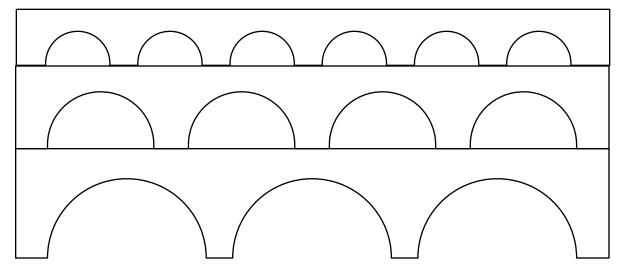
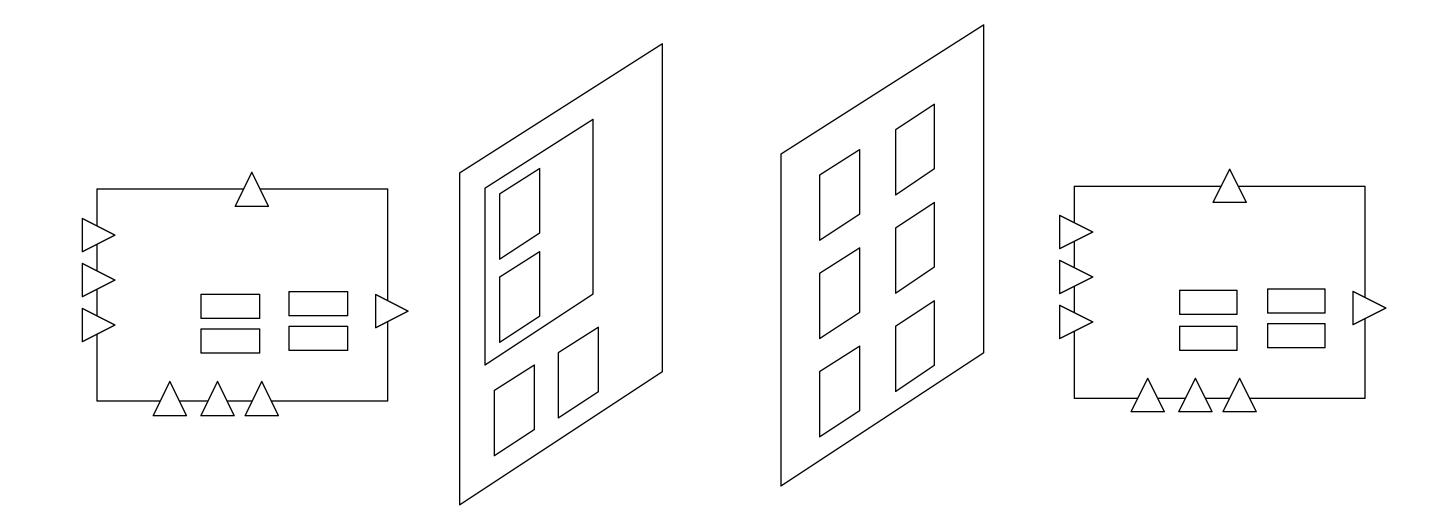
The Roman aqueduct model



Concepts of toolkits

Some common concepts

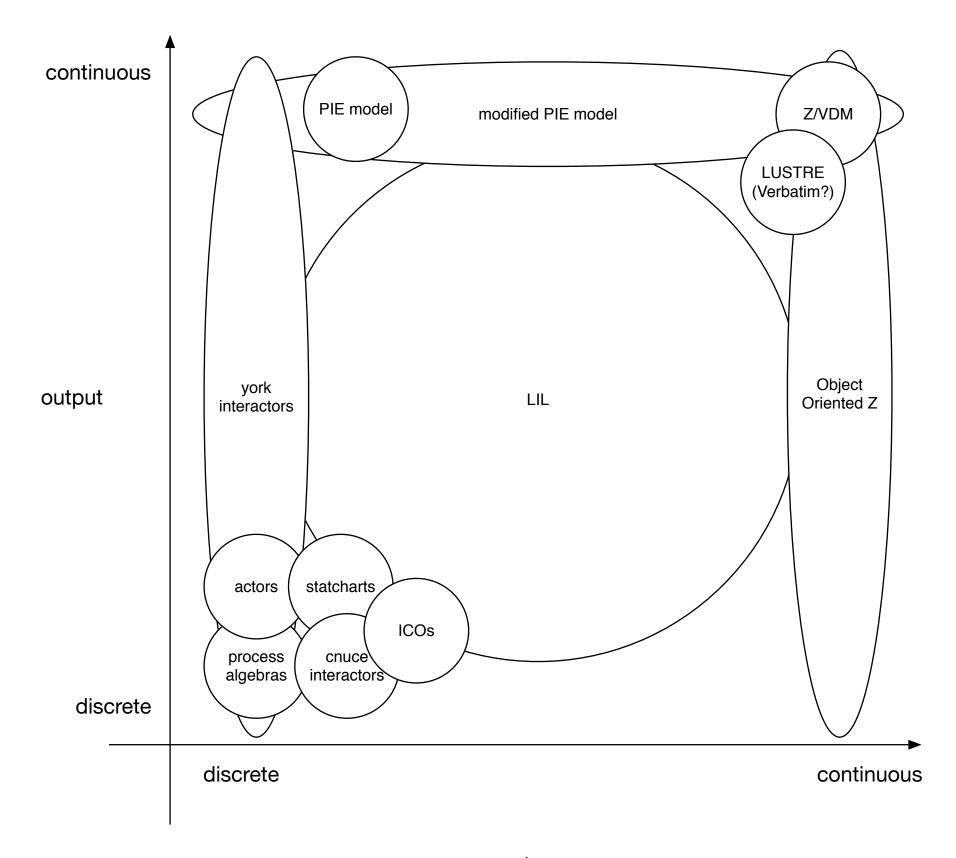
Undefined Base concepts



Grandes dualités

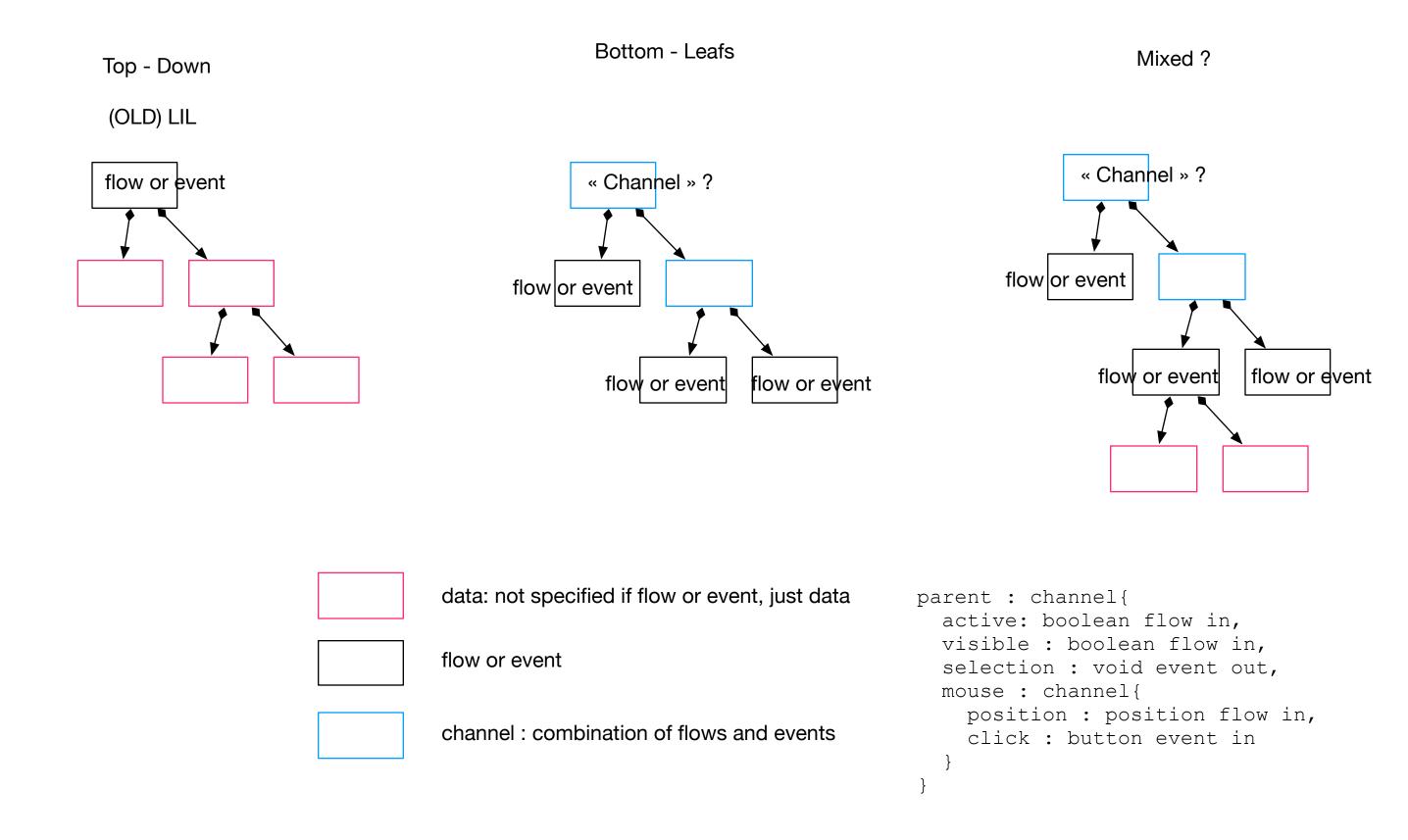


Synthetizated / State
React synthesized variables vs state



input

ncept of composition of flows and events



Concept of multi-composition

an interaction is part of MULTIPLE interactors it is SHARED between them

one has access to it and so does the other

an interactor has multiple parents

user hierarchy machine hierarchy the notion of PARENT

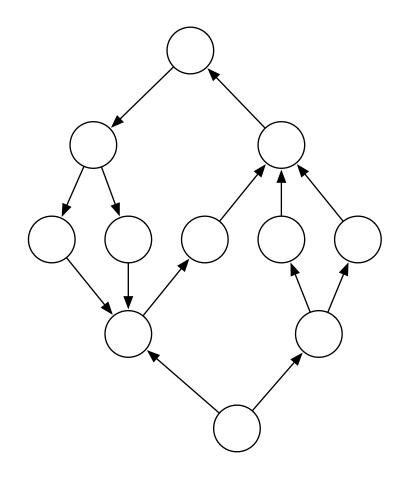
an actor is a perspective an actor is a projection axis an actor is a direction

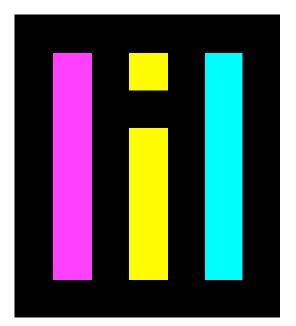
an interactor has got as much parents as actors he deals with

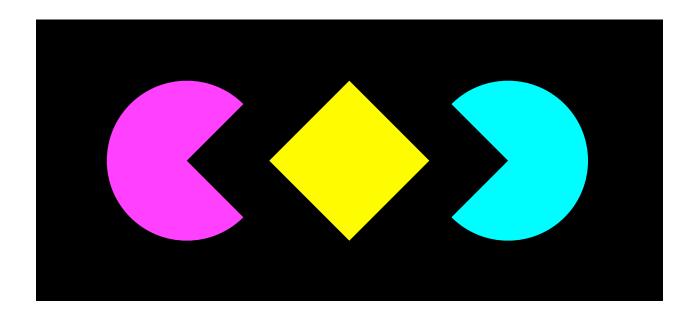
So we have as many interactor hierarchies as we have actors

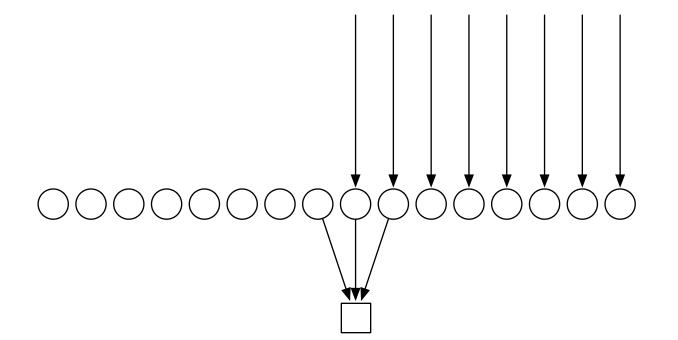
MUST merge with the notion of actor parent is the next interactor of the hierarchy in the direction of an actor

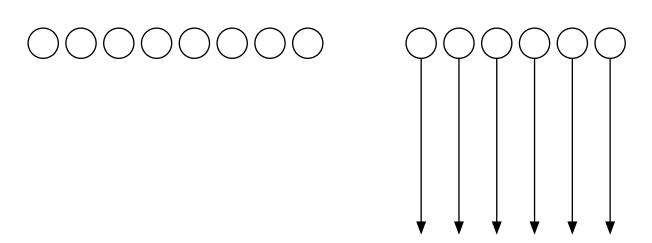
button interactor







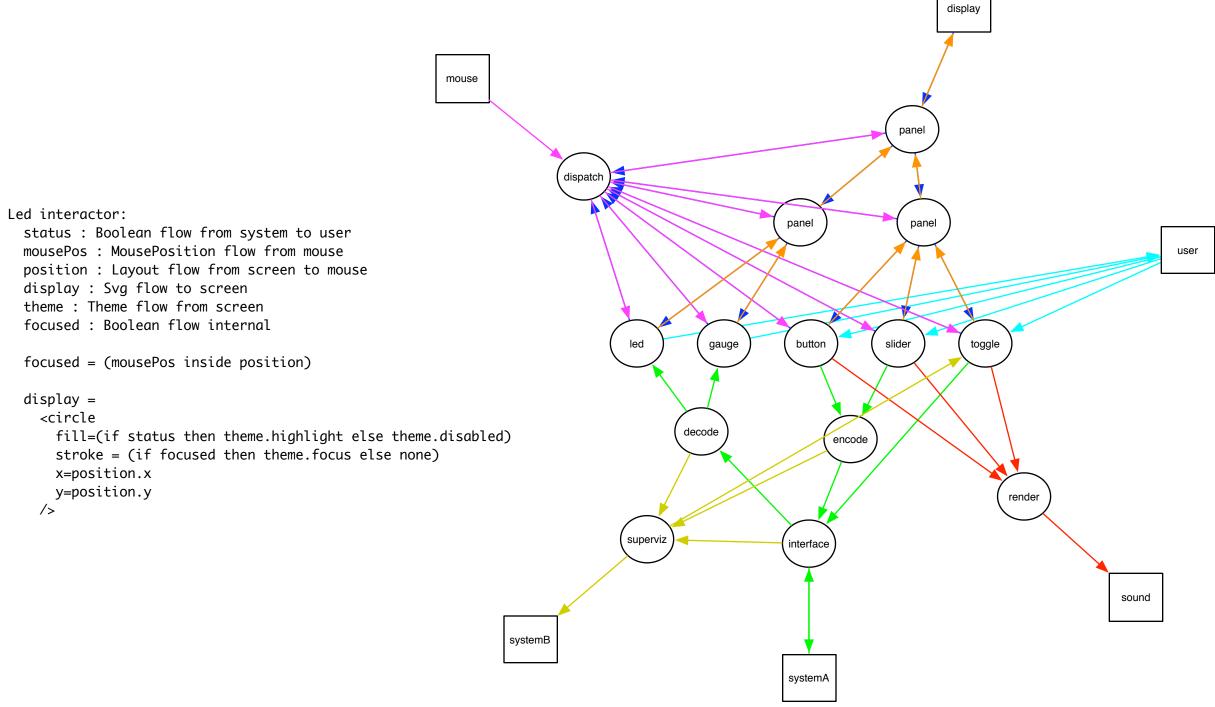




Multi composition example

Example multimodal

modalités en haut de chaque hierarchie



Check that:

(signal to user) <=> ((signal to sound) U (signal to screen)) signal from user <=> signal from mouse

layout info

mouse info

display info

systemA info

sound info

systemB info

user info

Multi composition example

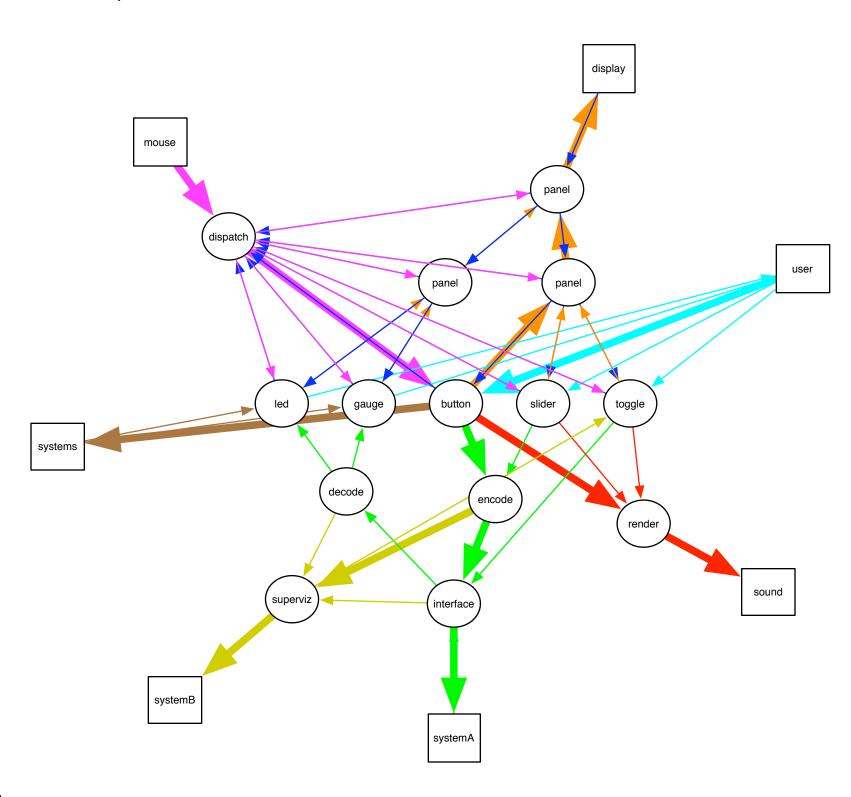
Example multimodal

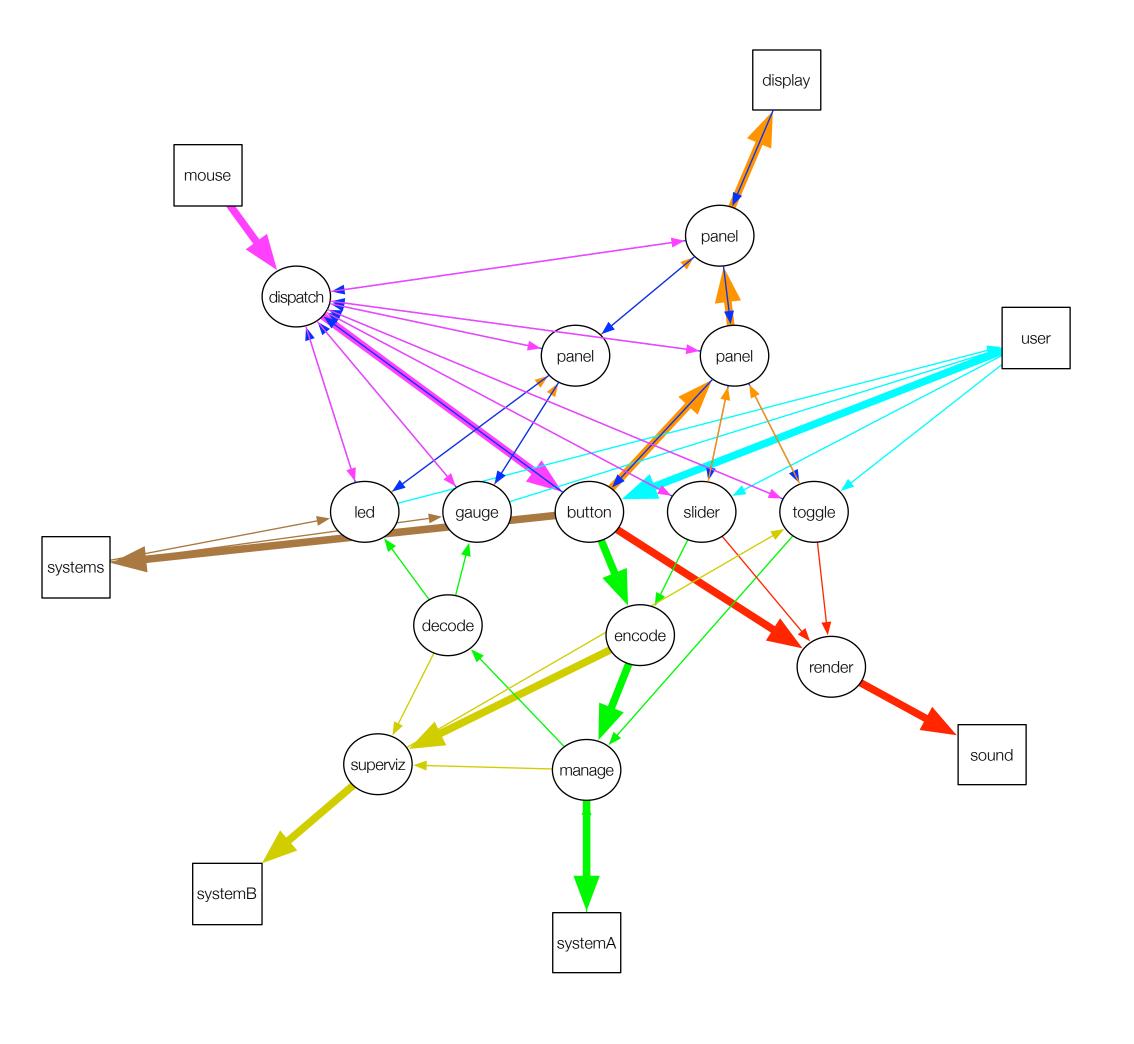
modalités en haut de chaque hierarchie

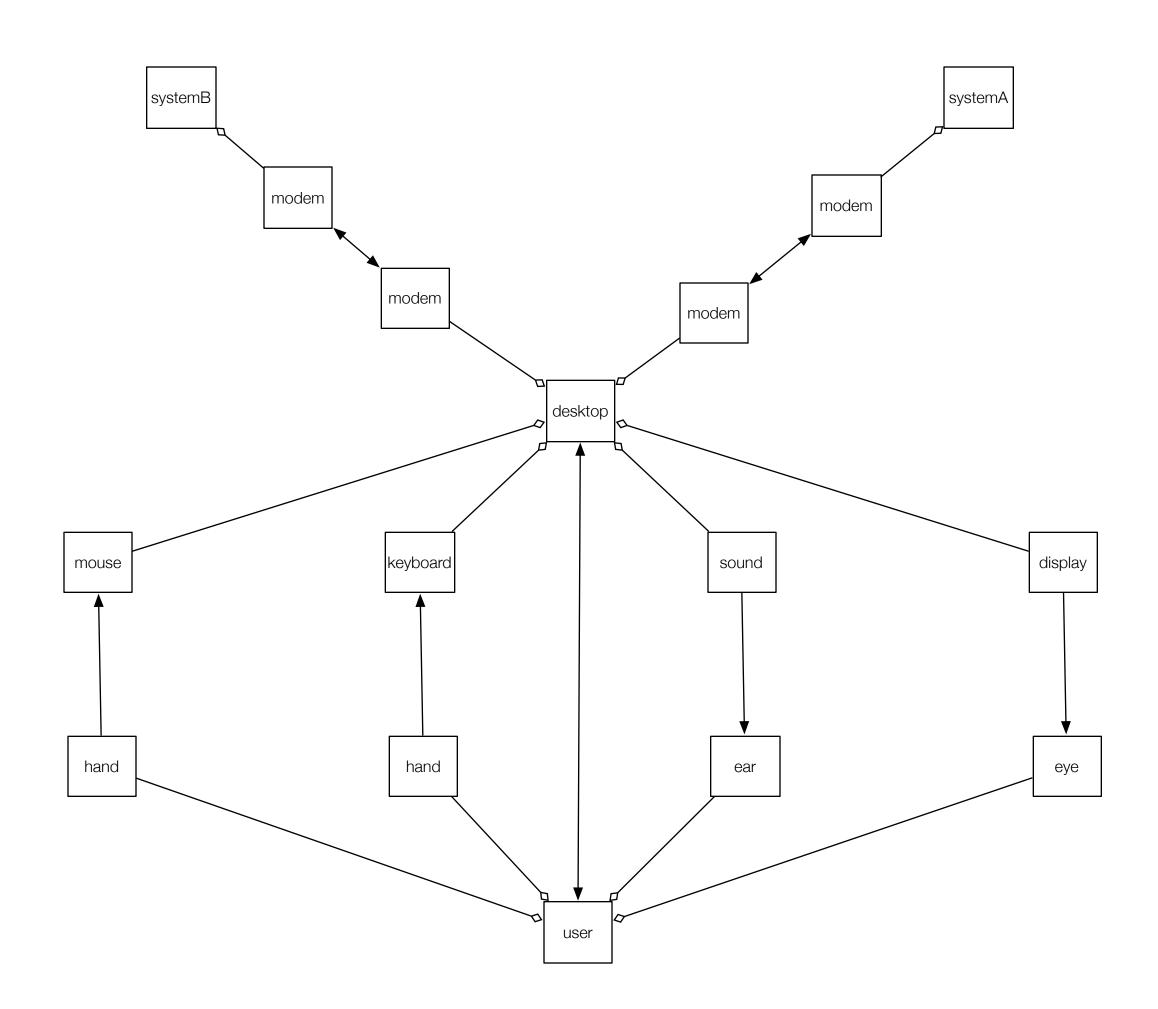
```
layout info
        mouse info
        display info
        systemA info
        sound info
        systemB info
        user info
Led interactor:
  status : Boolean flow from system to user
 mousePos: MousePosition flow from mouse
  position: Layout flow from screen to mouse
  display: Svg flow to screen
  theme: Theme flow from screen
  focused: Boolean flow internal
  focused = (mousePos inside position)
 display =
    <circle
      fill=(if status then theme.highlight else theme.disabled)
      stroke = (if focused then theme.focus else none)
      x=position.x
     y=position.y
```

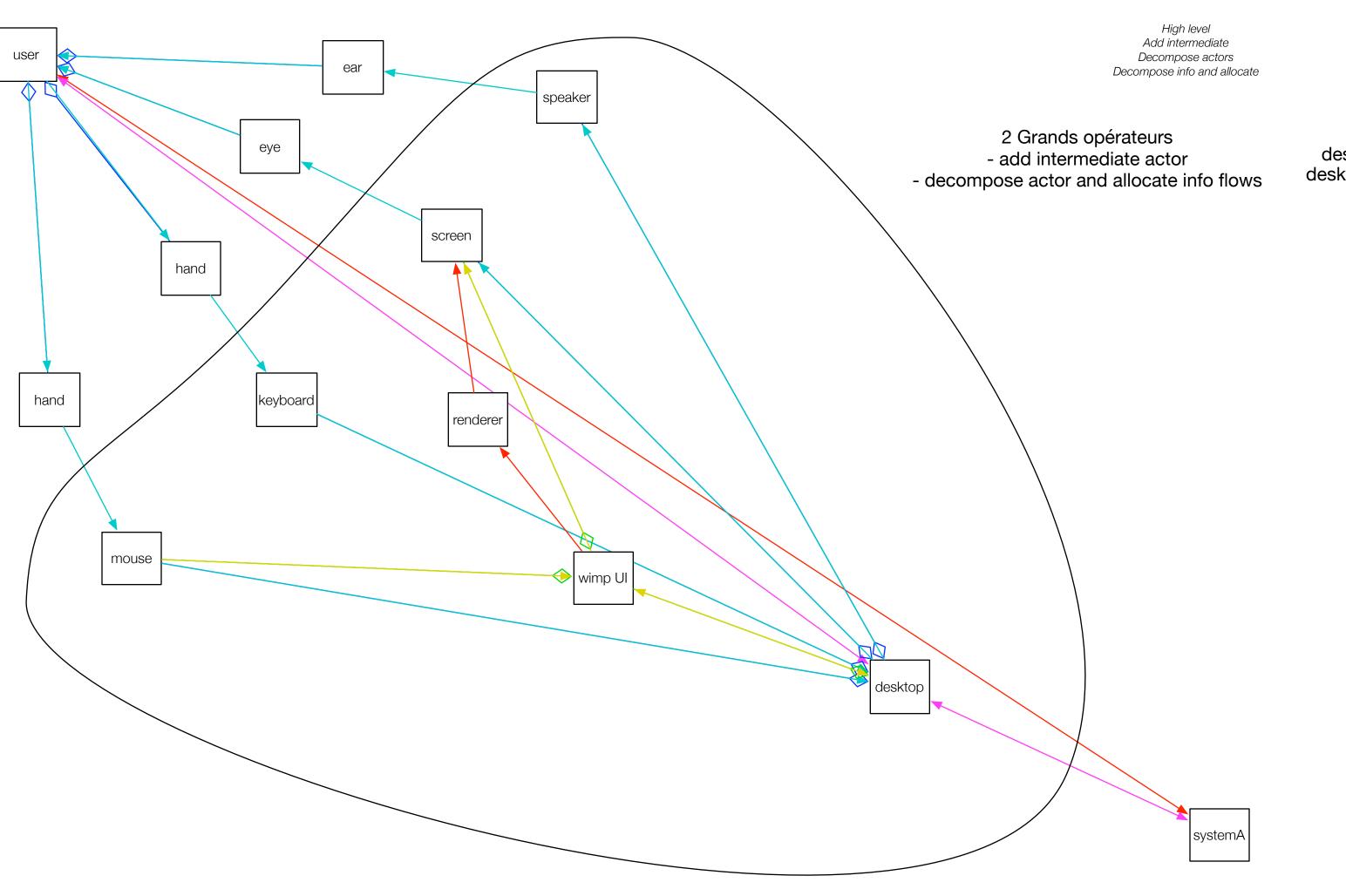
Check that:

(signal to user) <=> ((signal to sound) U (signal to screen))
signal from user <=> signal from mouse
(signal to systems) <=> signal to systemA U signal to systemB

