

Homework 3

April 30, 2021

1. Suppose $\mathbf{v}_1, \dots, \mathbf{v}_m$ is a list of vectors in V . Define $T \in \mathcal{L}(\mathbb{R}^m, V)$ by

$$T(\mathbf{x}) = x_1 \mathbf{v}_1 + \dots + x_m \mathbf{v}_m,$$

$$\text{for } \mathbf{x} = \begin{Bmatrix} x_1 \\ \vdots \\ x_m \end{Bmatrix} \in \mathbb{R}^m.$$

$$T(\mathbb{R}^m) = \text{span}(\mathbf{v}_1, \dots, \mathbf{v}_m) = V.$$

Surjective. $T(\mathbb{R}^m) = V.$

- (a) What property of T corresponds to $\mathbf{v}_1, \dots, \mathbf{v}_m$ spanning V ? Why?
- (b) What property of T corresponds to $\mathbf{v}_1, \dots, \mathbf{v}_m$ being linearly independent? Why? *Injective. If $T(\mathbf{x}) = 0$, $x_1 \mathbf{v}_1 + \dots + x_m \mathbf{v}_m = 0$. Since $\mathbf{v}_1, \dots, \mathbf{v}_m$ are linearly independent, $x_1 = \dots = x_m = 0 \Rightarrow \mathbf{x} = \mathbf{0} \Rightarrow \text{Ker}(T) = \{\mathbf{0}\}$. $\Rightarrow T$ is injective.*
2. (a) Suppose $T \in \mathcal{L}(V, W)$ is injective and $\mathbf{v}_1, \dots, \mathbf{v}_n$ is linearly independent in V . Prove that $T(\mathbf{v}_1), \dots, T(\mathbf{v}_n)$ is linearly independent in W .
- (b) Suppose $\mathbf{v}_1, \dots, \mathbf{v}_n$ spans V and $T \in \mathcal{L}(V, W)$. Prove that the list $T(\mathbf{v}_1), \dots, T(\mathbf{v}_n)$ spans $T(V)$.
- (c) Suppose V is finite-dimensional and that $T \in \mathcal{L}(V, W)$. Prove that there exists a subspace U of V such that $U \cap \text{Ker}(T) = \{\mathbf{0}\}$ and $T(V) = T(U)$. Find a basis.

3. (a) Suppose V and W are both finite-dimensional. Prove that there exists an injective linear transformation from V to W if and only if $\dim V \leq \dim W$.
- (b) Suppose V and W are both finite-dimensional. Prove that there exists a surjective linear transformation from V onto W if and only if $\dim V \geq \dim W$.
- (c) Suppose V and W are finite-dimensional and that U is a subspace of V . Prove that there exists $T \in \mathcal{L}(V, W)$ such that $\text{Ker}(T) = U$ if and only if $\dim U \geq \dim V - \dim W$.

$$T \in \mathcal{L}(V, W)$$

$$V: \{\underline{v}_1, \dots, \underline{v}_n\}$$

$$\downarrow \quad \vdots$$

$$T(\underline{v}_1) \in W \quad T(\underline{v}_n) \in W.$$

$$\forall \underline{v} \in V, \underline{v} = c_1 \underline{v}_1 + \dots + c_n \underline{v}_n$$

$$T(\underline{v}) = c_1 T(\underline{v}_1) + \dots + c_n T(\underline{v}_n)$$

$$r \geq n-m \Leftrightarrow m \geq n-r$$

$$\dim V = n$$

$$\dim W = m$$

$$\dim U = r$$

$$U \xrightarrow{T} W$$

$$\text{a basis of } U, \{u_1, \dots, u_r\} \rightarrow \text{a basis of } V \{u_1, \dots, u_r, u_{r+1}, \dots, u_n\}$$

$$\text{Let } \{w_1, \dots, w_m\} \text{ be a basis of } W.$$

$$T(U) = \{\mathbf{0}\}, U \subset \text{Ker}(T)$$

$$\Rightarrow \text{For } \underline{v} \in V, \text{ if } T(\underline{v}) = \mathbf{0}, \underline{v} = c_1 \underline{v}_1 + \dots + c_r \underline{v}_r + c_{r+1} \underline{v}_{r+1} + \dots + c_n \underline{v}_n$$

$$0 = T(\underline{v}) = c_1 T(\underline{v}_1) + \dots + c_r T(\underline{v}_r) + c_{r+1} T(\underline{v}_{r+1}) + \dots + c_n T(\underline{v}_n)$$

$$0 = c_1 w_1 + \dots + c_r w_r + c_{r+1} w_{r+1} + \dots + c_n w_n$$

$$m \geq n-r$$

Idea:

$$T(\underline{v}_1) = \mathbf{0} \quad T(\underline{v}_2) = \mathbf{0} \quad \dots \quad T(\underline{v}_n) = w_{n-r}$$

$$A = \left[\begin{array}{c|c} [L(e_1)]_{\{b_1, b_2, b_3\}} & [L(e_2)]_{\{b_1, b_2, b_3\}} \end{array} \right]$$

$$L(e_1) = (b_1, b_2, b_3) \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \quad L(e_2) = (b_1, b_2, b_3) \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad A = \begin{pmatrix} 0 & 1 \\ 1 & 1 \\ 1 & 1 \end{pmatrix}$$

$x_1=1, x_2=0$ $x_1=0, x_2=1$

4. Let

$$b_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, b_2 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, b_3 = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$$

and let L be the linear transformation from \mathbb{R}^2 into \mathbb{R}^3 define by

$$L(x) = x_1 b_1 + x_2 b_2 + (x_1 + x_2) b_3,$$

find the matrix A representing L with respect to the ordered bases $\{e_1, e_2\}$ and $\{b_1, b_2, b_3\}$.

5. Let

$$y_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, y_2 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, y_3 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

and let \mathcal{I} be the identity operator on \mathbb{R}^3 .

(a) Find the coordinates of $\mathcal{I}(e_1)$, $\mathcal{I}(e_2)$, and $\mathcal{I}(e_3)$ with respect to $\{y_1, y_2, y_3\}$.

(b) Find a matrix A such that Ax is the coordinate vector of x with respect to $\{y_1, y_2, y_3\}$.

$$\begin{aligned} \mathcal{I}(e_1) = e_1 &= (y_1, y_2, y_3) \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \\ \mathcal{I}(e_2) = e_2 &= (y_1, y_2, y_3) \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \\ \mathcal{I}(e_3) = e_3 &= (y_1, y_2, y_3) \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} \end{aligned}$$

$$(b). \quad A = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & -1 \\ 1 & -1 & 0 \end{pmatrix}$$

$$T(e_1) = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = (y_1, y_2, y_3) \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$