

Concerning Convolution on the Half-line

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0. We will say that a complex valued function on $[0, \infty)$ is locally integrable, locally p -integrable, locally of bounded variation, or locally absolutely continuous if it is integrable, p -integrable, of bounded variation, or absolutely continuous on each interval $[0, a]$, $a > 0$. The vector spaces of locally integrable and locally p -integrable functions will be denoted by \mathcal{L} and \mathcal{L}^p , while the corresponding normed vector spaces for the finite interval $[0, a]$ will be denoted by $L[0, a]$ and $L^p[0, a]$. If there is no danger of confusion, the $[0, a]$ will be omitted.

The spaces \mathcal{L}^p , $\infty \geq p \geq 1$, will each be considered to have the topology defined by the countable collection of semi-norms $\|f\|_n = \|f\|_{L^p[0, n]}$. \mathcal{L} can be considered to be a ring with convolution denoted by juxtaposition; thus, $k = fg$ is the function defined by the equation

$$k(t) = \int_0^t f(t-u) g(u) du, \quad t \geq 0.$$

Certain properties of the convolution are well known; for instance, if f is in \mathcal{L}^p and g is in \mathcal{L}^q , $1 \leq p \leq \infty$, $\frac{1}{p} + \frac{1}{q} = 1$, then fg is continuous. If f is in \mathcal{L}^p , $p \geq 1$, and g is in \mathcal{L} , then fg is in \mathcal{L}^p . Other properties of the convolution on the half line have been studied by MIKUSIŃSKI, RYLL-NARDZEWSKI [1], [2] and others. J. D. WESTON has studied transformations on a subspace of \mathcal{L} which commute with convolution and has based an operational calculus on them [3]. It is our purpose here to study transformations on \mathcal{L} into \mathcal{L}^p , $1 \leq p \leq \infty$, which commute with convolution, transformations, that is, for which $T(fg) = fT(g)$ for each f and g in \mathcal{L} .

The convolution integral equation on the half-line $xf = k$ with f and k in \mathcal{L} occurs frequently; however, there are no satisfactory existence theorems to show when there exists a solution x in \mathcal{L} . POLLARD & BLACKMAN [4] have demonstrated a method of solving the equation when there exists a solution in \mathcal{L} (however, it may not be easy to carry out). We will show a comparison test for the existence of solutions (Corollary 3.3). If $g = s \nu f$, where s is MIKUSIŃSKI's differentiation operator and ν is locally of bounded variation, then $xf = k$ has a solution in \mathcal{L} if $xg = k$ has a solution in \mathcal{L} . In Theorem 4.1 a necessary and sufficient condition is given in order that $xf = k$ have a solution when f is locally of bounded variation and $f(0^+) \neq 0$. Namely, k must be locally absolutely continuous and zero at the origin.

We shall not explicitly require that our transformations be linear, but we shall see that the requirement that T commute with convolution implies that T is linear, and it implies that T is continuous also. Our main theorem is Theorem 3.1, which characterizes the transformations on \mathcal{L} into \mathcal{L} which commute with convolution as being of the form $T = s \nu$ where s is the differentiation operator of MIKUSIŃSKI's operational calculus and ν is locally of bounded variation. That is, there is a ν such that whenever g is in \mathcal{L} $T(g) = s \nu g$. This result leads one to conjecture the result for transformations on \mathcal{L} into \mathcal{L}^p , $1 < p \leq \infty$, and Theorem 1.7 states that every transformation which commutes with convolution and takes \mathcal{L} into \mathcal{L}^p , $1 < p \leq \infty$, is such that there is an f in \mathcal{L}^p and $T(g) = f/g$ for every g in \mathcal{L} . Since the result for transformations on \mathcal{L} into \mathcal{L} depends in a minor way on the result for transformations on \mathcal{L} into \mathcal{L}^∞ , the latter result is proved first. But the result for transformations on \mathcal{L} into \mathcal{L} depends in a major way on the result characterizing the transformations which commute with convolution and take \mathcal{L} into the ring of functions which are locally of bounded variation. These transformations are characterized in Section 2. There it is shown that such a transformation is of the form $T = \nu$ (i.e. for every g in \mathcal{L} , $T(g) = \nu g$) for some ν which is locally of bounded variation. It is also shown that a transformation of this type must take \mathcal{L} not only into the ring of functions which are locally of bounded variation but, in fact, takes \mathcal{L} into the ring of functions which are locally absolutely continuous and zero at the origin.

