mathbb{E}[\Phi(\lambda) \overline{\Phi(\mu)}] = \delta(\lambda - \mu) dF(\lambda) \quad (14)$$

and covariance

$$\begin{aligned} R_Z(t, s) &= \mathbb{E}[Z(t) \overline{Z(s)}] = \int_{\mathbb{R}} A_t(\lambda) \overline{A_s(\lambda)} e^{i\lambda(t-s)} dF(\lambda) \\ &= \int_{\mathbb{R}} \varphi_t(\lambda) \overline{\varphi_s(\lambda)} dF(\lambda) \end{aligned} \quad (15)$$

Definition 7. [Evolutionary spectrum] The evolutionary power spectral density of an oscillatory process is given by is

$$\begin{aligned} dF_t(\lambda) &= S_t(\lambda)d\lambda \\ &= |A_t(\lambda)|^2 dF(\lambda) \\ &= |A_t(\lambda)|^2 S(\lambda)d\lambda \end{aligned} \quad (16)$$

Definition 8. [Variance of evolutionary process] The variance of an evolutionary process $Z(t)$ is given by integrating the evolutionary power spectral density $S_t(\lambda)$ over all frequencies

$$\text{var}(Z(t)) = \int_{-\infty}^{\infty} S_t(\lambda)d\lambda = \int_{-\infty}^{\infty} dF_t(\lambda) \quad (17)$$

Theorem 9. [Real-valuedness criterion for oscillatory processes] Let Z be an oscillatory process with oscillatory function $\varphi_t(\lambda) = A_t(\lambda) e^{i\lambda t}$ and spectral measure F . Then Z is real-valued if and only if

$$A_t(-\lambda) = \overline{A_t(\lambda)} \quad \text{for } F\text{-a.e. } \lambda \in \mathbb{R} \quad (18)$$

equivalently

$$\varphi_t(-\lambda) = \overline{\varphi_t(\lambda)} \quad \text{for } F\text{-a.e. } \lambda \in \mathbb{R} \quad (19)$$

Proof. If Z is real-valued, then $Z(t) = \overline{Z(t)}$ for all t . Taking conjugates in the representation $Z(t) = \int A_t(\lambda) e^{i\lambda t} d\Phi(\lambda)$ and using the symmetry relation for the orthogonal random measure appropriate for real-valued processes, a change of variable $\mu = -\lambda$ shows that the $L^2(F)$ -integrands must agree F -a.e., i.e. $A_t(\lambda) = \overline{A_t(-\lambda)}$, which is equivalent to (18). Using $\varphi_t(\lambda) = A_t(\lambda) e^{i\lambda t}$ then gives (19). The converse follows by reversing the steps \square

Theorem 10. [Existence of oscillatory processes with explicit L^2 -limit construction] Let F be an absolutely continuous spectral measure and the gain function $A_t(\lambda) \in L^2(F)$ for all $t \in \mathbb{R}$, measurable jointly in (t, λ) . Define the time-dependent spectrum

$$S_t := \int_{\mathbb{R}} |A_t(\lambda)|^2 dF(\lambda) = \int_{\mathbb{R}} |A_t(\lambda)|^2 S(\lambda) d\lambda < \infty \quad (20)$$

Then there exists a complex orthogonal random measure Φ with spectral measure F such that for each fixed t the stochastic integral

$$Z(t) = \int_{\mathbb{R}} A_t(\lambda) e^{i\lambda t} d\Phi(\lambda) \quad (21)$$

is well-defined as an $L^2(\Omega)$ -limit and has covariance R_Z as in (15)

Proof. Step 1 (simple functions and isometry). Let \mathbb{S} denote the set of simple functions

$$g(\lambda) = \sum_{j=1}^n c_j 1_{E_j}(\lambda) \quad (22)$$

with disjoint Borel E_j and $F(E_j) < \infty$, $c_j \in \mathbb{C}$. Define the stochastic integral on \mathbb{S} by

$$\int_{\mathbb{R}} g(\lambda) d\Phi(\lambda) := \sum_{j=1}^n c_j \Phi(E_j) \quad (23)$$

Using orthogonality of Φ ,

$$\mathbb{E}\left[\left|\int g d\Phi\right|^2\right] = \sum_{j=1}^n |c_j|^2 F(E_j) = \int_{\mathbb{R}} |g(\lambda)|^2 dF(\lambda) \quad (24)$$

Thus the map $I: \mathbb{S} \rightarrow L^2(\Omega)$, $I(g) = \int g d\Phi$, is an isometry with respect to the $L^2(F)$ -norm.

Step 2 (density and Cauchy property). Simple functions are dense in $L^2(F)$: for any $h \in L^2(F)$ there exists $g_n \in \mathbb{S}$ with $\|h - g_n\|_{L^2(F)} \rightarrow 0$. By (24),

$$\mathbb{E}\left[\left|\int g_n d\Phi - \int g_m d\Phi\right|^2\right] = \|g_n - g_m\|_{L^2(F)}^2 \xrightarrow{n,m \rightarrow \infty} 0 \quad (25)$$

so $\{\int g_n d\Phi\}$ is Cauchy in $L^2(\Omega)$.