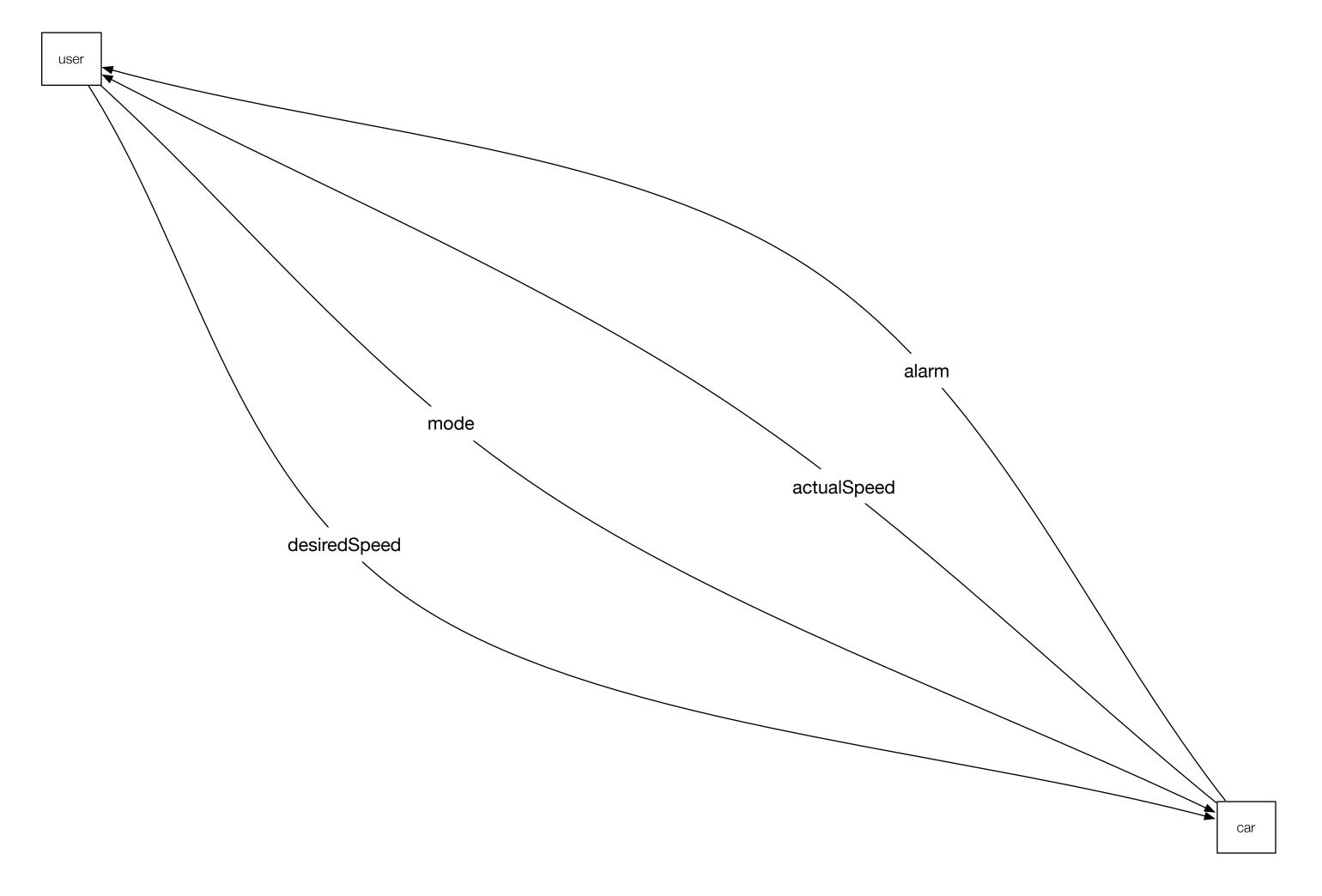








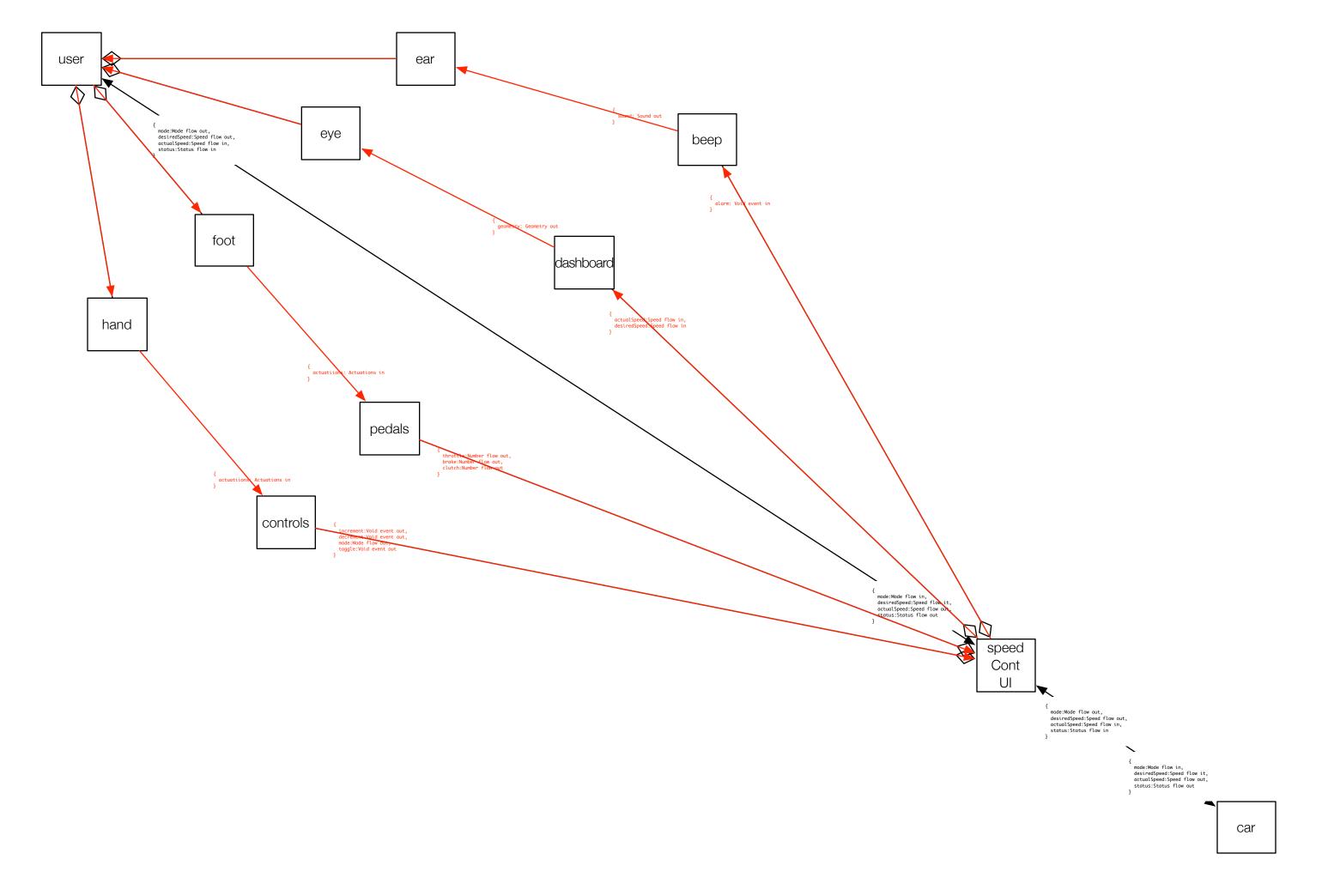
desktop INTERMEDIATE BETWEEN (user, systemA) desktop MADE OFF (screen, keyboard, speaker, mouse)

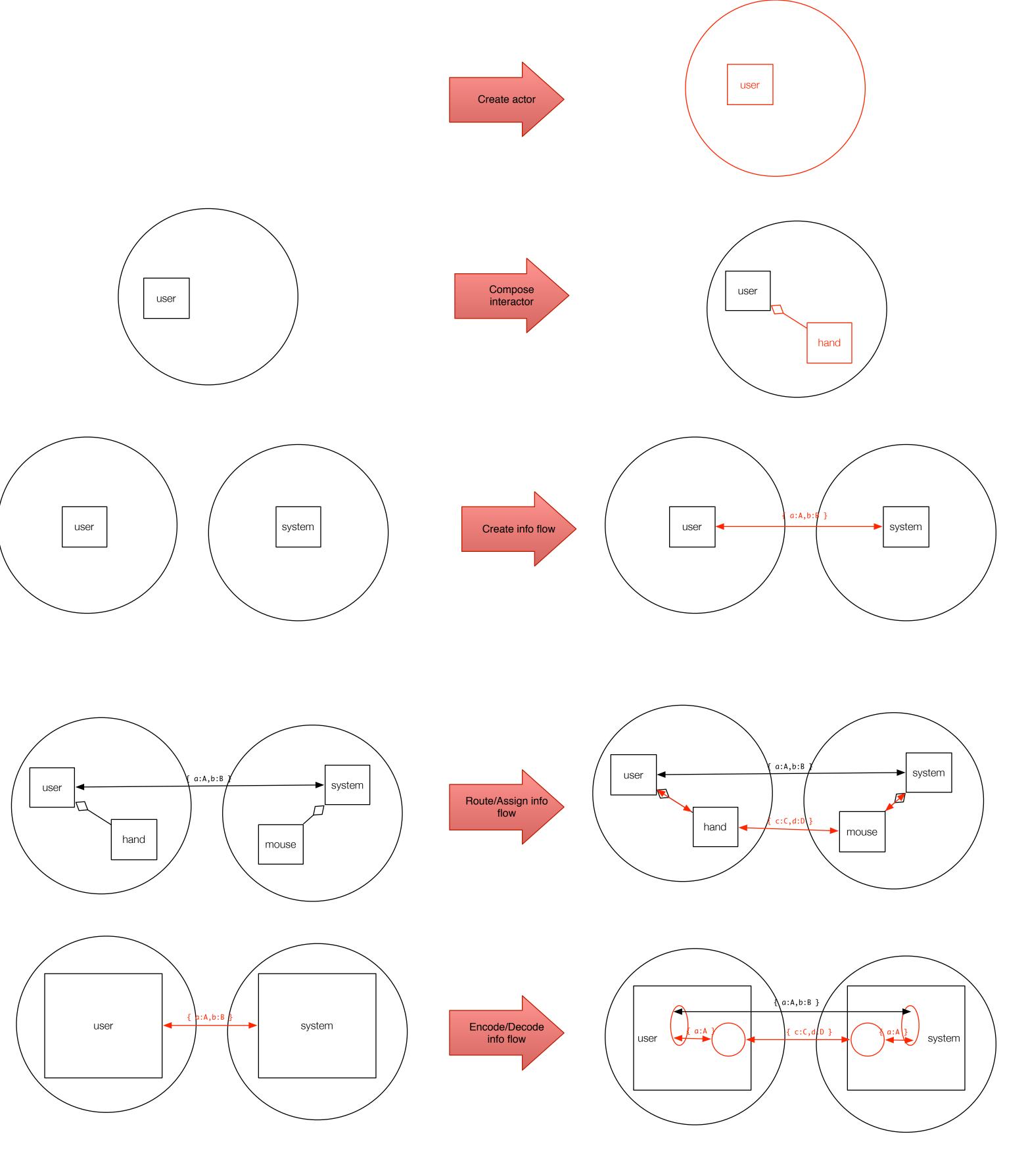


user mode:Mode flow from user to car, desiredSpeed:Speed flow from user to car, actualSpeed:Speed flow from car to user, status:Status flow from car to user car user mode:Mode flow out, desiredSpeed:Speed flow out, actualSpeed:Speed flow in, status:Status flow in mode:Mode flow in, desiredSpeed:Speed flow it, actualSpeed:Speed flow out, status:Status flow out car

```
user
        mode:Mode flow out,
        desiredSpeed:Speed flow out,
        actualSpeed:Speed flow in,
        status:Status flow in
      }
                                               mode:Mode flow in,
                                               desiredSpeed:Speed flow it,
                                               actualSpeed:Speed flow out,
                                               status:Status flow out
                                                                             speed
                                                                              Cont
                                                                              UI
                                                                                      mode:Mode flow out,
                                                                                      desiredSpeed:Speed flow out,
                                                                                      actualSpeed:Speed flow in,
                                                                                      status:Status flow in
                                                                                                                   mode:Mode flow in,
                                                                                                                   desiredSpeed:Speed flow it,
                                                                                                                   actualSpeed:Speed flow out,
                                                                                                                    status:Status flow out
                                                                                                                                                car
```

```
user
                   mode:Mode flow out,
                   desiredSpeed:Speed flow out,
                   actualSpeed:Speed flow in,
                   status:Status flow in
                                                                                                                                                mode:Mode flow in,
                                                                                                                                                desiredSpeed:Speed flow it,
                                                                                                                                                actualSpeed:Speed flow out,
                                                                                                                                                status:Status flow out
                                                                                                                                                                                                        speed
                                                                                                                                                                                                         Cont
                                                                                                                                                                                                                      f
mode:Mode flow out,
desiredSpeed:Speed flow out,
actualSpeed:Speed flow in,
status:Status flow in
                                                                                                                                                                                                                                          mode:Mode flow in,
desiredSpeed:Speed flow it,
actualSpeed:Speed flow out,
status:Status flow out
```





An actor IS a (super?)interactor

A behavior IS an (sub)interactor!

NO INTERACTORS, ACTORS, BEHAVIOR : ONLY INTERACTION
WE DESCRIBE THE SET OF POSSIBLE INTERACTIONS FOR AN ENTITY

And their relationship

exemple: inc/dec to set speed behavior

an interactor:
inputs from driver: inc dec
inputs from parent: limits
output to parent: value

Data Computation Interaction

we have Languages to describe data (e.g.: C,JSON, XML)

we have Languages to describe computation (e.g.: C,JS)

we don't have Languages to describe interaction ??????

Set of possible interactions and their relationship

Human interaction:

hands: Hands interaction foots: Foots interaction eyes: Eyes interaction ears: Ears interaction

SpeedController interaction:

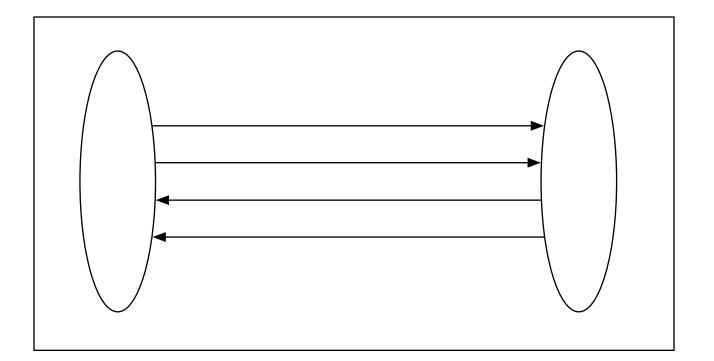
controls : Controls interaction
pedals : Pedals interaction

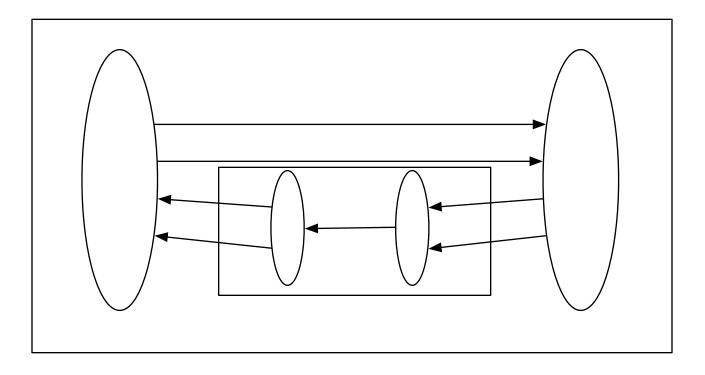
dashboard: Dashboard interaction

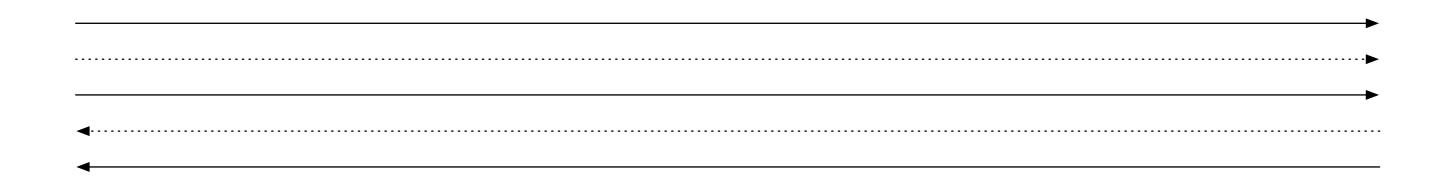
Controls interaction:

increment : Void event in
decrement : Void event in

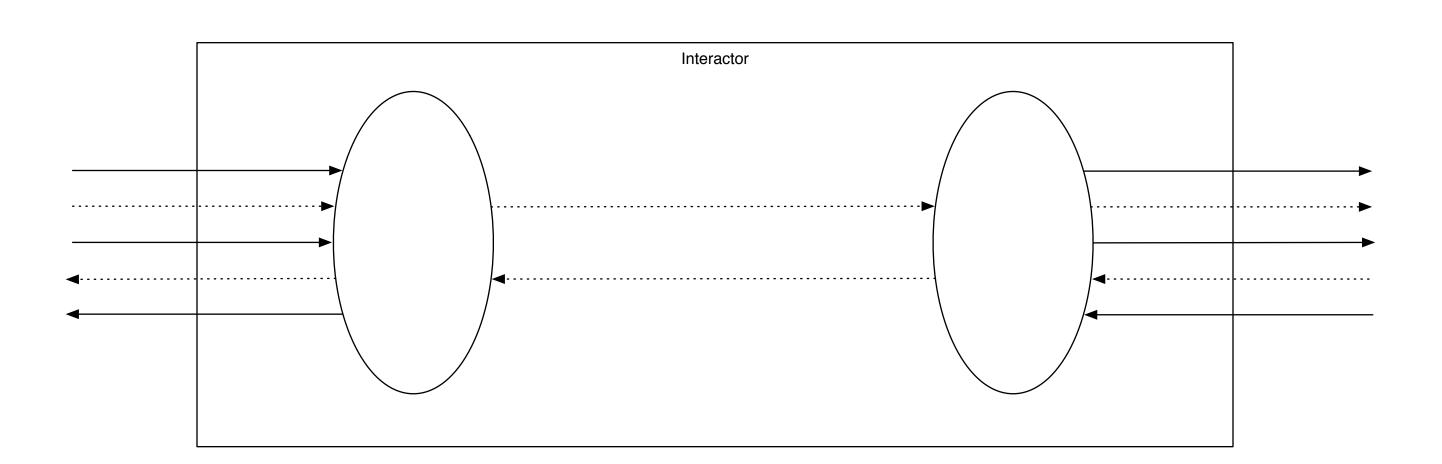
mode : Mode flow in



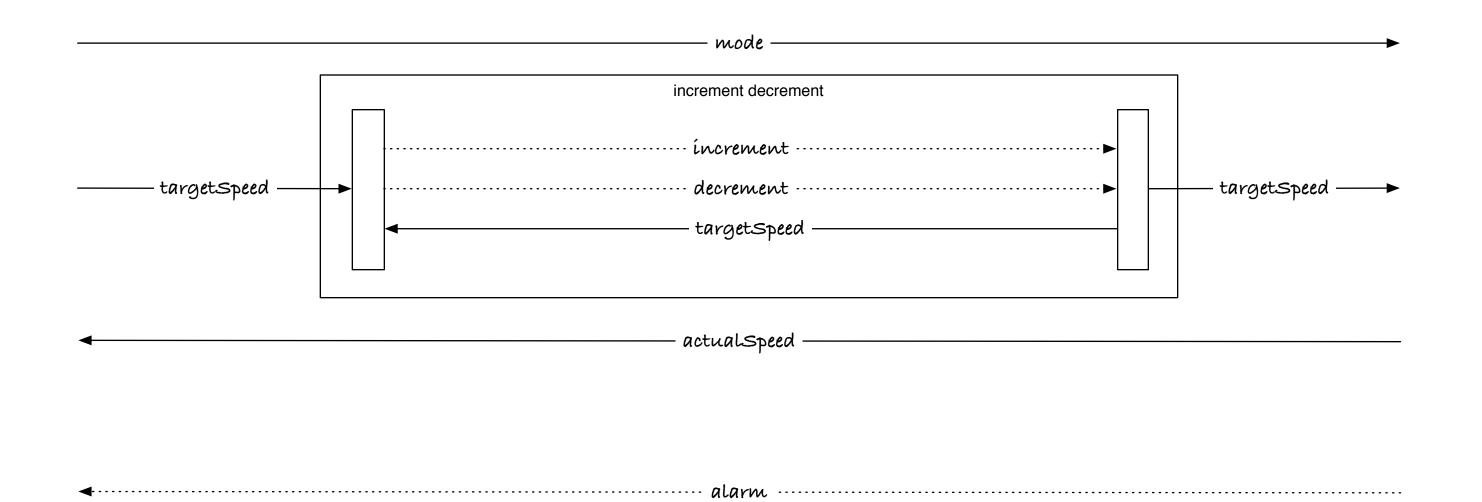


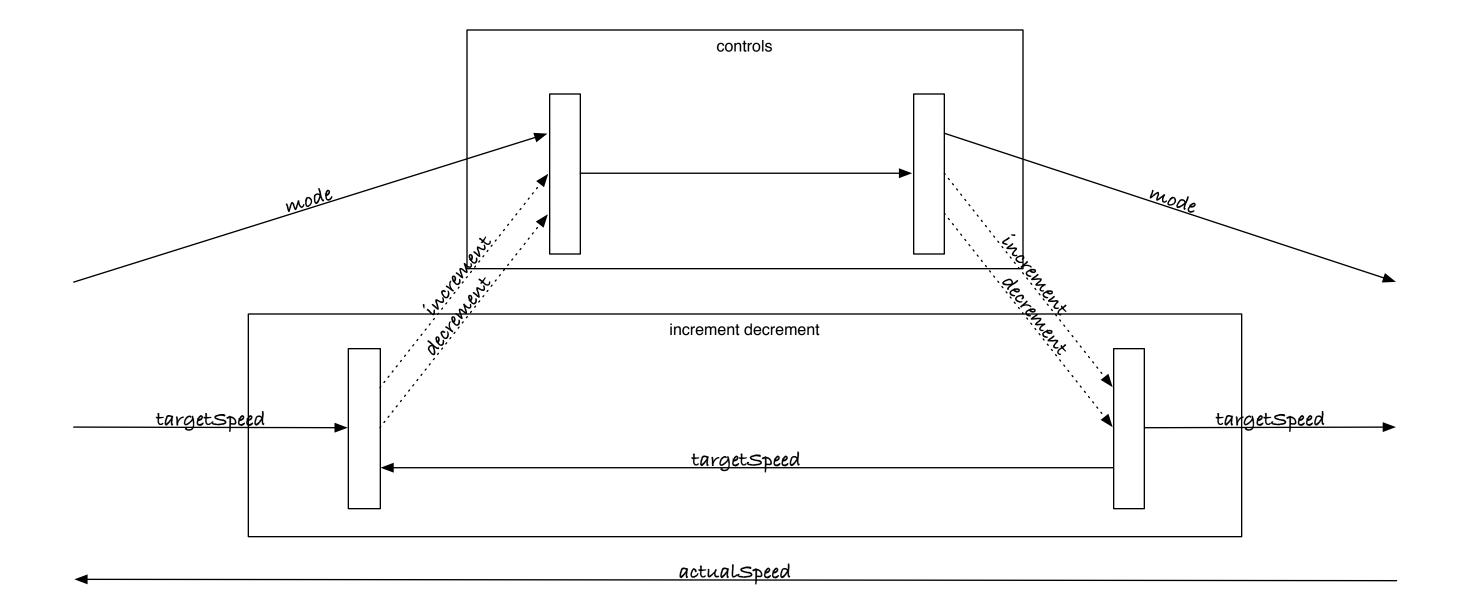




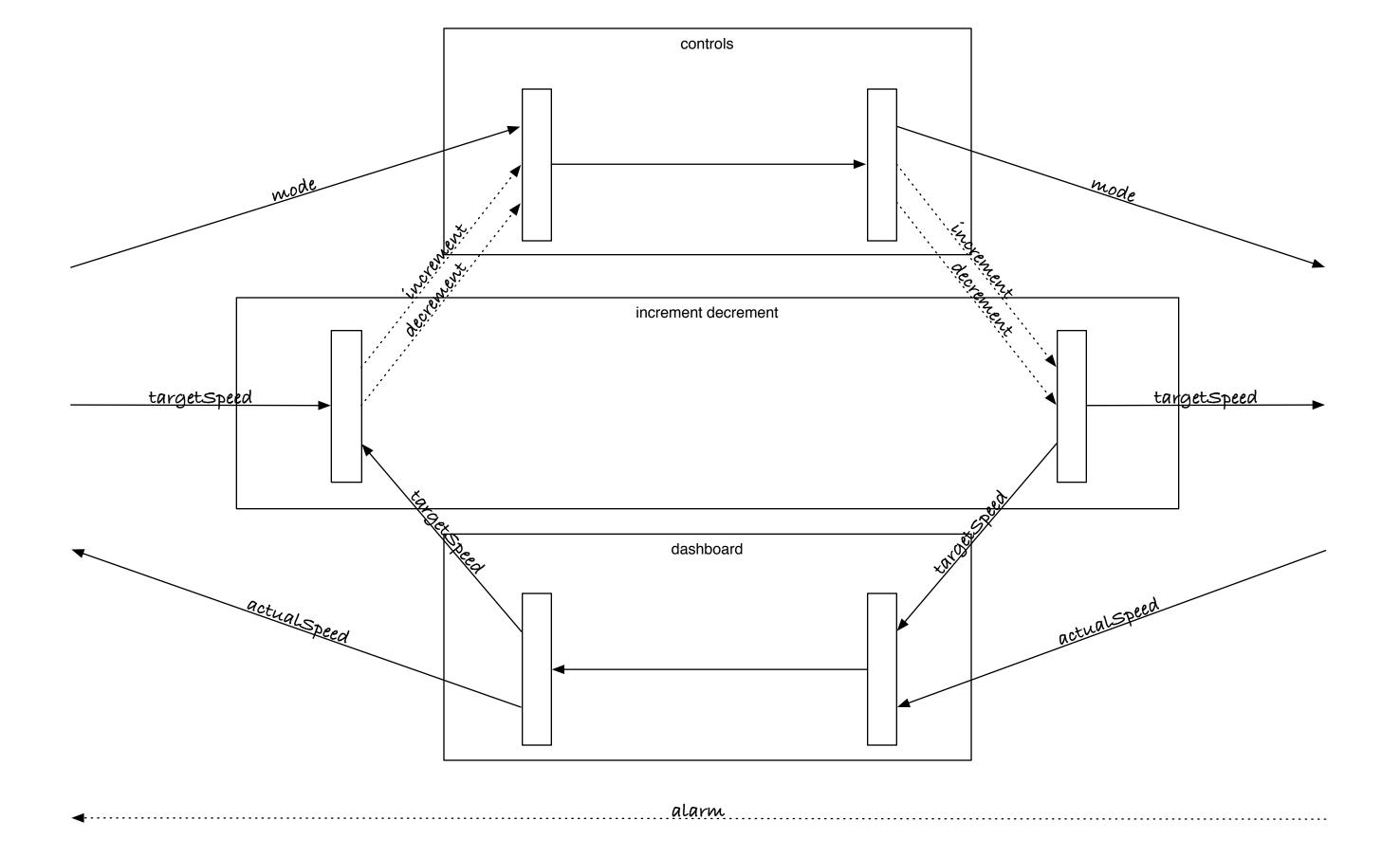


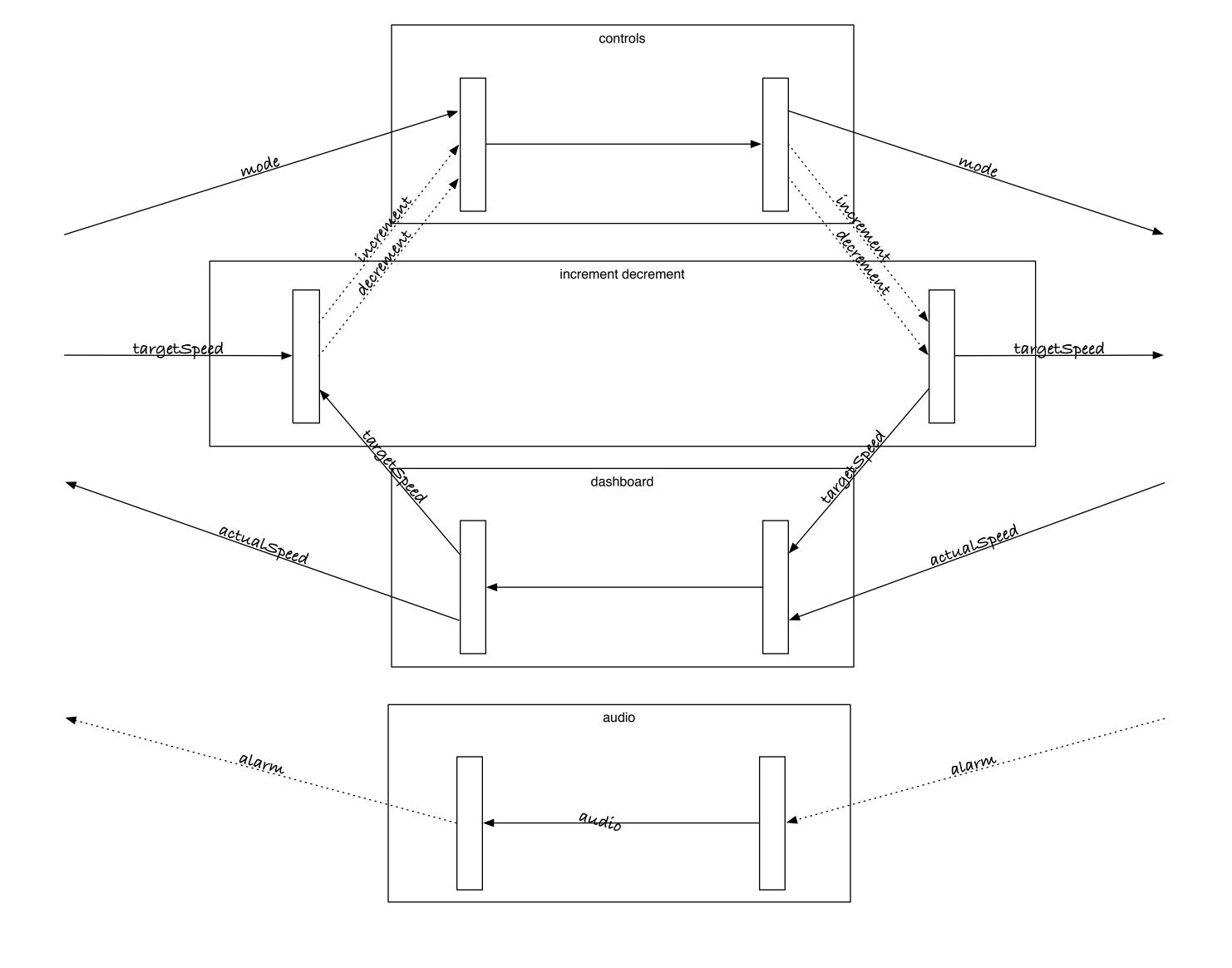
	— mode —
	targetSpeed
•	actualSpeed ————
◀	··· alarm ·····