For each of the theorems proved here concerning transformations on \mathcal{L} to \mathcal{L}^p , $1 \leq p \leq \infty$, there is an analogous theorem concerning transformations on $L[-\infty, \infty]$ to $L^p[-\infty, \infty]$, but we shall not prove these here. The proofs directly imitate those proofs we give here, but to a certain extent are more readily carried out because of the fact that $L[-\infty, \infty]$ and $L^p[-\infty, \infty]$ are Banach spaces while \mathcal{L} and \mathcal{L}^p are not. The theorem analogous to Theorem 3.1 characterizes the transformations on L to L in the following manner. For each such transformation T there is a function ν of bounded variation on $[-\infty, \infty]$ and with $\nu(-\infty) = 0$ such that $T(g) = k \Leftrightarrow k(t) = \int_{-\infty}^{\infty} g(t-u) d\nu(u)$ for almost all t , and for all g in L . In order to prove this it is necessary to have the analogue on $[-\infty, \infty]$ of the Hardy-Littlewood theorem (our Theorem H-L in Section 2) which has recently been proved by P. L. BUTZER [5]. It is interesting to compare the results concerning transformations on $L[-\infty, \infty]$ to $L^p[-\infty, \infty]$ with the results of R. P. AGNEW [6].

1. Every f in \mathcal{L} is also in $L[0, a]$, $a > 0$, and defines a continuous linear transformation on L to L by means of the equation $T_f(g) = fg$. We shall say that T_f is the linear transformation determined by f . By a simple application of Fubini's theorem on double integrals it is seen that T_f is bounded and

$$\|T_f\| \leq \|f\|_L = \int_0^a |f| d\nu.$$

For $n = 1, 2, \dots$ let g_n be the approximations to the delta function defined by $g_n(t) = n$ when $0 \leq t \leq \frac{1}{n}$ and $g_n(t) = 0$, $t > \frac{1}{n}$. The following theorem is well known, but for the sake of completeness the proof will be indicated.

Theorem 1.1. Let f be in \mathcal{L} , and let g_n be defined as stated above for $\frac{1}{n} < a$ and $a > 0$. Then $f g_n \rightarrow f$ in $L[0, a]$ as $n \rightarrow \infty$. The convergence is convergence in norm.

Proof. It is sufficient to prove the theorem for the case when f is a member of a dense subset of \mathcal{L} . Thus, let f be continuous and $f(0) = 0$. But for such an f direct calculation easily shows that $f g_n$ tends uniformly to f on $[0, a]$ and $f g_n$ tends to f also in norm.

Corollary 1.2. If f is in \mathcal{L} and $a > 0$, the norm of the linear transformation determined by f is $\|T_f\| = \|f\|_L$.

Proof. Since we know that $\|T_f\| \leq \|f\|_L$, it is only necessary to find for each $\varepsilon > 0$ a g such that $\|g\|_L = 1$ and $\|T_f(g)\| > \|f\|_L - \varepsilon$. But for the g_n specified above we have $\|g_n\| = 1$ for each n and $\|T_f(g_n)\| \rightarrow \|f\|_L$ as $n \rightarrow \infty$.

Now let $f = b$ be in \mathcal{L}^∞ . The linear transformation determined by b takes L into L^∞ (in fact $b g$ is continuous if g is in L). Again, it is clear that T_b as a transformation on L to L^∞ is continuous and $\|T_b\| \leq \|b\|_{L^\infty} = \text{ess. sup}_{0 \leq t \leq a} |b(t)|$. But we have

Theorem 1.3. If b is in \mathcal{L}^∞ and $a > 0$, the norm of the linear transformation T_b on L to L^∞ is

$$\|T_b\| = \|b\|_{L^\infty}.$$

Proof. Again it is only necessary to find a set of g_n such that $\|g_n\|_L = 1$ for each n and $\|b g_n\|_{L^\infty} \rightarrow \|b\|_{L^\infty} = K$ as $n \rightarrow \infty$. Define the sets

$$E_n = \left\{ u \mid 0 \leq u \leq a, |b(a-u)| > K - \frac{1}{n} \right\}, \quad n = 1, 2, \dots$$