Step 3 (definition by L^2 -limit and independence of approximating sequence). Since $L^2(\Omega)$ is complete, the limit exists. Define, for $h \in L^2(F)$,

$$\int_{\mathbb{R}} h(\lambda) d\Phi(\lambda) := \lim_{n \rightarrow \infty} \int_{\mathbb{R}} g_n(\lambda) d\Phi(\lambda) \quad (26)$$

where $g_n \in \mathbb{S}$ and $\|h - g_n\|_{L^2(F)} \rightarrow 0$. If g_n and \tilde{g}_n are two such approximating sequences, then $\|g_n - \tilde{g}_n\|_{L^2(F)} \rightarrow 0$ and again by (24) the corresponding integrals differ by an $L^2(\Omega)$ -null sequence, so the limit is independent of the sequence.

Step 4 (isometry and linearity extend). By continuity from (24) and (26),

$$\mathbb{E}\left[\left|\int h d\Phi\right|^2\right] = \int_{\mathbb{R}} |h(\lambda)|^2 dF(\lambda) \quad (27)$$

for $h \in L^2(F)$, and the map $h \mapsto \int h d\Phi$ is linear and isometric.

Step 5 (apply to φ_t). Since $|e^{i\lambda t}| = 1$, $\varphi_t(\lambda) = A_t(\lambda) e^{i\lambda t} \in L^2(F)$ and

$$\int_{\mathbb{R}} |\varphi_t(\lambda)|^2 dF(\lambda) = \int_{\mathbb{R}} |A_t(\lambda)|^2 dF(\lambda) = S_t < \infty \quad (28)$$

Hence $Z(t)$ in (21) is well-defined as the $L^2(\Omega)$ -limit (26) with $h = \varphi_t$. Computing covariance via sesquilinearity together with (14) yields (15) \square

1.4 Operator Representations

[2]

2 Unitarily Time-Changed Stationary Processes

2.1 Unitary time-change operator $U_\theta f$

Theorem 11. [Unitary time-change and local isometry] Let the time-scaling function $\theta: \mathbb{R} \rightarrow \mathbb{R}$ be absolutely continuous, strictly increasing, and bijective, with

$$\dot{\theta}(t) > 0 \quad (29)$$

almost everywhere and $\dot{\theta}(t) = 0$ only on sets of Lebesgue measure zero. For f measurable, define

$$(U_\theta f)(t) = \sqrt{\dot{\theta}(t)} f(\theta(t)) \quad (30)$$

Its inverse is given by

$$(U_\theta^{-1} g)(s) = \frac{g(\theta^{-1}(s))}{\sqrt{\dot{\theta}(\theta^{-1}(s))}} \quad (31)$$

For every compact set $K \subseteq \mathbb{R}$ and $f \in L^2_{\text{loc}}(\mathbb{R})$,

$$\int_K |(U_\theta f)(t)|^2 dt = \int_{\theta(K)} |f(s)|^2 ds \quad (32)$$

Moreover, U_θ^{-1} is the inverse of U_θ on $L^2_{\text{loc}}(\mathbb{R})$

Proof. By (30), $\int_K |(U_\theta f)(t)|^2 dt = \int_K \dot{\theta}(t) |f(\theta(t))|^2 dt$. With the change of variables $s = \theta(t)$ and $ds = \dot{\theta}(t) dt$, the domain maps to $\theta(K)$, giving (32). The two-sided inverse identities follow from direct substitution into (30) and (31) \square

2.2 Time-Varying (Convolution) Filter Representations

Theorem 12. TODO: insert time-varying filter representations (both forward and reverse)

2.2.1 The Oscillatory Subclass $Z(t) = U_\theta X(t)$

Theorem 13. [Filter representations of unitarily time-changed stationary processes] Let $\theta: \mathbb{R} \rightarrow \mathbb{R}$ be absolutely continuous, strictly increasing, and bijective with $\theta'(t) > 0$ a.e. Let $X(u) = \int_{\mathbb{R}} e^{i\lambda t} d\Phi(\lambda)$ be a realization of a stationary process, and set

$$Z(t) = \sqrt{\dot{\theta}(t)} Y(\theta(t)) \quad (33)$$

Then:

1. The forward filter kernel is

$$h(t, u) = \sqrt{\dot{\theta}(t)} \delta(u - \theta(t)) \quad (34)$$

2. The inverse filter kernel is

$$g(t, s) = \frac{\delta(s - \theta^{-1}(t))}{\sqrt{\dot{\theta}(\theta^{-1}(t))}} \quad (35)$$

3. The composition $(g \circ h)$ recovers the identity:

$$Y(t) = \int_{\mathbb{R}} g(t, s) Z(s) ds = \frac{Z(\theta^{-1}(t))}{\sqrt{\dot{\theta}(\theta^{-1}(t))}} \quad (36)$$

Proof. Using the sifting property of the Dirac delta in (34) gives (33). Likewise, applying (35), then substituting (33) at $s = \theta^{-1}(t)$ and $\theta \circ \theta^{-1} = \text{id}$ yields (36) \square