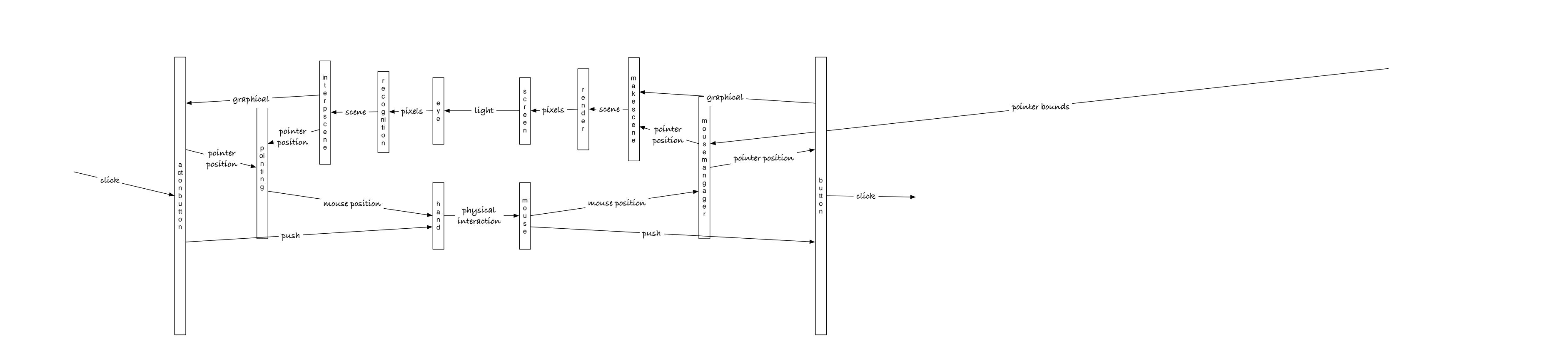


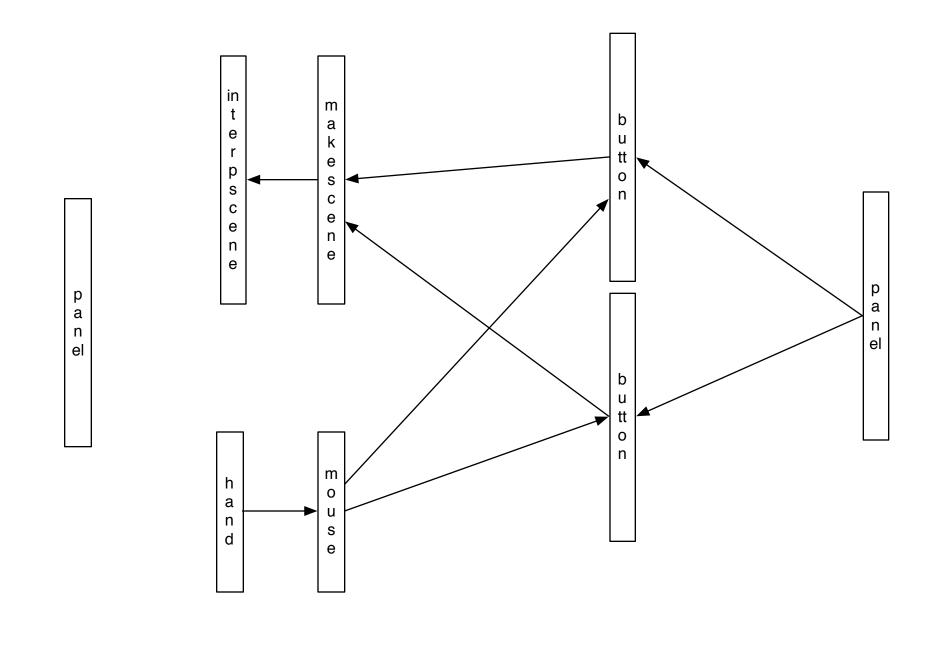


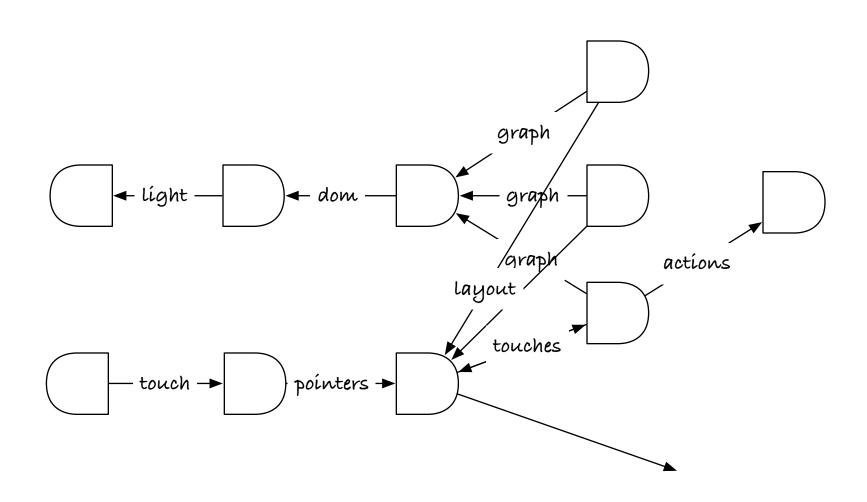
alarm

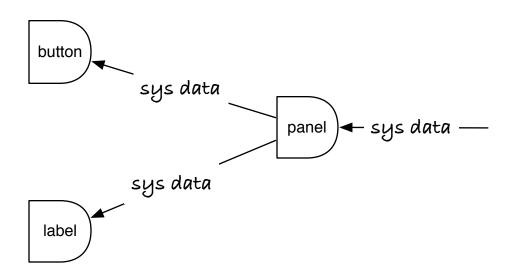


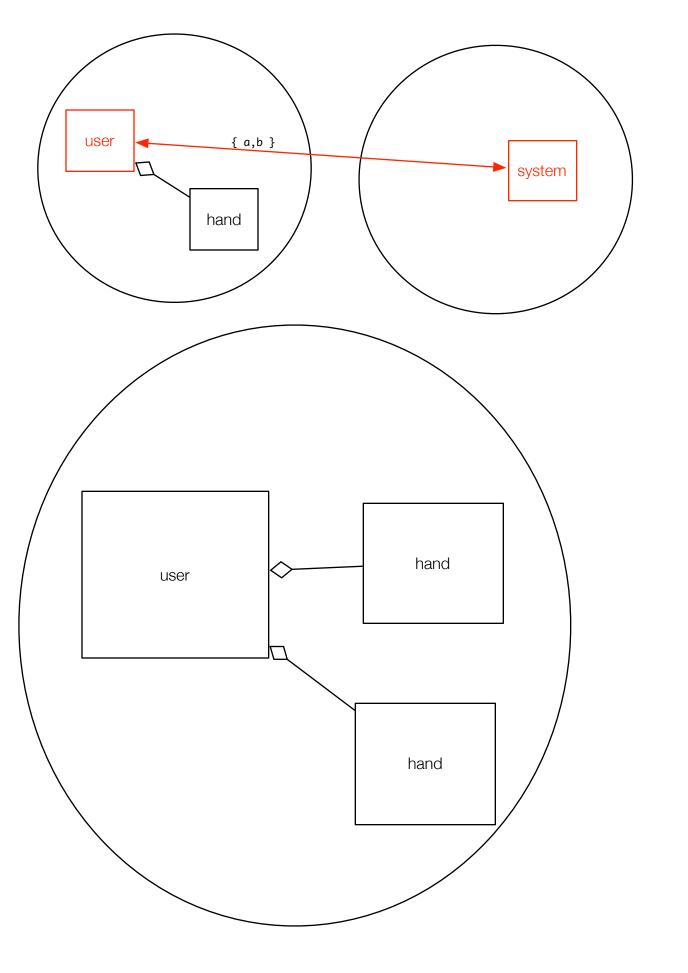


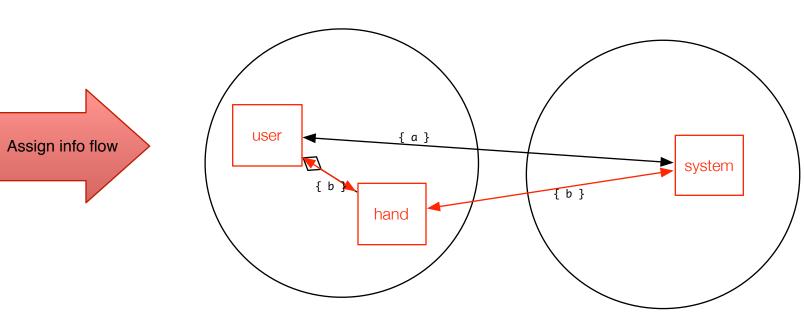












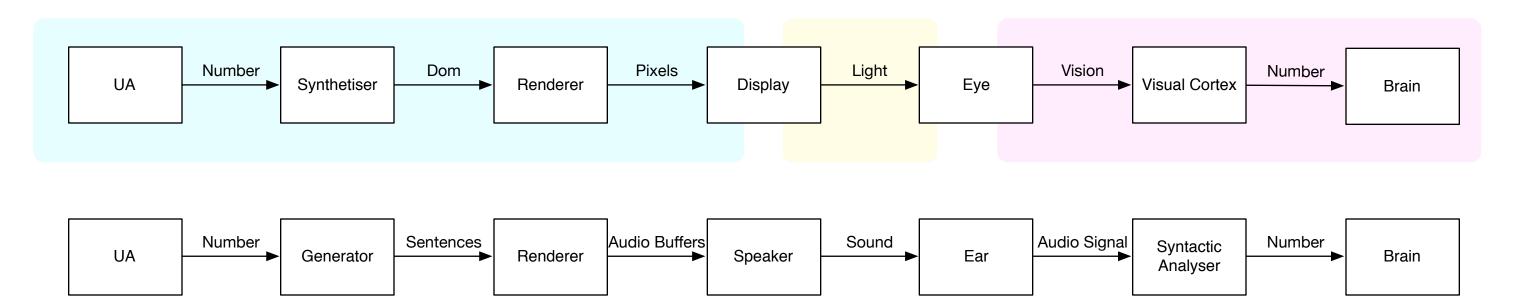
Kind of OSI layer model

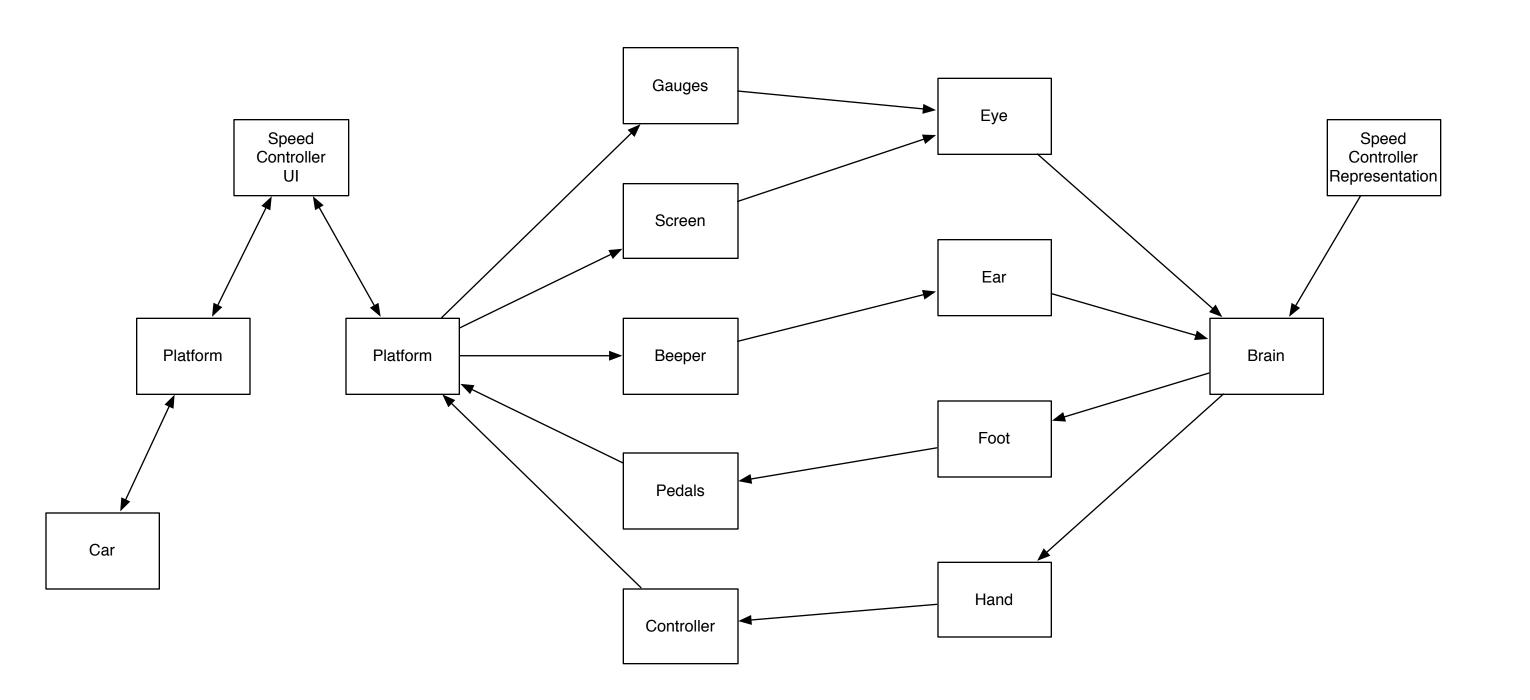
Model checking context

UA Number

Brain

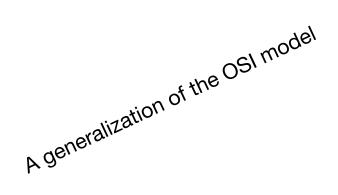
Actual context

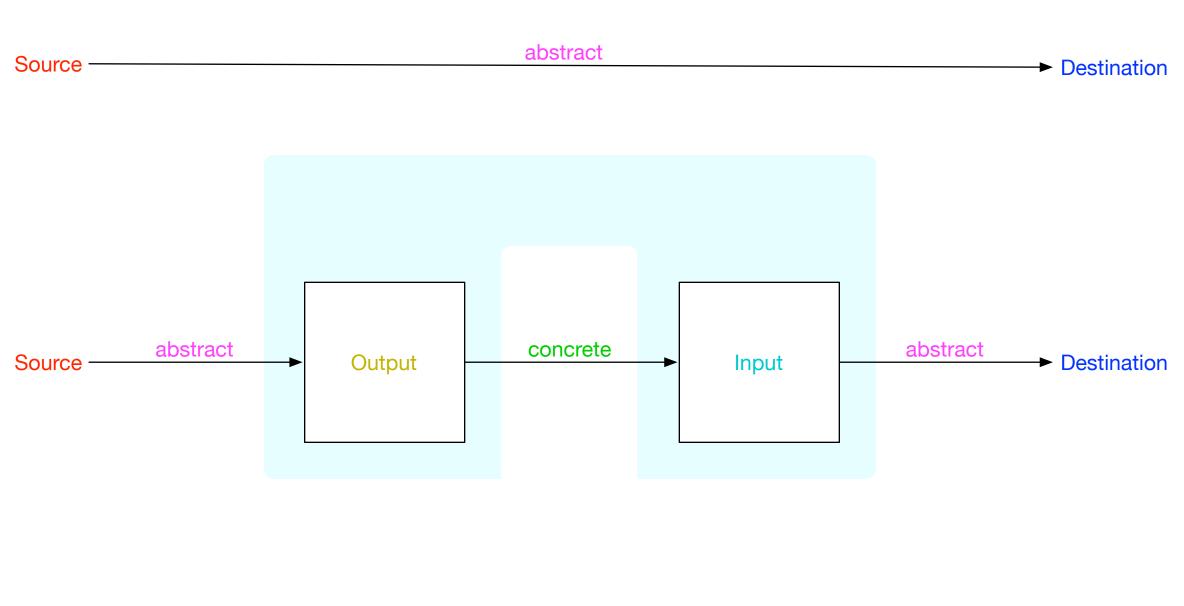


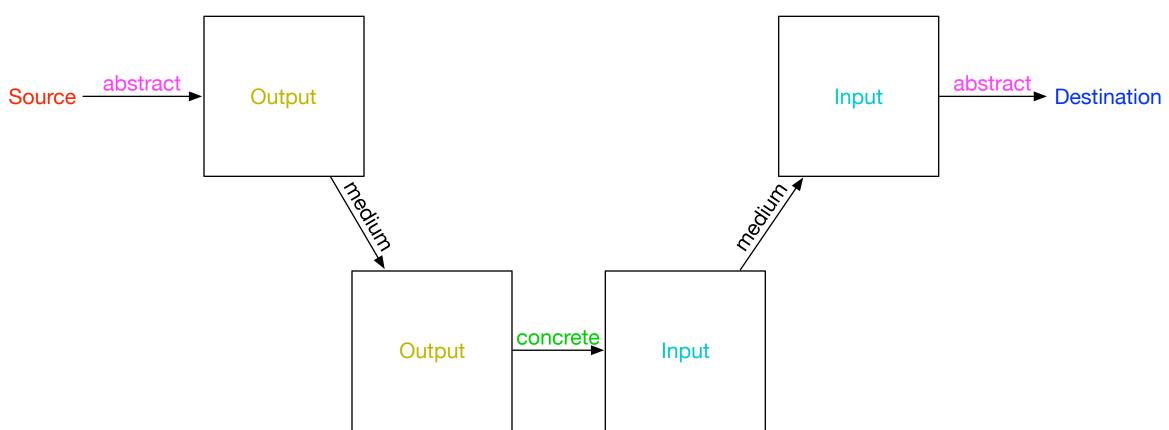


What is an interactive system?

A system that takes an abstract flow of information between a source and a destination, and transforms it into a concrete flow of information between an output and an input, mapping the output to the source, and the input to the destination. An important thing is that abstract and concrete are relative notions.



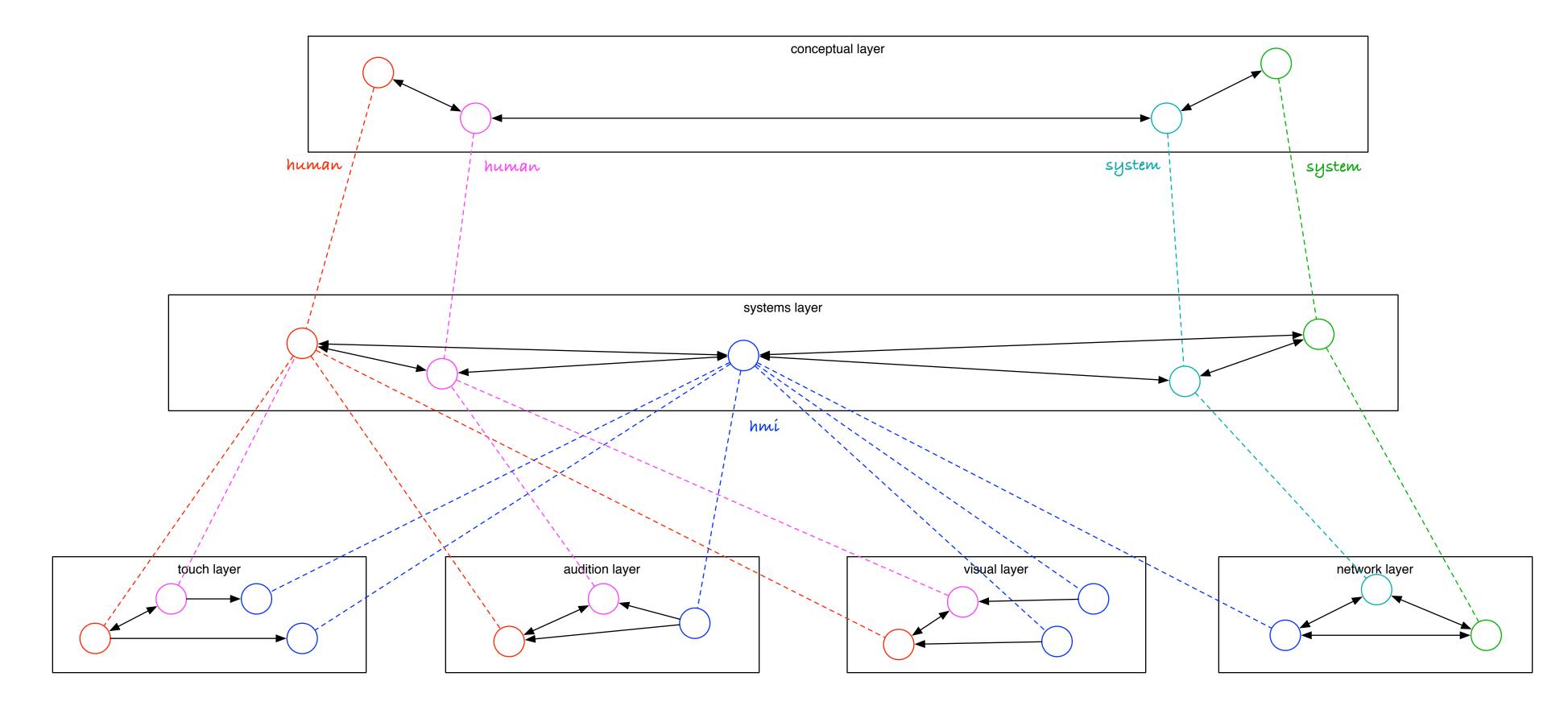


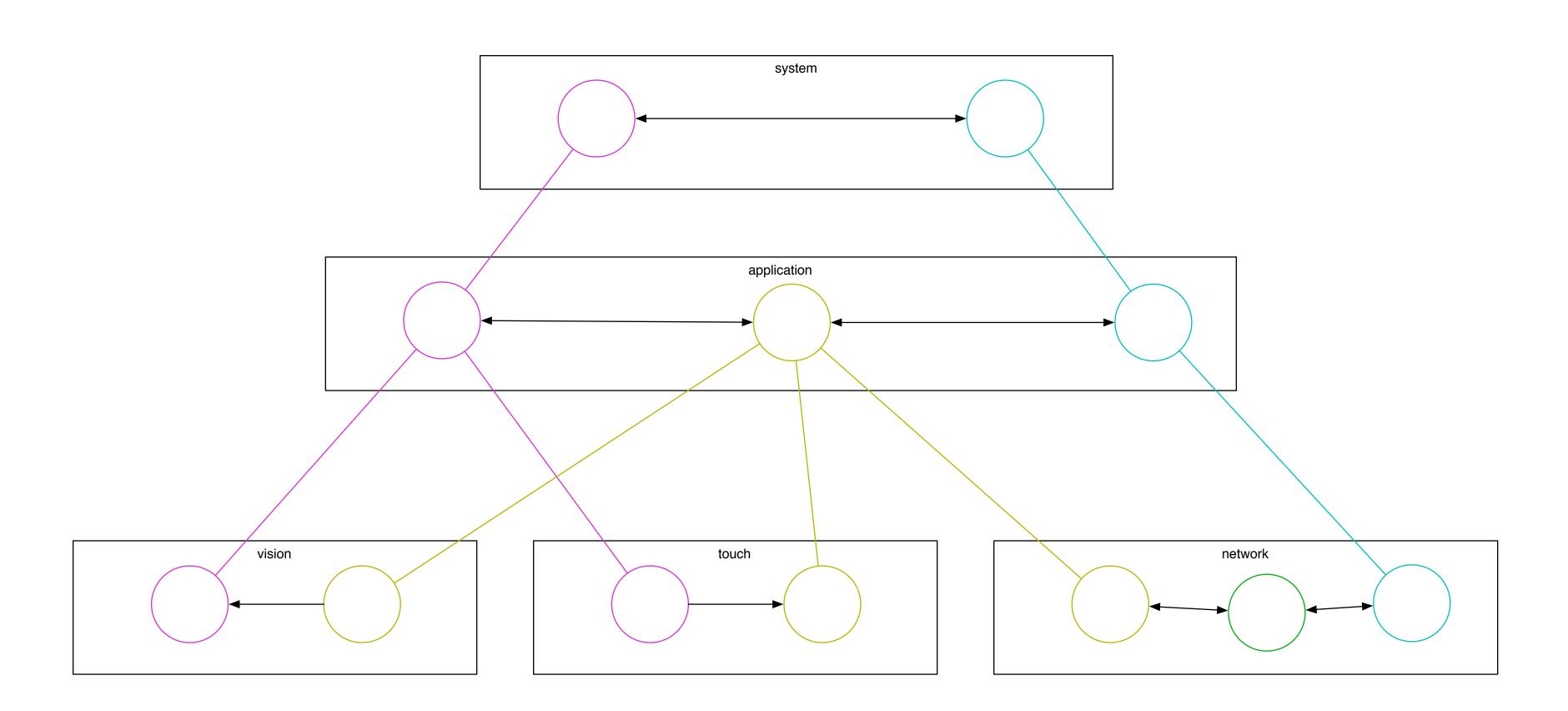


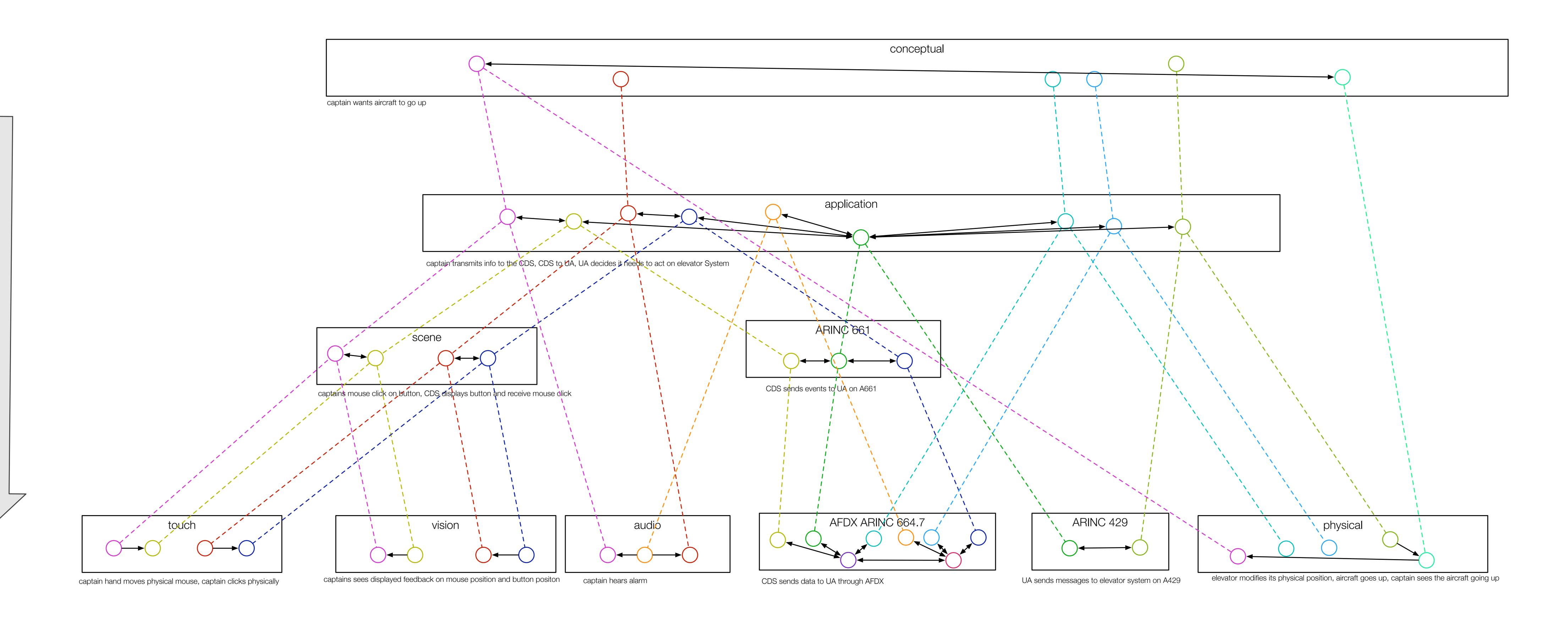
Different ways of concretization

- concretize signals origins and destination
 - instantiate concrete sub components

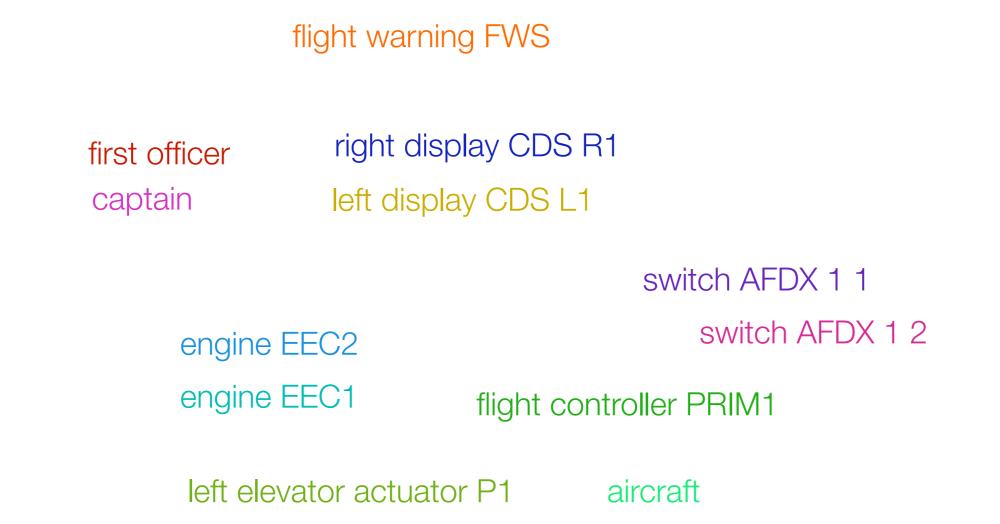
Pamela Zave geomorphic layer model of networks

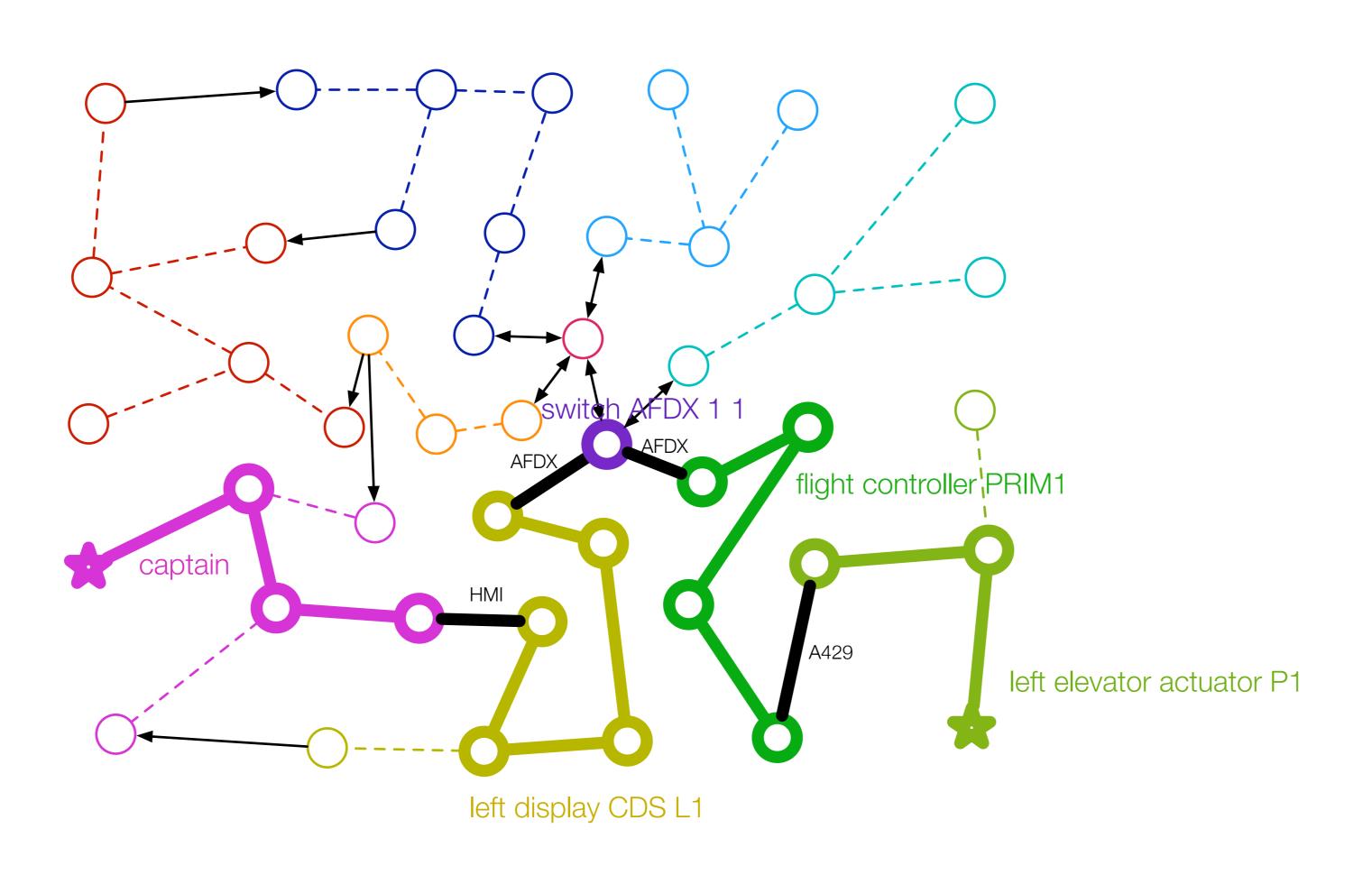






state variables and dynamic evolution and behavior are INSIDE Circles





emission:

active(identifier) value(identifier) {identifier:emission,...,identifier:emission}

reception:

active(identifier) value(identifier)

operator(reception,...,reception)
{identifier:reception,...,identifier:reception}

behavior:

affect(reception,emission)
on(reception,behavior)
always(behavior)
and(behavior,...,behavior)
or(behavior,...,behavior)

stepManage::behavior(min::reception, max::reception, init::reception, step::reception, var::emission, increment::reception, decrement::reception) :=
and(
 declare(temp),

stepManage::behavior(min::reception,max::reception,init::reception,step::reception,var::emission,increment::reception,decrement::reception) :=
and(