The measure, $\mu(E_n)$, of each E_n is positive if K is different from zero. If g_n is defined by

$$\mu(E_n) g_n(u) = \chi_{E_n}(u) \operatorname{sgn} b(a-u), \quad n = 1, 2, \dots, \quad 0 \leq u \leq a,$$

where χ_E is the characteristic function of the set E , then $\|g_n\|_L = 1$. Moreover,

$$(b g_n)(a) = \int_0^a b(a-u) g_n(u) du = \frac{1}{\mu(E_n)} \int_0^a \chi_{E_n}(u) |b(a-u)| du > K - \frac{1}{n}.$$

Since $b g_n$ is continuous, $\|b g_n\|_{L^\infty} \geq K - \frac{1}{n}$, and since $\|b g_n\|_{L^\infty} \leq K$, we have $\|b g_n\|_{L^\infty} \rightarrow \|b\|_{L^\infty}$ as $n \rightarrow \infty$, which completes the proof.

Since $L^\infty[0, a]$ is a conjugate space, it has weak* topology, and strongly closed spheres are compact in this topology. If f_m is a sequence of functions in \mathcal{L}^∞ , and if b in \mathcal{L}^∞ is such that for every $a > 0$ and every g in $L[0, a]$

$$\lim \int_0^a f_m(u) g(u) du = \int_0^a b(u) g(u) du,$$

we shall say that f_m tends weak* to b on each interval $[0, a]$.

Lemma 1.4. Let f_n , $n = 1, 2, \dots$, be a sequence of functions in \mathcal{L}^∞ , and suppose that for each $a > 0$ there is a $B_a < \infty$ such that $\|f_n\|_{L^\infty[0, a]} < B_a$. Then there is a b in \mathcal{L}^∞ and a subsequence f_m of f_n such that f_m tends weak* to b on each interval $[0, a]$.

Proof. Since strongly closed spheres in $L^\infty[0, a]$ are weak* compact, we can pick a set of subsequences $f_{K,n}$ of f_n , $K=1, 2, \dots$, such that $f_{K+1,n}$ is subsequence of $f_{K,n}$, and $f_{K,n}$ tends weak* to b_K on $[0, K]$ as $n \rightarrow \infty$. By the diagonal process a single subsequence f_m of f_n can be found which converges weak* on each $[0, K]$ to b_K . If $K_2 > K_1$ and g_1 is in $L[0, K_1]$, there is a corresponding function g_2 in $L[0, K_2]$ such that $g_2(t) = g_1(t)$ on $[0, K_1]$ and $g_2(t) = 0$ on $(K_1, K_2]$, and the fact that

$$\begin{aligned} \int_0^{K_1} b_{K_1}(u) g_1(u) du &= \lim_{m \rightarrow \infty} \int_0^{K_1} f_m(u) g_1(u) du = \lim_{m \rightarrow \infty} \int_0^{K_1} f_m(u) g_2(u) du \\ &= \int_0^{K_1} b_{K_1}(u) g_2(u) du = \int_0^{K_1} b_{K_1}(u) g_1(u) du \end{aligned}$$

makes it clear that $b_{K_1}(u) = b_{K_2}(u)$ almost everywhere on $[0, K_1]$. Thus the functions in \mathcal{L}^∞ which are equal to b_K on $[0, K]$ and zero on (K, ∞) converge almost everywhere on $[0, \infty]$ to a function b which has the desired property.

Lemma 1.5. *Let f_m and b be as described in Lemma 1.4. Then if g is in \mathcal{L} , the sequence $f_m g$ tends weak* on each interval $[0, a]$ to $b g$.*

Proof. For any k in $L[0, a]$ and k_1 such that $k_1(a-u) = k(u)$, $0 \leq u \leq a$, $\int_0^a (f_m g)(u) k(u) du = \int_0^a (f_m g)(u) k_1(a-u) du = \int_0^a f_m(u) (g k_1)(a-u) du$ which tends to

$$\int_0^a b(u) (g k_1)(a-u) du = \int_0^a (b g)(u) k(u) du \quad \text{as } m \rightarrow \infty.$$

Theorem 1.6. *Let T be a transformation which takes each element of \mathcal{L} into \mathcal{L}^∞ . If T commutes with convolution, then T is a continuous linear transformation of \mathcal{L} into \mathcal{L}^∞ , and there is a b in \mathcal{L}^∞ such that $T(g) = b g$ for each g in \mathcal{L} . As a transformation on L to L^∞ , $\|T\| = \|b\|_{L^\infty}$.*

Proof. The last statement of the theorem follows immediately from the preceding statement in view of Theorem 1.3.