2.3 Transformation of stationary to oscillatory processes via U_θ

Theorem 14. [Unitary time change produces oscillatory process] Let X be zero-mean stationary as in Definition 2. For a scaling function θ as in Theorem 11, define

$$Z(t) = (U_\theta X)(t) = \sqrt{\dot{\theta}(t)} X(\theta(t)) \quad (37)$$

Then Z is a realization of an oscillatory process with oscillatory function

$$\varphi_t(\lambda) = \sqrt{\dot{\theta}(t)} e^{i\lambda\theta(t)} \quad (38)$$

gain function

$$A_t(\lambda) = \sqrt{\dot{\theta}(t)} e^{i\lambda(\theta(t)-t)} \quad (39)$$

and covariance

$$\begin{aligned} R_Z(t, s) &= \mathbb{E}[Z(t) \overline{Z(s)}] \\ &= \sqrt{\dot{\theta}(t) \dot{\theta}(s)} \mathbb{E}[X(\theta(t)) \overline{X(\theta(s))}] \\ &= \sqrt{\dot{\theta}(t) \dot{\theta}(s)} R_X(\theta(t) - \theta(s)) \\ &= \sqrt{\dot{\theta}(t) \dot{\theta}(s)} \int_{\mathbb{R}} e^{i\lambda(\theta(t) - \theta(s))} dF(\lambda) \end{aligned} \quad (40)$$

Proof. From the Cramér representation (2), $X(\theta(t)) = \int e^{i\lambda\theta(t)} d\Phi(\lambda)$. Therefore

$$Z(t) = \sqrt{\dot{\theta}(t)} \int_{\mathbb{R}} e^{i\lambda\theta(t)} d\Phi(\lambda) = \int_{\mathbb{R}} \left(\sqrt{\dot{\theta}(t)} e^{i\lambda\theta(t)} \right) d\Phi(\lambda) = \int \varphi_t(\lambda) d\Phi(\lambda)$$

which is of the oscillatory form with φ_t as in (38) and A_t as in (39). The covariance follows from stationarity via (3) \square

Corollary 15. [Evolutionary spectrum of unitarily time-changed stationary process] The evolutionary spectrum is

$$\begin{aligned} dF_t(\lambda) &= |A_t(\lambda)|^2 dF(\lambda) \\ &= \dot{\theta}(t) dF(\lambda) \end{aligned} \tag{41}$$

Proof. Since $|e^{i\alpha}| = 1$, $|A_t(\lambda)|^2 = \dot{\theta}(t)$, giving (16) \square

2.4 Covariance operator conjugation

Proposition 16. [Operator conjugation] Let

$$(T_K f)(t) := \int_{\mathbb{R}} K(|t-s|) f(s) ds \tag{42}$$

with stationary kernel

$$K(h) = \int_{\mathbb{R}} e^{i\lambda h} dF(\lambda) \tag{43}$$

Define the transformed kernel

$$K_\theta(s, t) := \sqrt{\dot{\theta}(t) \dot{\theta}(s)} K(|\theta(t) - \theta(s)|) \tag{44}$$

Then for all $f \in L^2_{\text{loc}}(\mathbb{R})$,

$$(T_{K_\theta} f)(t) = (U_\theta T_K U_\theta^{-1} f)(t) \tag{45}$$

Proof. Compute

$$(U_\theta T_K U_\theta^{-1} f)(t) = \sqrt{\dot{\theta}(t)} (T_K U_\theta^{-1} f)(\theta(t)) = \sqrt{\dot{\theta}(t)} \int_{\mathbb{R}} K(|\theta(t) - s|) \frac{f(\theta^{-1}(s))}{\sqrt{\dot{\theta}(\theta^{-1}(s))}} ds$$

With $s = \theta(u)$, $ds = \dot{\theta}(u) du$, obtain

$$\sqrt{\dot{\theta}(t)} \int_{\mathbb{R}} K(|\theta(t) - \theta(u)|) \sqrt{\dot{\theta}(u)} f(u) du = \int_{\mathbb{R}} K_\theta(u, t) f(u) du = (T_{K_\theta} f)(t) \quad \square$$

3 Zero Localization

Definition 17. [Zero localization measure] Let Z be real-valued with $Z \in C^1(\mathbb{R})$ having only simple zeros

$$Z(t_0) = 0 \Rightarrow \dot{Z}(t_0) \neq 0 \quad (46)$$

Define, for Borel $B \subset \mathbb{R}$,

$$\mu(B) := \int_B \delta(Z(t)) |\dot{Z}(t)| dt \quad (47)$$

so that μ places unit mass at each simple zero of Z counted by the co-area/change-of-variables identity for C^1 functions. The induced space $L^2(\mu)$ consists of (equivalence classes of) functions supported on the zero set of Z , and the multiplication operator $(Lf)(t) = t f(t)$ is essentially self-adjoint on C_c^∞ functions supported on the zero set with pure point spectrum equal to the zero-crossing set

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