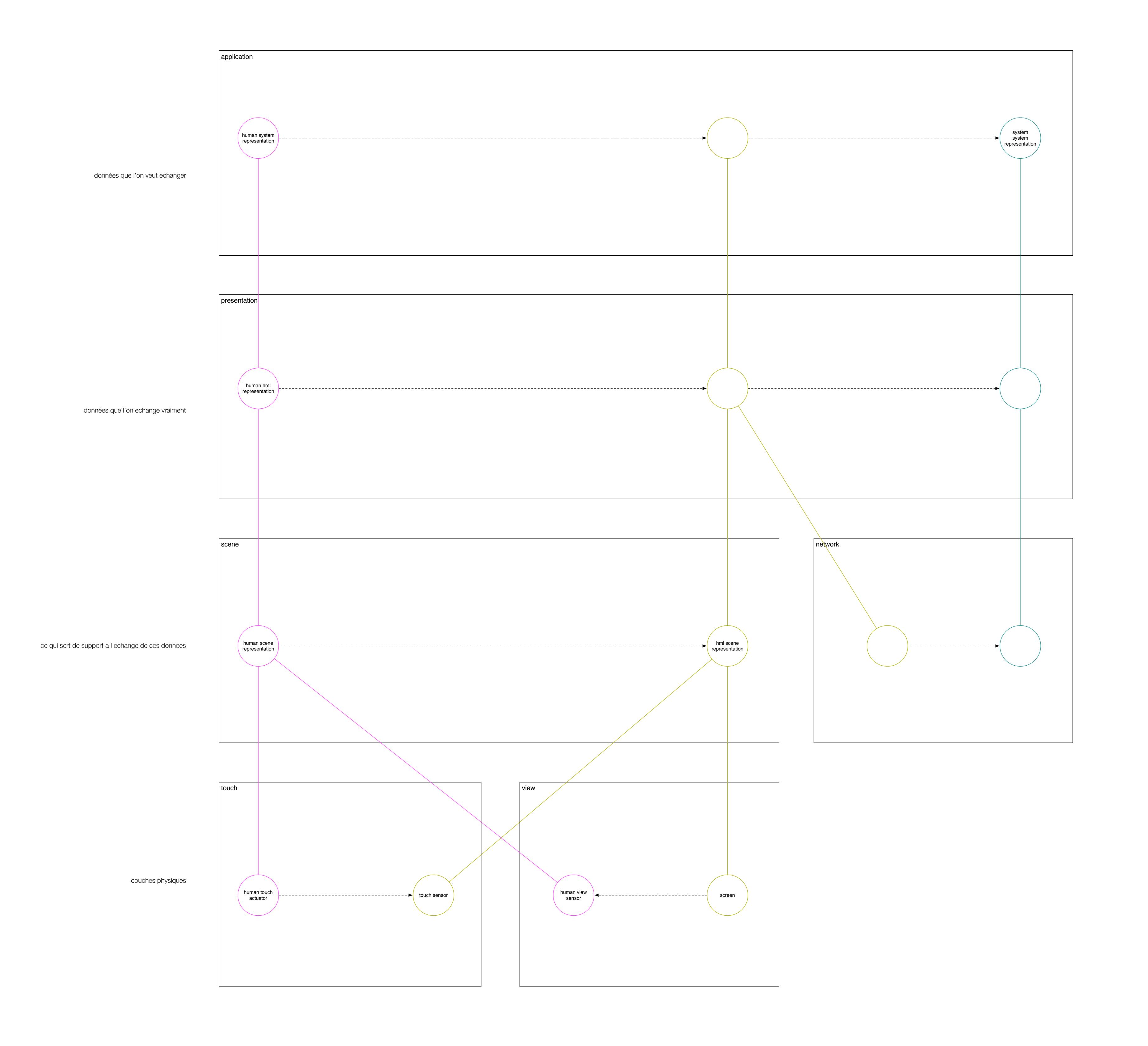
on(init(),
 affect(init,var)
),
on(increment,
 affect(add(pre(var),+1), temp)
),
on(decrement,
 affect(add(pre(var),-1), temp)
),
ensureIsInRange(0,100,temp,var)

on(decrement, affect(add(pre(var),-1), temp)

ensureIsInRange(0,100,temp,var)

ensureIsInRange::behavior(min::reception, max::reception, temp::reception, var::emission) :=
 affect(max(min, min(max, temp)), var)

speedcontroller:continuous:{
 driver:continuous:{
 actualspeed:continuous:number:in,
 desiredspeed:continuous:number:out,
 increment:discrete:void:in,
 decrement:discrete:void:in,
 toggle:discrete:void:in,

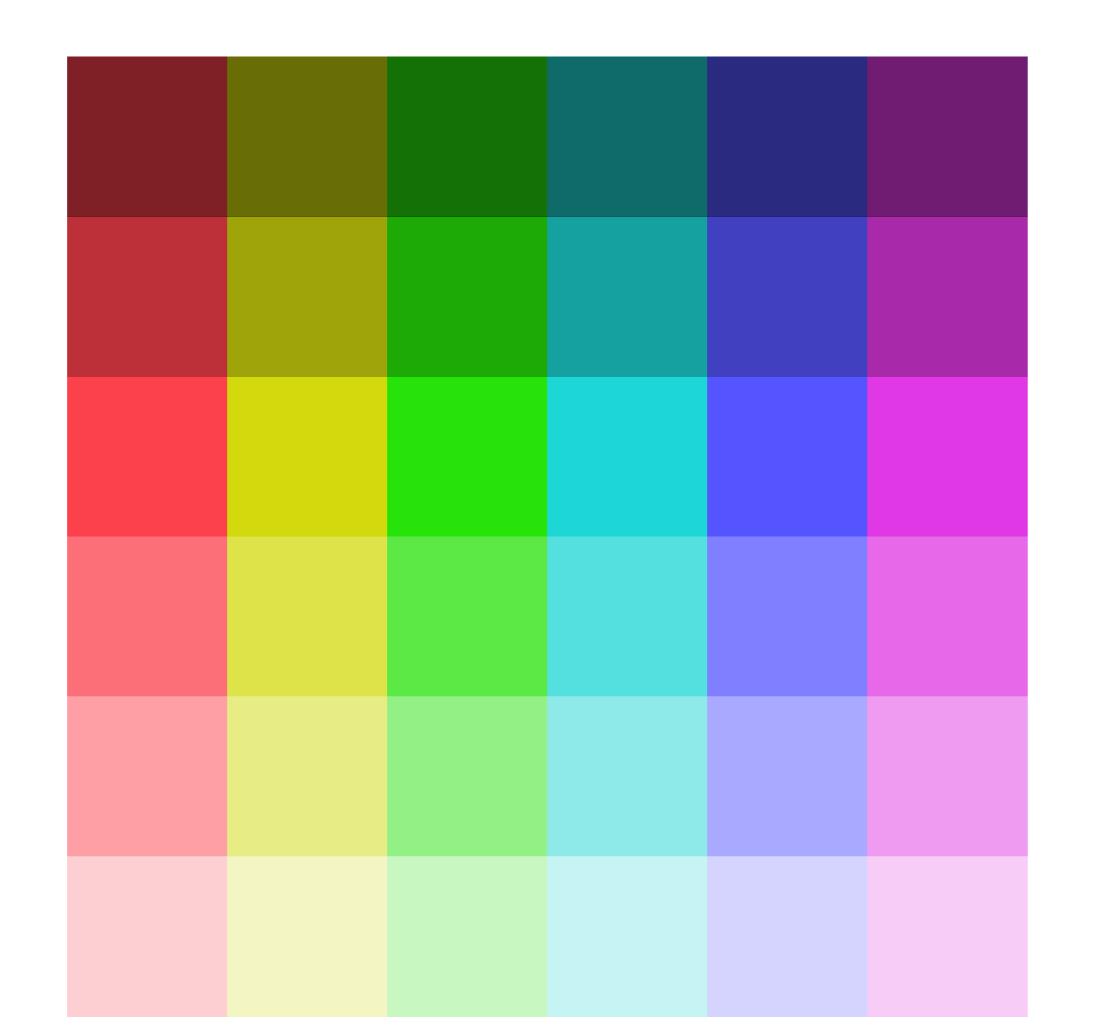


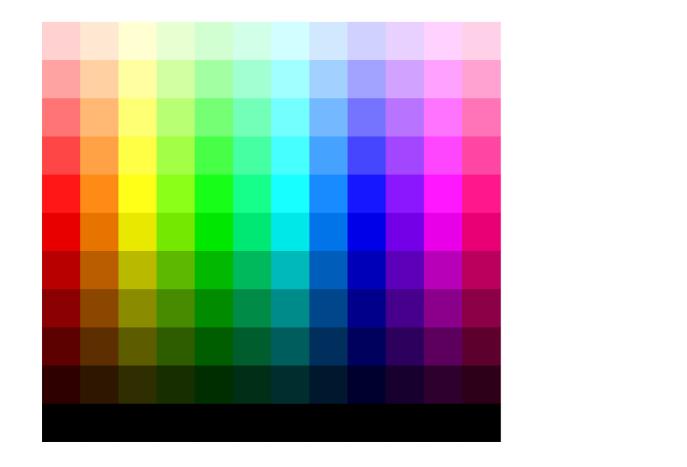
behavior:

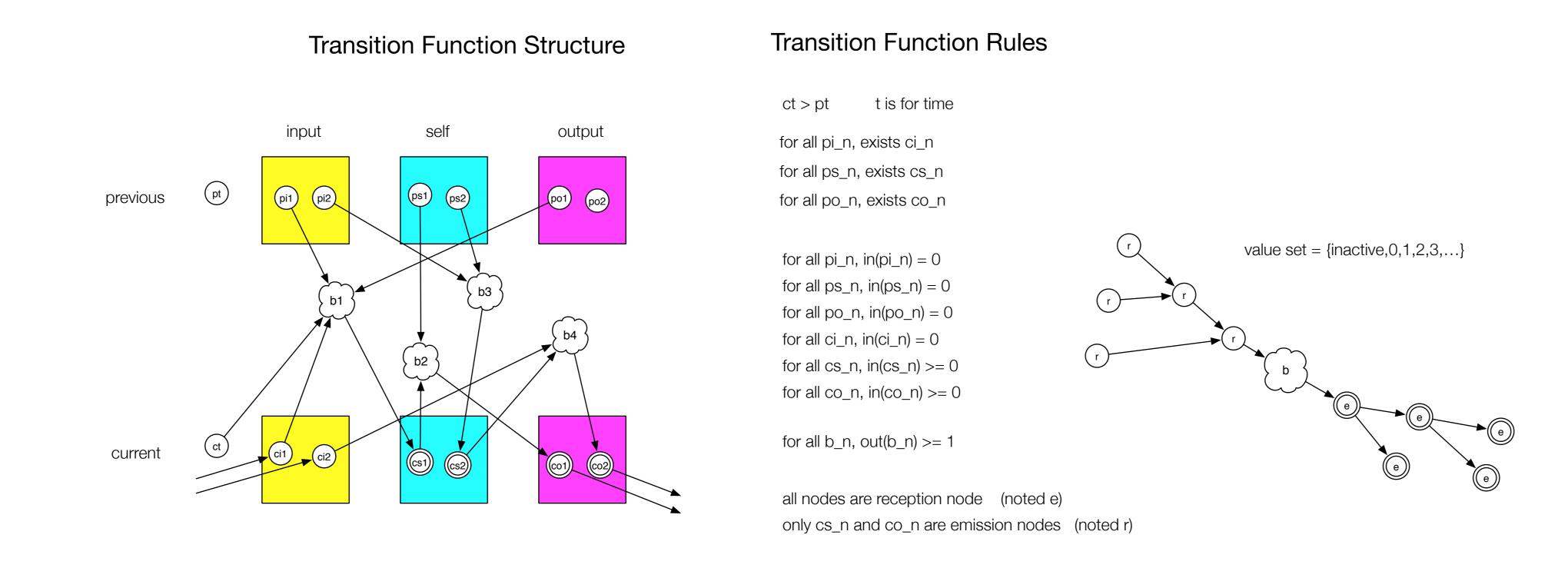
```
affect(reception,emission)
on(reception,behavior)
always(behavior)
and(behavior,...,behavior)
or(behavior,...,behavior)
```

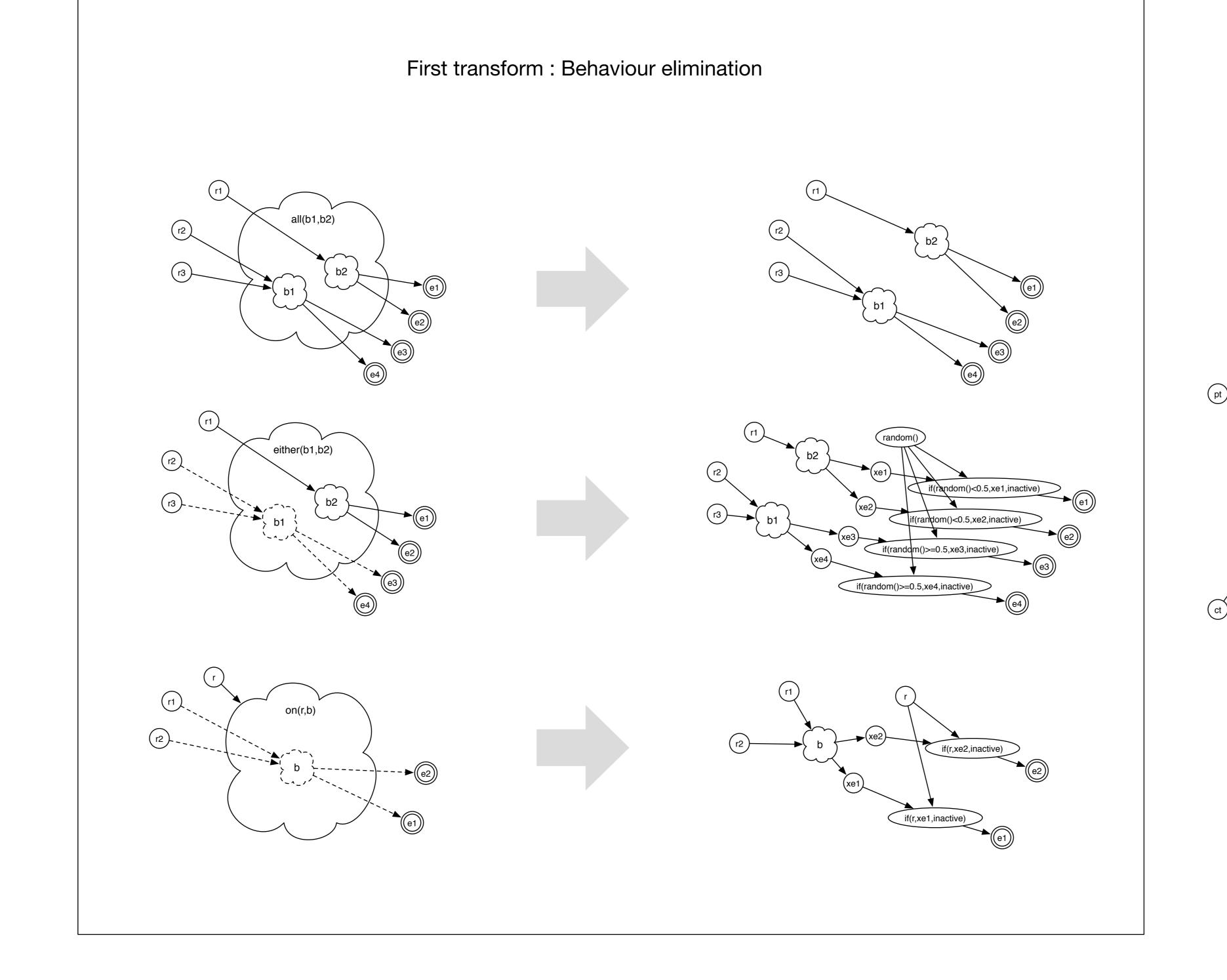
```
on(a,
on(b,
c = d
)
on(e,
on(f,
c = g
)
```

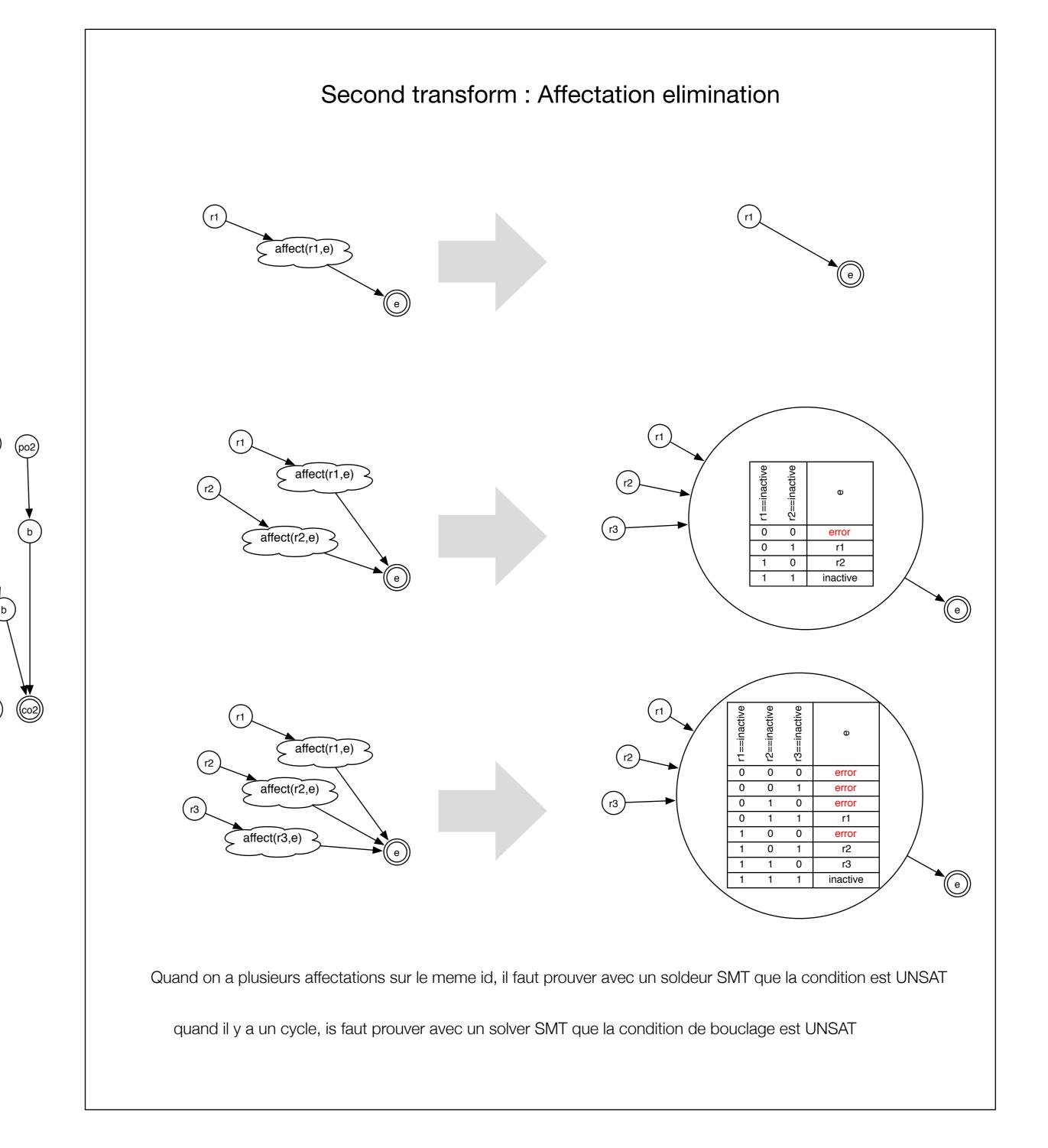
```
if((a&&b)&&not(e&&f)),
d,
if(e&&f,
g,
pre(c)
)
```