Let g_n be as in Theorem 1.1, and let T_n be the linear transformations determined by the functions $T(g_n)$. Thus $S_n(g) = g T(g_n) = T(g_n g) = g_n T(g)$ for g in \mathcal{L} . Each T_n takes $L[0, a]$ into $L^\infty[0, a]$, and the norm of T_n as a transformation on L to L^∞ is $\|T_n\| = \|T(g_n)\|_{L^\infty[0, a]}$. For any fixed g in $L[0, a]$, and n sufficiently large

$$\begin{aligned} \|T_n(g)\|_{L^\infty} &= \max_{0 \leq t \leq a} \left| \int_0^t T(g_n)(u) g(t-u) du \right| \\ &= \max_{0 \leq t \leq a} \left| \int_0^t T(g)(u) g_n(t-u) du \right| \\ &\leq \|T(g)\|_{L^\infty} \int_0^a g_n(u) du = \|T(g)\|_{L^\infty}. \end{aligned}$$

Since the T_n are bounded pointwise on L , they are bounded in norm (i.e. $a > 0$ implies there is a $B_a < \infty$ such that $\|T_n\| = \|T(g_n)\|_{L^\infty[0, a]} < B_a$). The functions $T(g_n)$ thus satisfy the conditions of Lemma 1.4. Consider then the subsequence $T(g_m)$ which converges weak* to b in \mathcal{L}^∞ . If g is in \mathcal{L} , the sequence $g T(g_m)$ converges weak* to $g b$ on each interval $[0, K]$ by Lemma 1.5. On the other

hand $gT(g_m) = g_m T(g)$, which by Theorem 1.1 converges in L norm to $T(g)$. The strong limit $T(g)$ and the weak* limit $g b$ of the sequence $gT(g_m)$ must be the same, that is

$$T(g) = g b$$

for each g in \mathcal{L} .

If $1 < p < \infty$, a similar theorem can be proved by the same methods. Indeed since there exist sets dense both in \mathcal{L} and in \mathcal{L}^p , $1 < p < \infty$, the theorem corresponding to Theorem 1.3 can be proved by the method of Theorem 1.1. The important point in Lemma 1.4 is that the strongly closed unit sphere in L^∞ is weak* compact. This is true also of L^p , $1 < p < \infty$. Thus we state

Theorem 1.7. *Let T be a transformation which takes each element of \mathcal{L} into \mathcal{L}^p , $1 < p \leq \infty$. If T commutes with convolution, then T is a continuous linear transformation of \mathcal{L} into \mathcal{L}^p , and there is an f in \mathcal{L}^p such that $T(g) = fg$ for each g in \mathcal{L} . As a transformation on L to L^p , $\|T\| = \|f\|_{L^p}$.*

2. The next theorem depends on a theorem of HARDY & LITTLEWOOD.

Theorem H-L. *Suppose that $a > 0$ and $f(u) = 0$ for $u > a$. Then*

$$\int_0^a |f(u+h) - f(u)| du = O(h) \quad (1)$$

if and only if f is equal almost everywhere to a function which is of bounded variation on $[0, a]$.

We shall need this theorem in the following form.

