

Homework 11

Due Tuesday, December 8

Please either give the assignment to Loraine at the CDS or send it via email to the graders **before noon**.

1. *Convexity (10 points)*. Let $f_i : \mathbb{R} \rightarrow \mathbb{R}$, $1 \leq i \leq m$ be m convex functions.
 - a. Prove that $f := \sum_{i=1}^n a_i f_i$ is a convex function if the constants a_1, \dots, a_m are nonnegative.
 - b. Prove that the function

$$g(x) = \max_{1 \leq i \leq m} f_i(x) \quad (1)$$

is convex.

- c. Prove that the function $h := \prod_{i=1}^m f_i$ is not necessarily convex.
2. *1D optimization (20 points)*. In this problem you will implement the 1D optimization algorithms described in Lecture Notes 11.
 - a. Complete the script `hw11_pb2.py`, implementing derivative descent and Newton's method. Submit the code that you add (*not* the whole script, just the code you write).
3. *Projected gradient descent (20 points)*. We have focused on methods for unconstrained optimization. However, it is often of interest to solve problems of the form

$$\min_{\mathbf{x} \in \mathcal{S}} f(\mathbf{x}) \quad (2)$$

where \mathcal{S} is a set.

Projected gradient descent is an algorithm that solves this type of problem by projecting onto \mathcal{S} after each iteration of gradient descent. The projection of a vector onto an arbitrary set is the point in the set that is nearest to the vector:

$$\mathcal{P}_{\mathcal{S}}(x) = \arg \min_{u \in \mathcal{S}} \|x - u\|_2. \quad (3)$$

Projecting onto the set of interest ensures that the points returned by the algorithm remain in \mathcal{S} .

- a. What is the projection of a vector $\mathbf{x} \in \mathbb{R}^n$ on the positive orthant \mathbb{R}_+^n ?

$$\mathbb{R}_+^n = \{\mathbf{x} \mid x_i \geq 0, 1 \leq i \leq n\}. \quad (4)$$

- b. What is the projection of a vector $\mathbf{x} \in \mathbb{R}^n$ on the unit ℓ_2 ball \mathcal{B}_{ℓ_2} in n dimensions?

$$\mathcal{B}_{\ell_2} = \{\mathbf{x} \mid \|\mathbf{x}\|_2 \leq 1\}. \quad (5)$$

(Hint: First show that the projection must lie in the span of x .)

- c. Complete the script `hw11_pb3.py`. Limit the projected gradient descent iterations to 10. Submit your code and the figures that you obtain.
 - d. Justify intuitively using the concept of contour line that the algorithm reaches the optimal point for both sets of interest.