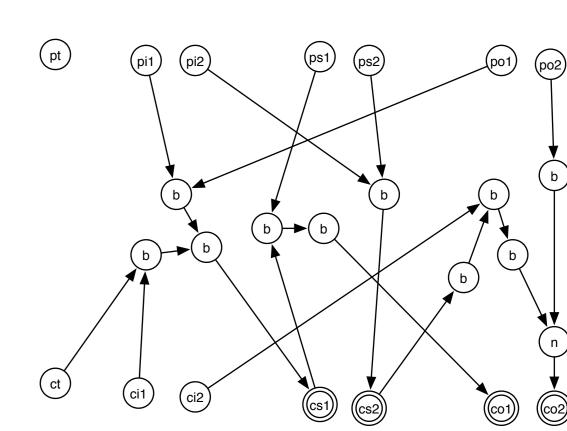


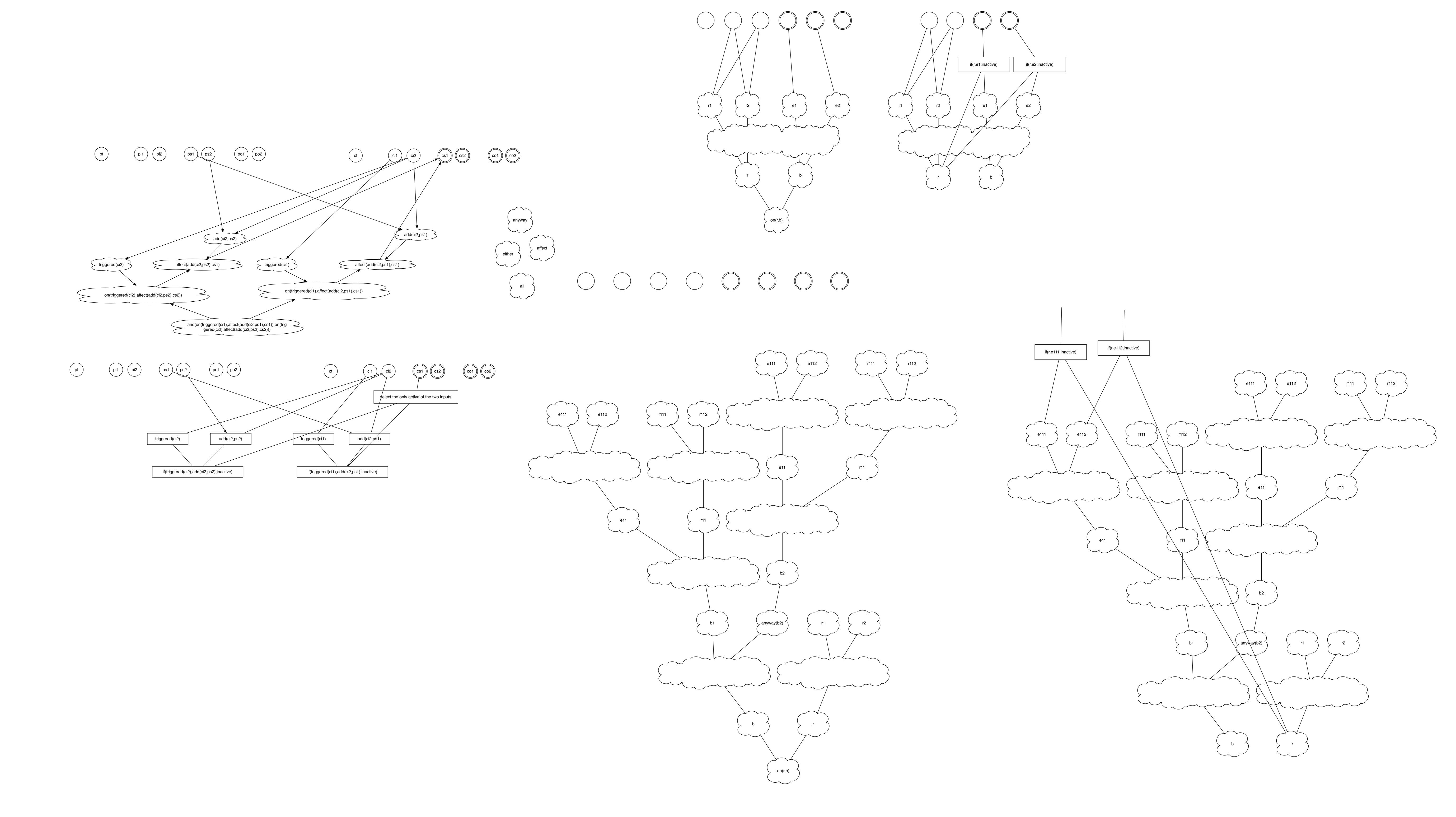


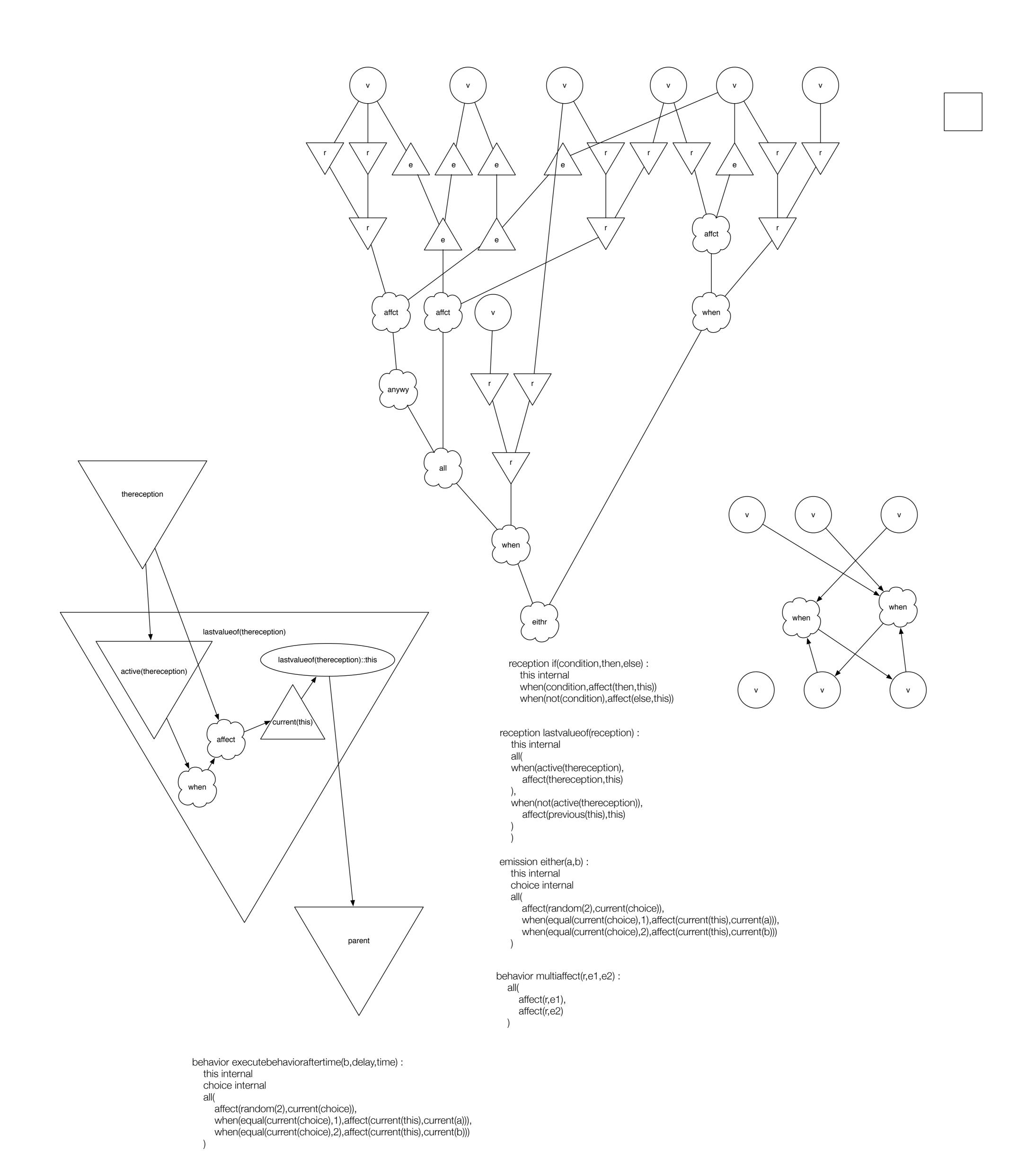


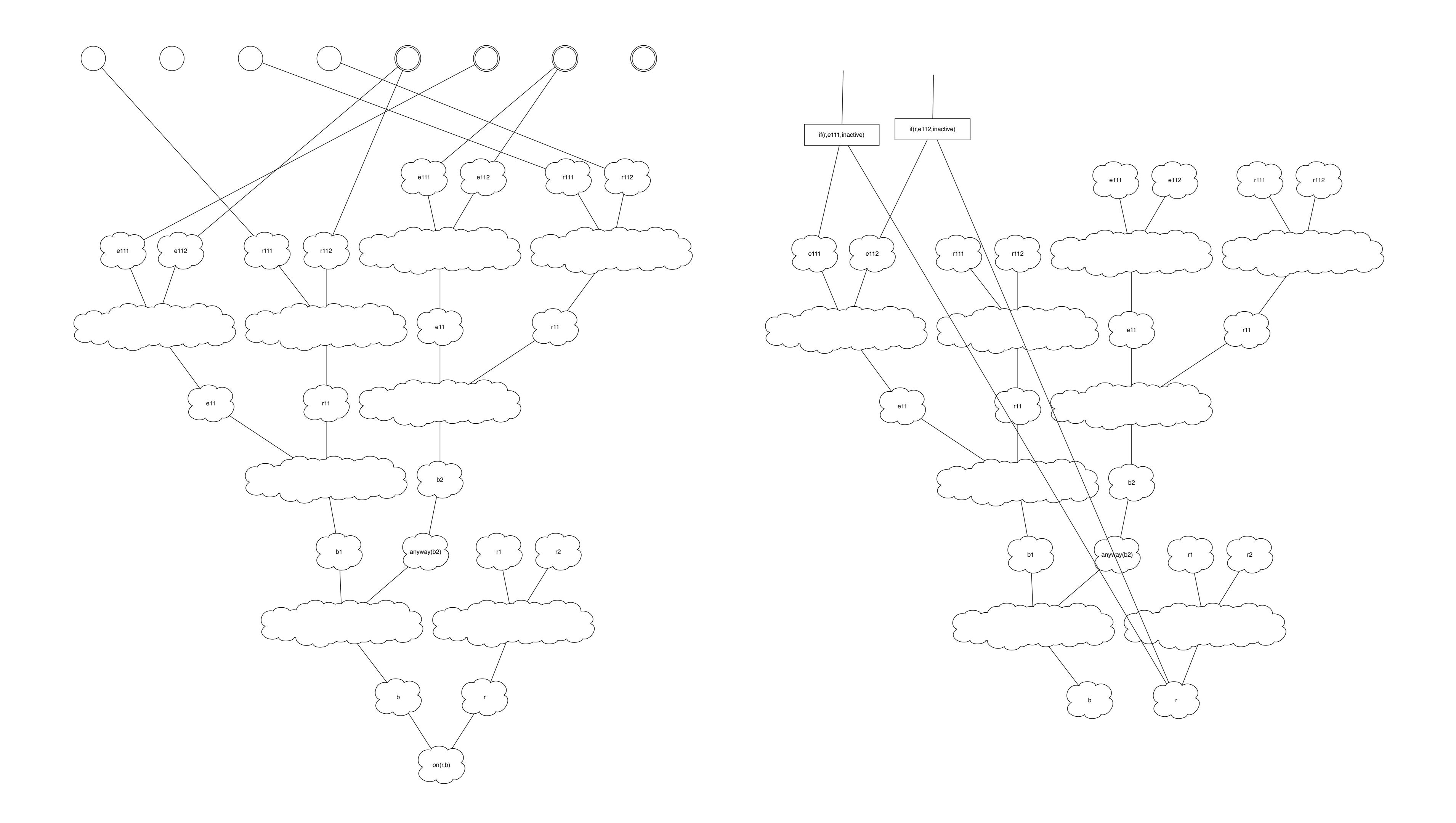










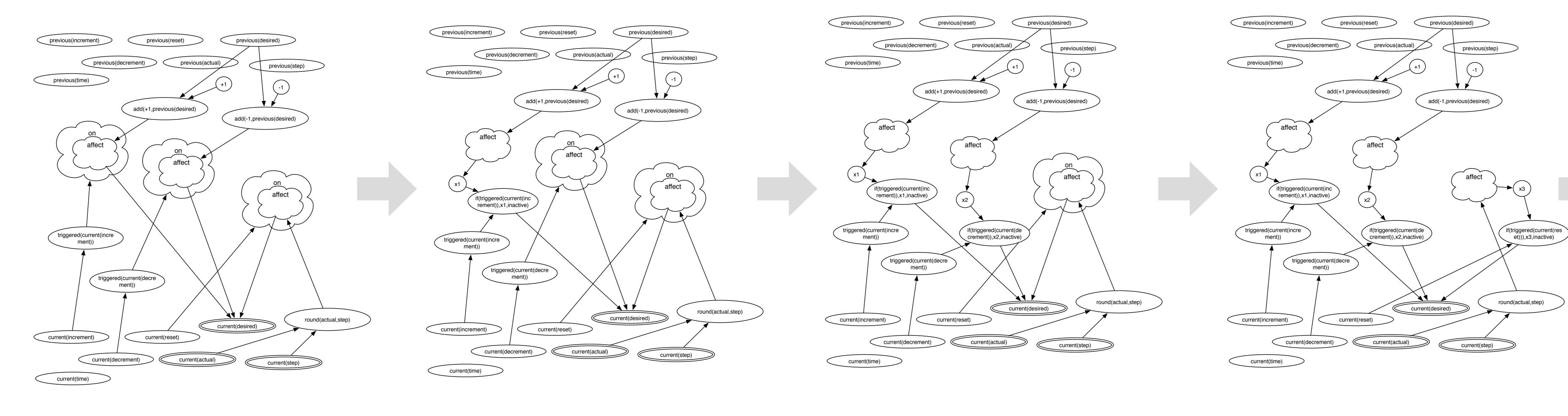


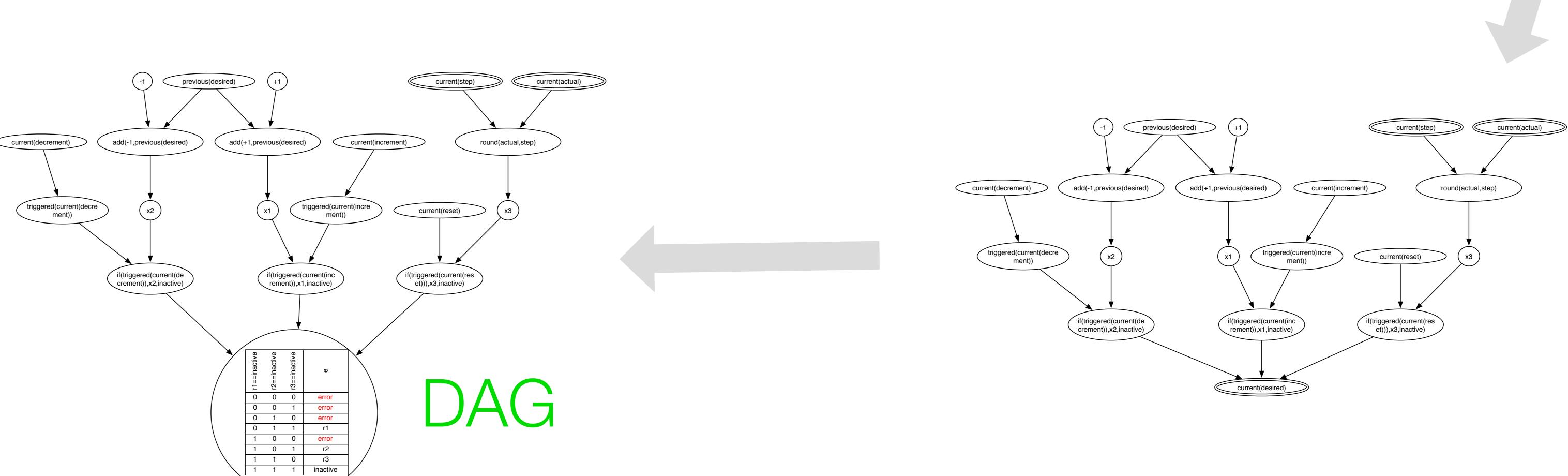
actual output desired output step internal

on(triggered(increment),
 affect(add(+1,previous(desired)),current(desired))

on(triggered(reset),
affect(round(actual,step),desired)







previous(reset)

add(+1,previous(desired)

previous(actual)

if(triggered(current(de crement)),x2,inactive)

add(-1,previous(desired)

round(actual,step)

previous(decrement)

if(triggered(current(inc rement)),x1,inactive)

triggered(current(incre ment))

current(increment)

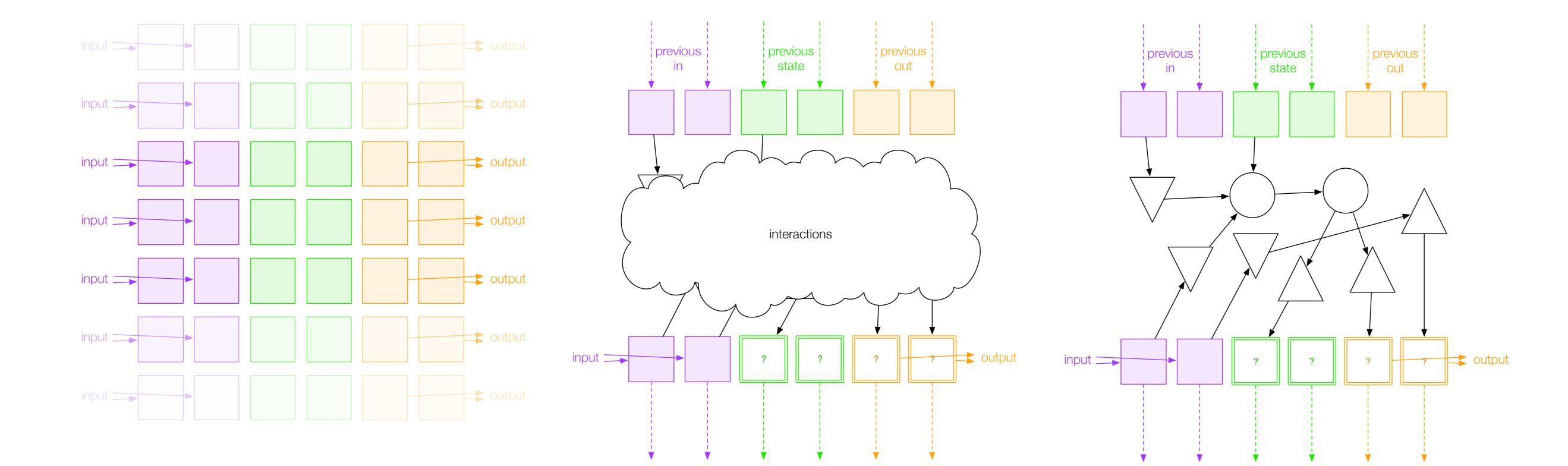
previous(time)

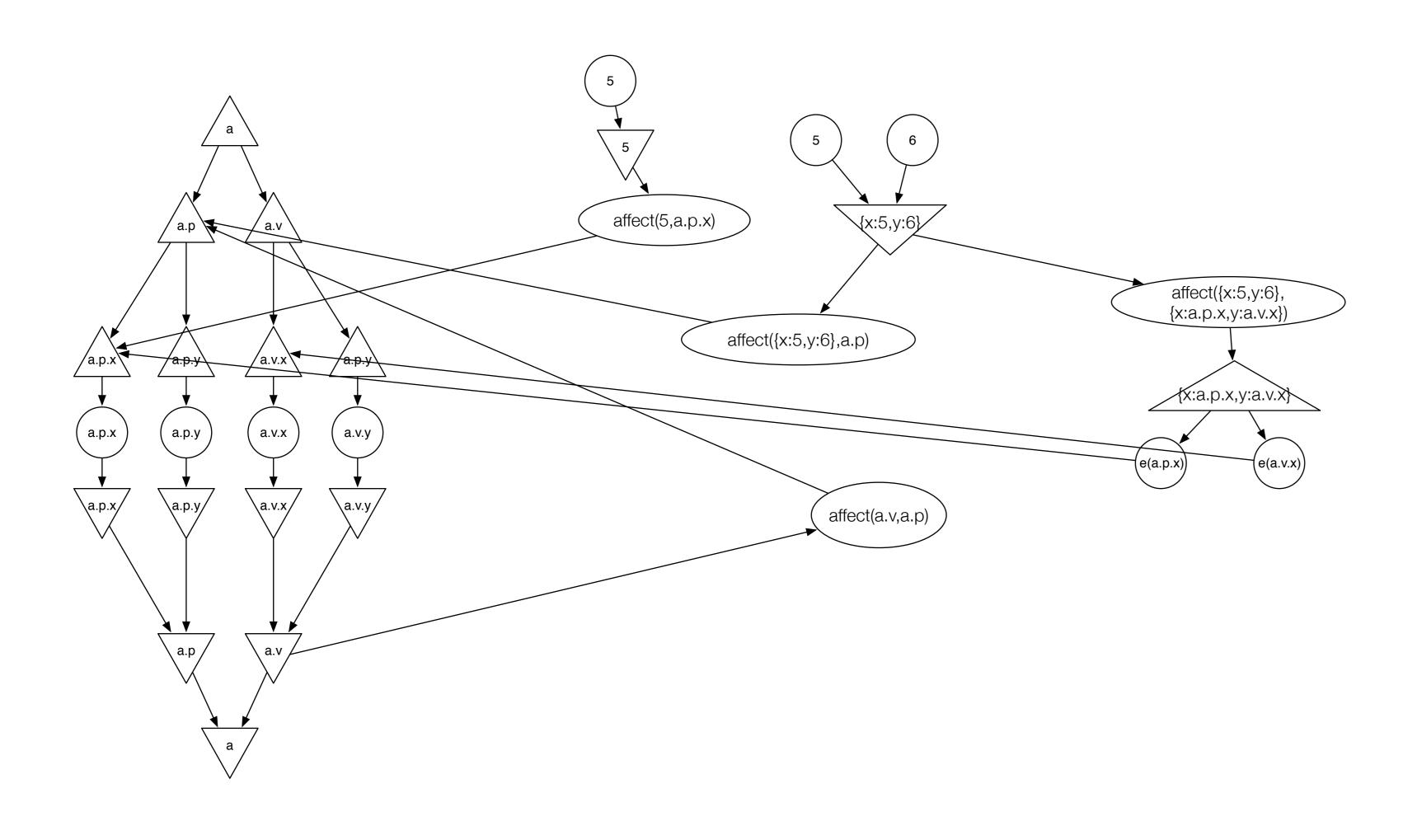
Merge Reception-Emissio-behavior

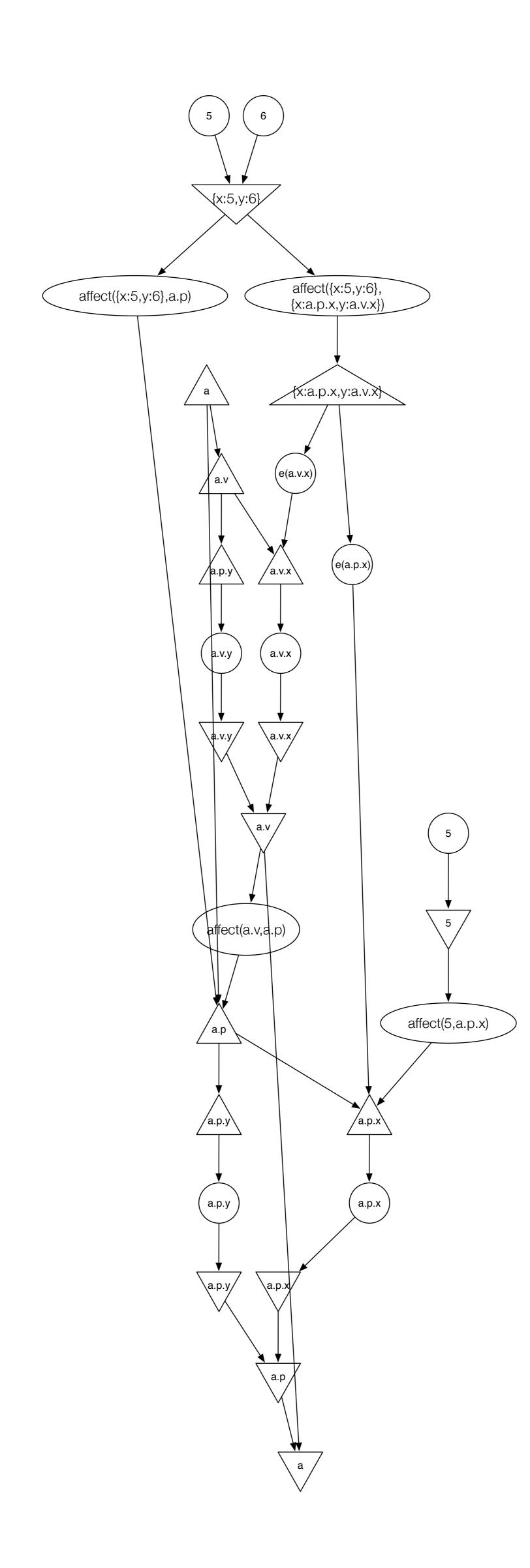
It's all the same thing finally

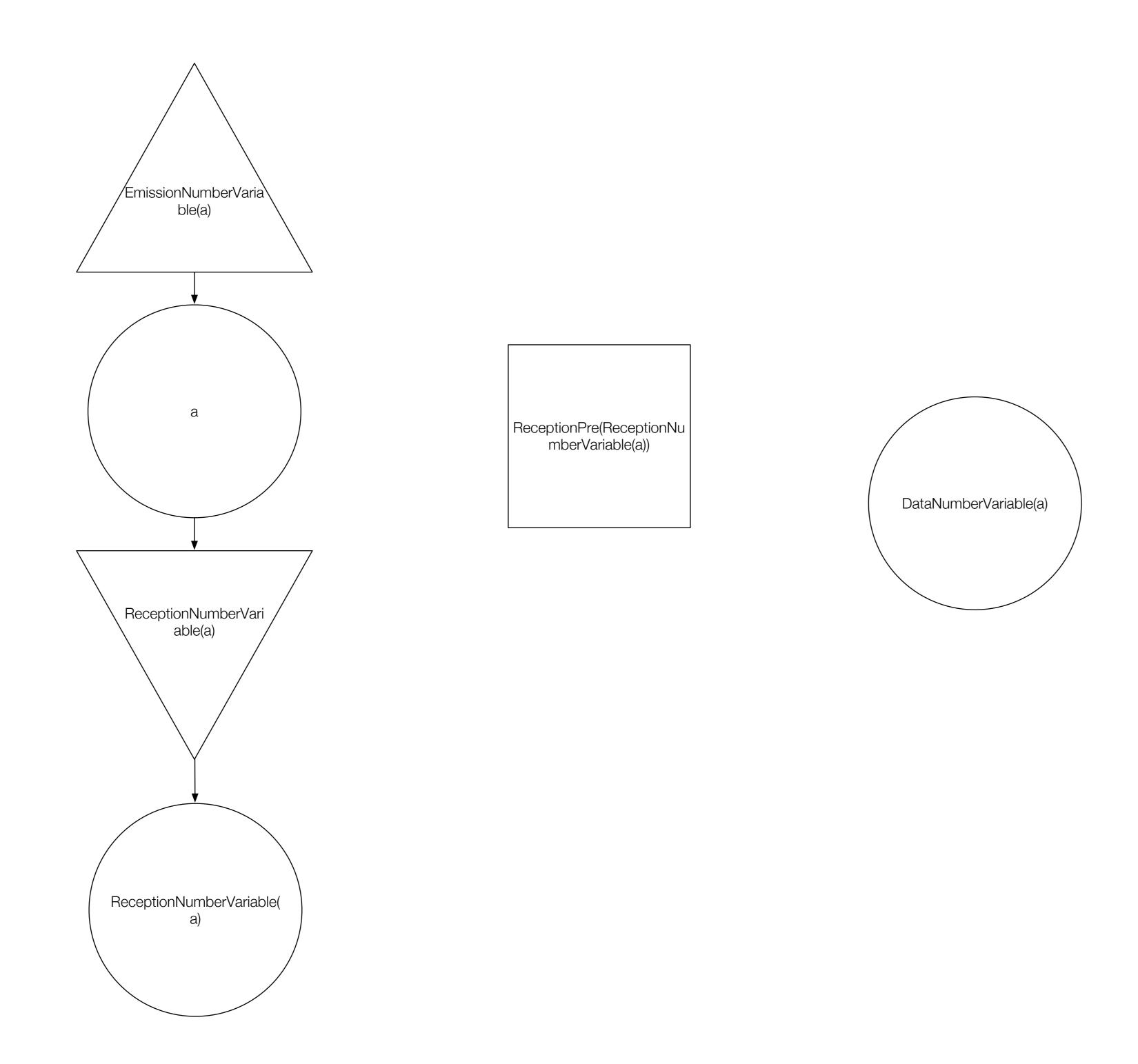
NO, because we could imagine receptions with side effects for example.

AND this would be wrong, because a reception with a side effect is misleading

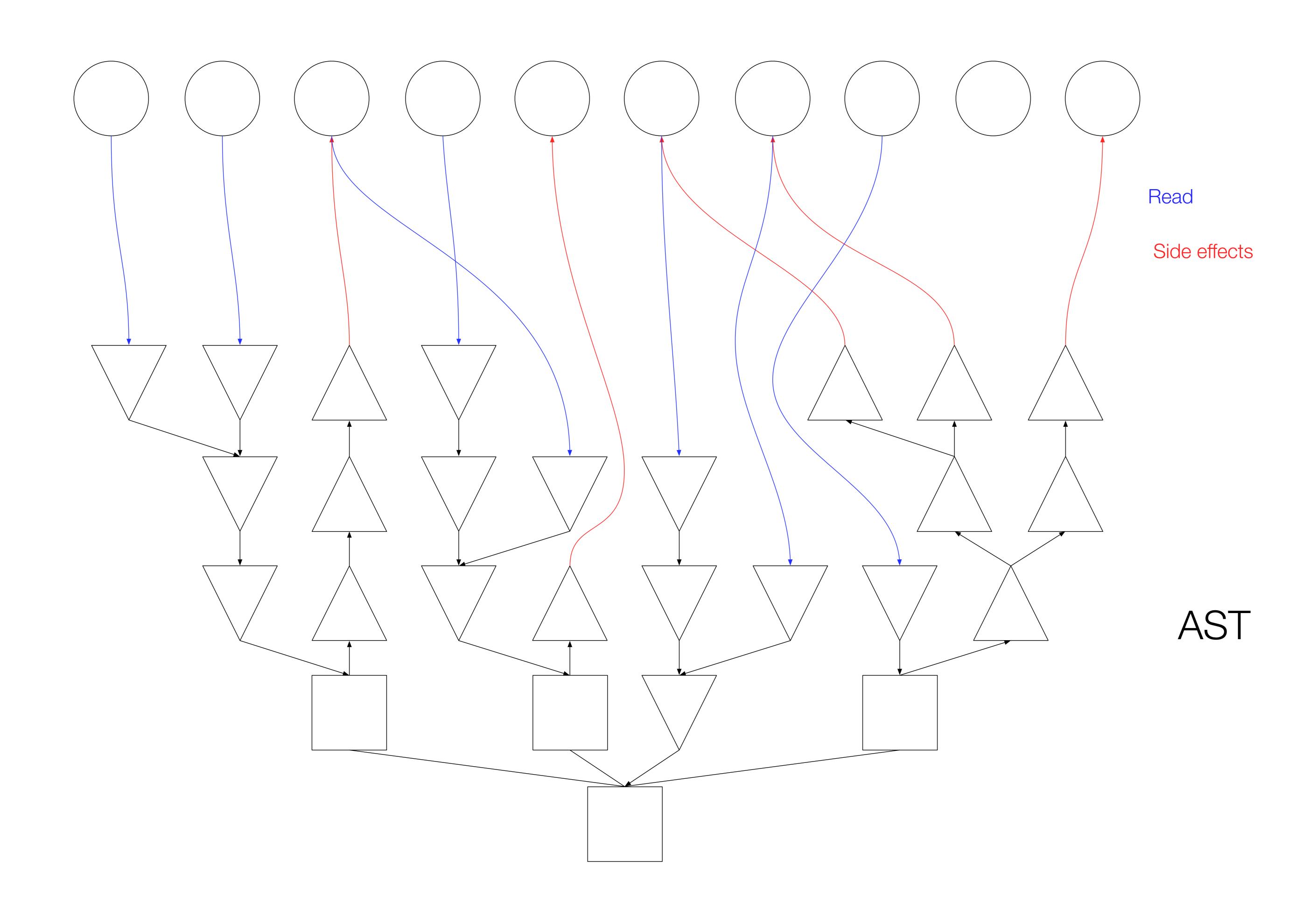




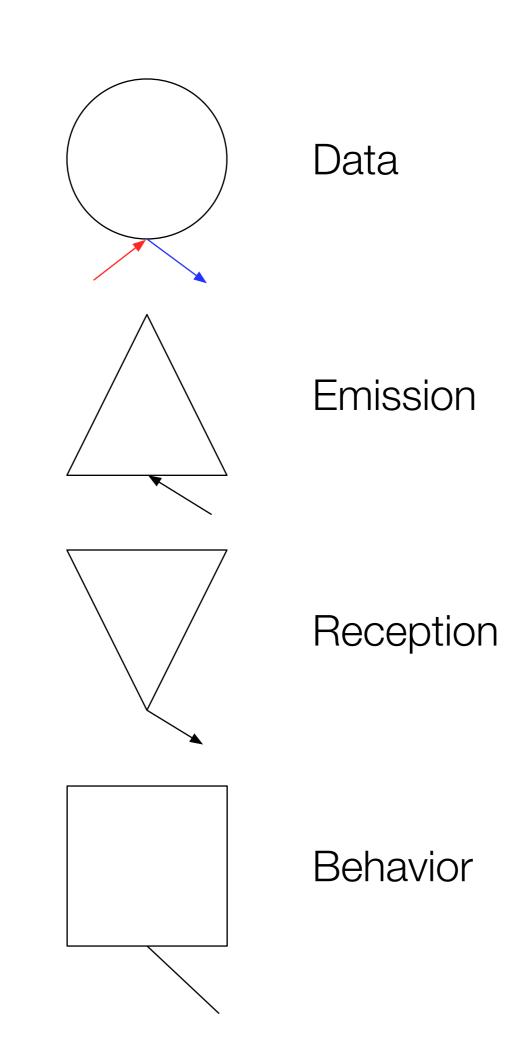


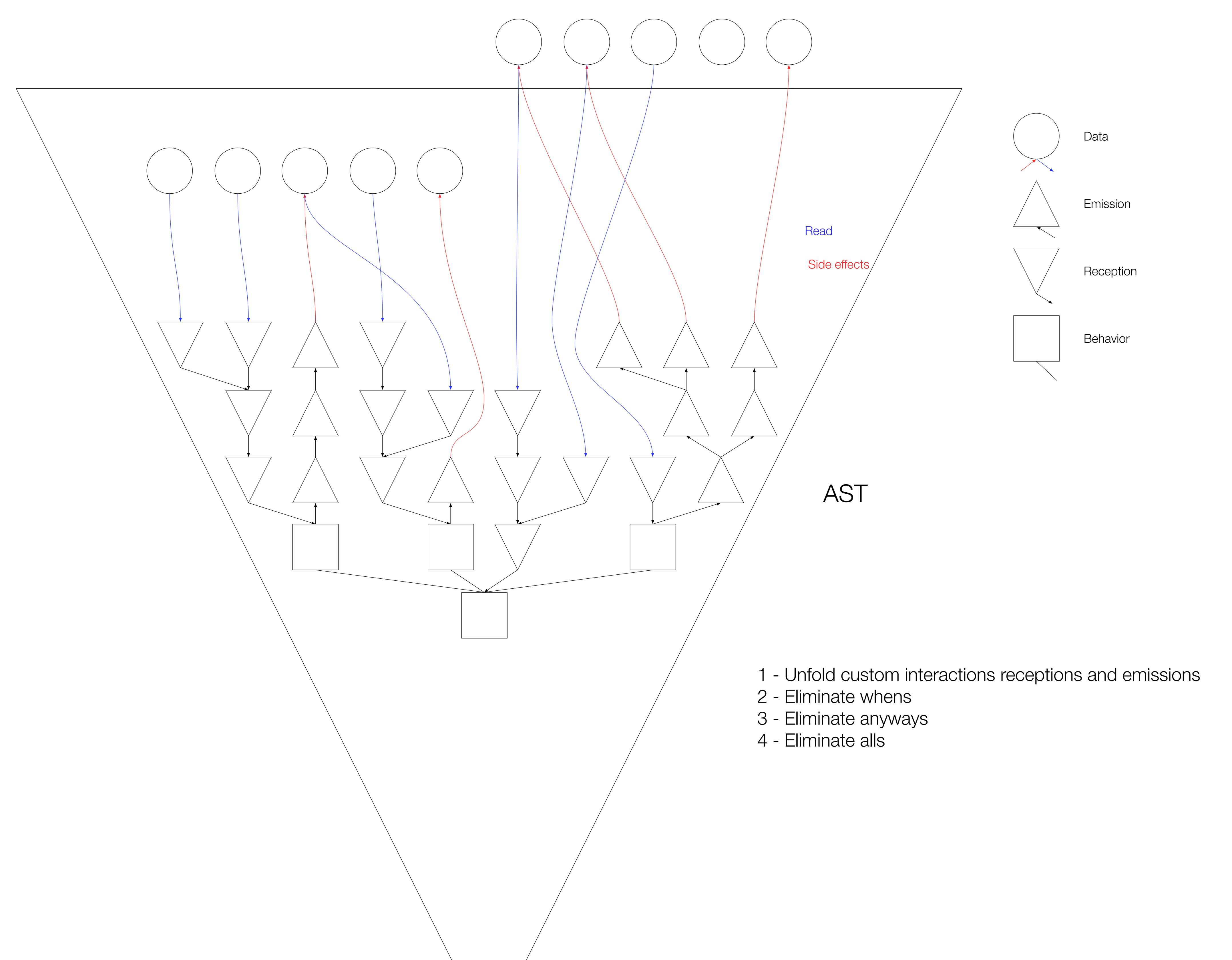


Data -> iii
Computation -> custom iii receptions
Interaction -> iii



- 1 Unfold custom interactions receptions and emissions
- 2 Eliminate whens
- 3 Eliminate anyways4 Eliminate alls