Corollary H-L. *Suppose that f is in \mathcal{L} . A necessary and sufficient condition that f be equal almost everywhere on $[0, \infty)$ to a function which is locally of bounded variation is that equation (1) holds for each $a > 0$.*

Theorem 2.1. *Let f be in \mathcal{L} . If for each g in \mathcal{L} , fg is equal almost everywhere to a function which is locally of bounded variation, then f itself is equal almost everywhere to a function which is locally of bounded variation.*

Proof. Take $a > 0$. Suppose g is in \mathcal{L} , and let $k = fg$. By corollary H-L

$$\int_0^a \left| \frac{k(u+h) - k(u)}{h} \right| du = O(1)$$

as $h \rightarrow 0$. Now

$$\begin{aligned} I_g(h) &= \int_0^a \left| \int_0^u \frac{f(u+h-\xi) - f(u-\xi)}{h} g(\xi) d\xi \right| du \\ &= \int_0^a \left| \frac{k(u+h) - k(u)}{h} - \frac{1}{h} \int_u^{u+h} f(u+h-\xi) g(\xi) d\xi \right| du \\ &\leq O(1) + \frac{1}{h} \int_0^a \int_u^{u+h} |f(u+h-\xi)| |g(\xi)| d\xi du. \end{aligned}$$

Now fg is certainly essentially bounded on $[0, a]$, and by Theorem 1.6 f is essentially bounded on $[0, a]$, which implies that the second term on the right

in the above inequality is $O(1)$ as $h \rightarrow 0$. Thus $I_h(h) = O(1)$ as $h \rightarrow 0$. Applying the uniform boundedness principle and Corollary 1.2, we have

$$\int_0^a \left| \frac{f(u+h) - f(u)}{h} \right| du = O(1)$$

for each positive a . Thus f is equal almost everywhere to a function which is locally of bounded variation.

The converse of the above theorem is well known.

MIKUSIŃSKI & RYLL-NARDZEWSKI [1] have shown that if f is locally of bounded variation and g is continuous, then fg is locally absolutely continuous. However, more is true.

Theorem 2.2. *If f is locally of bounded variation and g is in \mathcal{L} , then fg is locally absolutely continuous.*

Proof. The proof is straightforward. For $\varepsilon > 0$ we will show that the variation of fg on subintervals of $[0, a]$ the sum of whose lengths are sufficiently small is less than ε .

Clearly it is no restriction to take f non-decreasing, and even to suppose $f(0) = 0$. Suppose that f is non-decreasing, $f(0) = 0$, and that the variation of f on $[0, a]$ equals K . Now g can be split into a bounded part and a part whose norm is as small as we please. Let $g = g_B + g_\alpha$ where $|g_B(t)| < B$ and $\int_0^a |g_\alpha| du < \alpha$.

Suppose x_n, y_n are such that

$$0 \leq x_n < y_n \leq x_{n+1} < y_{n+1} \leq a, \quad n = 0, 1, \dots, N-1.$$

Let

$$h_n = y_n - x_n, \quad I_n = [x_n, y_n], \quad n = 0, 1, \dots, N,$$

and let

$$\Delta = \sum_{n=0}^N \left| \int_0^{y_n} f(y_n - u) g(u) du - \int_0^{x_n} f(x_n - u) g(u) du \right|.$$

Let $S = \bigcup_1^N I_n$. We choose $\delta_1 > 0$ so small that $\mu(S) < \delta_1$ implies $\int_S |g| du < \frac{\varepsilon}{3K}$.

We can take α to be as small as we please, and B depends only on α . Take $\alpha < \frac{\varepsilon}{3K}$. We now choose $\delta < \min \left[\delta_1, \frac{\varepsilon}{6BK} \right]$. Then suppose $\mu(S) < \delta$. Since K is a bound for f on $[0, a]$,

$$\Delta \leq \sum_{n=0}^N \left| \int_0^{x_n} [f(y_n - u) - f(x_n - u)] g(u) du \right| + K \int_S |g| du,$$

and the last term on the right is less than $\frac{1}{3}\varepsilon$. Further,

$$\begin{aligned} \sum_{n=0}^N \left| \int_0^{x_n} [f(y_n - u) - f(x_n - u)] g(u) du \right| &\leq \sum_{n=0}^N \left| \int_0^{x_n} [f(y_n - u) - f(x_n - u)] g_B(u) du \right| + \\ &+ \sum_{n=0}^N \left| \int_0^{x_n} [f(y_n - u) - f(x_n - u)] g_\alpha(u) du \right| = S_1 + S_2, \end{aligned}$$

where S_1 and S_2 are the first and second sums on the right in the above inequality.

