

1 Stationary Dilations

Definition 1. Let (Ω, \mathcal{F}, P) and $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P})$ be probability spaces. We say that (Ω, \mathcal{F}, P) is a factor of $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P})$ if there exists a measurable surjective map $\phi: \tilde{\Omega} \rightarrow \Omega$ such that:

1. For all $A \in \mathcal{F}$, $\phi^{-1}(A) \in \tilde{\mathcal{F}}$
2. For all $A \in \mathcal{F}$, $P(A) = \tilde{P}(\phi^{-1}(A))$

In other words, (Ω, \mathcal{F}, P) can be obtained from $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P})$ by projecting the larger space onto the smaller one while preserving the probability measure structure.

Remark 2. In the context of stationary dilations, this means that the original non-stationary process $\{X_t\}$ can be recovered from the stationary dilation $\{Y_t\}$ through a measurable projection that preserves the probabilistic structure of the original process.

Definition 3. (Stationary Dilation) Let (Ω, \mathcal{F}, P) be a probability space and let $\{X_t\}_{t \in \mathbb{R}_+}$ be a nonstationary stochastic process. A stationary dilation of $\{X_t\}$ is a stationary process $\{Y_t\}_{t \in \mathbb{R}_+}$ defined on a larger probability space $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P})$ such that:

1. (Ω, \mathcal{F}, P) is a factor of $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P})$
2. There exists a measurable projection operator Π such that:

$$X_t = \Pi Y_t \quad \forall t \in \mathbb{R}_+ \quad (1)$$

Theorem 4. (Representation of Nonstationary Processes) For a continuous-time nonstationary process $\{X_t\}_{t \in \mathbb{R}_+}$, its stationary dilation exists which has sample paths $t \mapsto X_t(\omega)$ which are continuous with probability one when X_t :

- is uniformly continuous in probability over compact intervals:

$$\lim_{s \rightarrow t} P(|X_s - X_t| > \epsilon) = 0 \quad \forall \epsilon > 0, t \in [0, T], T > 0 \quad (2)$$

- has finite second moments:

$$\mathbb{E}[|X_t|^2] < \infty \quad \forall t \in \mathbb{R}_+ \quad (3)$$

- has an integral representation of the form:

$$X_t = \int_0^t \eta(s) ds \quad (4)$$

where $\eta(t)$ is a measurable random function that is stationary in the wide sense (with $\int_0^t \mathbb{E}[|\eta(s)|^2] ds < \infty$ for all t)

- and has a covariance operator

$$R(t, s) = \mathbb{E}[X_t X_s] \quad (5)$$

which is symmetric ($R(t, s) = R(s, t)$), positive definite and continuous

Under these conditions, there exists a representation:

$$X_t = M(t) \cdot S_t \quad (6)$$

where:

- $M(t)$ is a continuous deterministic modulation function
- $\{S_t\}_{t \in \mathbb{R}_+}$ is a stationary process

This representation can be obtained through the stationary dilation by choosing:

$$Y_t = \begin{pmatrix} M(t) \\ S_t \end{pmatrix} \quad (7)$$

with the projection operator Π defined as:

$$\Pi Y_t = M(t) \cdot S_t \quad (8)$$

Proposition 5. (Properties of Dilation) *The stationary dilation satisfies:*

1. *Preservation of moments:*

$$\mathbb{E}[|X_t|^p] \leq \mathbb{E}[|Y_t|^p] \quad \forall p \geq 1 \quad (9)$$

2. *Minimal extension: Among all stationary processes that dilate X_t , there exists a minimal one (unique up to isomorphism) in terms of the probability space dimension*

Corollary 6. *For any nonstationary process satisfying the above conditions, the stationary dilation provides a canonical factorization into deterministic time-varying components and stationary stochastic components.*