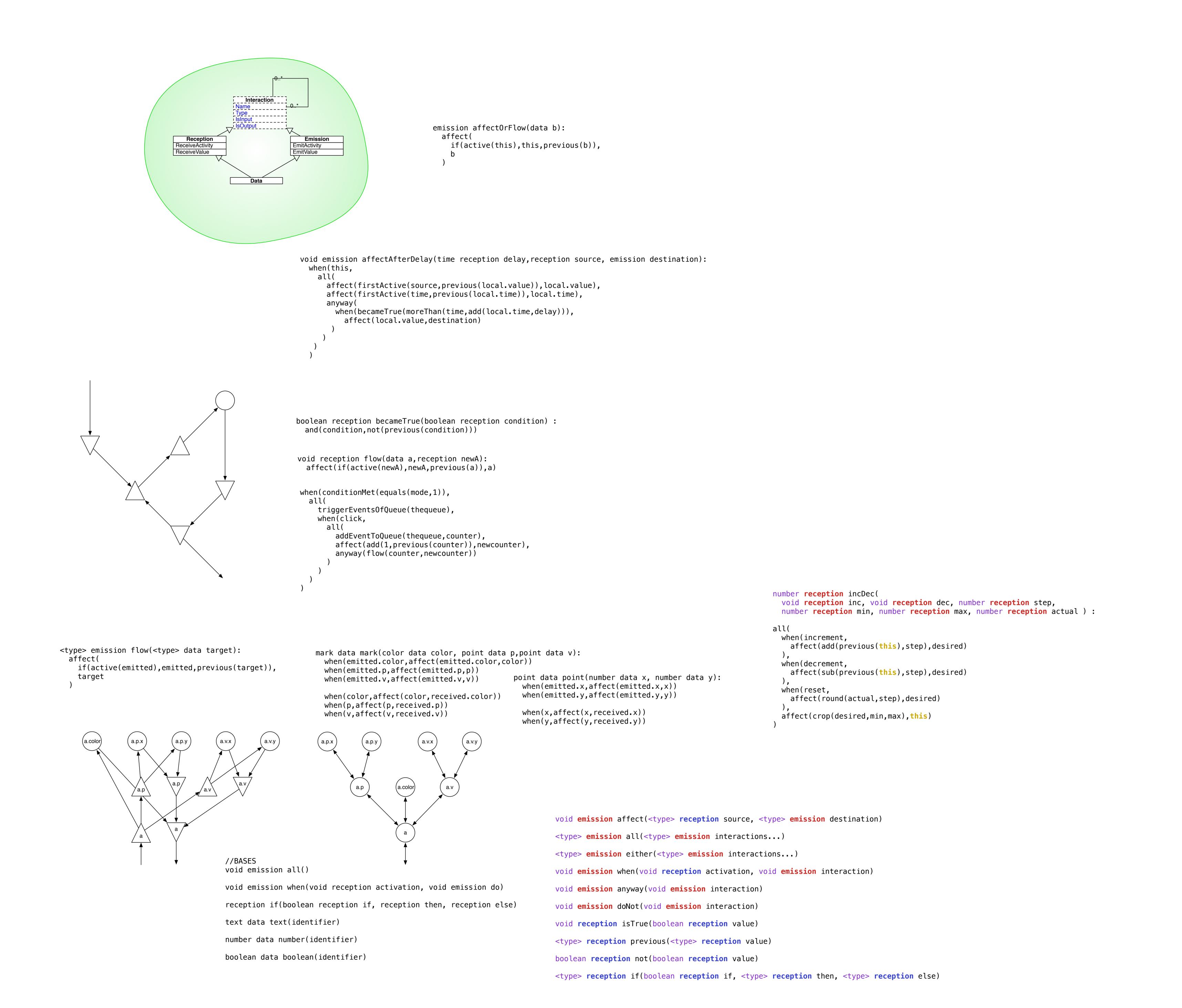


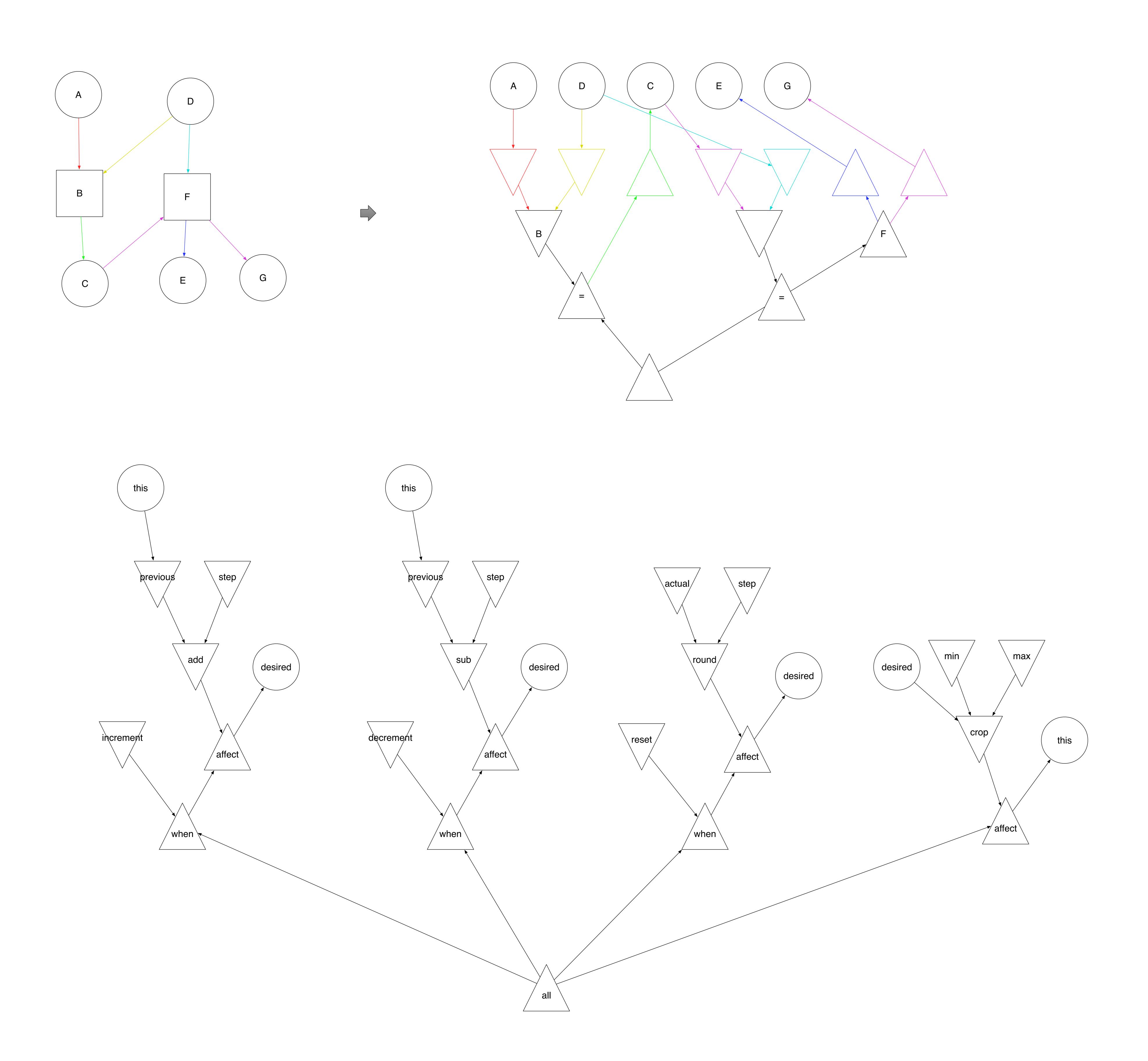


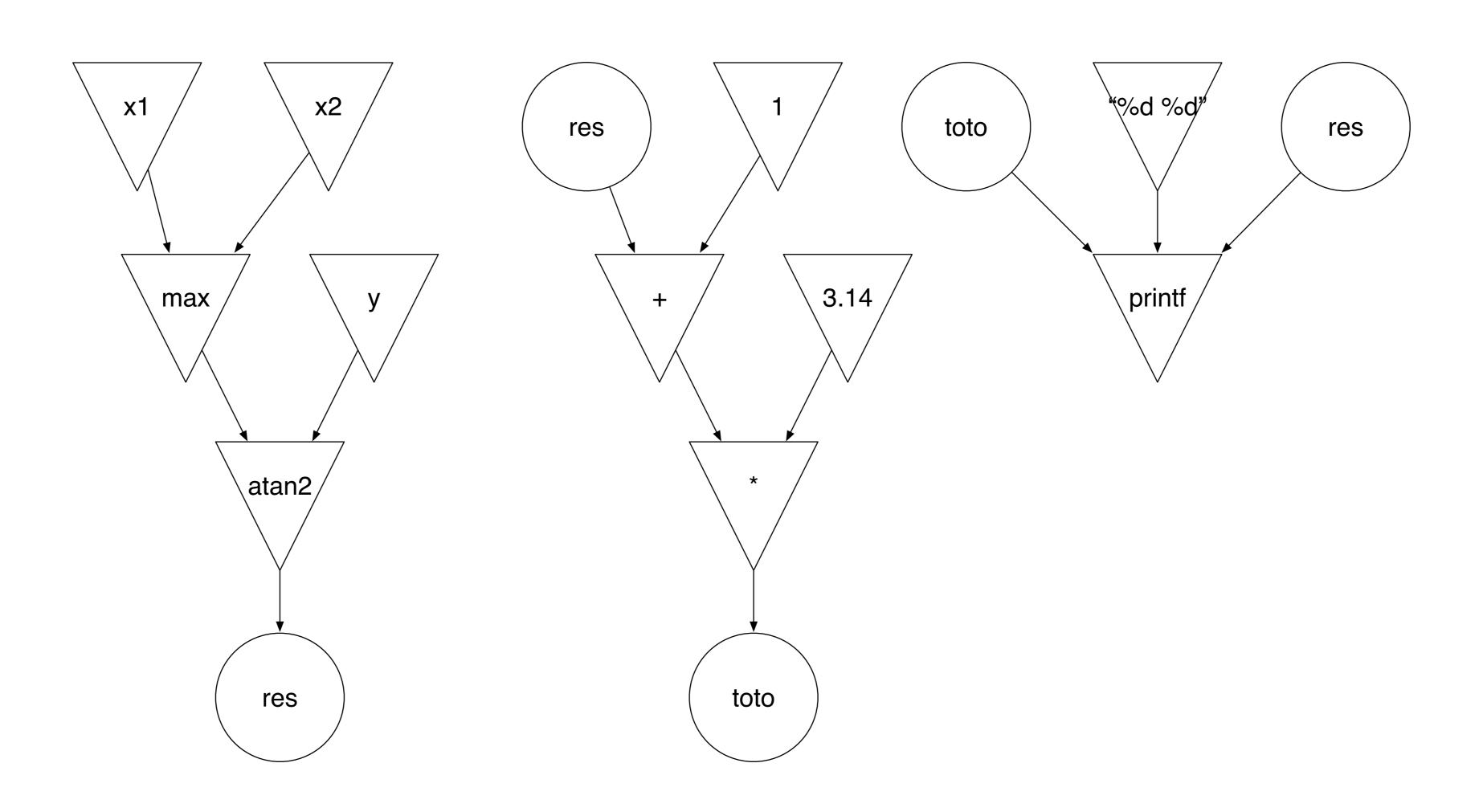
ACTIVE FOR ALL! NOT for the data, but for the actual NODES

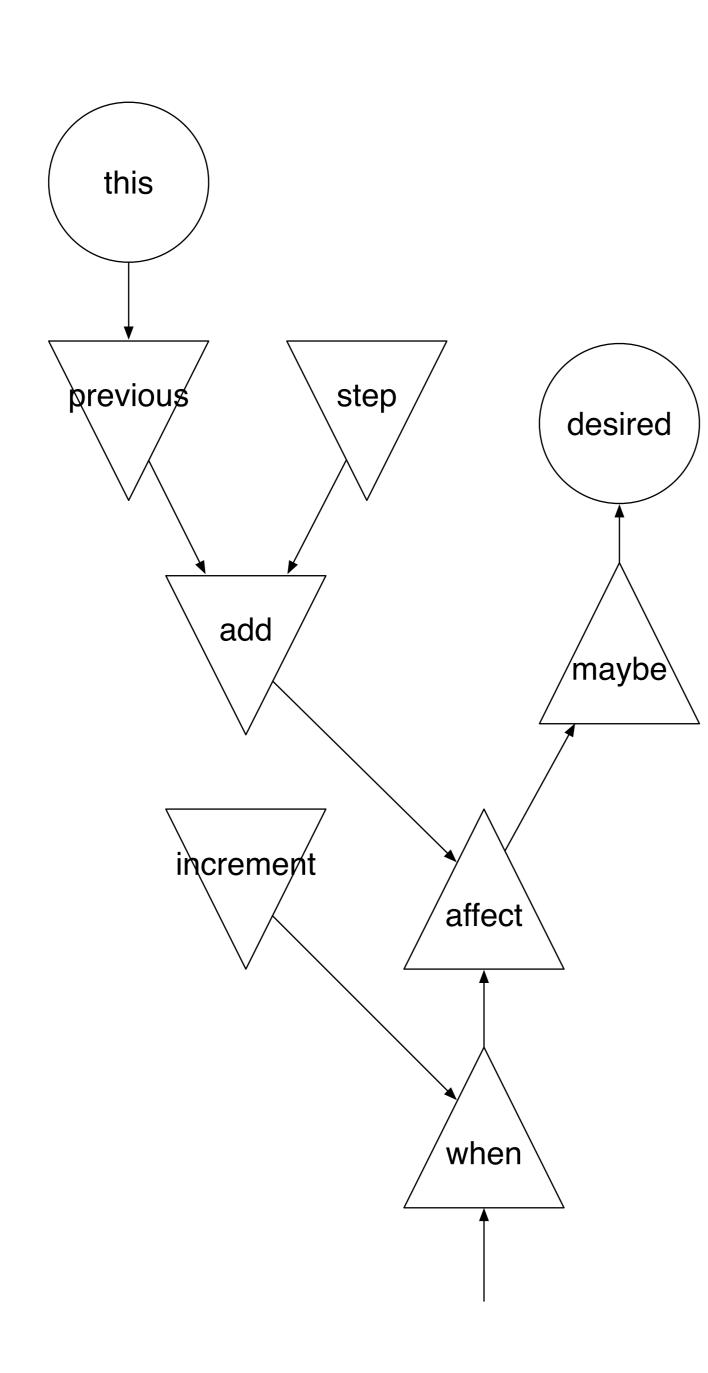
Activity for input = input received Activity for output = we send this output activity for variable = this thing is defined activity for behaviour = execute this now