Since f is increasing,

$$S_2 \leq K \int_0^a |g_\alpha| du \leq K \alpha < \frac{1}{3} \varepsilon.$$

Since f is increasing and g_B is bounded,

$$\begin{aligned} S_1 &\leq B \sum_{n=0}^N \int_0^{x_n} [f(y_n - u) - f(x_n - u)] du \\ &= B \sum_{n=0}^N \int_0^{x_n} [f(t + h_n) - f(t)] du = B \sum_{n=0}^N \left[\int_{x_n}^{x_n + h_n} f dt - \int_0^{h_n} f dt \right] \\ &\leq 2BK \sum_{n=0}^N h_n = 2BK \mu(S) < 2BK \delta < \frac{1}{3} \varepsilon. \end{aligned}$$

Thus $\Delta < \frac{1}{3} \varepsilon + \frac{1}{3} \varepsilon + \frac{1}{3} \varepsilon = \varepsilon$.

3. Let h be the function whose value is 1 for every non-negative t , and let s be the differentiation operator of MIKUSIŃSKI'S operational calculus (i.e. $s = h^{-1}$). We can now characterize transformations on \mathcal{L} to \mathcal{L} which commute with convolution.

Theorem 3.1. *Let T be a transformation on \mathcal{L} to \mathcal{L} which commutes with convolution. Then T is a continuous linear transformation on \mathcal{L} to \mathcal{L} . If $T(h) = f$, then f is equal almost everywhere to a function v which is locally of bounded variation and $T(g) = s v g$ for every g in \mathcal{L} . Furthermore, for any v which is locally of bounded variation the transformation $g \rightarrow s v g$ takes \mathcal{L} into \mathcal{L} and is a continuous linear transformation. If v is normalized by $v(t) = v(t^-)$ for $t > 0$ and $v(0) = v(0^+)$, the norm of T as a linear transformation on L to L is $\|T\| = \text{Variation } v + |v(0)|_{[0, a]}$.*

Proof. Let $T(h) = f$; then for every g in \mathcal{L} , $g f = g T(h) = h T(g)$ is locally absolutely continuous, and by Theorem 2.4 f is equal almost everywhere to a function v which is locally of bounded variation. Thus T is a linear transformation on \mathcal{L} to \mathcal{L} and $T(g) = s v g$ for all g . On the other hand any linear transformation on \mathcal{L} , which is such that $T(g) = s v g$ for all g with some fixed function which is locally of bounded variation, must have its range contained in \mathcal{L} , since $v g$ is locally absolutely continuous (by Theorem 2.2) and zero at the origin (since v is bounded in a neighborhood of the origin). That is, $v g = h k$ for k in \mathcal{L} and $s v g$ is in \mathcal{L} .

To find the norm of T as a transformation on L to L , let $k_\varepsilon(t) = \frac{v g(t - \varepsilon) - v g(t)}{\varepsilon}$ when $t \geq \varepsilon$ and $k_\varepsilon(t) = 0$ when $t < \varepsilon$. Then $k_\varepsilon \rightarrow T(g)$ almost everywhere as $\varepsilon \rightarrow 0^+$, and

$$k_\varepsilon = I_{1, \varepsilon} + I_{2, \varepsilon}$$

with

$$\begin{aligned} I_{1, \varepsilon}(t) &= \int_0^{t-\varepsilon} g(u) \frac{v(t-u-\varepsilon) - v(t-u)}{\varepsilon} du, & t \geq \varepsilon, \\ &= 0, & t < \varepsilon, \\ I_{2, \varepsilon}(t) &= \frac{1}{\varepsilon} \int_{t-\varepsilon}^t g(u) v(t-u) du, & t \geq \varepsilon, \\ &= 0, & t < \varepsilon. \end{aligned}$$

Since

$$\begin{aligned} \lim_{\varepsilon \rightarrow 0^+} \int_0^a |I_{1,\varepsilon}(t)| dt &\leq \|g\| \lim_{\varepsilon \rightarrow 0^+} \int_{\varepsilon}^a \left| \frac{v(u-\varepsilon) - v(u)}{\varepsilon} \right| du \\ &\leq \|g\| \text{Var } v_{[0,a]} \end{aligned}$$

and

$$\lim_{\varepsilon \rightarrow 0^+} \int_0^a |I_{2,\varepsilon}(t)| dt \leq \|g\| |v(0)|,$$

by Fatou's Lemma

$$\|T(g)\| \leq \|g\| (\text{Var } v + |v(0)|),$$

and

$$\|T\| \leq \text{Var } v + |v(0)|.$$

On the other hand if g_n , $n=1, 2, \dots$, are as in Theorem 1.1, the L norm of $sg_n v$ tends to $\text{Var } v + |v(0)|$ as n tends to infinity if v is normalized by $v(t) = v(t^-)$ for $t > 0$ and $v(0) = v(0^+)$.

