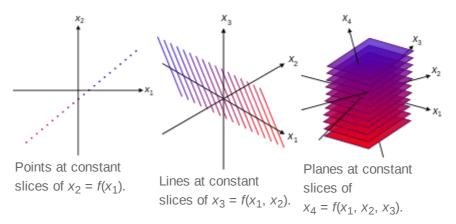
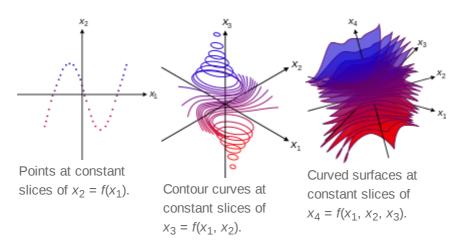
# Level set



(n-1)-dimensional level sets for functions of the form  $f(x_1, x_2, ..., x_n) = a_1x_1 + a_2x_2 + ... + a_nx_n$  where  $a_1, a_2, ..., a_n$  are constants, in (n+1)-dimensional Euclidean space, for n=1, 2, 3.



(n-1)-dimensional level sets of non-linear functions  $f(x_1, x_2, ..., x_n)$  in (n+1)-dimensional Euclidean space, for n=1, 2, 3.

In <u>mathematics</u>, a **level set** of a <u>real</u>-valued <u>function f of n real variables</u> is a <u>set</u> where the function takes on a given constant value c, that is:

$$L_c(f) = \{(x_1, \ldots, x_n) \mid f(x_1, \ldots, x_n) = c\}$$
,

When the number of independent variables is two, a level set is called a **level curve**, also known as <u>contour line</u> or <u>isoline</u>; so a level curve is the set of all real-valued solutions of an equation in two variables  $x_1$  and  $x_2$ . When n = 3, a level set is called a **level <u>surface</u>** (or <u>isosurface</u>); so a level surface is the set of all real-valued roots of an equation in three variables  $x_1$ ,  $x_2$  and  $x_3$ . For higher values of n, the level set is a **level hypersurface**, the set of all real-valued roots of an equation in n > 3 variables.

A level set is a special case of a fiber.

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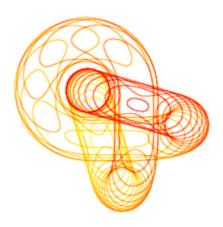
See also

References

#### Alternative names

Level sets show up in many applications, often under different names. For example, an <u>implicit curve</u> is a level curve, which is considered independently of its neighbor curves, emphasizing that such a curve is defined by an <u>implicit equation</u>. Analogously, a level surface is sometimes called an implicit surface or an isosurface.

The name isocontour is also used, which means a contour of equal height. In various application areas, isocontours have received specific names, which indicate often the nature of the values of the considered function, such as <u>isobar</u>, <u>isotherm</u>, <u>isogon</u>, <u>isochrone</u>, isoquant and indifference curve.



Intersections of a <u>co-ordinate</u> function's level surfaces with a <u>trefoil</u> <u>knot</u>. Red curves are closest to the viewer, while yellow curves are farthest.

### **Examples**

Consider the 2-dimensional Euclidean distance:

$$d(x,y) = \sqrt{x^2 + y^2}$$

A level set  $L_r(d)$  of this function consists of those points that lie at a distance of r from the origin, that make a <u>circle</u>. For example,  $(3,4) \in L_5(d)$ , because d(3,4) = 5. Geometrically, this means that the point (3,4) lies on the circle of radius 5 centered at the origin. More generally, a <u>sphere</u> in a <u>metric space</u> (M,m) with radius r centered at r0 can be defined as the level set r1.

A second example is the plot of <u>Himmelblau's function</u> shown in the figure to the right. Each curve shown is a level curve of the function, and they are spaced logarithmically: if a curve represents  $L_x$ , the curve directly "within" represents  $L_{x/10}$ , and the curve directly "outside" represents  $L_{10x}$ .

## Level sets versus the gradient

**Theorem:** If the function f is <u>differentiable</u>, the <u>gradient</u> of f at a point is either zero, or perpendicular to the level set of f at that point.

To understand what this means, imagine that two hikers are at the same location on a mountain. One of them is bold, and he decides to go in the direction where the slope is steepest. The other one is more cautious; he does not want to either climb or descend, choosing a path which will keep him at the same height. In our analogy, the above theorem says that the two hikers will depart in directions perpendicular to each other.

A consequence of this theorem (and its proof) is that if f is differentiable, a level set is a <u>hypersurface</u> and a <u>manifold</u> outside the <u>critical points</u> of f. At a critical point, a level set may be reduced to a point (for example at a <u>local extremum</u> of f) or may have a singularity such as a self-intersection point or a cusp.

# 3 -3 -6-6 -3 0 3 6

Log-spaced level curve plot of Himmelblau's function<sup>[1]</sup>

## Sublevel and superlevel sets

A set of the form

$$L_c^-(f)=\{(x_1,\ldots,x_n)\mid f(x_1,\ldots,x_n)\leq c\}$$

is called a **sublevel set** of *f* (or, alternatively, a **lower level set** or **trench** of *f*). A **strict sublevel** set of *f* is

$$\{(x_1,\ldots,x_n) \mid f(x_1,\ldots,x_n) < c\}$$

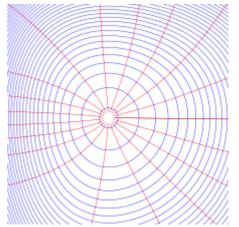
Similarly

$$L_c^+(f)=\{(x_1,\ldots,x_n)\mid f(x_1,\ldots,x_n)\geq c\}$$

is called a **superlevel set** of *f* (or, alternatively, an **upper level set** of *f*). And a **strict superlevel set** of *f* is

$$\{(x_1,\ldots,x_n)\mid f(x_1,\ldots,x_n)>c\}$$

Sublevel sets are important in minimization theory. By Weierstrass's theorem, the boundness of some non-empty sublevel set and the lower-semicontinuity of the function implies that a function attains its minimum. The convexity of all the sublevel sets characterizes quasiconvex functions. [2]



Consider a function *f* whose graph looks like a hill. The blue curves are the level sets; the red curves follow the direction of the gradient. The cautious hiker follows the blue paths; the bold hiker follows the red paths. Note that blue and red paths always cross at right angles.

#### See also

- Epigraph
- Level-set method
- Level set (data structures)

#### References

1. Simionescu, P.A. (2011). "Some Advancements to Visualizing Constrained Functions and Inequalities of Two Variables". *Journal of Computing and Information Science in Engineering*. **11** (1). doi:10.1115/1.3570770 (https://doi.org/10.1115%2F1.3570770).

2. Kiwiel, Krzysztof C. (2001). "Convergence and efficiency of subgradient methods for quasiconvex minimization". *Mathematical Programming, Series A*. Berlin, Heidelberg: Springer. **90** (1): 1–25. doi:10.1007/PL00011414 (https://doi.org/10.1007%2FPL00011414). ISSN 0025-5610 (https://www.worldcat.org/issn/0025-5610). MR 1819784 (https://www.ams.org/mathscinet-getitem?mr=1819784). S2CID 10043417 (https://api.semanticscholar.org/CorpusID:10043417).

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