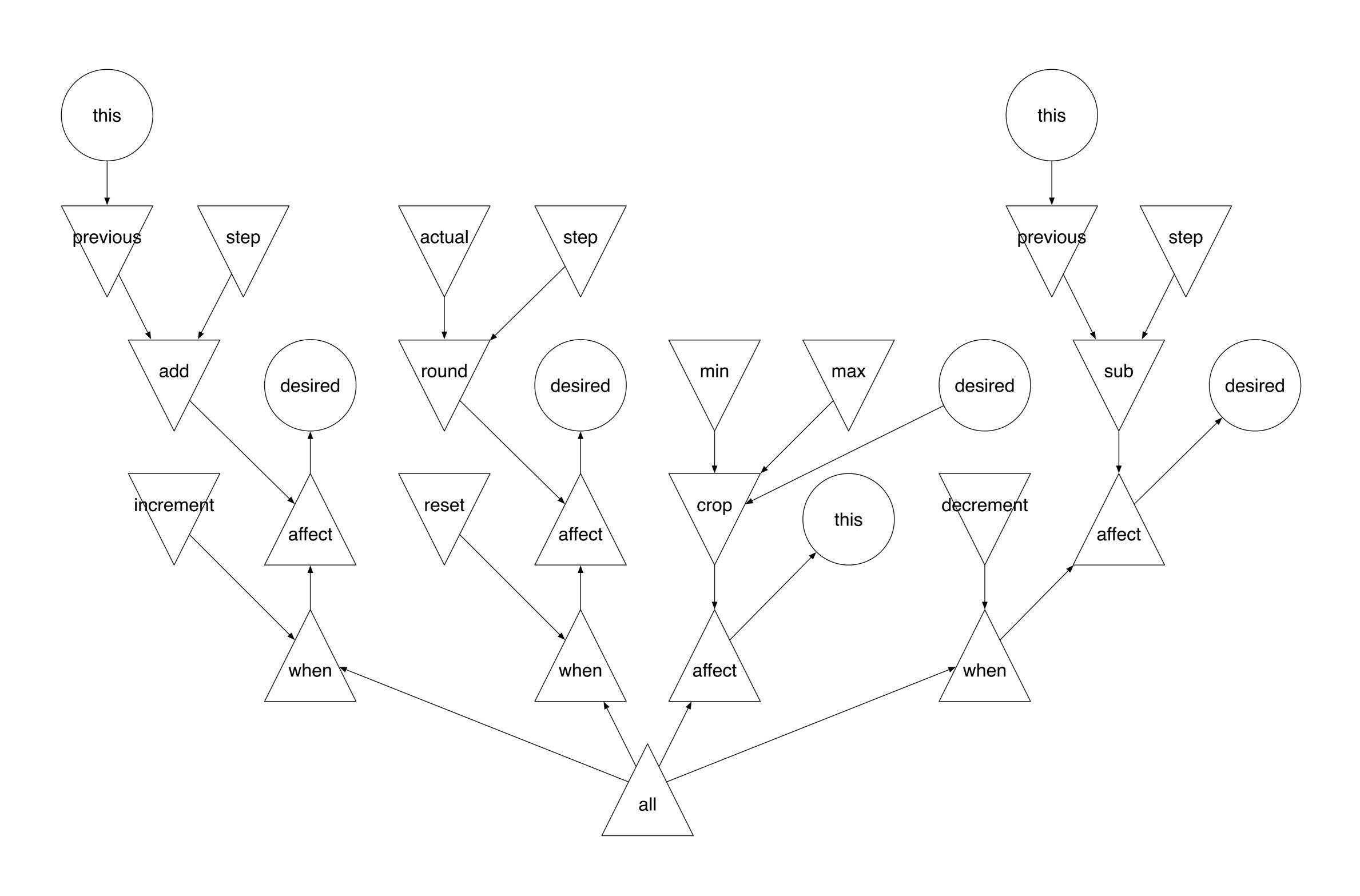
Unified into node activity

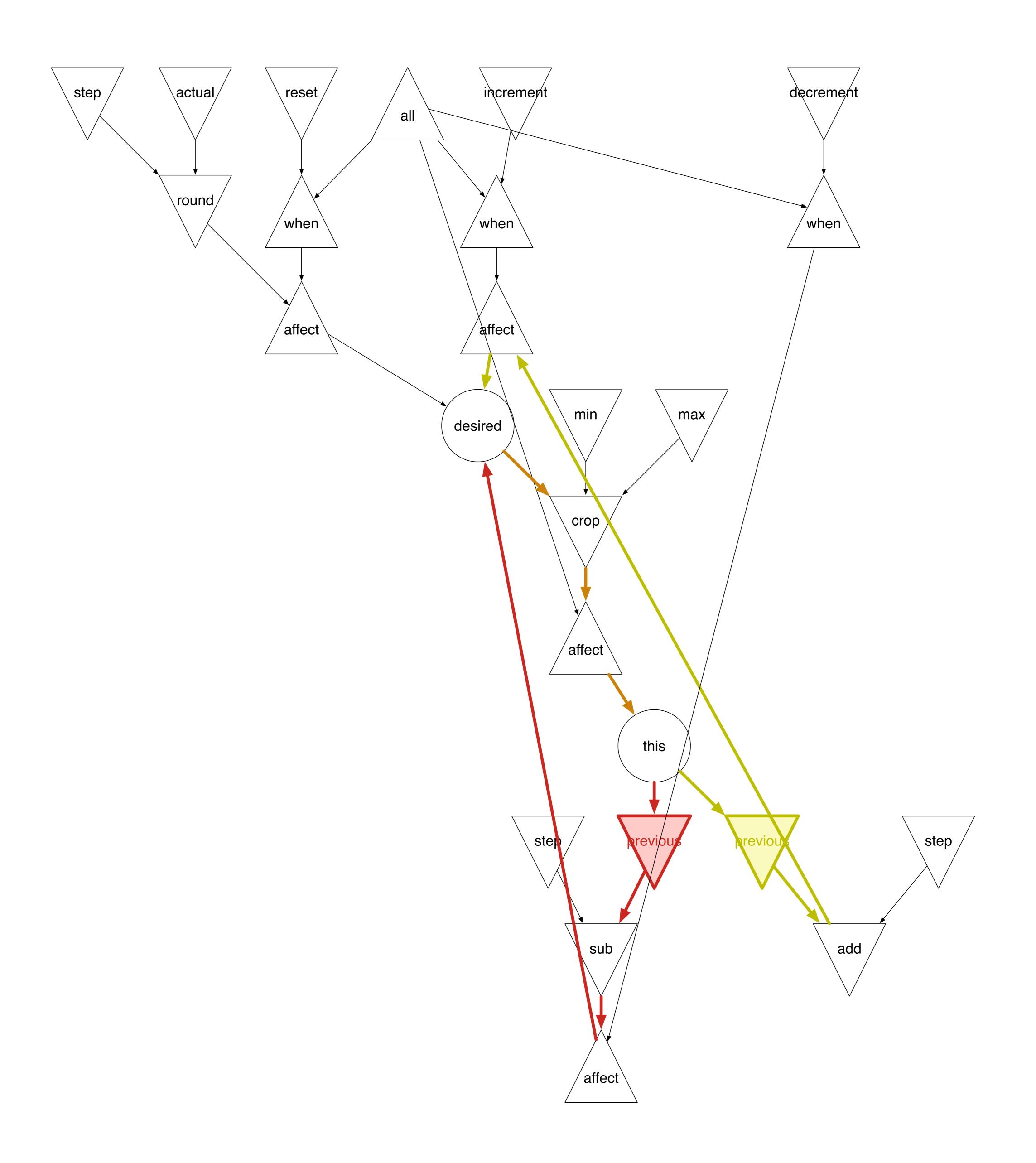


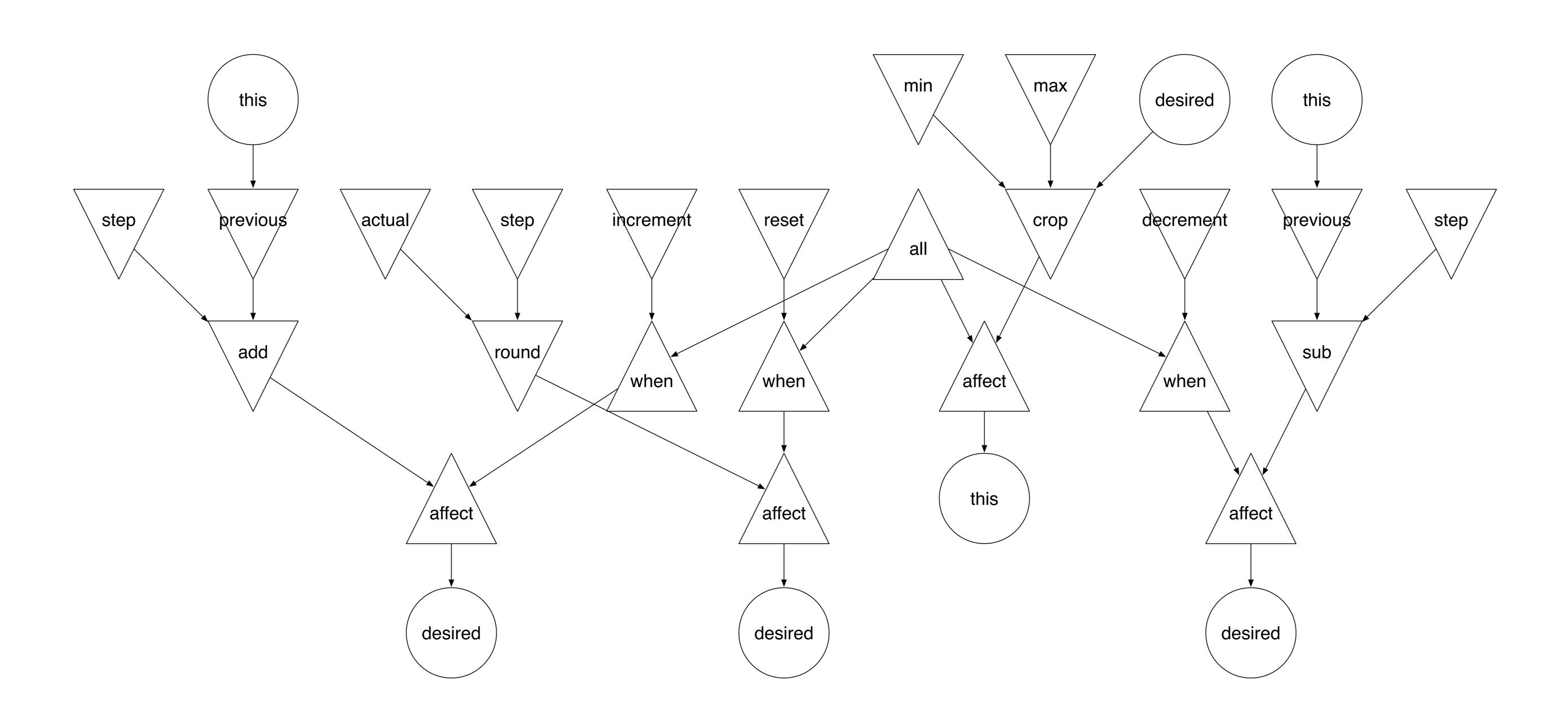


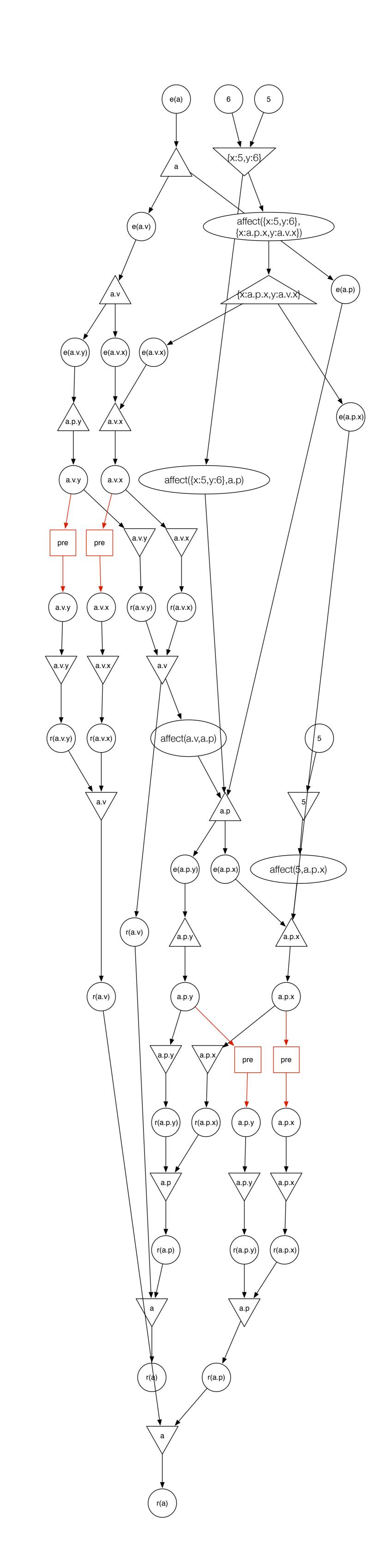


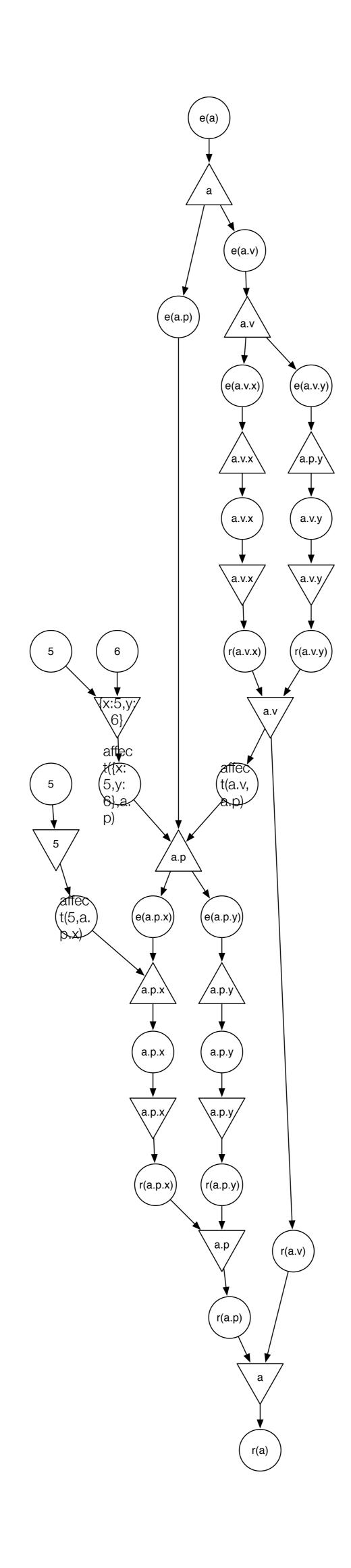






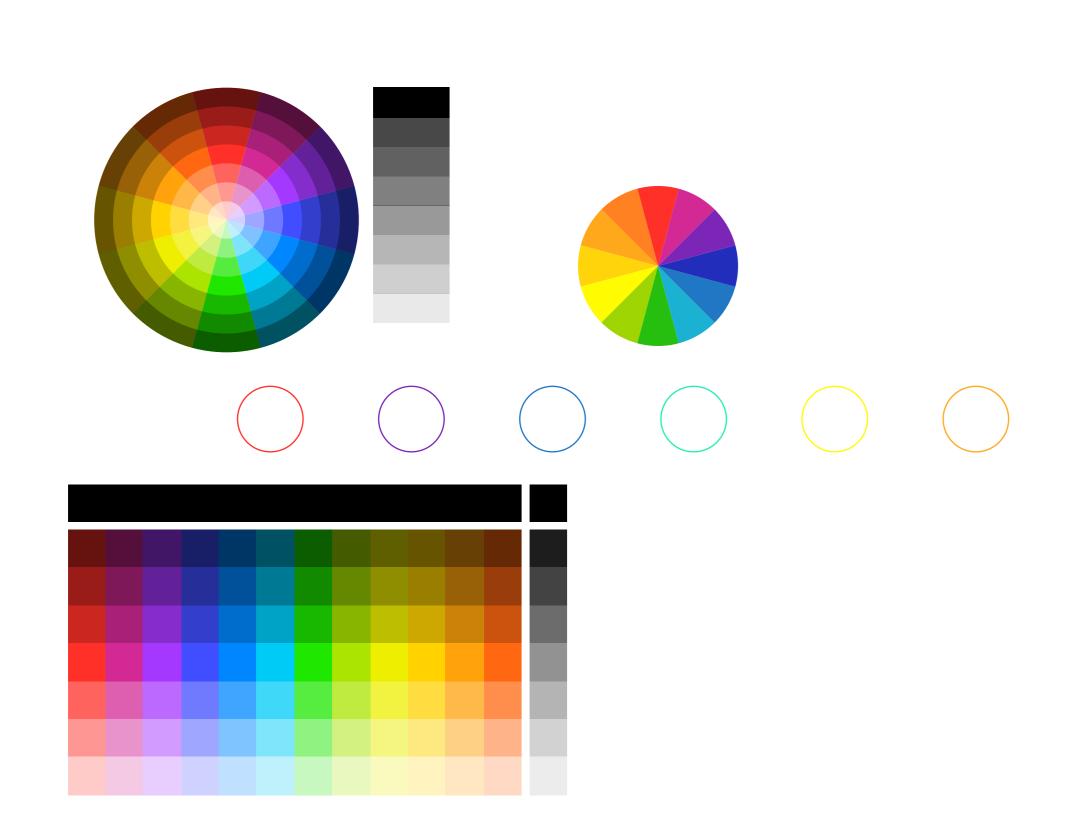






Pathologic

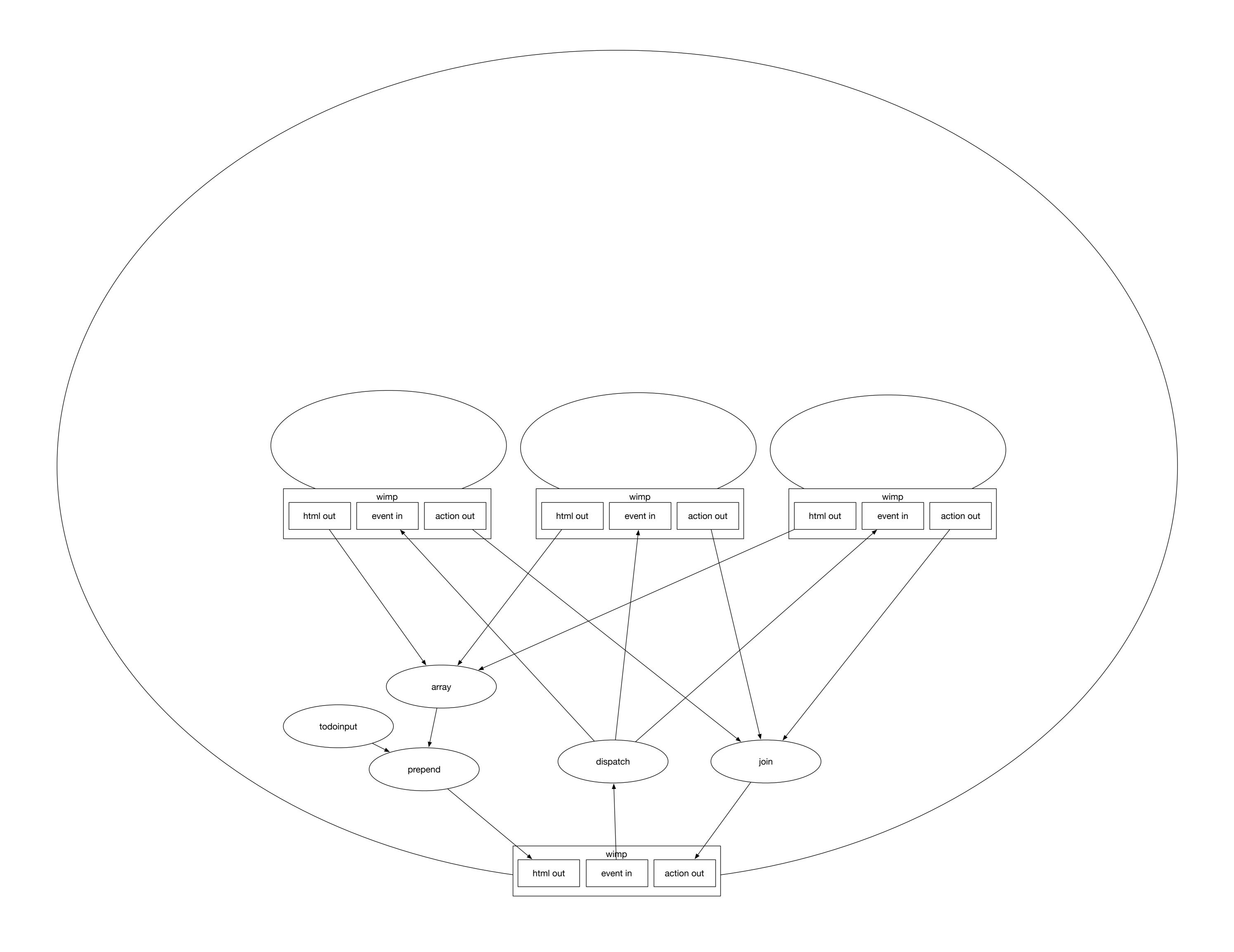






Multiple dispatch

Functional Reactive Programming



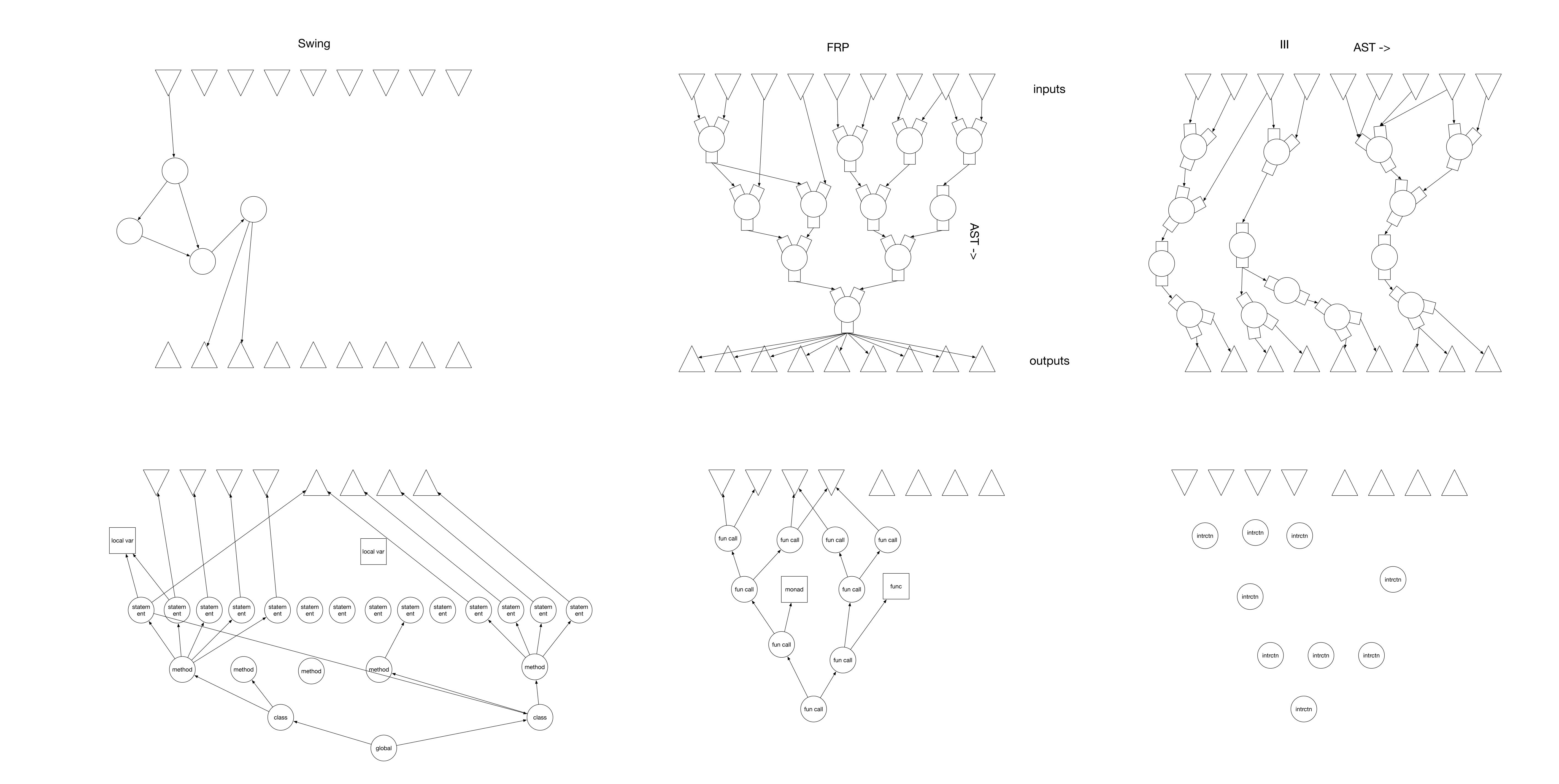
Position philosophique

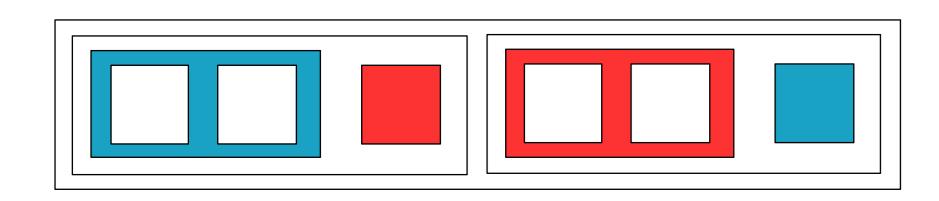
Symétrie avec previous et next

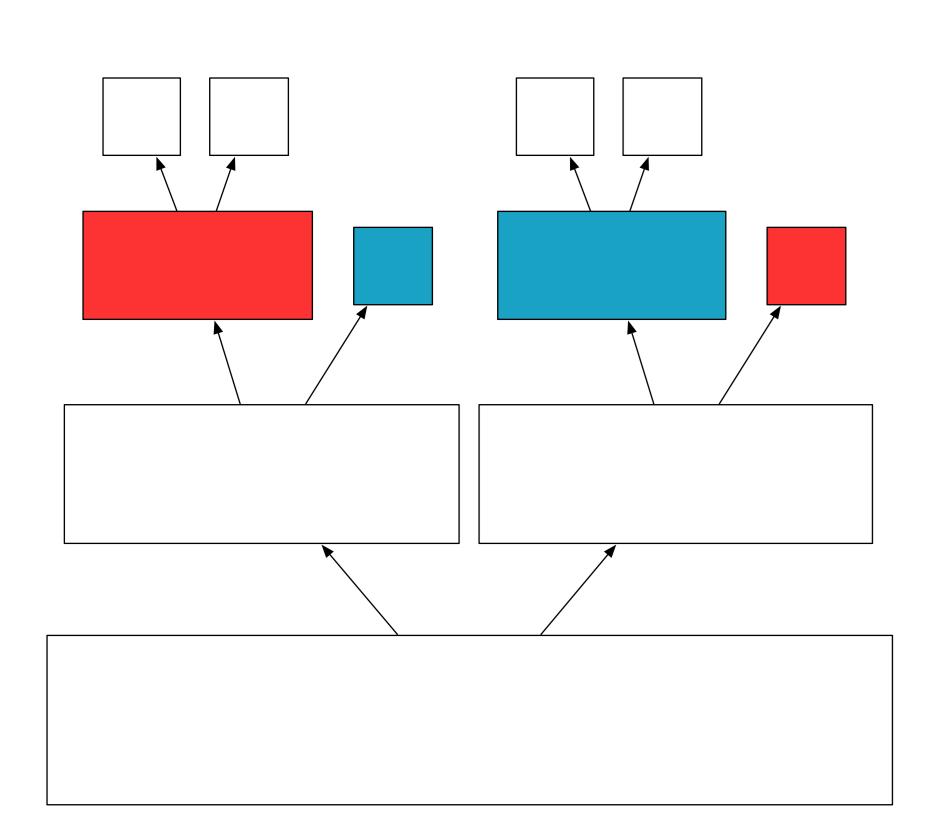
Ou

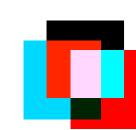
Asymétrie du temps avec seulement previous

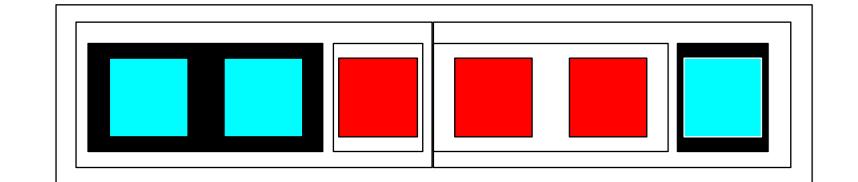
)——(

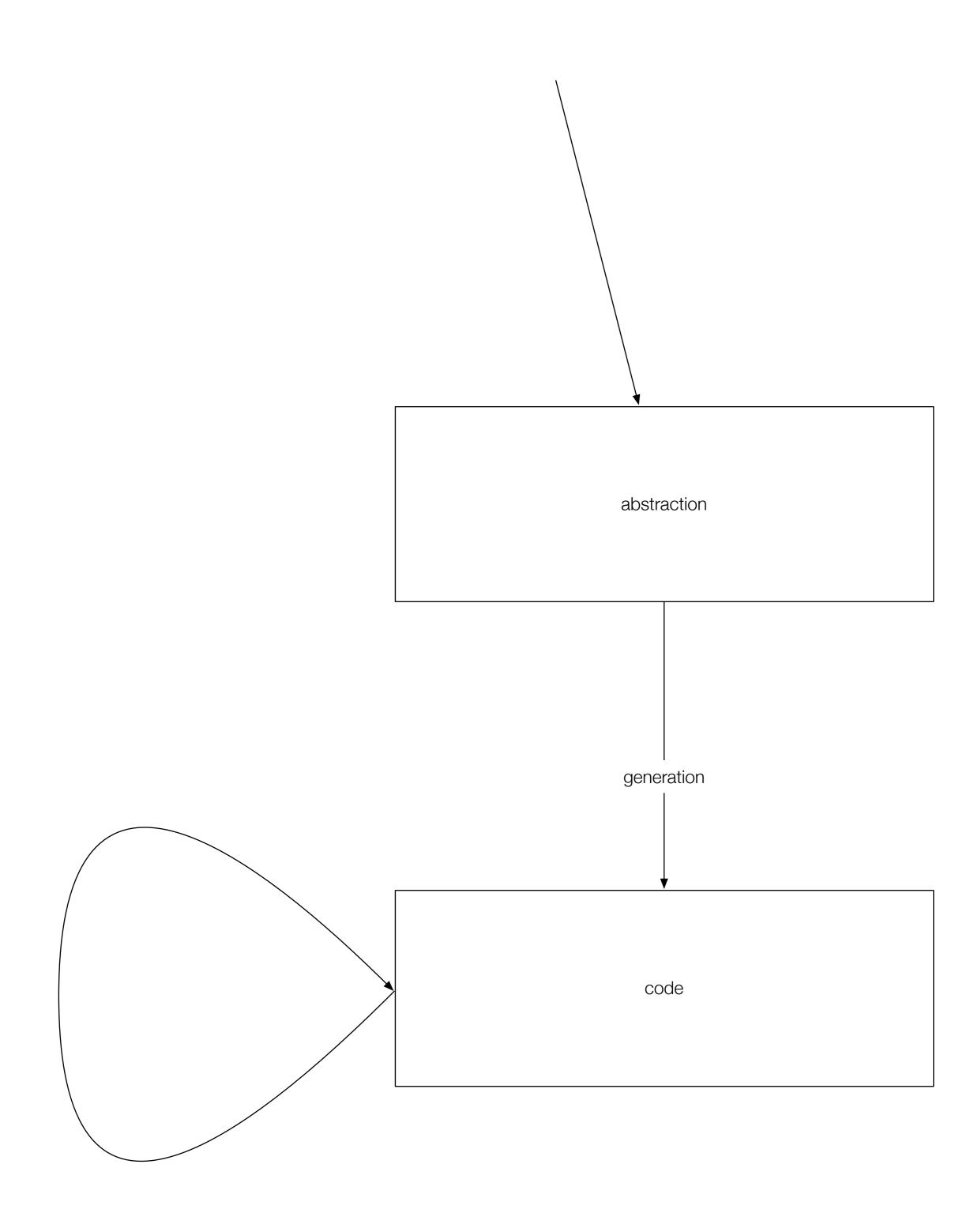


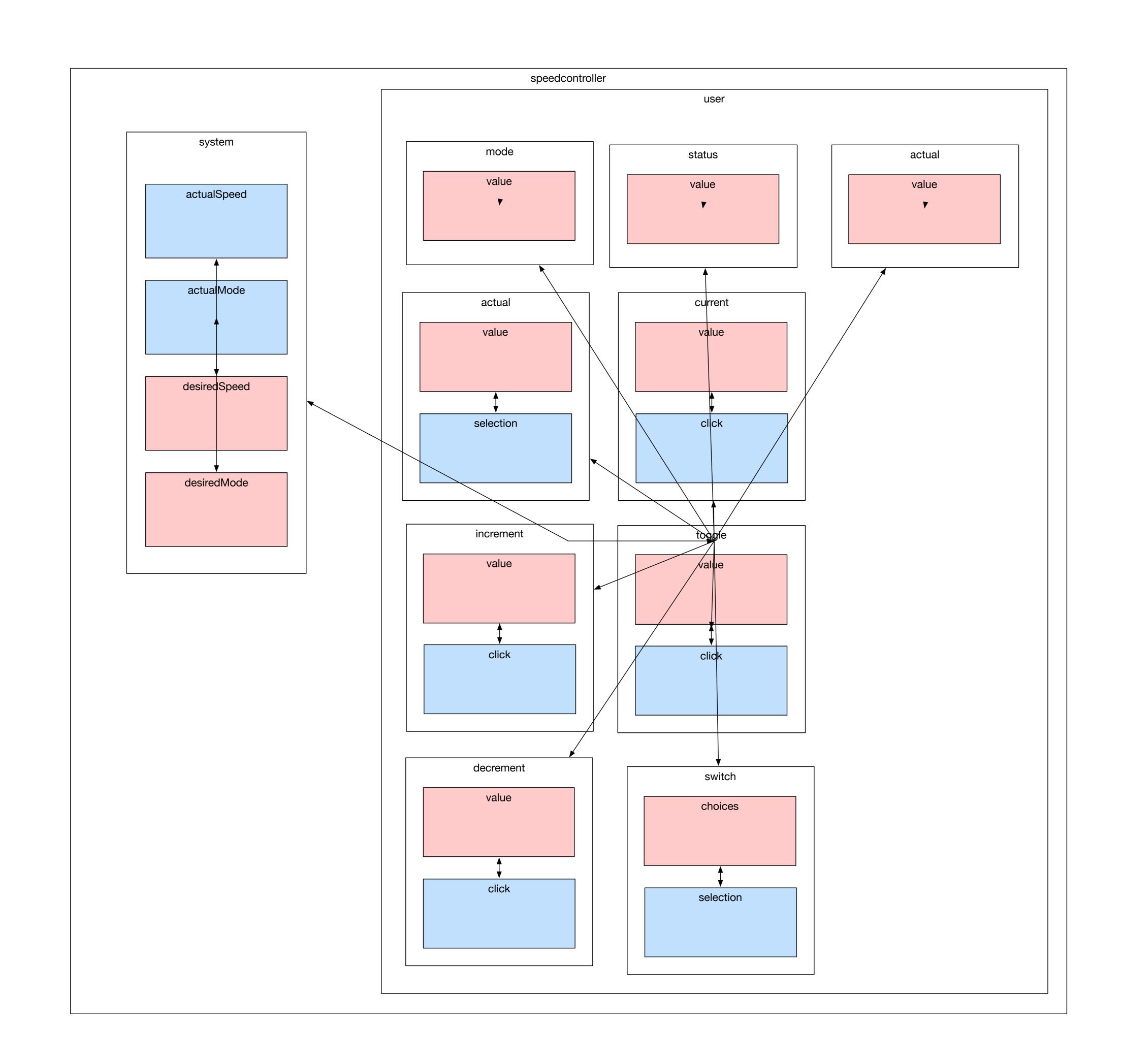


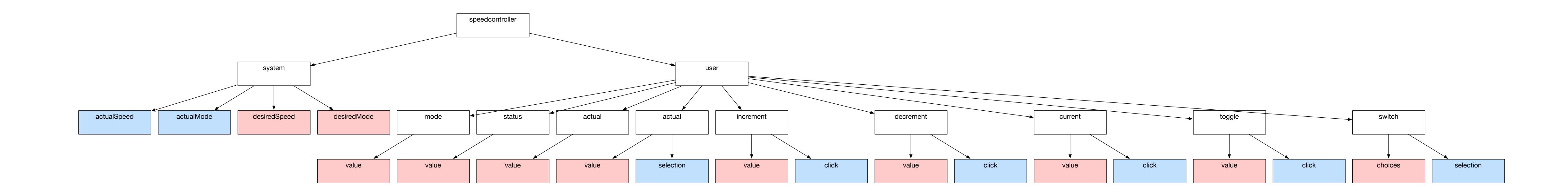


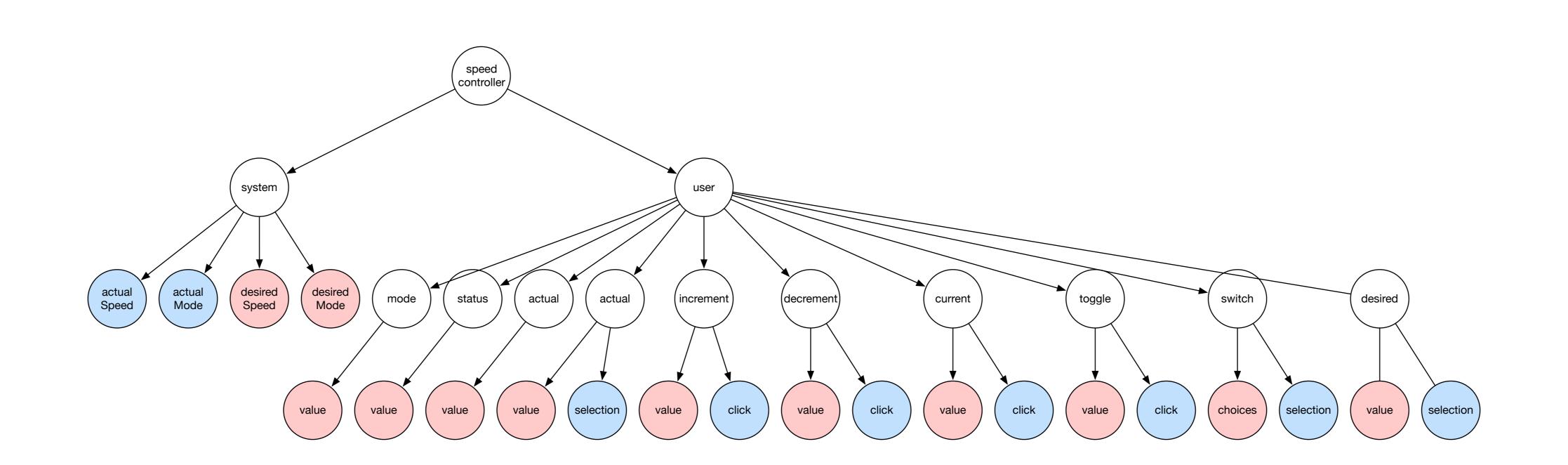


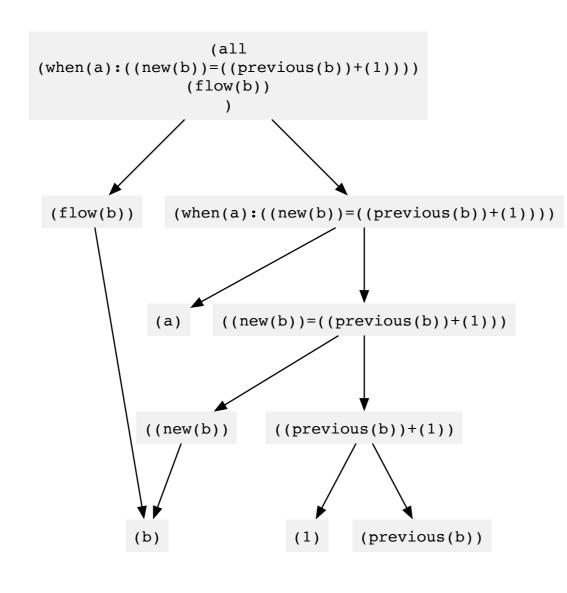


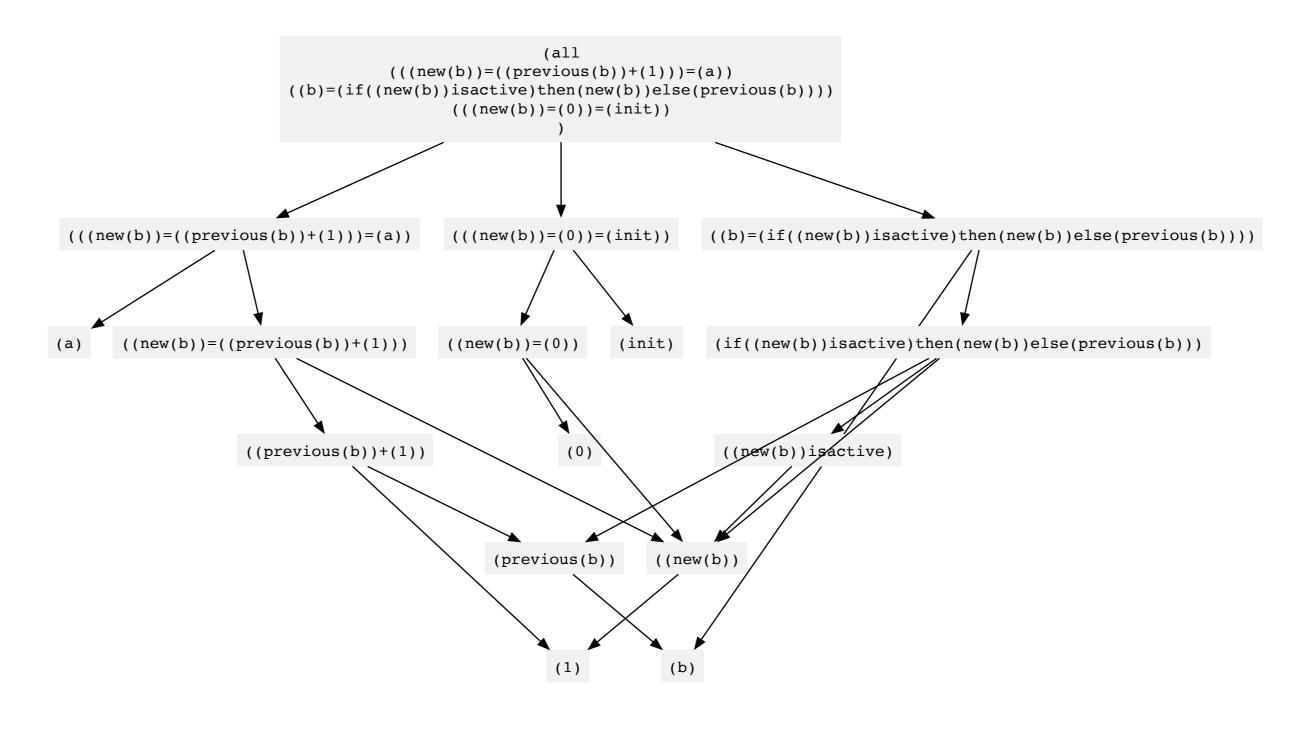


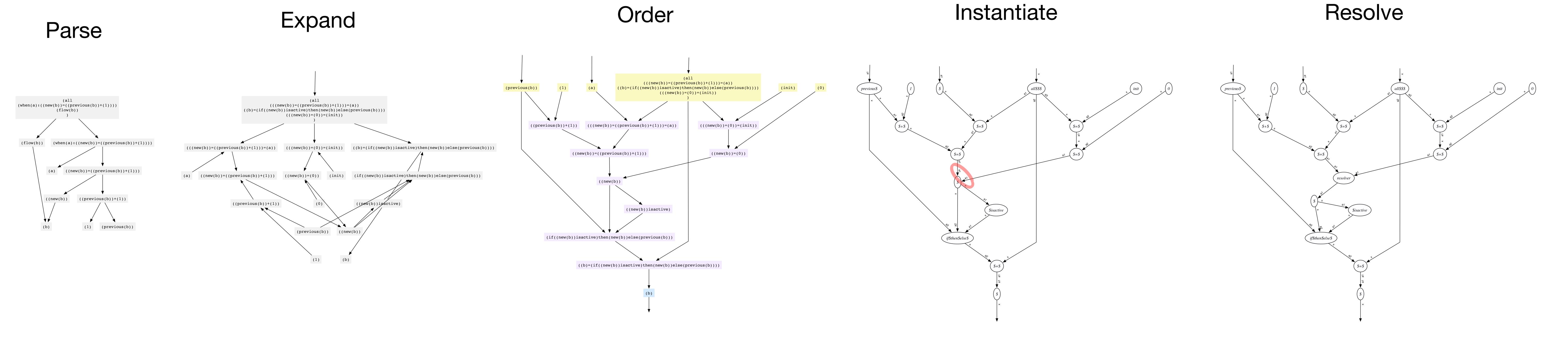






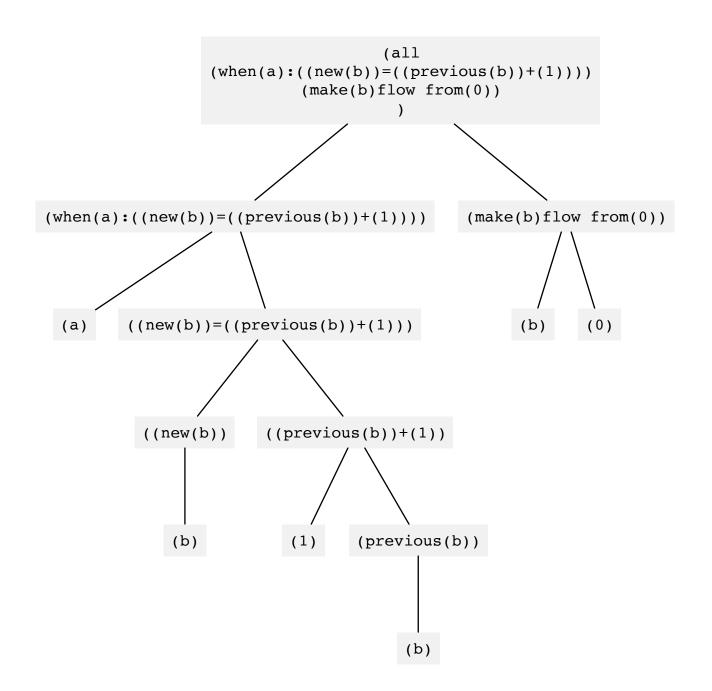




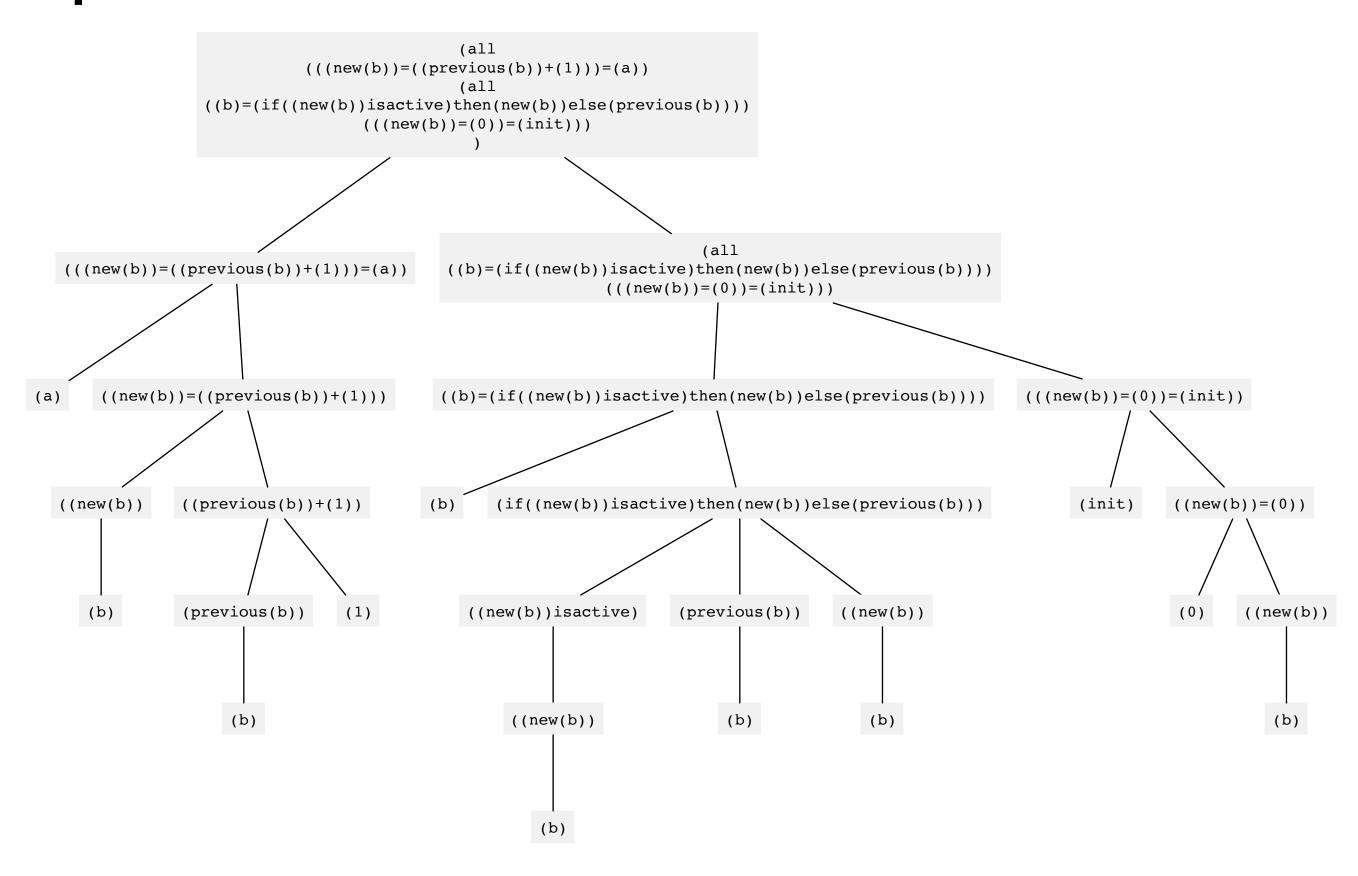


Parse

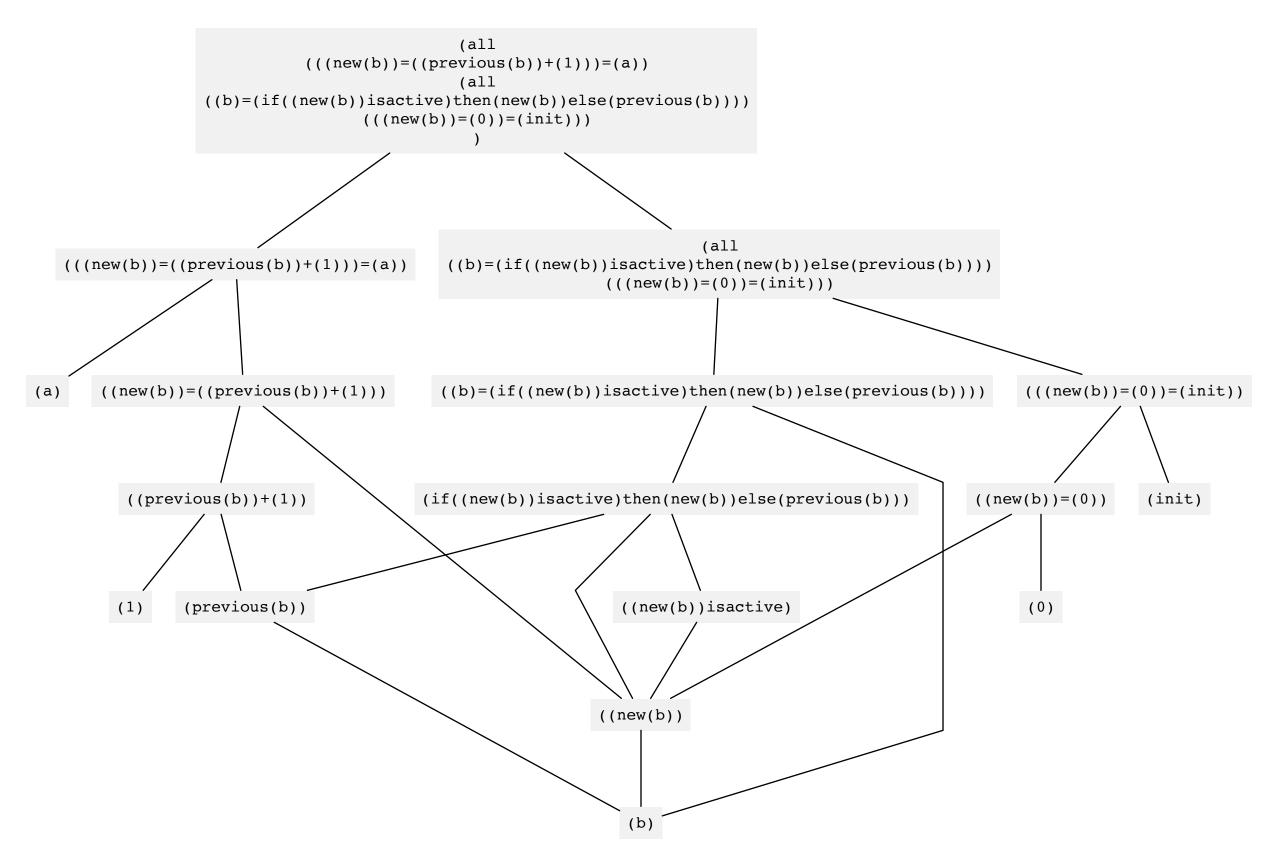
Here we parse the code and made the expression tree