It can also be shown that the Lebesgue-Stieltjes integral $\int_0^t g(t-u) dv(u)$ exists for almost every $t \geq 0$, is in \mathcal{L} , and is equal almost everywhere to svg . The proof follows the same line as in showing that gk is in \mathcal{L} whenever g and k are in \mathcal{L} . This yields an alternative method of proving Theorem 2.2.

It is a result of RYLL-NARDZEWSKI [2] that an operator of the form sv has an inverse of the form sv_1 , with v and v_1 locally of bounded variation if and only if $v(0^+) \neq 0$. That is, we know precisely which of the operators on \mathcal{L} to \mathcal{L} that commute with convolution have inverses.

If two elements of \mathcal{L} , f and g , are such that the range of the linear transformation determined by f includes the range of the linear transformation determined by g , we shall say $f \geq g$. If the containment is proper, we shall say $f > g$. Then

Theorem 3.2. (i) $f \geq g$ if and only if $g = svf$ where v is locally of bounded variation. (ii) $f > g$ if and only if $g = svf$ where v is locally of bounded variation and $v(0^+) = 0$.

Proof. (i) Suppose that $f \geq g$. Then every element of \mathcal{L} which has g as a factor also has f as a factor. Let k be in \mathcal{L} . Then g/f is in the field of Mikusiński operators, and

$$\frac{g}{f} k = \frac{gk}{f} = \frac{fk_1}{f} = k_1$$

where k_1 is in \mathcal{L} . Thus the transformation $k \rightarrow \frac{g}{f} k$ takes \mathcal{L} into \mathcal{L} and commutes with convolution. Thus $g/f = sv$ with v locally of bounded variation. On the other hand if $g = svf$ and v is locally of bounded variation, any function of the form gk is also of the form $(svf)k = f k_1$ so that $f \geq g$. (ii) If $g = svf$ and $v(0^+) \neq 0$, then $\frac{1}{sv} = sv_1$ so that $f = sv_1 g$. Thus the range of T must equal the range of T , and we cannot have $f > g$. On the other hand if the ranges of T_f and T_g are equal, we must have $g = svf$ and $f = sv_1 g$ with v and v_1 locally of bounded variation. Thus $\frac{1}{sv} = sv_1$, and by RYLL-NARDZEWSKI's theorem $v(0^+) v(0^+) \neq 0$.

Theorem 3.2 can be viewed as a comparison theorem for the existence of functional solutions to the convolution integral equation $xf=k$. Thus a re-statement of Theorem 3.2(i) is

Corollary 3.3. *Let f and g be in \mathcal{L} . The integral equation $xf=k$ has a solution in \mathcal{L} for every k in \mathcal{L} such that $xg=k$ has a solution in \mathcal{L} if and only if $g=svf$ where v is locally of bounded variation.*

4. A simple application is given by the functions which are locally of bounded variation. Any function f which is locally of bounded variation and for which $f(0^+) \neq 0$ is equivalent to h in the sense that both $h \geq f$ (since $f=(sf)h$) and $f \geq h$ (since $h=\frac{1}{sf}f=svf$). Thus the integral equations $xh=k$ and $xf=k$ have solutions for exactly the same set of k .

Theorem 4.1. *If f is locally of bounded variation and $f(0^+) \neq 0$, a necessary and sufficient condition that the convolution integral equation $xf=k$ has a solution x in \mathcal{L} is that k be locally absolutely continuous and zero at the origin.*

Proof. The condition on k is that k be the integral of a function in \mathcal{L} , and this is a necessary and sufficient condition that $xh=k$ have a solution x in \mathcal{L} .

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