

DC-Micromotors

Precious Metal Commutation

0,60 mNm

For combination with (overview on page 14-15) Gearheads: 10/1, 12/3 Encoders: 30B

		1219 N		4.5 G	006 G	012 G	015 G	
1	Nominal voltage	Un		4,5	6	12	15	Volt
	Terminal resistance	R		10,7	17,6	69,0	131	Ω
3	Output power	P _{2 max} .		0,46	0,49	0,50	0,41	W
4	Efficiency	η max.		74	73	72	70	%
	No-load speed	n _o		15 300	16 000	16 000	16 200	rpm
	No-load current (with shaft ø 0,8 mm)	lo		0,008	0,007	0,004	0,003	Α
	Stall torque	Мн		1,14	1,17	1,19	0,96	mNm
8	Friction torque	Mr		0,02	0,02	0,03	0,03	mNm
	Speed constant	k n		3 460	2 721	1 364	1 109	rpm/V
	Back-EMF constant	kε		0,289	0,368	0,733	0,902	mV/rpm
	Torque constant	kм		2,76	3,51	7,00	8,61	mNm/A
12	Current constant	k ı		0,362	0,285	0,143	0,116	A/mNm
13	Slope of n-M curve	Δη/ΔΜ		13 413	13 642	13 447	16 875	rpm/mNm
14	Rotor inductance	L		150	300	1 200	1 600	μH
15	Mechanical time constant	τm		20	20	18	19	ms
16	Rotor inertia	J		0,14	0,14	0,13	0,11	gcm ²
17	Angular acceleration	CL max.		81	84	92	87	·10³rad/s²
18	Thermal resistance	Rth 1 / Rth 2	17 / 48					K/W
	Thermal time constant	au w1 / $ au$ w2	3,5 / 386					S
20	Operating temperature range:							
	– motor		– 30 + 85 (optional -	- 30 + 12	25)			°C
	– rotor, max. permissible		+ 85 (optional + 125)				°C	
	Shaft bearings	sintered bronze sleeves ball bearings						
22	Shaft load max.:		(standard)	(optional)			
	 with shaft diameter 		0,8	1,0				mm
	 radial at 3 000 rpm (1,5 mm from bearin 	g)	0,5	5				N
	– axial at 3 000 rpm		0,1	0,5				N
	 axial at standstill 		20	5				N
23	Shaft play:							
	– radial	≤	0,03	0,02				mm
	– axial	≤	0,2	0,2				mm
	Housing material		steel, nickel plated					
	Weight		11					g
26	Direction of rotation		clockwise, viewed from	the front	face			
	commended values - mathematically indep		h other					
	Speed up to	Ne max.		12 000	12 000	12 000	12 000	rpm
	Torque up to	Me max.		0,60	0,60	0,60	0,60	mNm
	Current up to (thermal limits)	le max.		0,260	0,200	0,100	0,070	Α