Expand



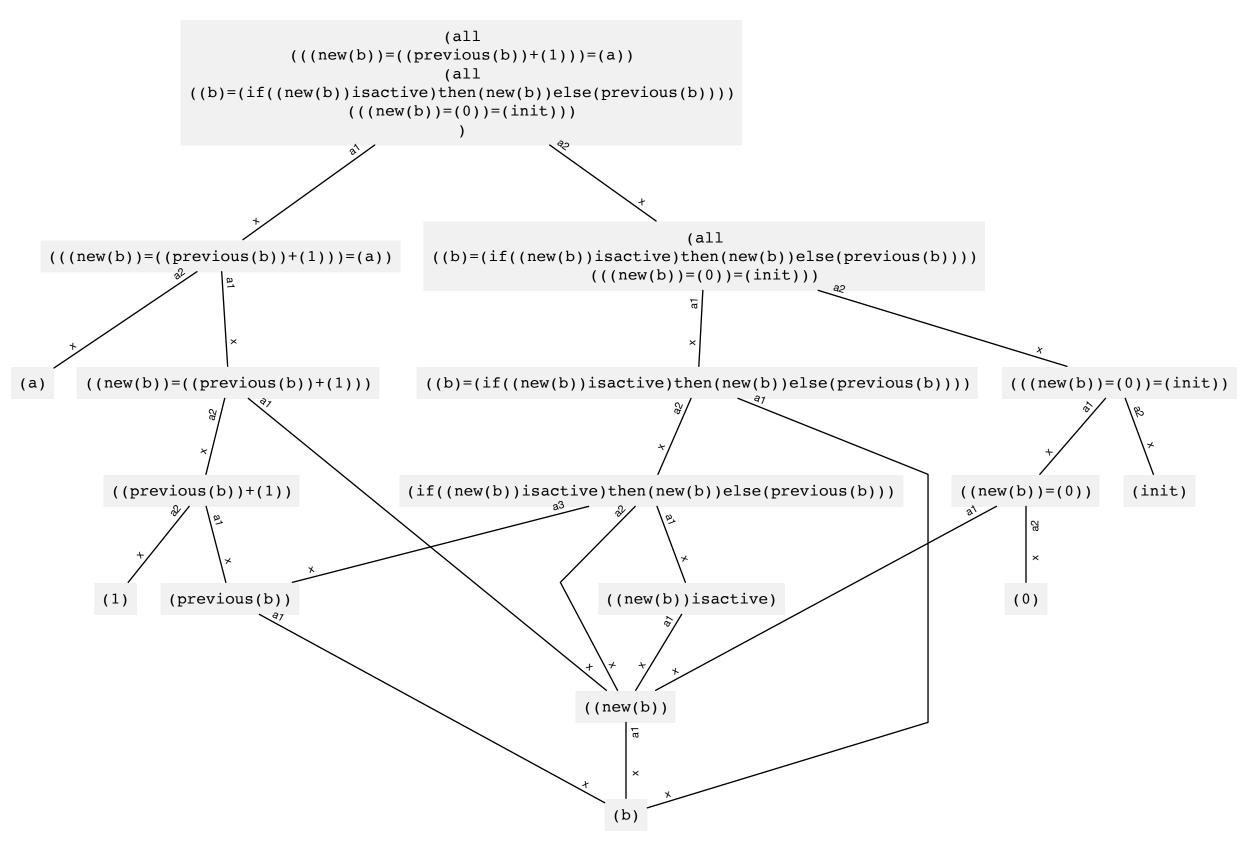
Link



Annotate

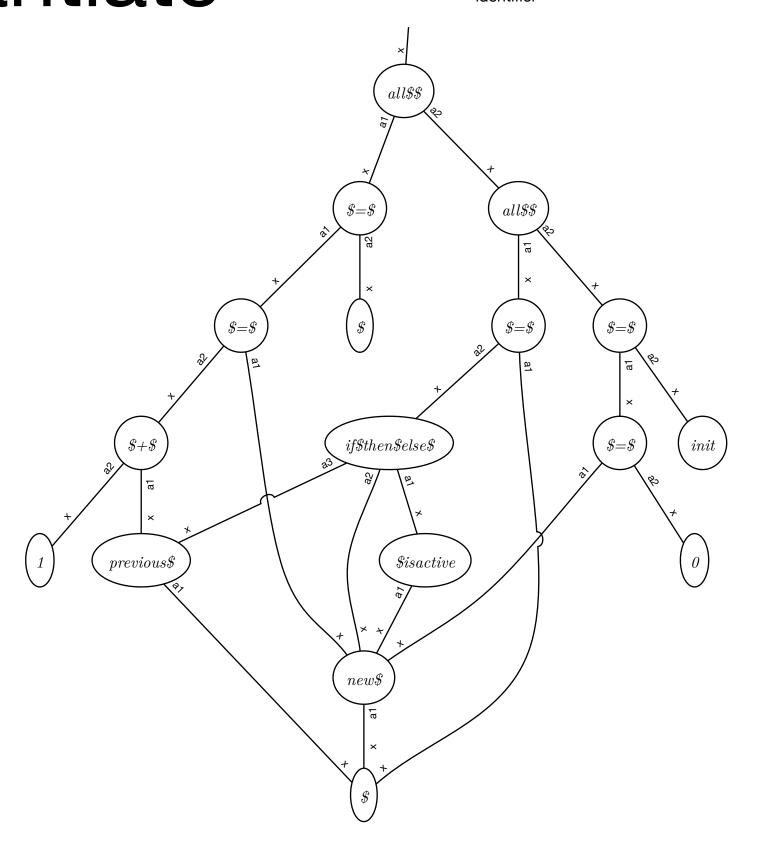
Here we added annotations to the graph edges, these annotations describe the role of each element in the expression (a1 for argument1, a2, ..., and x for the expression itself)

Note that adding annotations is straightforward, as the bottom end of each edge is an "x", and the top end is an "a" numbered according to the argument number.



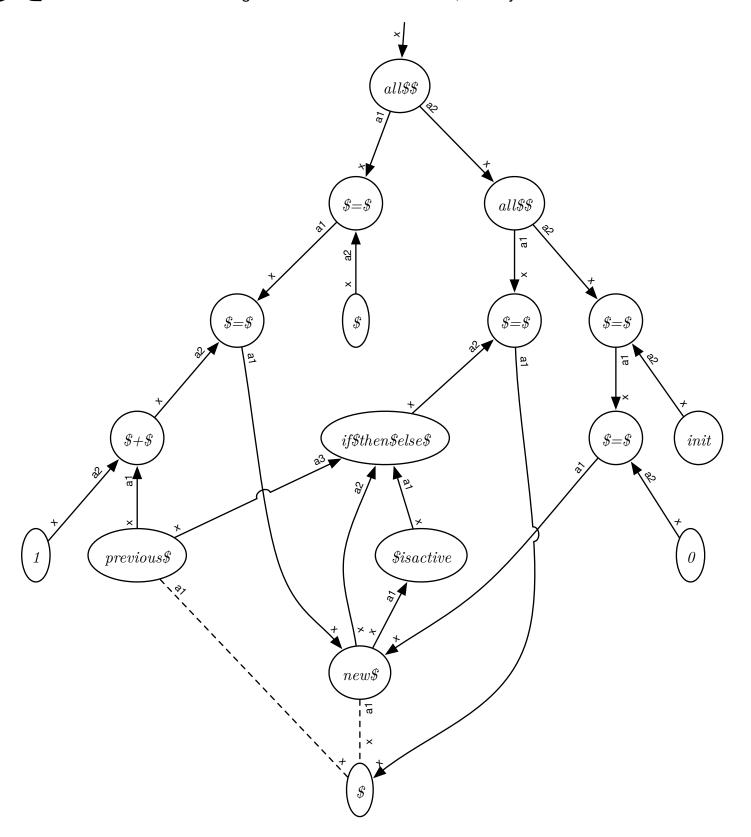
Instantiate

From here we don't need identifiers anymore, we can remove the notion of identifier, and rename nodes according to their operator instead of their identifier

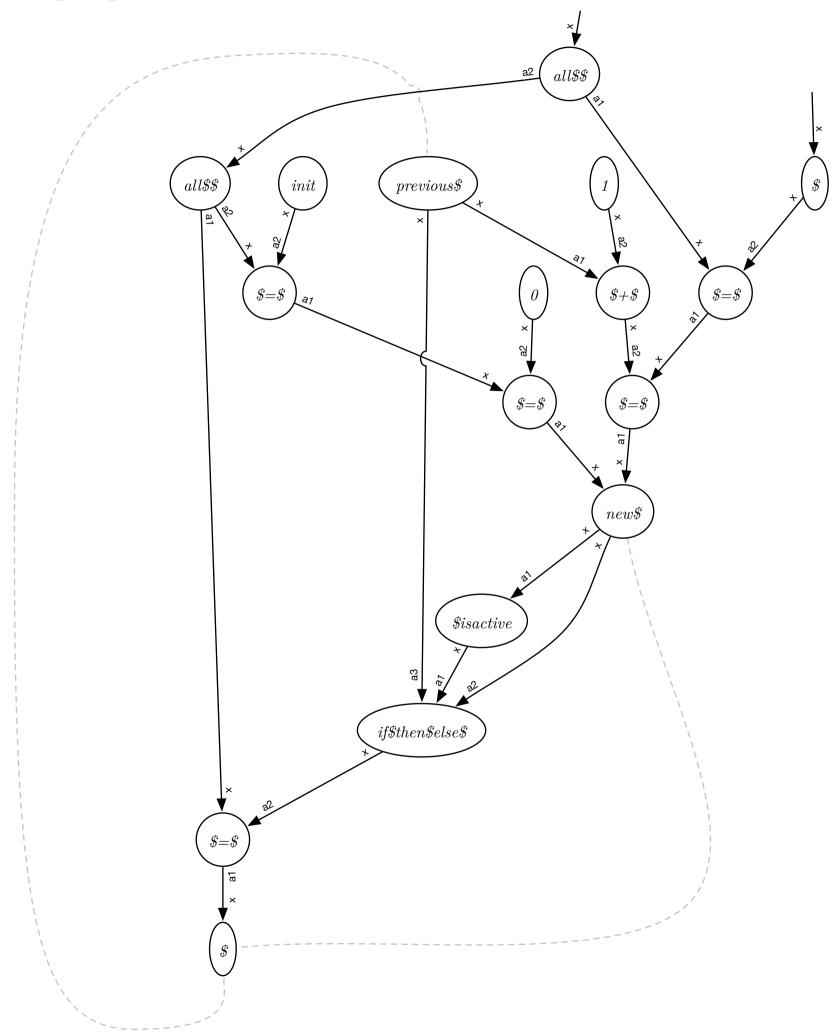


Direct

Here we keep the same graph, but we give directions to edges, according to the direction of the data flow. For this step to be possible, the program has to be consistent according to interfaces flow directions. (i.e. the OUTs must match the INs) Some edges do not denote a data flow, so they are dashed

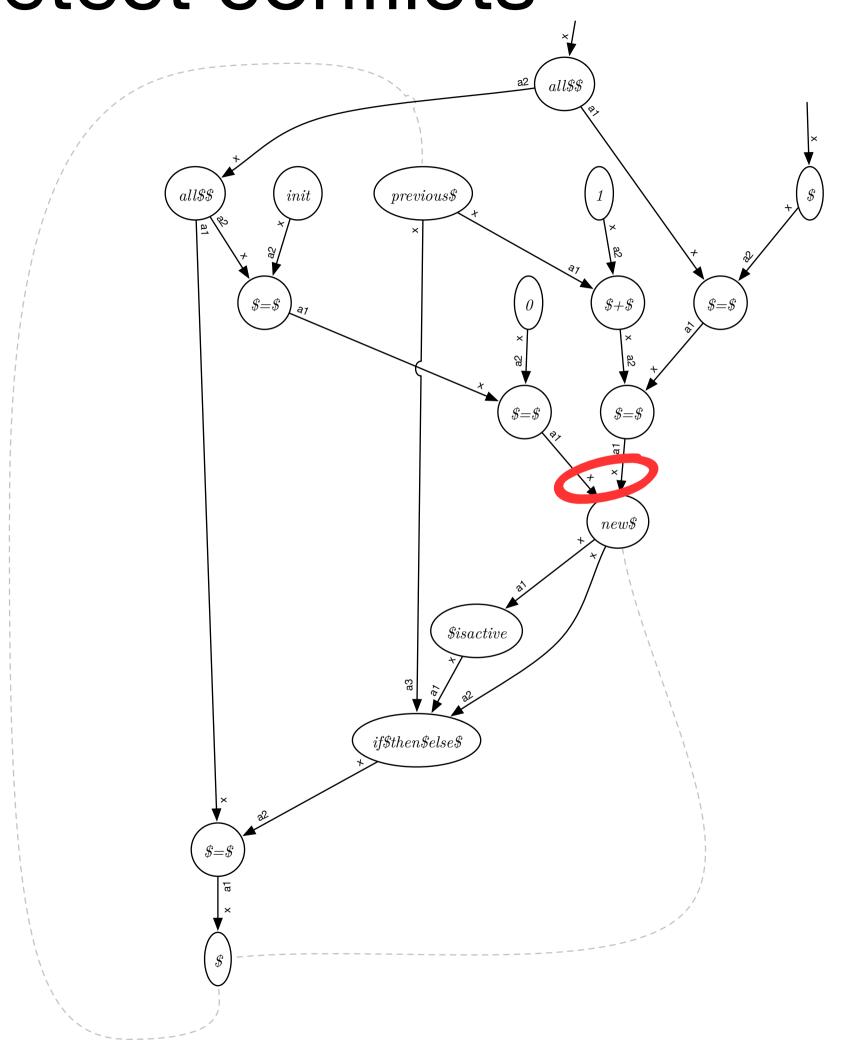


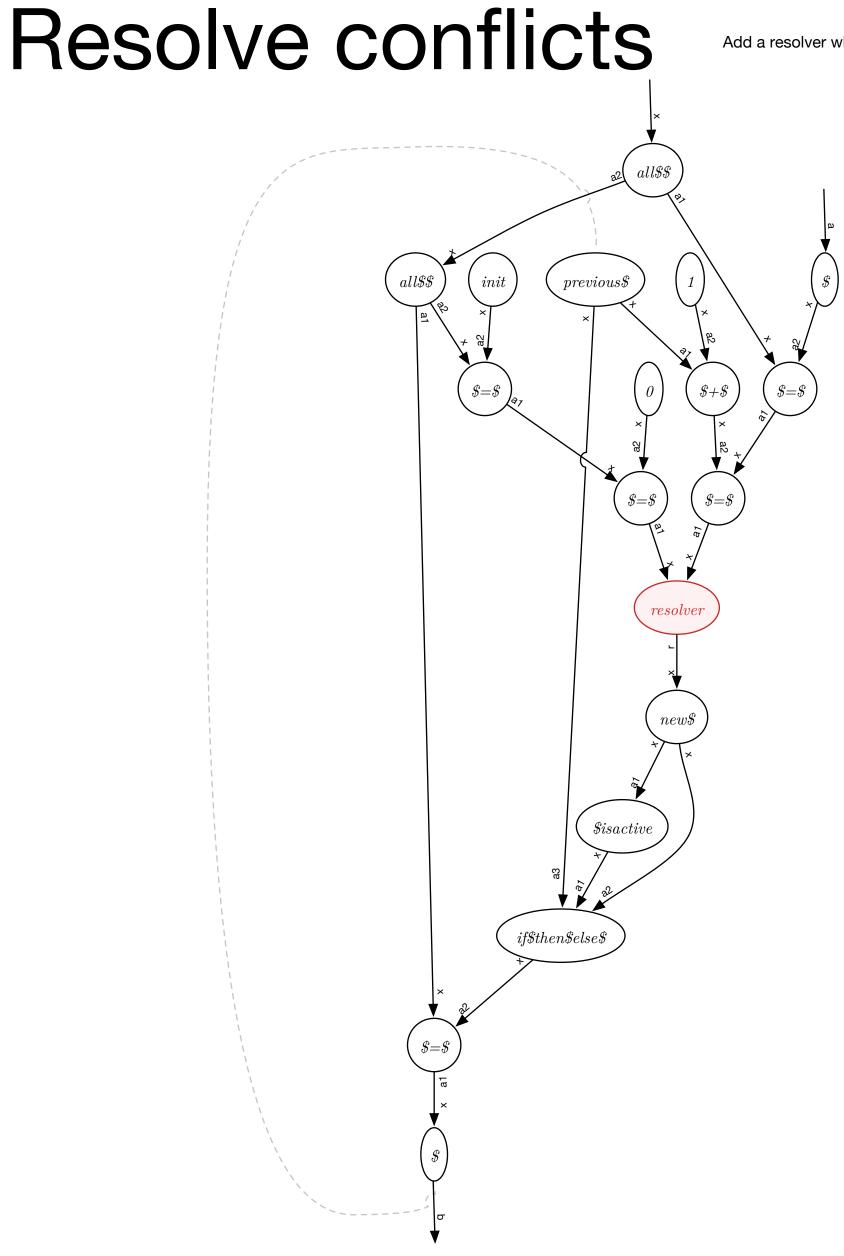
Order



Detect conflicts

We detect nodes where two incoming edges have the same annotations





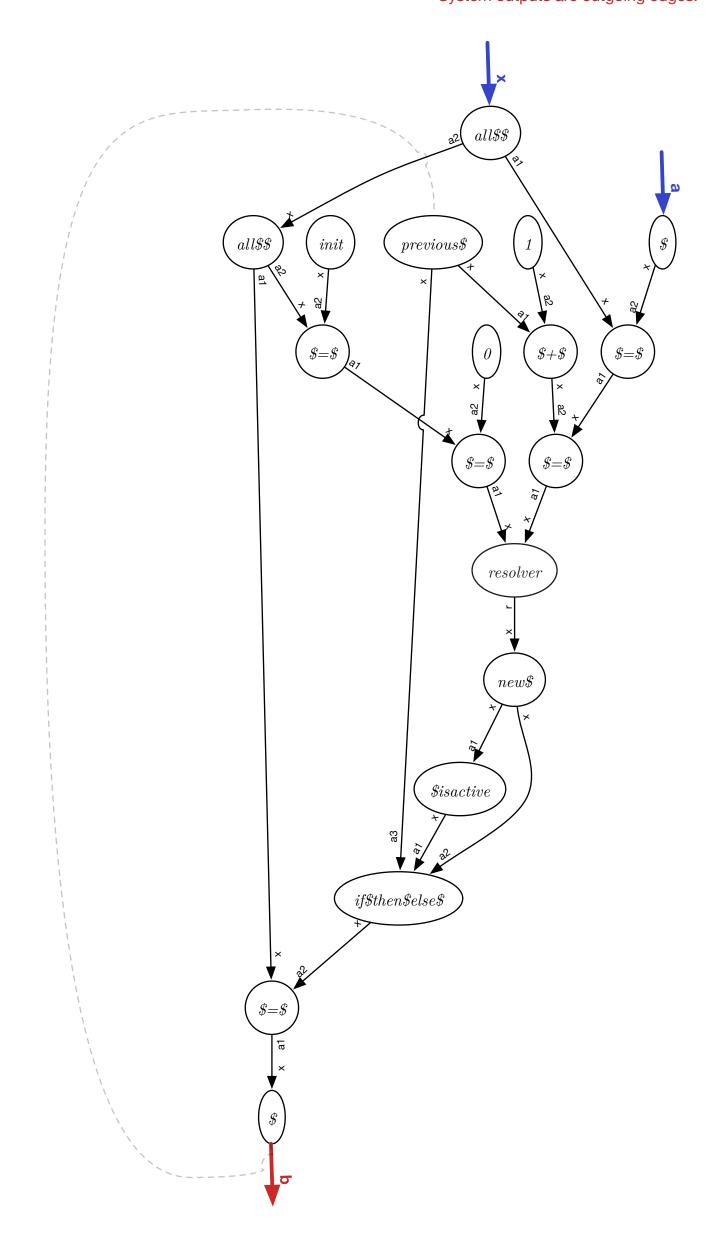
Execution

From here, the interaction is ready to be executed.

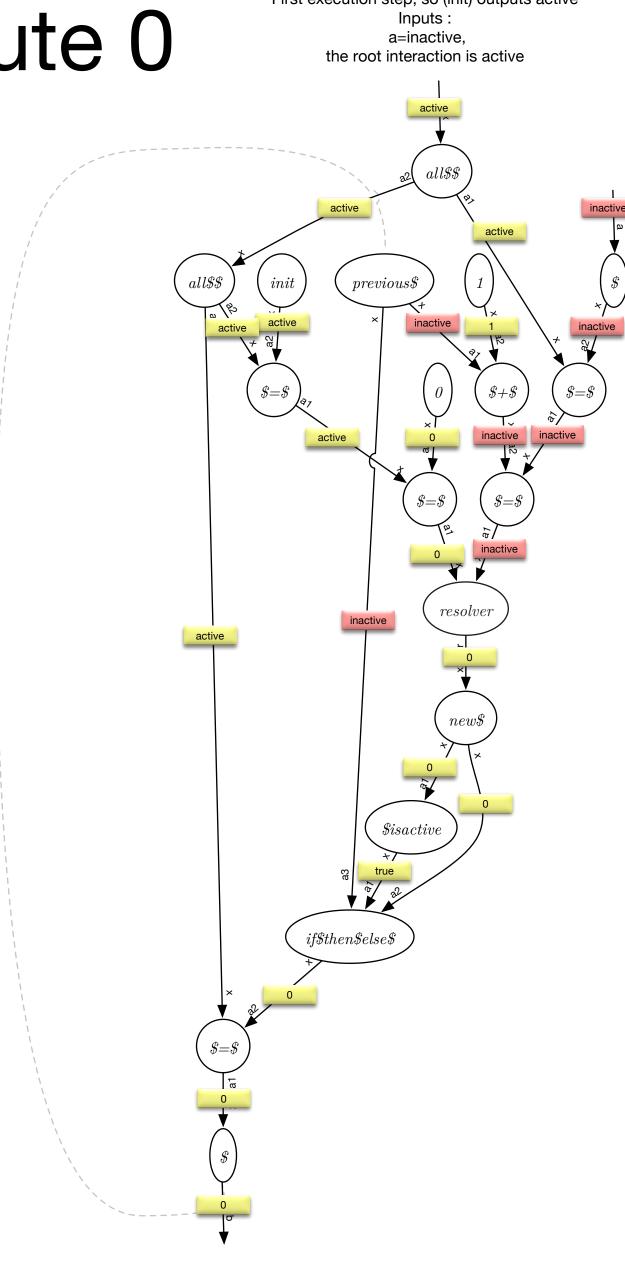
To execute, assign values to edges, from top to bottom.

System inputs are incoming edges.

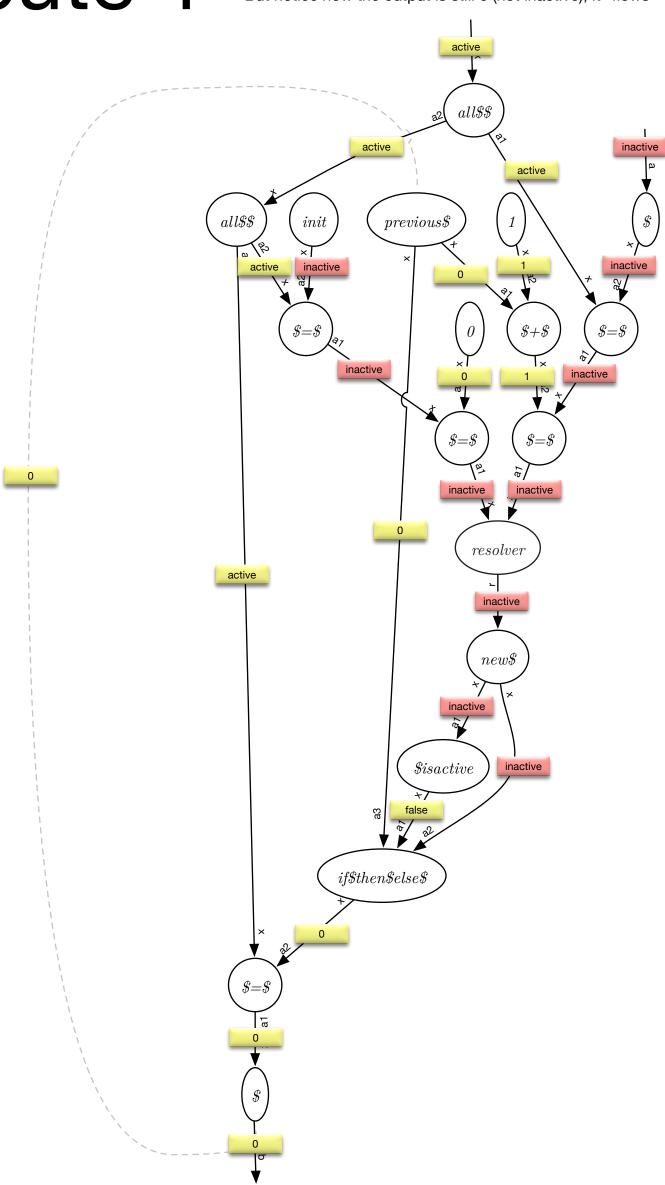
System outputs are outgoing edges.



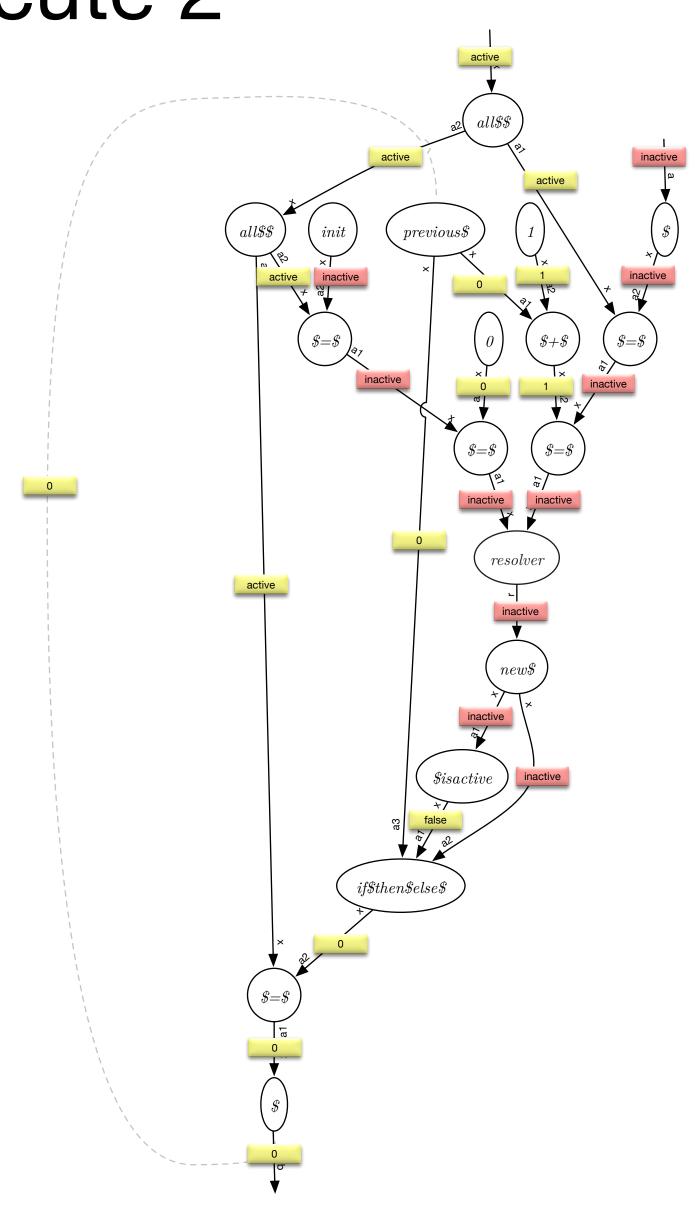
First execution step, so (init) outputs active Execute 0 Inputs: a=inactive, the root interaction is active previous \$resolveractive \$ is activeif\$ then\$ else\$



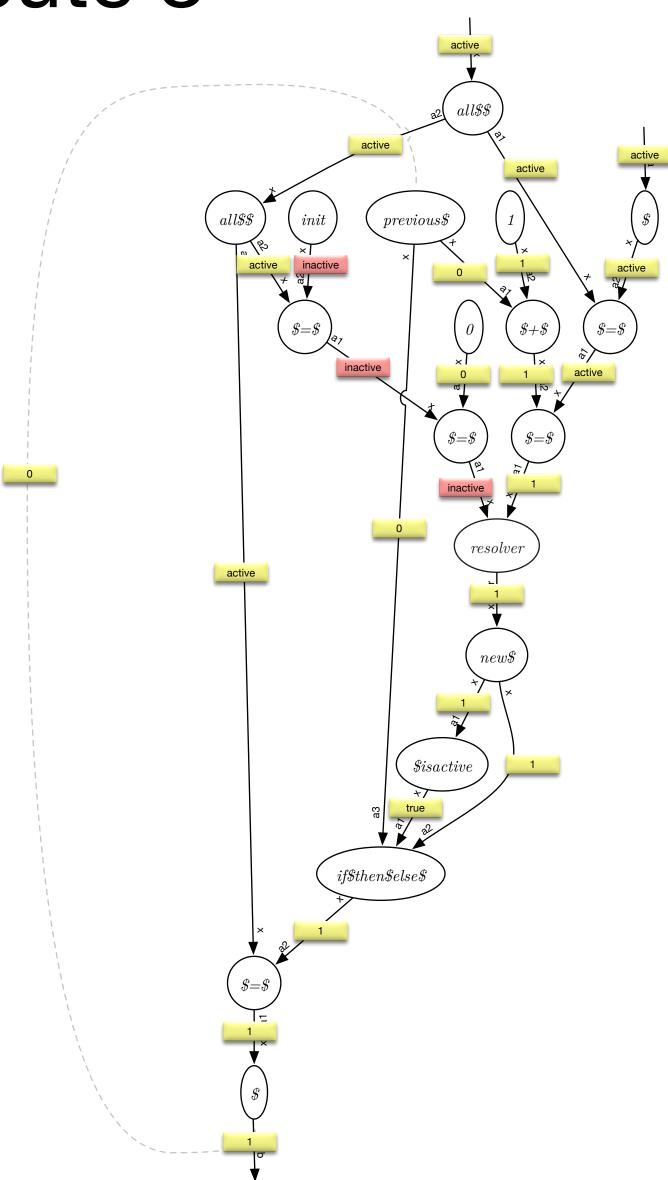
Second execution step, still no input on a, But notice how the output is still 0 (not inactive), it "flows"



Third execution step, still no input on a, nothing changes



Here the input a receives the value "active", the output value b is incremented



No input on a, b stays to 1

